

Compositional Recurrence Analysis Revisited

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How can we apply loop analyses to recursive procedures?

Over-approximating the behavior of loops

- Iterative program analysis [Cousot & Cousot POPL 1977]
 - Repeatedly evaluate the program under an abstract semantics until convergence upon a property that over-approximates all reachable states.

Over-approximating the behavior of loops

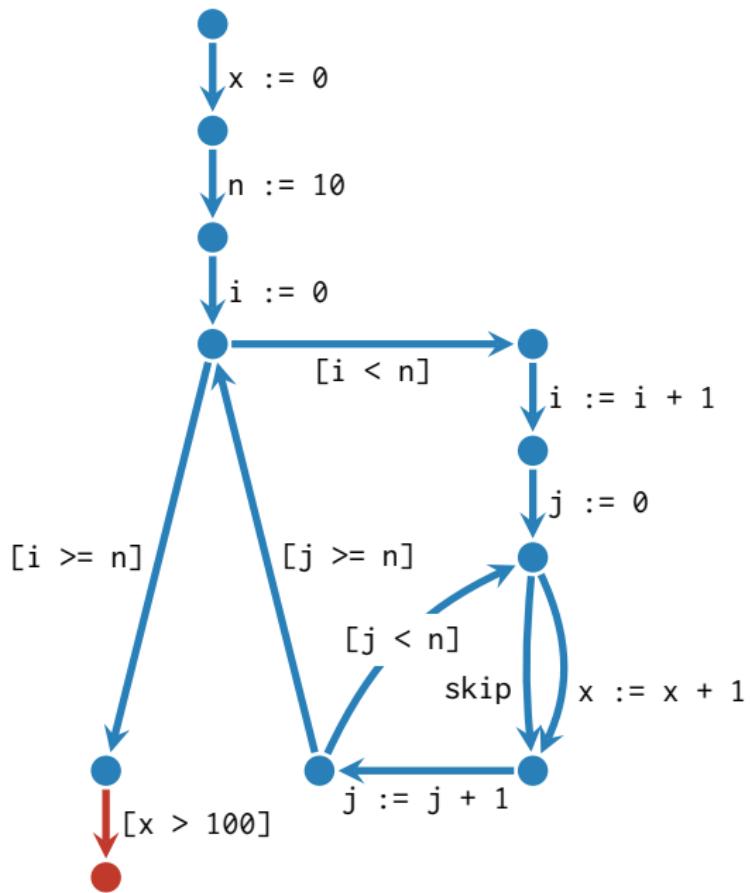
- Iterative program analysis [Cousot & Cousot POPL 1977]
 - Repeatedly evaluate the program under an abstract semantics until convergence upon a property that over-approximates all reachable states.
- Algebraic program analysis [Tarjan JACM 1981]
 - ① Compute a *path expression* to a point of interest (e.g., an assertion)
 - ② Evaluate the path expression in the *semantic algebra* defining the analysis to yield a property that over-approximates all paths.

```
x := 0
n := 10
i := 0
outer: if(i >= n):
        goto end
        i := i + 1
inner: j := 0
if(*):
        x := x + 1
        j := j + 1
        if(j < n):
                goto inner
        goto outer
end: assert(x <= 100)
```

