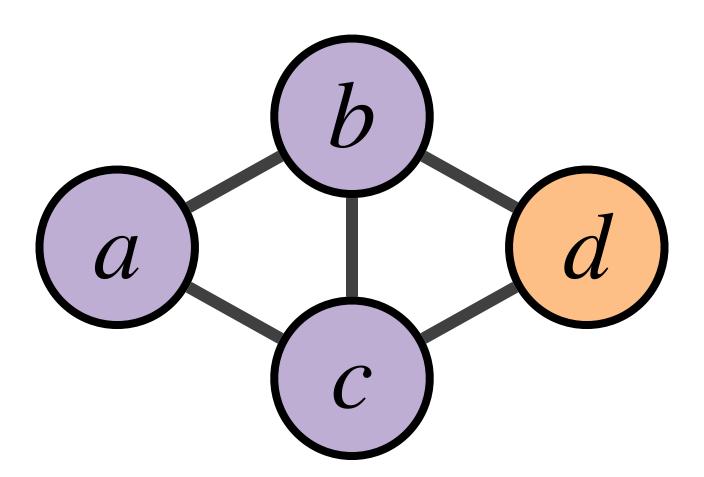
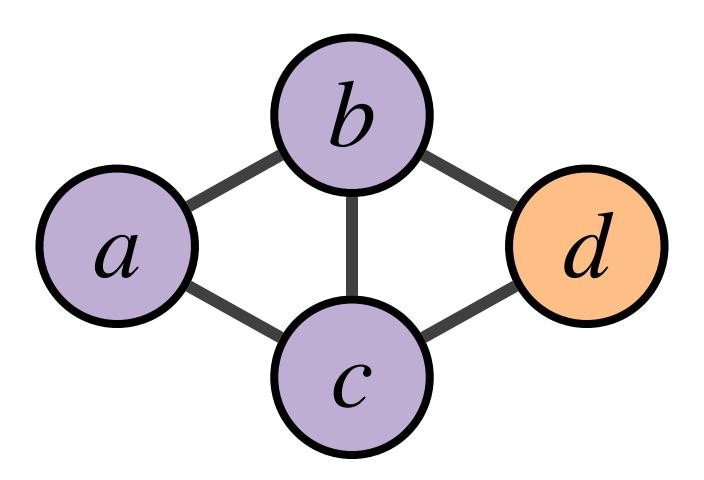
Modular Control Plane Verification via Temporal Invariants

Timothy Alberdingk Thijm
Princeton University
Aarti Gupta
Princeton University

Ryan Beckett
Microsoft Research
David Walker
Princeton University

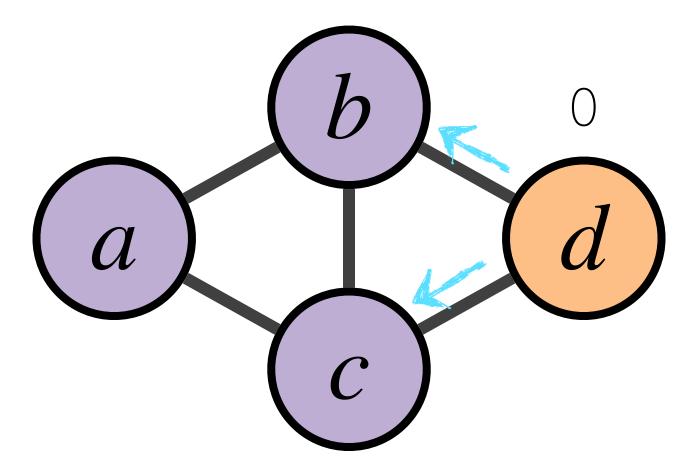


Goal: determine routes to use to forward traffic



Goal: determine routes to use to forward traffic

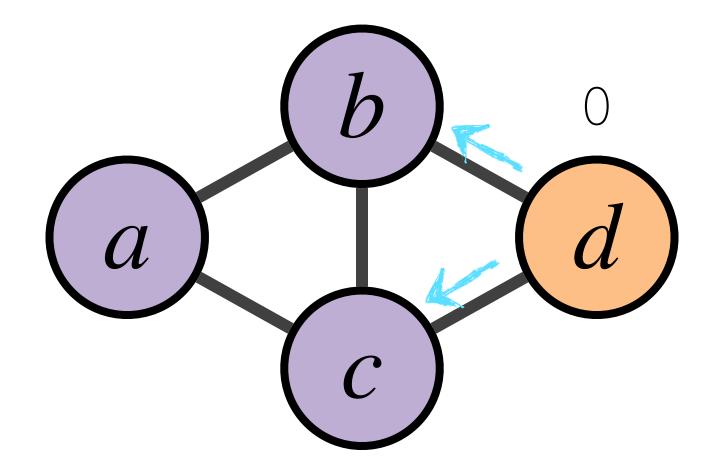
Send initial route announcements



Goal: determine routes to use to forward traffic

Send initial route announcements

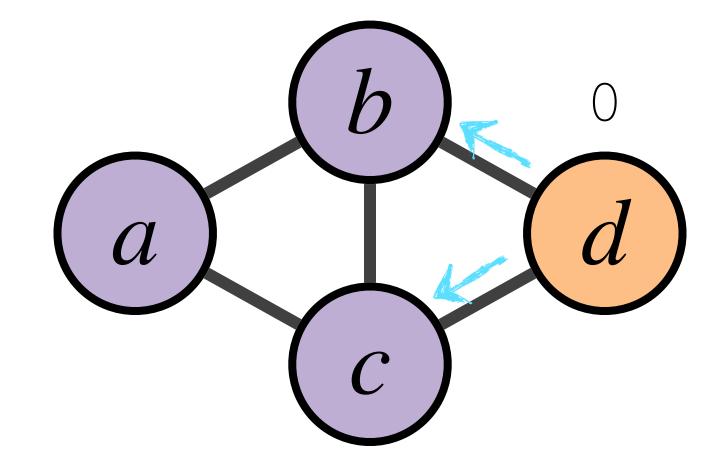
Receive announcements, process according to configs



Goal: determine routes to use to forward traffic

Send initial route announcements

Receive announcements, process according to configs

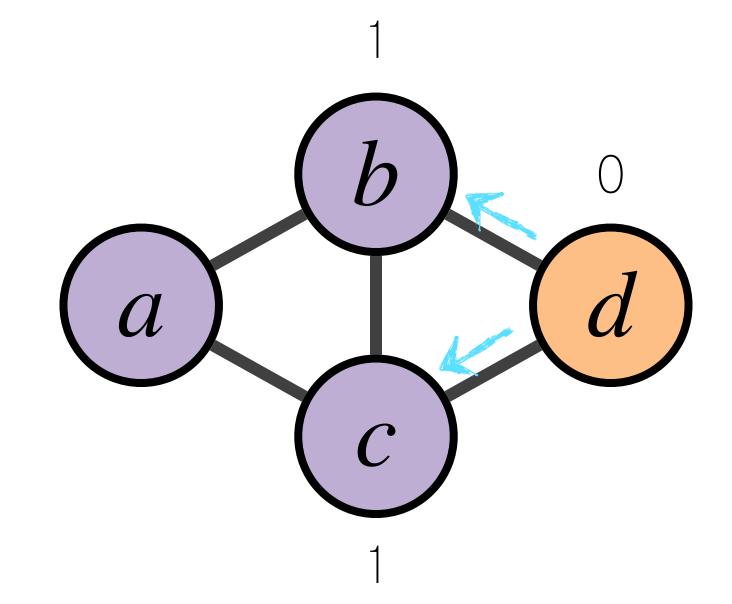


Goal: determine routes to use to forward traffic

Send initial route announcements

Receive announcements, process according to configs

Select best announcement



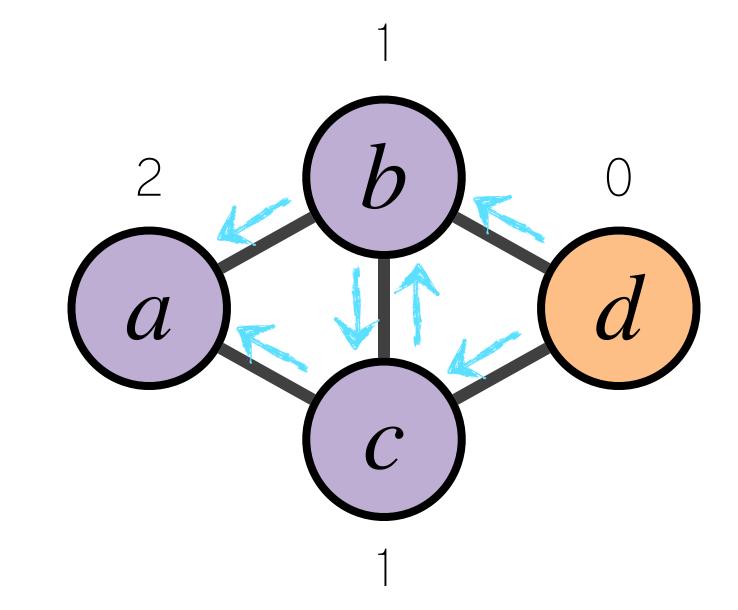
Goal: determine routes to use to forward traffic

Send initial route announcements

Receive announcements, process according to configs

Select best announcement

Broadcast selected route to neighbors



```
bat examples/INTERNET2/configs/newy32aoa.cfg

policy-statement CARREN-IN {
    term participent {
        protocol bgp;
        prefix-list-filter CAAREN-PARTICIPANT orlonger;
    }
    term segp {
        from {
            protocol bgp;
            prefix-list-filter CAAREN-SEGP orlonger;
    }
    term segp {
        from {
            community add SEGP;
            next policy;
    }
    }
    term sponsored {
        from {
            community add SEGP;
            next policy;
    }
    }
    term sponsored {
        from {
            protocol bgp;
            prefix-list-filter CAAREN-SPUNSURED orlonger;
    }
    }
    term sponsored {
        from {
            community add SPONSORED;
            next policy;
      }
    }
    **
    **S373
    **S374
    **S375
    **
    **S376
    **S377
    *** then reject-unicast {
        **
        *** then reject;
    }
    **S380
    **
}
```

Goal: determine routes to use to forward traffic

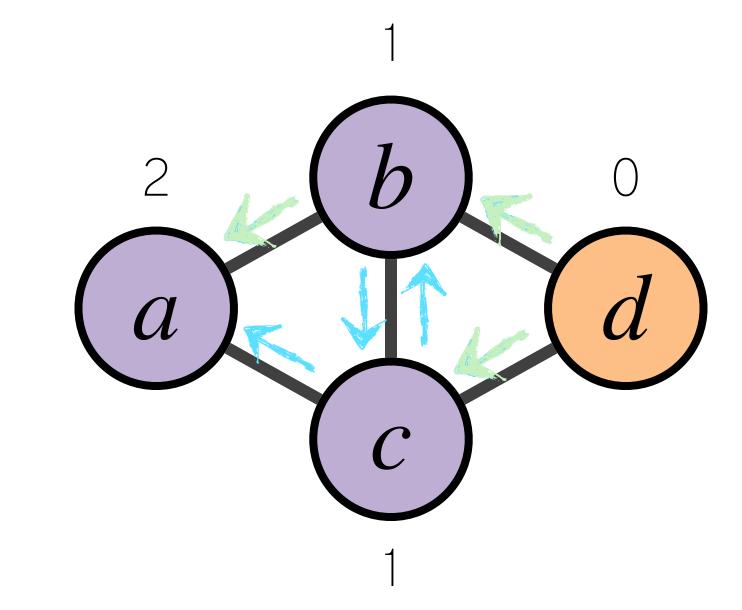
Send initial route announcements

Receive announcements, process according to configs

Select best announcement

Broadcast selected route to neighbors

Converge to a **stable state**



```
bat examples/INTERNET2/configs/newy32aoa.cfg

policy-statement CAREN-IN {
    tern perticipent {
        proteccl bgp;
        prefix-list-filter CAREN-PARTICIPANT orlonger;
}

tern segp {
    from {
        preteccl bgp;
        prefix-list-filter CAREN-SEGP orlonger;
}

tern segp {
    from {
        community add SEGP;
        next policy;
}

$366

$366

$366

$366

$366

$367

tern sponsored {
    from {
        proteccl bgp;
        prefix-list-filter CAREN-SEGP orlonger;
}

$370

$370

$370

$370

$371

then {
        community add SPONSORED;
        next policy;
}

$371

$372

then {
        community add SPONSORED;
        next policy;
}

$373

$374

tern reject-unicest {
        then reject;
}

$379

$388

$388

}
```

Goal: determine routes to use to forward traffic

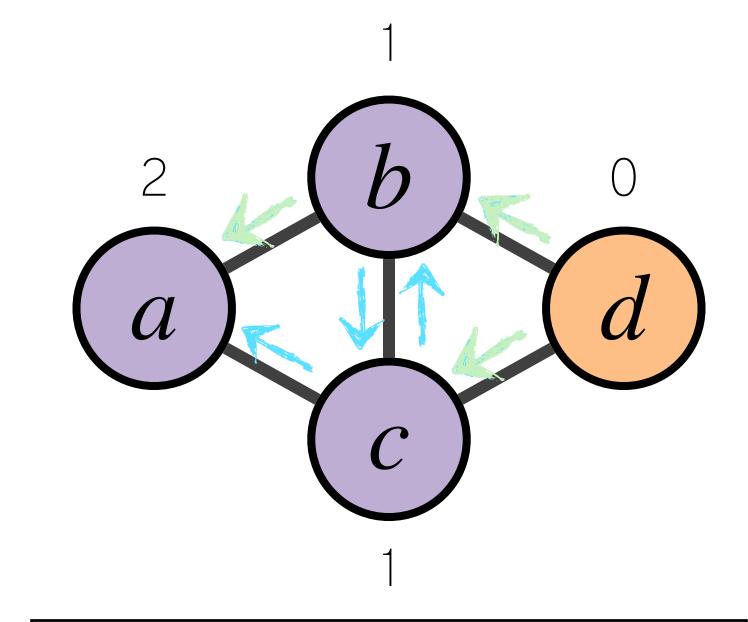
Send initial route announcements

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Converge to a **stable state**



Policies for security, traffic engineering, fault tolerance, cost, *etc.*

```
bat examples/INTERNET2/configs/newy32aoa.cfg

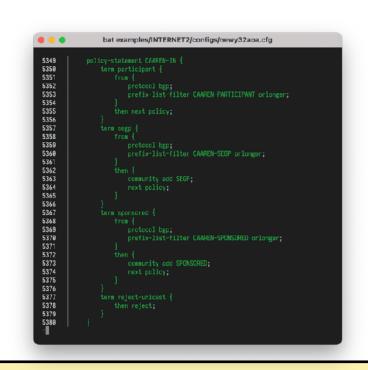
policy-statement CAAREN-IN {
    term participant {
        protocol bgp;
        prefix-list-filter CAAREN-PARTICIPANT orlonger;
    }
    term segp {
        protocol bgp;
        prefix-list-filter CAAREN-PARTICIPANT orlonger;
    }
    term segp {
        protocol bgp;
        prefix-list-filter CAAREN-SEGP orlonger;
    }
    then {
        community add SEGP;
        next policy;
    }
    term sponsored {
        from {
            community add SEGP;
            rext policy;
    }
    }
    then {
        community add SPONSORED;
        rext policy;
    }
    then {
        community add SPONSORED;
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    }
    }
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        then reject;
    }
}
```

How Do We Verify Control Planes?

Network configuration files

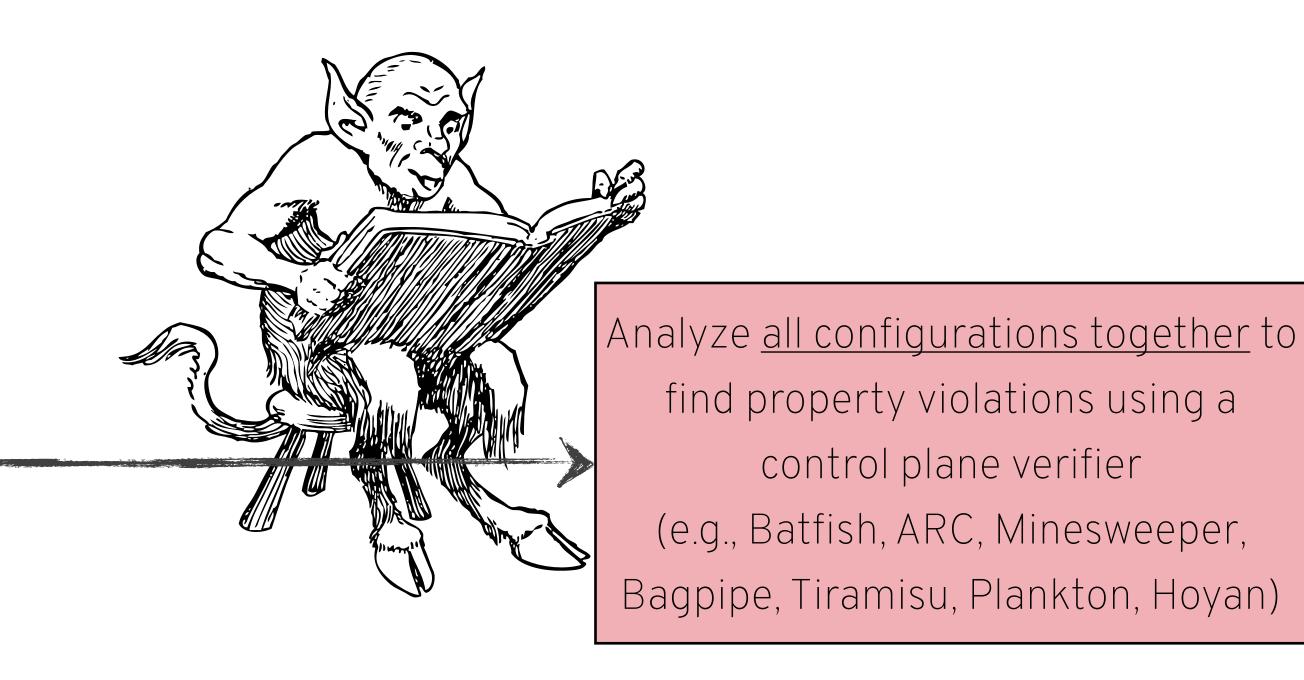
Policies for security, traffic engineering, fault tolerance, cost, *etc.*

How Do We Verify Control Planes?

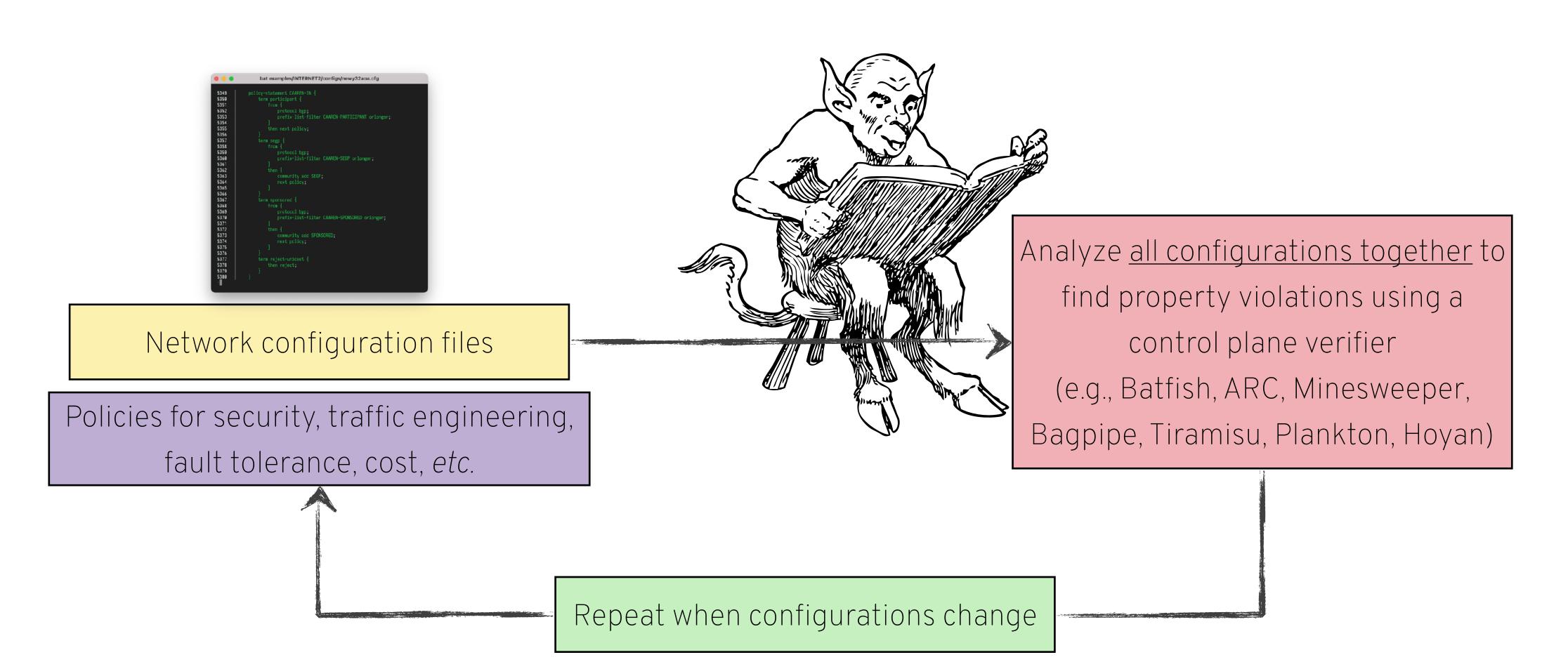


Network configuration files

Policies for security, traffic engineering, fault tolerance, cost, *etc.*



How Do We Verify Control Planes?



