

The Logical Approach to Stack Typing*

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ABSTRACT

We develop a logic for reasoning about *adjacency* and *separation* of memory blocks, as well as *aliasing* of pointers. We provide a memory model for our logic and present a sound set of natural deduction-style inference rules. We deploy the logic in a simple type system for a stack-based assembly language. The connectives for the logic provide a flexible yet concise mechanism for controlling allocation, deallocation and access to both heap-allocated and stack-allocated data.

Categories and Subject Descriptors

D.3.1 [Programming Languages]: Formal Definitions and Theory; F.3.1 [Logics and Meanings of Programs]: Specifying and Reasoning about Programs; F.3.2 [Logics and Meanings of Programs]: Semantics of Programming Languages

General Terms

Reliability, Security, Languages, Verification

Keywords

stack, memory management, ordered logic, bunched logic, linear logic, type systems, typed assembly language

1. INTRODUCTION

In a proof-carrying code system, a low-level program is accompanied by a proof that the program will not perform some “bad” action when executed. A host can verify that the program will be well-behaved by checking the proof before running the code, without having to trust the program or the compiler. Proof-carrying code technology not only

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enables untrusting hosts to verify the safety of programs they would like to use for their own purposes, but also allows them to donate idle computational resources to supercomputing projects such as SETI@Home [33] without having to be afraid that their system will be corrupted [4].

In order to develop proof-carrying code technology to the point where PCC systems can enforce the complex security policies required for applications such as grid computing, researchers must invent convenient abstractions that help structure proofs of common program properties. These abstractions should be flexible yet concise and relatively easy for the compiler implementor to understand and manipulate. The most successful abstractions will make it easier to build certifying compilers. They may also find their way from low-level compiler intermediate languages into general-purpose programming languages. In fact, we have already seen such migration: Grossman et al.’s Cyclone [10] uses Tofte and Talpin’s [37] region abstractions; DeLine and Fahndrich’s Vault [7] incorporates Walker et al.’s capabilities [40]; and O’Callahan [20] improves the JVML type system using mechanisms from Morrisett et al.’s STAL [16].

In this paper, we focus on reasoning about memory management as this domain tests our ability to encode a very wide range of invariants. Moreover, many other safety properties rely directly on our ability to reason about memory precisely. In order to be able to enforce higher-level security policies and other program properties statically, we must be able to provide an accurate picture of memory first.

Our main contribution is a logic for reasoning about *adjacency* and *separation* of memory blocks as well as aliasing of pointers. It is the first time that anyone has developed a simple and concise theory for reasoning about all of these concepts simultaneously. The logic was inspired by both the work of Polakow and Pfennig on ordered linear logic [28, 29, 27] and recent work on logics and type systems for reasoning about aliasing [16, 35, 41, 40, 22, 32, 12]. It is also related to Petersen et al.’s calculus for reasoning about data layout [25].

We use the logic to reason about stack allocation in a simple typed assembly language. Our presentation of typed assembly language is also new. We encode the state of our abstract machine entirely using our new substructural logic and consequently, the language has the feel of Hoare logic. However, we also wrap logical formulae up in higher-order types, which provides us with a simple way to extend traditional first-order Hoare logic to the higher-order domain of type theory.

In the next section, we introduce our state logic (SL). We

discuss the meaning of judgments and formulae in terms of a concrete memory model. We also provide the logical inference rules and prove a few simple metatheoretic properties. In section 3, we introduce our typed assembly language and show how to use our logic to reason about the stack. A proof of progress and preservation lemmas demonstrates that our type system is sound. In section 4, we discuss related work in greater detail and, in section 5, we suggest some directions for future research.

2. SL: A STATE LOGIC

In this section, we describe SL, a logic for reasoning about adjacency, separation and aliasing of memory blocks. The power of the logic comes from the fact that adjacency and separation properties are contained directly within the connectives of the logic. Most previous work with similar power has its roots in classical Hoare logic, where one reasons about adjacency or separation by equating locations with integers and reasoning about them using arithmetic. While reasoning exclusively with integers and arithmetic is possible, this technique results in an overflow of auxiliary arithmetic equations to keep track of adjacency or aliasing information. SL specifications can be much simpler since our rich logic allows us to omit these auxiliary arithmetic equations.

Before introducing the logic itself, we will introduce the values and memories that will serve as a model for the logic.

2.1 Values

We will be reasoning about several different sorts of values including integers, code locations, which contain executable code, proper memory locations (aka heap locations) and a fixed, finite set of registers. We will also need to reason about *store values*, the set of values that may be stored in a register or in a proper memory location. Registers are not included in the set of store values.

$$\begin{array}{lll} \text{Integers} & i & \in \text{Int} \\ \text{Proper Locations} & \ell & \in \text{Loc} \\ \text{Registers} & r & \in \text{Reg} \\ \text{Code Locations} & c & \in \text{Codeloc} \\ \text{Store Values} & h & \in \text{Sval} = (\text{Int} \cup \text{Loc} \cup \text{Codeloc}) \end{array}$$

In order to discuss adjacent locations, we take the further step of organizing the set *Loc* in a total order given by the relation \leq . We also assume a total function $\text{succ} : \text{Loc} \rightarrow \text{Loc}$, which maps a location ℓ to the location that immediately follows it. We write $\text{adj}(\ell, \ell')$ when $\ell' = \text{succ}(\ell)$. We write $\ell + i$ as syntactic sugar for $\text{succ}^i(\ell)$ and $\ell - i$ for the location ℓ' such that $\ell = \text{succ}^i(\ell')$.

Types. Our subsequent semantics for formulae will incorporate a simple typing judgment for values. We give integers and locations singleton types which identify them exactly. Code locations will be given code types as described by a code context. These code types have the form $(F) \rightarrow 0$, where F is a logical formula that describes requirements that must be satisfied by the state of the abstract machine before it is safe to jump to the code. Code can only “return” by explicitly jumping to a continuation (a return address) that it has been passed as an argument and therefore our code types do not have proper return types. Abstract types α arise through existential or universal quantification in for-

mulae.

$$\begin{array}{ll} \text{Types} & \tau ::= \alpha \mid \mathbf{S}(i) \mid \mathbf{S}(\ell) \mid (F) \rightarrow 0 \\ \text{Code Contexts} & \Psi ::= \cdot \mid \Psi, c : (F) \rightarrow 0 \end{array}$$

Store values are given types via a judgment of the form $\vdash^\Psi h : \tau$. Since the code context never changes in a typing derivation, we normally omit it from the judgment form as in the rules below.

$$\frac{}{\vdash i : \mathbf{S}(i)} \text{ (int)} \quad \frac{}{\vdash \ell : \mathbf{S}(\ell)} \text{ (loc)}$$

$$\frac{\Psi(c) = (F) \rightarrow 0}{\vdash c : (F) \rightarrow 0} \text{ (code)}$$

2.2 Memories

A memory is a partial map from generic locations g to store values h .

$$\begin{array}{ll} \text{Generic Loc's} & g \in (\text{Loc} \cup \text{Reg}) \\ \text{Memories} & m \in (\text{Loc} \cup \text{Reg}) \rightarrow \text{Sval} \end{array}$$

Registers are special (second-class) locations that may appear in the domain of a memory but may not appear stored in other locations.

We use the following notation to manipulate memory.

- $\text{dom}(m)$ denotes the domain of the memory m
- $m(g)$ denotes the store value at location g
- $m[g := h]$ denotes a memory m' in which g maps to h but is otherwise the same as m . If $g \notin \text{dom}(m)$ then the update is undefined.
- Given a set of locations $X \subseteq \text{Loc}$, $\lceil X \rceil$ is the greatest member (the *supremum*) of the set and $\lfloor X \rfloor$ is the least member (the *infimum*) of the set according to the total order \leq . We also let $\lceil X \cup R \rceil = \lceil X \rceil$ and $\lfloor X \cup R \rfloor = \lfloor X \rfloor$ when $R \subseteq \text{Reg}$. $\lceil \emptyset \rceil$ and $\lfloor \emptyset \rfloor$ (and hence $\lceil R \rceil$ and $\lfloor R \rfloor$) are undefined.
- $m_1 \# m_2$ indicates that the memories m_1 and m_2 have disjoint domains
- $m_1 \uplus m_2$ denotes the union of disjoint memories; if the domains of the two memories are not disjoint then this operation is undefined.
- $m_1 @ m_2$ denotes the union of disjoint memories with the additional caveat that either $\text{adj}(\lceil \text{dom}(m_1) \rceil, \lfloor \text{dom}(m_2) \rfloor)$ or one of m_1 or m_2 is empty.

