

Proofs That Count

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Goal

Given a program P and a specification $\varphi_{\text{pre}}/\varphi_{\text{post}}$, prove

$$\{\varphi_{\text{pre}}\}P\{\varphi_{\text{post}}\}$$

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- Proofs for concurrent programs sometimes make use of *counting* arguments.
 - Readers/Writers protocol: “the number of active readers”
 - Ticket protocol: “the number of processes with a smaller ticket”

What is a counting argument?

A counting argument is a proof that a program satisfies its specification which uses auxiliary *counters*:

- Can be used in assertions.
- *Auxiliary* (or *ghost*) variables: do not appear in the program.
Think: Owicki-Gries.

Example

Precondition: $\{s = t = 0\}$

1: `t++`

2: `assert(t > s)`

3: `s++`

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There is *no* Owicki-Gries proof that does not use auxiliary variables.

Example

Precondition: $\{s = t = 0\}$

1: <code>t++</code>		1: <code>t++</code>		...		1: <code>t++</code>
2: <code>assert(t > s)</code>		2: <code>assert(t > s)</code>				2: <code>assert(t > s)</code>
3: <code>s++</code>		3: <code>s++</code>				3: <code>s++</code>

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Inductive invariant:

$$\#2 + \#3 = t - s$$

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of threads at line 3

How do we formalize counting arguments?

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How do we synthesize counting arguments automatically?

Language-theoretic approach

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||
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...

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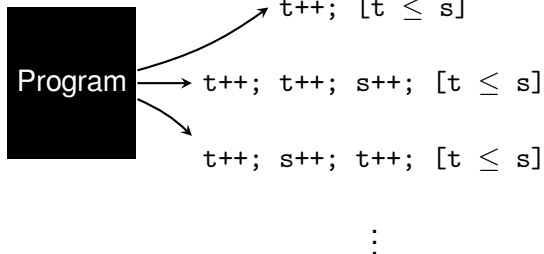
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Language-theoretic approach

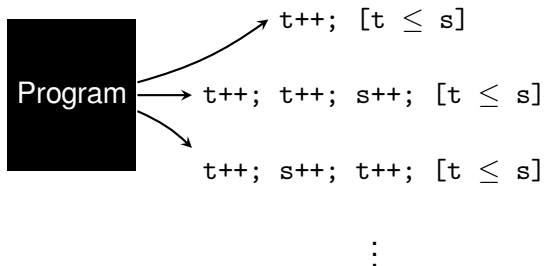
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Error traces



Language-theoretic approach

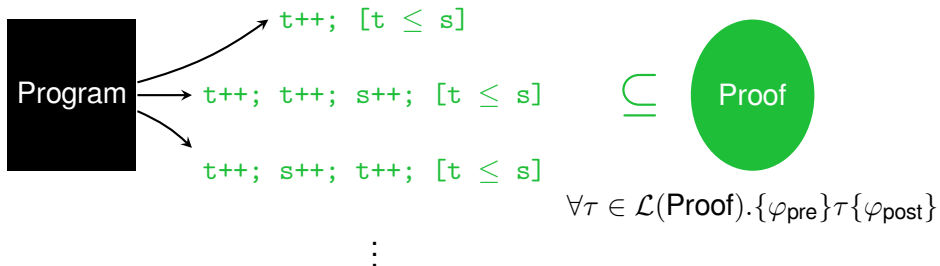
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$\forall T \in \mathcal{L}(\mathbf{Proof}). \{\varphi_{\text{pre}}\}_T \{\varphi_{\text{post}}\}$

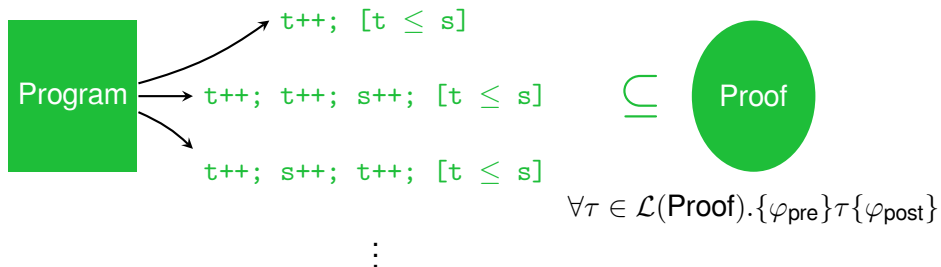
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Proof rule

