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## 3.2 BINARY SEARCH TREES

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- *BSTs*
- *iteration*
- *ordered operations*



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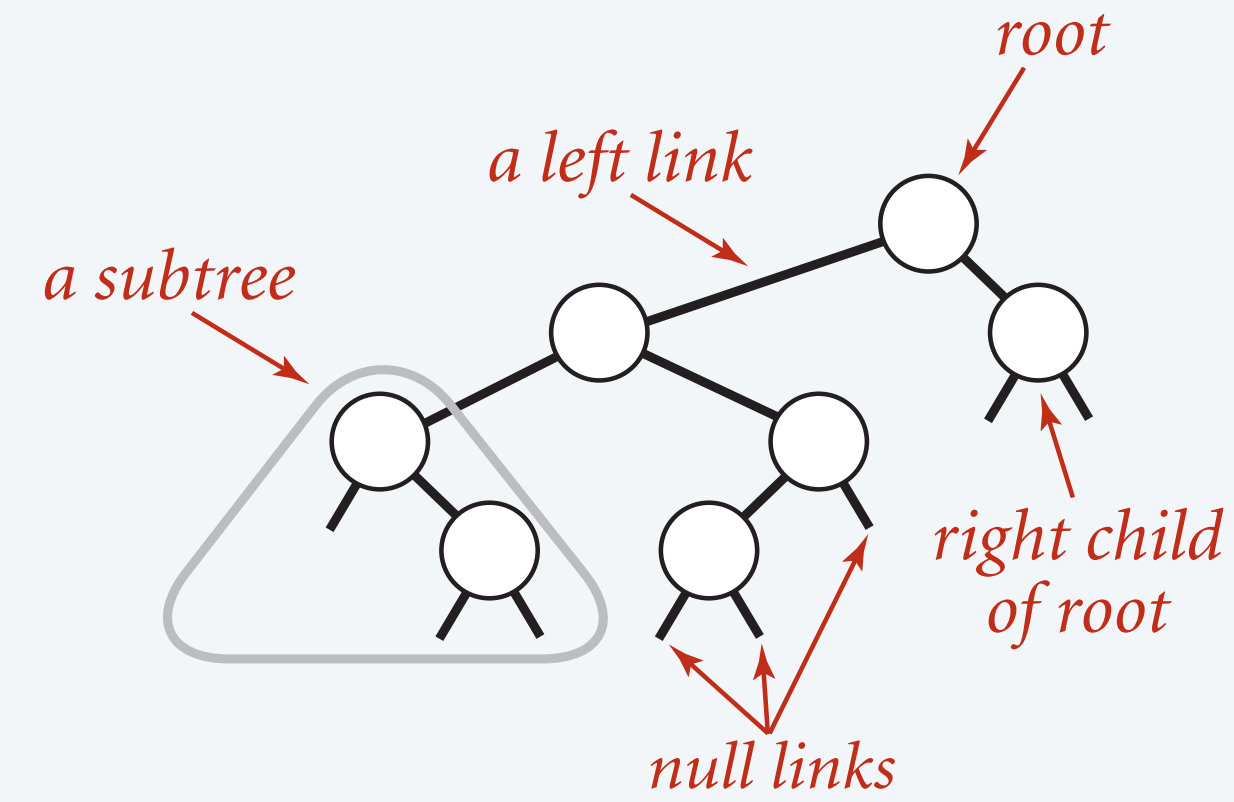
- *BSTs*
- *iteration*
- *ordered operations*

# Binary search trees

**Definition.** A BST is a **binary tree** in **symmetric order**.

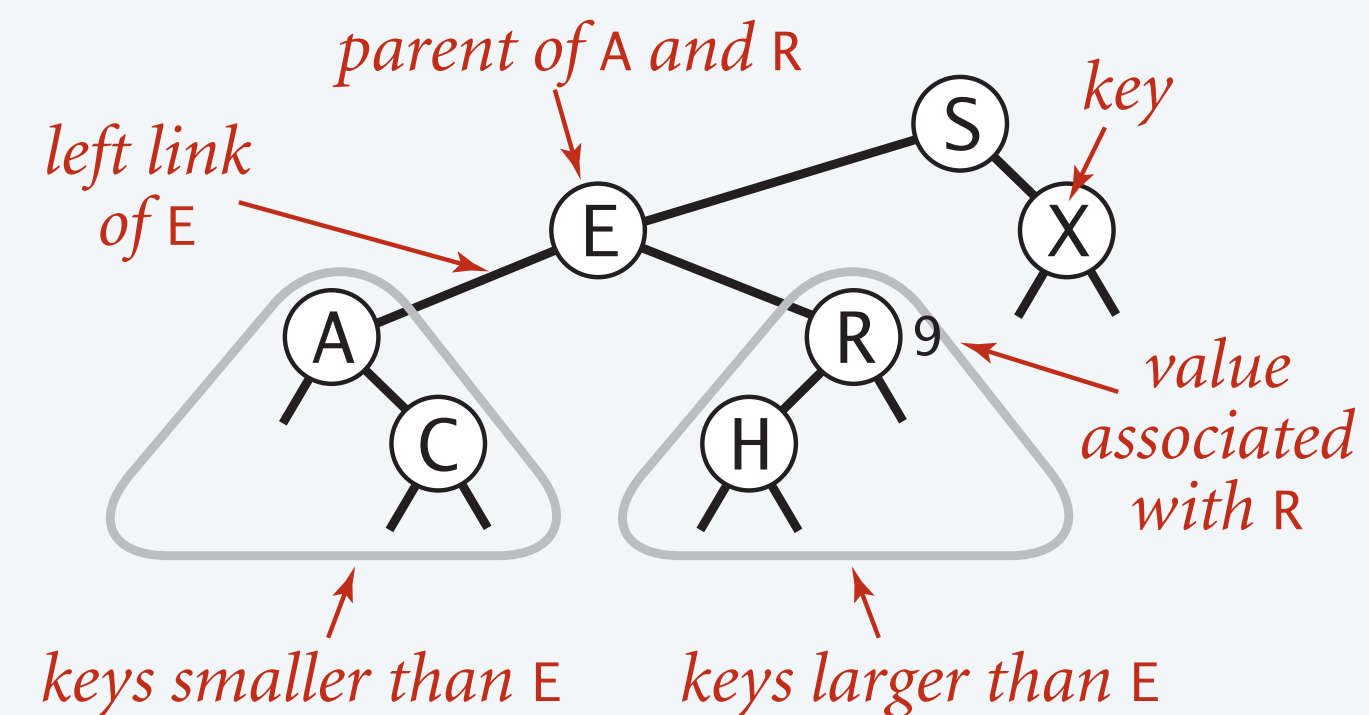
A binary tree is either:

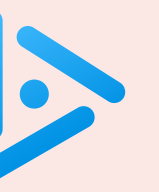
- Empty.
- A node with links to two disjoint binary trees—the left subtree and the right subtree.



**Symmetric order.** Each node has a key that is:

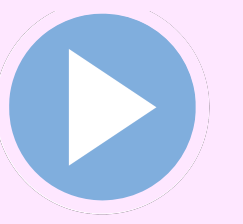
- Strictly larger than all keys in its left subtree.
- Strictly smaller than all keys in its right subtree.
- [Duplicate keys not permitted.]





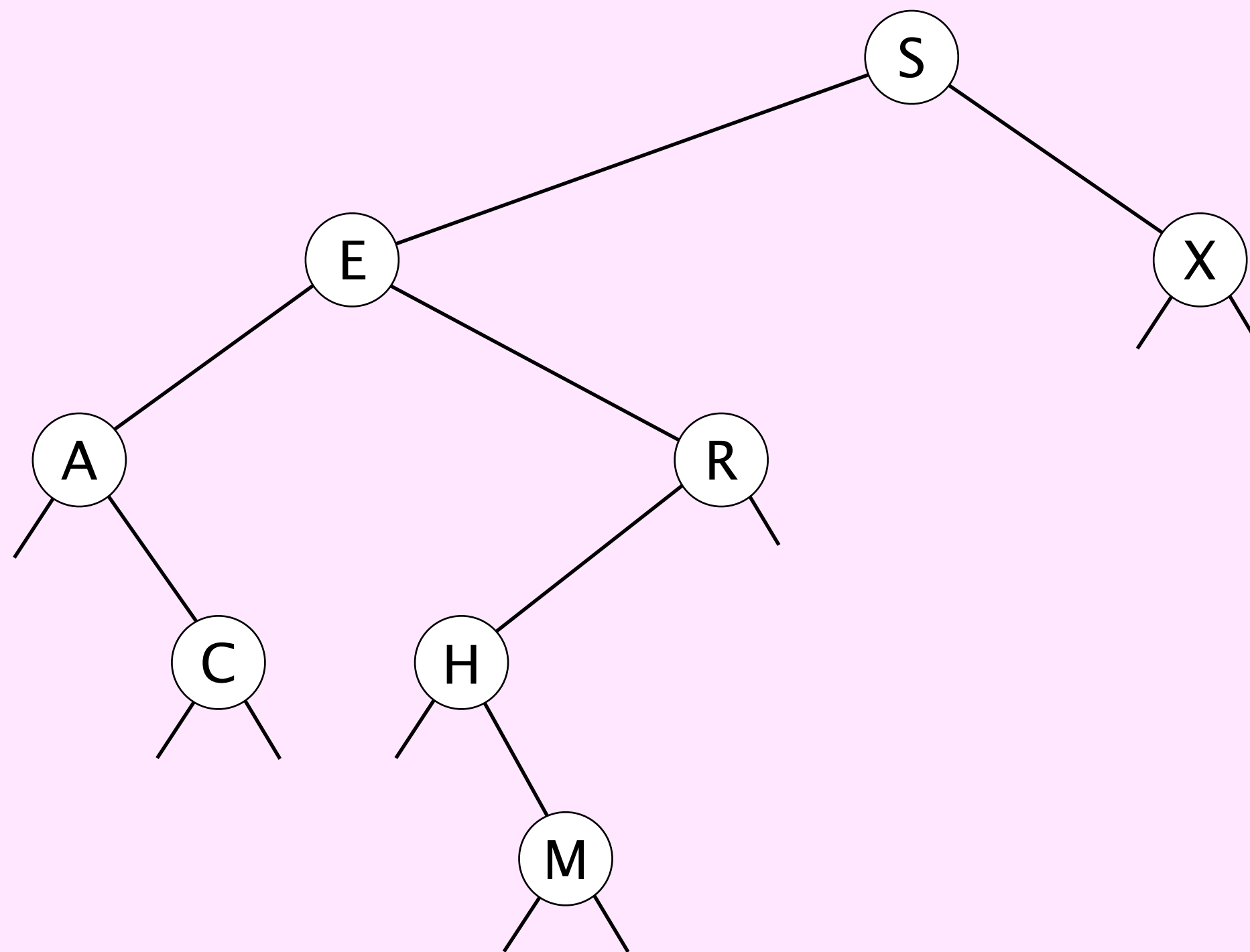
Which of the following properties hold?