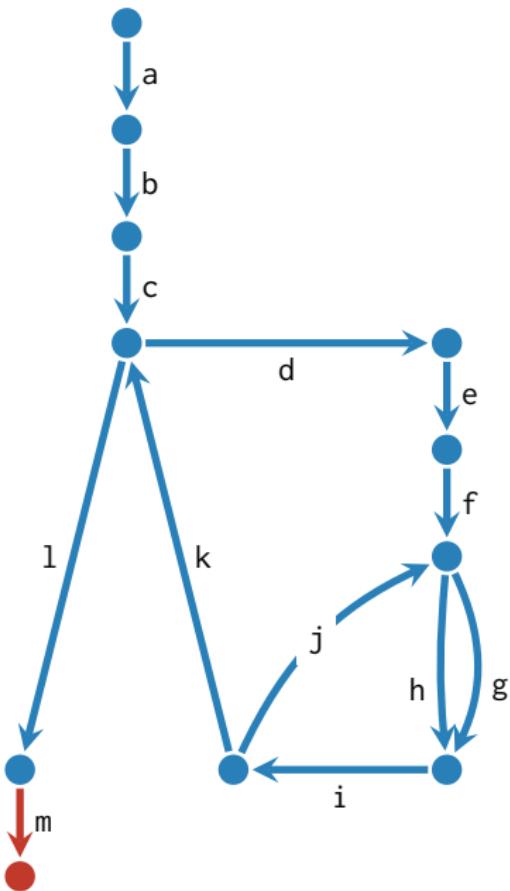
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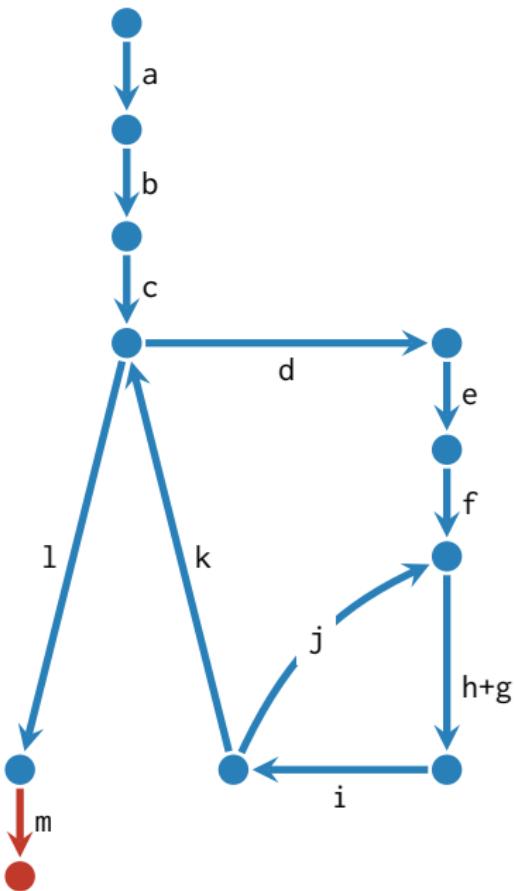
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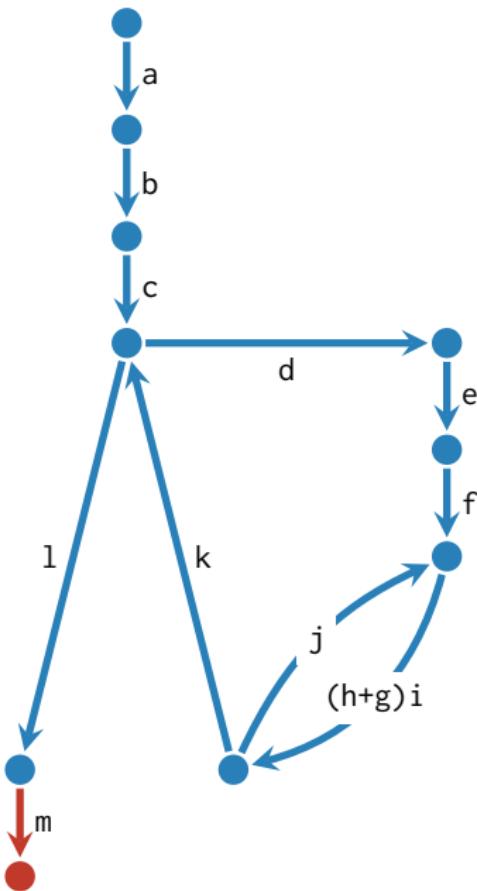
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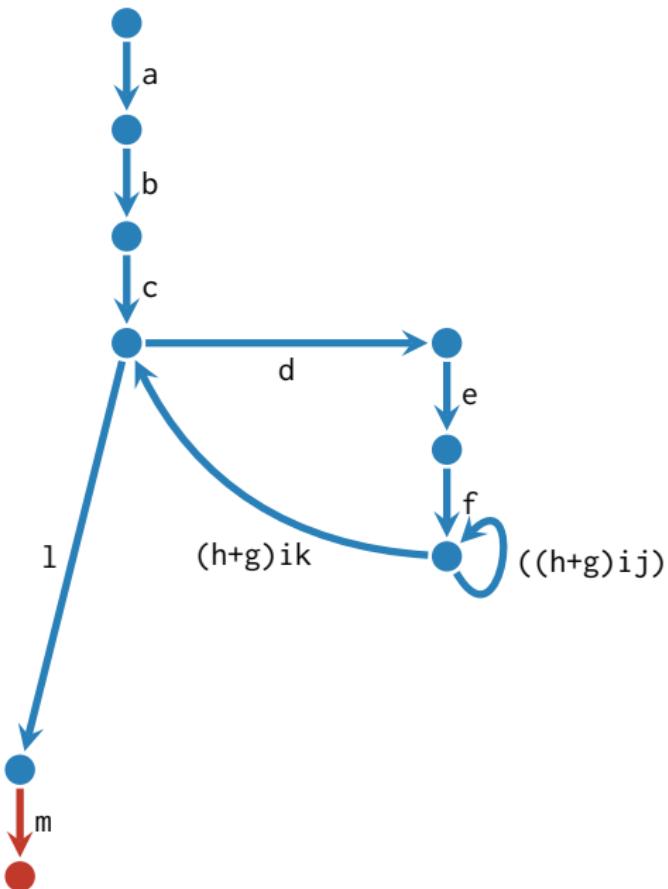
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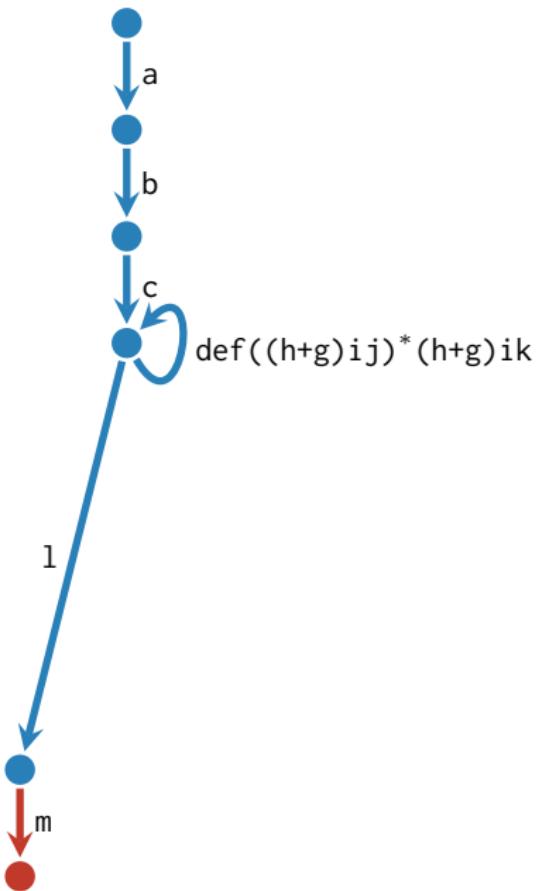
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abc(def((h+g)ij)* (h+g)ik)*lm

