

An Improved LP-Based Approximation for Steiner Tree

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Joint work with

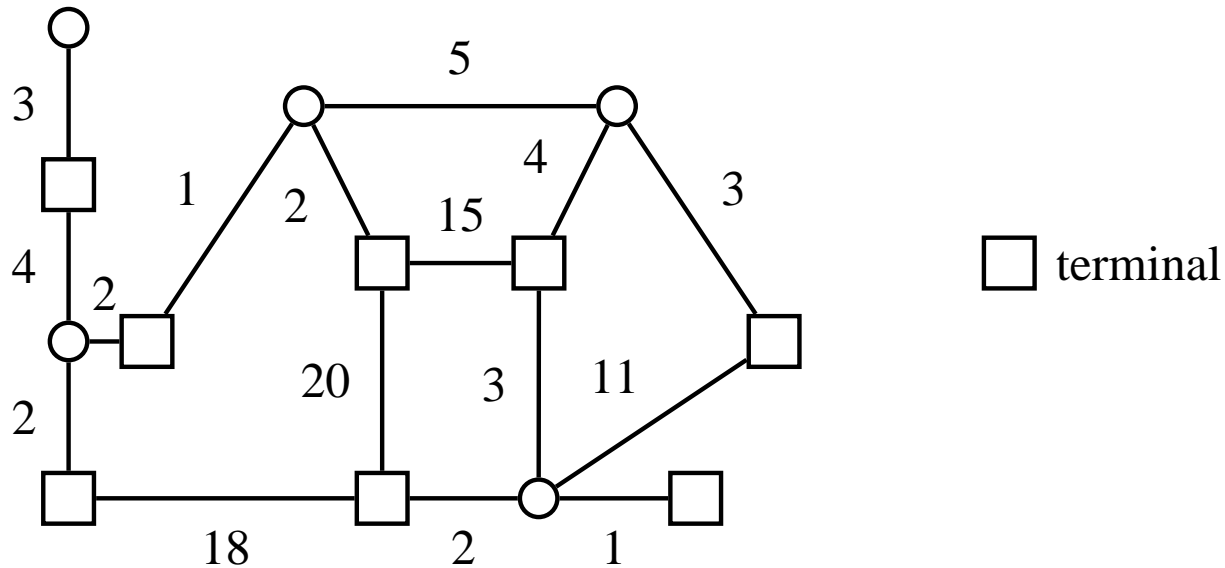
J. Byrka, T. Rothvoß, L. Sanità

The Steiner Tree Problem

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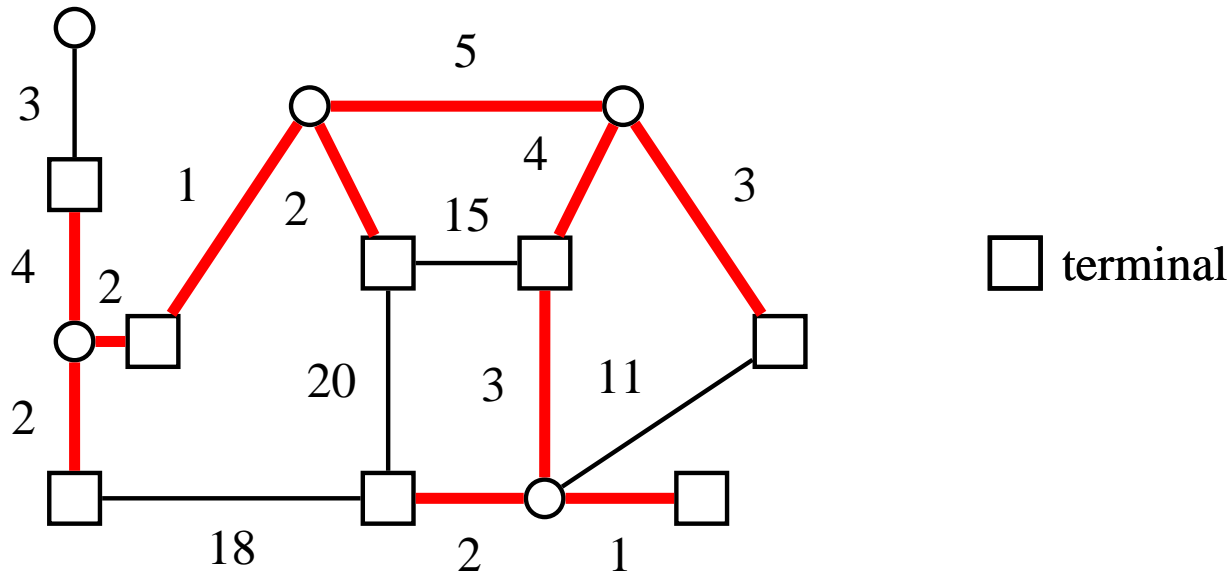
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Known Results

Hardness:

- NP-hard even for edge costs in $\{1, 2\}$ [Bern&Plassmann'89]
- no $< \frac{96}{95}$ -apx unless P=NP [Chlebik&Chlebikova'02]

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Approximation:

- 2-apx [minimum spanning tree heuristic]
- 1.83-apx [Zelikovsky'93]
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Integrality gap:

- ≤ 2 [Goemans&Williamson'95, Jain'98]

Our Results and Techniques

Thr There is an (LP-based) deterministic $\ln 4 + \varepsilon < 1.39$ approximation for the Steiner tree problem

- Here we show an expected $1.5 + \varepsilon$ apx

Thr There is an LP-relaxation for Steiner tree with integrality gap at most $1 + \ln(3)/2 < 1.55$

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- **Directed-Component Cut Relaxation**

- ◇ bidirected cut relaxation
- ◇ k -components

- **Iterative Randomized Rounding**

- ◇ randomized rounding
- ◇ iterative rounding



Directed-Component Cut Relaxation

Bidirected Cut Relaxation

- We select a **root** $r \in R$ and bi-direct the edges. Then

$$\min \sum_{e \in E} c(e) z_e \quad (\text{BCR})$$

$$\sum_{e \in \delta^+(U)} z_e \geq 1 \quad \forall U \subseteq V - r, U \cap R \neq \emptyset$$

$$z_e \geq 0 \quad \forall e \in E$$

- $\delta^+(U) = \{ab \in E : a \in U \text{ and } b \notin U\}$

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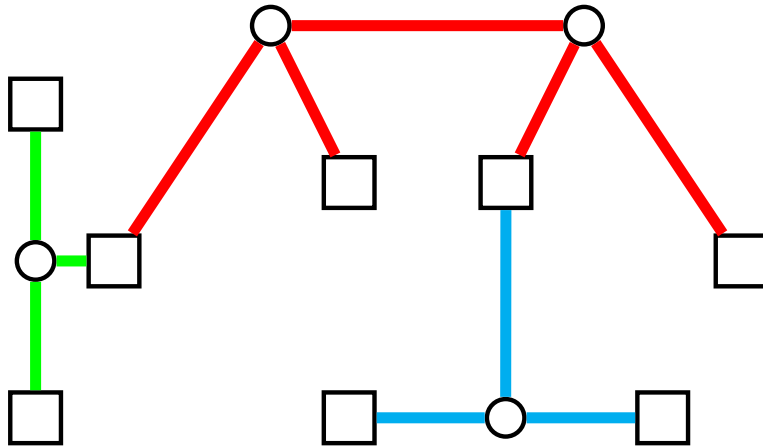
Thr [Edmonds'67] For $R = V$, BCR is integral

Rem the undirected version has integrality gap 2 even for $R = V$

Components

Def A **component** of a Steiner tree is a maximal subtree whose terminals coincide with its leaves

- A **k-component** is a component with at most k terminals
- A Steiner tree made of k -components is **k-restricted**.



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Thr [Borchers & Du'97] If opt_k and opt are the costs of an optimal k -restricted Steiner tree and an optimal Steiner tree, respectively, then

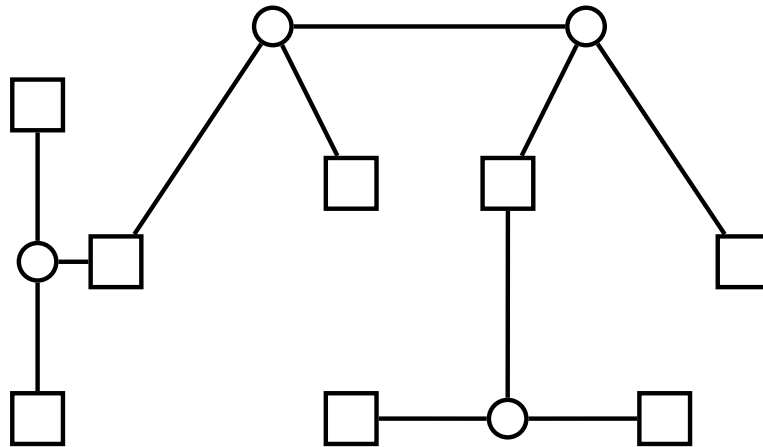
$$opt_k \leq \left(1 + \frac{1}{\lfloor \log_2 k \rfloor} \right) opt$$

Directing Components

- Direct the edges of an optimal Steiner tree towards a root terminal $r \in R$. This way we obtain **directed components**