If there exists a *Proof* such that $\mathcal{L}(\text{Program}) \subseteq \mathcal{L}(\text{Proof})$, then

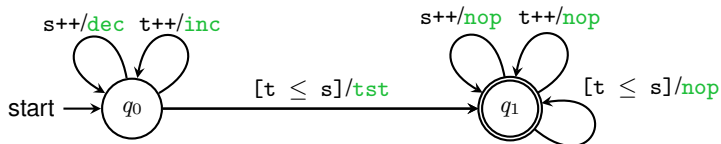
$$\{\varphi_{\text{pre}}\} \text{Program} \{\varphi_{\text{post}}\}$$

Counting proof = counting automaton + inductive annotation

Counting proofs

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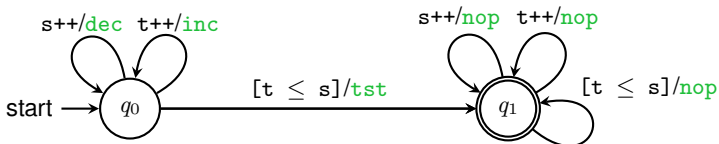
- Counting automaton = DFA with additional \mathbb{N} -valued counter variables.
Assume one counter variable for this talk.
Transitions are labeled by a counter action $\in \{\text{inc}, \text{dec}, \text{tst}, \text{nop}\}$



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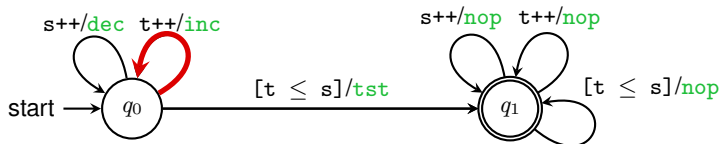


q_0
 $k = 0$

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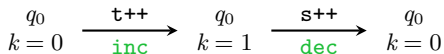
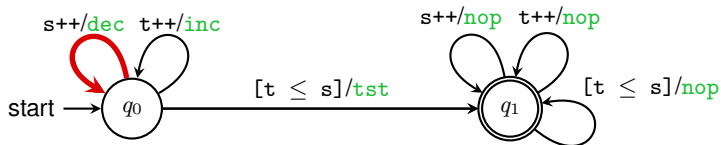


$$\begin{array}{ccc} q_0 & \xrightarrow{t++} & q_0 \\ k = 0 & \xrightarrow{\text{inc}} & k = 1 \end{array}$$