Path expression:

Regular expression over alphabet of control flow edges

Evaluation of a path expression:

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Composition operators

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$$\begin{aligned}\llbracket abc(def((h+g)ij)^*(h+g)ik)^*lm \rrbracket &= \llbracket a \rrbracket \otimes \llbracket b \rrbracket \otimes \llbracket c \rrbracket \\ &\quad \otimes \left(\llbracket d \rrbracket \otimes \llbracket e \rrbracket \otimes \llbracket f \rrbracket \right. \\ &\quad \left. \otimes ((\llbracket h \rrbracket \oplus \llbracket g \rrbracket) \otimes \llbracket i \rrbracket \otimes \llbracket j \rrbracket) \right)^* \\ &\quad \left. \otimes ((\llbracket h \rrbracket \oplus \llbracket g \rrbracket) \otimes \llbracket i \rrbracket \otimes \llbracket k \rrbracket) \right)^* \\ &\quad \otimes \llbracket l \rrbracket \otimes \llbracket m \rrbracket\end{aligned}$$

Compositional recurrence analysis [Farzan & Kincaid FMCAD 2015]

- D is the set of *transition formulas* in non-linear integer arithmetic

$$[\![x := x + 1]\!] \triangleq x' = x + 1 \wedge y' = y$$

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- $\varphi^* \triangleq \dots$

CRA's iteration operator

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while(i < n):  
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loop body ...