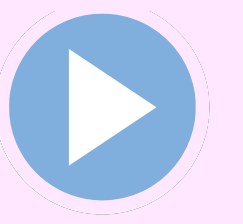
- A. If a binary tree is max-heap ordered, then it is symmetrically ordered.
- B. If a binary tree is symmetrically ordered, then it is max-heap ordered.
- C. Both A and B.
- D. Neither A nor B.



**Search.** If less, go left; if greater, go right; if equal, search hit.

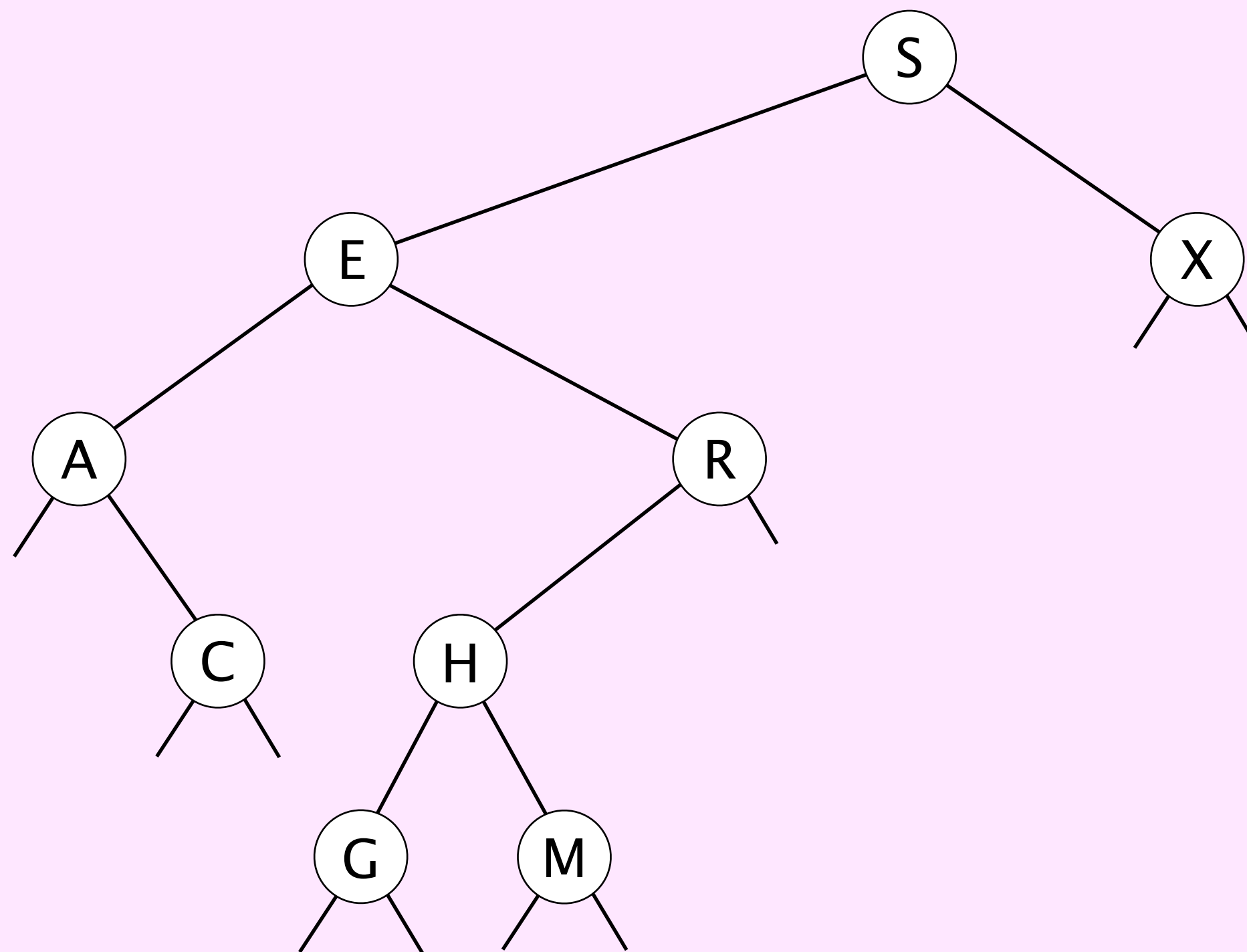
**successful search for H**





**Insert.** If less, go left; if greater, go right; if `null`, insert.

**insert G**



# BST representation in Java

Java representation. A BST holds a reference to a root **Node**.

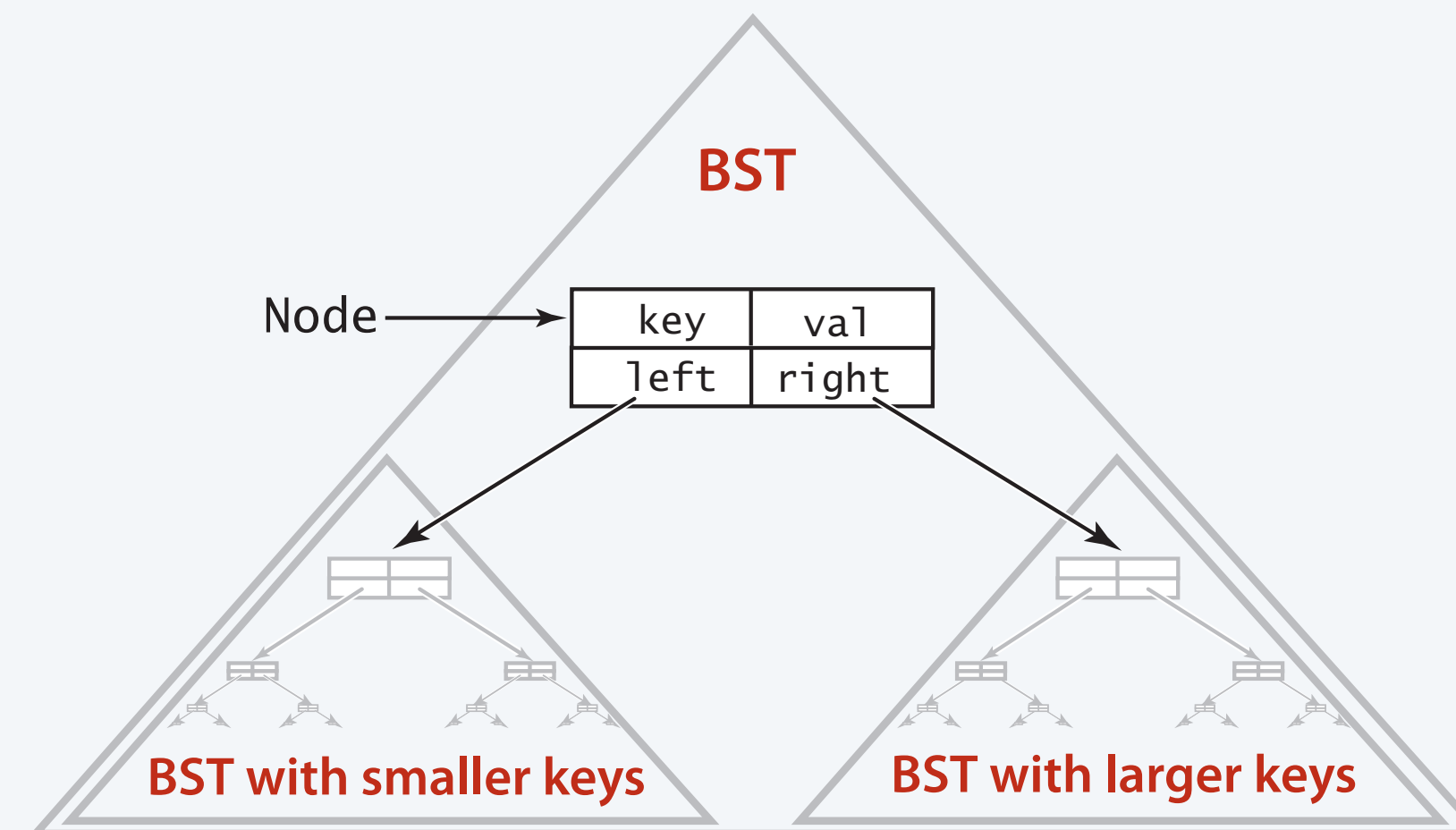
A **Node** is composed of four fields:

- A **Key** and a **Value**.
- A reference to the left and right subtree.