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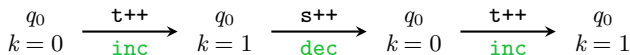
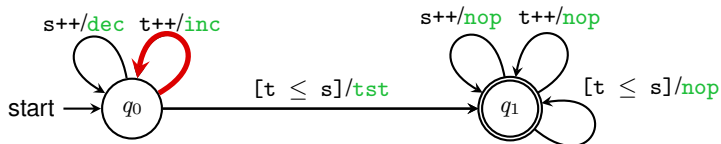
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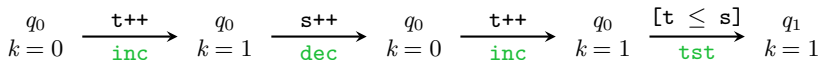
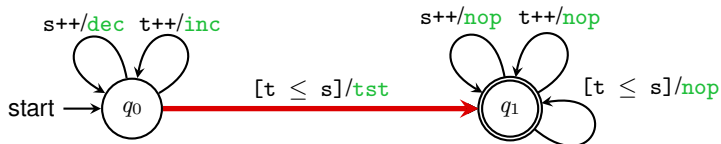
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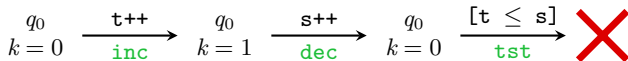
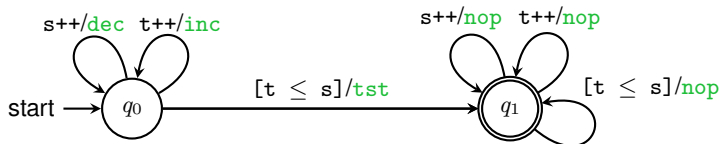
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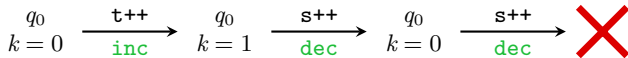