Scaling Control Plane Verification

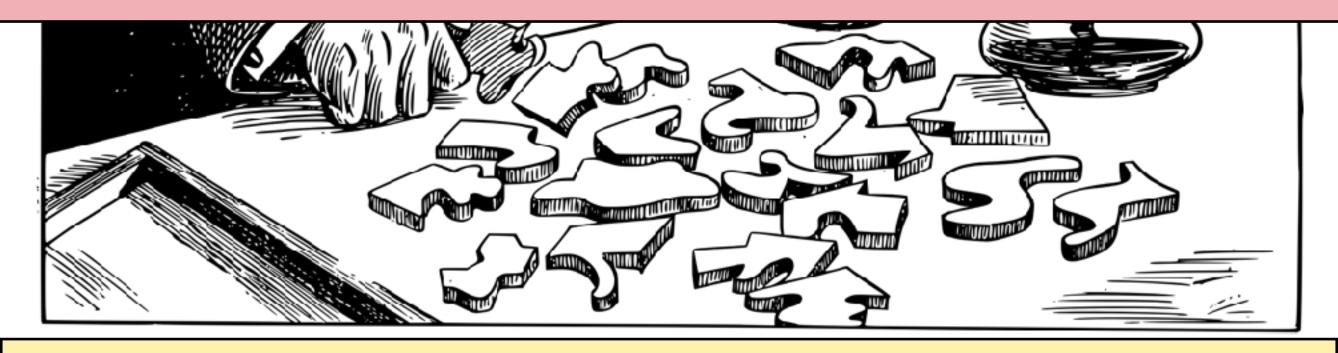


Many networks are too big and too complex to verify monolithically!

Scaling Control Plane Verification

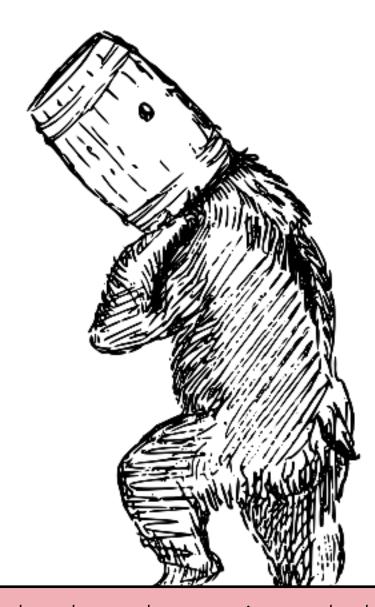


modular verification to the rescue!



Many networks are too big and too complex to verify monolithically!

Our Contributions



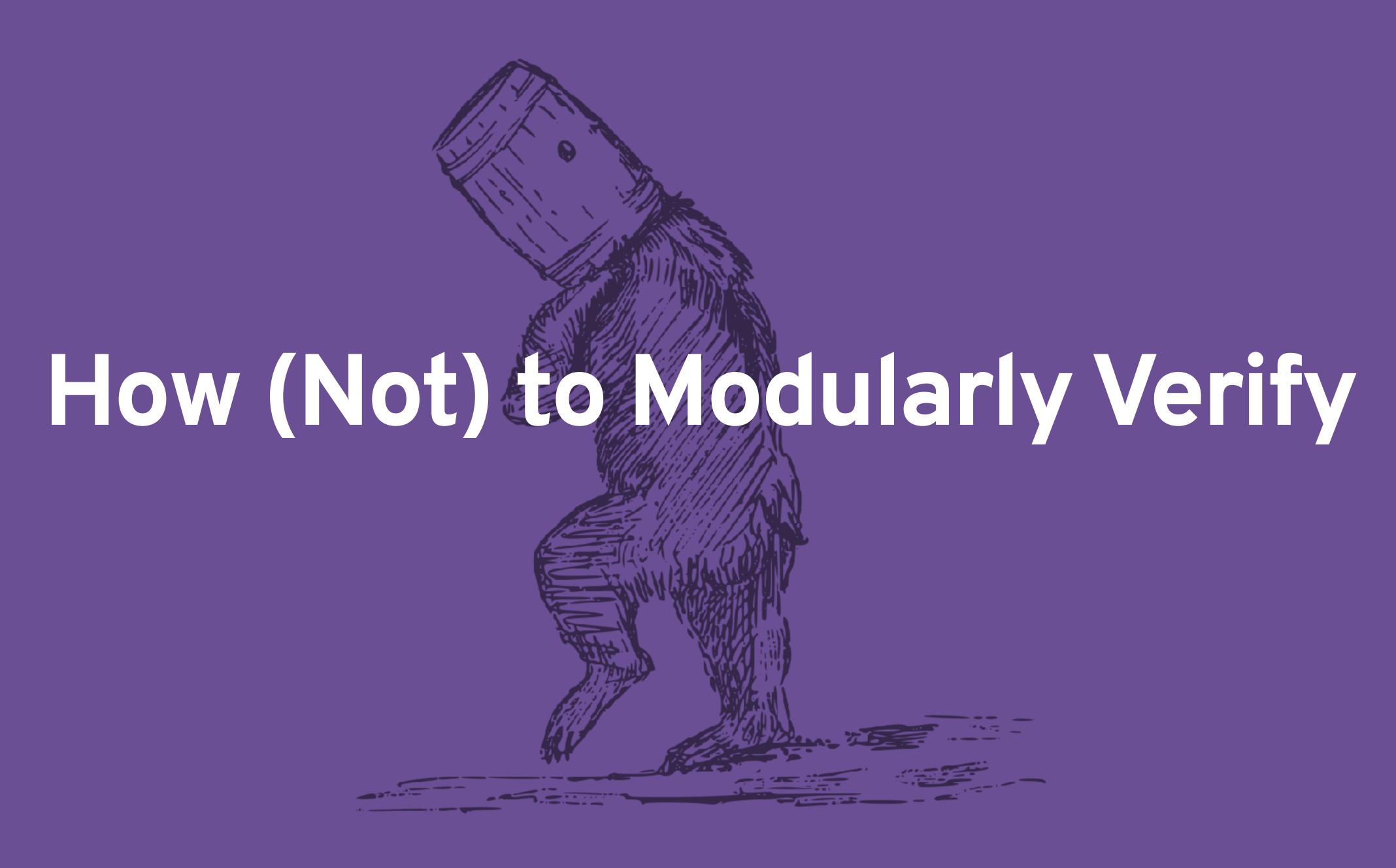
demonstrate why naive stable states analysis is unsuitable for modular verification

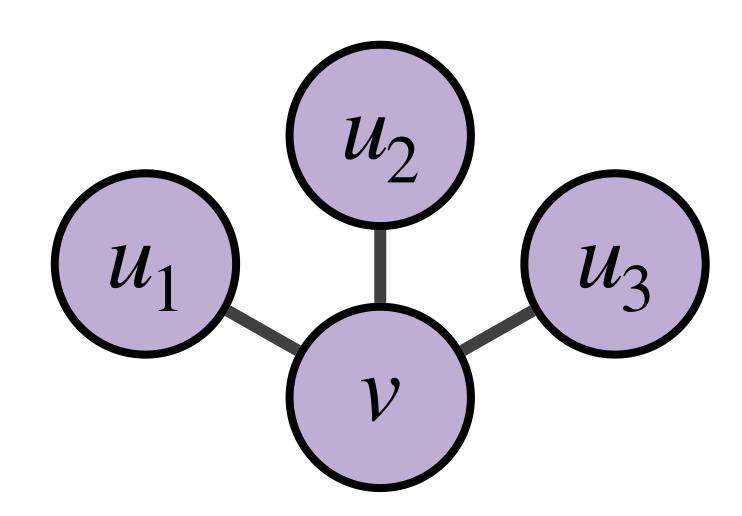


present time-based theory for modular control plane analysis, with SMT-based verification procedure



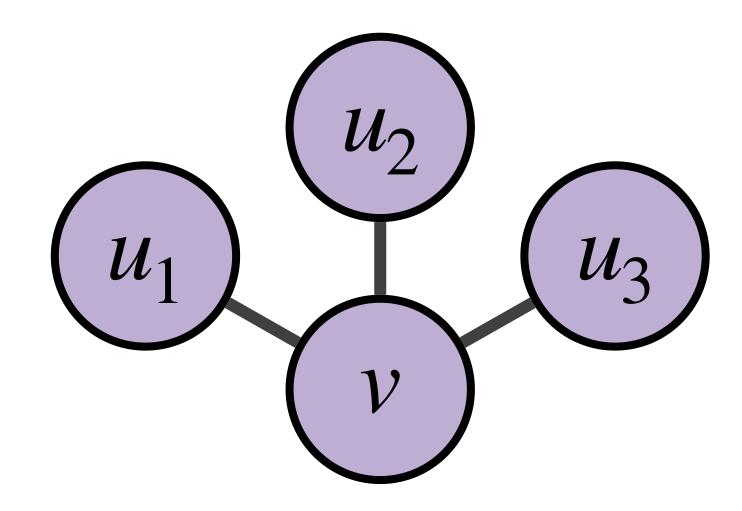
verify properties of 2000-node data centers and complex wide-area networks in seconds!





sound modular analysis:

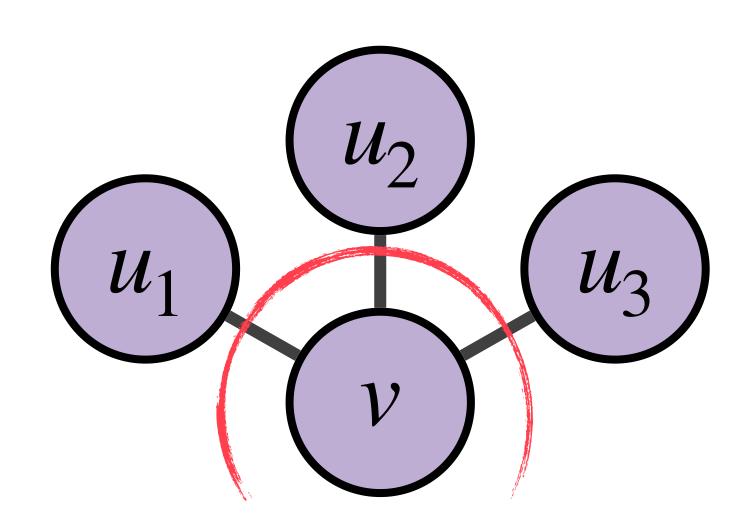
captures all monolithic routing behavior



sound modular analysis:

captures all monolithic routing behavior

split the network up into node-local components to verify independently

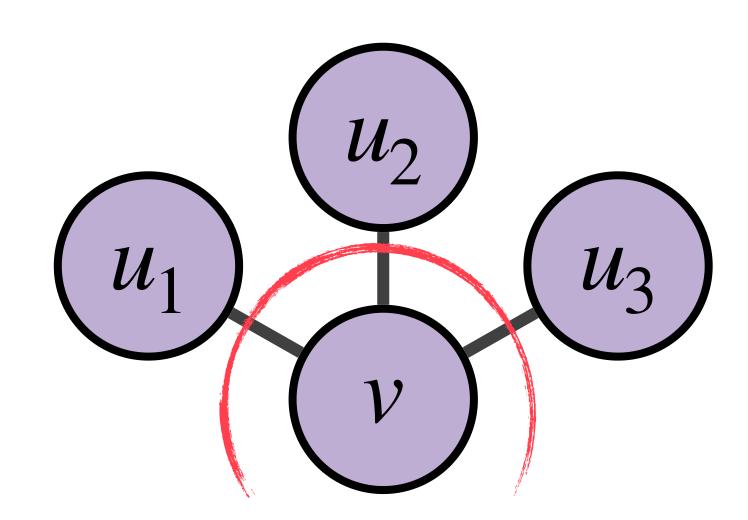


sound modular analysis:

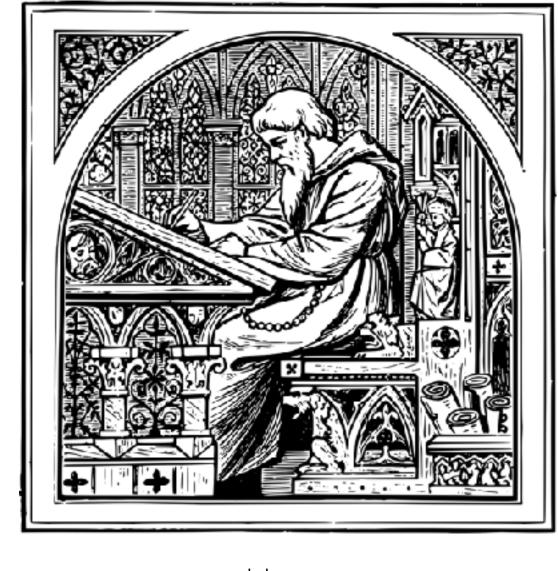
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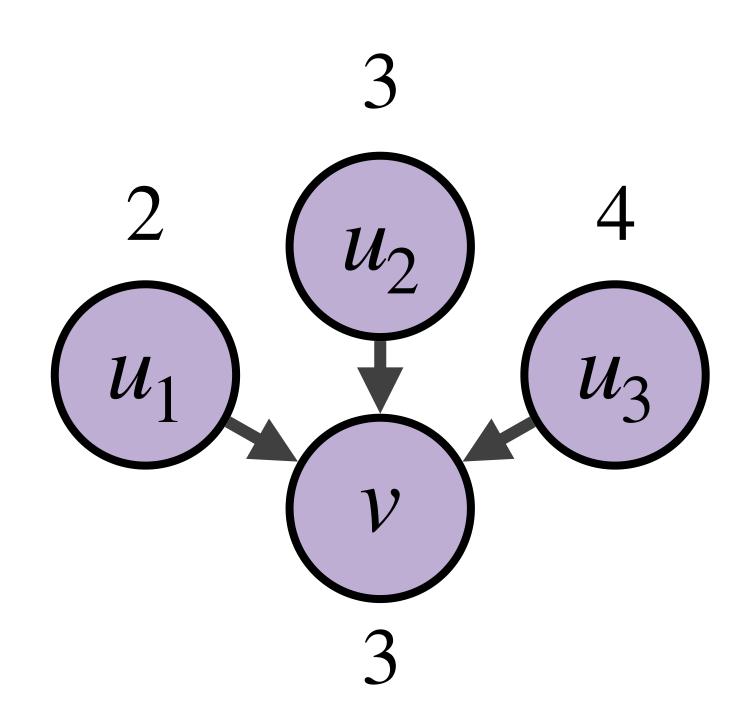
represent cross-component dependencies using **interfaces**



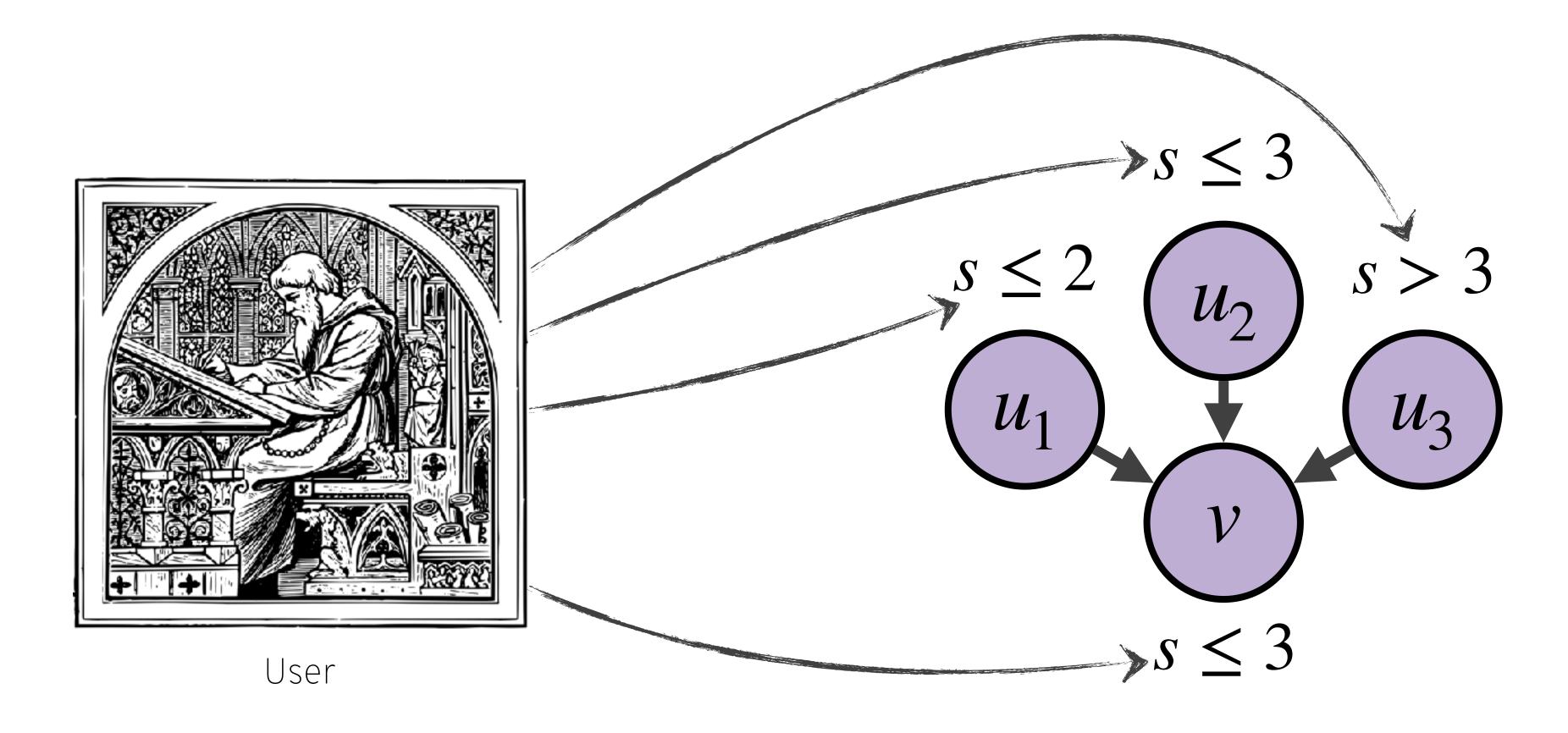
Interfaces



User

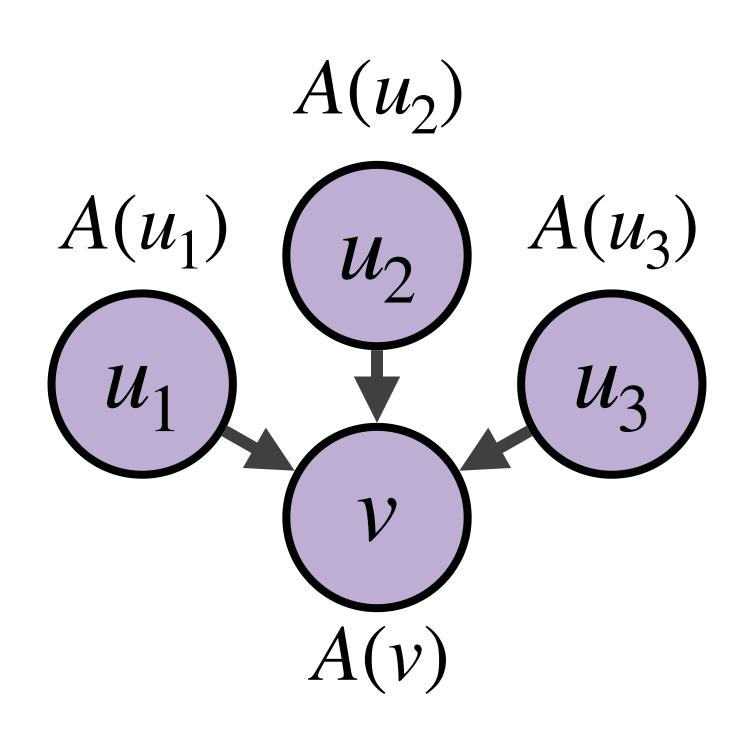


Interfaces



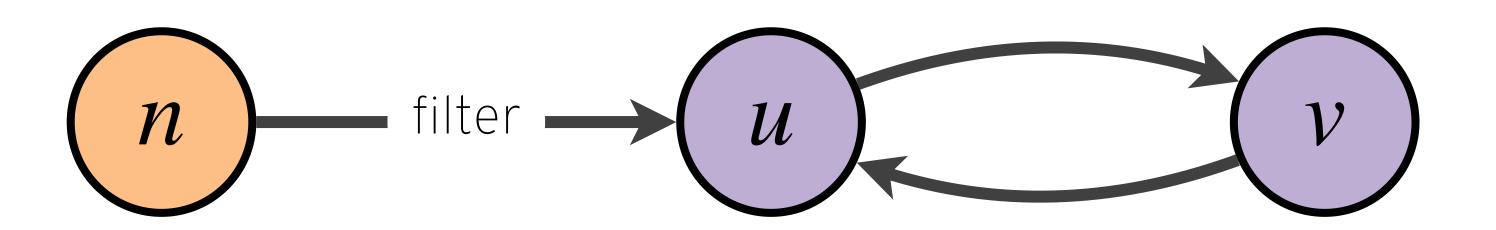
interface A over-approximates the converged states of the node v with a set of states A(v)