2.3 Formulae

Figure 1 presents the syntax of formulae. We use a notation reminiscent of connectives from linear logic [9] and Polakow and Pfenning’s ordered logic [28, 29, 27]. However, these logics should only be used as an approximate guide to the meaning of formulae. There are some differences as we will see below.

In addition to multiplicative (linear and ordered) connectives, the logic contains additive connectives and quantification. The bindings in quantification formulae describe the sort, (integer \mathbb{I} , proper location \mathbb{L} , type \mathbb{T} , or formula \mathbb{F}), of the bound variable. We reuse the metavariable ℓ (for concrete locations) as a location variable below. There is,

<i>Predicates</i>	$p ::= (g:\tau) \mid \text{more}^{\leftarrow} \mid \text{more}^{\rightarrow}$
<i>Formulae</i>	$F ::= p \mid \mathbf{1} \mid F_1 \otimes F_2 \mid F_1 \circ F_2 \mid F_1 \multimap F_2 \mid F_1 \rightarrowtail F_2 \mid F_1 \rightarrowtailtail F_2 \mid \top \mid F_1 \& F_2 \mid \mathbf{0} \mid F_1 \oplus F_2 \mid \phi \mid \forall b.F \mid \exists b.F$
<i>Bindings</i>	$b ::= i:\mathbf{l} \mid \ell:\mathbf{L} \mid \alpha:\mathbf{T} \mid \phi:\mathbf{F}$

Figure 1: SL Formulae

however, a reason to distinguish between them: if ℓ is a concrete location, we can compute $\ell + i$, which is not the case if ℓ is a location variable. From now on, the reader may assume that occurrences of ℓ denote a variable, unless otherwise noted in the text. We use abbreviations for the following common formulae.

- $\exists i:\mathbf{l}. (g:\mathbf{S}(i))$ is abbreviated $g:\mathbf{int}$
- $\exists \alpha:\mathbf{T}. (g:\alpha)$ is abbreviated $g:__$
- $\exists \ell:\mathbf{L}. \exists \alpha:\mathbf{T}. (\ell:\alpha)$ is abbreviated \mathbf{ns}
- We use metavariable R to range over formulae with shape $r_1:\tau_1 \otimes \dots \otimes r_n:\tau_n$

Our logic contains quite a number of formulae, but one need not be intimidated. Each formula is defined orthogonally from all others and can be understood independently. Moreover, the logic makes sense if we choose to use any subset of the formulae. Consequently, a system designer need not understand or implement all of the connectives but can choose the subset that suits their application.

Semantics. We use formulae to describe memories and write $m \models^\Psi F$ when the formula F describes the memory m . The reader can safely ignore the superscript Ψ for now. The most basic formulae are predicates with the form $(g:\tau)$. These predicates describe memories that contain a single location g that holds a value with type τ . There are two other basic predicates more^{\leftarrow} and $\text{more}^{\rightarrow}$. They describe an infinite sequence of locations that increases to the left (right). Later, we will use more^{\leftarrow} to indicate that the stack may be grown to the left. Analogously, $\text{more}^{\rightarrow}$ may be used to indicate that some region of memory may be grown to the right, although we do not use it in this paper.

The key to reasoning about adjacent memories is a form of ordered conjunction, which we will call *fuse*. Semantically, $m \models^\Psi F_1 \circ F_2$ if and only if m can be divided into two adjacent parts, m_1 and m_2 such that $m_1 \models^\Psi F_1$ and $m_2 \models^\Psi F_2$. More formally, we require $m = m_1 @ m_2$.

To get accustomed to some of the properties of fuse, we will reason about the following memories, which contain locations in the set $\{\ell_i \mid 0 \leq i \leq n\}$ where each location in this set is adjacent to the next in sequence (i.e., for all i , $\text{adj}(\ell_i, \ell_{i+1})$).

Memory	Domain	Describing Formula
m_1	$\{\ell_1, \ell_3\}$	F_1
m_2	$\{\ell_4, \ell_6\}$	F_2
m_3	$\{\ell_2\}$	F_3
m_4	\emptyset	F_4

First, notice that $m_1 \cup m_2$ may be described using the formula $F_1 \circ F_2$ since the supremum of m_1 is adjacent to the

infimum of m_2 . This same memory cannot be described by $F_2 \circ F_1$ — fuse is not generally commutative. On the other hand, m_1 can be described by either $F_1 \circ F_4$ or $F_4 \circ F_1$ since $m_1 = m_1 @ \emptyset = \emptyset @ m_1$. Since neither the supremum nor the infimum of m_3 is adjacent to the infimum or supremum, respectively, of m_1 or m_2 we cannot readily use fuse to describe the relationship between these memories.

When we don't know or don't care about the ordering relationship between two disjoint memories we will use the unordered multiplicative conjunction $F_1 \otimes F_2$ (which we call tensor). A memory m can be described by $F_1 \otimes F_2$ if and only if there exist m_1, m_2 , such that $m_1 \models^\Psi F_1$ and $m_2 \models^\Psi F_2$ and $m = m_1 \uplus m_2$. This definition differs from the definition for \circ only in that the disjoint union operator “ \uplus ” makes none of the ordering requirements of the adjacent disjoint union operator “ $@$ ”. To see the impact of the change, we consider the following further memories.

Memory	Domain	Describing Formula
m_1	$\{\ell_1, \ell_2\}$	F_1
m_2	$\{\ell_3, \ell_4\}$	F_2
m_3	$\{\ell_5\}$	F_3
m_4	\emptyset	F_6

The memory $m = m_1 \cup m_2 \cup m_3$ can be described by the formula $(F_1 \otimes F_2) \otimes F_3$ since m can be broken into two disjoint parts, $m_1 \cup m_2$ and m_3 , which satisfy the subformulae $(F_1 \otimes F_2)$ and F_3 respectively. The memory m also satisfies the formulae $F_1 \otimes (F_2 \otimes F_3)$ and $(F_3 \otimes F_2) \otimes F_1$ since it is defined in terms of the associative and commutative disjoint union operator.

Our logic contains one more sort of conjunction, the additive $F_1 \& F_2$. A memory m can be described by this formula if the memory (the whole thing!) can be described by both subformulae. Meanwhile, the additive disjunction of two formulae, $F_1 \oplus F_2$, describes a memory m if the entire memory can be described either one of F_1 or F_2 .

The multiplicative $\mathbf{1}$ describes the empty memory and serves as the (right and left) unit for both fuse and tensor. In other words, if $m \models^\Psi F$ then both $m \models^\Psi F \circ \mathbf{1}$ and $m \models^\Psi F \otimes \mathbf{1}$. The unit for additive conjunction \top describes any memory, while the unit for additive disjunction $\mathbf{0}$ describes no memories. These properties can easily be verified from the semantic definitions of the connectives.

The semantics of the other connectives are largely standard. In the semantics of quantifiers, we use the notation $X[a/b]$ to denote capture-avoiding substitution of a for the variable in b in the object X . We extend this notation to substitution for a sequence of bindings as in $X[a_1, \dots, a_n/b]$ or $X[\vec{b}'/\vec{b}]$. In either case, the objects substituted for variables must have the correct sort (type, formula, location or integer) and the sequences must have the same length or else the substitution is undefined. The semantics of all formulae are collected in figure Figure 2. We include the semantics of linear and ordered implications (\multimap , \rightarrowtail , \rightarrowtailtail) but, in the interest of space, we do not describe them here. The semantics of these connectives follow the work of Ishtiaq and O'Hearn [12].

An Extended Example. Recall that it is safe to jump to a code location of type $(F) \rightarrow 0$ if the requirements described by F are satisfied by the current state of the abstract machine. More specifically, we require that the current memory m be described by F , that is, $m \models^\Psi F$.