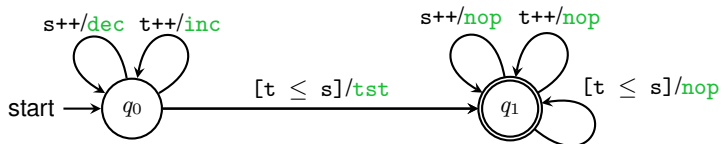
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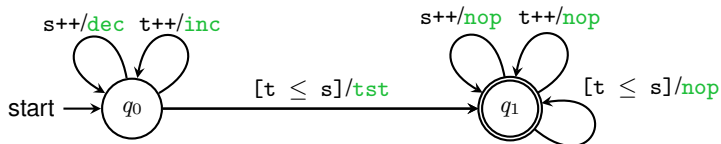
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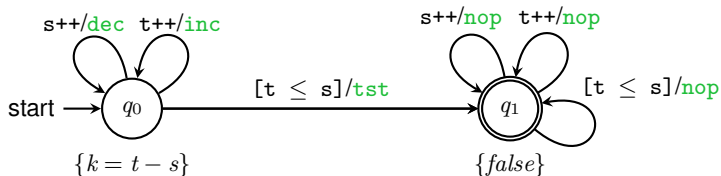
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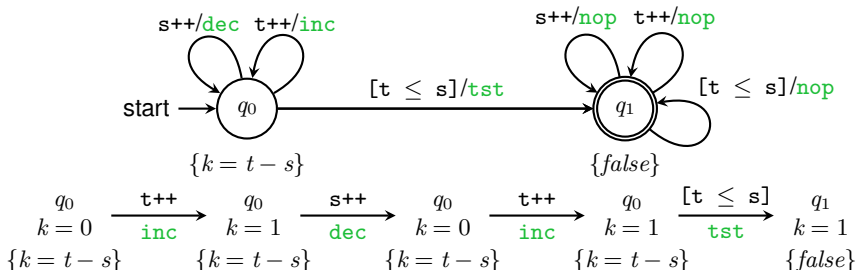
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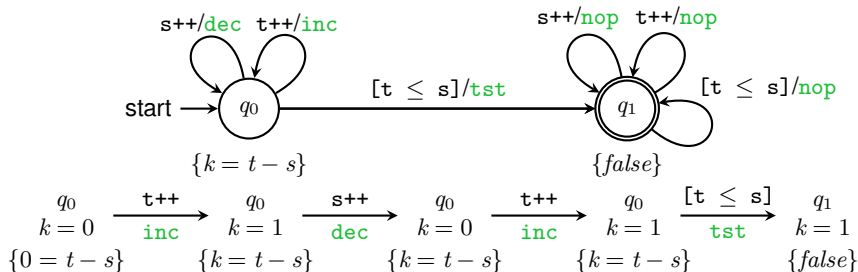