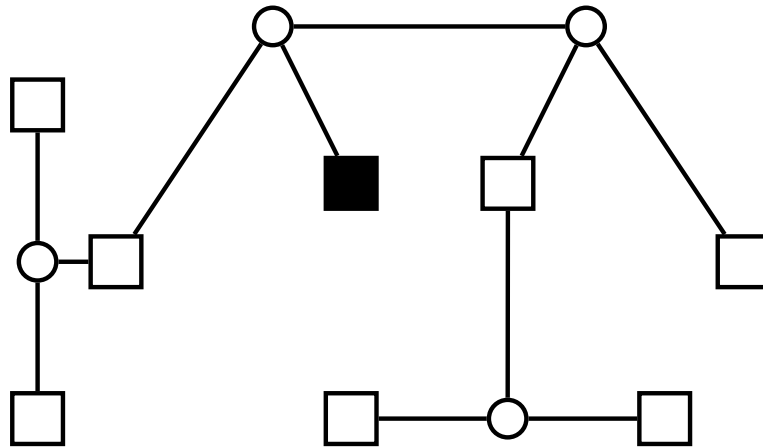
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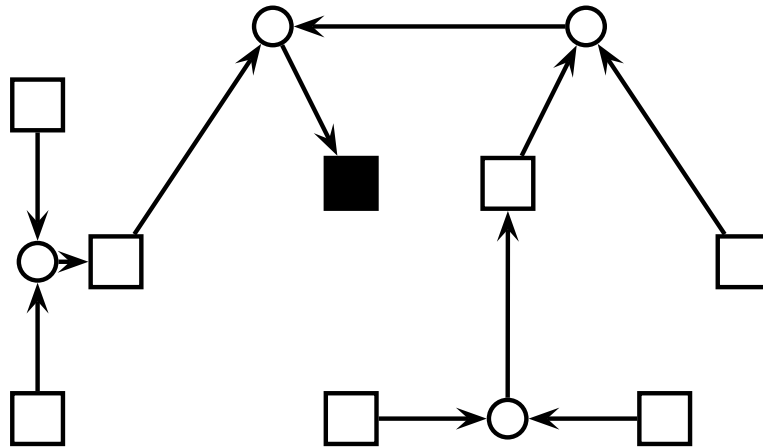
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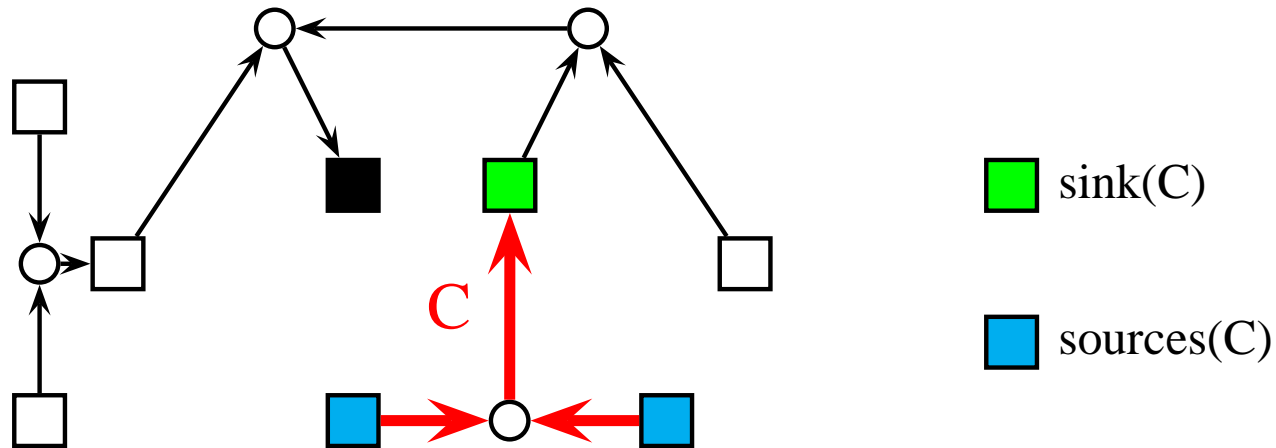
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Directed-component Cut Relaxation

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- \mathcal{C} is the set of candidate directed components
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Lem A $(1 + \varepsilon)$ approximation of the optimal fractional solution opt^f to DCR can be computed in polynomial time

Lem The cost of a minimum terminal spanning tree is $\leq 2 opt^f$

Lem DCR is strictly stronger than BCR



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Rem In **randomized rounding** variables are rounded randomly and (typically) simultaneously

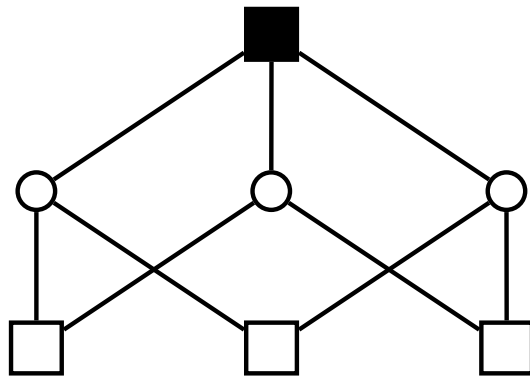
Rem In **iterative rounding** variables are rounded deterministically and (typically) one at a time

Algorithm IRR

- For $t = 1, 2, \dots$
 - ◇ Compute a $(1 + \varepsilon)$ -apx solution x^t for DCR
 - ◇ Sample a component $C = C^t$ with probability
$$p_C^t := x_C^t / \sum_{D \in \mathcal{C}} x_D^t$$
 - ◇ Contract C^t and update DCR consequently
 - ◇ If there is only one terminal, output the sampled components

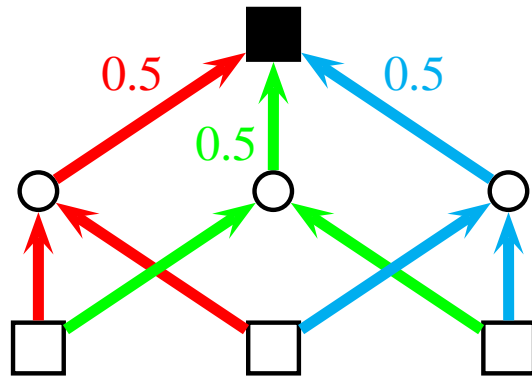
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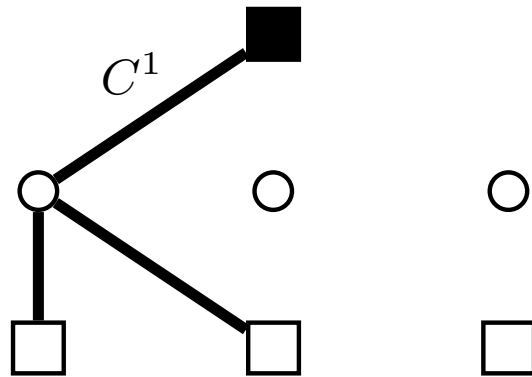
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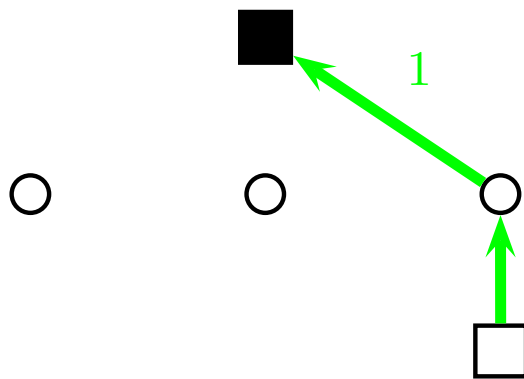
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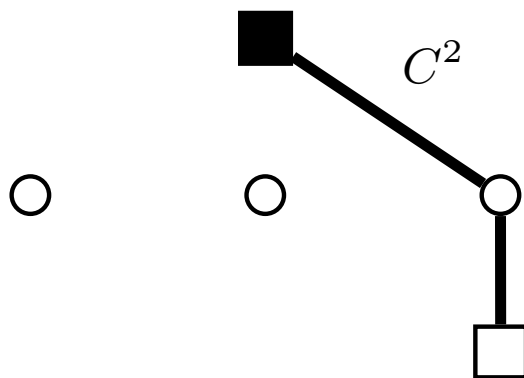
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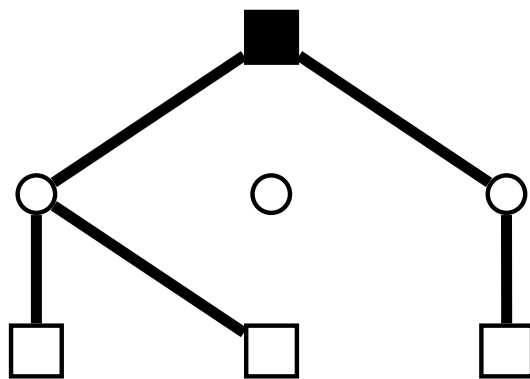
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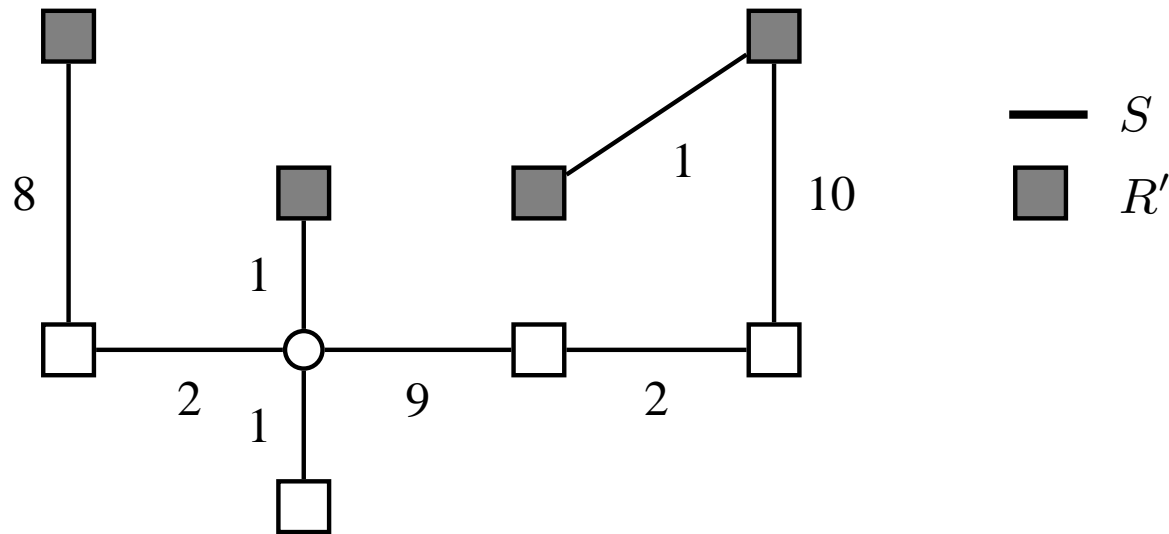
Rem By adding a dummy component in the root, we can assume w.l.o.g. that $M := \sum_{D \in \mathcal{C}} x_D^t$ is fixed for all t