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loop abstraction ...

$$\exists k. k \geq 0 \wedge i' = i + k \wedge x' + y' = x + y + k(k+1)/2 + ki_0 \wedge x' \geq x \wedge y' \geq y$$

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recurrences

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$$i^{(k)} = i^{(0)} + k$$

$$x^{(k)} + y^{(k)} = x^{(0)} + y^{(0)} + \frac{k(k+1)}{2} + ki_0$$

$$x^{(k)} \geq x^{(0)}$$

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$$\exists k. k \geq 0 \wedge i' = i + k \wedge x' + y' = x + y + k(k+1)/2 + ki_0 \wedge x' \geq x \wedge y' \geq y$$

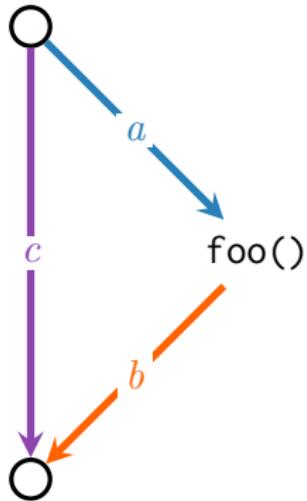
closed forms

loop abstraction

How can we apply CRA to recursive procedures?

Recursive procedures have non-regular path languages

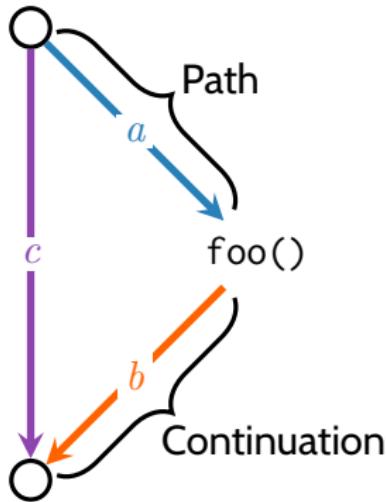
foo():



$$paths(\text{foo}) = \{a^i c b^i : i \geq 0\} \text{ is not regular!}$$

Tensor domains [Reps, Turetsky, Prabhu POPL 2016]

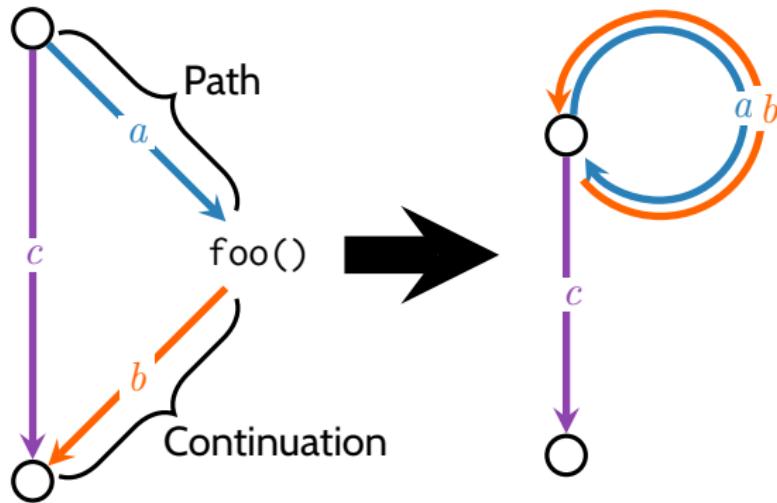
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A tensored path (p, k) is a pair consisting of a path p and a continuation k .

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Tensor product pairs a paths and continuations

$$P \odot K \triangleq \{(p, k) : p \in P, k \in K\}$$

Detensor product places a path between a path & continuation

$$Q \ltimes T \triangleq \{\textcolor{blue}{p} q \textcolor{orange}{k} : q \in Q, (\textcolor{blue}{p}, \textcolor{orange}{k}) \in T\}$$

For example, $c \ltimes (\textcolor{orange}{a} \odot \textcolor{blue}{b})^* = \{\textcolor{orange}{a}^i c \textcolor{blue}{b}^i : i \geq 0\}$.