*smaller keys*      *larger keys*

```
private class Node {  
    private Key key;  
    private Value val;  
    private Node left, right;  
  
    public Node(Key key, Value val) {  
        this.key = key;  
        this.val = val;  
    }  
}
```

Key and Value are generic types; Key is Comparable




binary search tree



# BST implementation (skeleton)

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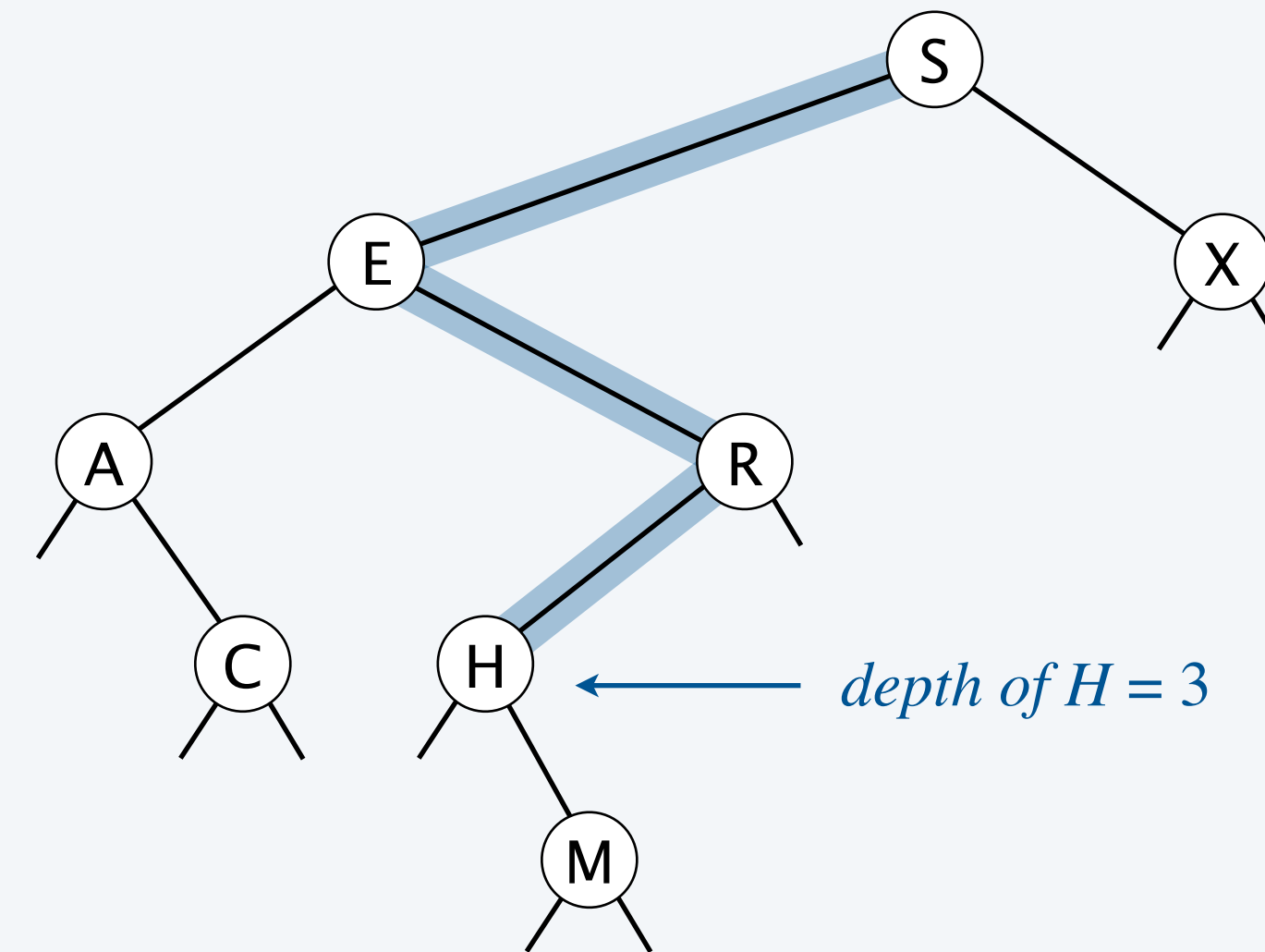
```
public class BST<Key extends Comparable<Key>, Value> {  
  
    private Node root;  ← root of BST  
  
    private class Node  
    { /* see previous slide */ }  
  
    public void put(Key key, Value val)  
    { /* see slide in this section */ }  
  
    public Value get(Key key)  
    { /* see next slide */ }  
  
    public Iterable<Key> keys()  
    { /* see slides in next section */ }  
  
    public void delete(Key key)  
    { /* see textbook */ }  
  
}
```



# BST search: Java implementation

**Get.** Return value corresponding to given key, or `null` if no such key.

```
public Value get(Key key) {  
    Node x = root;  
    while (x != null) {  
        int cmp = key.compareTo(x.key);  
        if (cmp < 0) x = x.left;  
        else if (cmp > 0) x = x.right;  
        else return x.val;  
    }  
    return null;  
}
```



**Cost.** Number of compares = 1 + depth of deepest node reached.

# BST insert

**Put.** Associate value with key.

- Search for key in BST.
- Case 1: Key in BST  $\implies$  reset value.
- Case 2: Key not in BST  $\implies$  add new node.

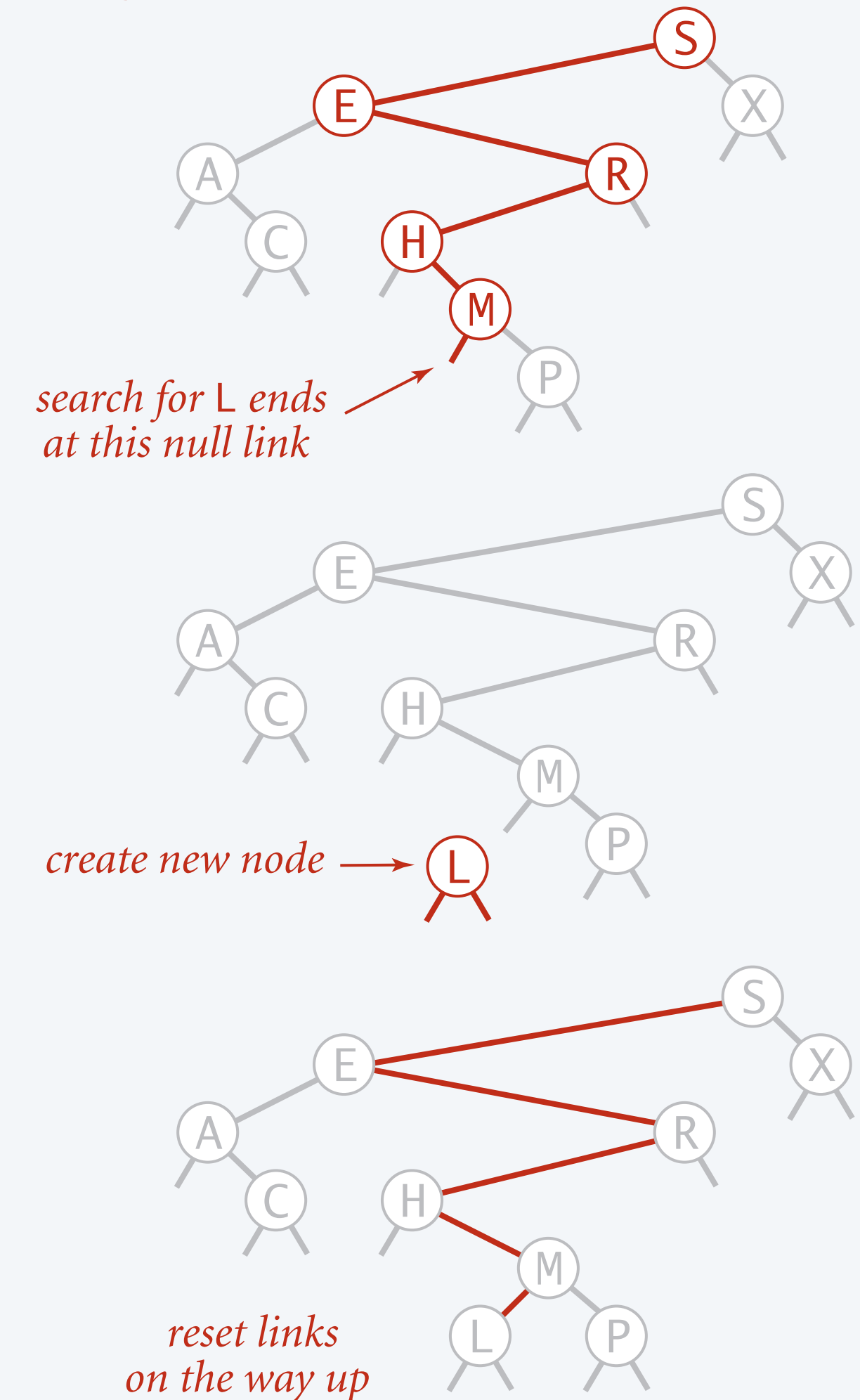
```
public void put(Key key, Value val) {  
    root = put(root, key, val);  
}
```

```
private Node put(Node x, Key key, Value val) {  
    if (x == null) return new Node(key, val);  
    int cmp = key.compareTo(x.key);  
    if (cmp < 0) x.left = put(x.left, key, val);  
    else if (cmp > 0) x.right = put(x.right, key, val);  
    else x.val = val;  
    return x;  
}
```



