

# A Fast and Accurate Dependency Parser using Neural Networks



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Stanford University

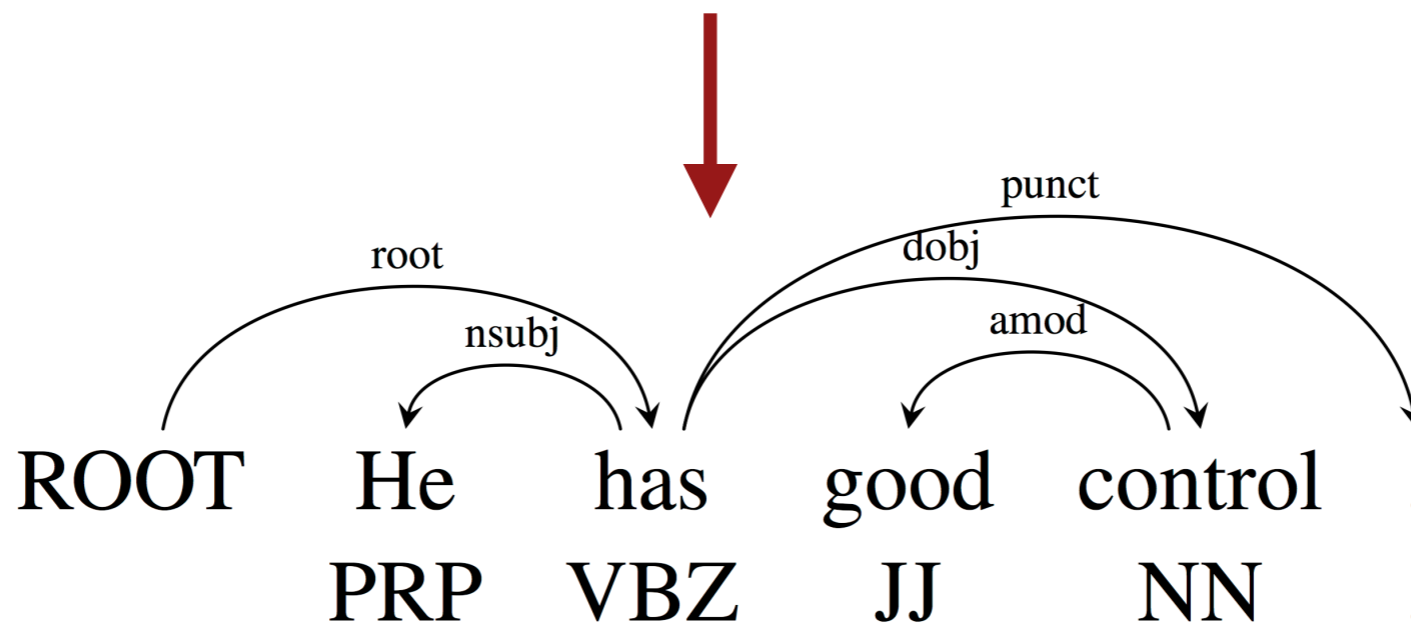
October 27, 2014



# Dependency Parsing

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He has good control.



Goal: **accurate** and **fast** parsing



# Our Work

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- A neural network based dependency parser!



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Parsing on English Penn Treebank (§23):

Unlabeled attachment score (UAS)                      sent / s

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Transition  
-based



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Graph  
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MSTParser

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12

TurboParser

93.1\*

31\*



# Our Work

- A neural network based dependency parser!

Parsing on English Penn Treebank (§23):

Unlabeled attachment score (UAS)

sent / s

		UAS		sent / s
Transition -based	MaltParser (greedy)	89.9	+2.1	560
	<b>Our Parser (greedy)</b>	<b>92.0</b>		<b>1013</b>
	Zpar: beam = 64	92.9*		29*
Graph -based	MSTParser	92.0		12
	TurboParser	93.1*		31*

*Note: Red arrows in the original image indicate a +2.1 point increase in UAS and a 1.8x increase in speed for 'Our Parser' compared to MaltParser.*





# Outline

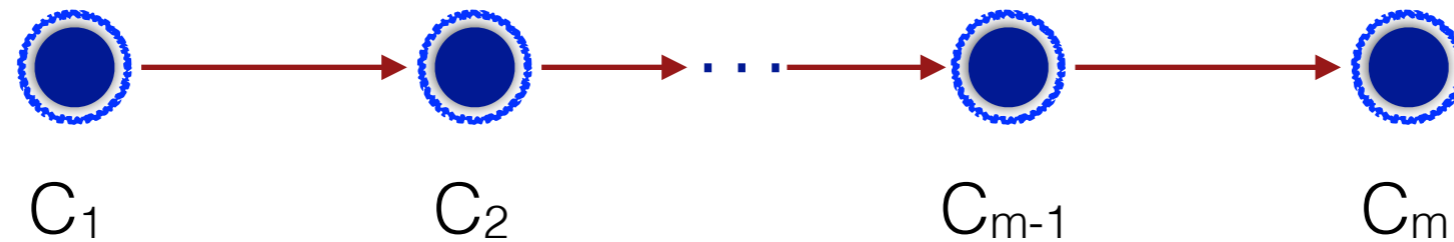
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- Background & Motivation
- Model
- Experiments
- Analysis



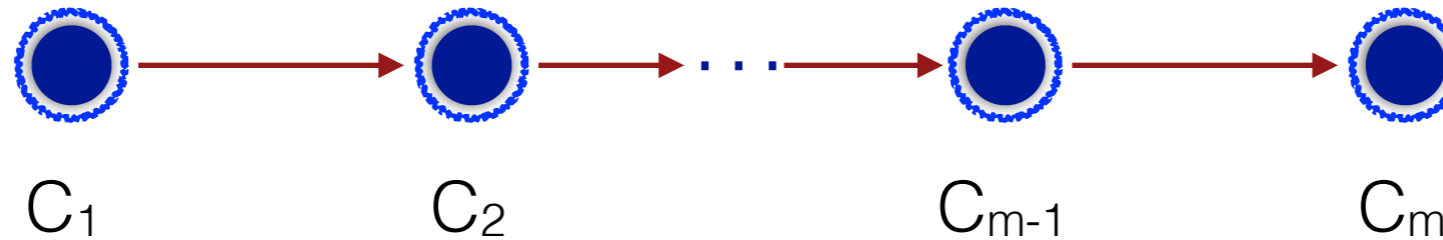
# Greedy Transition-based Parsing

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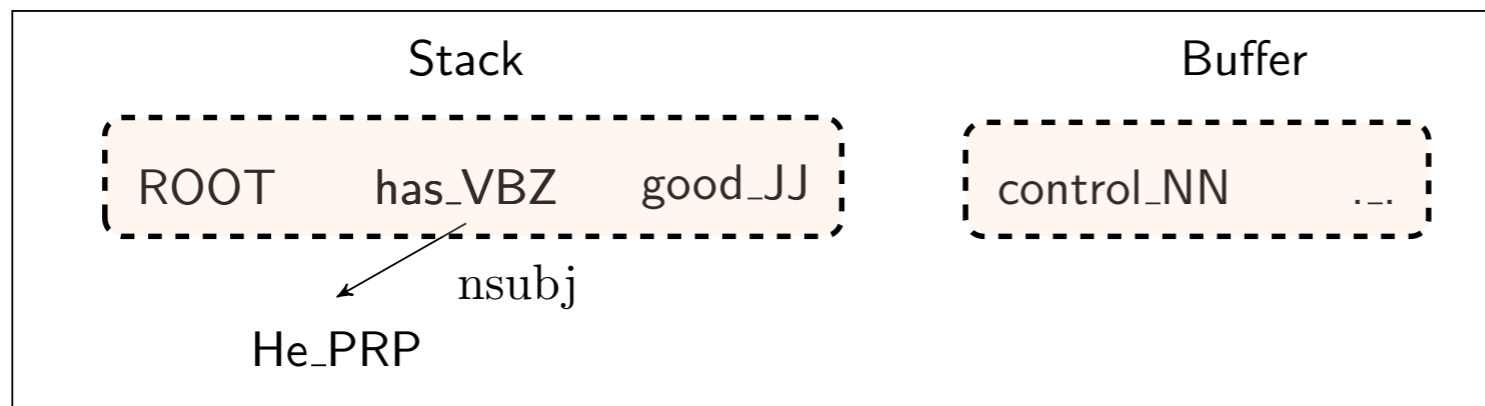




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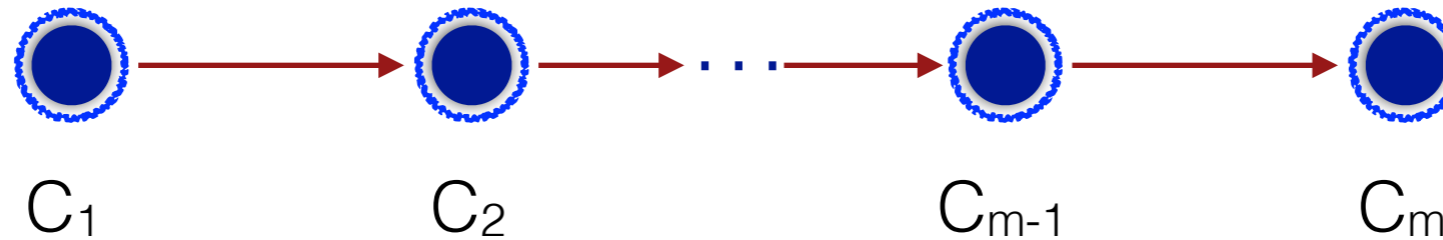


- A configuration = a stack, a buffer and some dependency arcs

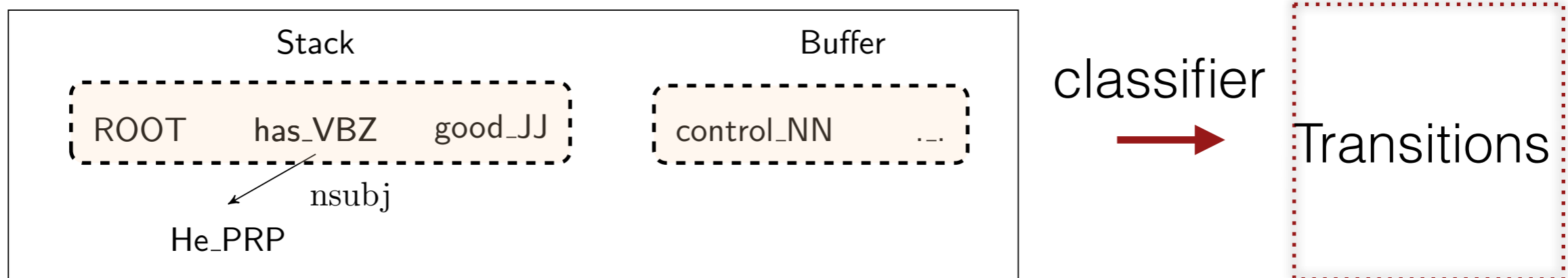




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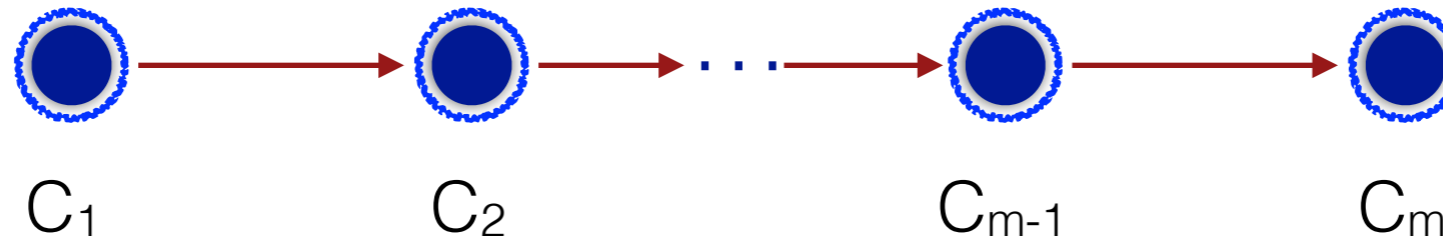


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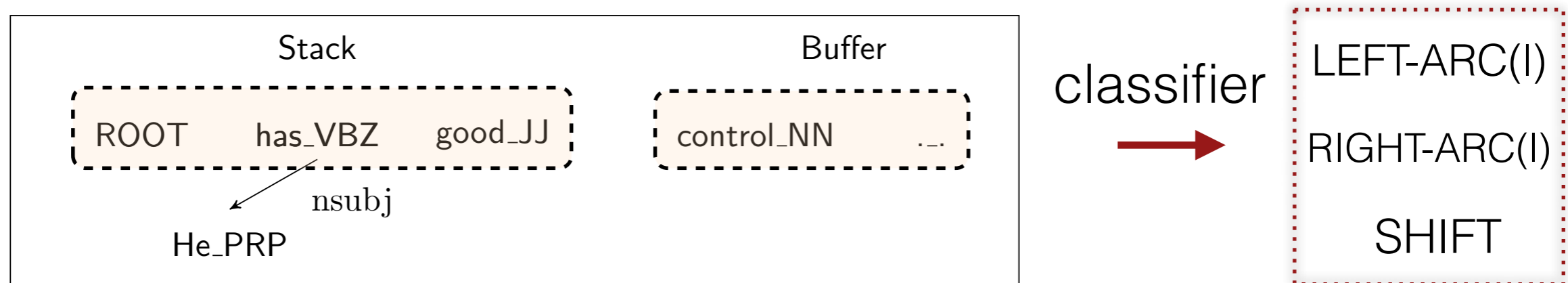




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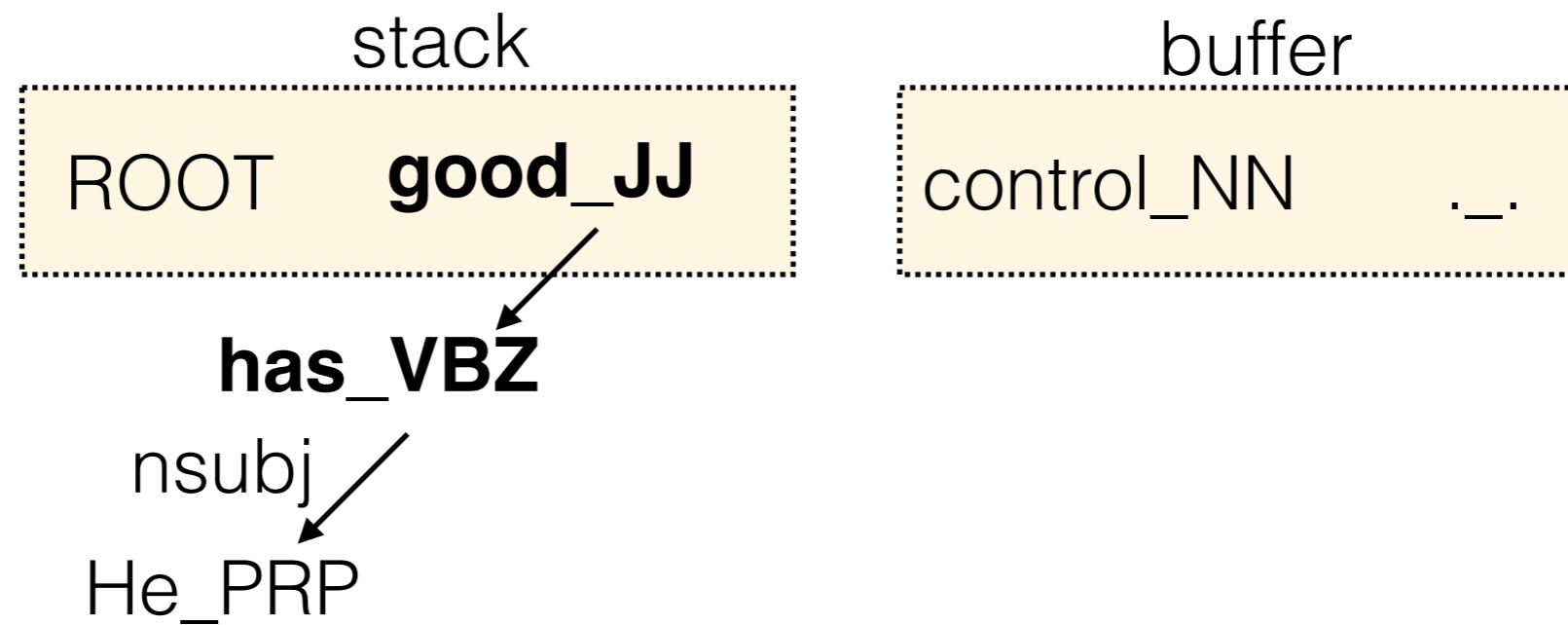
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- We employ the **arc-standard** system.