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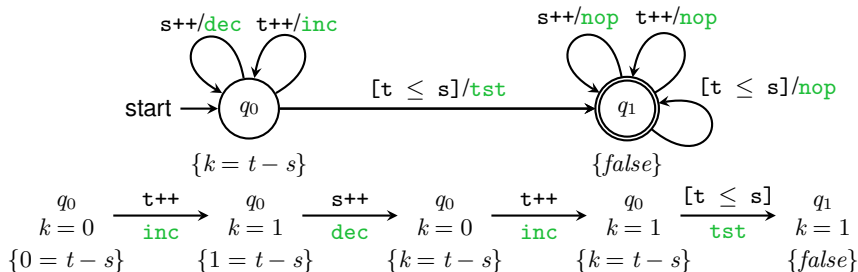
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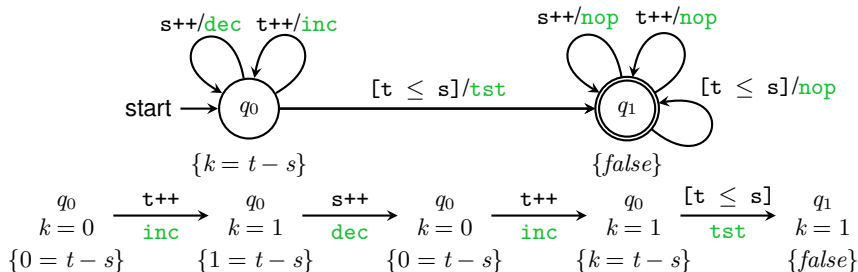
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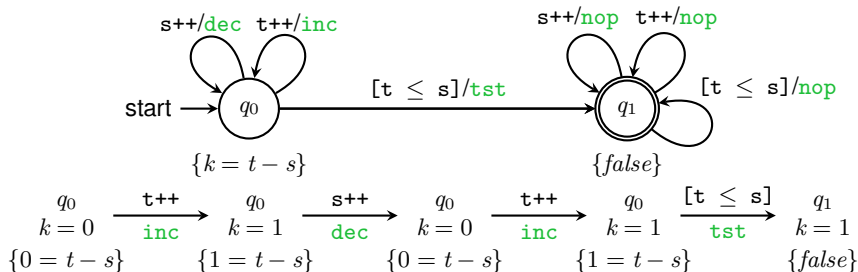
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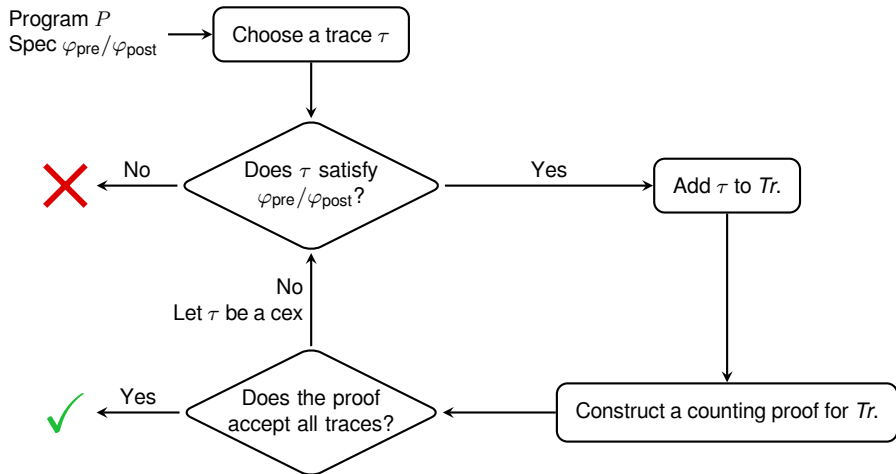
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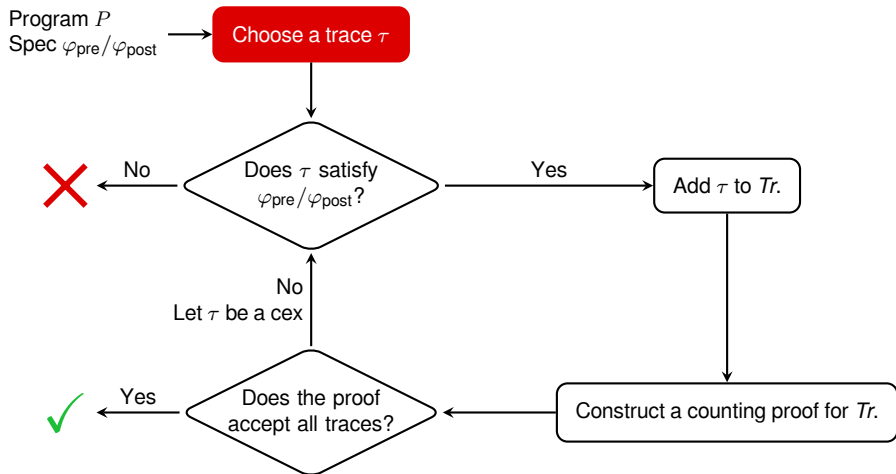