**Warning: concise but tricky code!**

inserting L



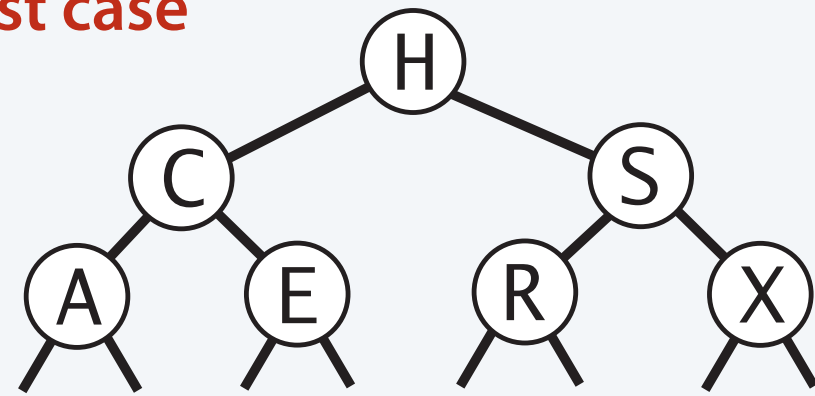
**Cost.** Number of compares = 1 + depth of deepest node reached.

insertion into a BST

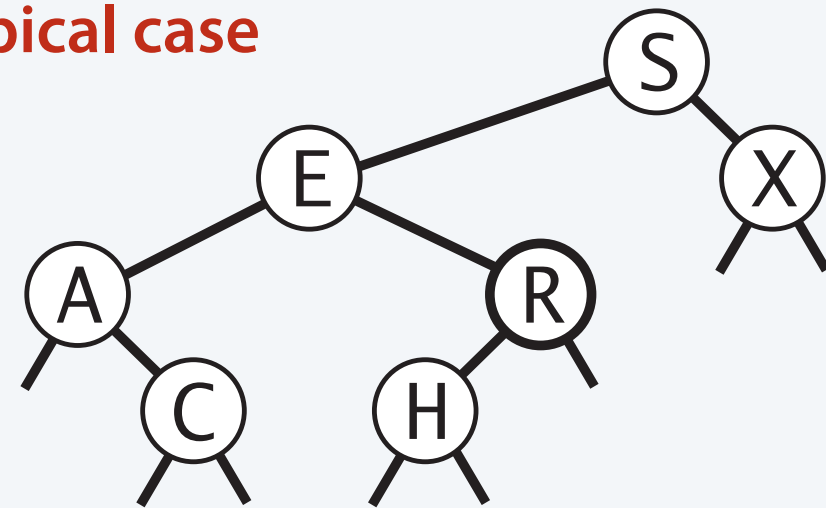
# Tree shape

- Many BSTs correspond to same set of keys.
- Number of compares for search/insert = 1 + depth of deepest node reached.

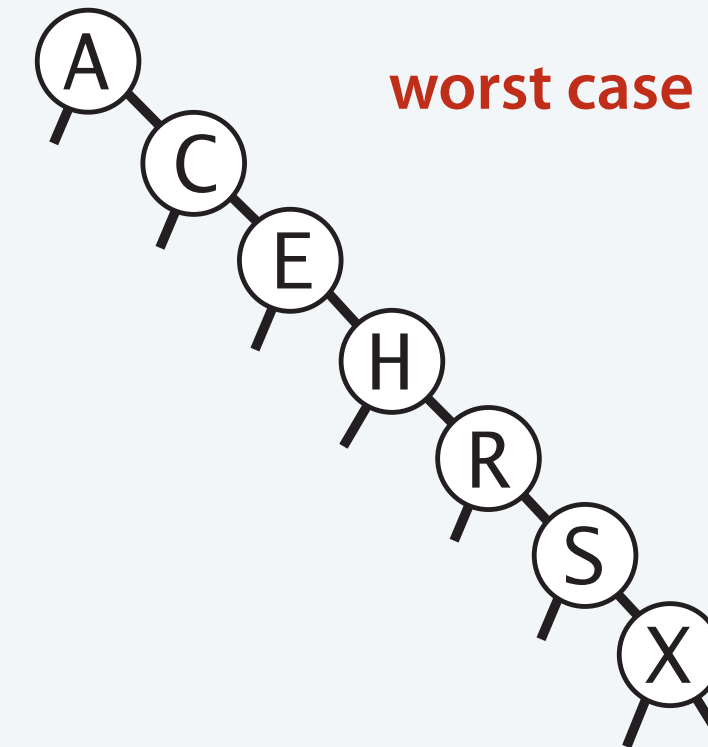
best case



typical case



worst case



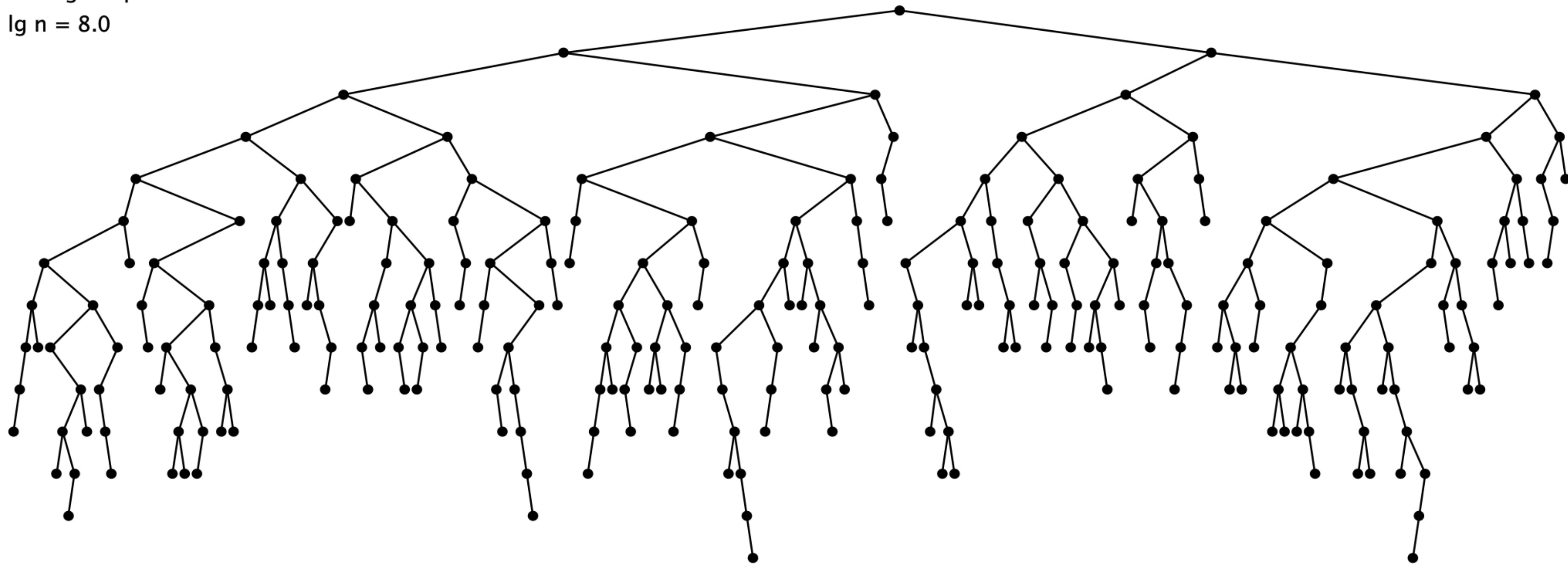
*height between  $\log_2 n$  and  $n - 1$*

Bottom line. Tree shape depends on order of insertion.

# BST insertion: random order visualization

Ex. Insert 255 keys in random order.