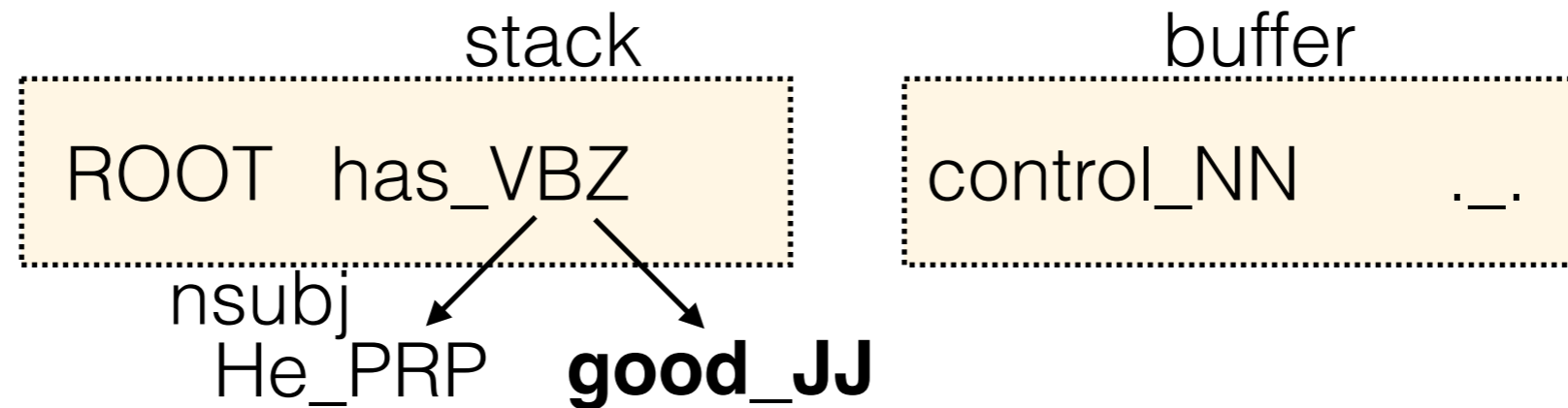


# LEFT-ARC (I)



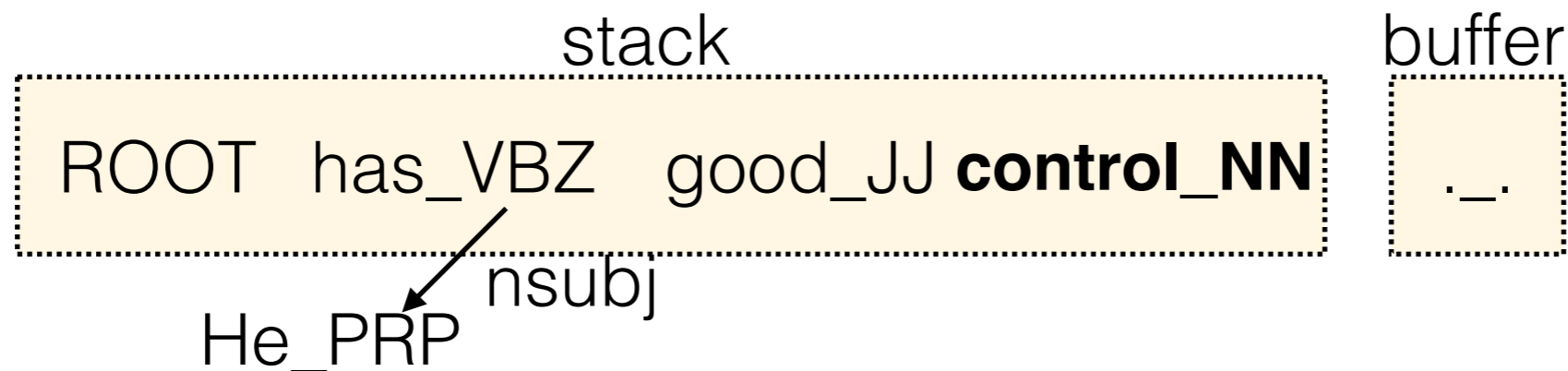


# RIGHT-ARC (I)





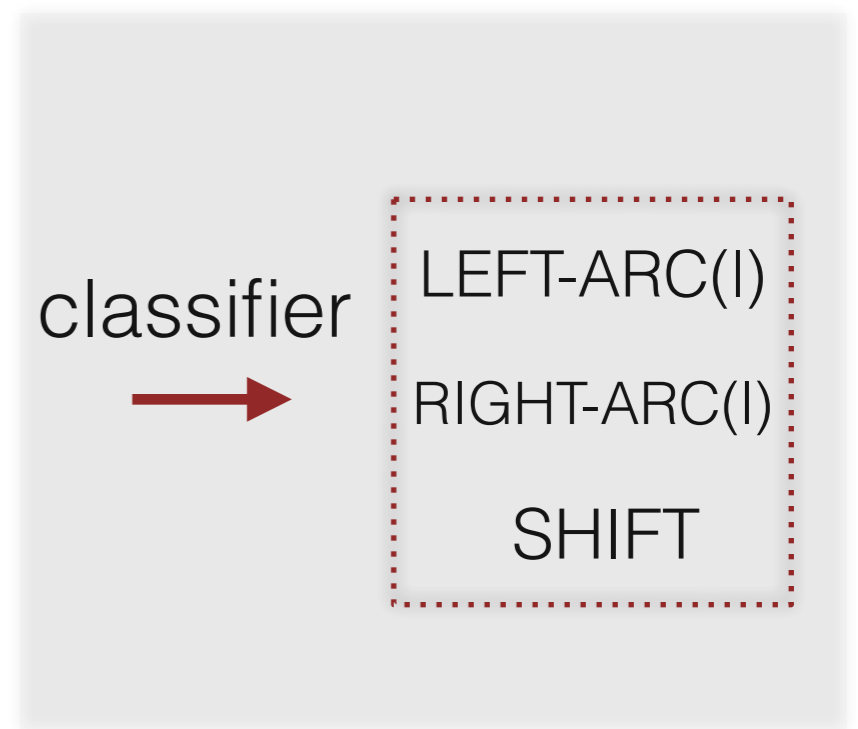
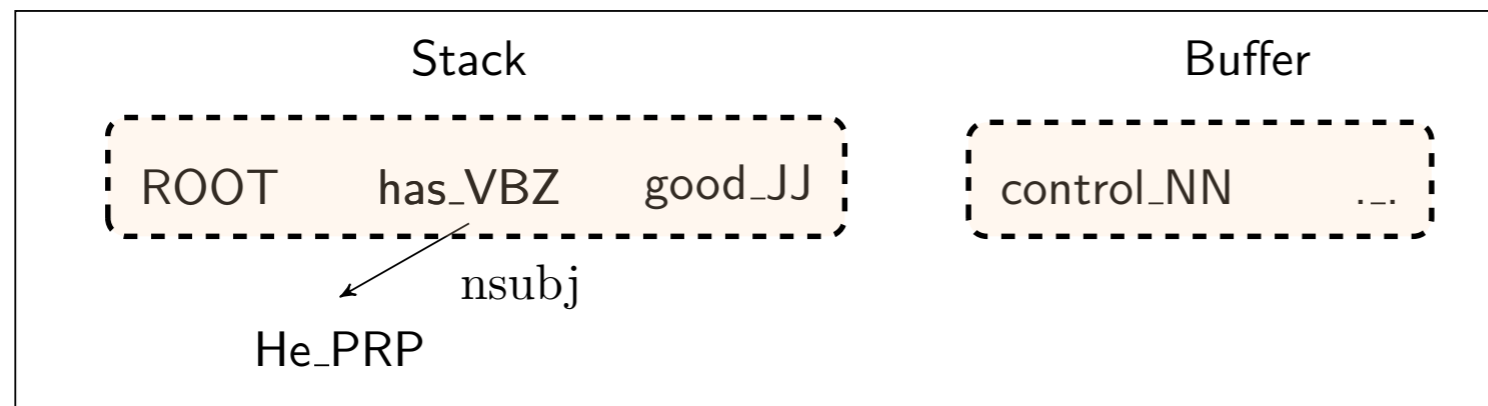
# SHIFT





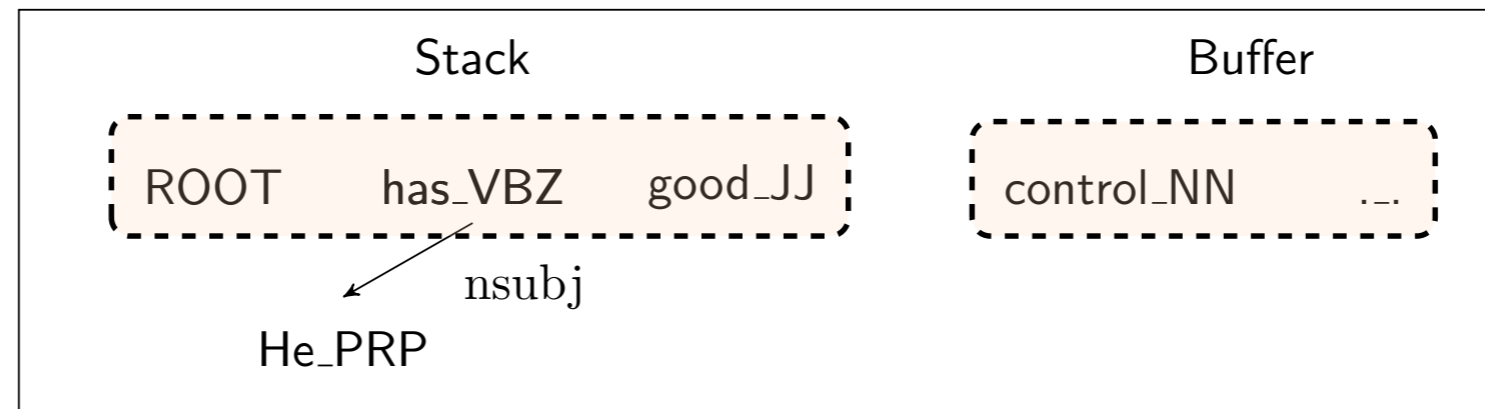


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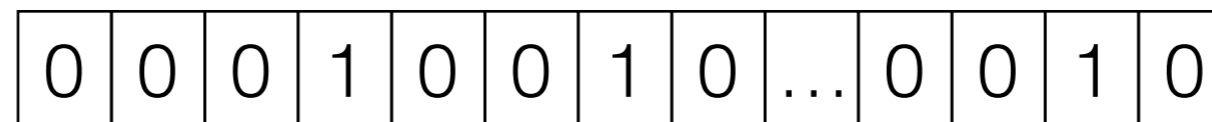




# Traditional Features



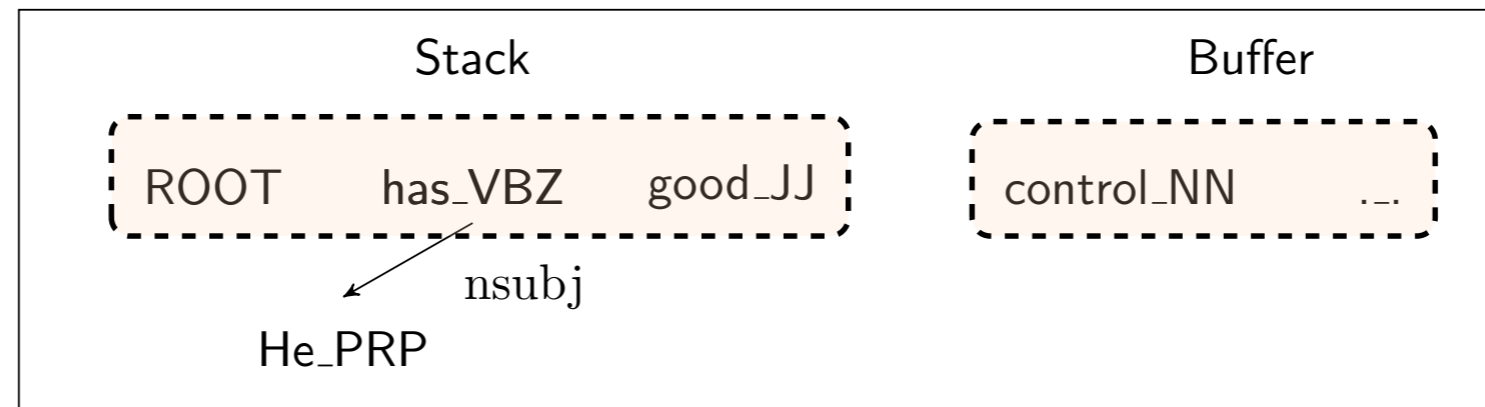
binary, sparse  
dim =  $10^6 \sim 10^7$



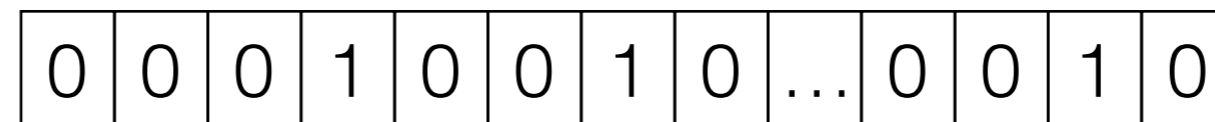
**Feature templates:** usually a combination of **1 ~ 3** elements from the configuration.



# Traditional Features



binary, sparse  
dim =  $10^6 \sim 10^7$

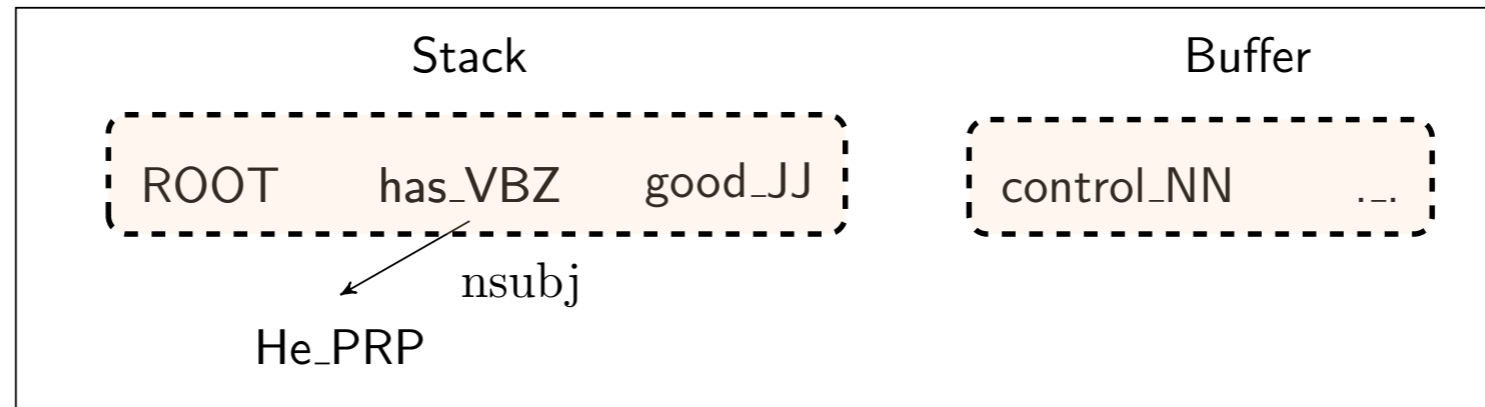


Indicator  
features

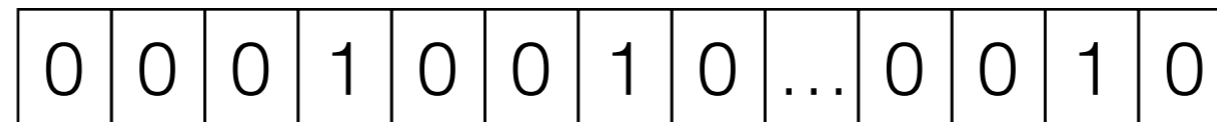
$$\begin{aligned}
 & s_2.w = \text{has} \wedge s_2.t = \text{VBZ} \\
 & s_1.w = \text{good} \wedge s_1.t = \text{JJ} \wedge b_1.w = \text{control} \\
 & lc(s_2).t = \text{PRP} \wedge s_2.t = \text{VBZ} \wedge s_1.t = \text{JJ} \\
 & lc(s_2).w = \text{He} \wedge lc(s_2).l = \text{nsubj} \wedge s_2.w = \text{has}
 \end{aligned}$$