$m \models^\Psi F$ if and only if

- $F = (g : \tau)$ and $\text{dom}(m) = \{g\}$ and $m(g) = h$ and $\vdash^\Psi h : \tau$
- $F = \text{more}^-$ and $\text{dom}(m) = \{g \mid \exists g'. g \leq g'\}$
- $F = \text{more}^+$ and $\text{dom}(m) = \{g \mid \exists g'. g \geq g'\}$
- $F = \mathbf{1}$ and $\text{dom}(m) = \emptyset$
- $F = F_1 \otimes F_2$ and there exist m_1, m_2 , such that $m = m_1 \uplus m_2$ and $m_1 \models^\Psi F_1$ and $m_2 \models^\Psi F_2$
- $F = F_1 \circ F_2$ and there exist m_1, m_2 , such that $m = m_1 @ m_2$ and $m_1 \models^\Psi F_1$ and $m_2 \models^\Psi F_2$
- $F = F_1 \multimap F_2$ and for all memories m_1 such that $m_1 \models^\Psi F_1$ and $m_1 \# m, m_1 \uplus m \models^\Psi F_2$
- $F = F_1 \rightsquigarrow F_2$ and for all memories m_1 such that $m_1 \models^\Psi F_1, m_1 \# m$ and $\text{adj}(\lceil \text{dom}(m_1) \rceil, \lfloor \text{dom}(m) \rfloor)$, $m_1 @ m \models^\Psi F_2$
- $F = F_1 \twoheadrightarrow F_2$ and for all memories m_1 such that $m_1 \models^\Psi F_1, m_1 \# m$ and $\text{adj}(\lceil \text{dom}(m_1) \rceil, \lfloor \text{dom}(m_1) \rfloor)$, $m @ m_1 \models^\Psi F_2$
- $F = \top$ (and no other conditions need be satisfied)
- $F = F_1 \& F_2$ and $m \models^\Psi F_1$ and $m \models^\Psi F_2$
- $F = \mathbf{0}$ and false (this formula can never be satisfied)
- $F = F_1 \oplus F_2$ and either
 1. $m \models^\Psi F_1$, or
 2. $m \models^\Psi F_2$.
- $F = \forall x:K.F'$ and $m \models^\Psi F'[a/x]$ for all $a \in K$
- $F = \exists x:K.F'$ and there exists some $a \in K$ such that $m \models^\Psi F'[a/x]$

Figure 2: Semantics of Formulae

Consider the type of code location c which, among other things, requires that registers r_1 and r_2 point to locations in memory and that r_3 contain the address of the continuation:

$$c : (\exists \ell:L, \ell':L, \text{mem}:F. (((\ell:\text{int}) \otimes \top) \& ((\ell':\text{int}) \otimes \top) \& \text{mem}) \otimes (r_1:\mathbf{S}(\ell)) \otimes (r_2:\mathbf{S}(\ell')) \otimes (r_3:\tau_{\text{cont}})) \rightarrow 0$$

and $\tau_{\text{cont}} = (\text{mem} \otimes (r_1:-) \otimes (r_2:-) \otimes (r_3:-)) \rightarrow 0$

There are a number of things to note about the calling convention described by the above type. First, the semantics of $\&$ dictate that to jump to c the caller must pack the variable mem with a formula that describes all the proper (non-register) locations in memory. Second, since the formula describing the proper locations is abstracted using the variable mem , the code at c can only jump to the continuation when the register-free subset of memory is in the same state as it was upon jumping to c . Finally, a caller may

jump to code location c if there exists some location ℓ that register r_1 points to, and some location ℓ' that register r_2 points to. The locations ℓ and ℓ' may or may not be the same location, which we illustrate next by considering two different scenarios.

Scenario 1. Consider the following memory where ℓ_i are concrete locations such that $\text{adj}(\ell_1, \ell_2)$ and $\text{adj}(\ell_2, \ell_3)$:

$$m_1 = \{\ell_1 \mapsto 5, \ell_2 \mapsto 3, \ell_3 \mapsto 9, r_1 \mapsto \ell_2, r_2 \mapsto \ell_2, r_3 \mapsto c'\} \\ \text{where } c' : (((\ell_1:\text{int}) \circ (\ell_2:\text{int}) \circ (\ell_3:\text{int})) \\ \otimes (r_1:-) \otimes (r_2:-) \otimes (r_3:-)) \rightarrow 0$$

The three consecutive proper locations in m_1 may be thought of as a stack. The memory also consists of three registers, two of which (r_1 and r_2) contain aliases of location ℓ_2 in the stack. Register r_3 contains a code location c' . We can conclude that we may safely jump to code location c when m_1 is the current memory as follows.

- Since the formula $(\ell_2 : \text{int})$ describes $\{\ell_2 \mapsto 3\}$ and \top describes $\{\ell_1 \mapsto 5\} \uplus \{\ell_3 \mapsto 9\}$, the formula $((\ell_2 : \text{int}) \otimes \top)$ describes the memory $\{\ell_2 \mapsto 3\} \uplus \{\ell_1 \mapsto 5\} \uplus \{\ell_3 \mapsto 9\}$.
- Similarly, we can conclude that the formula $((\ell_2 : \text{int}) \otimes \top)$ describes $\{\ell_1 \mapsto 5, \ell_2 \mapsto 3, \ell_3 \mapsto 9\}$.
- The formula $(\ell_1 : \text{int}) \circ (\ell_2 : \text{int}) \circ (\ell_3 : \text{int})$ describes $\{\ell_1 \mapsto 5, \ell_2 \mapsto 3, \ell_3 \mapsto 9\}$ since ℓ_1, ℓ_2 and ℓ_3 are consecutive locations.
- $(r_1:\mathbf{S}(\ell_2))$ describes $\{r_1 \mapsto \ell_2\}$.
- $(r_2:\mathbf{S}(\ell_2))$ describes $\{r_2 \mapsto \ell_2\}$.
- $(r_3:\tau_{\text{cont}}[((\ell_1:\text{int}) \circ (\ell_2:\text{int}) \circ (\ell_3:\text{int}))/\text{mem}])$ describes $\{r_3 \mapsto c'\}$.
- Then, the formula

$$(((\ell_2:\text{int}) \otimes \top) \& ((\ell_2:\text{int}) \otimes \top) \\ \& (((\ell_1:\text{int}) \circ (\ell_2:\text{int}) \circ (\ell_3:\text{int}))) \\ \otimes (r_1:\mathbf{S}(\ell_2)) \\ \otimes (r_2:\mathbf{S}(\ell_2)) \\ \otimes (r_3:\tau_{\text{cont}})) \rightarrow 0$$

describes

$$\{\ell_1 \mapsto 5, \ell_2 \mapsto 3, \ell_3 \mapsto 9\} \uplus \{r_1 \mapsto \ell_2\} \uplus \{r_2 \mapsto \ell_2\} = m_1.$$

- Using existential introduction, where location ℓ_2 serves as a witness for both ℓ and ℓ' , and $((\ell_1 : \text{int}) \circ (\ell_2 : \text{int}) \circ (\ell_3 : \text{int}))$ serves as a witness for mem , we can conclude the following.

$$m_1 \models^\Psi \exists \ell:L, \ell':L, \text{mem}:F. (((\ell:\text{int}) \otimes \top) \& ((\ell':\text{int}) \otimes \top) \& \text{mem}) \otimes (r_1:\mathbf{S}(\ell)) \otimes (r_2:\mathbf{S}(\ell')) \otimes (r_3:\tau_{\text{cont}})$$

Consequently, if m_1 is our memory, we can jump to c .

Scenario 2. Consider the memory m_2 which is identical to m_1 except that location ℓ_2 is no longer aliased by registers r_1 and r_2 :

$$m_2 = \{\ell_1 \mapsto 5, \ell_2 \mapsto 3, \ell_3 \mapsto 9, r_1 \mapsto \ell_2, r_2 \mapsto \ell_3, r_3 \mapsto c'\}$$

Using reasoning similar to the above, we can conclude that the formula

$$\begin{aligned} & (((\ell_2:\text{int}) \otimes \top) \& ((\ell_3:\text{int}) \otimes \top) \\ & \quad \& ((\ell_1:\text{int}) \circ (\ell_2:\text{int}) \circ (\ell_3:\text{int}))) \\ & \otimes (r_1:\mathbf{S}(\ell_2)) \\ & \otimes (r_2:\mathbf{S}(\ell_3)) \\ & \otimes (r_3:\tau_{cont})) \rightarrow 0 \end{aligned}$$

describes

$$\{\ell_1 \mapsto 5, \ell_2 \mapsto 3, \ell_3 \mapsto 9\} \uplus \{r_1 \mapsto \ell_2\} \uplus \{r_2 \mapsto \ell_3\} = m_2.$$

Then, to conclude that it is safe to jump to c when the current memory is m_2 we use existential introduction with locations ℓ_2 and ℓ_3 as witnesses for ℓ and ℓ' respectively.