Bear's Modular Verification Procedure

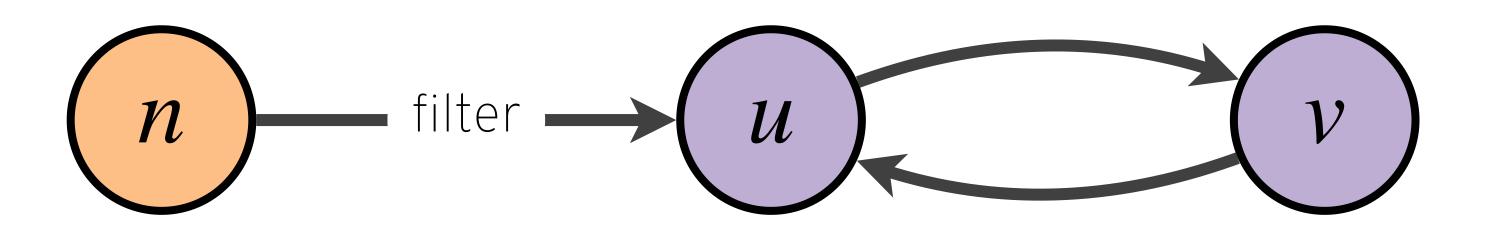


Verification condition:

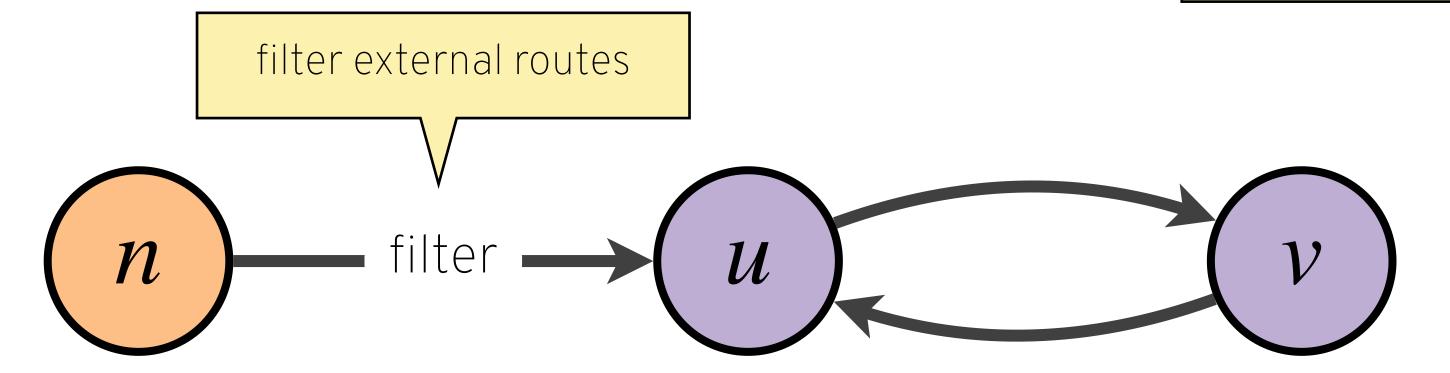
If v receives any routes satisfying $A(u_1), A(u_2), \ldots, A(u_m)$, does its selected route satisfy A(v)?



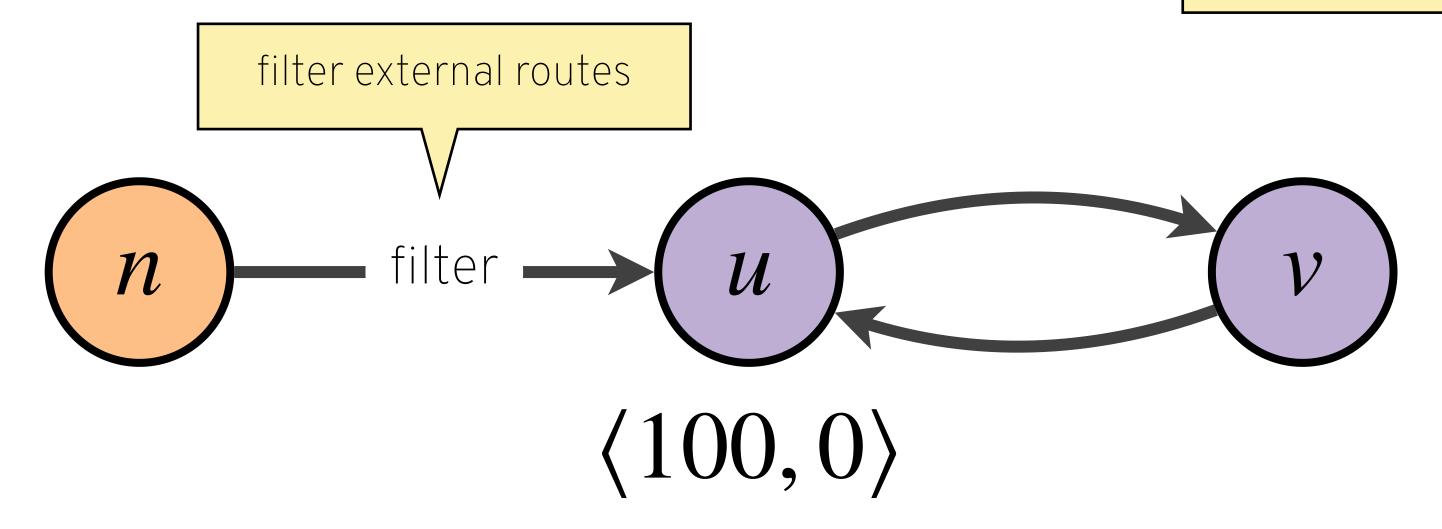
routes: $\langle lp : \mathbb{N}, len : \mathbb{N} \rangle$ or ∞



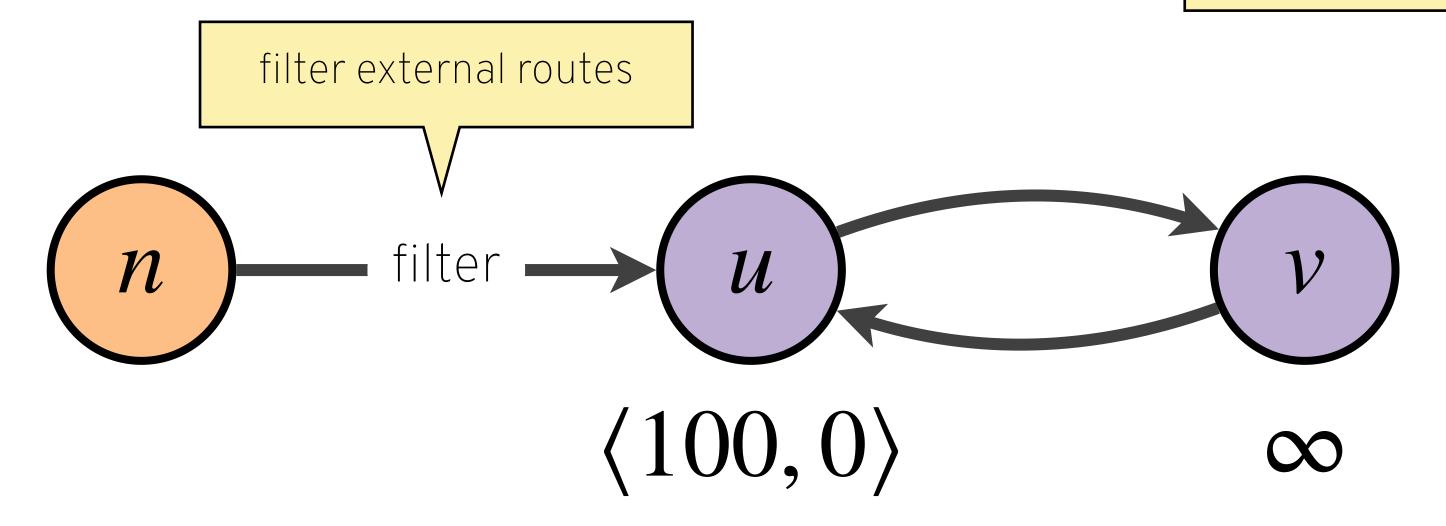
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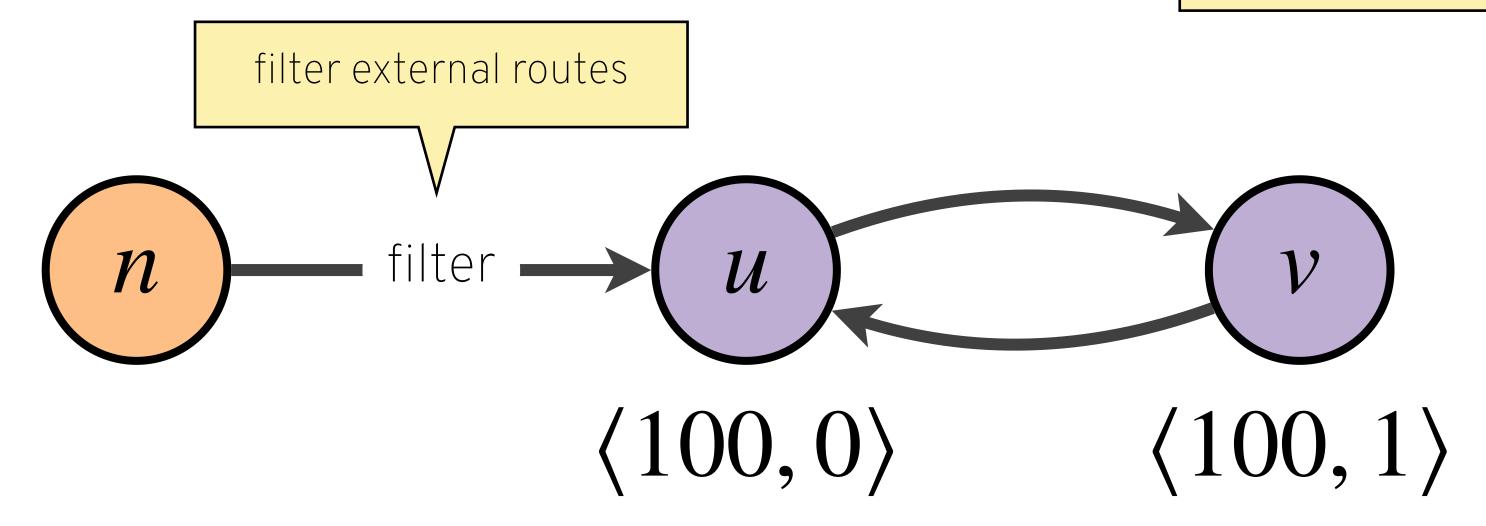
routes: $\langle lp : \mathbb{N}, len : \mathbb{N} \rangle$ or ∞

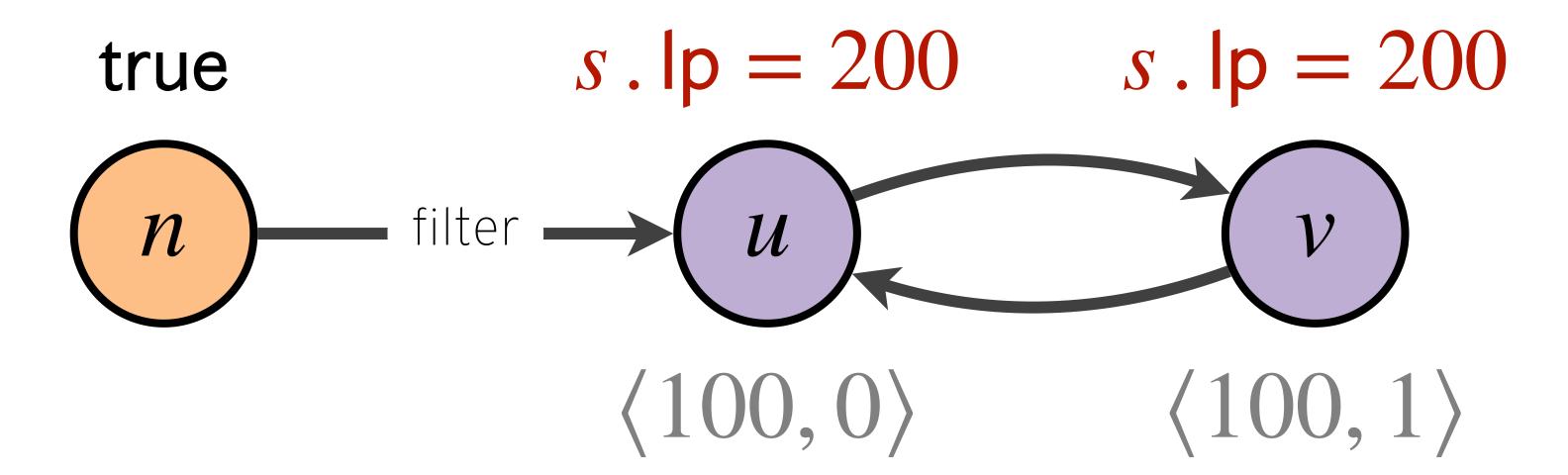


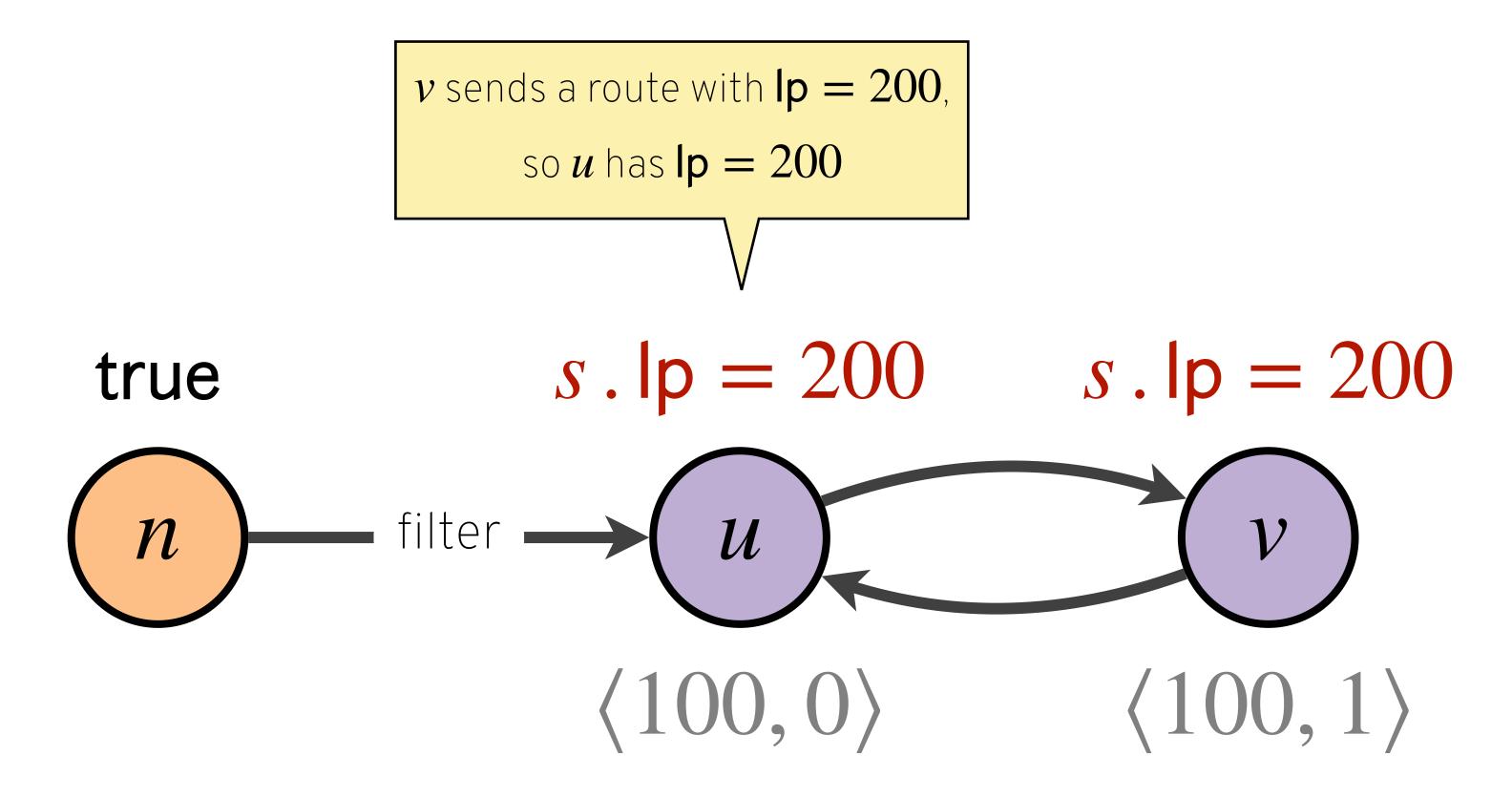
routes: $\langle lp : \mathbb{N}, len : \mathbb{N} \rangle$ or ∞