Bridge Lemma

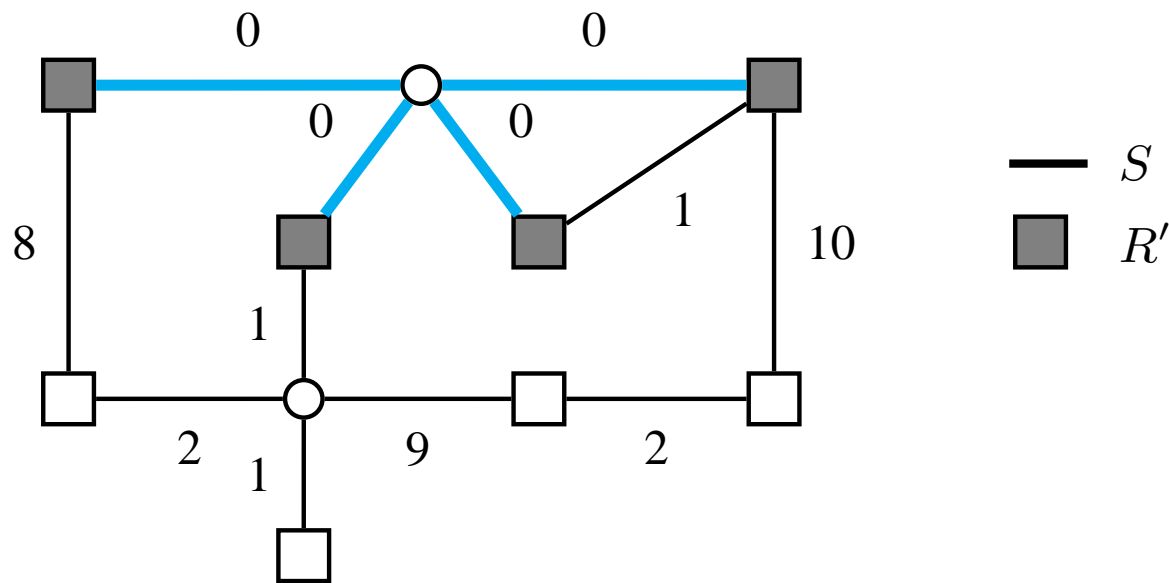
Bridges

Def Given a Steiner tree S and $R' \subseteq R$, the **bridges** $br_{S,c}(R')$ of S w.r.t. R' (and edge costs c) are the edges of S which do not belong to the minimum spanning tree of $V(S)$ after the contraction of R'



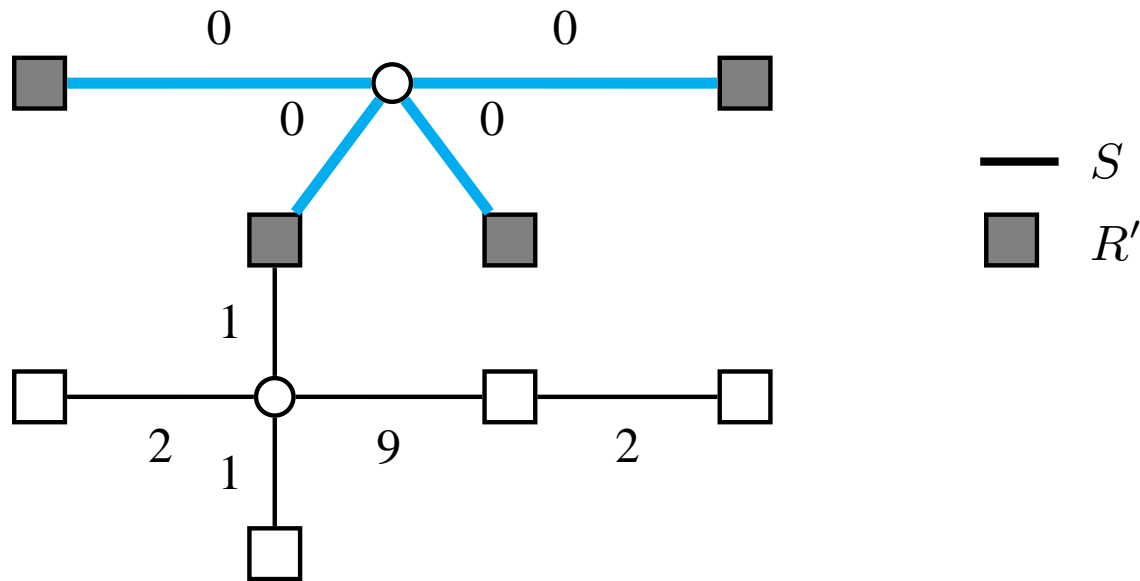
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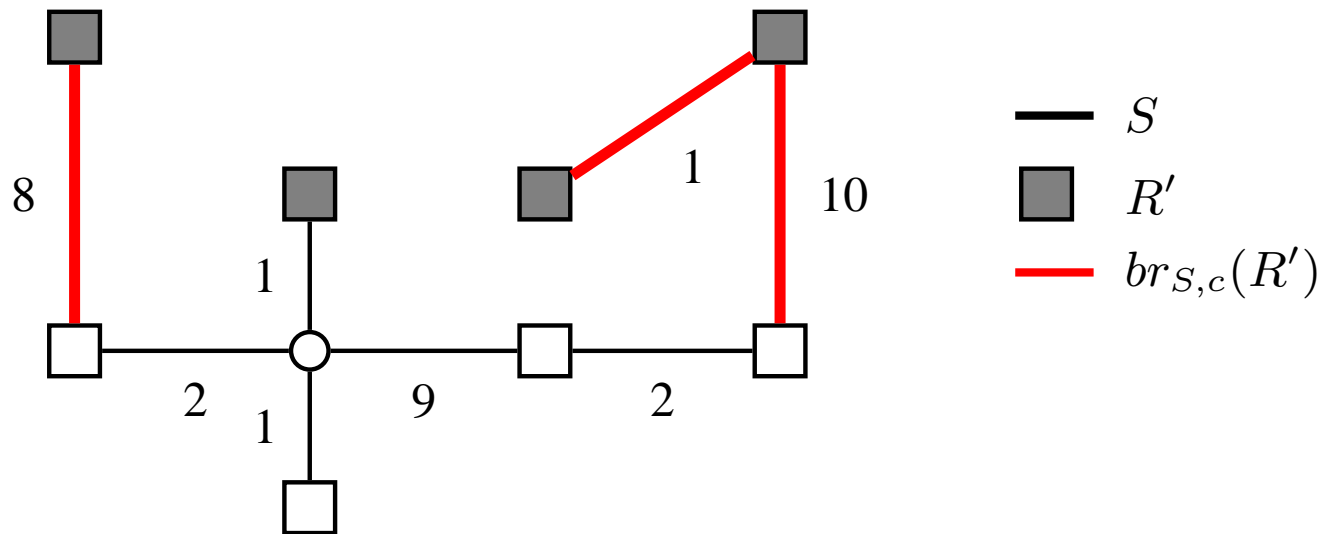
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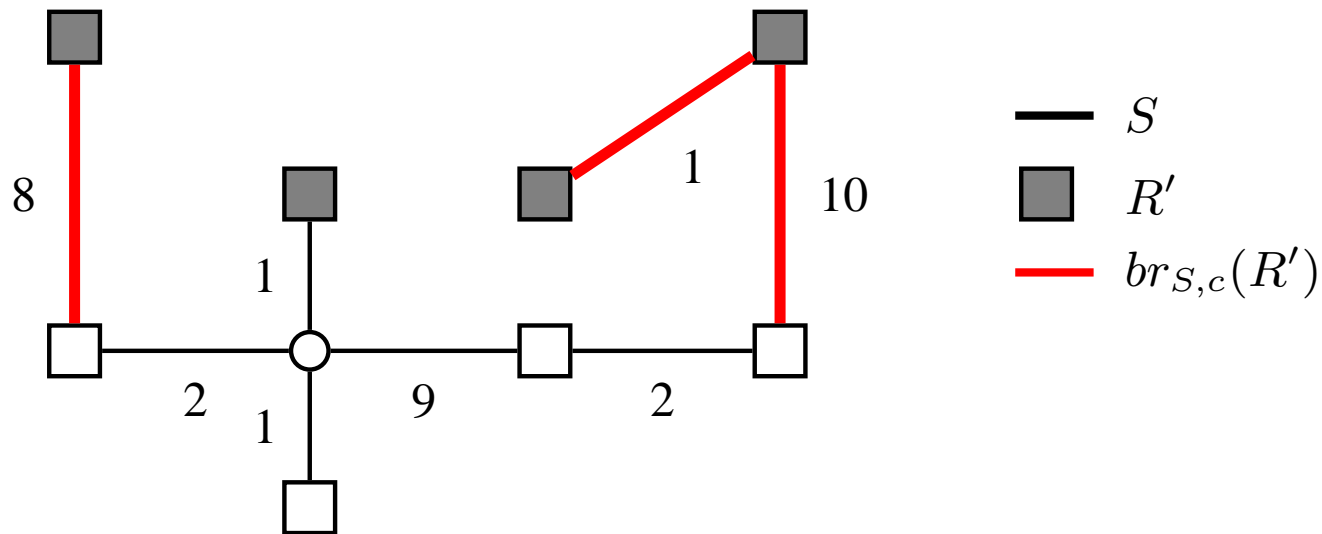
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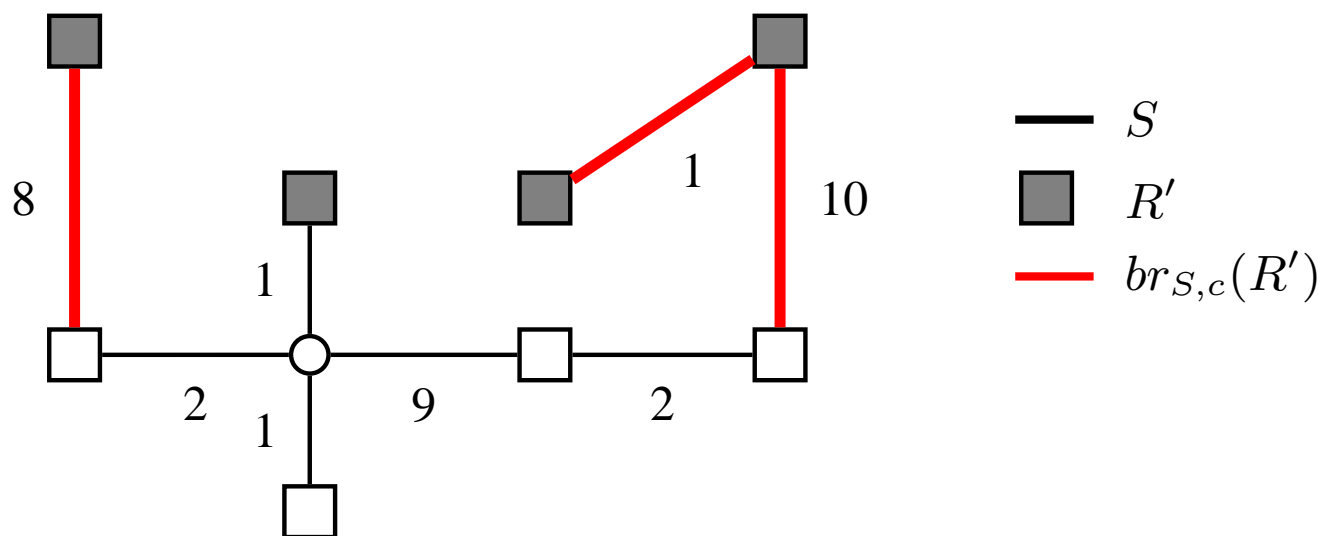
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Rem The most expensive edge on a path between two gray nodes is a bridge