It should be noted that the type ascribed to c is somewhat simplistic. Normally we would like to abstract the formula that describes the stack using the variable mem , but the above type prohibits the code at c from allocating additional space on the stack. We rectify the problem by using more^\leftarrow to describe the part of memory where additional stack cells may be allocated, and by requiring a register r_{sp} that points to the top of the stack as follows.

$$\begin{aligned} c : & (\exists \ell_{hd}:L, \alpha:T, \ell:L, \ell':L, tail:F. \\ & (\text{more}^\leftarrow \circ (\ell_{hd}:\alpha) \\ & \quad \circ (((\ell:\text{int}) \otimes \top) \& ((\ell':\text{int}) \otimes \top) \& tail)) \\ & \otimes (r_1:\mathbf{S}(\ell)) \\ & \otimes (r_2:\mathbf{S}(\ell')) \\ & \otimes (r_3:\tau_{cont}) \\ & \otimes (r_{sp}:\mathbf{S}(\ell_{hd}))) \rightarrow 0 \end{aligned}$$

$$\text{and } \tau_{cont} = ((\ell_{hd}:\alpha) \circ tail) \otimes (r_1:-) \\ \otimes (r_2:-) \\ \otimes (r_3:-)) \rightarrow 0$$

2.4 Contexts

We may model separation and adjacency using judgments of the form $\Delta \vdash F$. Following O'Hearn and Pym [22], our logical contexts Δ are bunches (trees) rather than simple lists. The nodes in our bunches are labeled either with an ordered separator “;” or an (unordered) linear separator “,”. The leaves of our bunches are either empty or a single formula labeled with a variable u . We write our contexts as follows.

$$\Delta ::= \cdot \mid u:F \mid \Delta_1, \Delta_2 \mid \Delta_1; \Delta_2$$

We will also frequently have reason to work with a context containing a single hole that may be filled by another context. We use the metavariable Γ to range over contexts with a hole and write $\Gamma(\Delta)$ to fill the hole in Γ with Δ .

$$\Gamma ::= () \mid \Gamma, \Delta \mid \Delta, \Gamma \mid \Gamma; \Delta \mid \Delta; \Gamma$$

We require that no variables are repeated in a context and consider $\Gamma(\Delta)$ to be undefined if Γ and Δ have any variables in common. Again following O'Hearn and Pym, we define an equivalence relation on contexts. It is the reflexive, symmetric and transitive closure of the following axioms.

- 1. $\cdot, \Delta \equiv \Delta$
- 2. $\cdot; \Delta \equiv \Delta$
- 3. $\Delta; \cdot \equiv \Delta$

- 4. $(\Delta_1, \Delta_2), \Delta_3 \equiv \Delta_1, (\Delta_2, \Delta_3)$
- 5. $(\Delta_1; \Delta_2); \Delta_3 \equiv \Delta_1; (\Delta_2; \Delta_3)$
- 6. $\Delta_1, \Delta_2 \equiv \Delta_2, \Delta_1$
- 7. $\Gamma(\Delta) \equiv \Gamma(\Delta') \text{ if } \Delta \equiv \Delta'$

Semantics. Like individual formulae, contexts can describe memories. The semantics of contexts appears in Figure 3. Notice that the semantics of the ordered separator “;” mirrors the semantics of fuse whereas the semantics of the linear separator “,” mirrors the semantics of tensor.

Our proofs require that we also give semantics to contexts with a hole (also in Figure 3). This semantic judgment has the form $(m, L) \models_C^\Psi \Gamma$ which may be read as saying that the memory m is described by Γ when the hole in Γ is filled in by a context Δ that describes the memory defined on the locations in the set L .

$m \models_C^\Psi \Delta$ if and only if

- $\Delta = \cdot \text{ and } \text{dom}(m) = \emptyset$
- $\Delta = u:F \text{ and } m \models^\Psi F$
- $\Delta = \Delta_1, \Delta_2 \text{ and } m = m_1 \uplus m_2 \text{ and } m_1 \models_C^\Psi \Delta_1 \text{ and } m_2 \models_C^\Psi \Delta_2$
- $\Delta = \Delta_1; \Delta_2 \text{ and } m = m_1 @ m_2 \text{ and } m_1 \models_C^\Psi \Delta_1 \text{ and } m_2 \models_C^\Psi \Delta_2$

$(m, L) \models_C^\Psi \Gamma$ if and only if

- $\Gamma = () \text{ and } \text{dom}(m) = \emptyset$
- $\Gamma = \Gamma', \Delta' \text{ and } (m_1, L) \models_C^\Psi \Gamma' \text{ and } m_2 \models_C^\Psi \Delta' \text{ and } m = m_1 \uplus m_2$
- $\Gamma = \Gamma'; \Delta' \text{ and } (m_1, L) \models_C^\Psi \Gamma' \text{ and } m_2 \models_C^\Psi \Delta' \text{ and } m = m_1 \uplus m_2 \text{ and one of } \text{adj}(\lceil \text{dom}(m_1) \cup L \rceil, \lfloor \text{dom}(m_2) \rfloor), \text{ or } (\text{dom}(m_1) \cup L) = \emptyset, \text{ or } \text{dom}(m_2) = \emptyset.$
- $\Gamma = \Delta'; \Gamma' \text{ and } m_1 \models_C^\Psi \Delta' \text{ and } (m_2, L) \models_C^\Psi \Gamma' \text{ and } m = m_1 \uplus m_2 \text{ and one of } \text{adj}(\lceil \text{dom}(m_1) \rceil, \lfloor \text{dom}(m_2) \cup L \rfloor), \text{ or } \text{dom}(m_1) = \emptyset, \text{ or } (\text{dom}(m_2) \cup L) = \emptyset.$

Figure 3: Semantics of Contexts

2.5 Basic Semantic Properties

In this section, we outline some simple, but necessary properties of our semantics.

We will need to reason about the decomposition of a memory m described by the context $\Gamma(\Delta)$ into two parts, the part described by Γ and the part described by Δ . The following lemma allows us to decompose and then recompose memories.

Lemma 1 (Semantic Decomposition)

- If $m \models_C^\Psi \Gamma(\Delta)$ then there exist m_1 and m_2 , such that $m = m_1 \uplus m_2$ and $(m_1, \text{dom}(m_2)) \models_C^\Psi \Gamma$ and $m_2 \models_C^\Psi \Delta$.
- If $(m_1, \text{dom}(m_2)) \models_C^\Psi \Gamma$ and $m_2 \models_C^\Psi \Delta$, then $m_1 \uplus m_2 \models_C^\Psi \Gamma(\Delta)$.

PROOF. By induction on the structure of Γ . \square

Our semantics does not distinguish between equivalent contexts.

Lemma 2 (Soundness of Context Equivalence)

- If $m \models_C^\Psi \Delta$ and $\Delta \equiv \Delta'$ then $m \models_C^\Psi \Delta'$.
- If $(m, L) \models_C^\Psi \Gamma$ and $\Gamma \equiv \Gamma'$ then $(m, L) \models_C^\Psi \Gamma'$.

PROOF. By induction on the definition of context equivalence. In the case for equivalence rule 7, we use Lemma 1. \square

Finally, since the append operator “@” makes more requirements of a context than the disjoint union operator “ \uplus ” we may easily prove that whenever a memory can be described by the context $\Delta_1; \Delta_2$ it can also be described by the context Δ_1, Δ_2 . This notion is formalized by the following lemma.

Lemma 3 (Semantic Disorder)

If $m \models_C^\Psi \Gamma(\Delta_1; \Delta_2)$ then $m \models_C^\Psi \Gamma(\Delta_1, \Delta_2)$.