# Traditional Features



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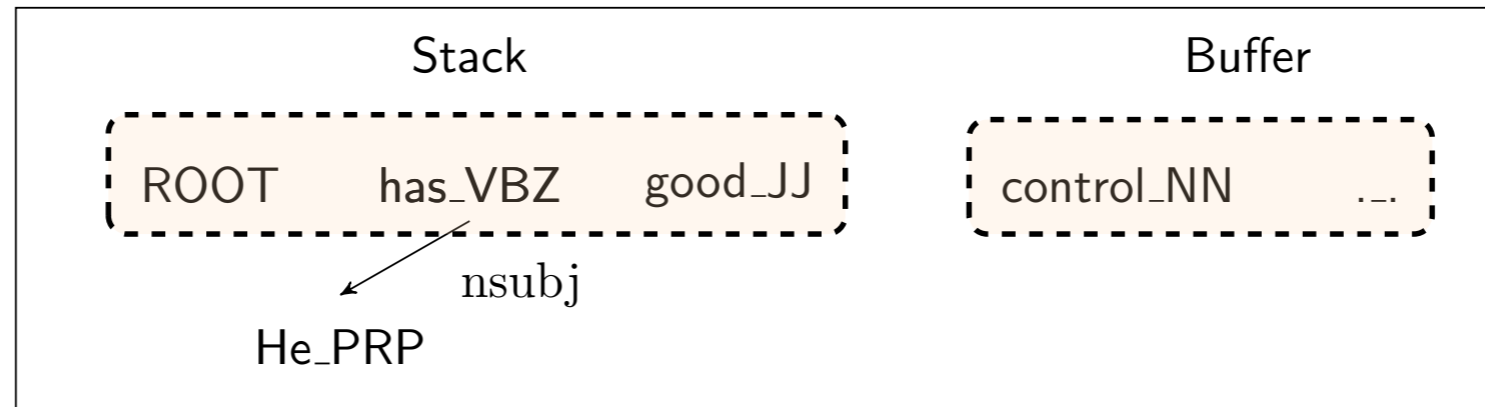


Indicator features

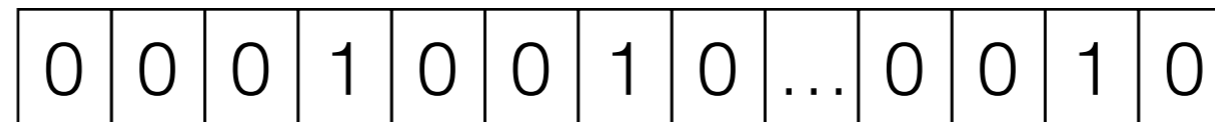
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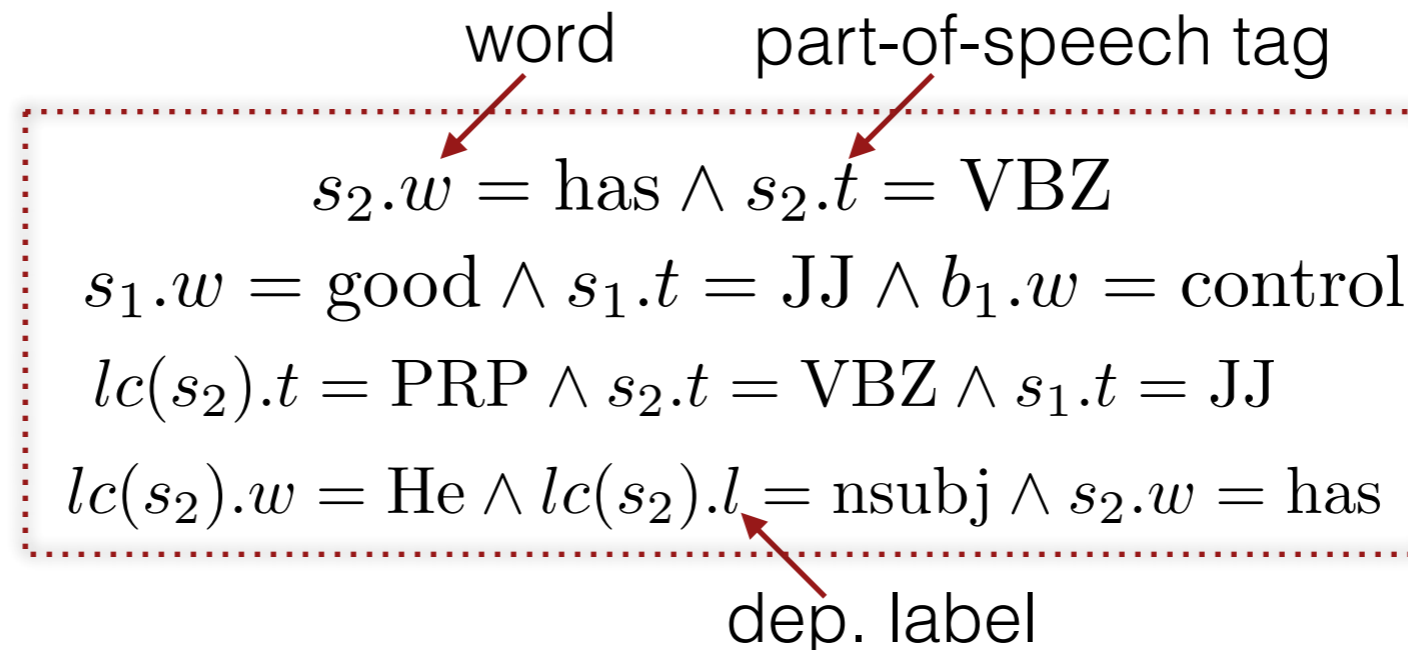
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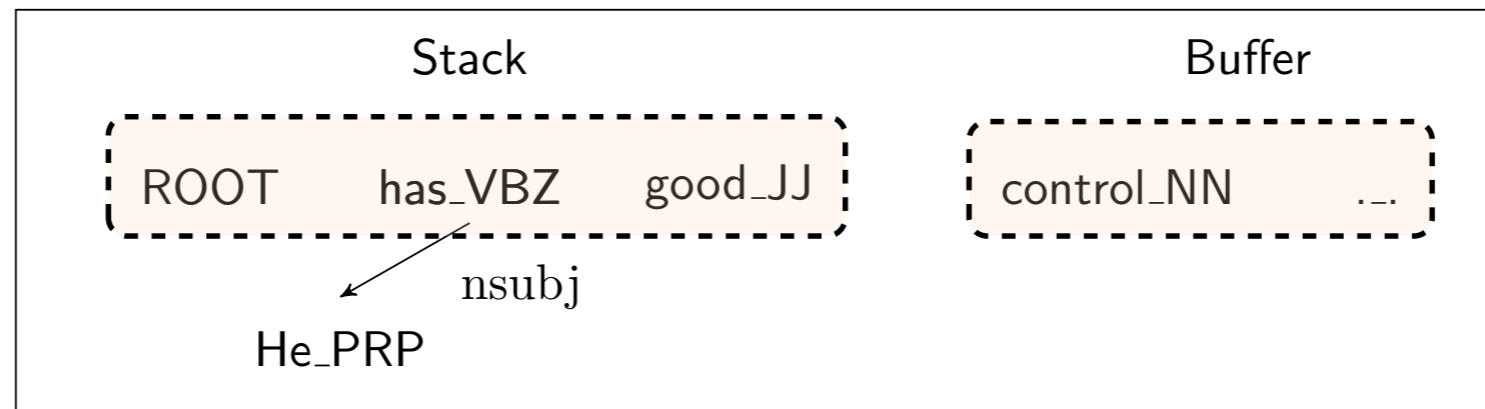


Indicator  
features

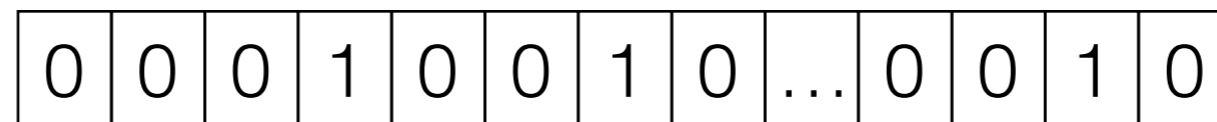




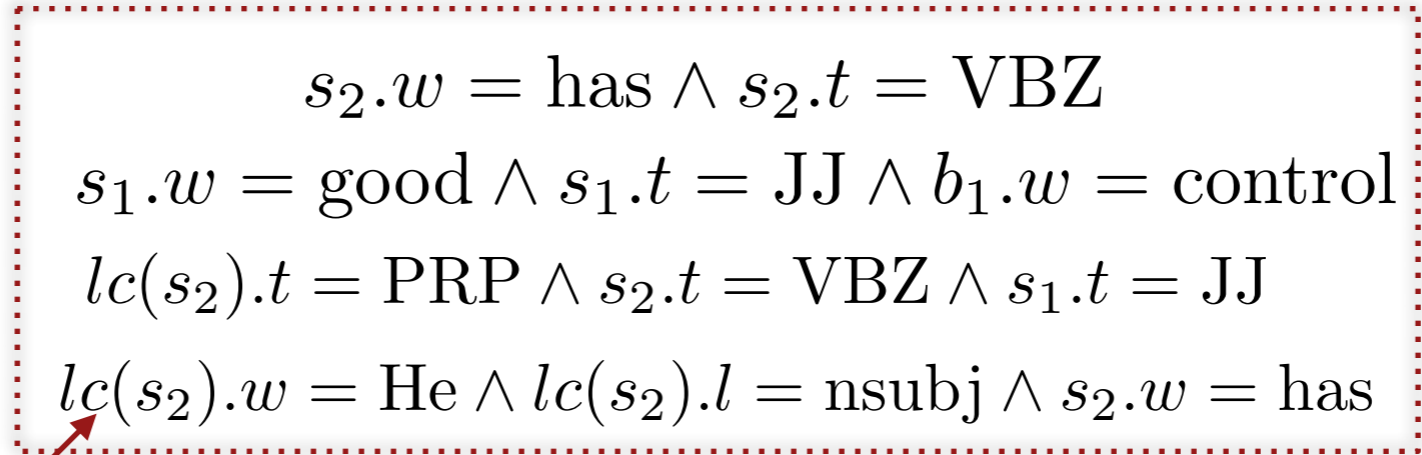
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Indicator features



leftmost child



# Indicator Features Revisited

---

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# Indicator Features Revisited

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- Problem #1: sparse
  - ▶ lexicalized features
  - ▶ high-order interaction features

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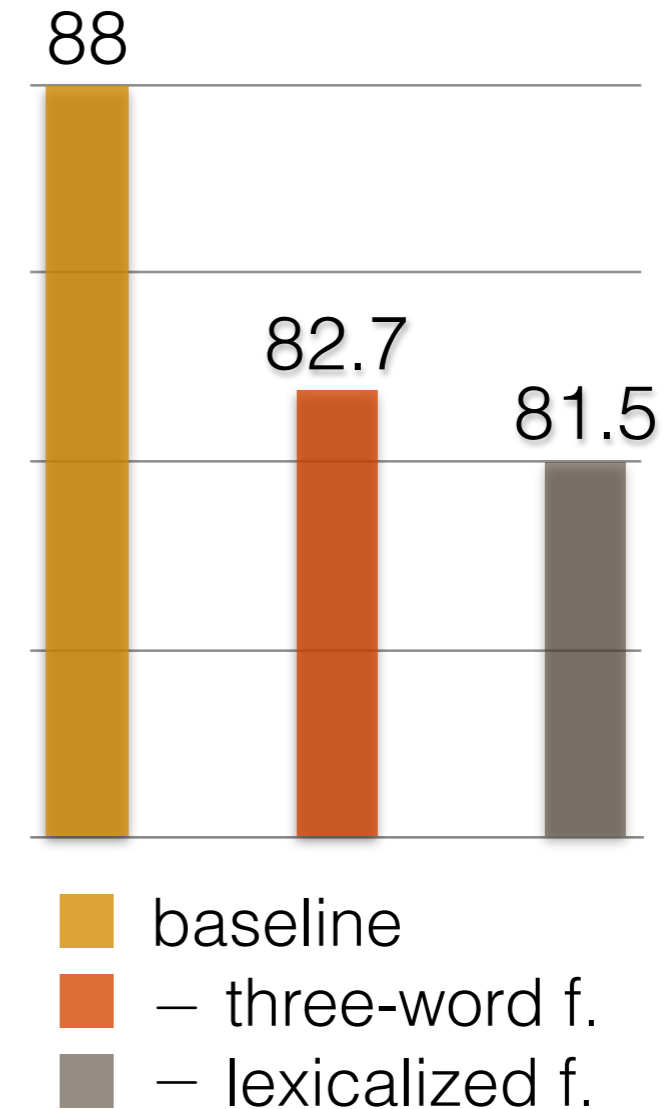




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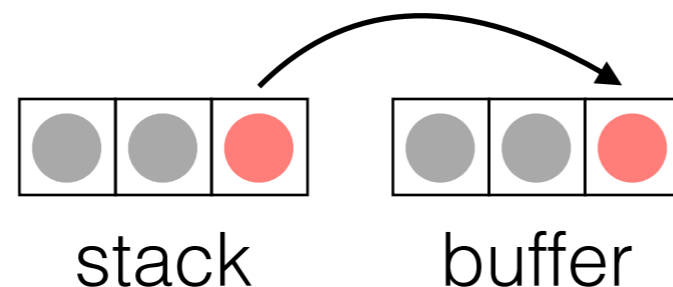
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# Indicator Features Revisited

- Problem #1: sparse
- Problem #2: incomplete

Unavoidable in hand-crafted feature templates.



~~RIGHT-ARC~~

$s_2.w = \text{has} \wedge s_2.t = \text{VBZ}$   
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# Indicator Features Revisited

---

- Problem #1: sparse
- Problem #2: incomplete
- Problem #3: computationally expensive

More than **95%** of parsing time is consumed by feature computation.