Bridges

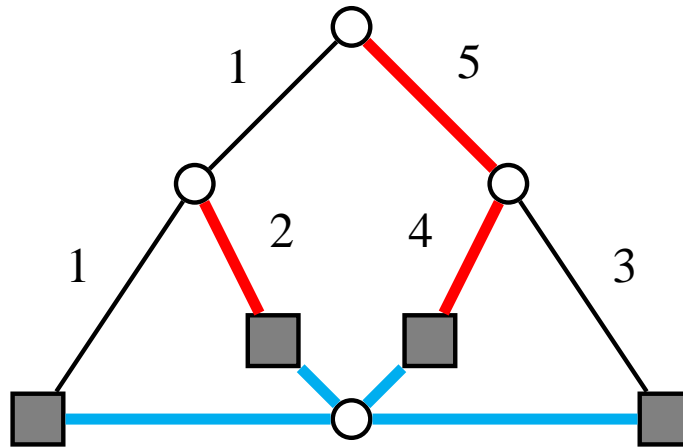
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Rem Let $br_S(R') = br_{S,c}(R')$, $br_S(R') := c(br_S(R'))$ and $br_S(C) := br_S(R \cap C)$.

Bridges

Lem For any Steiner tree S on R , $br_S(R) \geq \frac{1}{2}c(S)$



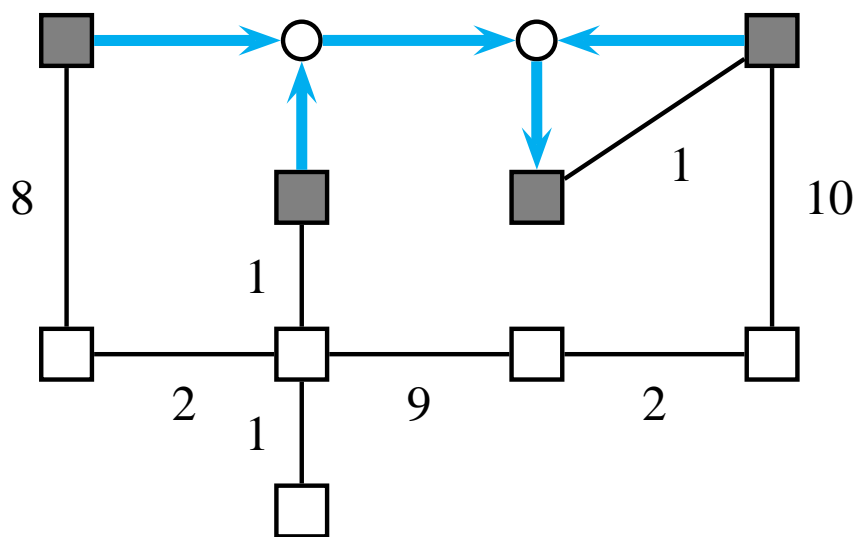
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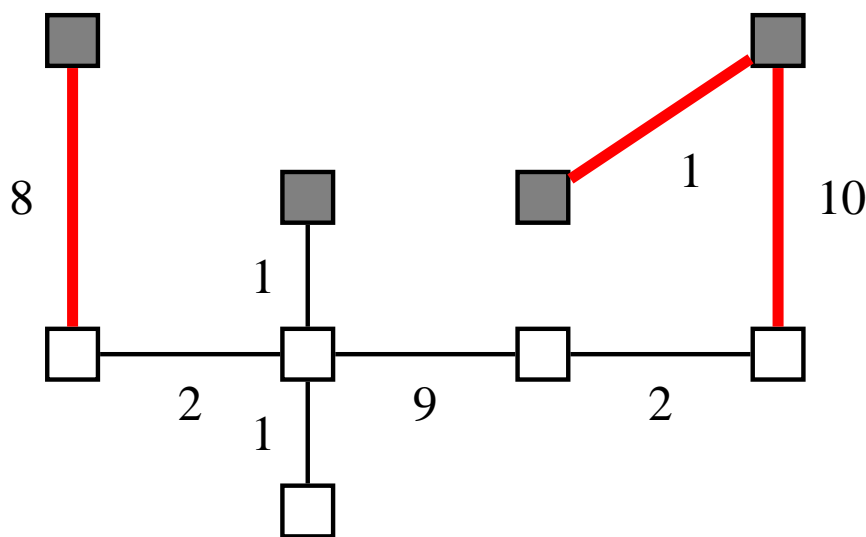
- For every $C \in \mathcal{C}$, with capacity x_C , construct a directed terminal spanning tree Y_C on $R \cap C$, with capacity x_C and edge weights w , as follows