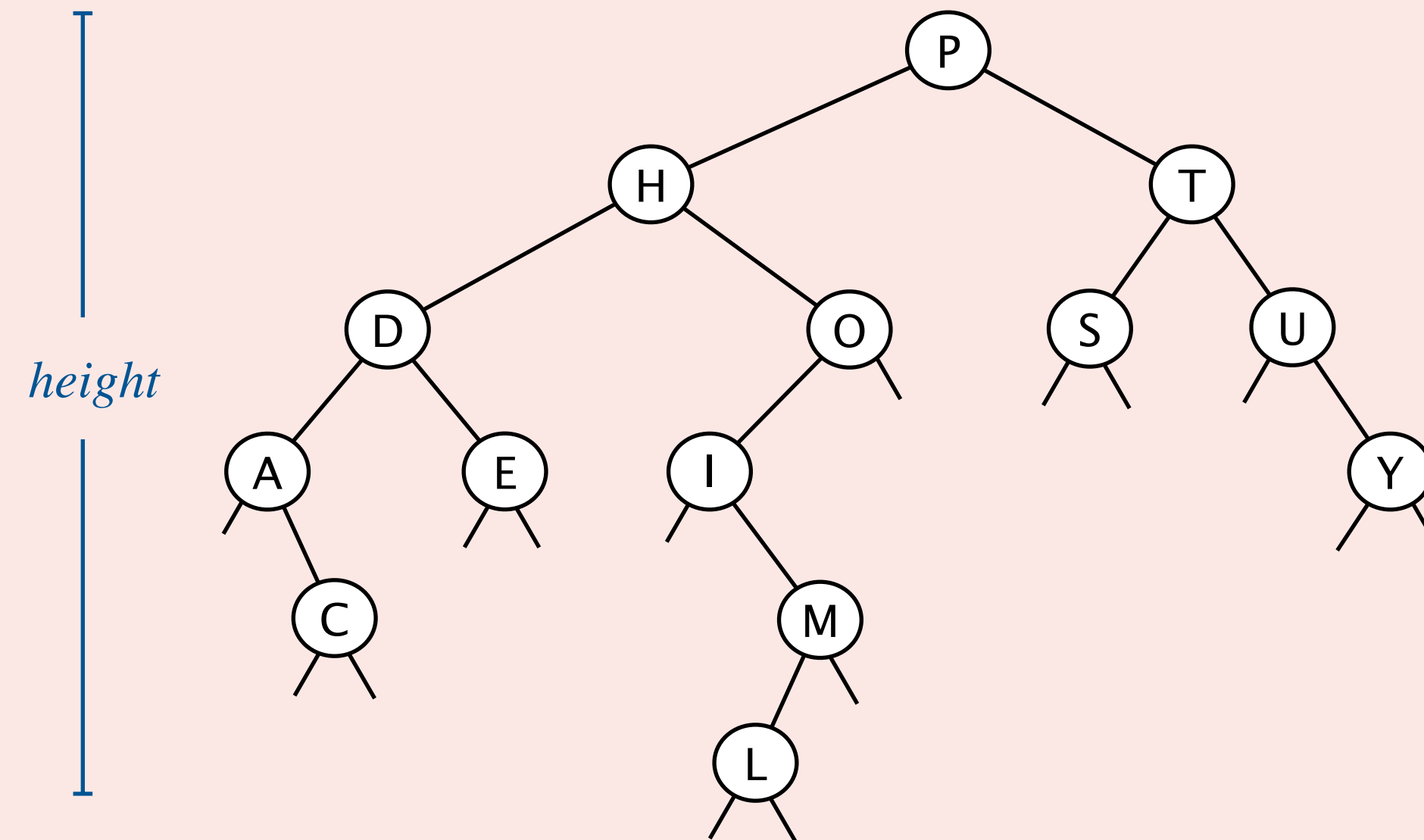
$n = 255$   
height = 13  
average depth = 7.3  
 $\lg n = 8.0$





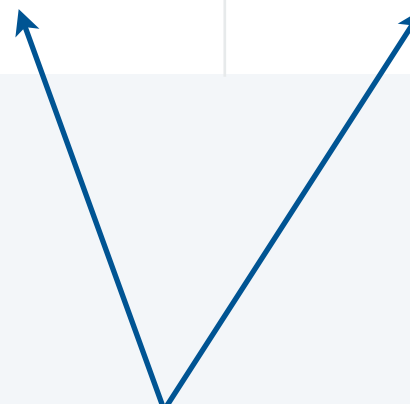
Suppose that you insert  $n$  distinct keys in uniformly random order into a BST.  
What is the **expected height** of the resulting BST?

- A.  $\sim \log_2 n$
- B.  $\sim 2 \ln n$
- C.  $\sim 4.31107 \ln n$
- D.  $\sim \frac{1}{2} n$
- E.  $\sim n$



# ST implementations: performance summary

implementation	worst case		typical case		operations on keys
	search	insert	search hit	insert	
sequential search (unordered list)	$n$	$n$	$n$	$n$	<code>equals()</code>
binary search (ordered array)	$\log n$	$n$	$\log n$	$n$	<code>compareTo()</code>
BST	$n$	$n$	$\log n$	$\log n$	<code>compareTo()</code>



*Why not shuffle to ensure  
a (probabilistic) guarantee  
of  $O(\log n)$  time à la quicksort ?*



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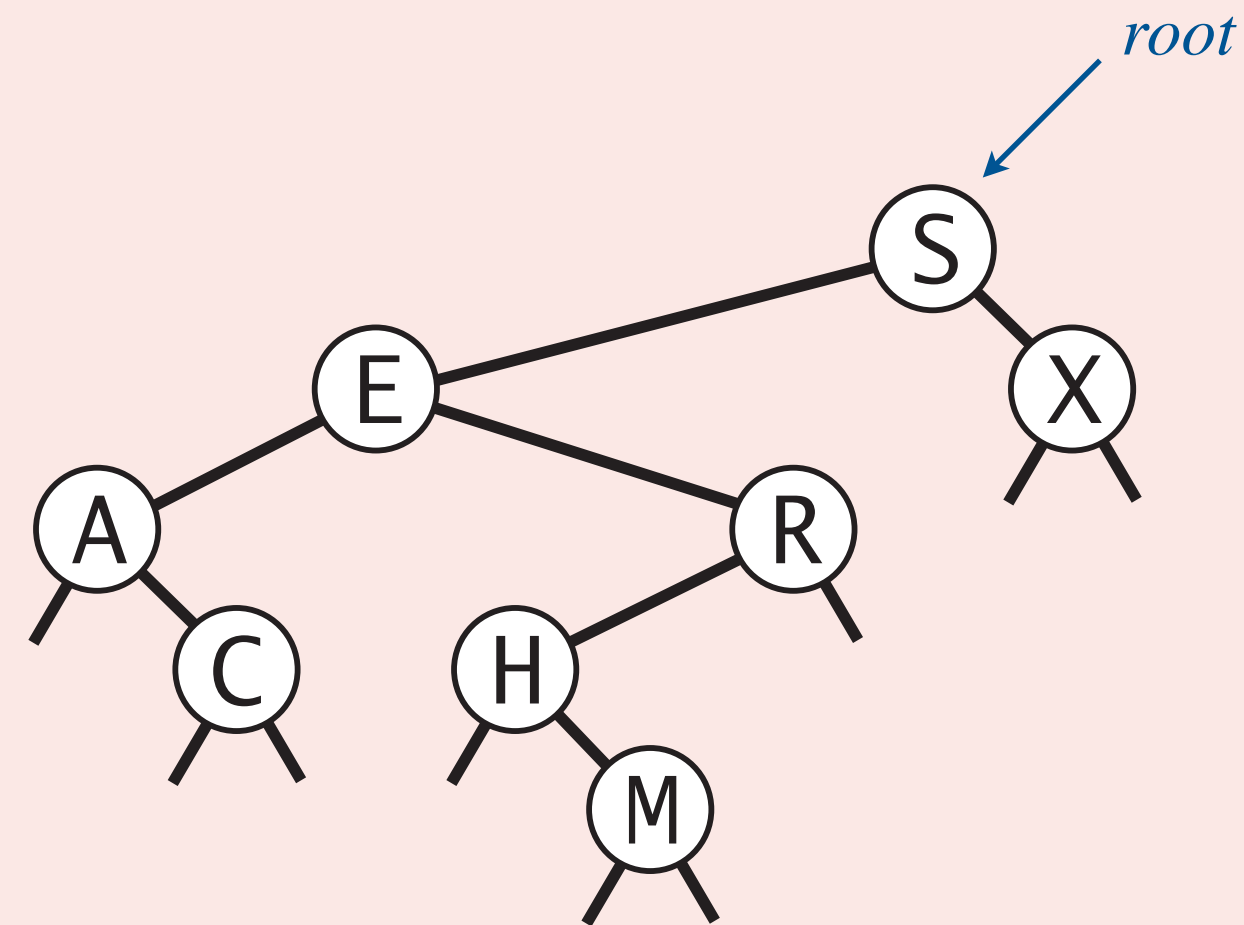




In which order does `traverse(root)` print the keys in the BST?

```
private void traverse(Node x) {  
    if (x == null) return;  
    traverse(x.left);  
    StdOut.println(x.key);  
    traverse(x.right);  
}
```