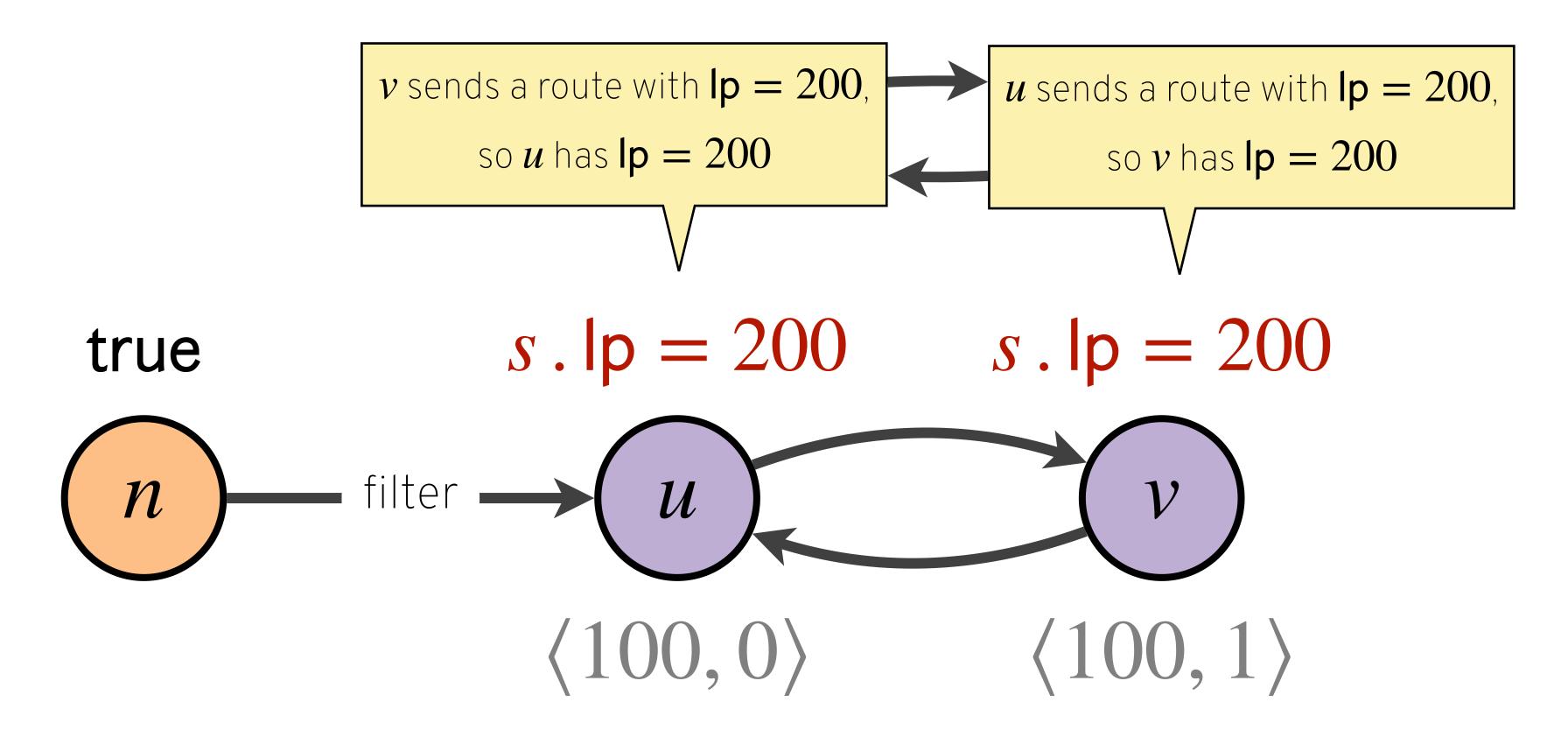


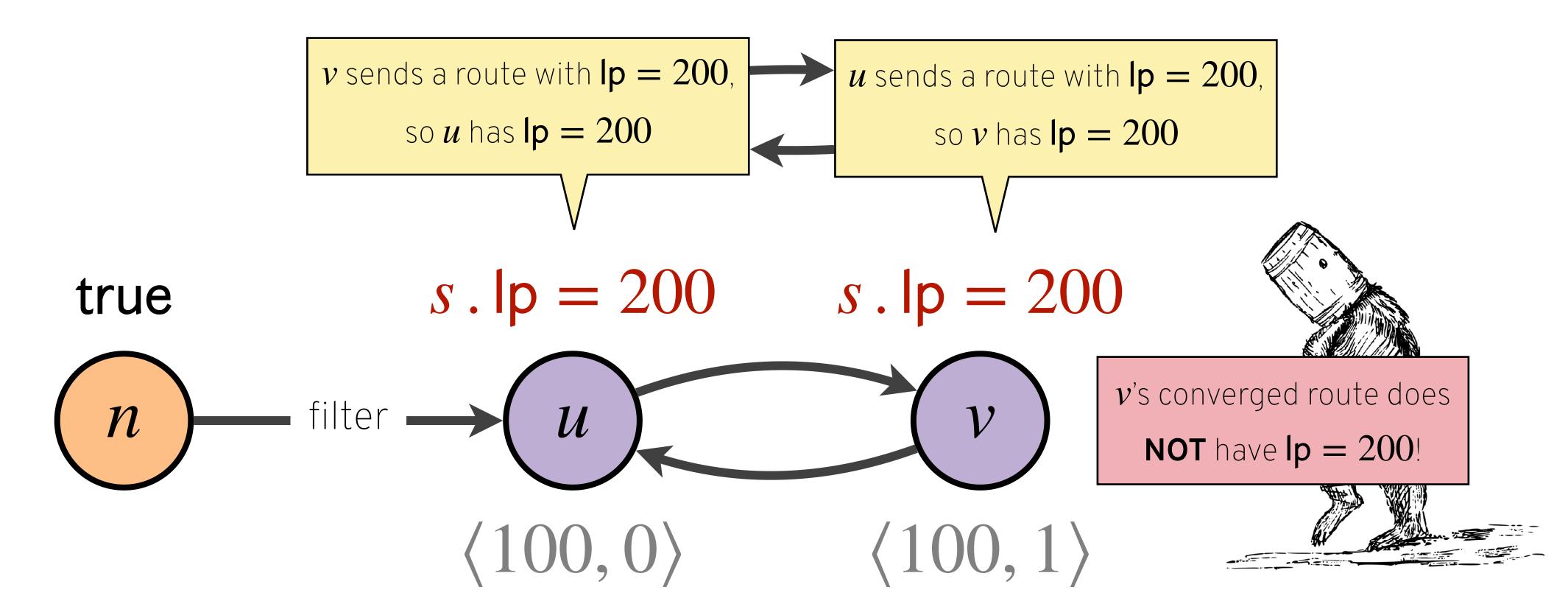
routes: $\langle lp : \mathbb{N}, len : \mathbb{N} \rangle$ or ∞

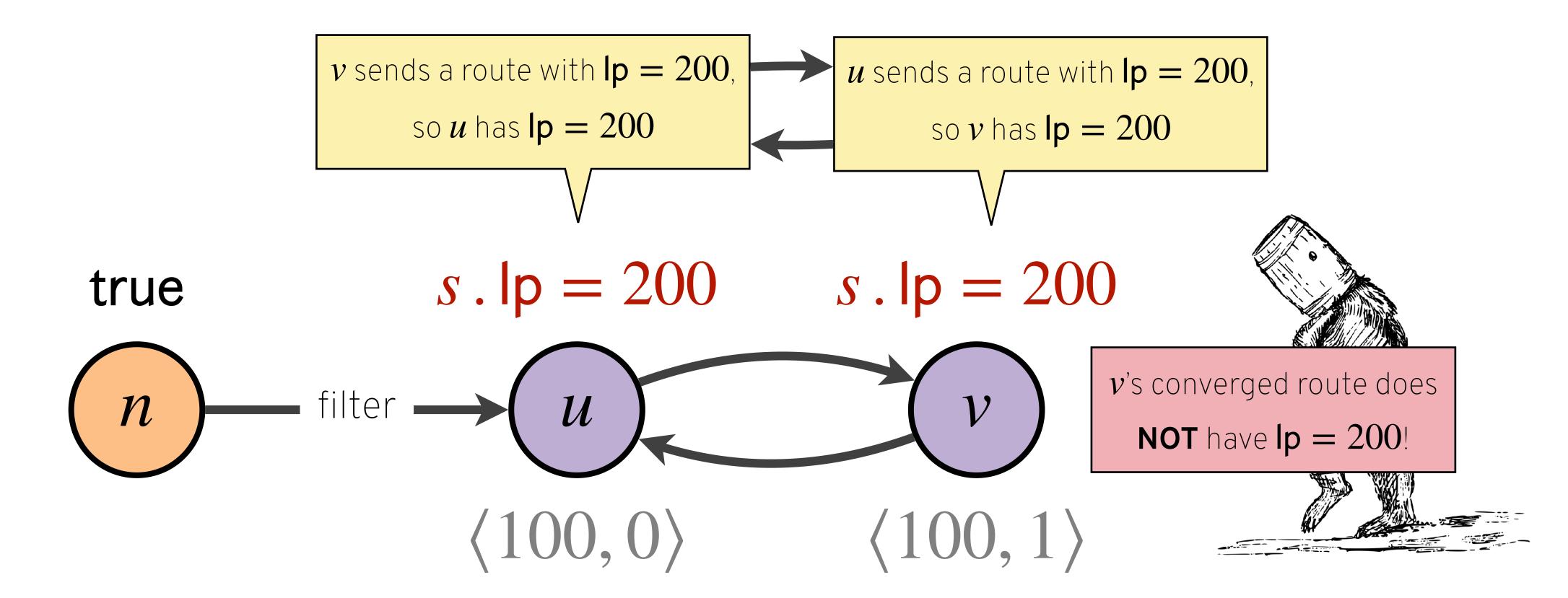






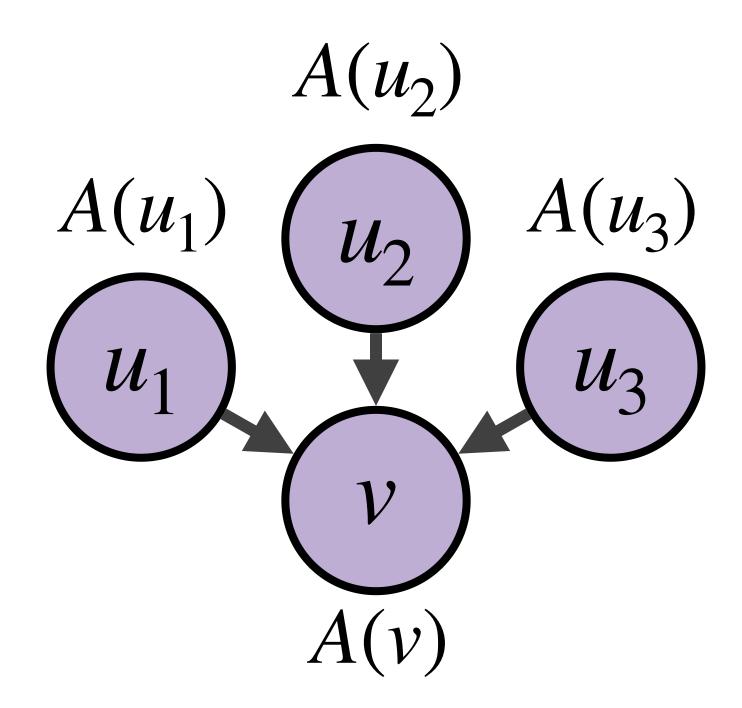




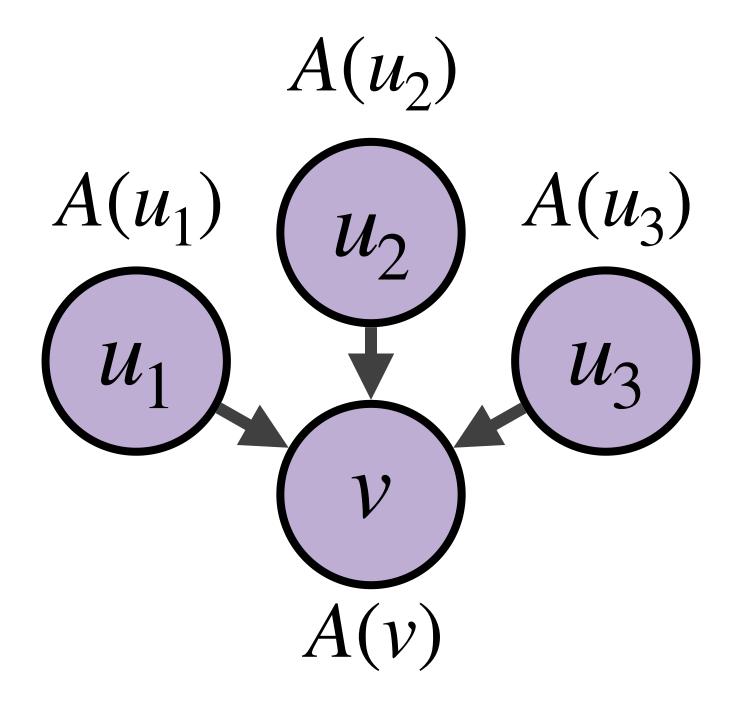


interfaces are unsound: exclude the legitimate converged routes, but the checks pass!



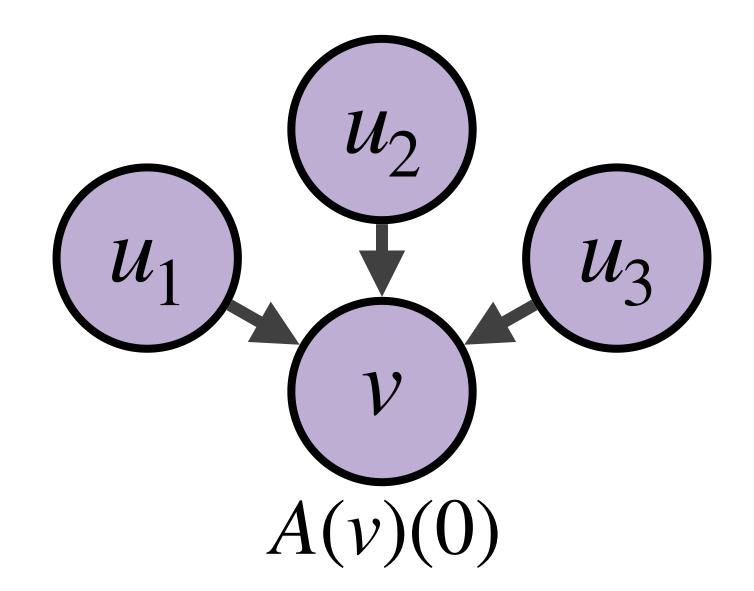


interface A over-approximates the converged states of the node v with a set of states A(v)



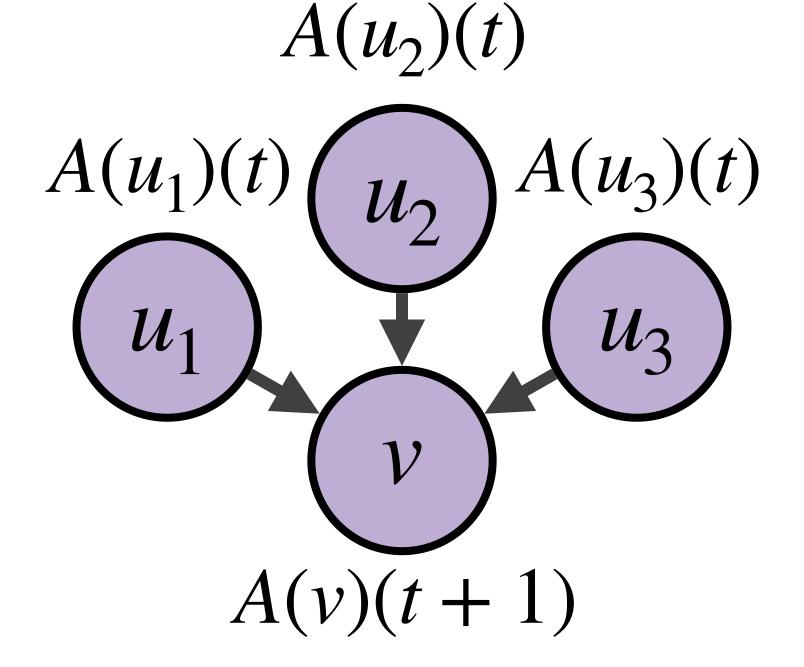
temporal interface A over-approximates the states of the node v at time t with a set of states A(v)(t)

base check: interfaces at time 0 holds on initial routes



temporal interface A over-approximates the states of the node v at time t with a set of states A(v)(t)

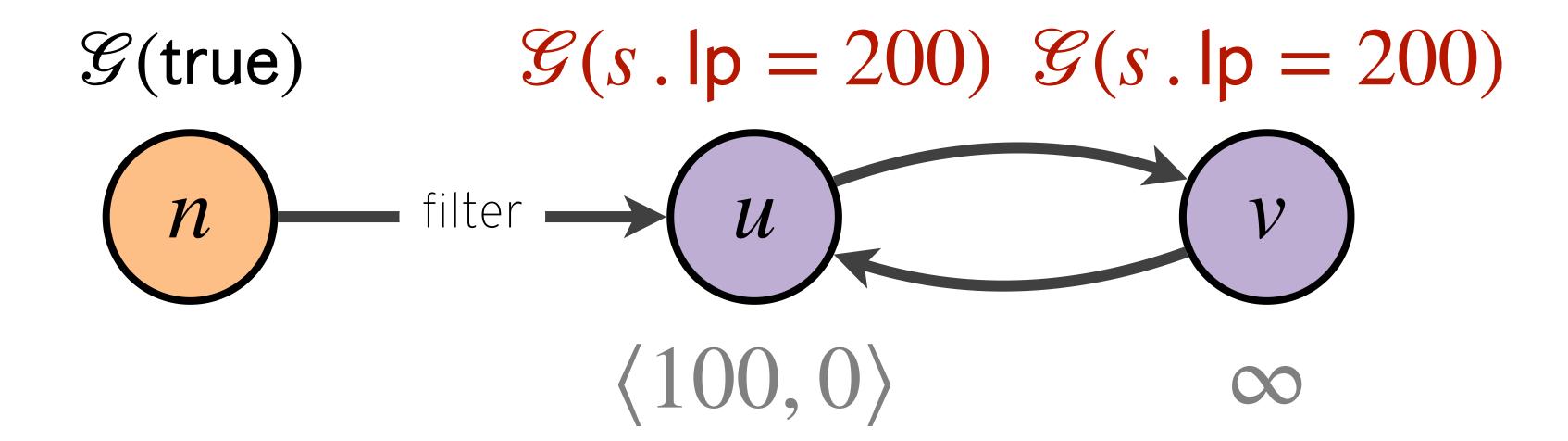
base check: interfaces at time 0 holds on initial routes



inductive check: for all times t, interfaces at time t+1 holds given interfaces from time t

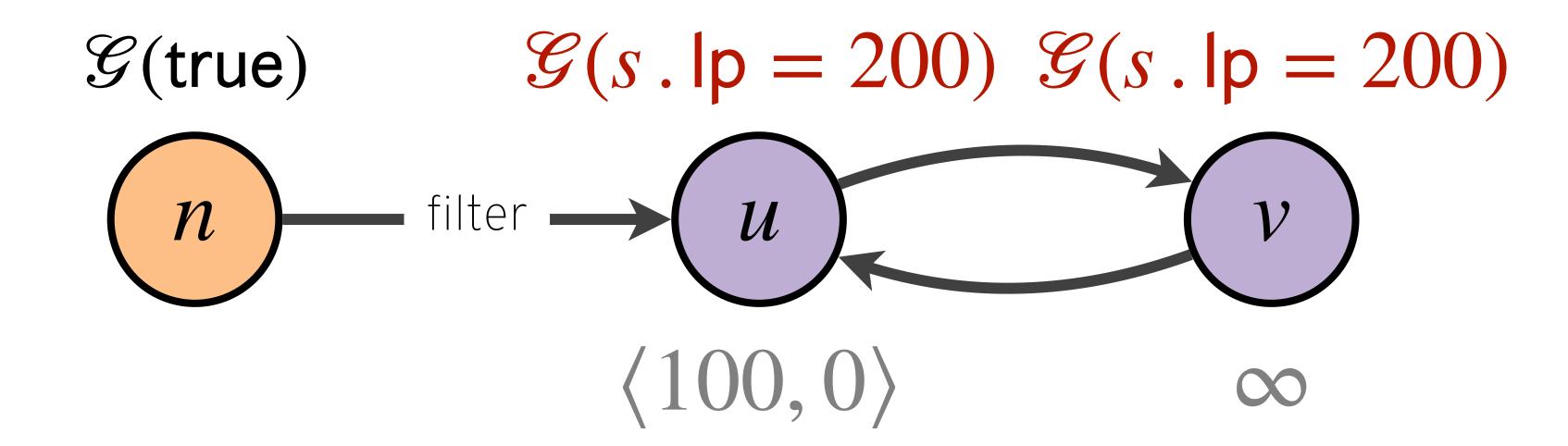
temporal interface A over-approximates the states of the node v at time t with a set of states A(v)(t)