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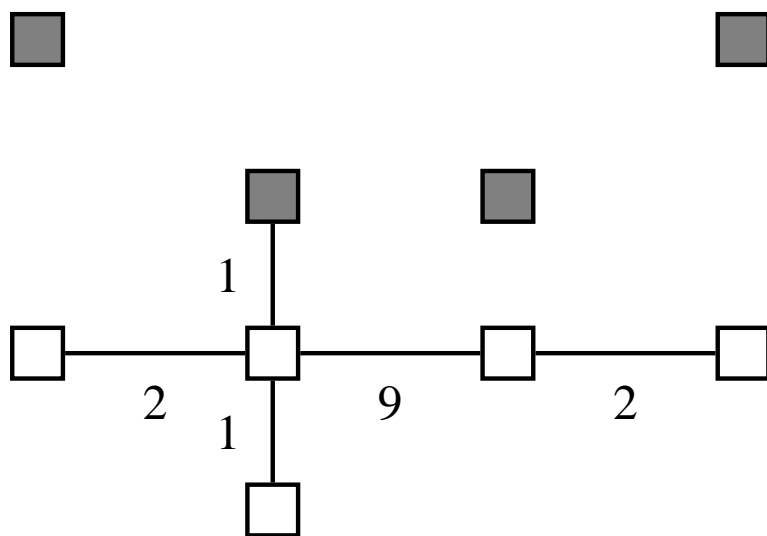
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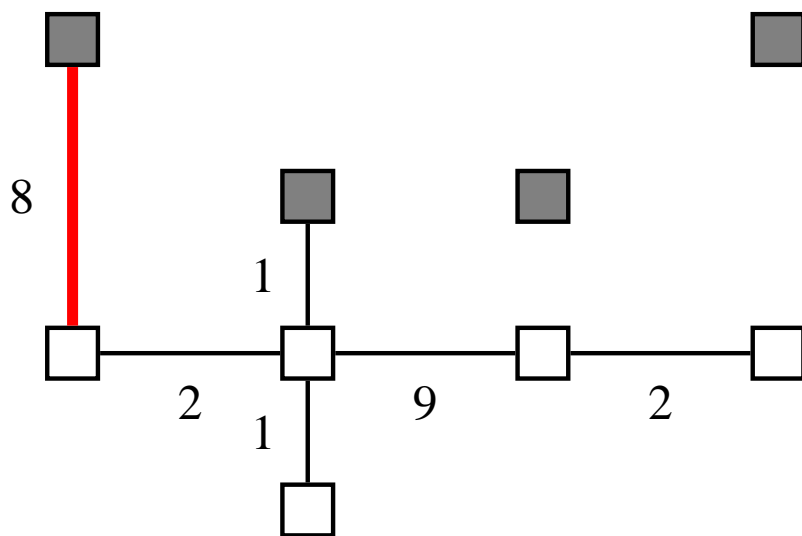
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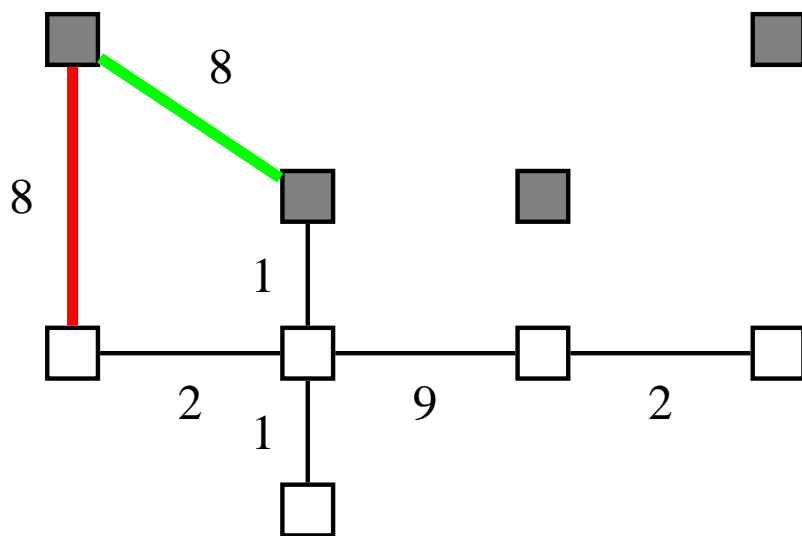
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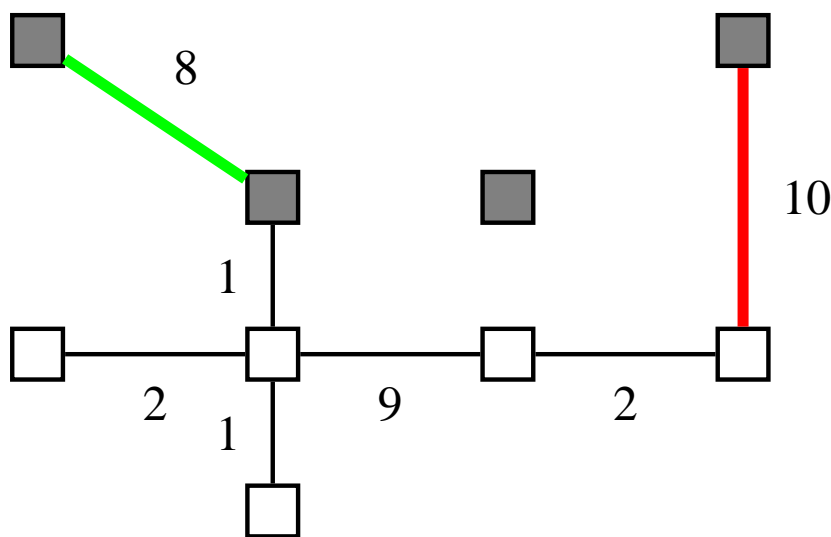
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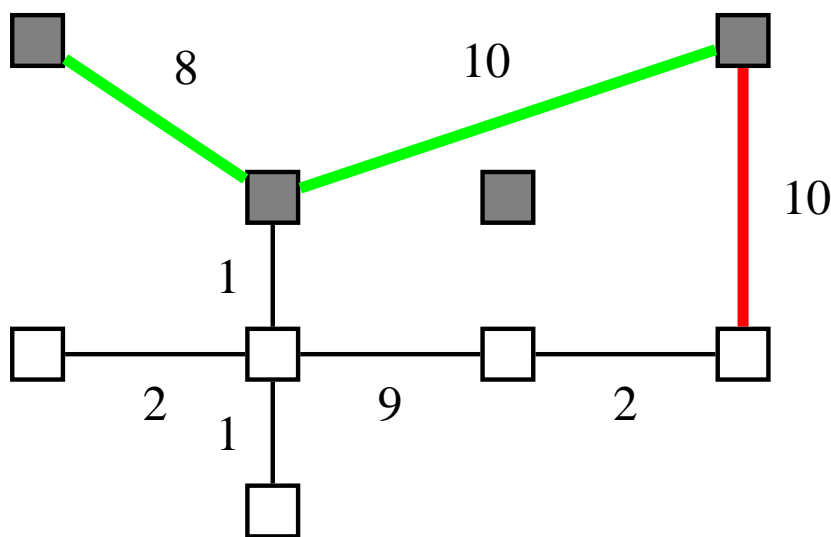
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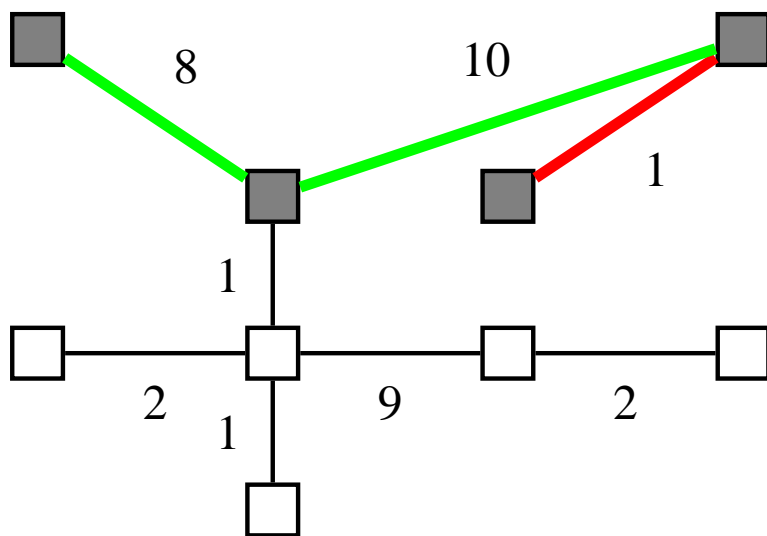
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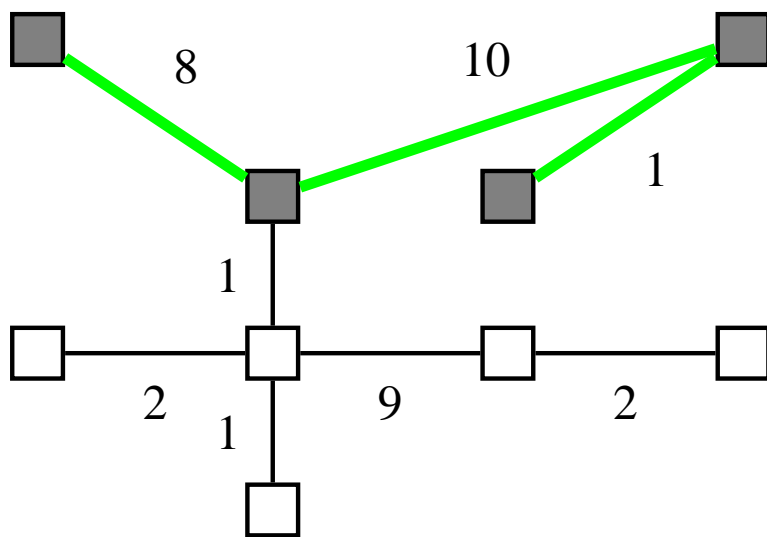
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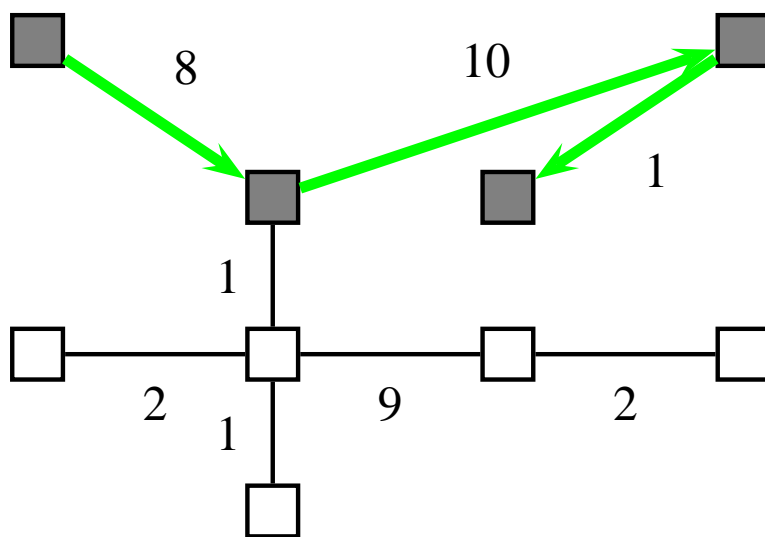
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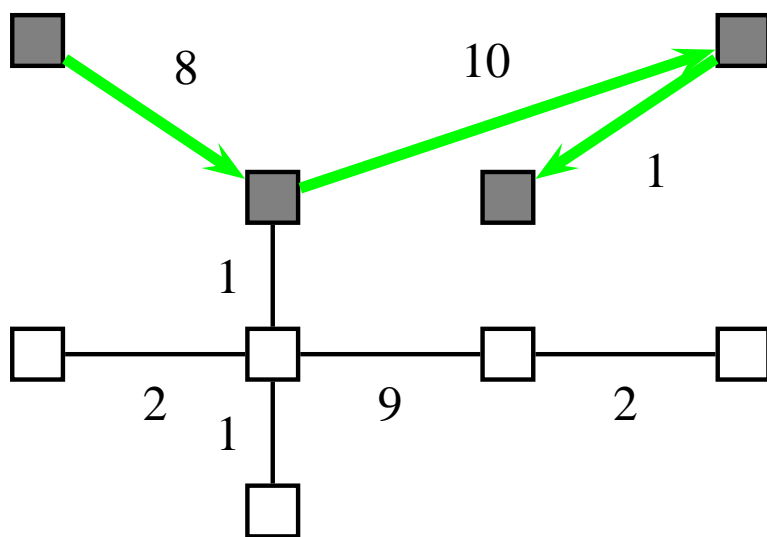
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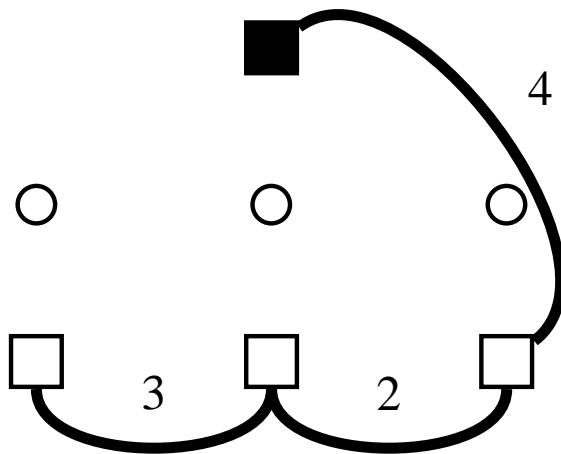
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Rem Y_C supports the same flow to the root as C w.r.t. terminals

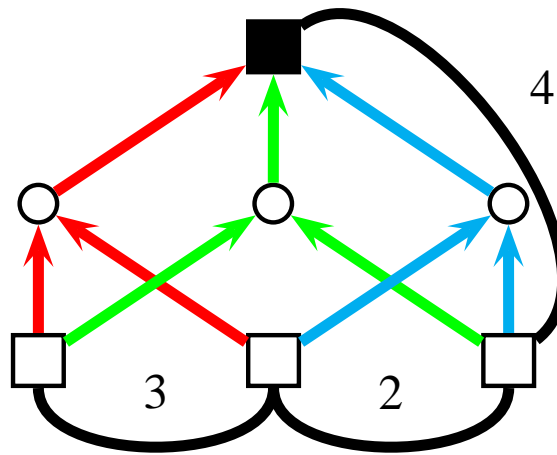
The Bridge Lemma

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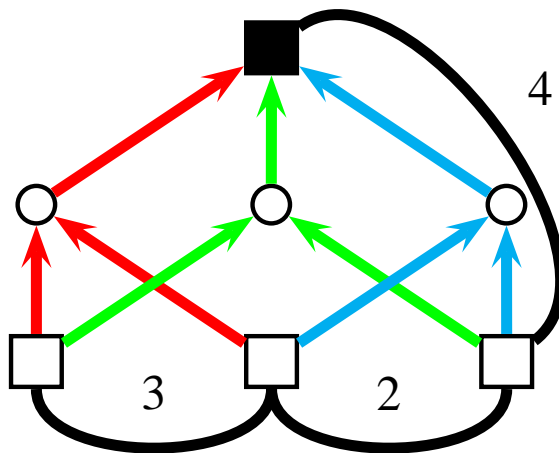
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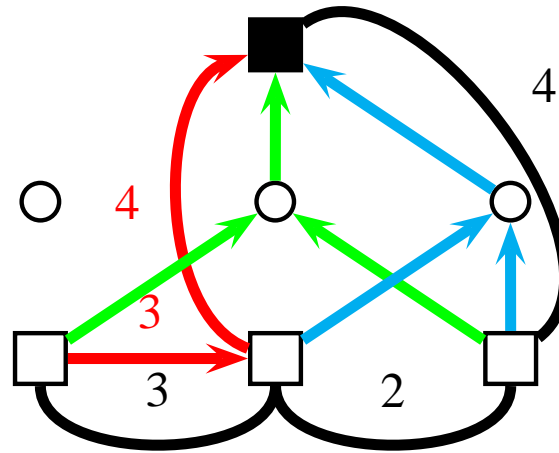
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- Replace each component C with the corresponding Y_C (cumulating capacities)