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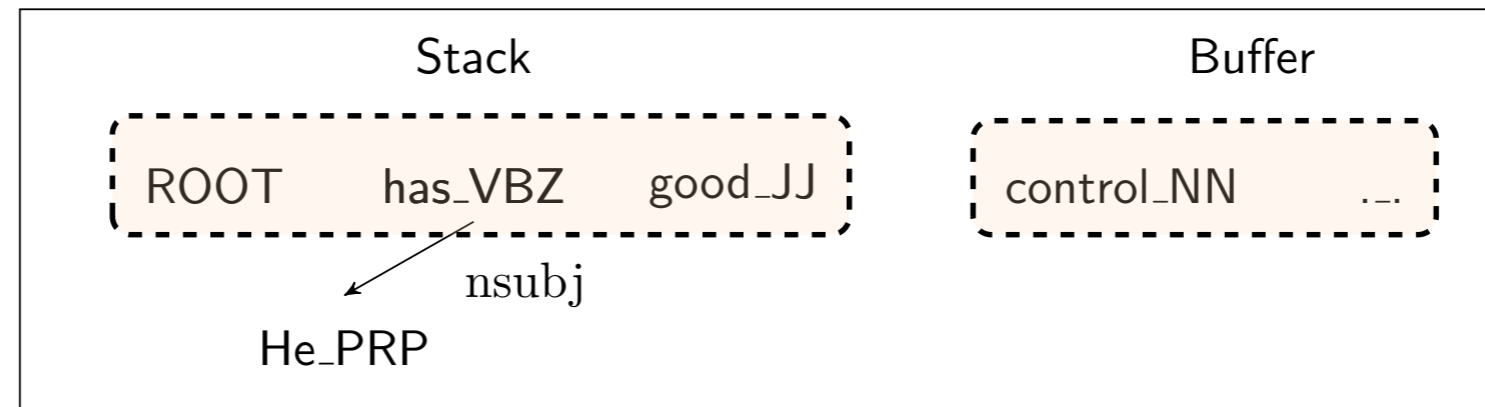
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# Indicator Features Revisited



dense  
dim = 200



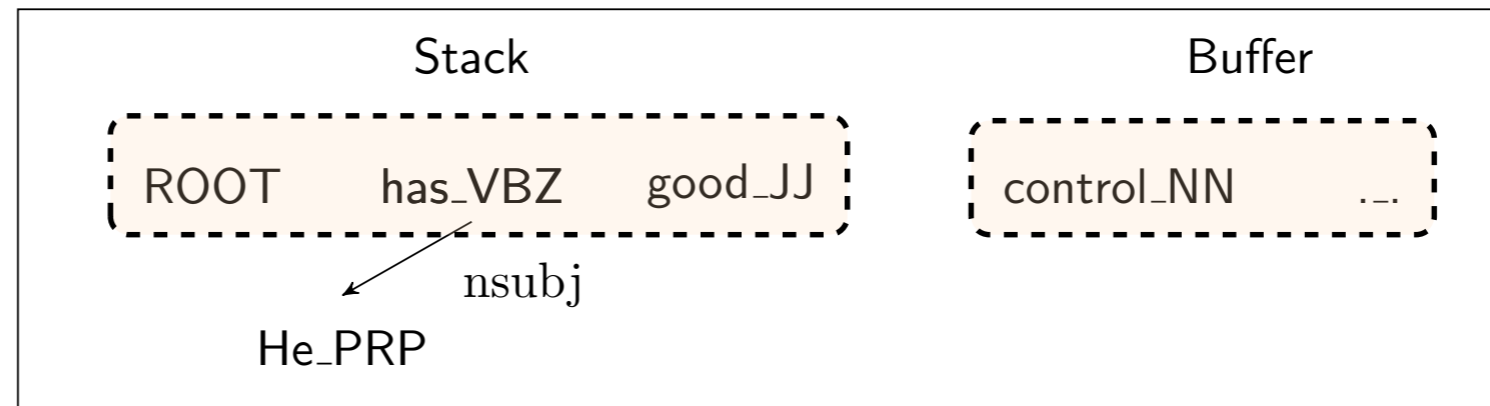
0.1	0.9	-0.2	0.3	...	-0.1	-0.5
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**Our Solution:** Neural Networks!

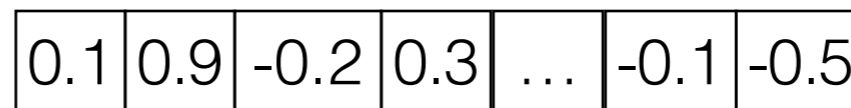
Learn a **dense** and **compact** feature representation



# The Challenge



dense  
dim = 200



- How to encode all the available information?
- How to model high-order features?



# Distributed Representations

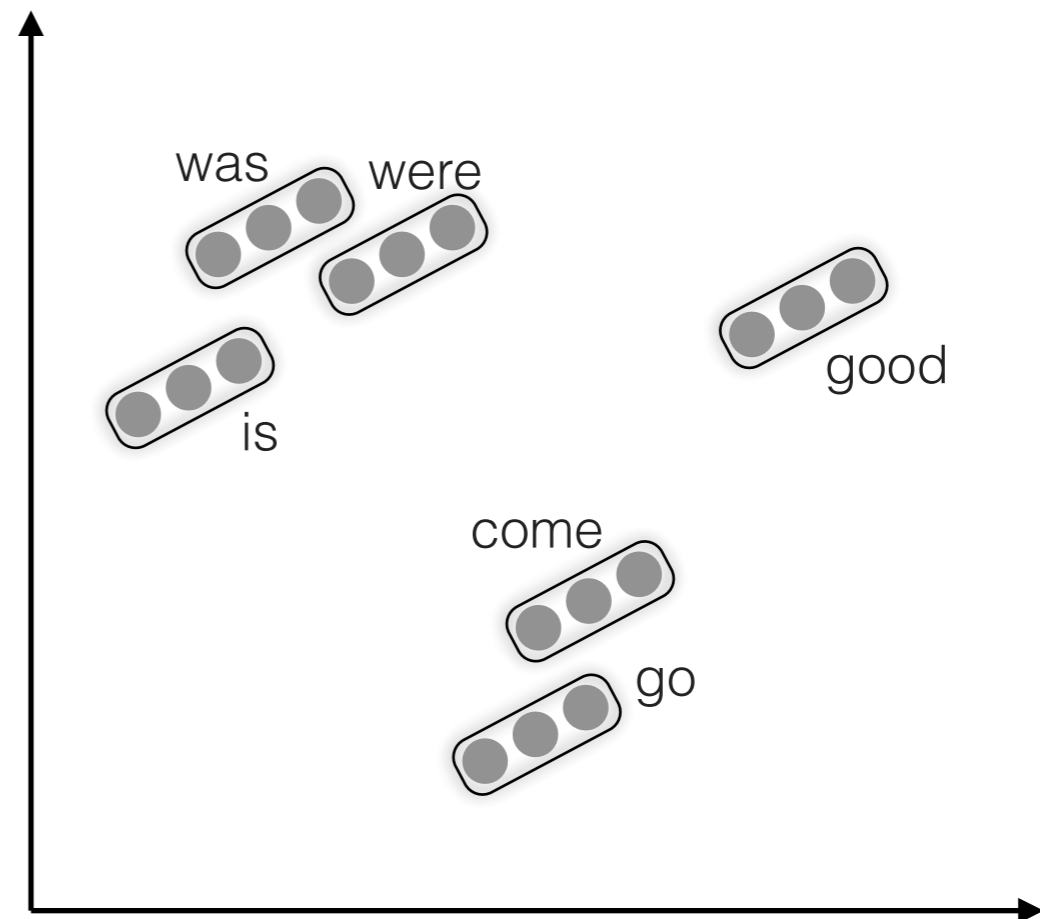
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# Distributed Representations

- We represent each word as a  $d$ -dimensional dense vector (i.e., word embeddings).
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  - POS and dependency embeddings.
  - The smaller discrete sets also exhibit many semantical similarities.



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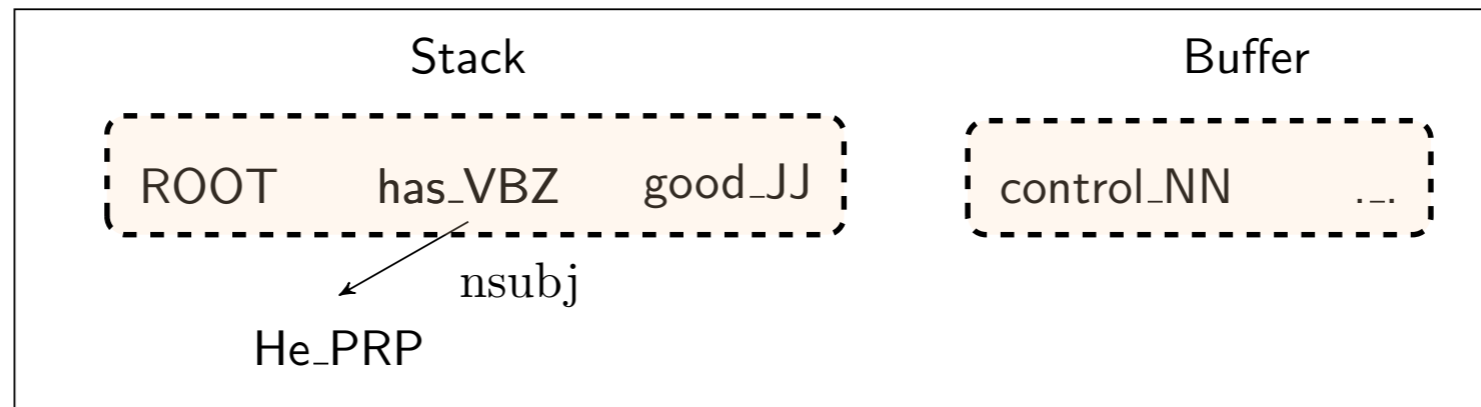
NNS (plural noun) should be close to NN (singular noun).

num (numerical modifier) should be close to amod (adjective modifier).



# Extracting Tokens from Configuration

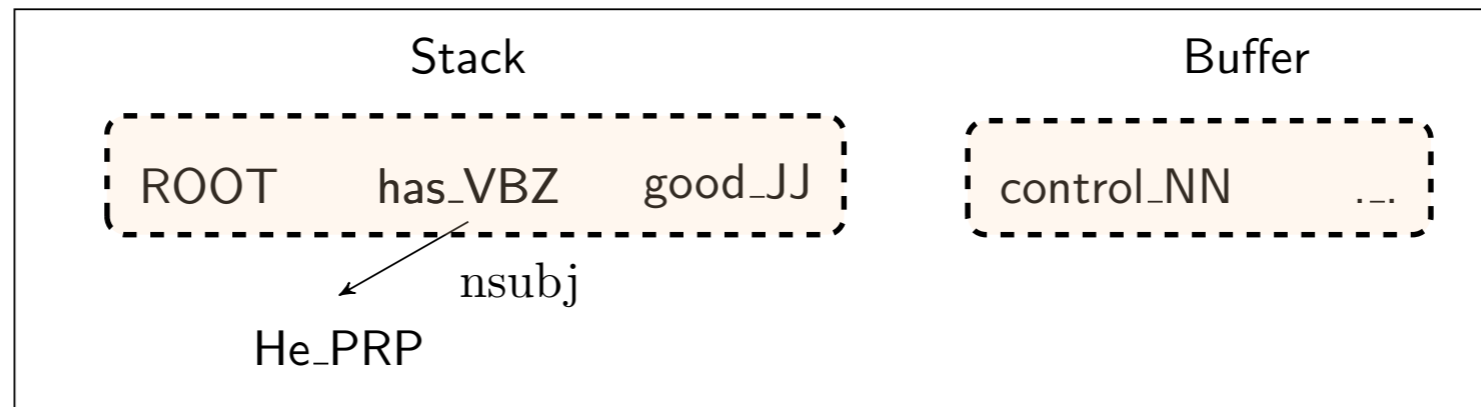
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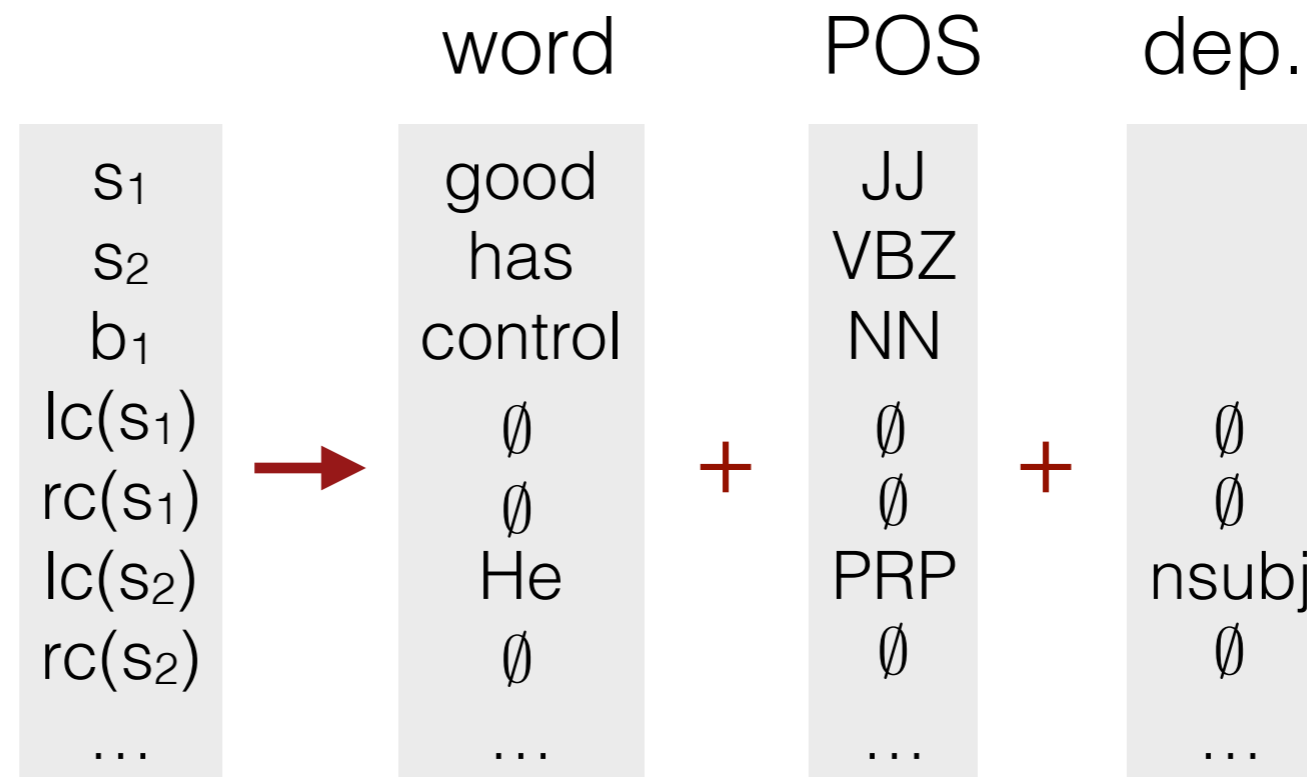
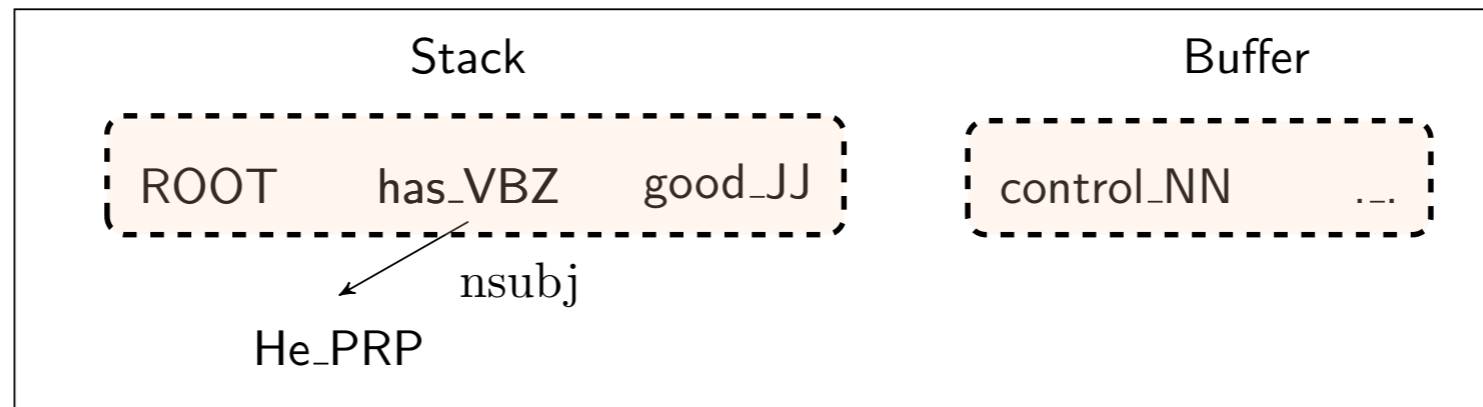


S<sub>1</sub>  
 S<sub>2</sub>  
 b<sub>1</sub>  
 lc(S<sub>1</sub>)  
 rc(S<sub>1</sub>)  
 lc(S<sub>2</sub>)  
 rc(S<sub>2</sub>)  
 ...