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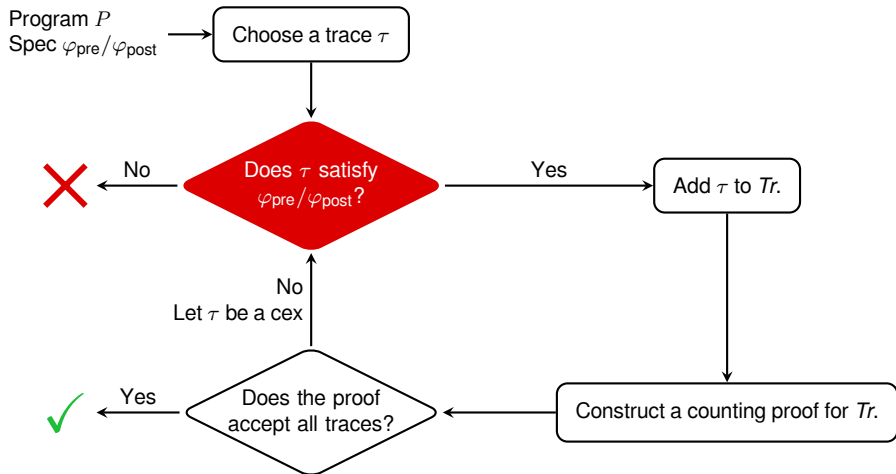
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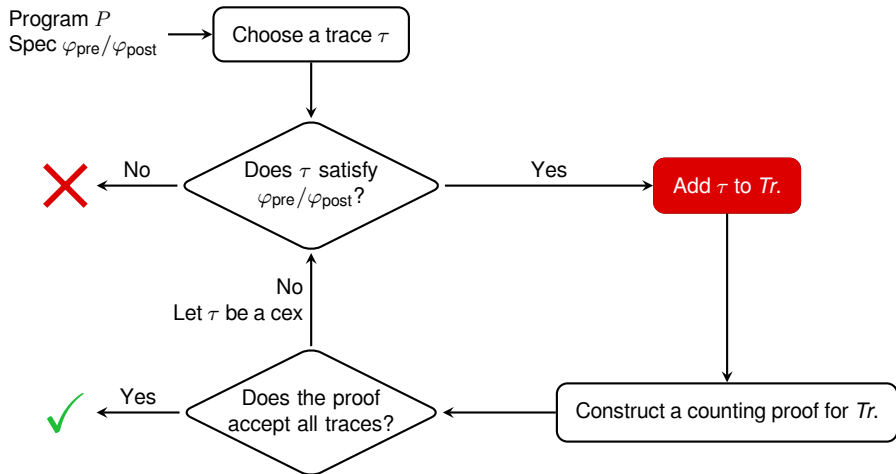
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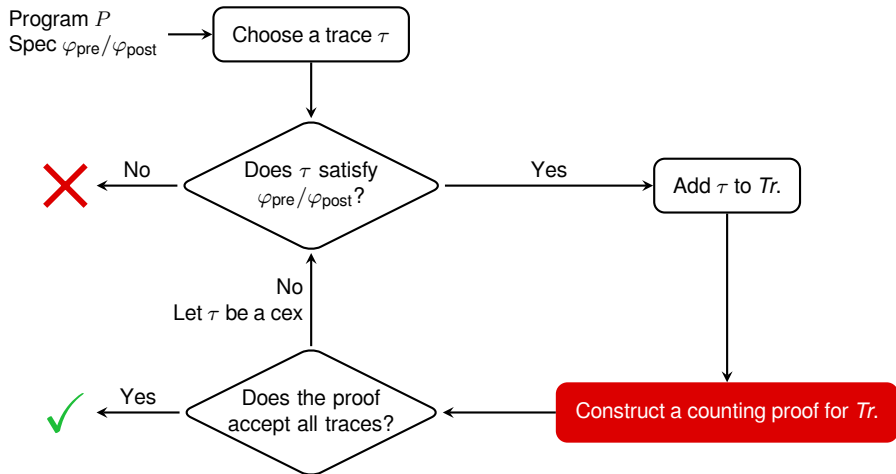
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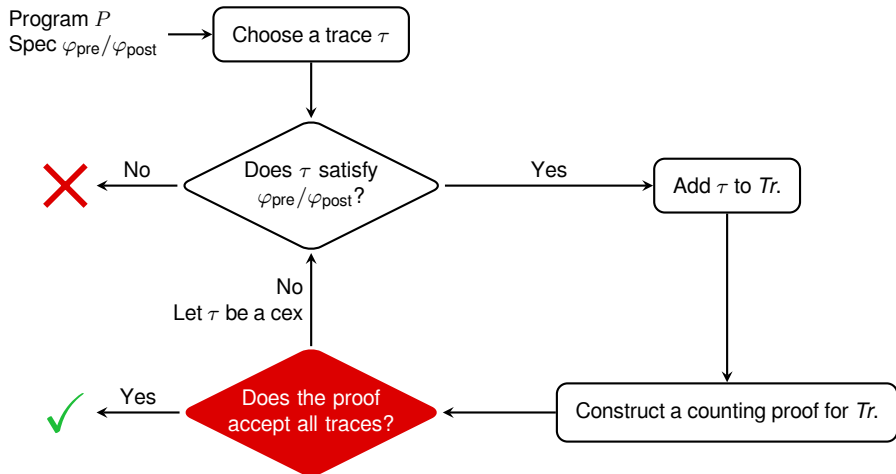
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Constructing a counting proof