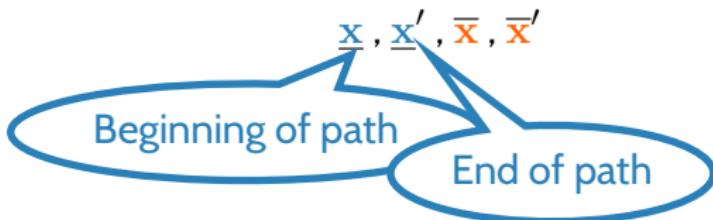
Tensor domain of CRA

Tensored transition formula \sim formula over *four* copies of the program variables

$$\underline{\mathbf{x}}, \underline{\mathbf{x}}', \bar{\mathbf{x}}, \bar{\mathbf{x}}'$$

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Tensor domain of CRA

Tensored
variables

Beginning of continuation

copies of the program

End of continuation

$\underline{x}, \underline{x}', \bar{x}, \bar{x}'$

Beginning of path

End of path

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- $\Phi \oplus \Psi, \Phi^*$ as for the untensored case
- $\varphi \odot \psi \triangleq \varphi[\mathbf{x} \mapsto \underline{\mathbf{x}}, \mathbf{x}' \mapsto \underline{\mathbf{x}}'] \wedge \psi[\mathbf{x} \mapsto \bar{\mathbf{x}}, \mathbf{x}' \mapsto \bar{\mathbf{x}}']$
 - E.g., $(x' = x + 1) \odot (y' = y + 2) = (\underline{x}' = \underline{x} + 1 \wedge \bar{y}' = \bar{y} + 2)$
- $\varphi \ltimes \Psi \triangleq \exists \underline{\mathbf{x}}, \underline{\mathbf{x}}', \bar{\mathbf{x}}, \bar{\mathbf{x}}'. \varphi[\mathbf{x} \mapsto \underline{\mathbf{x}}', \mathbf{x}' \mapsto \bar{\mathbf{x}}] \wedge \Phi[\underline{\mathbf{x}} \mapsto \mathbf{x}, \bar{\mathbf{x}}' \mapsto \mathbf{x}']$
 - E.g., $(y' = x) \ltimes (\underline{x}' = \underline{x} + 1 \wedge \bar{y}' = \bar{y} + 2) = (y' = x + 3)$

Solving non-linear recursive systems

```
fib(n):
    if(i > 1):
        f1 := fib(n-1)
        f2 := fib(n-2)
        return f1 + f2
    else
        return 1
```

Solving non-linear recursive systems

$\text{paths}(\text{fib}) \sim \text{least fixed point of } X = aXbXc + d$

Solving non-linear recursive systems

$\text{paths}(\text{fib}) \sim \text{least fixed point of } X = aXbXc + d$

[Reps, Turetsky, Prabhu POPL 2016] solves this via *Newton iteration*:

Solve a sequence of *linearized* systems until convergence on a property that over-approximates all paths.

..... Newton iteration

$$\nu_0 = 0$$

$$\nu_1 = d \ltimes ((a \odot b\nu_0 c) \oplus (a\nu_0 b \odot c))^*$$

$$\nu_2 = d \ltimes ((a \odot b\nu_1 c) \oplus (a\nu_1 b \odot c))^*$$

⋮

(repeat until $\nu_{n+1} = \nu_n$)

The problem with Newton iteration

- ① Transition formulas have infinite ascending chains (convergence is not guaranteed)
- ② Transition formula equivalence is undecidable (convergence can't be detected)

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while(i < n):  
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$$\begin{array}{l} \text{loop body} \\ \boxed{i < n \wedge \left(\begin{array}{l} x' = x + i \wedge y' = y \\ \vee y' = y + i \wedge x' = x \end{array} \right) \wedge i' = i + 1 \wedge n' = n} \end{array}$$