PROOF. By induction on the structure of Γ . \square

2.6 Logical Deduction

To support universal and existential quantification we extend the judgments of our logic to additionally depend on a variable context Θ . The basic judgment for the natural deduction formulation of our logic has the form $\Theta \parallel \Delta \vdash F$ where Θ consists of the set of variables that may appear free in Δ or F . These variables may be integer, location, type, or formula variables. (The syntax of bindings b was given in Figure 1.)

$$\text{Variable Contexts } \Theta ::= \cdot \mid \Theta, b$$

The inference rules (see Figures 4, 5) are very similar to the rules given by O’Hearn and Pym [22] so we only highlight the central differences. The most important difference, of course, is the presence of our ordered separator and linear separator as opposed to the linear separator and additive separator that is the focus of most of O’Hearn and Pym’s work. Moreover, there is only a single unit for the two contexts rather than two units as in O’Hearn and Pym’s work. Finally, since we have no additive separator in the context, our elimination form for the additive conjunction is slightly different from the elimination form given by O’Hearn and Pym. It seems likely that the additives suggested by O’Hearn and Pym are compatible with this system, but we have not investigated this possibility.

We do not have an explicit structural rule to mark the movement between equivalent contexts. Instead, we treat equivalence implicitly: the logical judgments and inference rules operate over equivalence classes of contexts. For example, when we write

$$\frac{\Theta \parallel \Delta_1 \vdash F_1 \quad \Theta \parallel \Delta_2 \vdash F_2}{\Theta \parallel \Delta_1, \Delta_2 \vdash F_1 \otimes F_2} \otimes I$$

we implicitly assume the presence of equivalence as in the following more explicit rule.

$$\frac{\Delta \equiv \Delta_1, \Delta_2 \quad \Theta \parallel \Delta_1 \vdash F_1 \quad \Theta \parallel \Delta_2 \vdash F_2}{\Theta \parallel \Delta \vdash F_1 \otimes F_2} \otimes I$$

The rules of Figures 4,5 define a sound logical system. However, for our application, we would like one further property: It should be possible to forget adjacency information. We saw in the previous section (Lemma 3) that, if a memory satisfies a context that imposes ordering conditions via “;”, then the same memory will satisfy a context that does not impose these ordering conditions (in other words, it is sound for “;” to replace “;”). In order to include this principle in our deductive system, we allow any proof of a judgment with the form $\Theta \parallel \Gamma(\Delta_1, \Delta_2) \vdash F$ to be considered a proof of $\Theta \parallel \Gamma(\Delta_1; \Delta_2) \vdash F$. To mark the inclusion of one proof for another in the premise of a rule, we put a asterisk beside the name of that rule, as in the following derivation.

$$\frac{\Theta \parallel u_3:F_3 \vdash F_3 \quad \Theta \parallel u_2:F_2 \vdash F_2}{\Theta \parallel u_2:F_2, u_3:F_3 \vdash F_3 \otimes F_2} \otimes I^*$$

These inclusions give rise the following principle.

Principle 4 (Logical Disorder)

If $\Theta \parallel \Gamma(\Delta_1, \Delta_2) \vdash F$ then $\Theta \parallel \Gamma(\Delta_1; \Delta_2) \vdash F$.

We borrow the idea of including one sort of proof for another from Pfenning and Davies’ judgmental reconstruction of modal logic [26]. In that work, they include proofs of truth directly as proofs of possibility. An alternative to this approach would be to add an explicit structural rule, but we prefer to avoid structural rules as every use of such a rule changes the structure and height of a derivation.

Our logic obeys standard substitution principles and deduction is sound with respect to our semantic model.

Lemma 5 (Substitution)

If $\text{FV}(\Delta) \cap \text{FV}(\Gamma) = \emptyset$ then

- If $\Gamma(u:F) \equiv \Gamma'(u:F)$ then $\Gamma(\Delta) \equiv \Gamma'(\Delta)$.
- If $\Theta \parallel \Delta \vdash F$ and $\Theta \parallel \Gamma(u:F) \vdash F'$ then $\Theta \parallel \Gamma(\Delta) \vdash F'$.
- If $\Theta, x : K \parallel \Delta \vdash F$ then for all $a \in K$, $\Theta \parallel \Delta[a/x] \vdash F[a/x]$.

PROOF. By induction on the appropriate derivation in each case. \square

Lemma 6 (Soundness of Logical Deduction)

If $m \models_C^\Psi \Delta$ and $\cdot \parallel \Delta \vdash F$, then $m \models_C^\Psi F$.

PROOF. By induction on the natural deduction derivation. \square

2.7 Operations on Formulae

Our typing rules will make extensive use of an operation to *look up* the type of a location offset by an index ($g[i]$) in a formula. To facilitate this operation we use the notation $F(g[i])$ which is defined as follows.

Definition (Formula Lookup)

$$F(g_0[i]) = \tau_i \quad \text{if } \cdot \parallel u:F \vdash \top \otimes ((g_0:\tau_0) \circ \dots \circ (g_i:\tau_i))$$

We *update* the type of a location $g[i]$ in a formula F using the notation $F[g[i] := \tau]$ which is defined as follows.

$$\boxed{\Theta \parallel \Delta \vdash F}$$

Hypothesis

$$\frac{}{\Theta \parallel u:F \vdash F} \text{ Hyp } (u)$$

Linear and Ordered Unit

$$\frac{}{\Theta \parallel \cdot \vdash \mathbf{1}} \text{ 1I} \quad \frac{\Theta \parallel \Delta \vdash \mathbf{1} \quad \Theta \parallel \Gamma(\cdot) \vdash C}{\Theta \parallel \Gamma(\Delta) \vdash C} \text{ 1E}$$

Linear Conjunction

$$\frac{\Theta \parallel \Delta_1 \vdash F_1 \quad \Theta \parallel \Delta_2 \vdash F_2}{\Theta \parallel \Delta_1; \Delta_2 \vdash F_1 \otimes F_2} \otimes I$$

$$\frac{\Theta \parallel \Delta \vdash F_1 \otimes F_2 \quad \Theta \parallel \Gamma(u_1:F_1, u_2:F_2) \vdash C}{\Theta \parallel \Gamma(\Delta) \vdash C} \otimes E$$

Ordered Conjunction

$$\frac{\Theta \parallel \Delta_1 \vdash F_1 \quad \Theta \parallel \Delta_2 \vdash F_2}{\Theta \parallel \Delta_1; \Delta_2 \vdash F_1 \circ F_2} \circ I$$

$$\frac{\Theta \parallel \Delta \vdash F_1 \circ F_2 \quad \Theta \parallel \Gamma(u_1:F_1; u_2:F_2) \vdash C}{\Theta \parallel \Gamma(\Delta) \vdash C} \circ E$$

Linear Implication

$$\frac{\Theta \parallel \Delta, u:F_1 \vdash F_2}{\Theta \parallel \Delta \vdash F_1 \multimap F_2} \multimap I$$

$$\frac{\Theta \parallel \Delta \vdash F_1 \multimap F_2 \quad \Theta \parallel \Delta_1 \vdash F_1}{\Theta \parallel \Delta, \Delta_1 \vdash F_2} \multimap E$$

Ordered Implications

$$\frac{\Theta \parallel u:F_1; \Delta \vdash F_2}{\Theta \parallel \Delta \vdash F_1 \rightsquigarrow F_2} \rightsquigarrow I$$

$$\frac{\Theta \parallel \Delta \vdash F_1 \rightsquigarrow F_2 \quad \Theta \parallel \Delta_1 \vdash F_1}{\Theta \parallel \Delta_1; \Delta \vdash F_2} \rightsquigarrow E$$

$$\frac{\Theta \parallel \Delta; u:F_1 \vdash F_2}{\Theta \parallel \Delta \vdash F_1 \rightarrowtail F_2} \rightarrowtail I$$

$$\frac{\Theta \parallel \Delta \vdash F_1 \rightarrowtail F_2 \quad \Theta \parallel \Delta_1 \vdash F_1}{\Theta \parallel \Delta; \Delta_1 \vdash F_2} \rightarrowtail E$$