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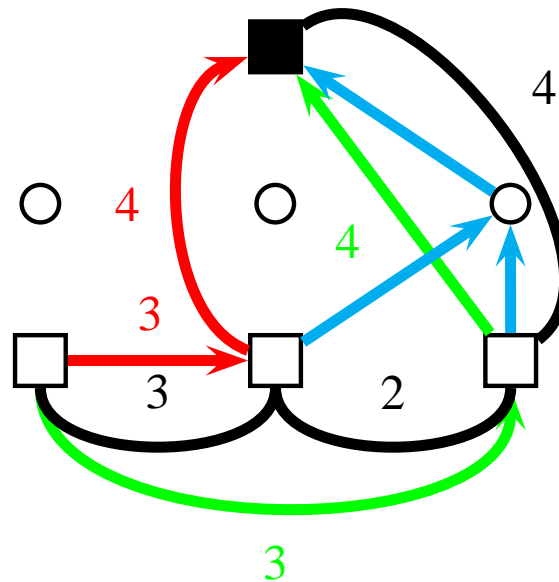
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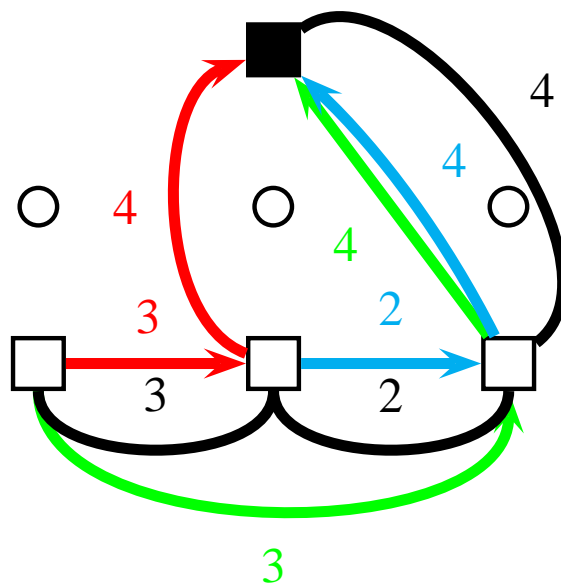
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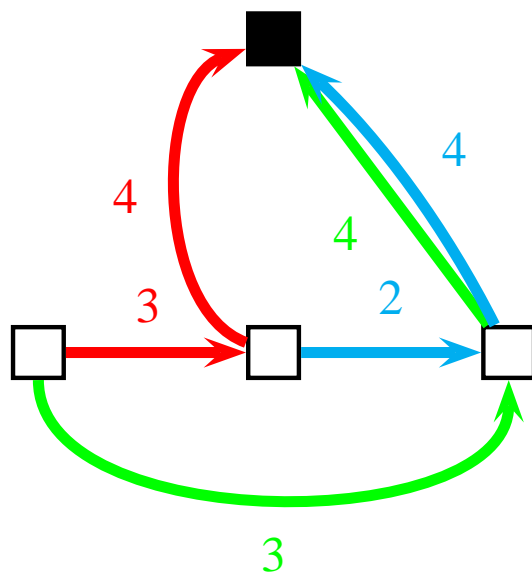
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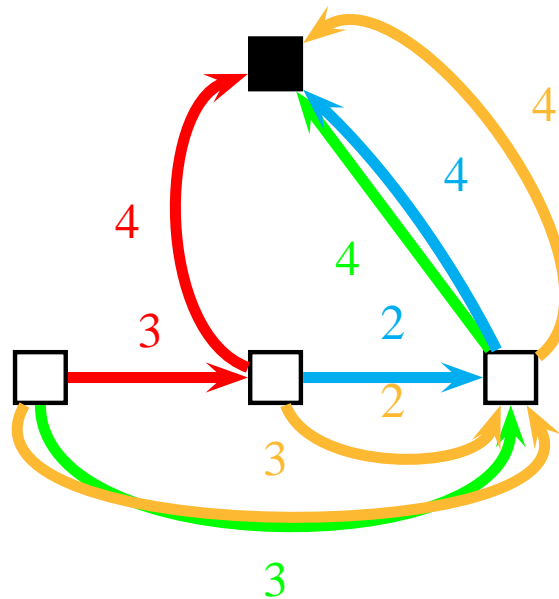
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- We obtain a feasible fractional directed terminal spanning tree on a directed graph with $V = R$ and edge costs w

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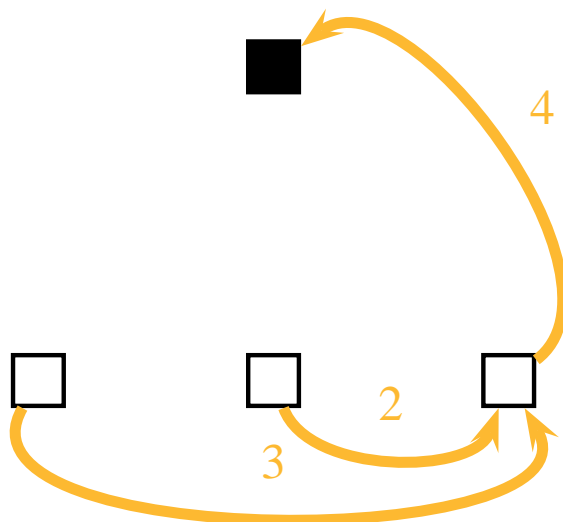
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- ⇒ By Edmod's thr there is a cheaper (w.r.t. w) integral directed terminal spanning tree F

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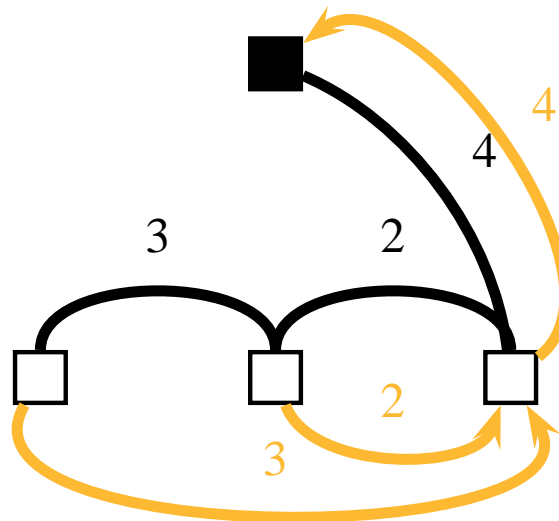
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- The new terminal spanning tree F is more expensive than the original terminal spanning tree T by the cycle-rule

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- Summarizing

$$\sum_{C \in \mathcal{C}} x_C \cdot br_T(C) = \underbrace{\sum_{C \in \mathcal{C}} x_C \cdot w(Y_C)}_{\substack{w\text{-cost of} \\ \text{fractional} \\ \text{terminal} \\ \text{spanning tree}}} \geq \underbrace{w(F)}_{\substack{w\text{-cost of} \\ \text{integral} \\ \text{terminal} \\ \text{spanning tree}}} \geq c(T)$$



Approximation Factor

A First Bound

Thr Algorithm IRR computes a solution of expected cost
 $\leq (1 + \ln 2 + \varepsilon) \text{opt}^f$

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Cor The integrality gap of DCR is at most $1 + \ln 2 < 1.7$

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$$\begin{aligned} E[\text{apx}] &= \sum_{t \geq 1} E[c(C^t)] \leq \sum_{t \geq 1} E\left[\sum_C \frac{x_C^t}{M} c(C)\right] \leq \frac{1 + \varepsilon}{M} \sum_{t \geq 1} E[\text{opt}^{f,t}] \\ &\leq \frac{1 + \varepsilon}{M} \sum_{t=1}^{M \ln 2} \text{opt}^f + \frac{1 + \varepsilon}{M} \sum_{t > M \ln 2} E[c(T^t)] \end{aligned}$$

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Rem This bound might not hold w.r.t. opt^f

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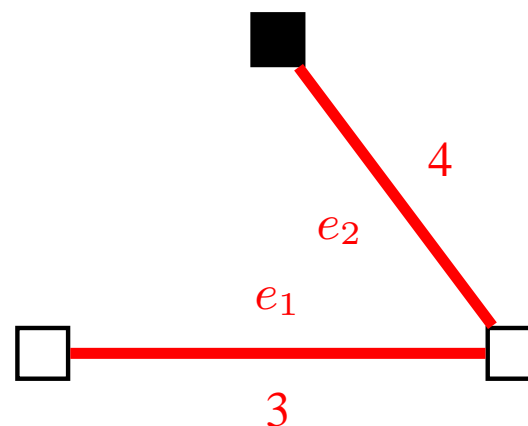
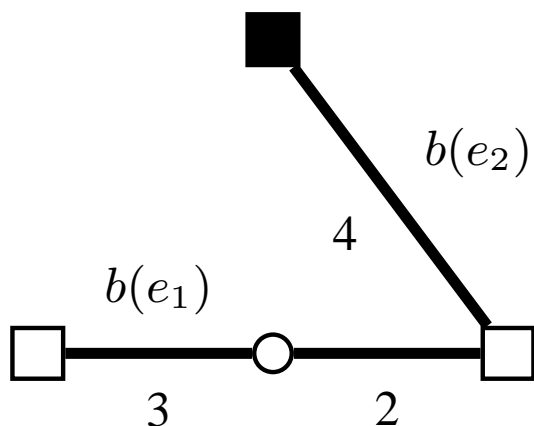
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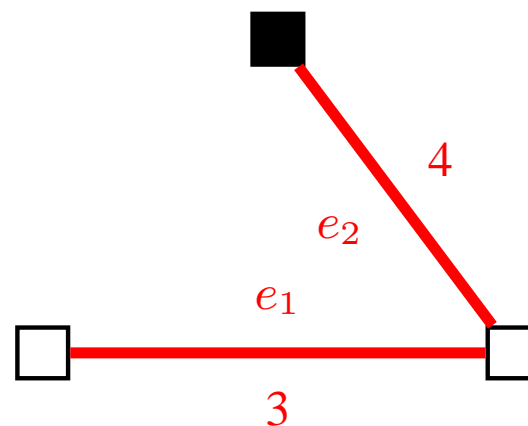
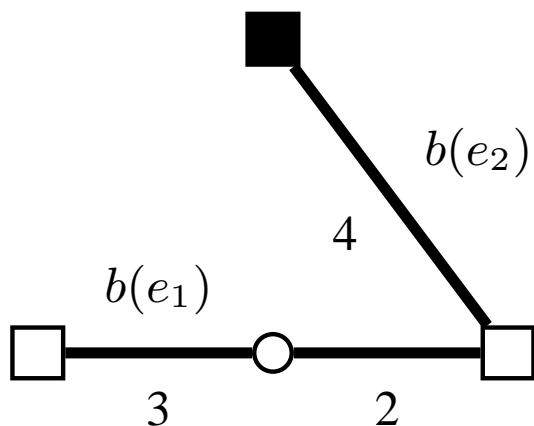