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Polyhedron

α

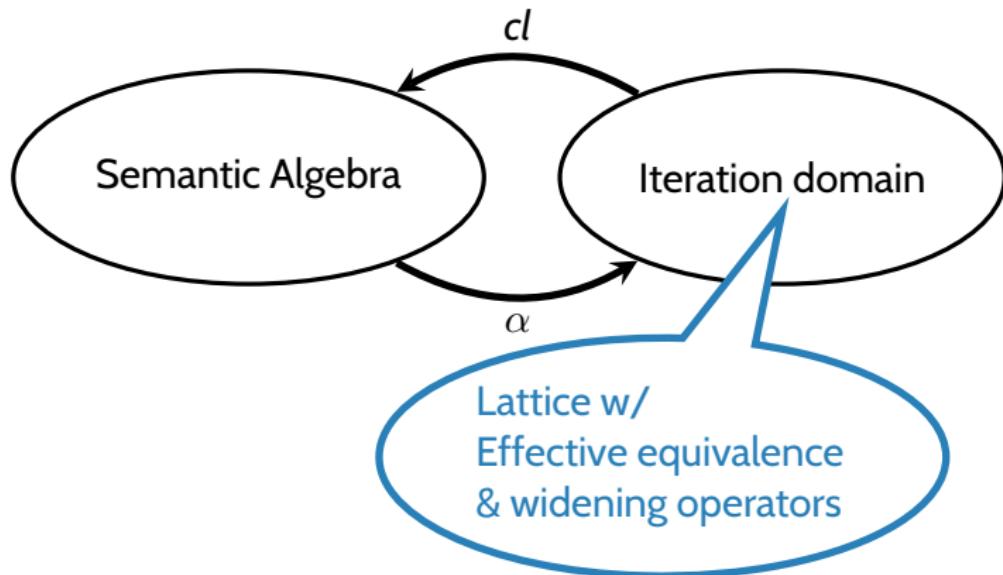
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Iteration domains

$$\varphi^* = \text{cl}(\alpha(\varphi))$$

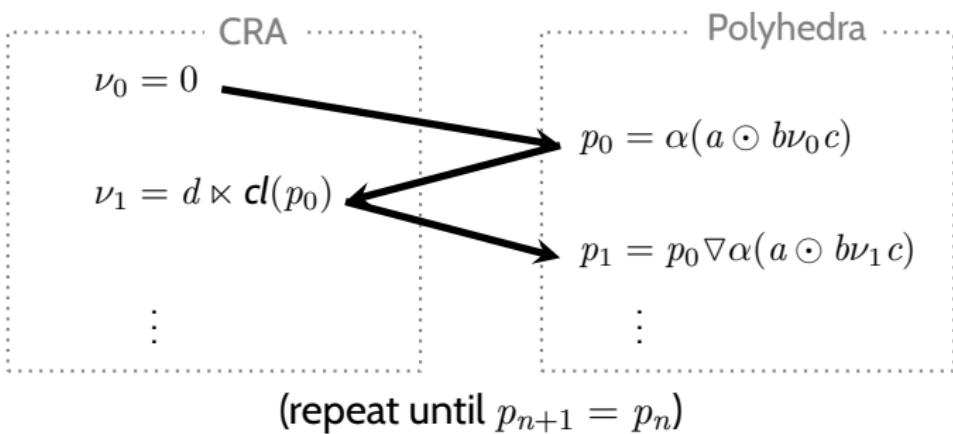


*Key idea: we have an opportunity to detect / enforce convergence at every place we apply the * operator.*

$$X = aXbXc + d \rightsquigarrow X = d \ltimes (a \odot bXc)^*$$

All variables appear below *

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Over-approximating recursive procedures

Given a system of recursive equations describing a set of paths,

- ① Using the tensor domain, rewrite the system so that every variable appears below a star (similar to Gauss-Jordan elimination)
- ② Compute solution to resulting system iteratively, using iteration domains to detect and enforce convergence.