# Extracting Tokens from Configuration

- We extract a set of tokens based on the positions:



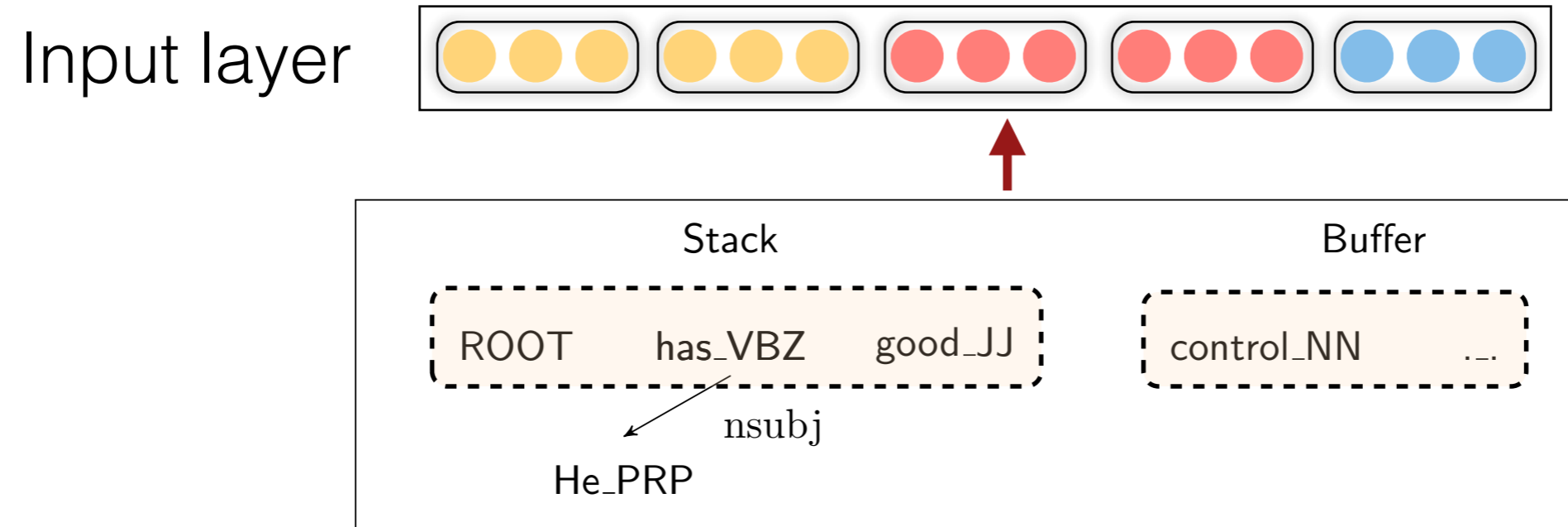


# Model Architecture

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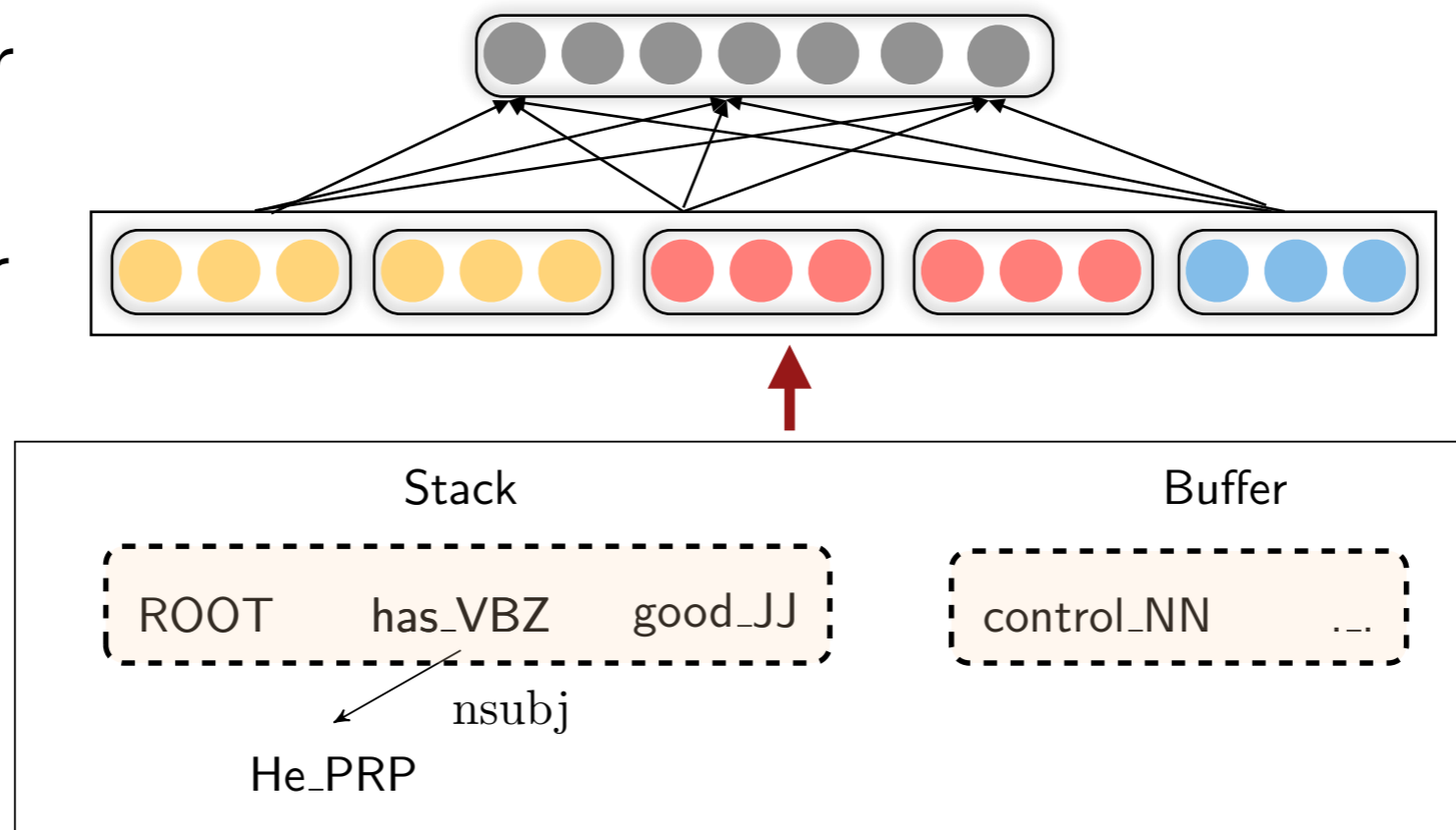




# Model Architecture

Hidden layer

Input layer



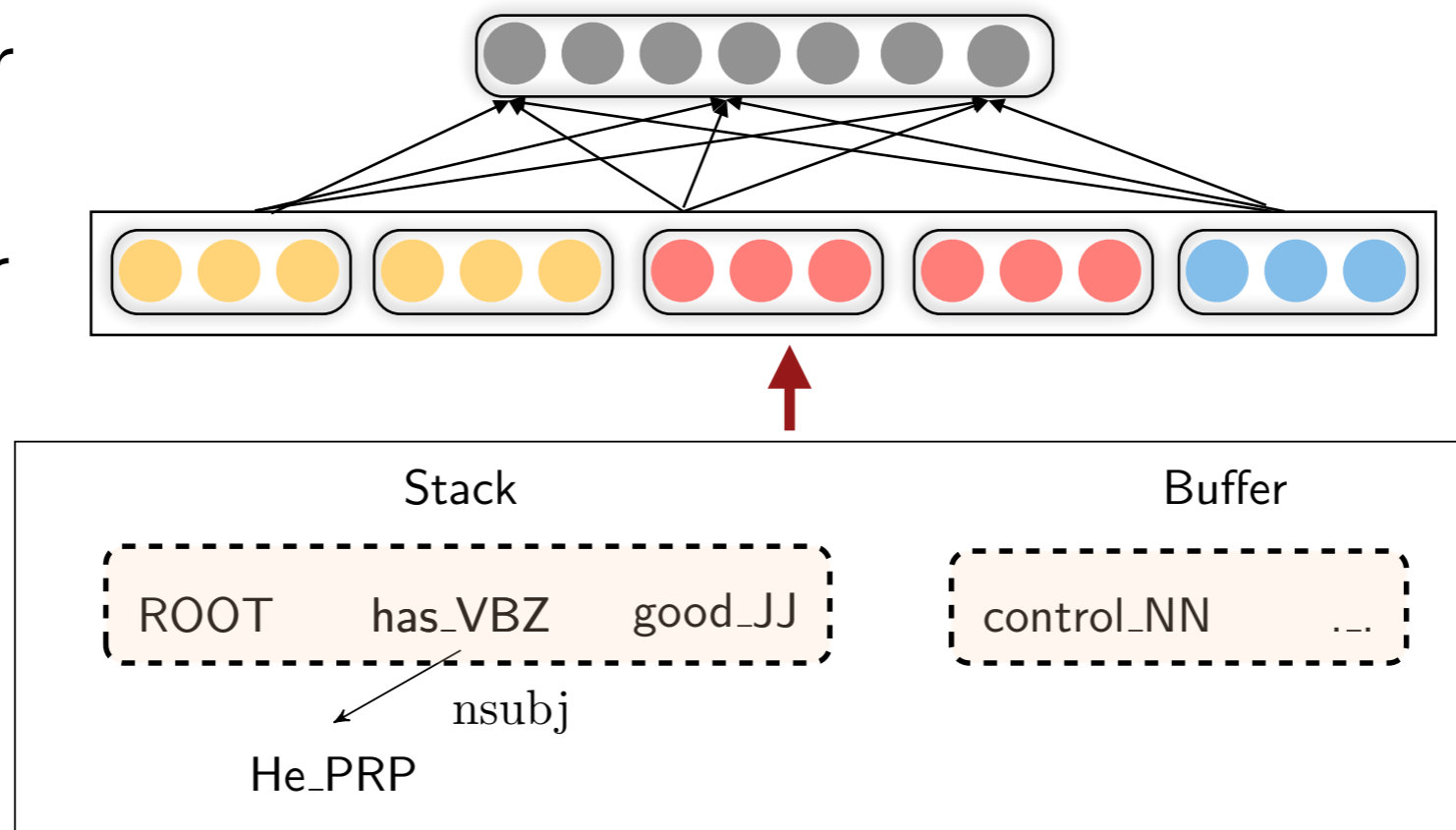


# Model Architecture

Cube activation function:  $g(x) = x^3$

Hidden layer

Input layer





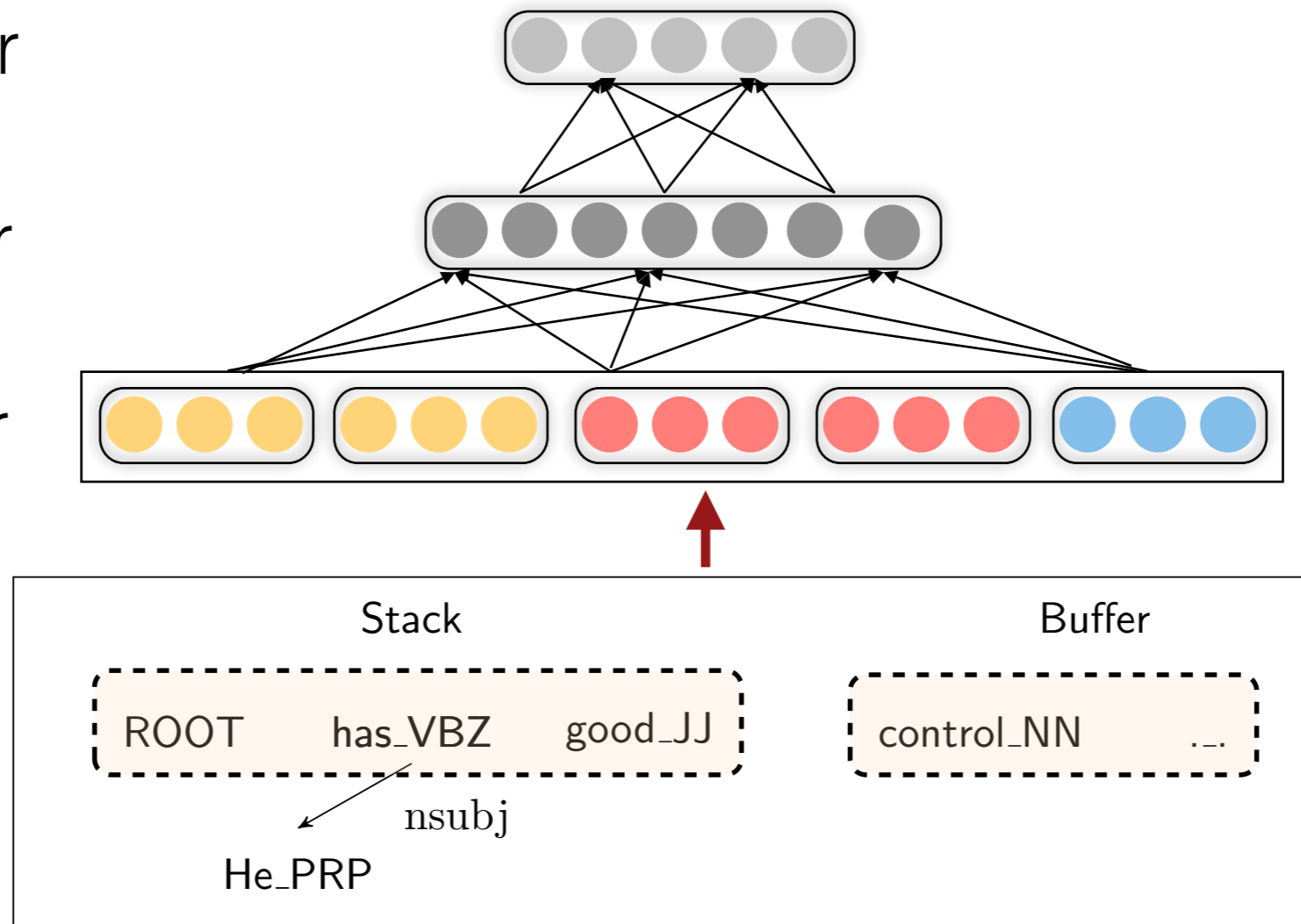
# Model Architecture

## Softmax probabilities

Output layer

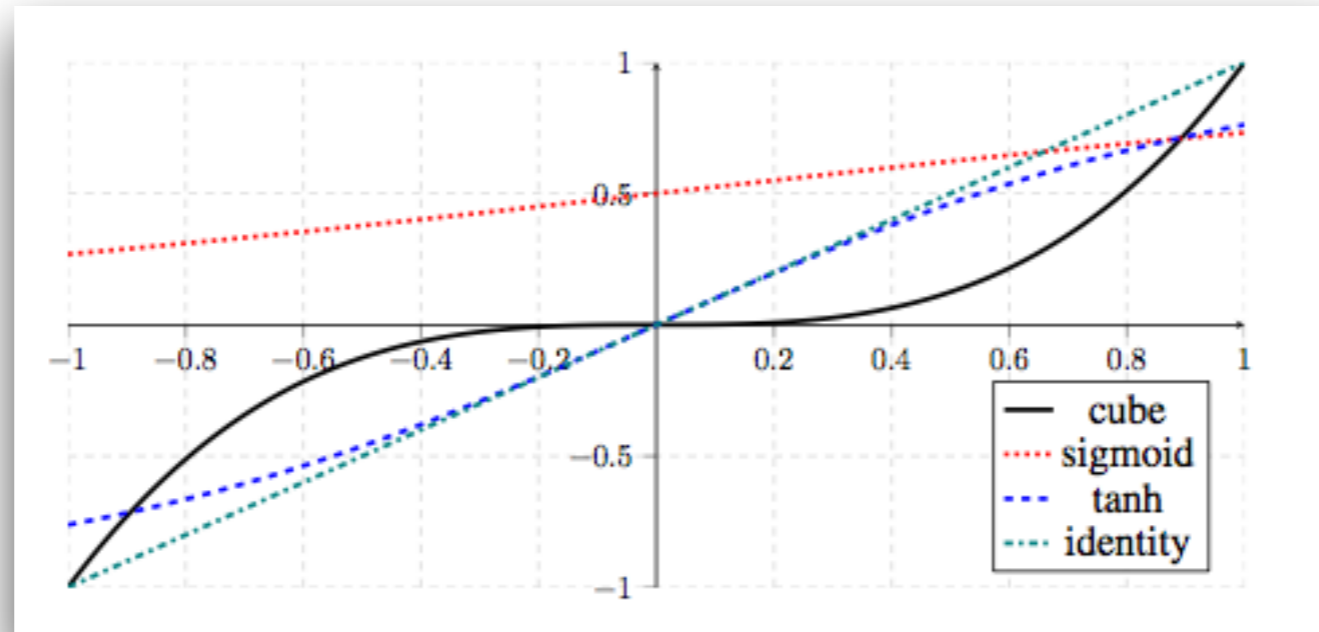
Hidden layer

Input layer





# Cube Activation Function



$$g(w_1x_1 + \dots + w_mx_m + b) = \sum_{i,j,k} (w_iw_jw_k)x_ix_jx_k + \sum_{i,j} b(w_iw_j)x_ix_j \dots$$

Better capture the **interaction** terms!