Figure 4: SL : Multiplicative Connectives

Definition (Formula Update)

$$F[g_0[i] := \tau] \stackrel{\text{def}}{=} F_1 \otimes (F_2 \circ (g_0:\tau_0) \circ \dots \circ (g_i:\tau) \circ F_3)$$

if $\cdot \parallel u:F \vdash F_1 \otimes (F_2 \circ (g_0:\tau_0) \circ \dots \circ (g_i:\tau_i) \circ F_3)$

The following lemma states that formula lookup and update are sound with respect to the semantics. This lemma is used extensively in the proof of soundness of our type system.

$$\boxed{\Theta \parallel \Delta \vdash F}$$

Additive Conjunction and Unit

$$\frac{}{\Theta \parallel \Delta \vdash \top} \top I$$

$$\frac{\Theta \parallel \Delta \vdash F_1 \quad \Theta \parallel \Delta \vdash F_2}{\Theta \parallel \Delta \vdash F_1 \& F_2} \& I$$

$$\frac{\Theta \parallel \Delta \vdash F_1 \& F_2}{\Theta \parallel \Delta \vdash F_1} \& E1 \quad \frac{\Theta \parallel \Delta \vdash F_1 \& F_2}{\Theta \parallel \Delta \vdash F_2} \& E2$$

Additive Disjunction and Unit

$$\frac{\Theta \parallel \Delta \vdash \mathbf{0}}{\Theta \parallel \Delta \vdash F} 0E$$

$$\frac{\Theta \parallel \Delta \vdash F_1}{\Theta \parallel \Delta \vdash F_1 \oplus F_2} \oplus I^1 \quad \frac{\Theta \parallel \Delta \vdash F_2}{\Theta \parallel \Delta \vdash F_1 \oplus F_2} \oplus I^2$$

$$\frac{\Theta \parallel \Delta \vdash F_1 \oplus F_2 \quad \Theta \parallel \Gamma(u_1:F_1) \vdash C \quad \Theta \parallel \Gamma(u_2:F_2) \vdash C}{\Theta \parallel \Gamma(\Delta) \vdash C} \oplus E$$

Universal Quantification

$$\frac{\Theta, x:K \parallel \Delta \vdash F}{\Theta \parallel \Delta \vdash \forall x:K.F} \forall I \quad \frac{\Theta \parallel \Delta \vdash \forall x:K.F \quad a \in K}{\Theta \parallel \Delta \vdash F[a/x]} \forall E$$

Existential Quantification

$$\frac{\Theta \parallel \Delta \vdash F[a/x] \quad a \in K}{\Theta \parallel \Delta \vdash \exists x:K.F} \exists I$$

$$\frac{\Theta \parallel \Delta \vdash \exists x:K.F \quad \Theta, x:K \parallel \Gamma(u:F) \vdash C}{\Theta \parallel \Gamma(\Delta) \vdash C} \exists E$$

Figure 5: SL : Additive Connectives and Quantifiers

Lemma 7

- If $m \models^\Psi F$ and $F(g[i]) = \tau$, then $m(g[i]) = h$ and $\vdash^\Psi h:\tau$.
- If $m \models^\Psi F$ and $\vdash^\Psi h:\tau$, then $m[g[i]:=h] \models^\Psi F[g[i]:=\tau]$.

PROOF. By the soundness of logical deduction and the semantics of formulae. \square

3. A SIMPLE ASSEMBLY LANGUAGE

In this section, we develop the simplest possible assembly language that allows us to write stack-based programs.

3.1 Syntax

There are four main components of a program. A code region C is a finite partial map from code values to blocks of code B . Each block is a sequence of instructions ι terminated by a jump instruction. Finally, the operands (v) which appear in instructions are made up of the values that

we have seen before.

$$\begin{array}{ll}
\text{Operands} & v ::= h \mid r \\
\text{Instructions} & \iota ::= \text{add } r_d, r_s, v \mid \text{sub } r_d, r_s, v \mid \\
& \quad \text{blte } r, v \mid \text{mov } r_d, v \mid \\
& \quad \text{ld } r_d, r_s[i] \mid \text{st } r_d[i], r_s \\
\text{Blocks} & B ::= \text{jmp } v \mid \iota; B \\
\text{Code Region} & C ::= \cdot \mid C, c \mapsto B
\end{array}$$

3.2 Types and Typing Rules

The type system for our assembly language is defined by the following judgments.

$$\begin{array}{ll}
F \vdash^\Psi v : \tau & \text{Operand } v \text{ has type } \tau \text{ in } F \\
\Theta \parallel F \vdash^\Psi \iota : F' & \text{Instruction } \iota \text{ requires a context } \Theta \parallel F \text{ and yields } F' \\
\Theta \parallel F \vdash^\Psi B \text{ ok} & \text{Block } B \text{ is well-formed in context } \Theta \parallel F \\
\vdash C : \Psi & \text{Code region } C \text{ has type } \Psi \text{ assuming } \Psi \\
\vdash \Sigma \text{ ok} & \text{State } \Sigma \text{ is well-formed}
\end{array}$$

Once again, although judgments for operands, instructions and blocks are formally parameterized by Ψ , we normally omit this annotation. The static semantics is given in Figures 6 and 7.

We assume our type system will be used in the context of proof-carrying code. More specifically, we assume a complete derivation will be attached to any assembly language program that needs to be checked for safety. To check that a program is well formed one need only check that it corresponds to the attached derivation and that the derivation uses rules from our type system and associated logic. The problem of inferring a derivation from an unannotated program is surely undecidable, but not relevant to a proof-carrying code application as a compiler can generate the appropriate derivation from a more highly structured source-level program.

Operand Typing. The rules for giving types to store values are extended to allow us to give types to operands, which include both store values and registers. The rule for registers requires that we look up the type of the register in the formula that describes the current state.

Instruction Typing. Instruction typing is performed in a context in which the free variables are described by Θ and the current state of the memory is described by the input formula F . An instruction will generally transform the state of the memory and result in a new state described by the formula F' . For instance, if the initial state is described by F , and we can verify that r_s and v contain integers then the instruction $\text{add } r_d, r_s, v$ transforms the state so that the result is described by $F[r_d := \text{int}]$. This resulting formula uses our formula update notation, which we defined in Section 2.7. The simple rule for integer subtraction is identical. To type check the conditional branch we must show that the second operand has code type and that the formula describing the current state entails the requirements specified in the function type. The rule for typing move is straightforward.

The rules for typing load and store instructions make use of our formula lookup operations. The formula lookup operation $F(\ell[i]) = \tau$ suffices to verify that the location $\ell + i$ exists in memory and contains a value with type τ (recall Lemma 7).

Finally, our type system allows simple pointer arithmetic,

$$F \vdash v : \tau$$

$$\frac{\vdash h : \tau}{F \vdash h : \tau} \text{ (sval)} \quad \frac{}{F \vdash r : F(r[0])} \text{ (reg)}$$

$$\Theta \parallel F \vdash \iota : F'$$

$$\begin{array}{c}
\frac{F \vdash r_s : \text{int} \quad F \vdash v : \text{int}}{\Theta \parallel F \vdash \text{add } r_d, r_s, v : F[r_d := \text{int}]} \text{ (add)} \\
\frac{F \vdash r_s : \text{int} \quad F \vdash v : \text{int}}{\Theta \parallel F \vdash \text{sub } r_d, r_s, v : F[r_d := \text{int}]} \text{ (sub)} \\
\frac{F \vdash r : \text{int} \quad F \vdash v : (F') \rightarrow 0 \quad \Theta \parallel u : F \vdash F'}{\Theta \parallel F \vdash \text{blte } r, v : F} \text{ (blte)} \\
\frac{F \vdash v : \tau}{\Theta \parallel F \vdash \text{mov } r_d, v : F[r_d := \tau]} \text{ (mov)} \\
\frac{F \vdash r_s : \mathbf{S}(\ell) \quad F(\ell[i]) = \tau}{\Theta \parallel F \vdash \text{ld } r_d, r_s[i] : F[r_d := \tau]} \text{ (ld)} \\
\frac{F \vdash r_d : \mathbf{S}(\ell) \quad F \vdash r_s : \tau \quad F(\ell[i]) = \tau'}{\Theta \parallel F \vdash \text{st } r_d[i], r_s : F[\ell[i] := \tau']} \text{ (st)} \\
\frac{\Theta \parallel u : F \vdash \top \otimes ((\ell_0 : _) \circ (\ell_1 : _) \circ \dots \circ (\ell_i : _))}{\Theta \parallel F \vdash \text{add } r_d, r_s, v : F[r_d := \mathbf{S}(\ell_i)]} \text{ (addr-add)} \\
\frac{\Theta \parallel u : F \vdash \top \otimes ((\ell_0 : _) \circ \dots \circ (\ell_i : _))}{\Theta \parallel F \vdash \text{sub } r_d, r_s, v : F[r_d := \mathbf{S}(\ell_0)]} \text{ (addr-sub)}
\end{array}$$