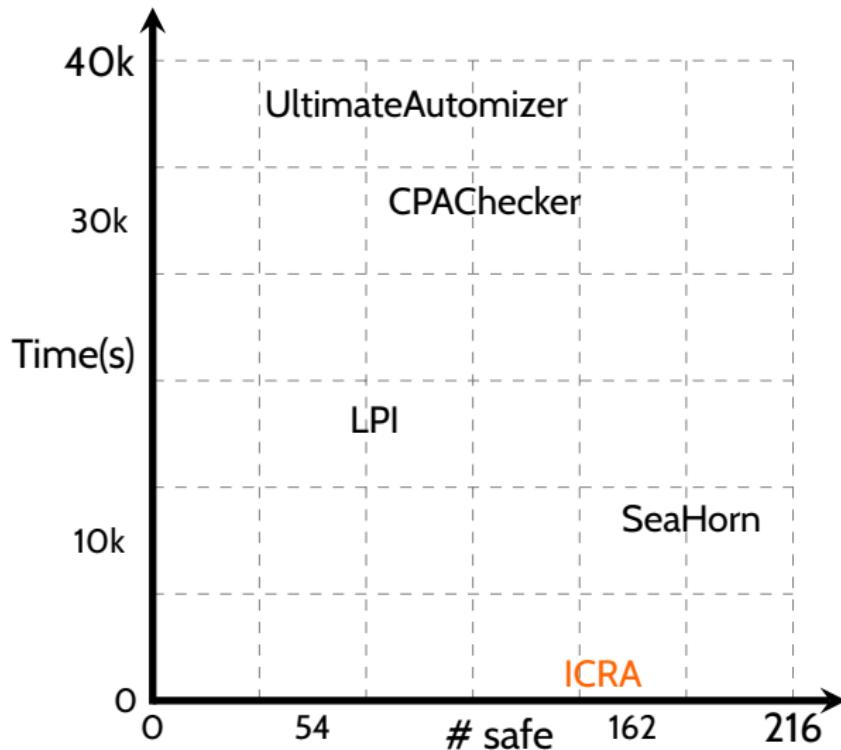
Implementation & Evaluation

ICRA was implemented on top of CRA and WALi

- (uses Cil C frontend, Z3 SMT solver, Apron abstract domain library)

Experimental set-up

- Ran on 216 *safe* benchmarks collected from SV-Comp, C4B (resource bound verification problems), and misc examples
- Compare with SeaHorn, CPAChecker, LPI, Ultimate Automizer



Summary

Algebraic analyses can be extended to recursive procedures using

- ① *Tensor domains*, to re-arrange recursion into loops
- ② *Iteration domains*, to detect and enforce convergence

Experimental results

Benchmark Suite	Total	ICRA		UAut.		CPA		LPI		SEA	
	#A	Time	#A	Time	#A	Time	#A	Time	#A	Time	#A
recursive	18/7	40.7	7	1952.1	8	1817.8	10	62.0	0	1334.0	14
rec.-simple	36/38	168.7	21	6979.3	28	2760.4	32	179.5	3	743.8	36
Rec. (tot.)	54/45	209.4	28	8931.4	36	4578.1	42	241.5	3	2077.8	50
loop-accel.	19/16	20.8	13	6696.5	7	4565.7	13	4227.7	13	2713.1	15
loop-invgen	18/1	53.1	16	1876.2	7	4909.6	2	1282.3	15	506.0	16
loop-lit	15/1	316.5	12	2722.9	5	2720.6	7	444.9	13	305.2	13
loops	34/32	209.7	22	3984.1	19	4380.1	28	3356.8	26	1821.5	27
loop-new	8/0	304.8	7	2147.9	1	1866.1	3	929.6	4	302.8	6
Loops (tot.)	94/50	904.8	70	17427.6	39	18442.2	53	10241.3	71	5648.6	77
C4B	35/0	30.3	30	6156.6	1	7817.8	2	6726.7	0	1867.6	29
misc	10/4	76.7	10	492.2	8	334.4	7	332.2	1	5.3	10
rec-loop-lit	15/1	312.7	9	2755.5	3	51.0	6	40.4	0	922.6	12
rec-loop-new	8/0	6.2	5	1546.9	2	25.6	2	19.6	0	905.7	4
Misc.-Rec.	33/5	395.6	24	4794.6	13	410.9	15	392.2	1	1833.7	26