# Training

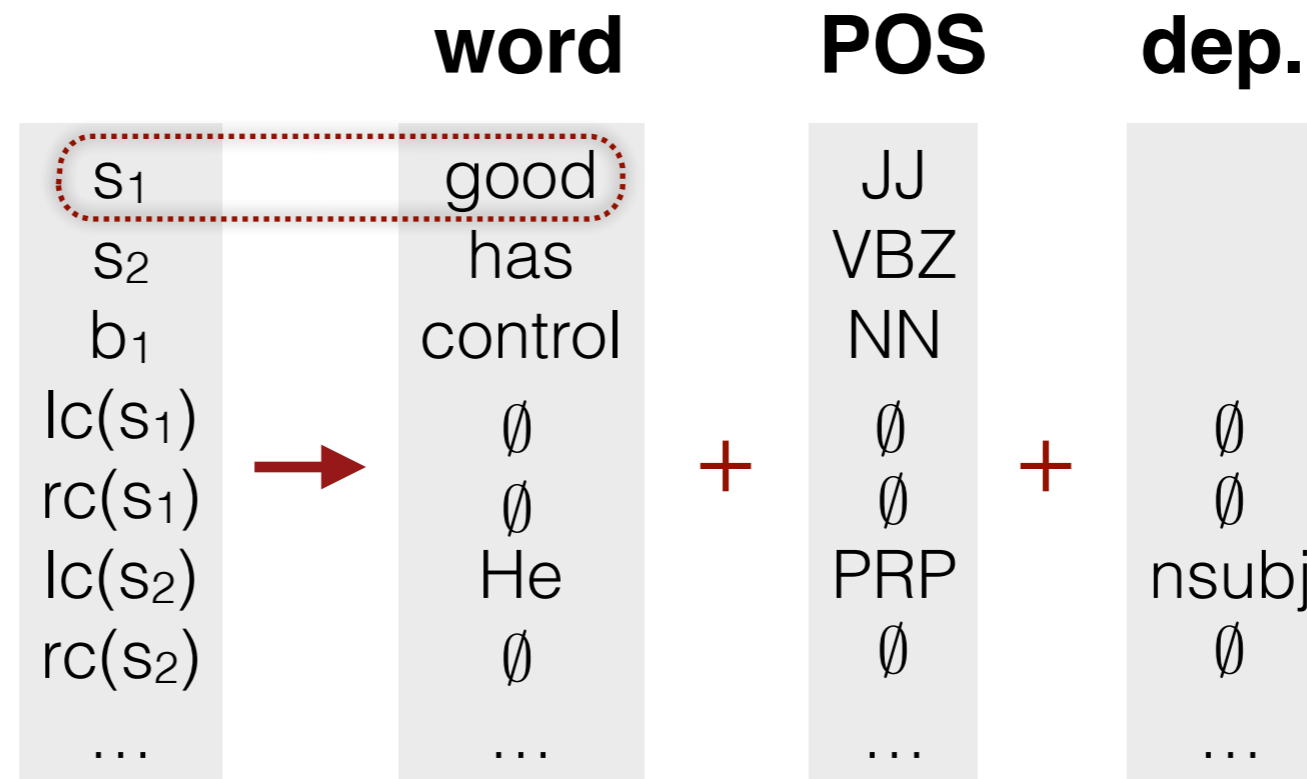
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- Generating training examples using a fixed oracle.
- **Training objective:** cross entropy loss
- Back-propagation to all embeddings.
- **Initialization:**
  - Word embeddings from pre-trained word vectors.
  - Random initialization for others.



# Parsing Speed-up

- Pre-computation trick:



- If we have seen (s<sub>1</sub>, good) many times in training set, we can pre-compute matrix multiplications before parsing — reducing multiplications to additions.
- 8 ~ 10 times faster.



# Indicator vs. Dense Features

---

- Problem #1: sparse

Distributed representations can capture similarities.



# Indicator vs. Dense Features

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- **Problem #1: sparse**

Distributed representations can capture similarities.

- **Problem #2: incomplete**

We don't need to enumerate the combinations.  
Cube non-linearity can learn combinations automatically.





# Indicator vs. Dense Features

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- **Problem #1: sparse**

Distributed representations can capture similarities.

- **Problem #2: incomplete**

We don't need to enumerate the combinations.  
Cube non-linearity can learn combinations automatically.

- **Problem #3: computationally expensive**

String concatenation + look-up in a big table  $\implies$  matrix operations. Pre-computation trick can speed up.



# Experimental Setup

---

- **Datasets**
  - English Penn Treebank (PTB)
  - Chinese Penn Treebank (CTB)
- **Representations**
  - CoNLL representations (CD) for PTB and CTB
  - Stanford Dependencies V3.3.0 (SD) for PTB
- **Part-of-speech tags:**
  - Stanford POS tagger for PTB (97.3% accuracy)
  - Gold tags for CTB



# Details

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- Embedding size = 50
- Hidden size = 200
- Use mini-batched AdaGrad for optimization ( $\alpha = 0.01$ )
- Use 0.5 dropout on hidden layer.
  
- Pre-trained word vectors:
  - C & W for English
  - Word2vec for Chinese
  
- We use a rich set of 18 tokens from the configuration.



# Baselines

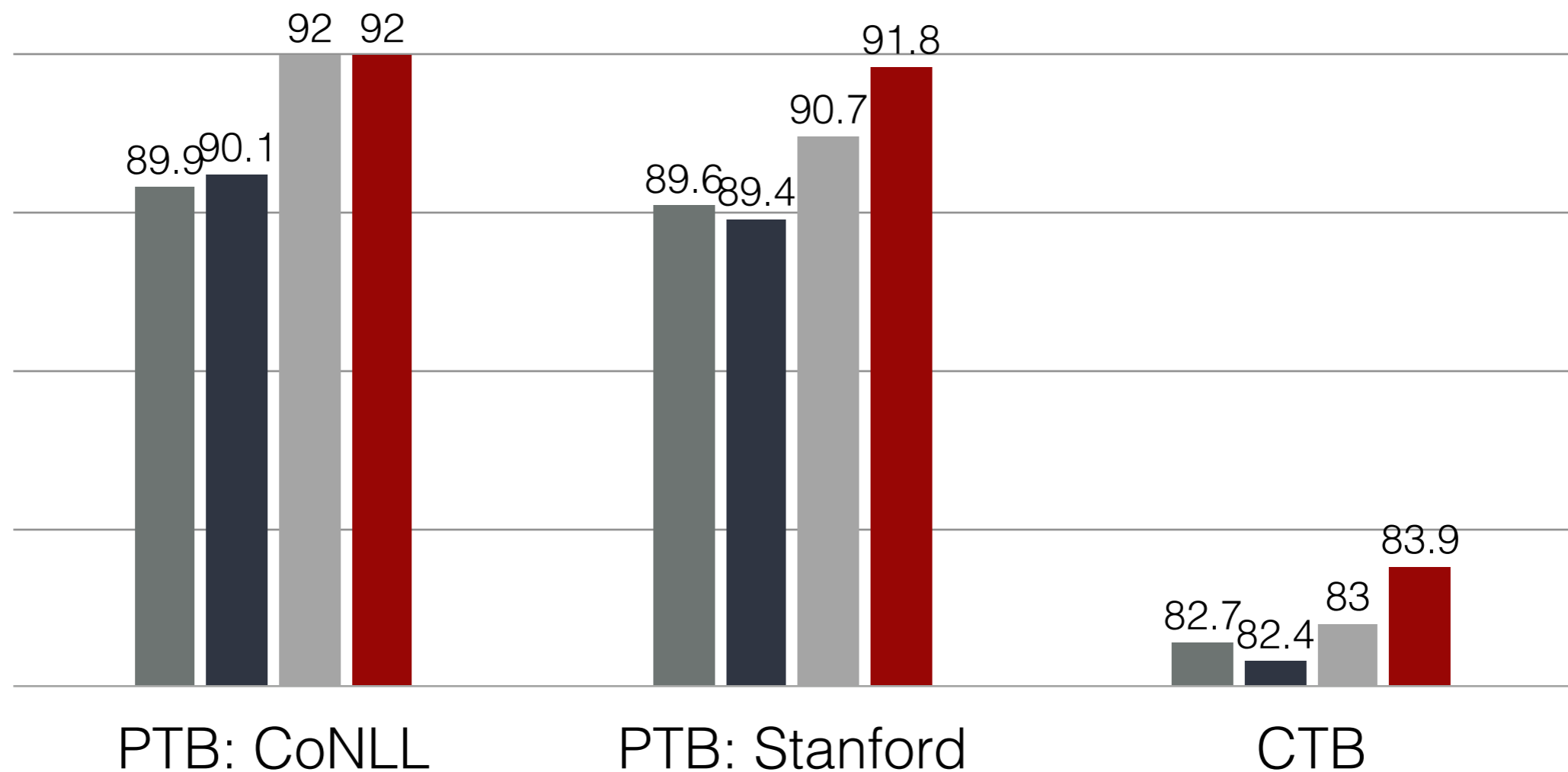
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- **Standard / eager:** our own implemented perceptron-based greedy parsers using arc-standard or arc-eager system, with a rich feature set from (Zhang and Nivre, 2011).
- **MaltParser**
  - two algorithms **stackproj** and **nivreeager**.
- **MSTParser**



# Unlabeled Attachment Score (UAS)

- Standard / eager
- Malt (stackproj / nirveeager)
- MST
- Our Parser

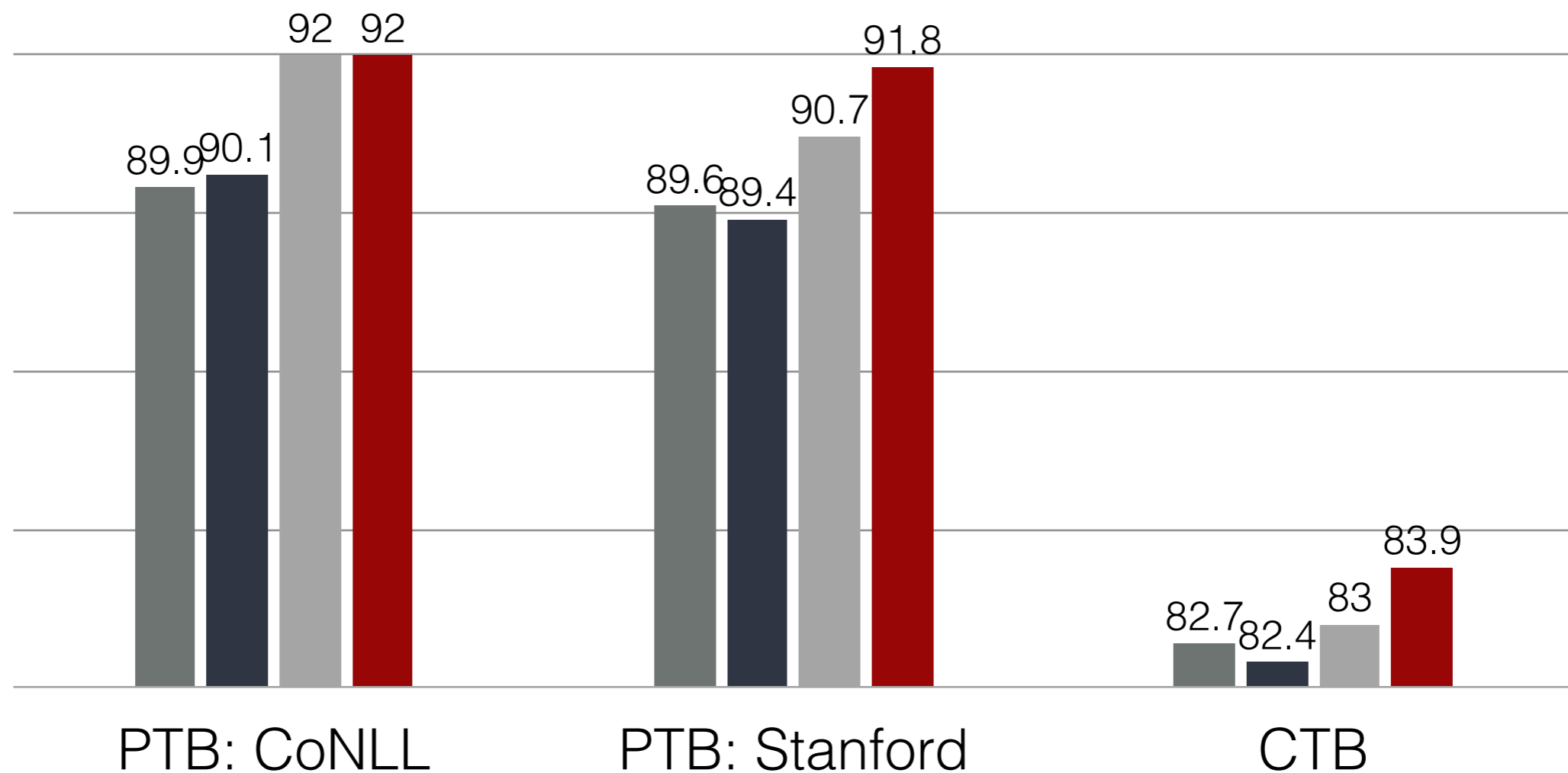




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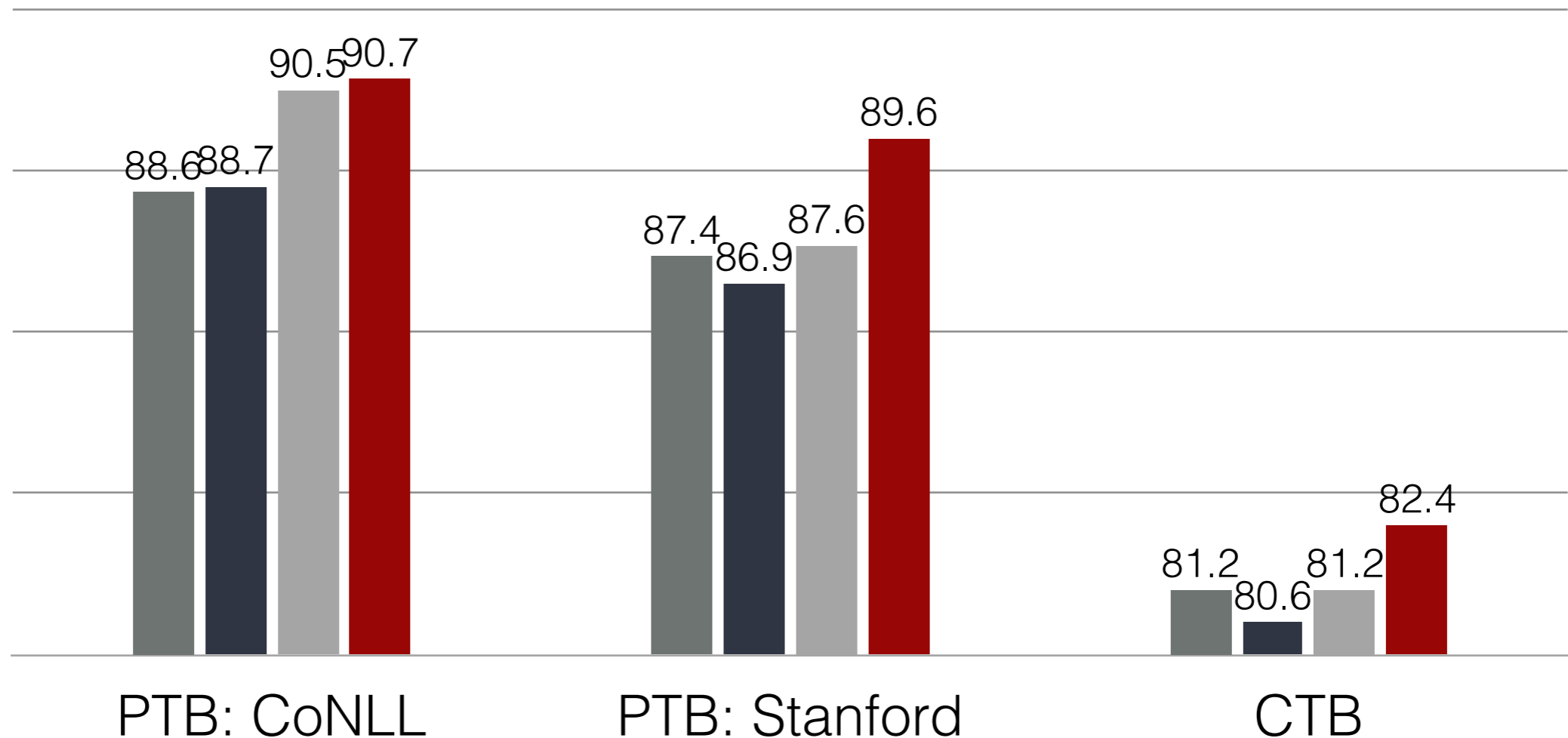
Compared with greedy parsers,  
 PTB: > 2.0%  
 CTB: > 1.2%