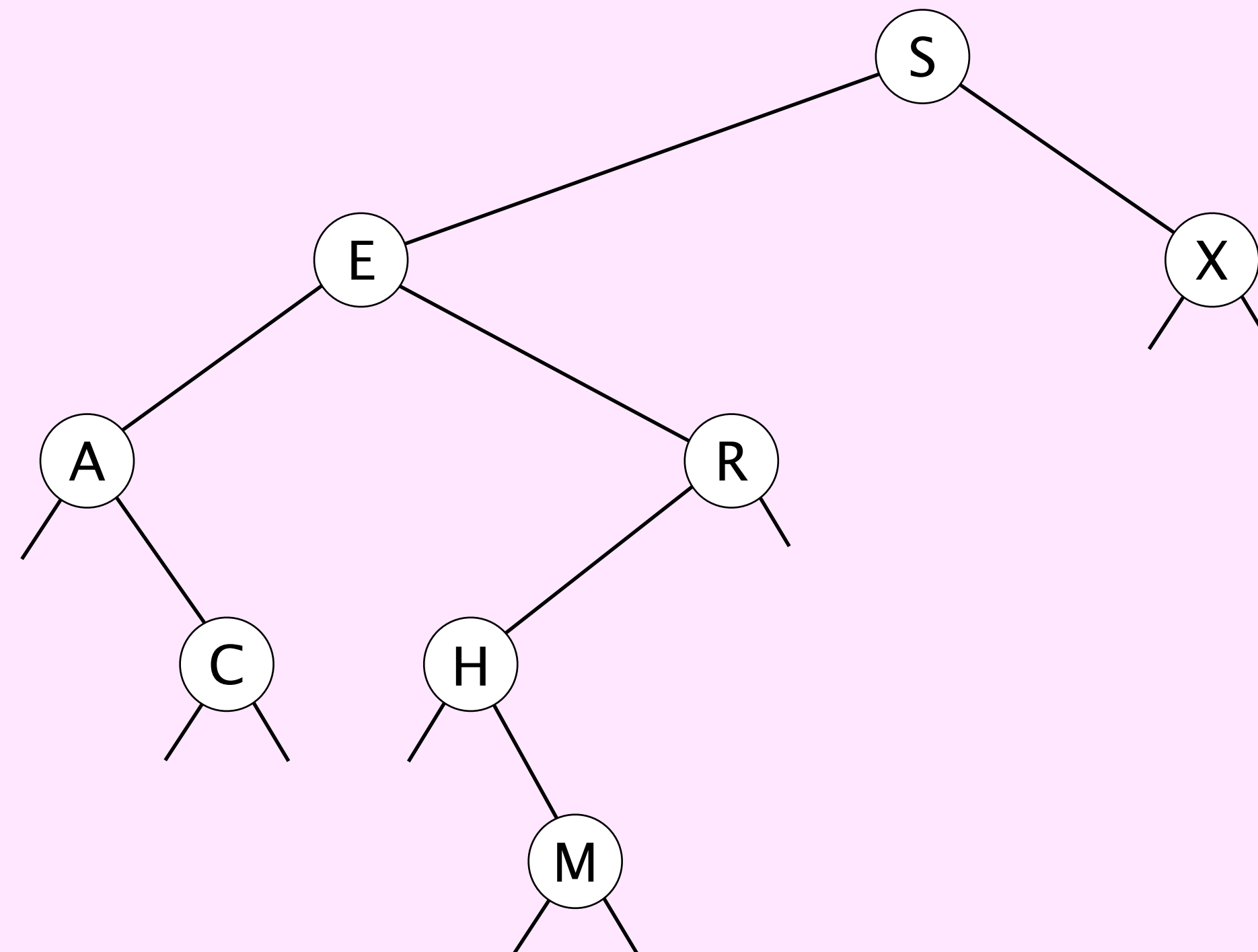
- A. A C E H M R S X
- B. S E A C R H M X
- C. C A M H R E X S
- D. S E X A R C H M



# Inorder traversal



```
inorder(S)
  inorder(E)
    inorder(A)
      print A
      inorder(C)
        print C
        done C
      done A
    print E
    inorder(R)
      inorder(H)
        print H
        inorder(M)
          print M
          done M
        done H
      print R
      done R
    done E
  print S
  inorder(X)
    print X
    done X
  done S
```



output: **A C E H M R S X**

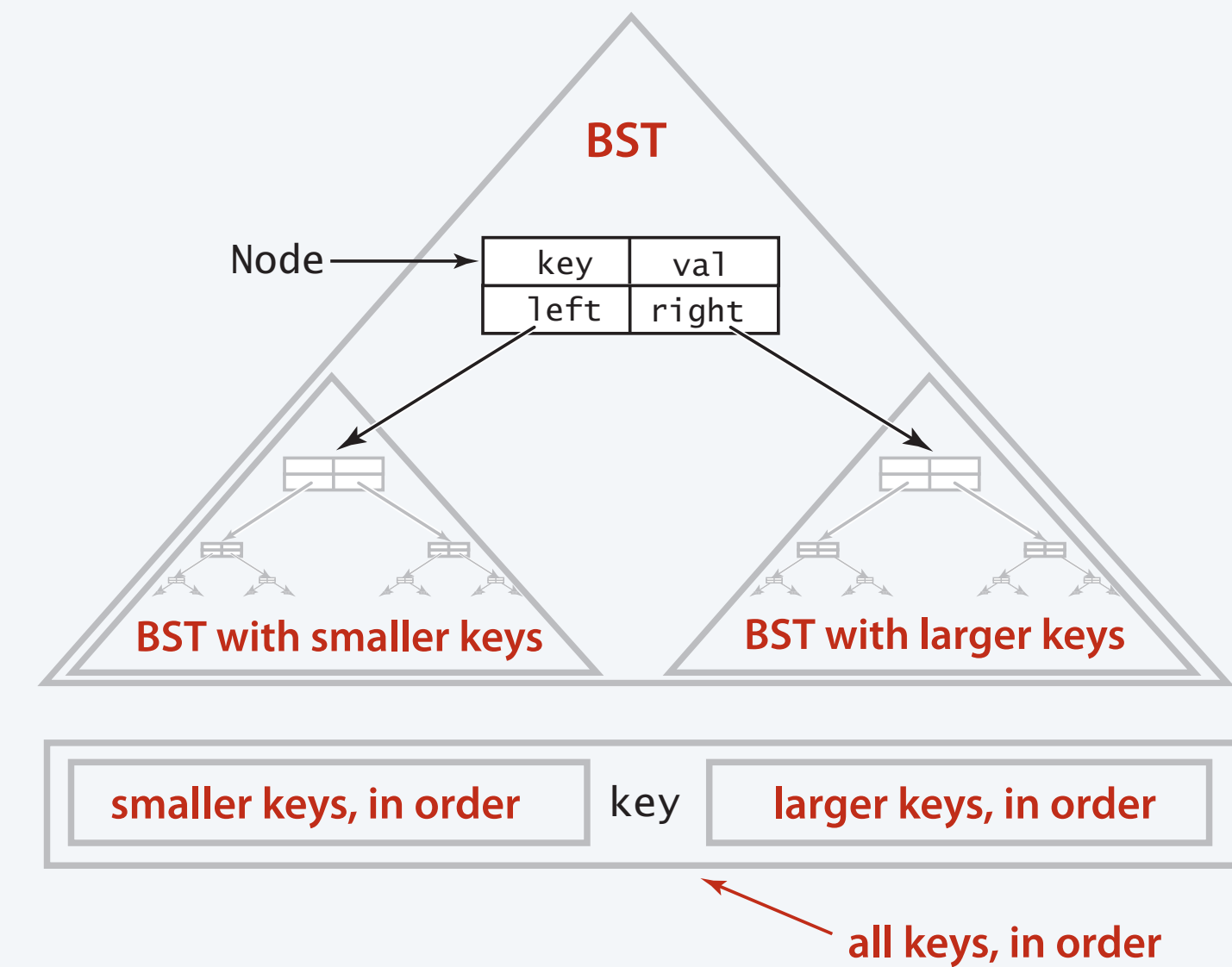
# Inorder traversal

- Traverse left subtree.
- Enqueue key.
- Traverse right subtree.

*add items to a collection that is Iterable  
and return that collection*

```
public Iterable<Key> keys() {  
    Queue<Key> queue = new Queue<Key>();  
    inorder(root, queue);  
    return queue;  
}
```

```
private void inorder(Node x, Queue<Key> queue) {  
    if (x == null) return;  
    inorder(x.left, queue);  
    queue.enqueue(x.key);  
    inorder(x.right, queue);  
}
```