Figure 6: Static Semantics (Values and Instructions)

which can be used to bump up the stack pointer. The rules **addr-add** and **addr-sub** provide alternate typing rules for addition and subtraction operations. If r_s contains the (constant or variable) location ℓ_0 and v is the constant integer i and we can prove that the current memory can be described as

$$\top \otimes ((\ell_0 : _) \circ (\ell_1 : _) \circ \dots \circ (\ell_i : _))$$

then the result of addition is the location ℓ_i . We can come to this conclusion even though we do not know exactly which locations ℓ_0 and ℓ_i that we're dealing with. The fuse operator allows us to reason that each of the locations in the sequence in the formula are adjacent to one another and therefore that ℓ_i is i locations from ℓ_0 . We may reason about the address subtraction typing rule analogously.

Block Typing. Block typing is described in Figure 7. The basic block typing rules are **b-instr**, which processes one instruction in a block and then the rest of the block, and **b-jmp** which types the jump instruction that ends a block.

Block typing also includes rules to extend our view of memory (**b-stackgrow**) or retract our view of memory (**b-stackcut**). Typically, when we wish to push more data on the stack, we will first use the **b-stackgrow** rule (as many times

$\Theta \parallel F \vdash B \text{ ok}$
$\frac{F \vdash v : (F') \rightarrow 0 \quad \Theta \parallel u : F \vdash F'}{\Theta \parallel F \vdash \text{jmp } v \text{ ok}} \text{ (b-jmp)}$
$\frac{\Theta \parallel F \vdash \iota : F' \quad \Theta \parallel F' \vdash B \text{ ok}}{\Theta \parallel F \vdash \iota ; B \text{ ok}} \text{ (b-instr)}$
$\frac{\Theta \parallel (\text{more}^\leftarrow \circ F_2) \otimes R \vdash B \text{ ok}}{\Theta \parallel (\text{more}^\leftarrow \circ F_1 \circ F_2) \otimes R \vdash B \text{ ok}} \text{ (b-stackcut)}$
$\frac{\Theta \parallel (\text{more}^\leftarrow \circ \text{ns} \circ F_2) \otimes R \vdash B \text{ ok}}{\Theta \parallel (\text{more}^\leftarrow \circ F_2) \otimes R \vdash B \text{ ok}} \text{ (b-stackgrow)}$
$\frac{\Theta, b \parallel F' \vdash B \text{ ok}}{\Theta \parallel \exists b. F' \vdash B \text{ ok}} \text{ (b-unpack)}$
$\frac{\Theta \parallel u : F \vdash F' \quad \Theta \parallel F' \vdash B \text{ ok}}{\Theta \parallel F \vdash B \text{ ok}} \text{ (b-weaken)}$
$\vdash C : \Psi$
$\frac{\begin{array}{l} \text{dom}(C) = \text{dom}(\Psi) \\ \forall c \in \text{dom}(C). \quad \Psi(c) = (F) \rightarrow 0 \\ \text{implies } \cdot \parallel F \vdash^\Psi C(c) \text{ ok} \end{array}}{\vdash C : \Psi} \text{ (codergn)}$
$\vdash \Sigma \text{ ok}$
$\frac{\vdash C : \Psi \quad m \models^\Psi F \quad \cdot \parallel F \vdash^\Psi B \text{ ok}}{\vdash (C, m, B) \text{ ok}} \text{ (state)}$

Figure 7: Static Semantics (Blocks and States)

as necessary), then we will add the appropriate amount to the stack pointer and finally we will store onto the stack the data we wish to keep there. To pop the stack, we do the reverse, first loading data off the stack into registers, subtracting the appropriate amount from the stack pointer and then using the b-stackcut rule.

State Typing. The rule for typing code is the standard rule for a mutually recursive set of functions. The rule for typing an overall machine state requires that we type check our program C and then check the code we are currently executing (B) under the assumption F , which describes the current memory m .

An Example. The stack may be used to save temporary values during the course of a computation. The code sequence in Figure 8 saves registers r_1 through r_n , which contain values of types τ_1 through τ_n , on the stack, performs a computation A , and then restores the n values to their original registers. The formulae to the right of each instruction describe the state of the memory at each step.

3.3 Operational Semantics

Abstract Machine States. An abstract machine state Σ is a 3-tuple containing a code region C , a *complete* memory m and the block of code B that is currently being executed. A complete memory is a *total* function from generic locations to store values (i.e., $(Loc \cup Reg) \rightarrow Sval$). We require memories to be complete in order to justify the b-stackcut rule.

Operational Semantics. We define execution of our abstract machine using a small-step operational semantics $\Sigma \longrightarrow \Sigma'$. The operational semantics is given in Figure 9. In the semantics, we use \widehat{m} to convert an operand to a value that may be stored at a location.

$$\begin{aligned} \widehat{m}(i) &= i \\ \widehat{m}(c) &= c \\ \widehat{m}(\ell) &= \ell \\ \widehat{m}(r) &= m(r) \end{aligned}$$

We also make use of the fact that “+” and “−” are overloaded so they operate both on integers and locations. This allows us to write a single specification for the execution of addition and subtraction operations. Aside from these details, the operational semantics is quite intuitive.

$(C, m, B) \longmapsto \Sigma$ where	
If $B =$	then $\Sigma =$
$\text{add } r_d, r_s, v; B'$	$(C, m[r_d := (m(r_s) + \widehat{m}(v))], B')$
$\text{sub } r_d, r_s, v; B'$	$(C, m[r_d := (m(r_s) - \widehat{m}(v))], B')$
$\text{blte } r, v; B'$ and $m(r) > 0$	(C, m, B')
$\text{blte } r, v; B'$ and $m(r) \leq 0$	(C, m, B'') where $C(\widehat{m}(v)) = B''$
$\text{mov } r_d, v; B'$	$(C, m[r_d := \widehat{m}(v)], B')$
$\text{ld } r_d, r_s[i]; B'$	$(C, m[r_d := m(m(r_s) + i)], B')$
$\text{st } r_d[i], r_s; B'$	$(C, m[g := m(r_s)], B')$ where $g = m(r_d) + i$
$\text{jmp } v$	(C, m, B'') where $C(\widehat{m}(v)) = B''$

Figure 9: Operational Semantics

3.4 Progress & Preservation

To demonstrate that our language is sound, we have proven progress and preservation lemmas. Preservation requires the following lemma in the case for the b-stackcut and b-stackgrow rules.

Lemma 8 (Stack Cut / Stack Grow Soundness)

- If m is a complete memory and $m \models^\Psi (\text{more}^\leftarrow \circ F_1 \circ F_2) \otimes R$ then $m \models^\Psi (\text{more}^\leftarrow \circ F_2) \otimes R$.
- If $m \models^\Psi (\text{more}^\leftarrow \circ F_2) \otimes R$ then $m \models^\Psi (\text{more}^\leftarrow \circ \text{ns} \circ F_2) \otimes R$.

PROOF. By inspection of the semantics of formulae. \square

Theorem 9 (Progress & Preservation)

If $\vdash (C, m, B) \text{ ok}$ then

1. $(C, m, B) \longrightarrow (C, m', B')$.
2. if $(C, m, B) \longrightarrow (C, m', B')$ then $\vdash (C, m', B') \text{ ok}$.