# Labeled Attachment Score (LAS)

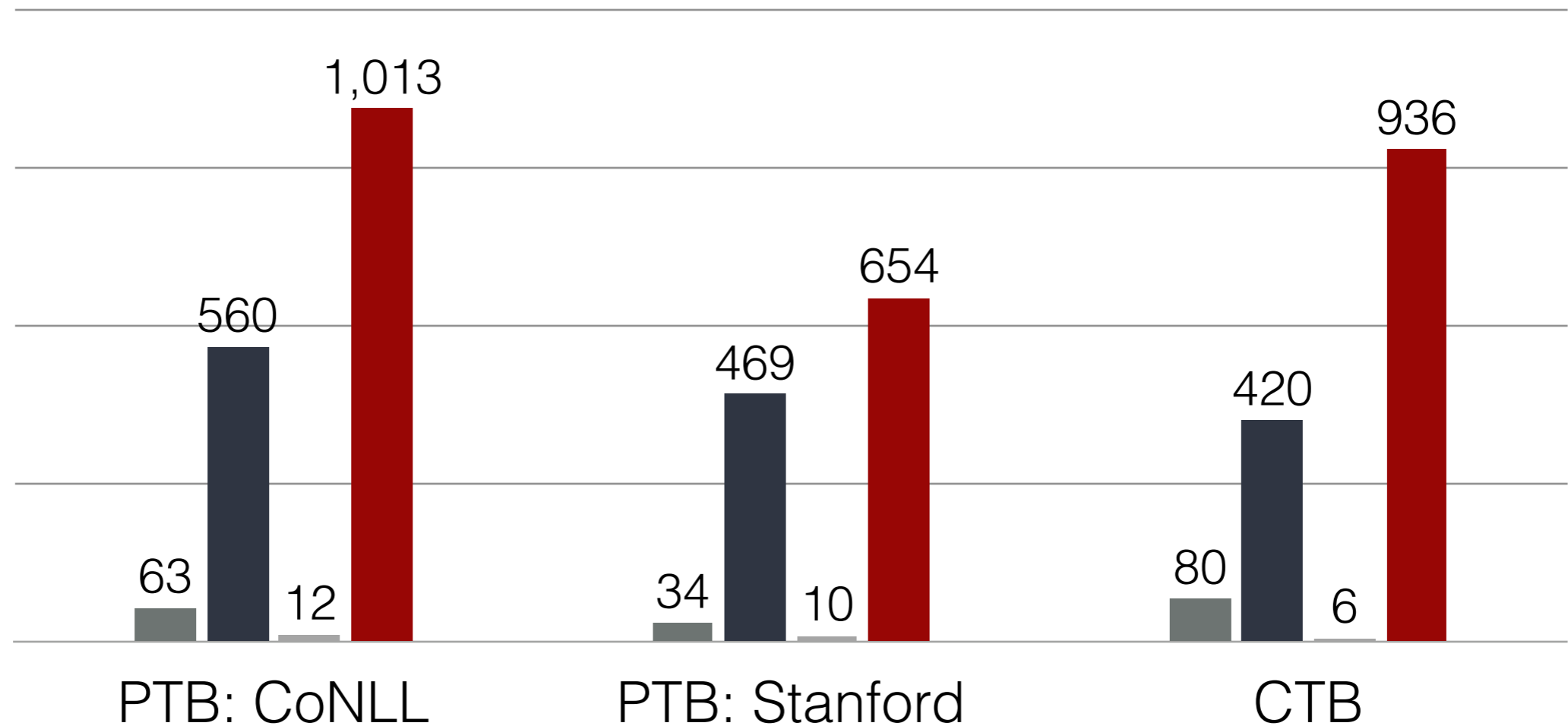
- Standard / eager
- Malt (stackproj / nirveeager)
- MST
- Our Parser





# Parsing Speed (sent/s)

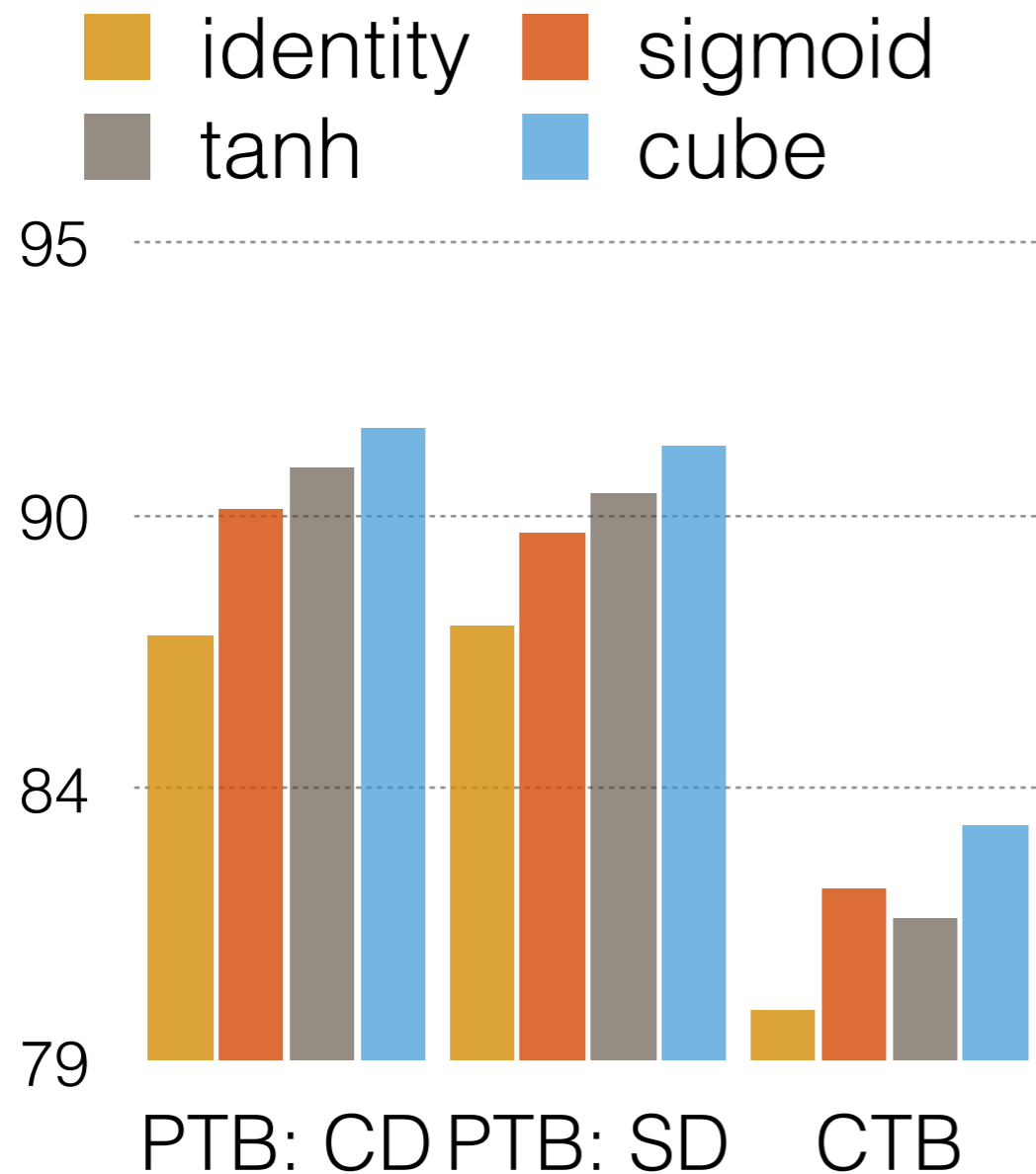
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- MST
- Our Parser