Preventing Interference



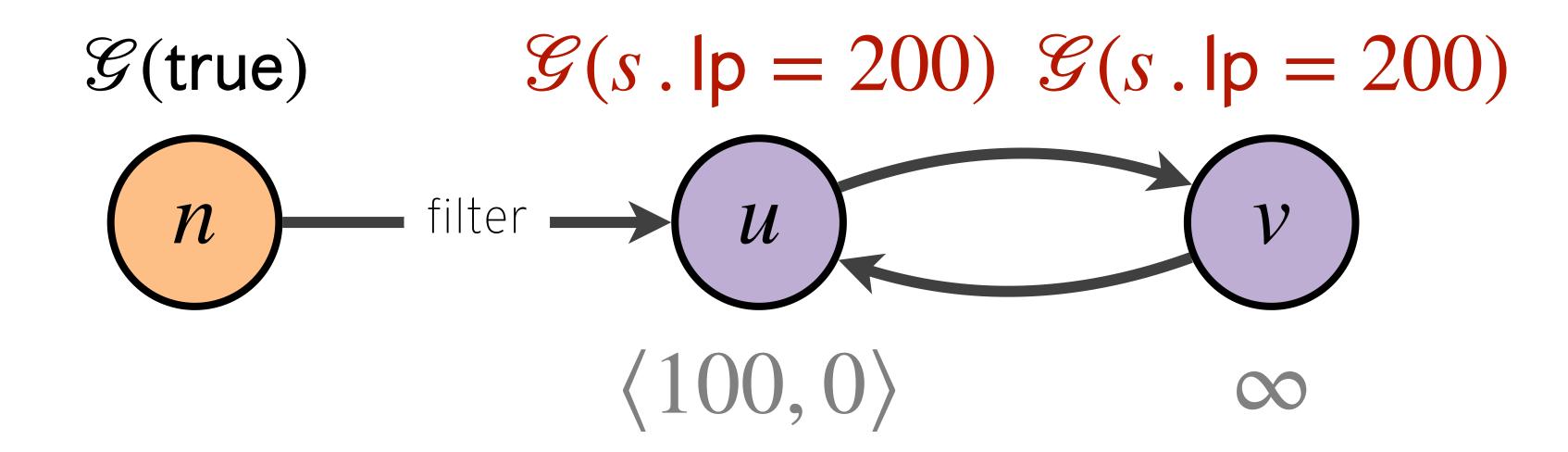
Preventing Interference

 $\mathscr{G}P$ (globally P): at every point in time, the predicate P holds

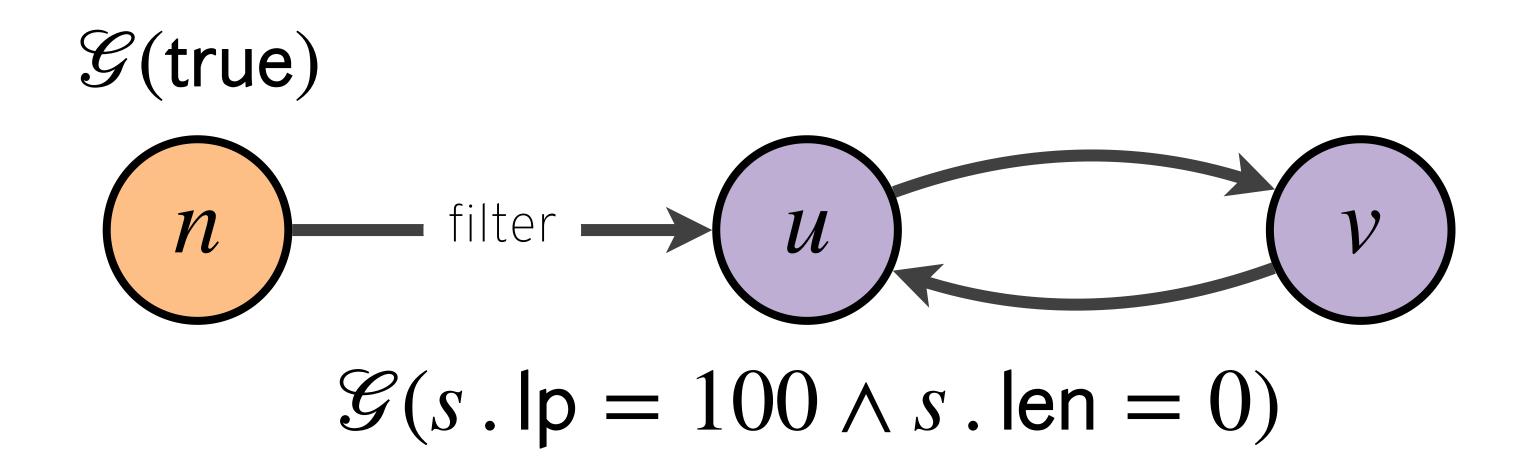


Preventing Interference

 $\mathscr{G}P$ (globally P): at every point in time, the predicate P holds



Base checks fail: interfaces A(u) and A(v) do not hold for initial routes at time 0



$$\mathcal{G}(\text{true}) \qquad s = \infty \ \mathcal{U}^1 \ s \cdot \text{lp} = 100 \land s \cdot \text{len} \le 1$$

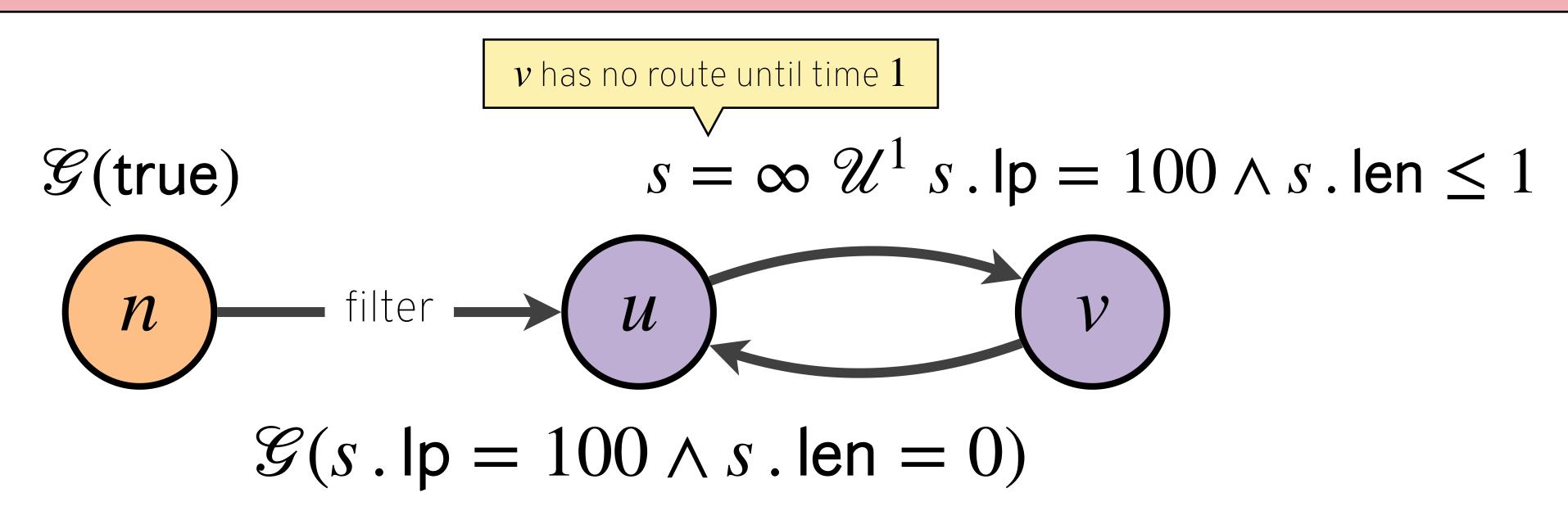
$$\mathcal{G}(s \cdot \text{lp} = 100 \land s \cdot \text{len} = 0)$$

 $P \ \mathcal{U}^t \ Q \ (P \ ext{until} \ Q \ ext{at} \ t)$: until time t, P holds; at and after t, Q holds

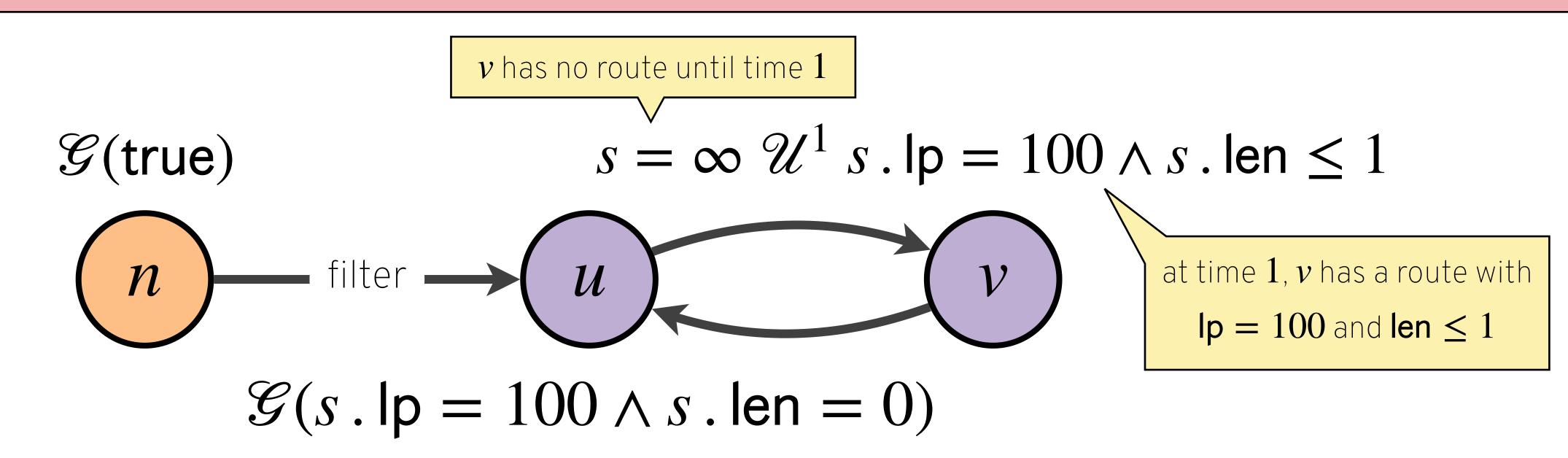
$$\mathcal{G}(\text{true}) \qquad s = \infty \ \mathcal{U}^1 \ s . \ \text{lp} = 100 \land s . \ \text{len} \le 1$$

$$\mathcal{G}(s . \ \text{lp} = 100 \land s . \ \text{len} = 0)$$

 $P \ \mathcal{U}^t \ Q \ (P \ ext{until} \ Q \ ext{at} \ t)$: until time t, P holds; at and after t, Q holds



 $P \ \mathcal{U}^t \ Q \ (P \ ext{until} \ Q \ ext{at} \ t)$: until time t, P holds; at and after t, Q holds



Soundness Theorem



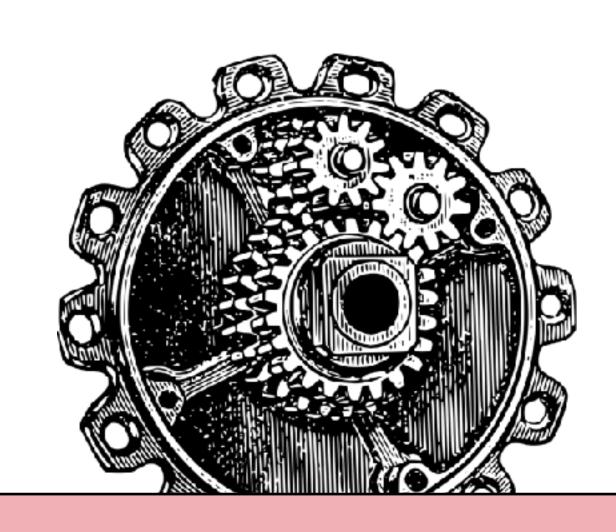
If interface $m{A}$ satisfies the base and inductive checks for all nodes, then $m{A}$ includes all states computable via (monolithic) simulation.



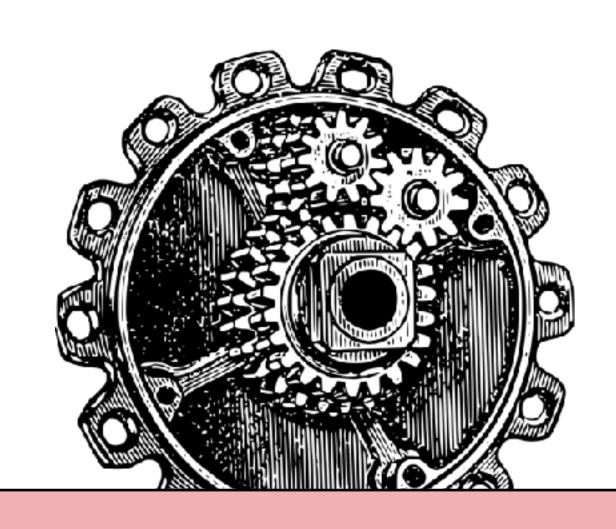
If interface $m{A}$ satisfies the base and inductive checks for all nodes, then $m{A}$ includes all states computable via (monolithic) simulation.

Proof by induction on time.

WHEN SHEET AND THE STATE OF THE



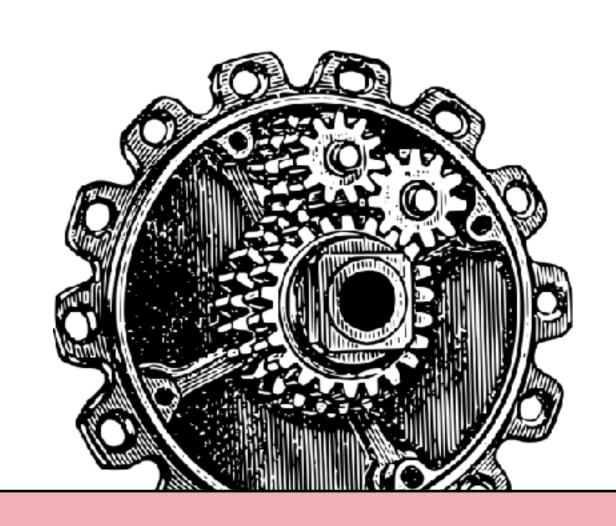
define network semantics in C# or via configurations (via Batfish)



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write interfaces using C# library of temporal operators ($\mathcal{G}, \mathcal{U}^t, \mathcal{F}^t$)



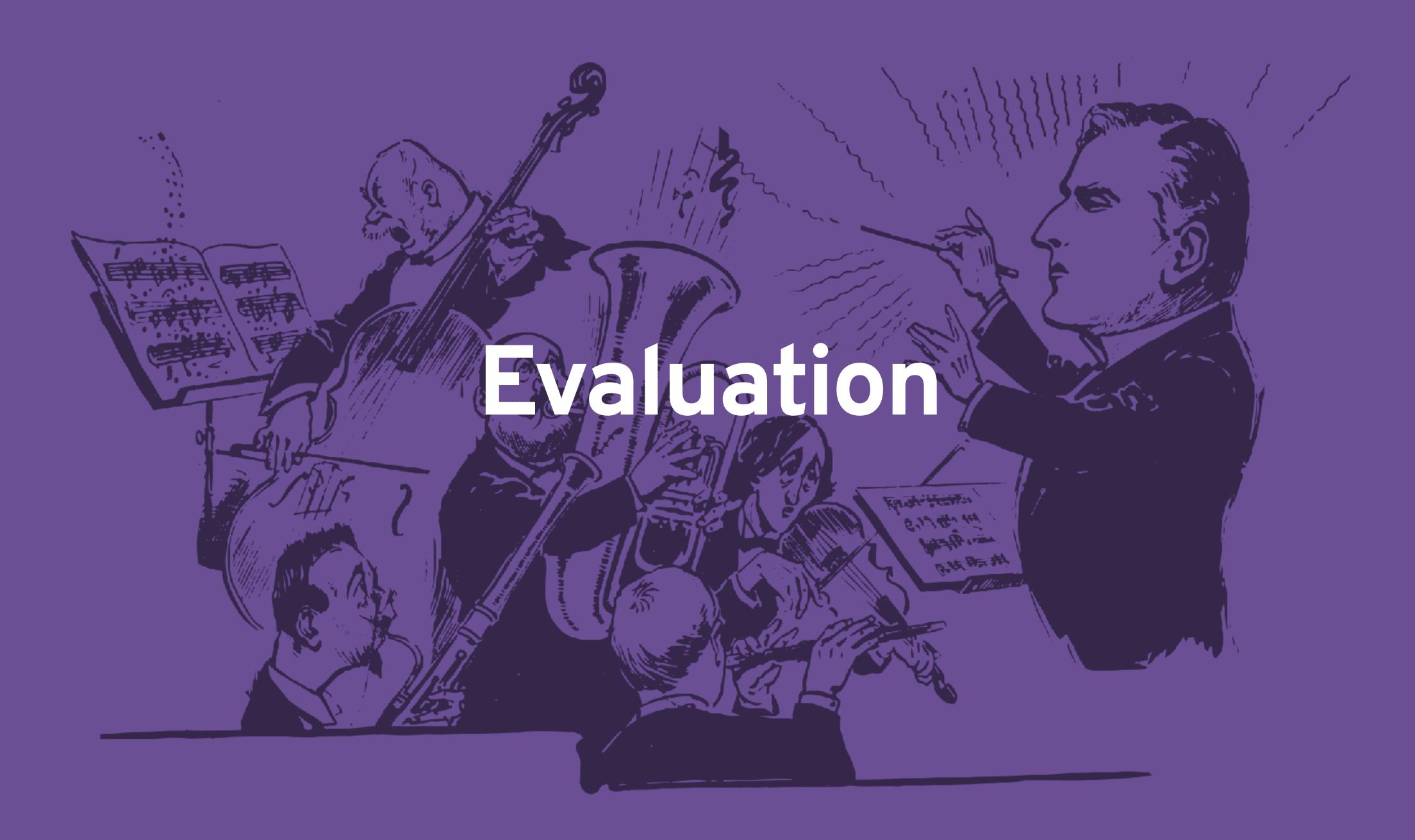
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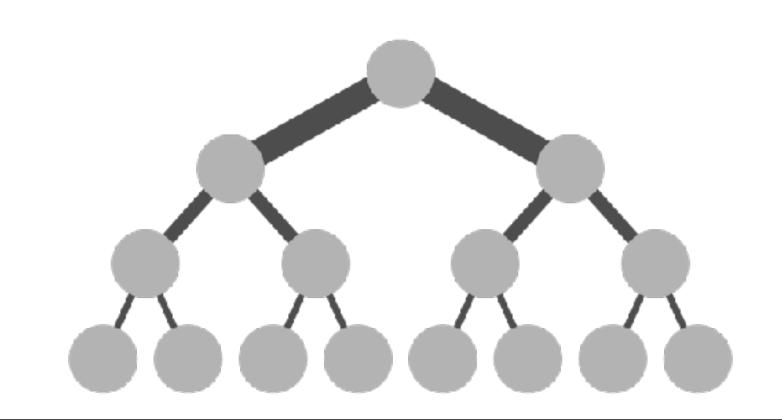
check VCs *in parallel* on every node using Satisfiability Modulo
Theories (SMT) solver



does Timepiece scale to large networks?

does Timepiece handle complex policies?

how easy is it to write invariants for different properties?