**Property.** Inorder traversal of a BST yields keys in ascending order.

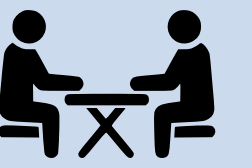
## Inorder traversal: running time



**Property.** Inorder traversal of a binary tree with  $n$  nodes takes  $\Theta(n)$  time (and no compares).

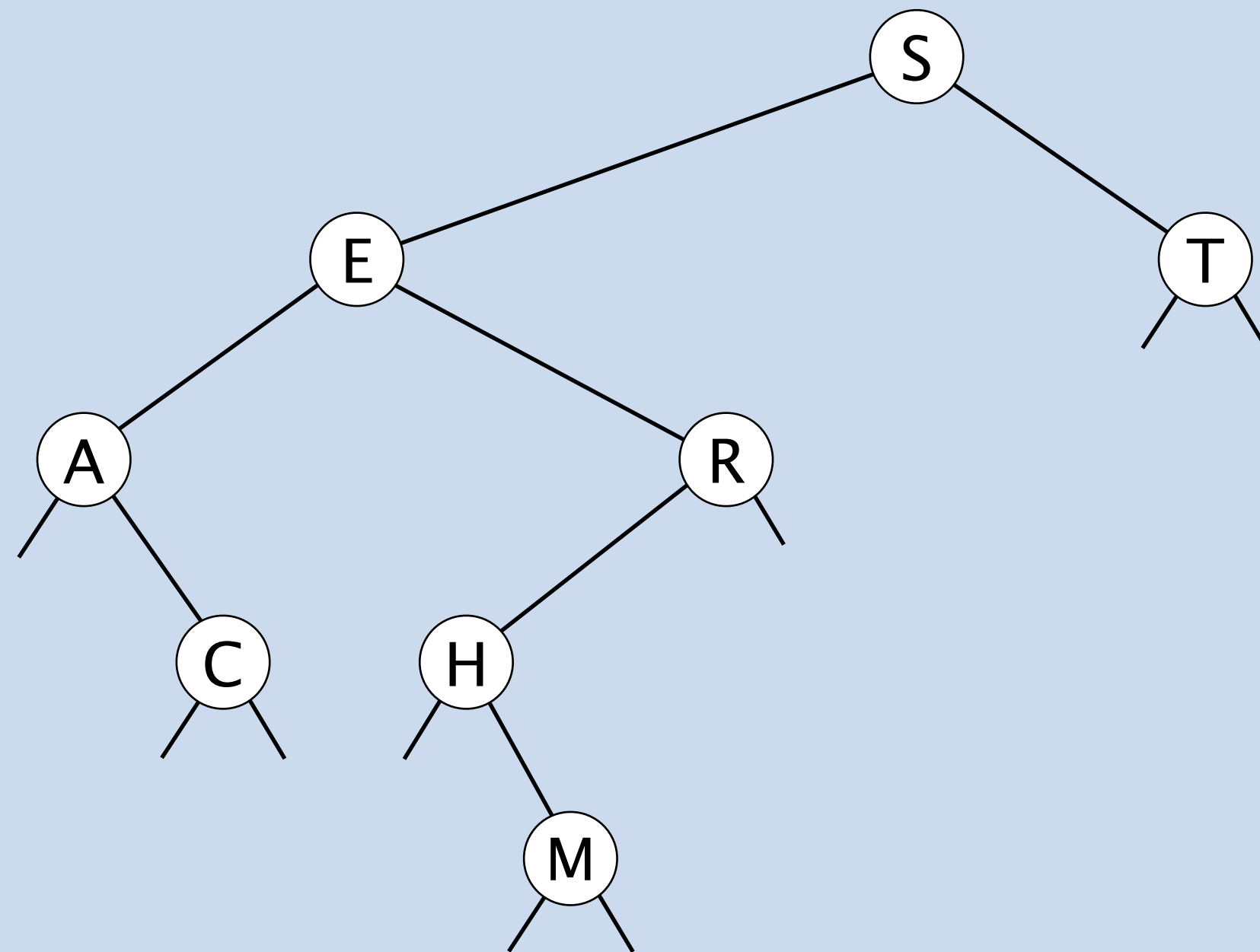
**Pf.** It takes  $\Theta(1)$  time per node in BST.



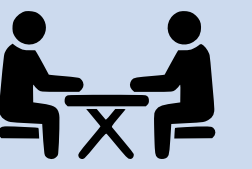


## Level-order traversal of a binary tree.

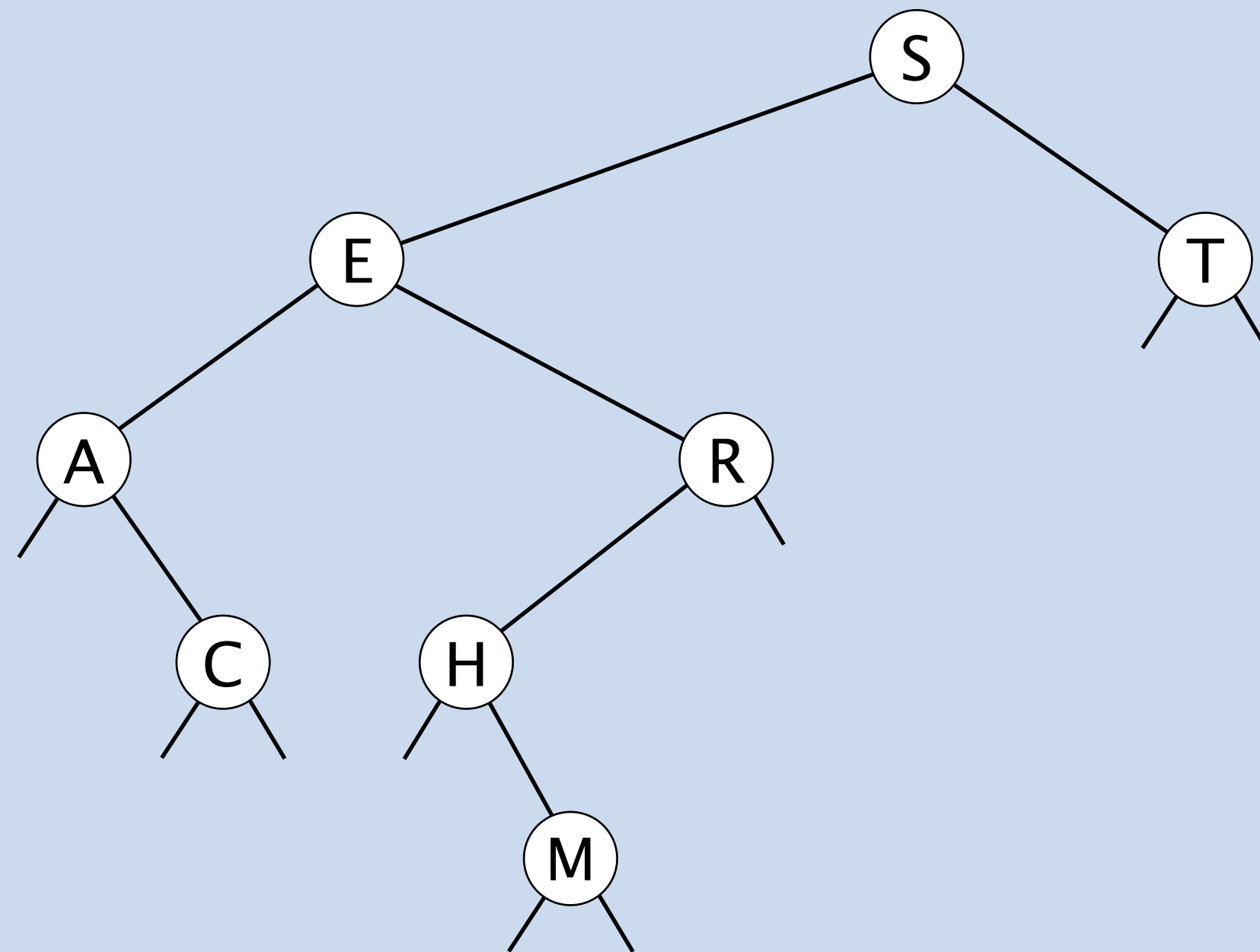
- Process root.
- Process children of root, from left to right.
- Process grandchildren of root, from left to right.
- ...



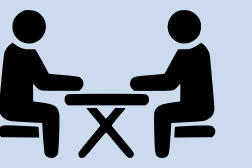
level-order traversal: **S E T A R C H M**



Q1. How to compute level-order traversal of a binary tree in  $\Theta(n)$  time?