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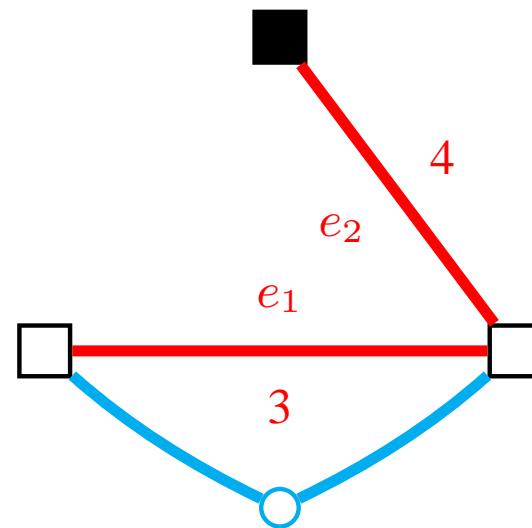
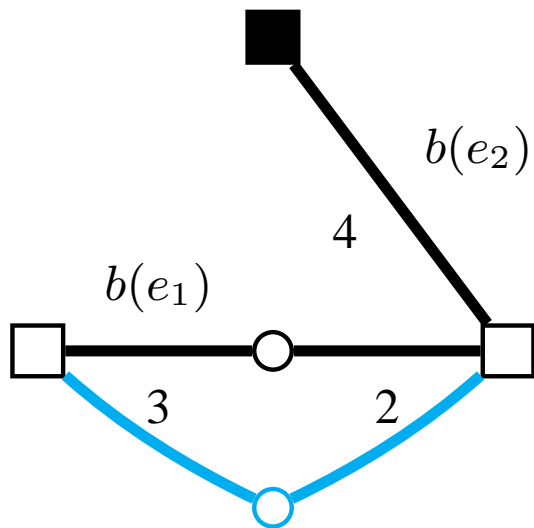


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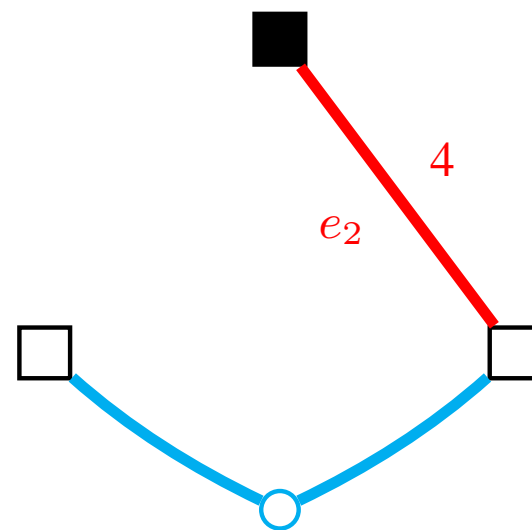
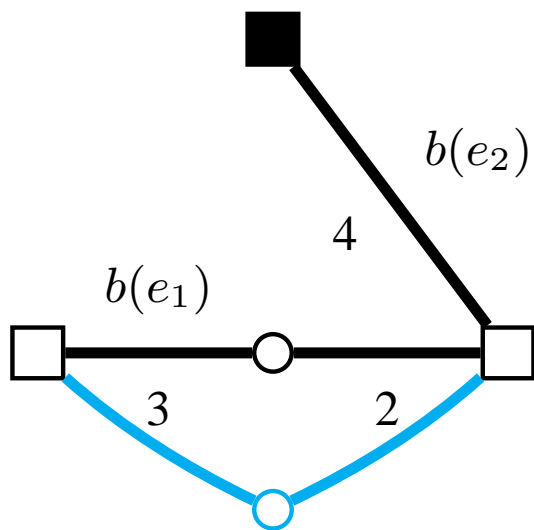


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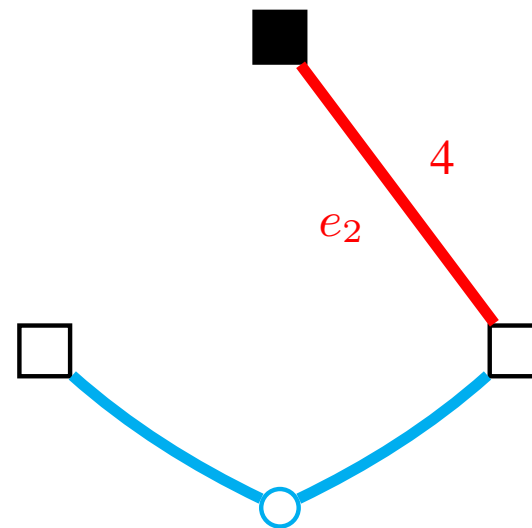
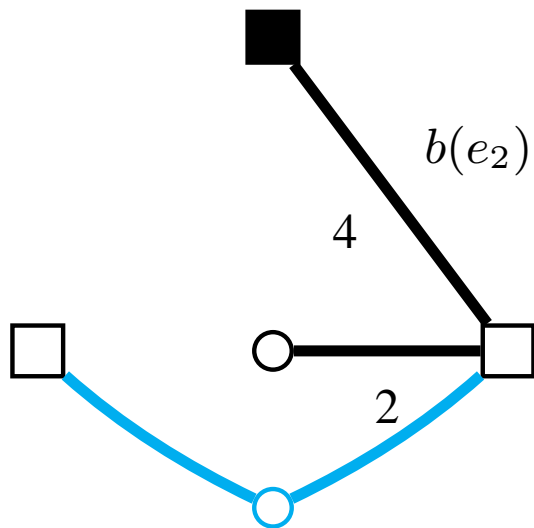


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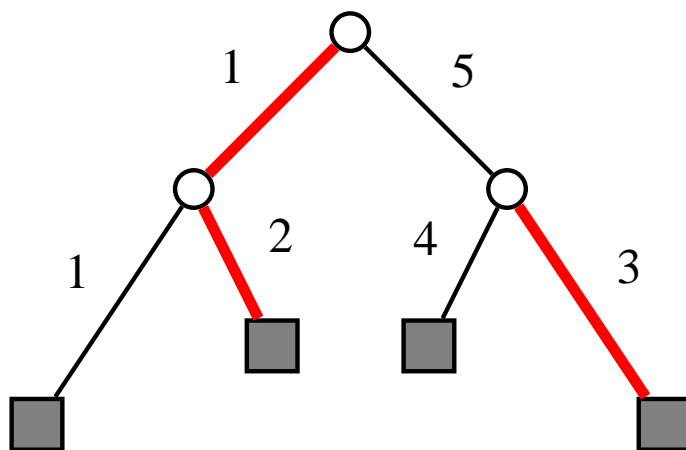
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An Even Better Bound

Thr Algorithm IRR computes a solution of expected cost
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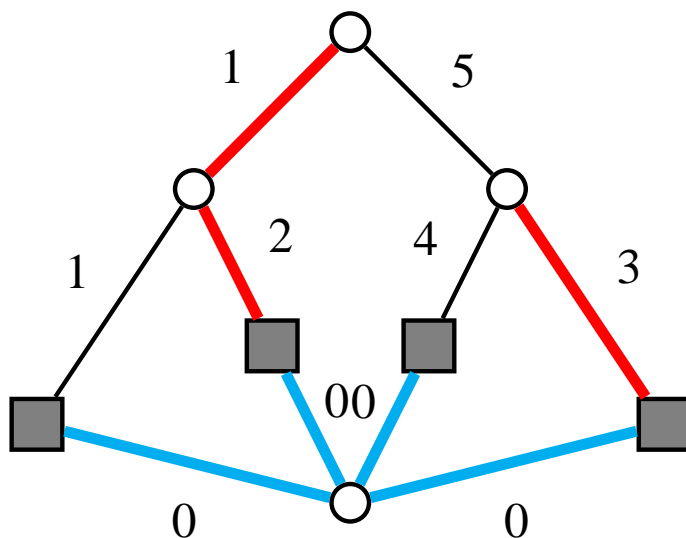
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- We define a random terminal spanning tree W (*witness tree*)