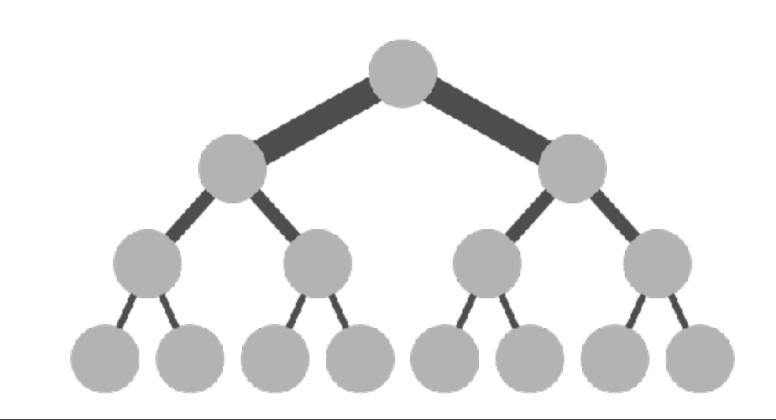
Fat-tree data center networks

C# model of eBGP routing protocol

20-2000 nodes

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Fat-tree data center networks

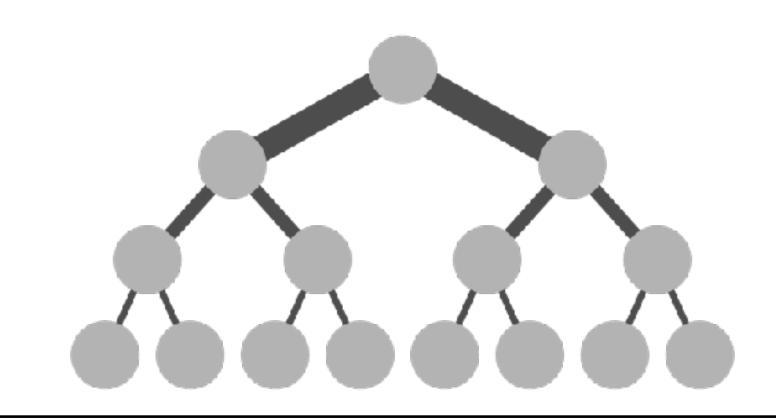
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Internet2 wide-area network 102,753 lines of Juniper configuration code 263 nodes (10 internal, 253 external)

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Fat-tree data center networks

C# model of eBGP routing protocol

20-2000 nodes

Reachability

Path length

Valley freedom

Hijack filtering



Internet2 wide-area network 102,753 lines of Juniper configuration code 263 nodes (10 internal, 253 external)

No transit

on Microsoft Azure D96s VM with 96 vCPUs and 384GB RAM

Benchmark

Reachability

Path length

Valley freedom

Hijack filtering

No transit

Benchmark	Network LoC		
Reachability	81		
Path length	88		
Valley freedom	89		
Hijack filtering	146		
No transit	88 (+102,753)		

Benchmark	Network LoC	Annotation LoC
Reachability	81	3
Path length	88	7
Valley freedom	89	12
Hijack filtering	146	21
No transit	88 (+102,753)	5

Benchmark	Network LoC	Annotation LoC	Nodes
Reachability	81	3	2000
Path length	88	7	2000
Valley freedom	89	12	2000
Hijack filtering	146	21	2000
No transit	No transit 88 (+102,753)		263

Benchmark	Network LoC	Annotation LoC	Nodes	Monolithic time
Reachability	81	3	2000	14s
Path length	88	7	2000	>2h
Valley freedom	89	12	2000	>2h
Hijack filtering	146	21	2000	>2h
No transit	88 (+102,753)	5	263	>2h

Benchmark	Network LoC	Annotation LoC	Nodes	Monolithic time	Modular time
Reachability	81	3	2000	14s	28s
Path length	88	7	2000	>2h	1204s
Valley freedom	89	12	2000	>2h	398s
Hijack filtering	146	21	2000	>2h	142s
No transit	88 (+102,753)	5	263	>2h	38s

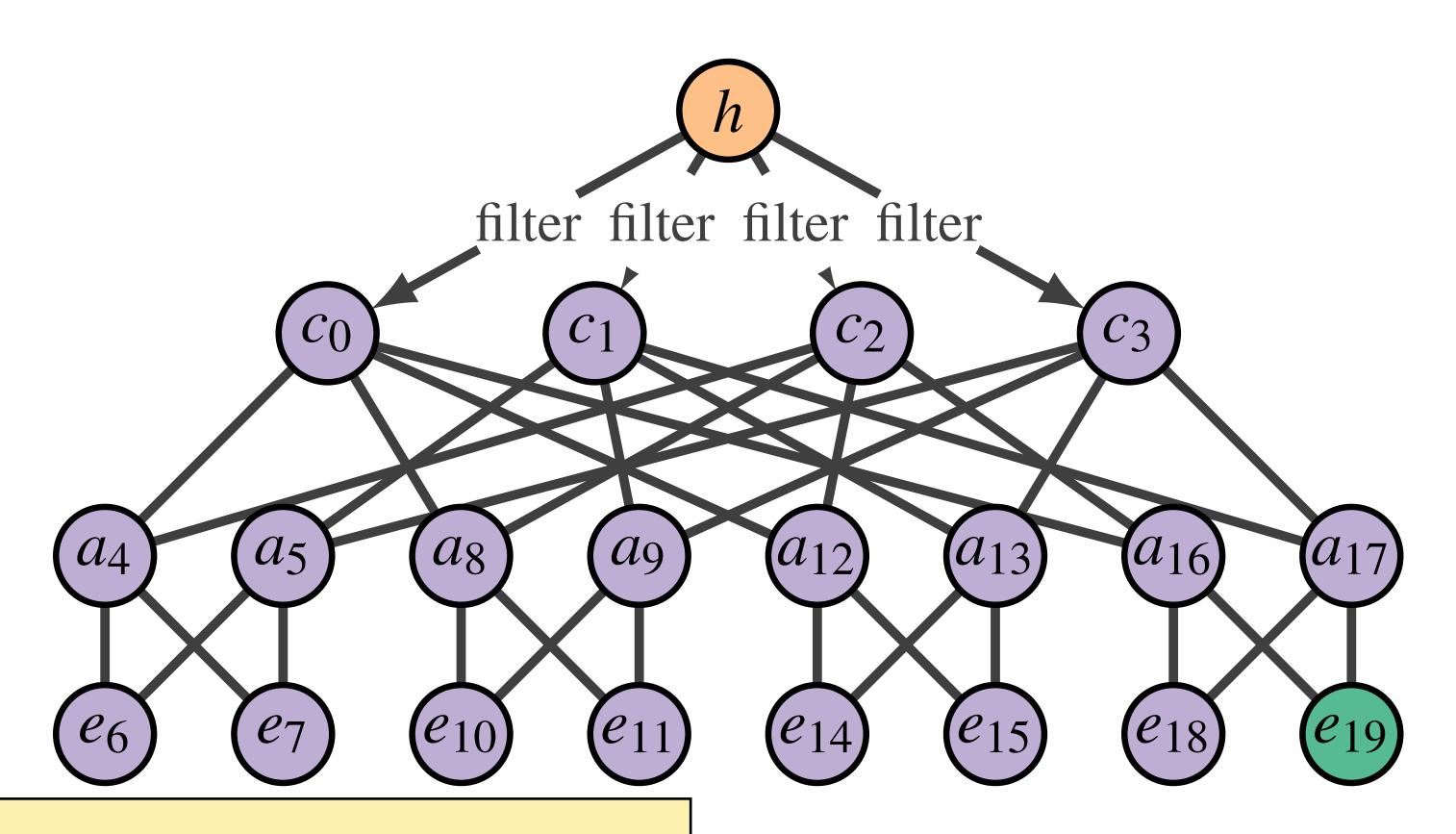
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Fat-tree Hijack Filtering

BGP misconfiguration/attack:

a "hijacker" node announces it has a path to a prefix it doesn't own, misleading others to route through the hijacker

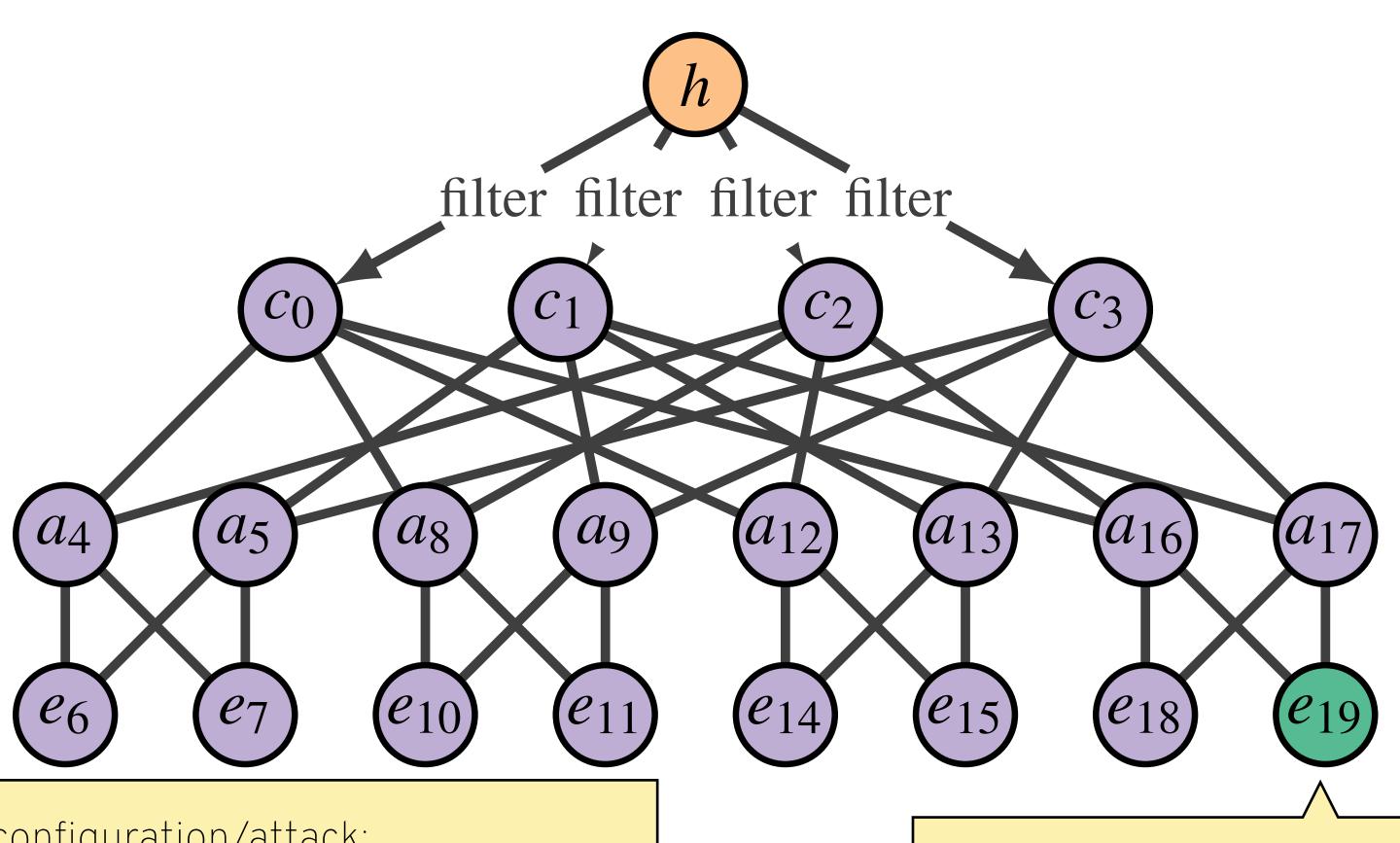
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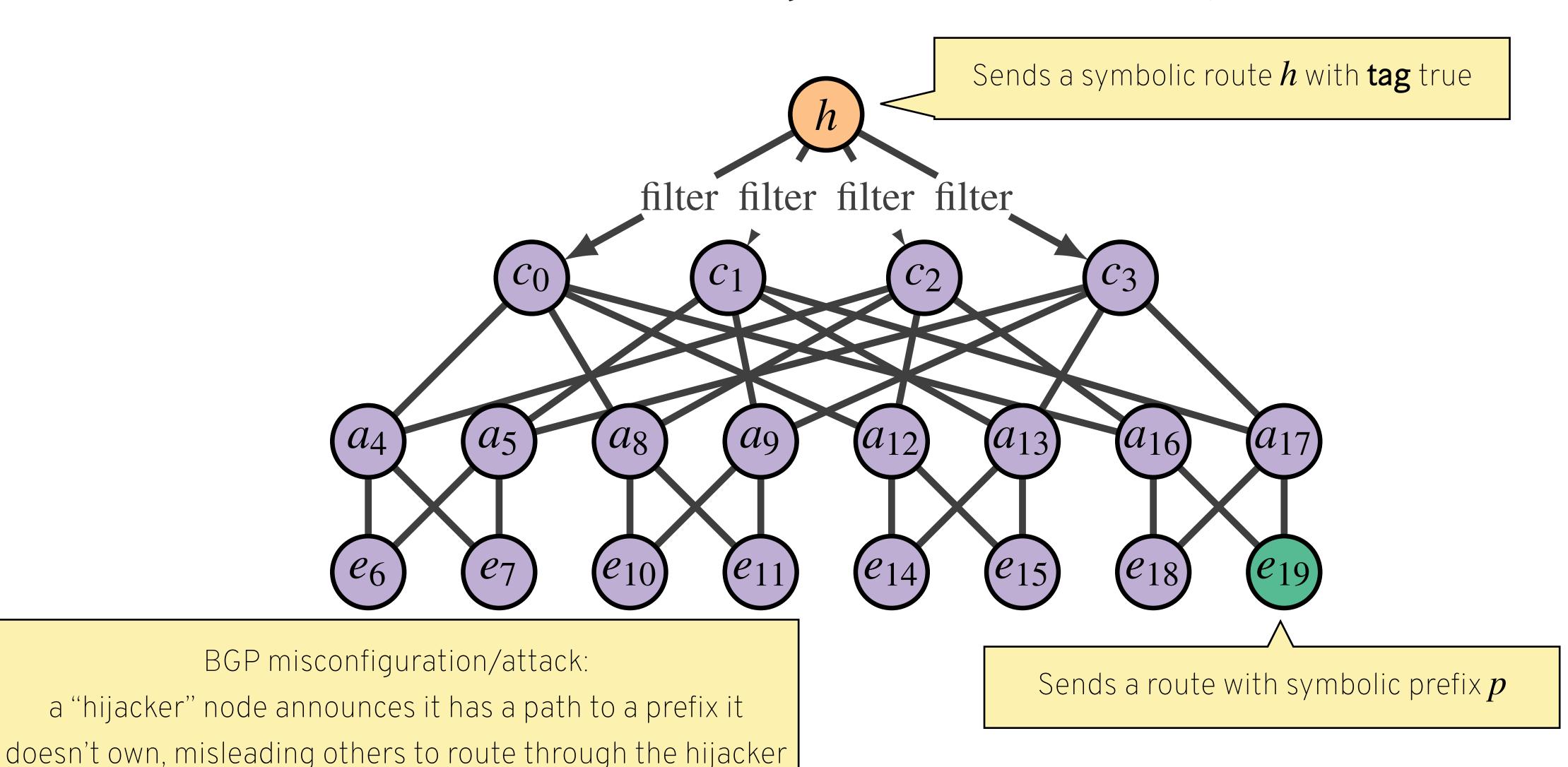
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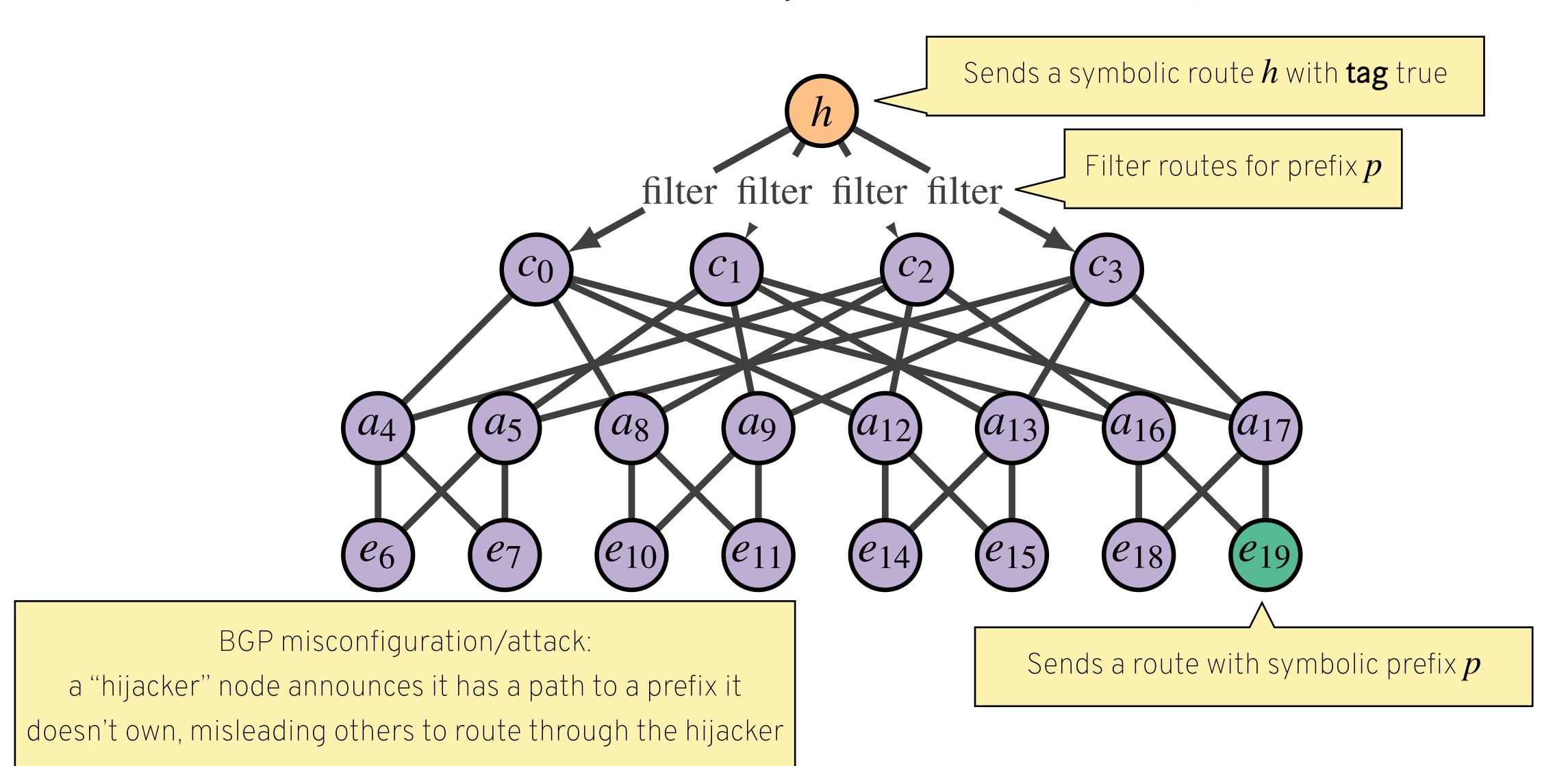


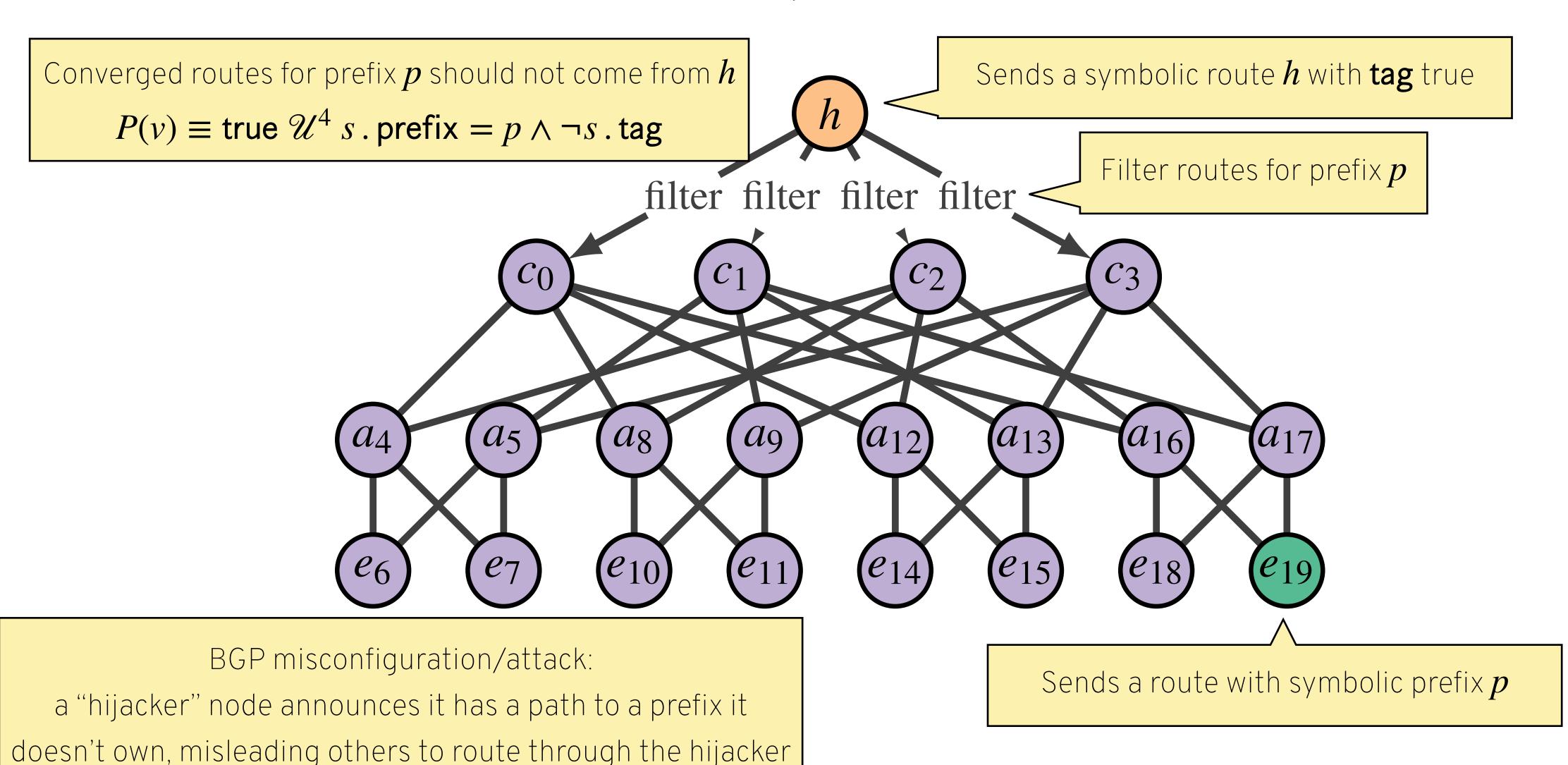
BGP misconfiguration/attack:

a "hijacker" node announces it has a path to a prefix it doesn't own, misleading others to route through the hijacker