<i>Code</i>	<i>Describing Formula</i>
(b-stackgrow) <i>Repeat n times</i>	$(\text{more}^\leftarrow \circ (\ell : \tau) \circ F_1) \otimes (r_{sp} : \mathbf{S}(\ell))$
(b-unpack) <i>Repeat n times</i>	$(\text{more}^\leftarrow \circ \text{ns} \circ \dots \circ \text{ns} \circ (\ell : \tau) \circ F_1) \otimes (r_{sp} : \mathbf{S}(\ell))$
sub r_{sp}, r_{sp}, n	$(\text{more}^\leftarrow \circ (\ell_1 : _) \circ \dots \circ (\ell_n : _) \circ (\ell : \tau) \circ F_1) \otimes (r_{sp} : \mathbf{S}(\ell))$
st $r_{sp}[0], r_1$	$(\text{more}^\leftarrow \circ (\ell_1 : _) \circ (\ell_2 : _) \circ \dots \circ (\ell_n : _) \circ (\ell : \tau) \circ F_1) \otimes (r_{sp} : \mathbf{S}(\ell_1))$
\vdots	\vdots
st $r_{sp}[n - 1], r_n$	$(\text{more}^\leftarrow \circ (\ell_1 : \tau_1) \circ (\ell_2 : \tau_2) \circ \dots \circ (\ell_n : \tau_n) \circ (\ell : \tau) \circ F_1) \otimes (r_{sp} : \mathbf{S}(\ell_1))$
<i>Code for A</i>	$(\text{more}^\leftarrow \circ (\ell_1 : \tau_1) \circ (\ell_2 : \tau_2) \circ \dots \circ (\ell_n : \tau_n) \circ (\ell : \tau) \circ F_1) \otimes (r_{sp} : \mathbf{S}(\ell_1))$
1d $r_1, r_{sp}[0]$	\vdots
\vdots	\vdots
1d $r_n, r_{sp}[n - 1]$	$(\text{more}^\leftarrow \circ (\ell_1 : \tau_1) \circ (\ell_2 : \tau_2) \circ \dots \circ (\ell_n : \tau_n) \circ (\ell : \tau) \circ F_1) \otimes (r_{sp} : \mathbf{S}(\ell_1))$
add r_{sp}, r_{sp}, n	$(\text{more}^\leftarrow \circ (\ell_1 : \tau_1) \circ (\ell_2 : \tau_2) \circ \dots \circ (\ell_n : \tau_n) \circ (\ell : \tau) \circ F_1) \otimes (r_{sp} : \mathbf{S}(\ell))$
(b-stackcut)	$(\text{more}^\leftarrow \circ (\ell : \tau) \circ F_1) \otimes (r_{sp} : \mathbf{S}(\ell))$

Figure 8: Saving Temporaries on the Stack

4. RELATED WORK

Our logic and type system for assembly language grew out of a number of previous efforts to handle explicit memory management in a type-safe language. Our language incorporates the ability to reason about *separation* with the multiplicative connectives of the logic (\otimes, \multimap), *adjacency* with the ordered connectives ($\circ, \rightarrowtail, \rightarrowtail$), and *aliasing* with the use of singleton types. Other systems have considered these properties individually, but ours is the first to consider all three together. We consider related work primarily in terms of these three concepts.

Separation and Aliasing. Immediately after Girard developed linear logic [9], researchers rushed to investigate computational interpretations of the logic that take advantage of its separation properties to safely manage memory [13, 38, 5]. Each of these projects, and many others, use linear logic or some variant as a type system for a lambda calculus with explicit allocation and deallocation of memory. Early researchers did not consider the problem of safe initialization of data because safe low-level programming languages such as JVML [14] and typed assembly language [17] had not yet been invented. However, it is straightforward to add an extra “junk type” to these linear languages and reason about initialization as well [11, 39].

More recently, a new approach was suggested by John Reynolds [32] and Ishtiaq and O’Hearn [12]. Rather than using a substructural logic to type lambda terms, they use a logic to describe the shape of the store. They have focused on using O’Hearn and Pym’s bunched logic [22], which contains additive and linear separators, rather than linear and ordered separators as we have done. Consequently, we are aware of no simple encoding of stack-based memory management invariants in their system. O’Hearn briefly mentions adding an adjacency operator to the logic in his work on bunched typing, but he does not investigate the idea in detail [21].

Work on alias types by Smith, Walker and Morrisett [35, 41] is closely related to Reynolds, Ishtiaq and O’Hearn’s Hoare logic. One key difference is that the former group uses singleton types to encode aliasing relationships between pointers. We borrow that technique in this work.

Adjacency. Any type system containing pairs $\tau_1 \times \tau_2$ uses juxtaposition in the type structure to reason about adjacent locations. However, the development of proof-carrying code [19, 18] and typed assembly language [17, 15] provides motivation to consider sophisticated logics for reasoning about adjacency and its interaction with other spatial concepts. Morrisett et al. [15] developed an algebra of lists to reason about adjacent locations on the stack. However, this discipline is quite inflexible when compared with our logic. It is impossible to hide the relative order of objects on the stack since they have no analogue of our tensor connective. This deficiency often makes it impossible to store data deep on the stack. They also have no analogue of our additive connectives which allow us to specify different “views” of the stack. Stack-based typed assembly language also has quite a limited ability to handle aliasing.

Our research is also inspired by Polakow and Pfenning’s ordered linear logic [28, 29, 27]. In fact, we initially attempted to encode memory invariants using their logic directly. However, we found their particular linear, ordered judgment $\Delta; \Omega \vdash F$ was incompatible with the adjacency property we desired. The formulae in Δ are linear but *mobile* and they may be placed in between formulae that are juxtaposed in Ω . Therefore, Ω describes *relative ordering*, but not necessarily adjacency.

Nevertheless, Polakow and Pfenning’s ordered logic works well as a type system for an ordered lambda calculus. Polakow and Pfenning have applied their logic to the problem of reasoning about continuations allocated and deallocated on a stack [30]. Petersen et al. [25] further observed that Polakow and Pfenning’s mobility modality could be interpreted as pointer indirection and their fuse connective could join two adjacent structs. They develop a calculus based on these ideas and use it to reason about allocation via “pointer-bumping,” as is commonly done in a copying garbage collector. Petersen et al. do not consider aliasing, separation, or deallocation of data.

Other Work. Among the first to investigate explicit memory management in a type-safe language were Tofte and Talpin, who developed a provably sound system of region-based memory management [37]. At approximately the same time, Reynolds and O’Hearn [31, 24] were investigating the semantics of Algol and its translation to low-level interme-

diate languages with explicit memory management. Later, the development of proof-carrying code [19, 18] and typed assembly language [17, 15] provided new motivation to study safe memory management at a low-level of abstraction.

Recently, researchers have developed very rich logics that are capable of expressing essentially any compile-time property of programs. For instance, Appel et al. [2, 3] use higher-order logic to code up the semantics of a flexible type system and Shao et al. [34] and Crary and Vanderwaart [6] incorporate logical frameworks into their type systems. With enough effort, implementors could surely code up our abstractions in these systems. However, our logic and language still serves a purpose in these settings: it may be used as a convenient and concise logical intermediate language. No matter how powerful the logic, it is still necessary to think carefully about how to structure one’s proofs. Our research, which defines a logic at just the right level of abstraction for reasoning about the stack, provides that structure.

The bunched logic we have described here can be extended to allow reasoning about hierarchical memory management [1]. The extended logic can be used to describe the layout of bits in a memory word, the layout of memory words in a region [37], the layout of regions in an address space, or even the layout of address spaces in a multiprocessor environment. Ahmed et al. [1] use the logic to develop a type system for a simplified version of the Kit Abstract Machine [8], the intermediate language used in the ML Kit with regions [36].

5. FUTURE WORK

There are several directions for future work. First, we would like to continue to investigate substructural logics for reasoning about explicit memory management. In particular, we would like to determine whether we can find a logic in which deduction is complete for our memory model, or a related model such as the store model used by Ishtiaq and O’Hearn. Second, we would like to study certifying compilation for stack allocation algorithms in more detail. What are the limitations of our stack logic? Are there current optimization techniques that we cannot capture? Third, we feel confident that we will be able to use Walker and Morrisett’s recursive formulae [41] or O’Hearn et al.’s inductive definitions [23] to code up recursive data structures, which we do not handle here, but the topic deserves deeper investigation. Finally, we have not discussed arrays in this paper. They would have to be handled either through a special macro that does the bounds check, or the system would need to be augmented with arithmetic formulae as in the work by Xi and Pfenning [42].

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