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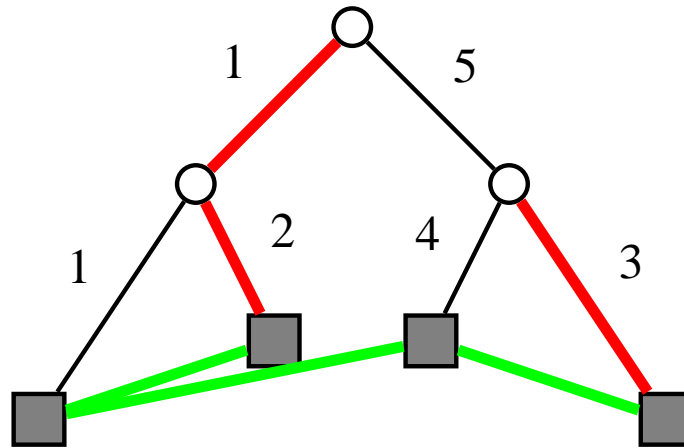
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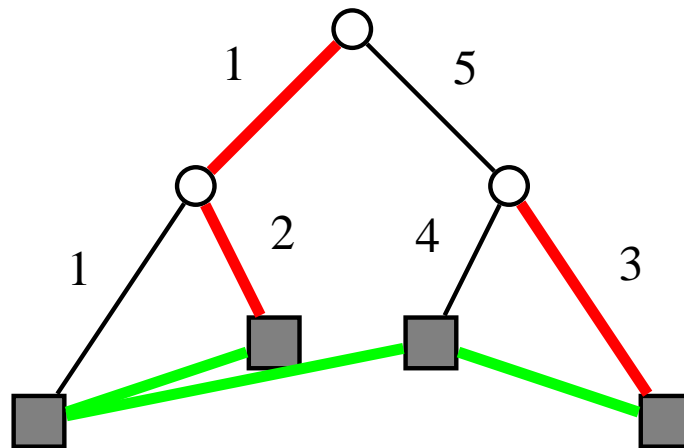
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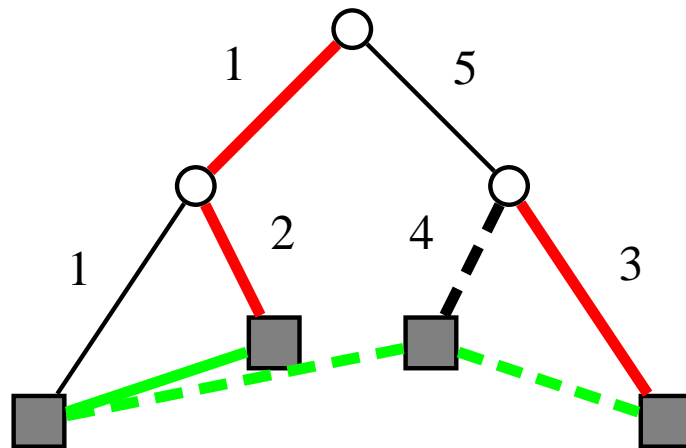
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- We associate to each e in the Steiner tree S the edges $W(e)$ of W such that the corresponding path in S contains e
- Observe that $|W(e)|$ is 1, 2... with probability $\frac{1}{2}, \frac{1}{4}, \dots$

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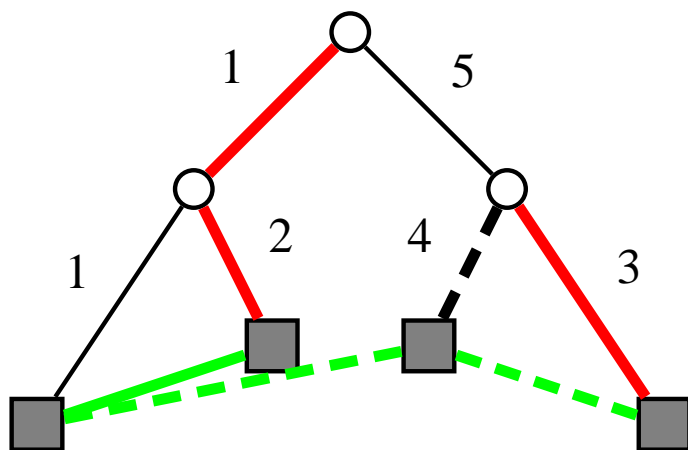
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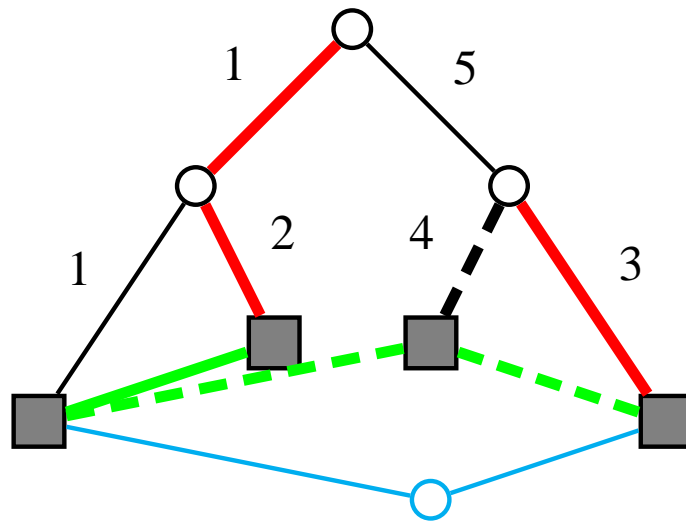
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- For any sampled component C^t , we delete from W a random set of bridges such that each edge of W is deleted with probability $\geq 1/M$ (\leftarrow Farkas' lemma+Bridge lemma)
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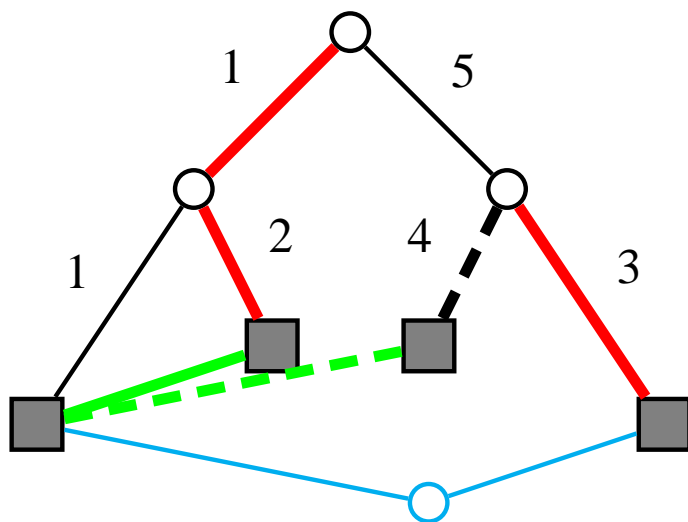
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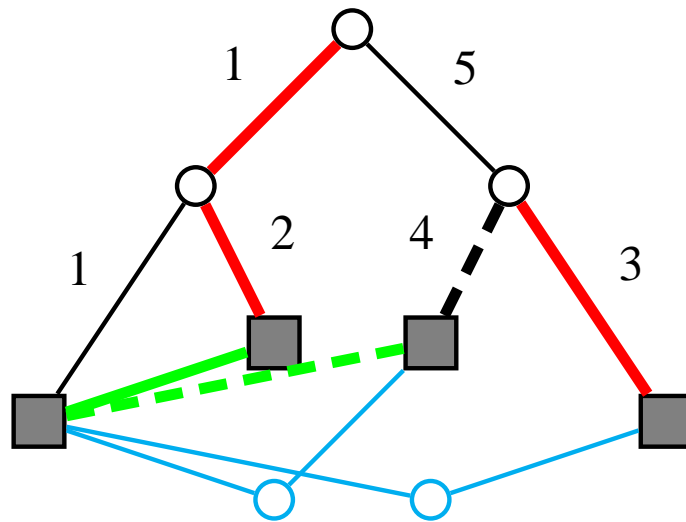
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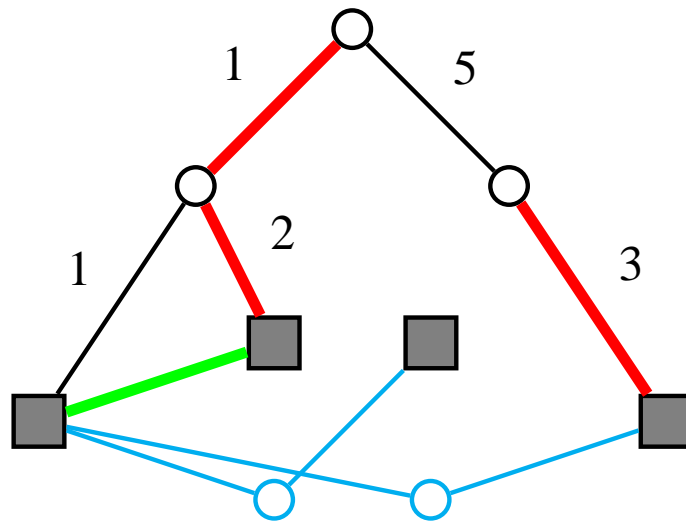
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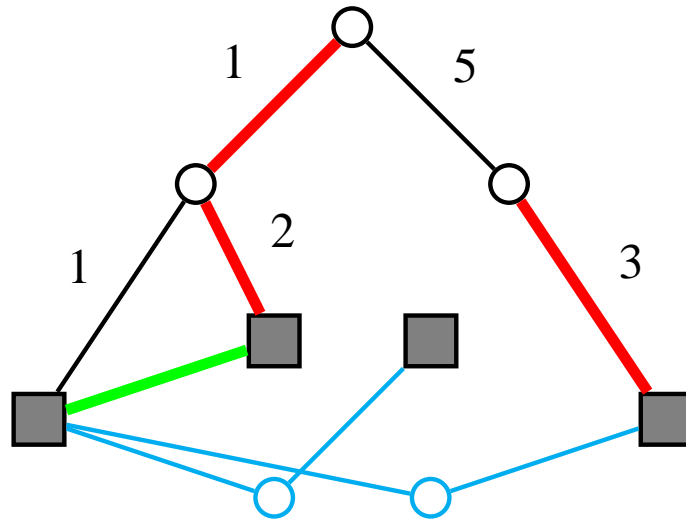
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An Even Better Bound

Thr Algorithm IRR computes a solution of expected cost $\leq (\ln 4 + \varepsilon) \text{opt}$



- Each $e \in S$ survives in expectation $M \cdot \ln 4$ rounds

Derandomization

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- We define a phase-based randomized algorithm, with $1/\varepsilon^2$ phases s
- At each phase, we sample a proper number of components (without updating the LP)
- It is sufficient to guarantee that, at each phase:
 - ◇ Each component is sampled with probability $O(\varepsilon)x_C^s$
 - ◇ Each edge of the witness tree W is marked with probability $\Omega(\varepsilon)$
- This can be done by using only $O(\log n)$ random bits per phase

Open Problems

- The best 1.39 (and even 1.5) bound is w.r.t. the optimal integral solution. Does it hold w.r.t. the fractional one?
- Other applications of iterative randomized rounding?
 - ◇ Prize-collecting Steiner tree
 - ◇ k-MST
 - ◇ Single-Sink Rent-or-Buy
 - ◇ ...

THANKS!!!