Sends a route with symbolic prefix p



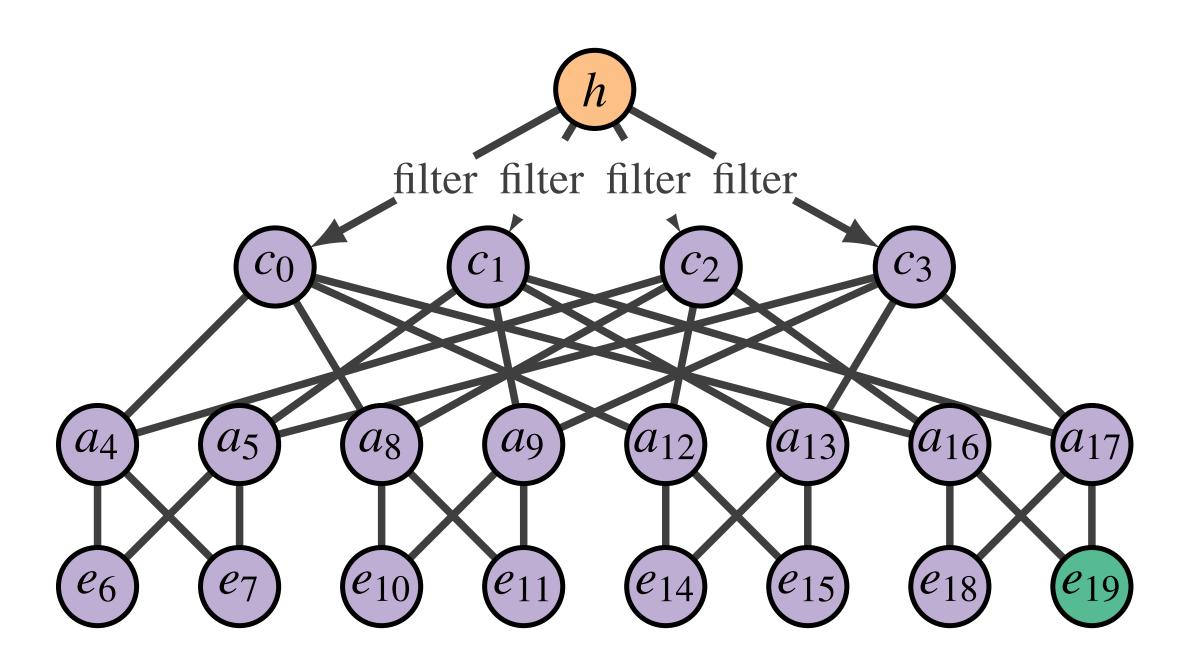




Converged routes for prefix $oldsymbol{p}$ should not come from $oldsymbol{h}$

$$P(v) \equiv \text{true } \mathcal{U}^4 \ s \text{ . prefix} = p \land \neg s \text{ . tag}$$

Interface **composes** an "eventual invariant" with a "safety invariant"

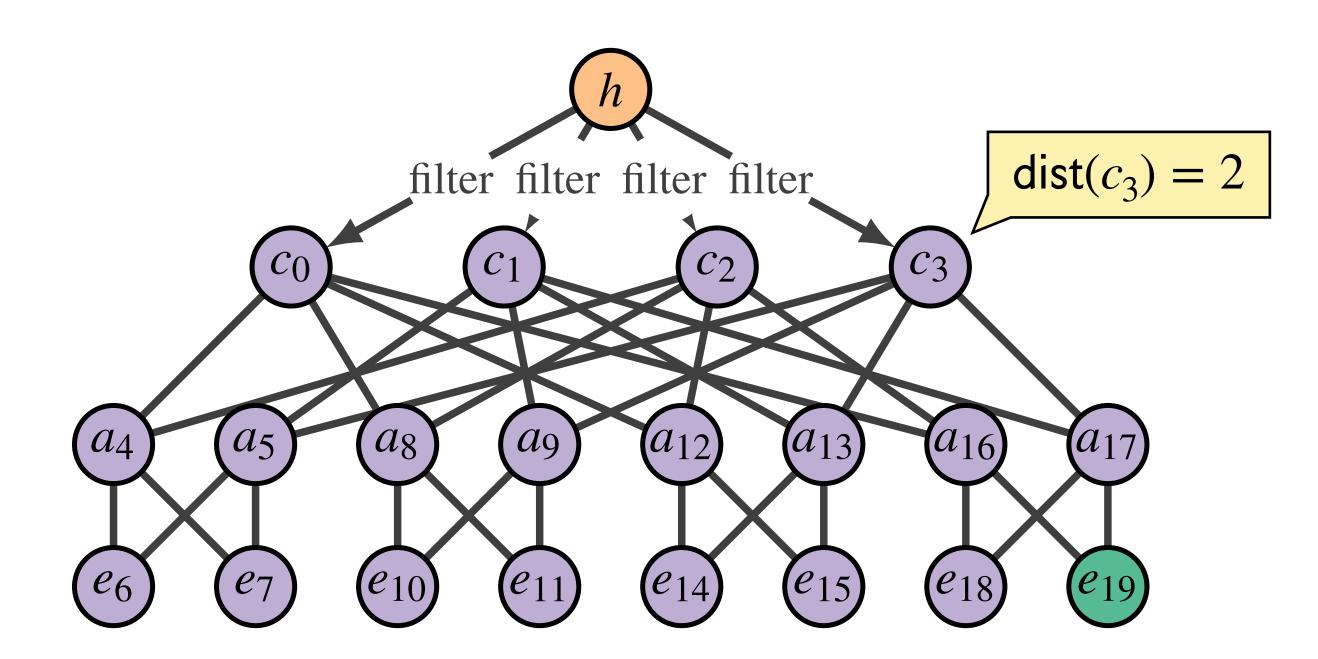


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All nodes' interfaces are parameterized by their distance $\operatorname{dist}(v)$ from e_{19}



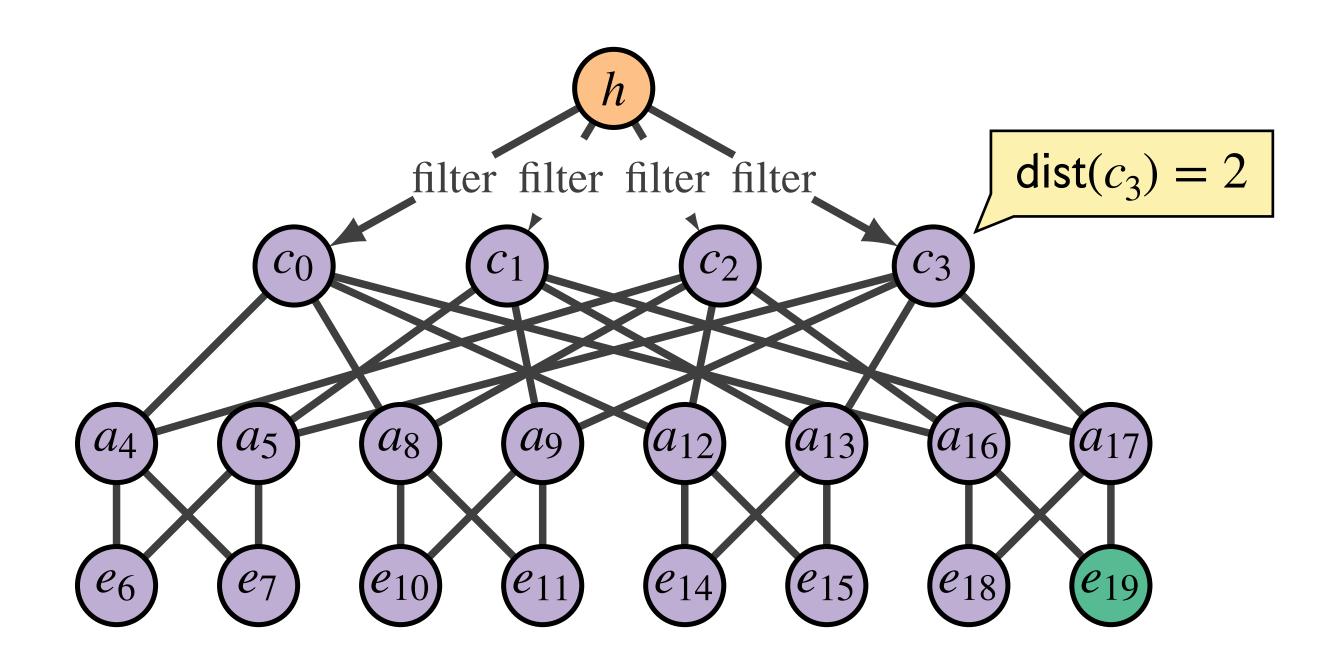
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Interface **composes** an "eventual invariant" with a "safety invariant"

All nodes' interfaces are parameterized by their distance ${\sf dist}(v)$ from e_{19}

Nodes are **eventually** "internally reachable" true $\mathcal{U}^{\text{dist}(v)}$ s. prefix = $p \land \neg s$. tag



Converged routes for prefix $oldsymbol{p}$ should not come from h

$$P(v) \equiv \text{true } \mathcal{U}^4 \ s \text{ . prefix} = p \land \neg s \text{ . tag}$$

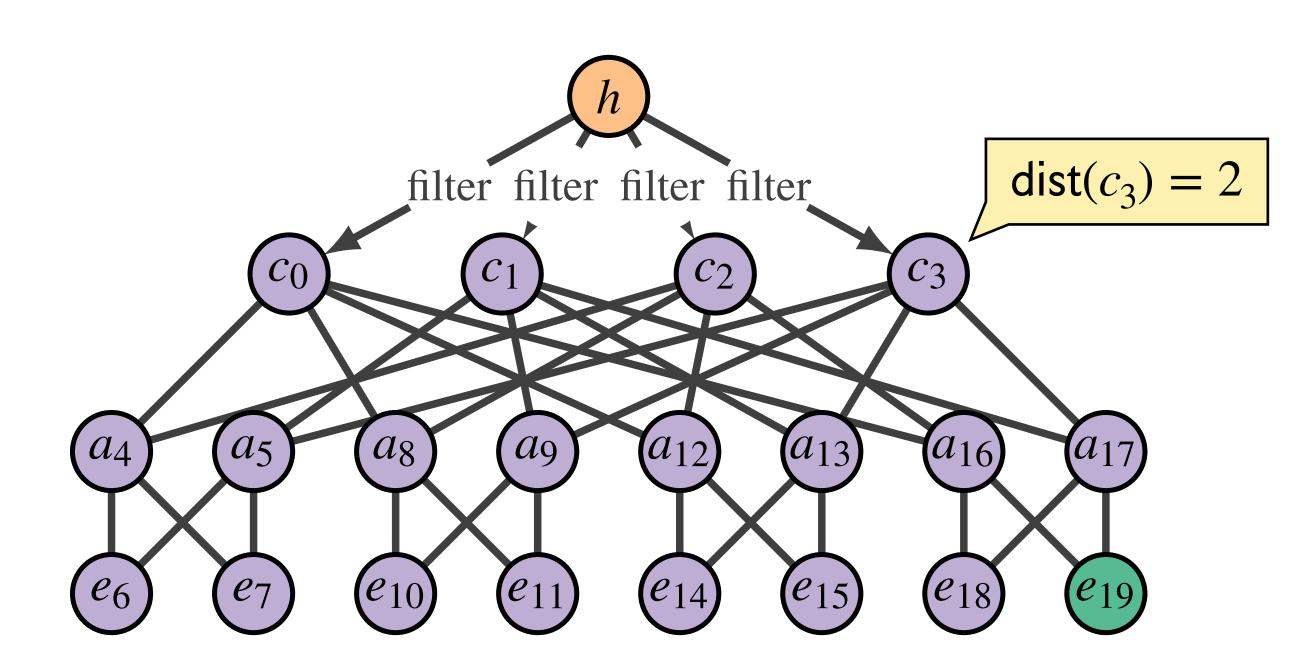
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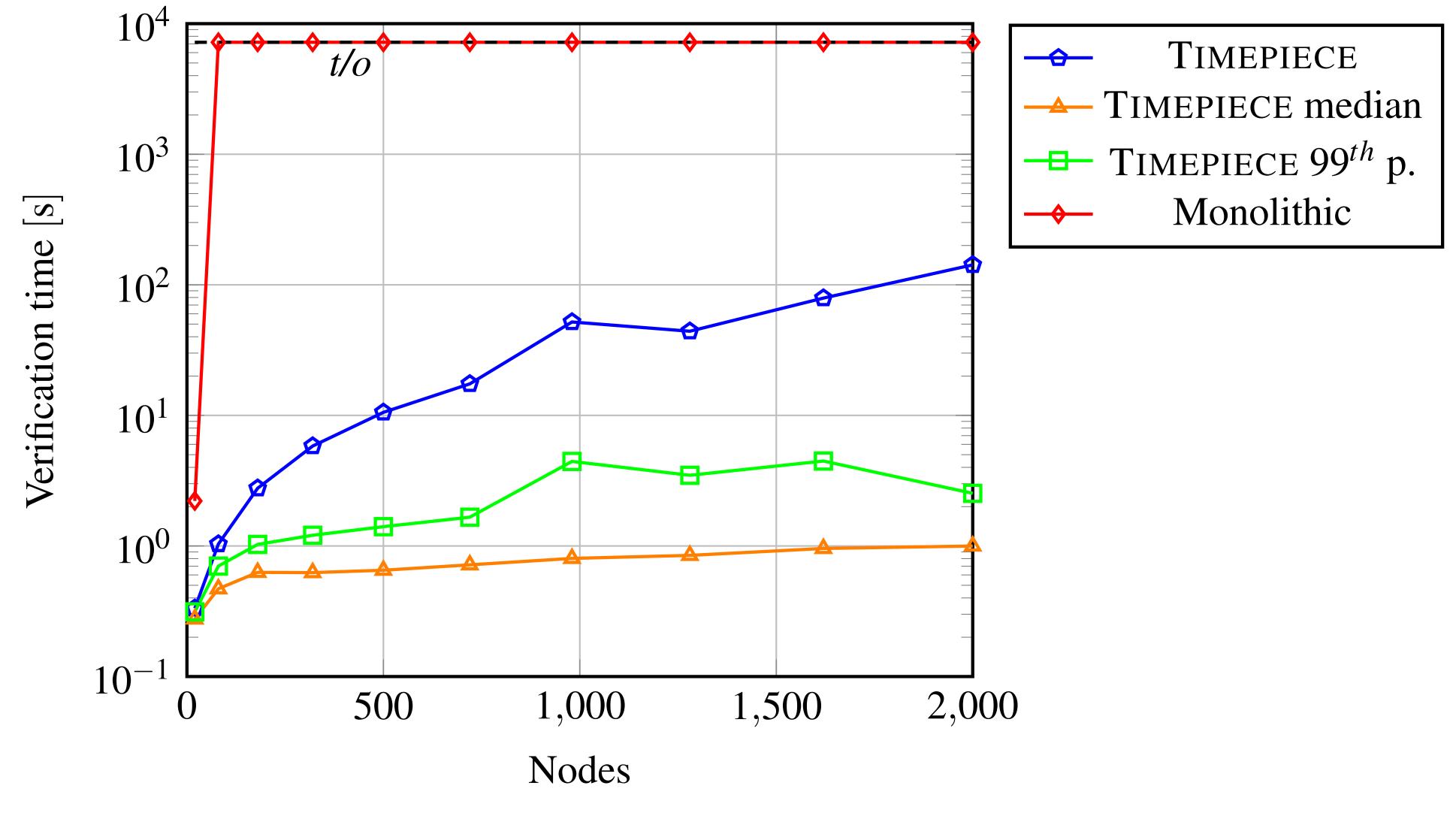
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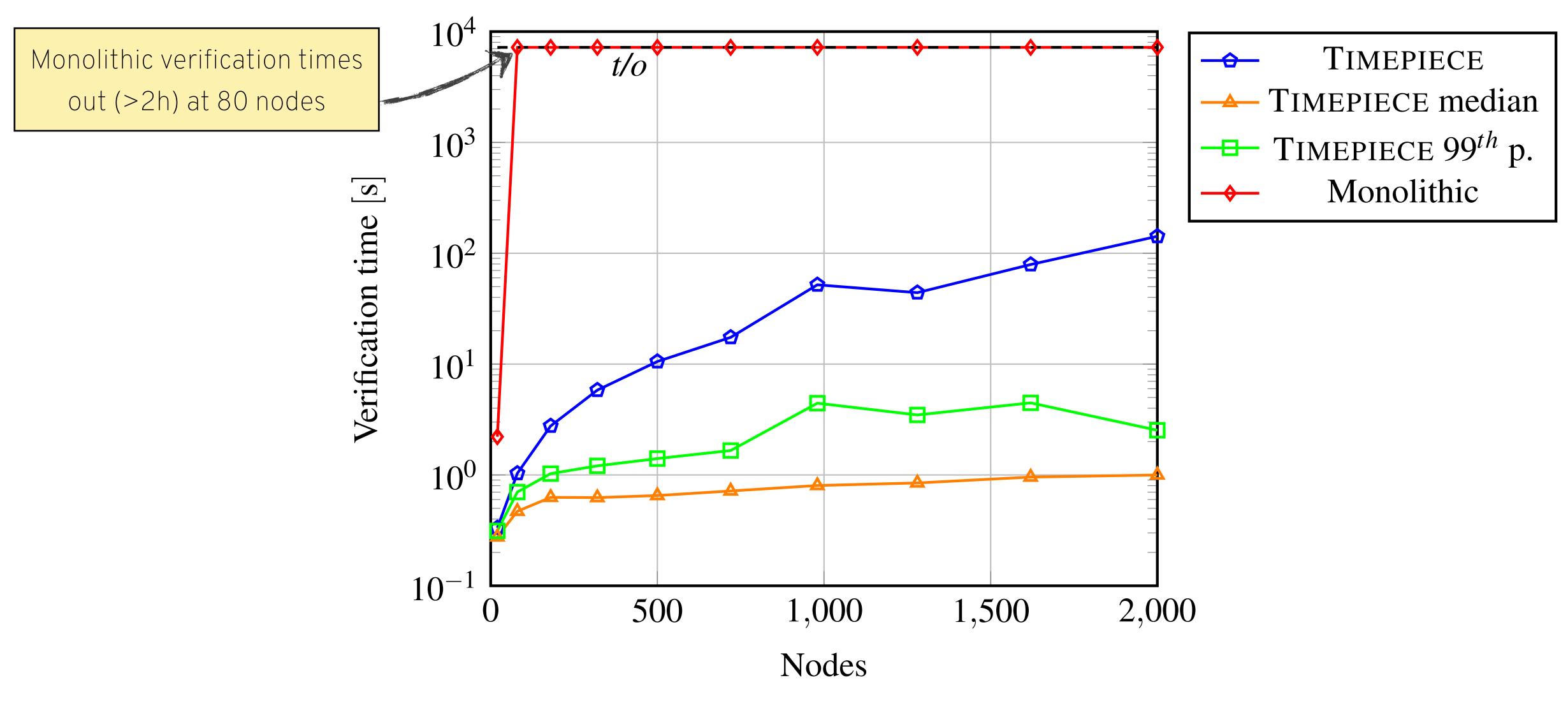
Nodes are **eventually** "internally reachable" $\mathsf{true}\ \mathscr{U}^{\mathsf{dist}(v)}\ s\ .\ \mathsf{prefix} = p \land \neg s\ .\ \mathsf{tag}$