Goal

Given a finite set of traces Tr and a spec $\varphi_{\text{pre}}/\varphi_{\text{post}}$, construct a counting proof $\langle A, \varphi \rangle$ such that $Tr \subseteq \mathcal{L}(A)$.

Constructing a counting proof requires us to find a counting automaton and an inductive annotation *simultaneously*.

- Insight #1: Bounded synthesis is decidable
 - Bound the size of the counting proof (think: # of states)
 - Encode bounded proof synthesis as a formula in a decidable theory (QF_UFNRA)
 - Use uninterpreted function symbols to encode the transition relation.
 - Use Farkas' lemma to generate constraints searching for an inductive annotation (*à la* Colón et al.^a)

^aLinear Invariant Generation using Non-linear Constraint Solving, CAV'03

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- Insight #2: Occam's Razor – search for a “small” proof. **More likely to generalize & use counters!**

$$\tau = t++; s++; t++; [t \leq s]$$

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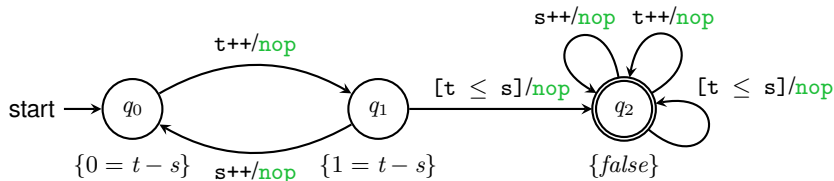
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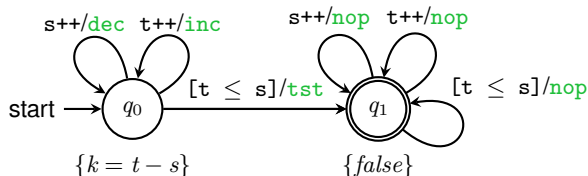
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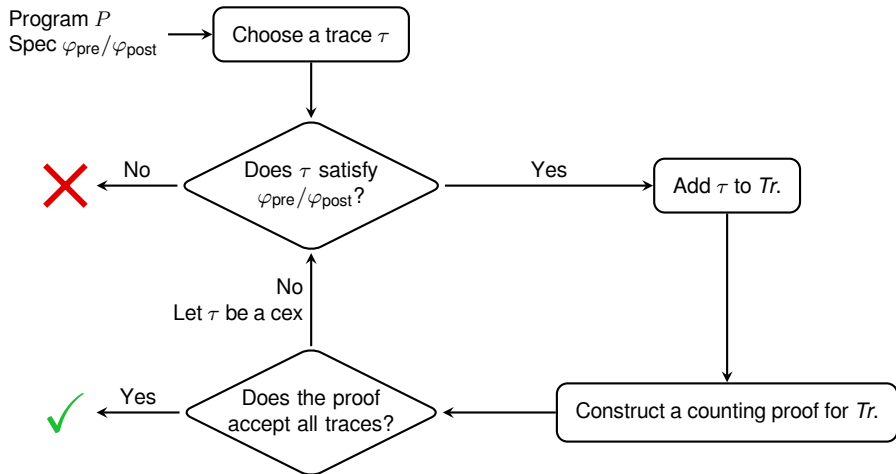
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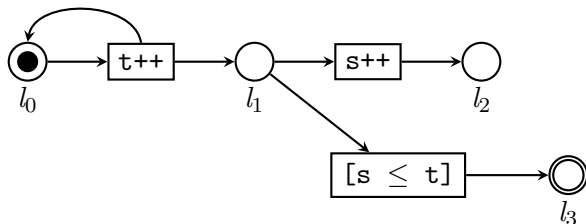


Control flow net = Petri net + program commands

Control flow nets

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3: s++		3: s++				3: s++



Represents the set of error traces for the program.

Theorem

Let P be a control flow net, and let A be a counting automaton. The problem of determining whether $\mathcal{L}(P) \subseteq \mathcal{L}(A)$ is decidable.

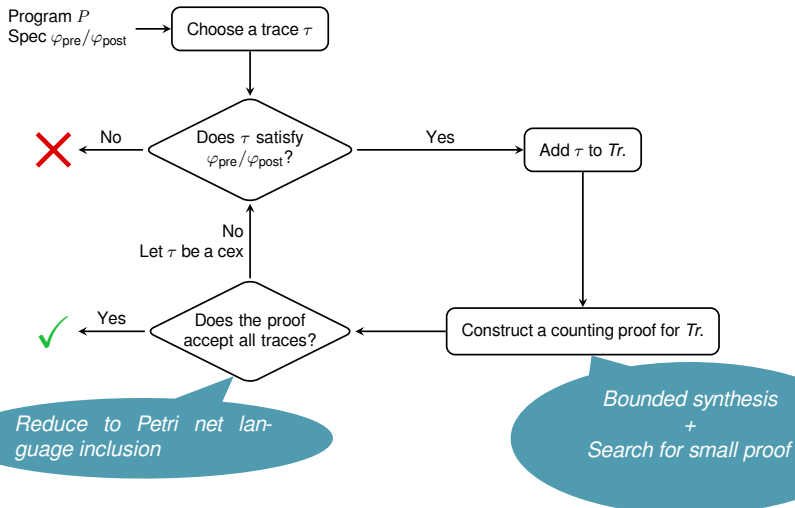
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- Reduction to Petri net language inclusion.

Summary

We can automate synthesis of a class of auxiliary variables!



What's next?

- Implementation & Evaluation
 - Practical algorithm for inclusion?
 - Ultimately, inclusion relies on a reduction to Petri net reachability.
 - Practical nonlinear constraint solving?
- Synthesize other classes of auxiliary variables?