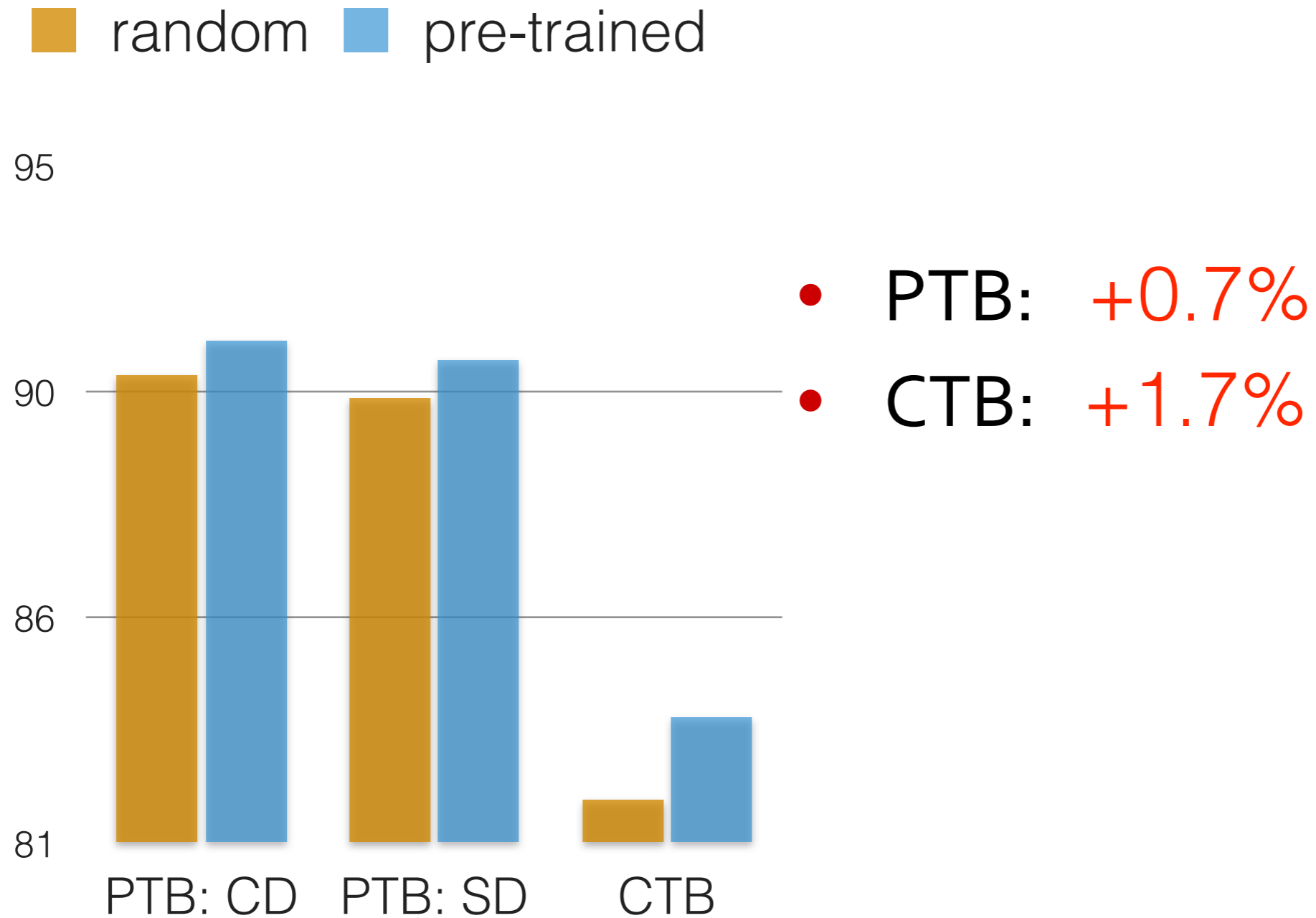
# Cube Activation Function



Cube:  
+0.8% ~ 1.2%

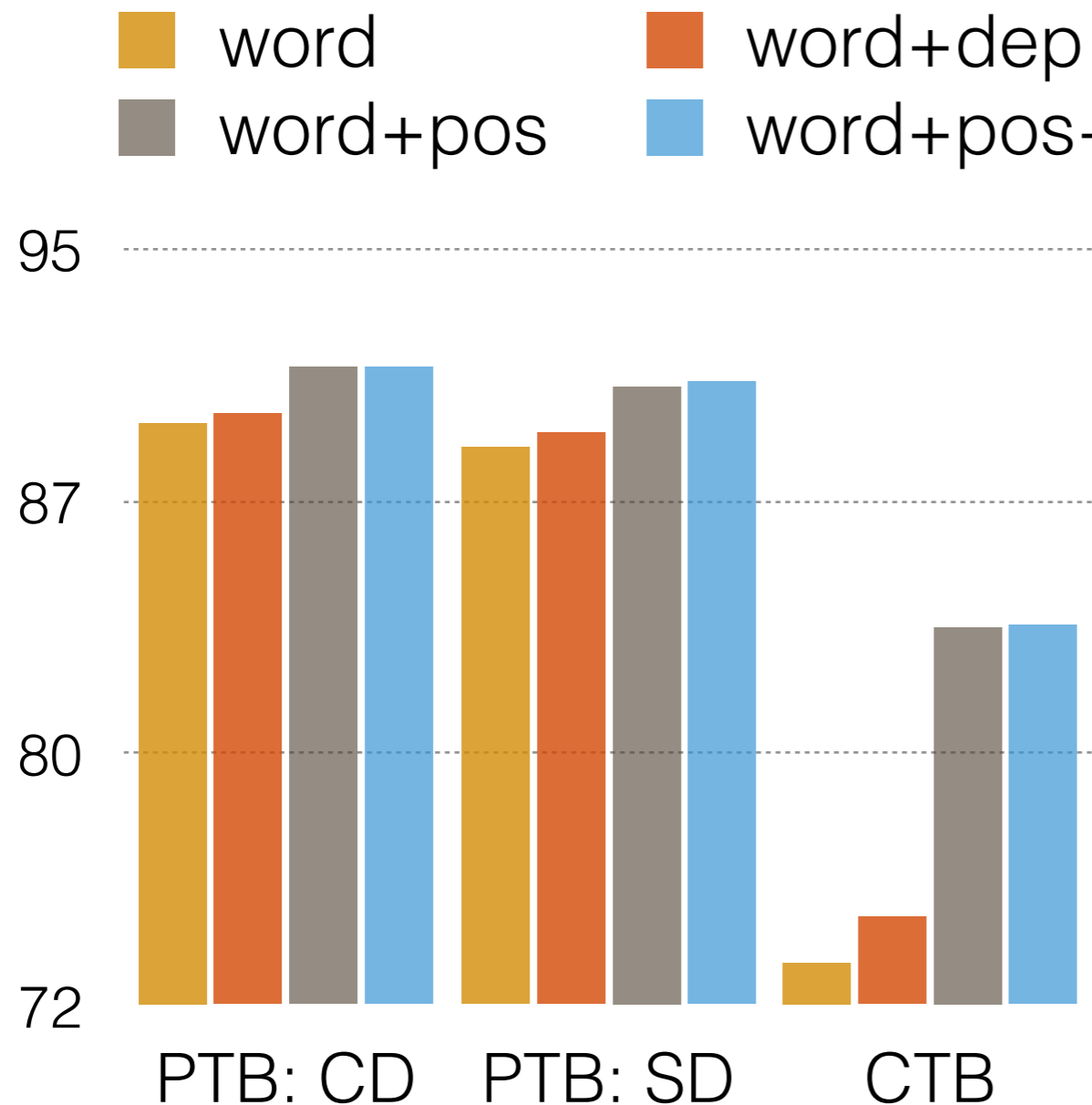


# Pre-trained Word Vectors





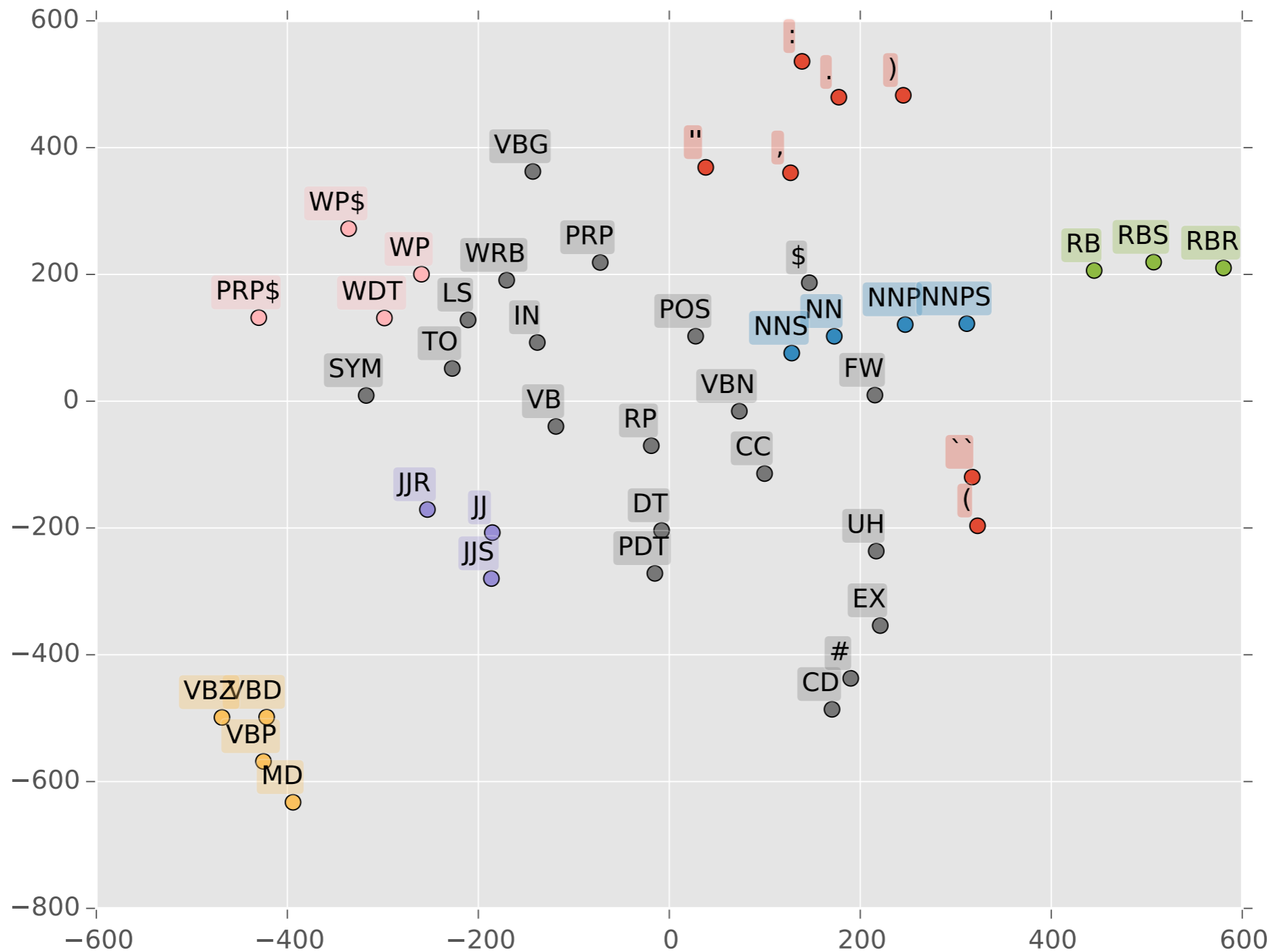
# POS / Dependency Embeddings



- POS embeddings help a lot:
  - PTB: +1.7%
  - CTB: +10.2%
- Slight gain from dependency embeddings.

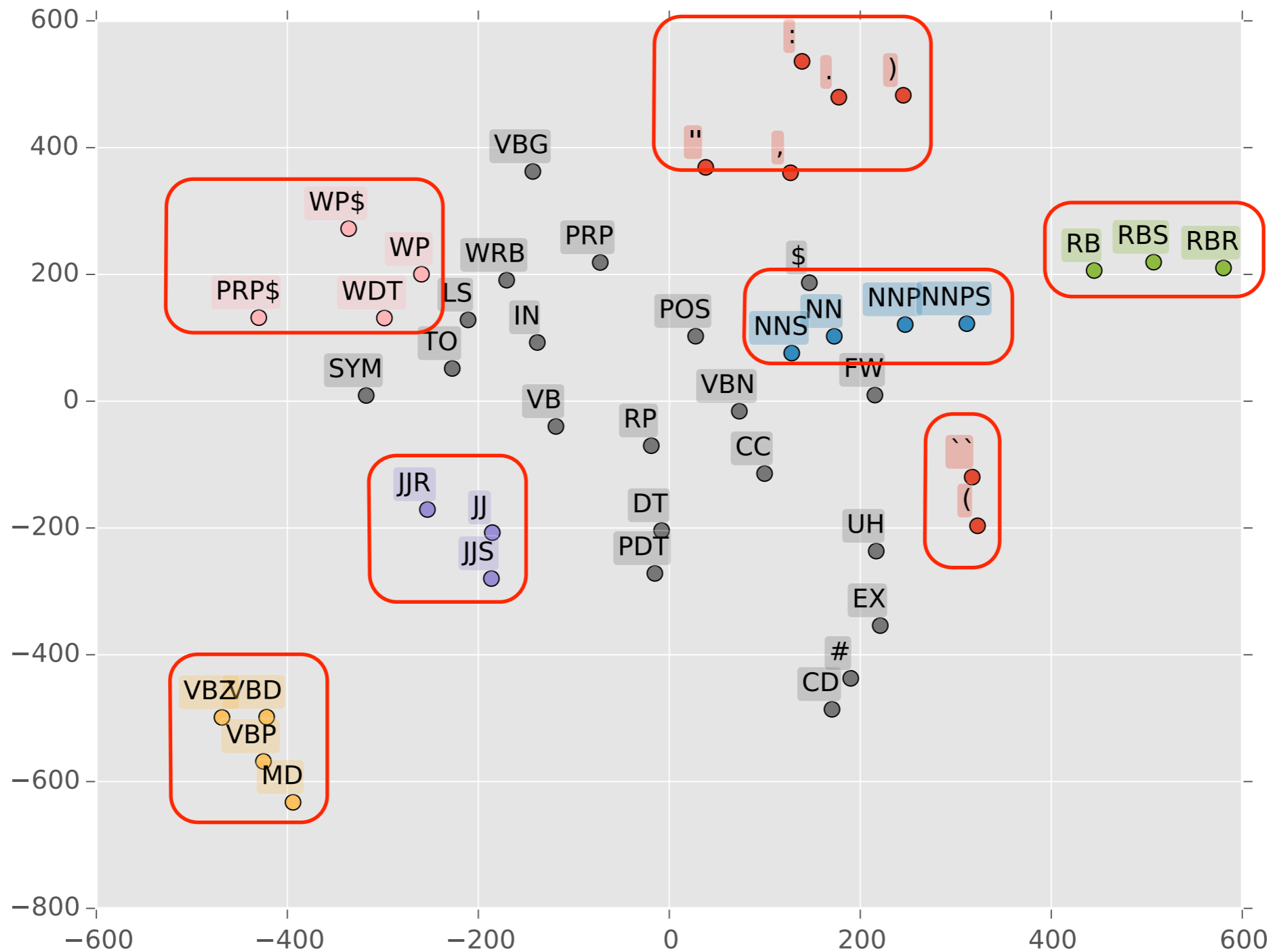


# POS Embeddings



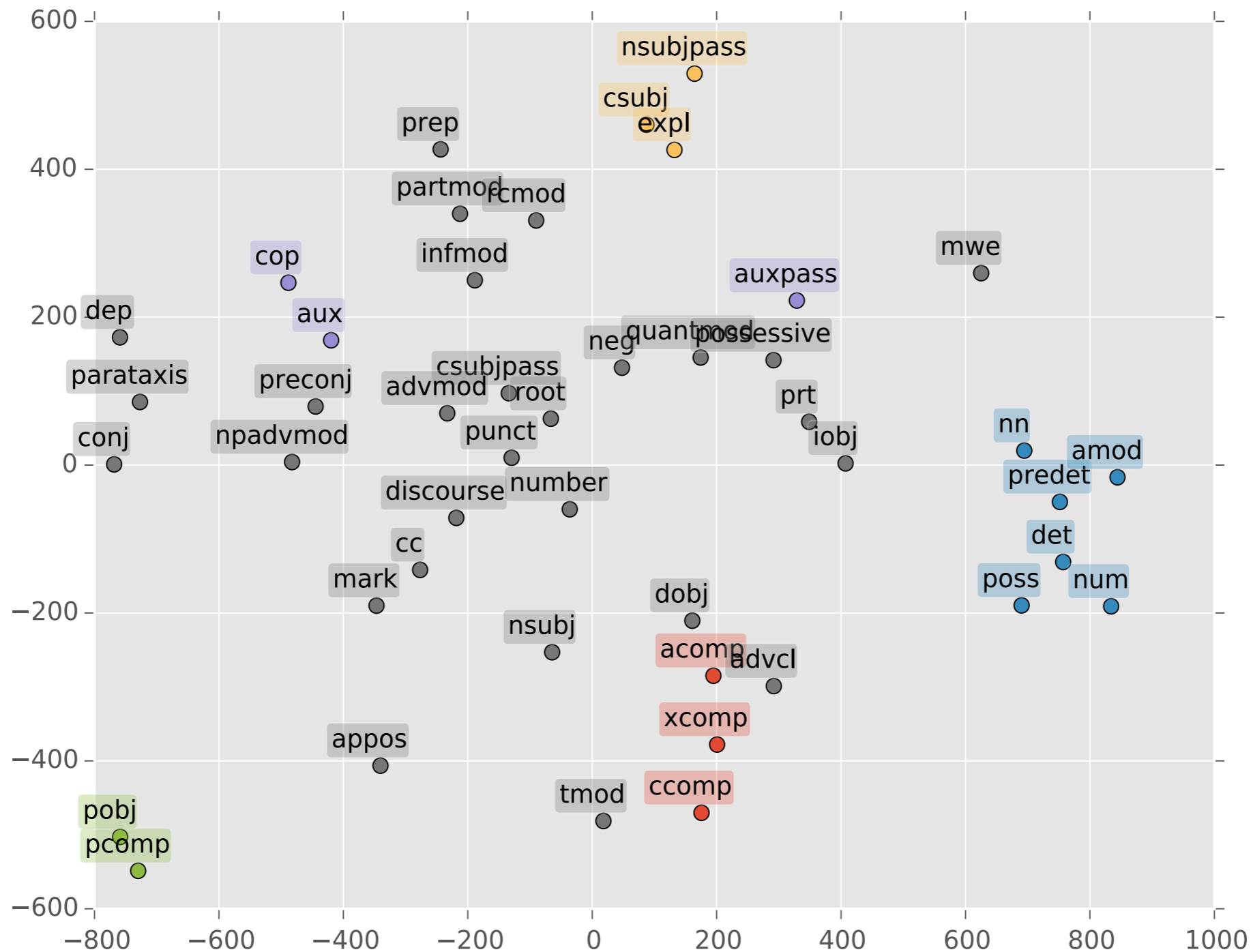


# POS Embeddings



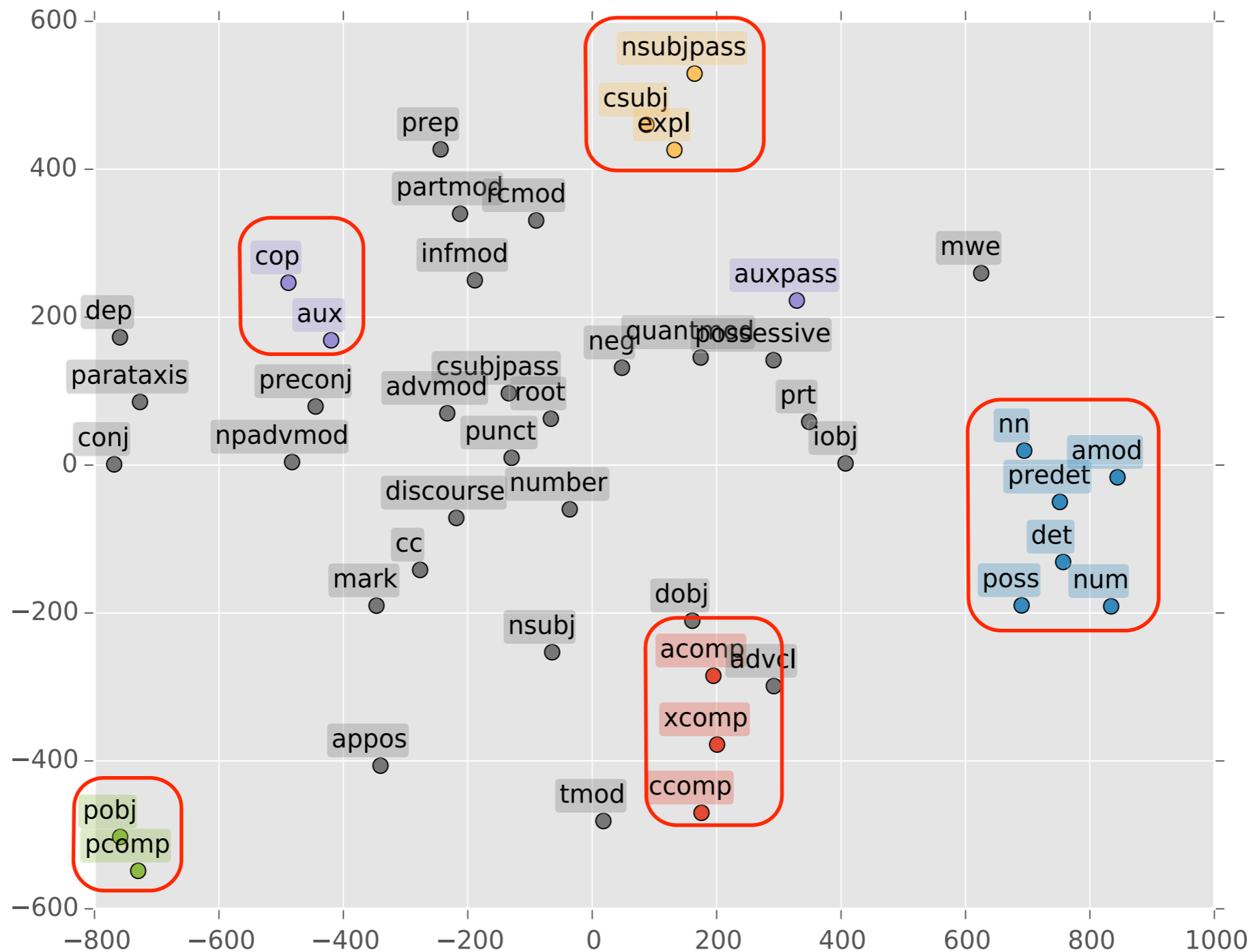


# Dependency Embeddings





# Dependency Embeddings





# Conclusion

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- **Summary**

- Presented a state-of-the-art greedy parser using NNs.
- Excellent accuracy and speed.
- Introduced POS / dep. embeddings, and cube activation function.

- **Future work**

- Beam search
- Dynamic oracle
- Richer features (lemma, morph, distance, etc).
- Better representation for modeling interactions





# Thanks

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- Code is available!
- Try fast dependency parsing in **Stanford CoreNLP v3.5.0**,
  - annotators: tokenize,ssplit,pos,**depparse**
- Or check out full training / testing code at:
  - <http://nlp.stanford.edu/software/nndep.shtml>
- Contact: danqi@cs.stanford.edu