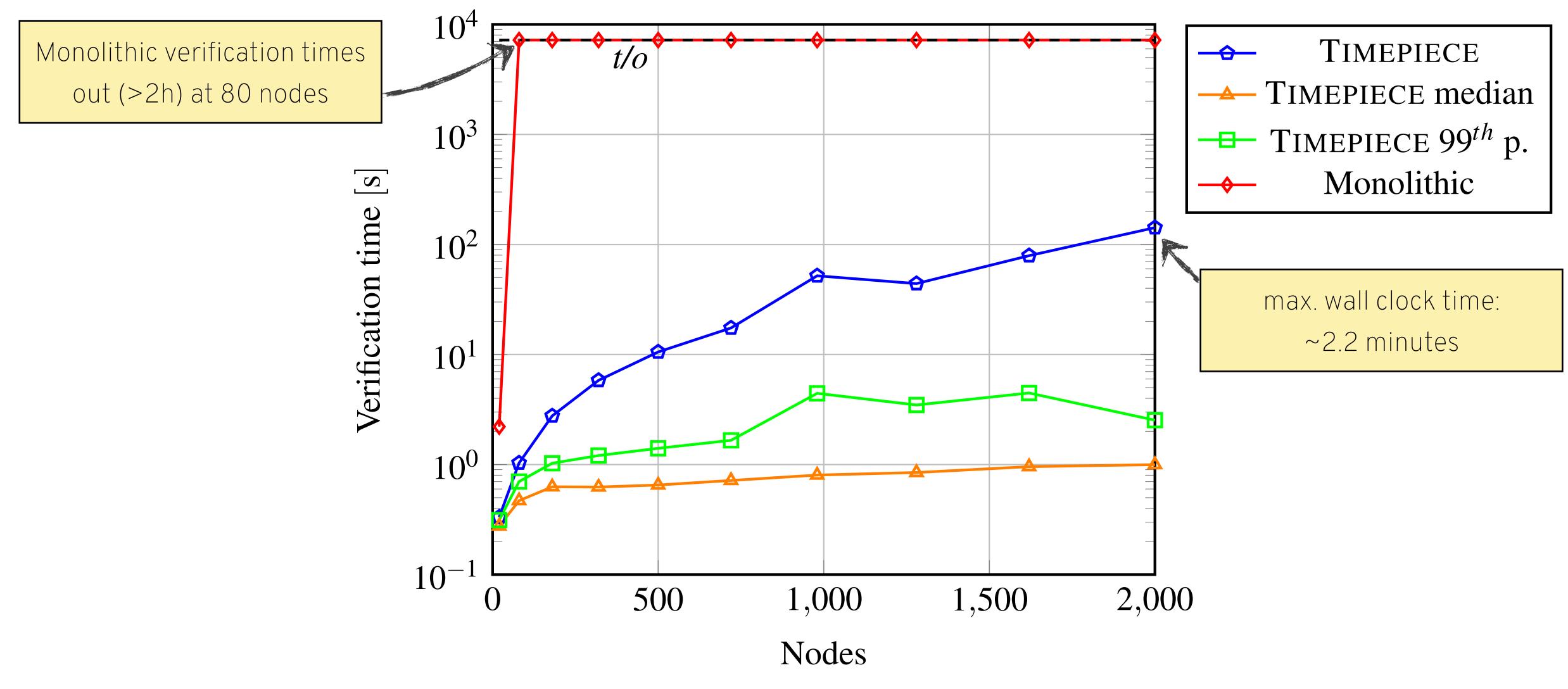
Nodes **never** use hijacking routes

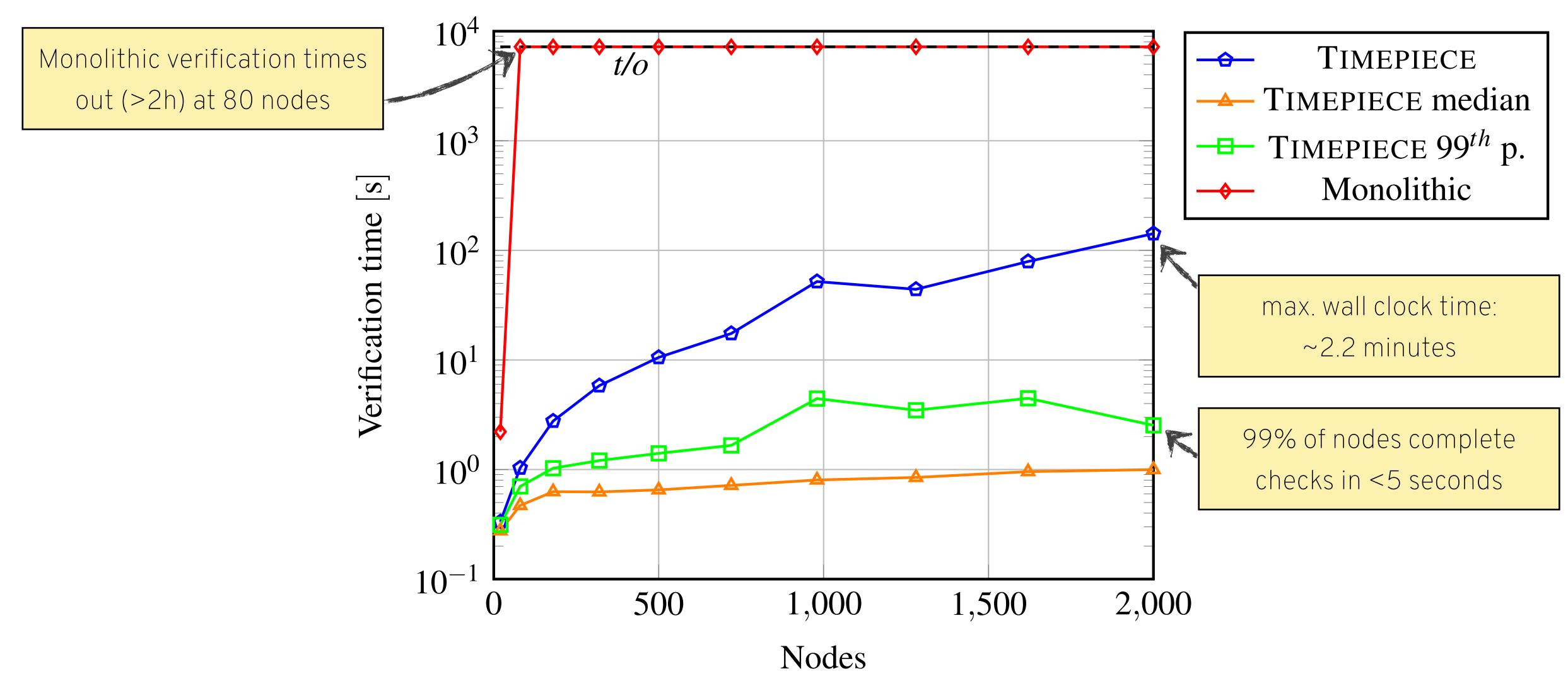
$$\mathcal{G}(s \cdot \mathsf{prefix} = p \to \neg s \cdot \mathsf{tag})$$

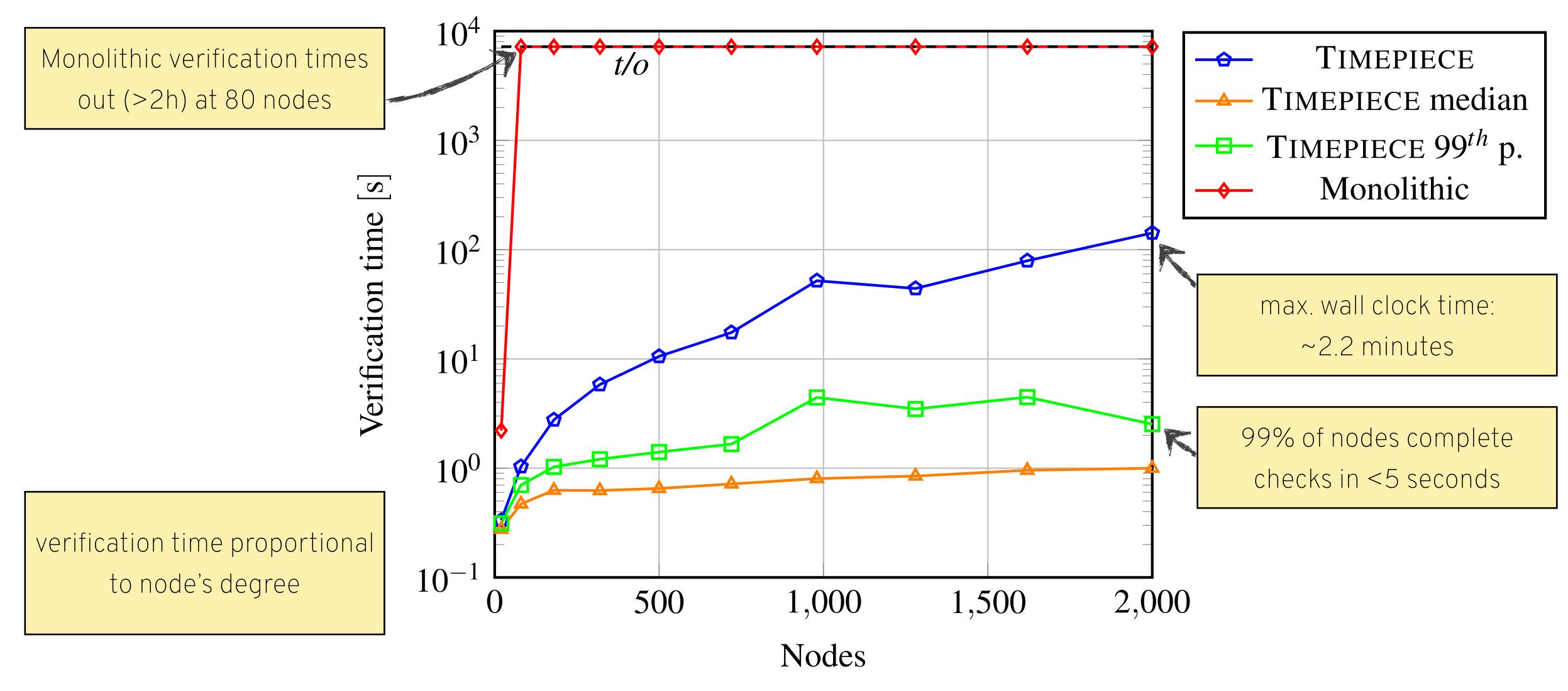














Big, complex control planes need modular tools



Big, complex control planes need modular tools

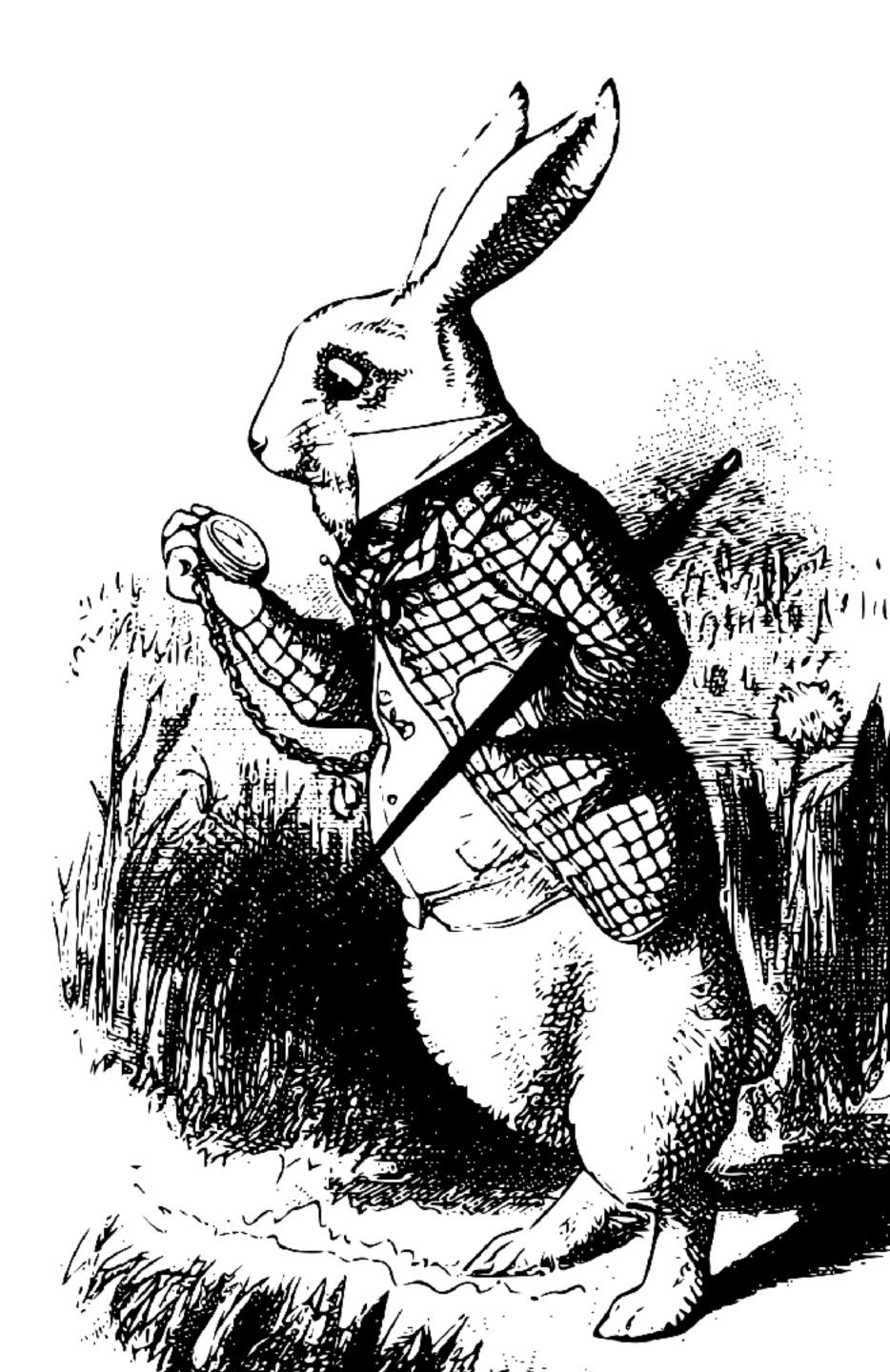
Temporal invariants provide a correct basis for modular verification



Big, complex control planes need modular tools

Temporal invariants provide a correct basis for modular verification

Scale to thousands of nodes & complex policies



Big, complex control planes need modular tools

Temporal invariants provide a correct basis for modular verification

Scale to thousands of nodes & complex policies

Read the paper to learn more!



Thank You.



Our paper

I'm looking for a job! cs.princeton.edu/~tthijm



Tim Alberdingk Thijm

Princeton



Ryan Beckett

Microsoft Research

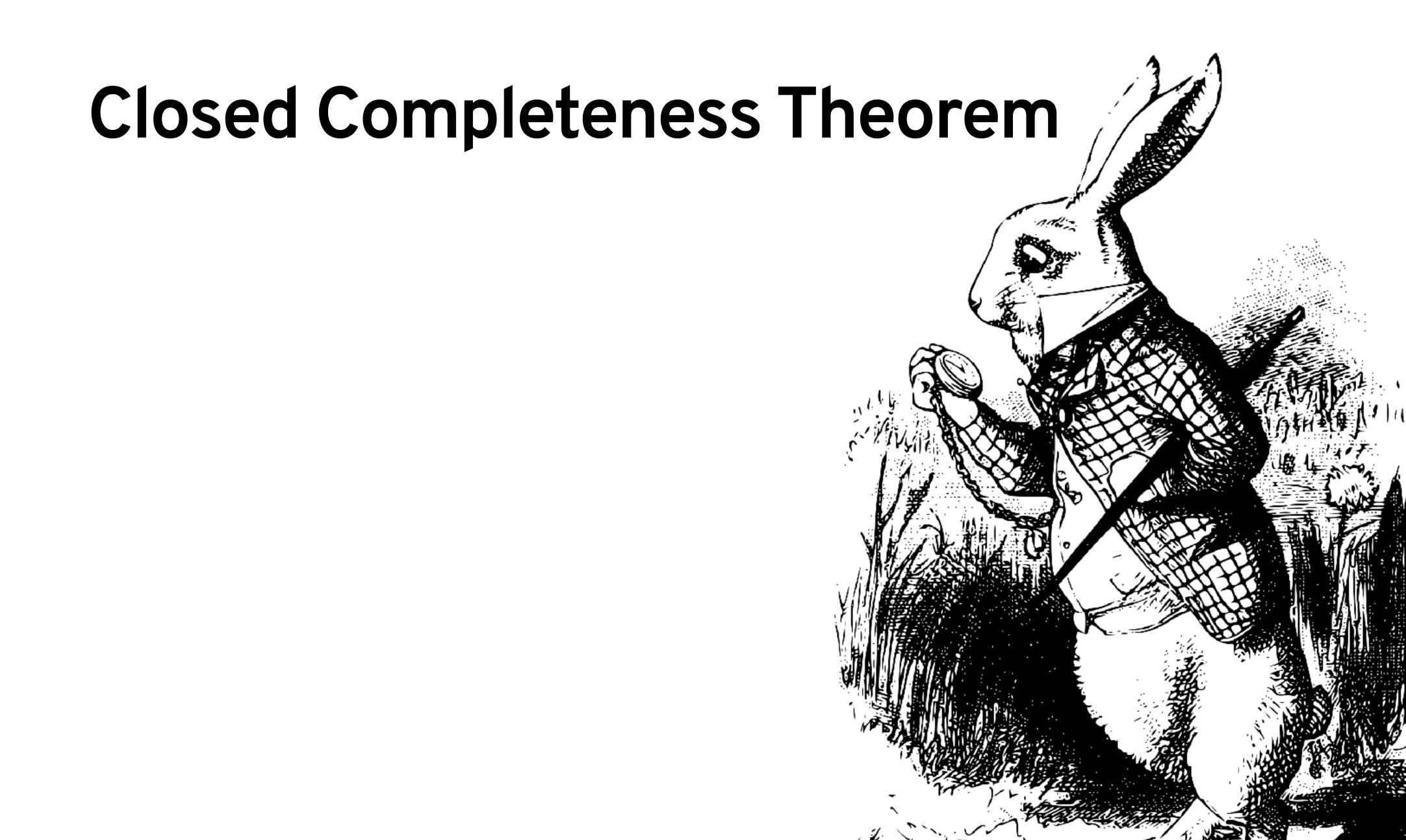


Aarti Gupta
Princeton



Dave Walker
Princeton

Extra slides



Closed Completeness Theorem

Starting from fixed initial routes, if $\sigma(v)(t)$ is the (monolithic) state of node v at time t, then the interface $A(v)(t) = \{\sigma(v)(t)\}$ satisfies the base and inductive checks for all nodes.

Closed Completeness Theorem

Starting from fixed initial routes, if $\sigma(v)(t)$ is the (monolithic) state of node v at time t, then the interface $A(v)(t) = \{\sigma(v)(t)\}$ satisfies the base and inductive checks for all nodes.

Proof by induction on time.

Benchmark

Reachability

Path length

Valley freedom

Hijack filtering

No transit

Benchmark	Nodes
Reachability	20-2000
Path length	20-2000
Valley freedom	20-2000
Hijack filtering	20-2000
No transit	263

Benchmark	Nodes	Network LoC
Reachability	20-2000	81
Path length	20-2000	88
Valley freedom	20-2000	89
Hijack filtering	20-2000	146
No transit	263	88 (+102,753)

Benchmark	Nodes	Network LoC	Annotation LoC
Reachability	20-2000	81	3
Path length	20-2000	88	7
Valley freedom	20-2000	89	12
Hijack filtering	20-2000	146	21
No transit	263	88 (+102,753)	5

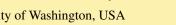
Benchmark	Nodes	Network LoC	Annotation LoC	Monolithic hits 2h timeout?
Reachability	20-2000	81	3	No (fixed dest.) 80 nodes (symbolic dest.)
Path length	20-2000	88	7	80 nodes (fixed dest.) 20 nodes (symbolic dest.)
Valley freedom	20-2000	89	12	180 nodes
Hijack filtering	20-2000	146	21	80 nodes (fixed dest.) 20 nodes (symbolic dest.)
No transit	263	88 (+102,753)	5	Yes

Benchmark	Nodes	Network LoC	Annotation LoC	Monolithic hits 2h timeout?	Modular verification time
Reachability	20-2000	81	3	No (fixed dest.) 80 nodes (symbolic dest.)	28s (fixed 2000 nodes) 336s (symbolic 2000 nodes)
Path length	20-2000	88	7	80 nodes (fixed dest.) 20 nodes (symbolic dest.)	1204s (fixed 2000 nodes) 3953s (symbolic 2000 nodes)
Valley freedom	20-2000	89	12	180 nodes	398s (fixed 2000 nodes) 3506s (symbolic 1280 nodes)
Hijack filtering	20-2000	146	21	80 nodes (fixed dest.) 20 nodes (symbolic dest.)	142s (2000 nodes) 2196s (symbolic 2000 nodes)
No transit	263	88 (+102,753)	5	Yes	38s

Satisfiability Modulo Theories (SMT)-based verification

Scalable Verification of Border Gateway Protocol Configurations with an SMT Solver

> Konstantin Weitz Doug Woos Emina Torlak Michael D. Ernst Arvind Krishnamurthy Zachary Tatlock University of Washington, USA



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A General Approach to Network Configuration Verification

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Aarti Gupta Princeton University

David Walker Princeton University

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simulation-based verification

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modular SMT-based verification

LIGHTYEAR: Using Modularity to Scale BGP Control Plane Verification

Alan Tang University of California, Los Angeles Todd Millstein

Ryan Beckett Karthick Jayaraman Microsoft

George Varghese UCLA

Microsoft

Kirigami, the Verifiable Art of Network Cutting

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Challenges