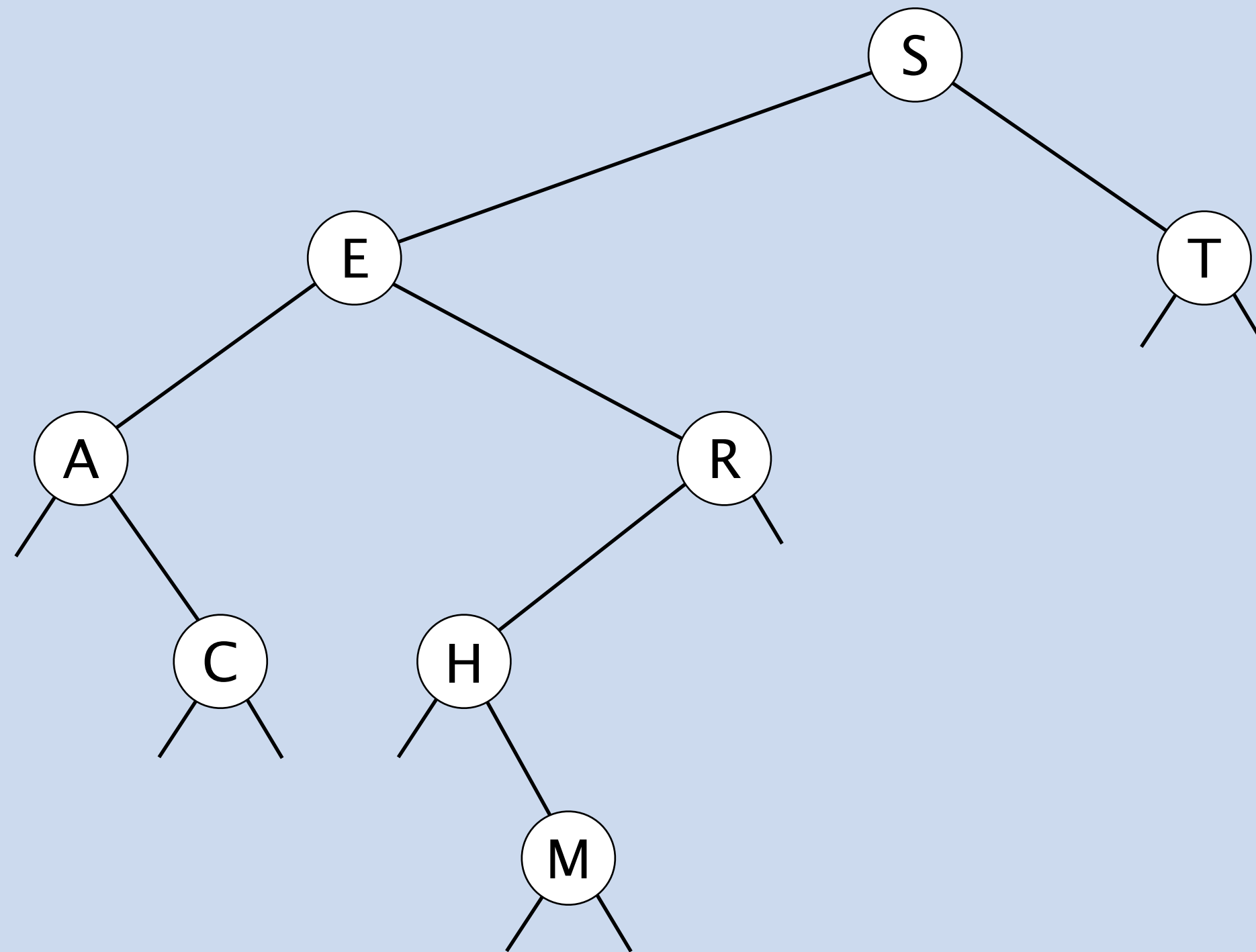
level-order traversal: **S E T A R C H M**



Q2. Given the level-order traversal of a BST, how to (uniquely) reconstruct?

Ex. ~~S~~ ~~E~~ ~~T~~ ~~A~~ ~~R~~ ~~C~~ ~~H~~ ~~M~~

*needed for PrairieLearn quizzes*







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# Minimum and maximum

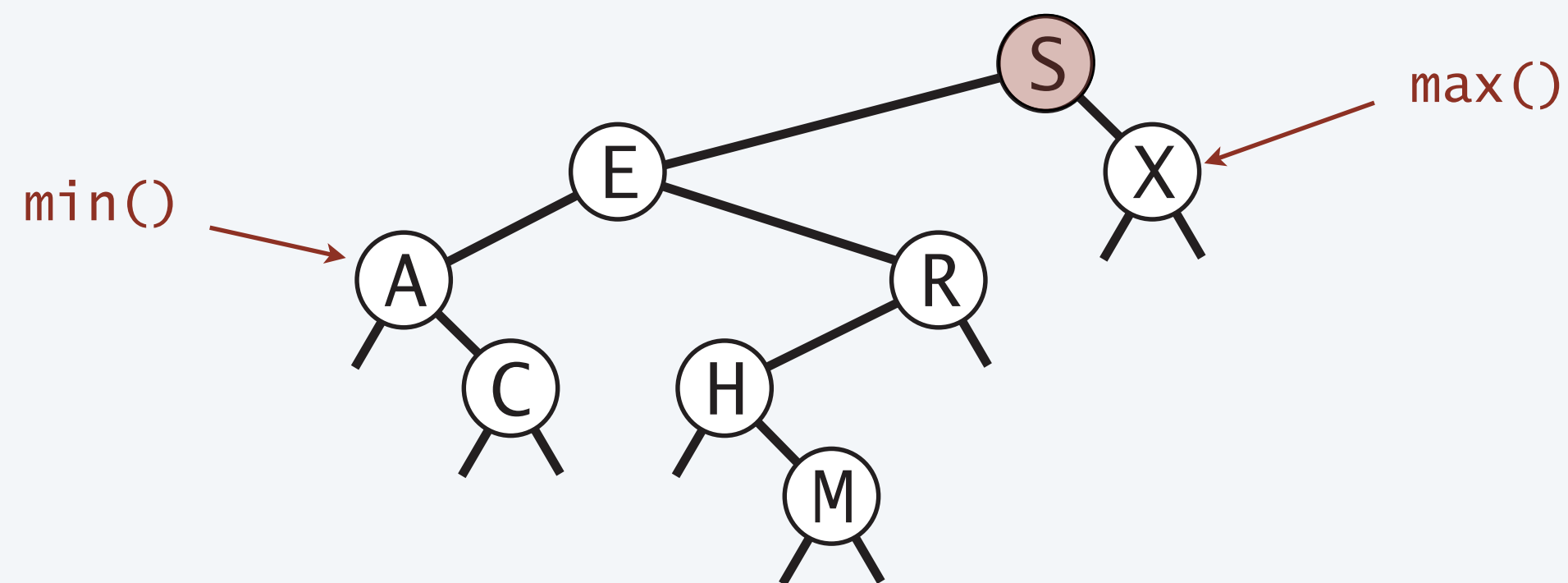
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**Minimum.** Smallest key in BST.

**Maximum.** Largest key in BST.

**Q.** How to find the min / max?

**A.** Go down left / right spine. ← *running time proportional to  
depth of node in BST  
(but 0 compares)*

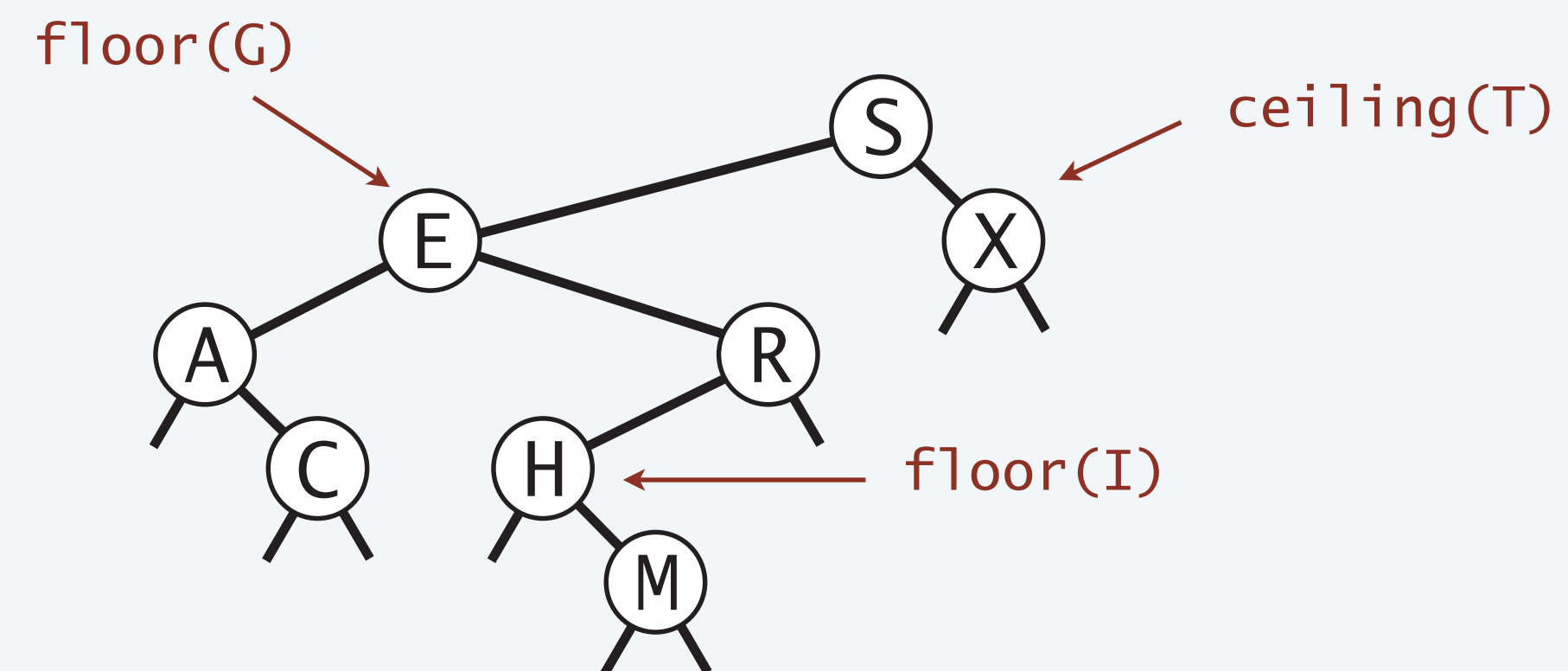


# Floor and ceiling

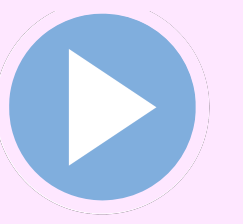
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**Floor.** Largest key in BST  $\leq$  query key.

**Ceiling.** Smallest key in BST  $\geq$  query key.



# Computing the floor

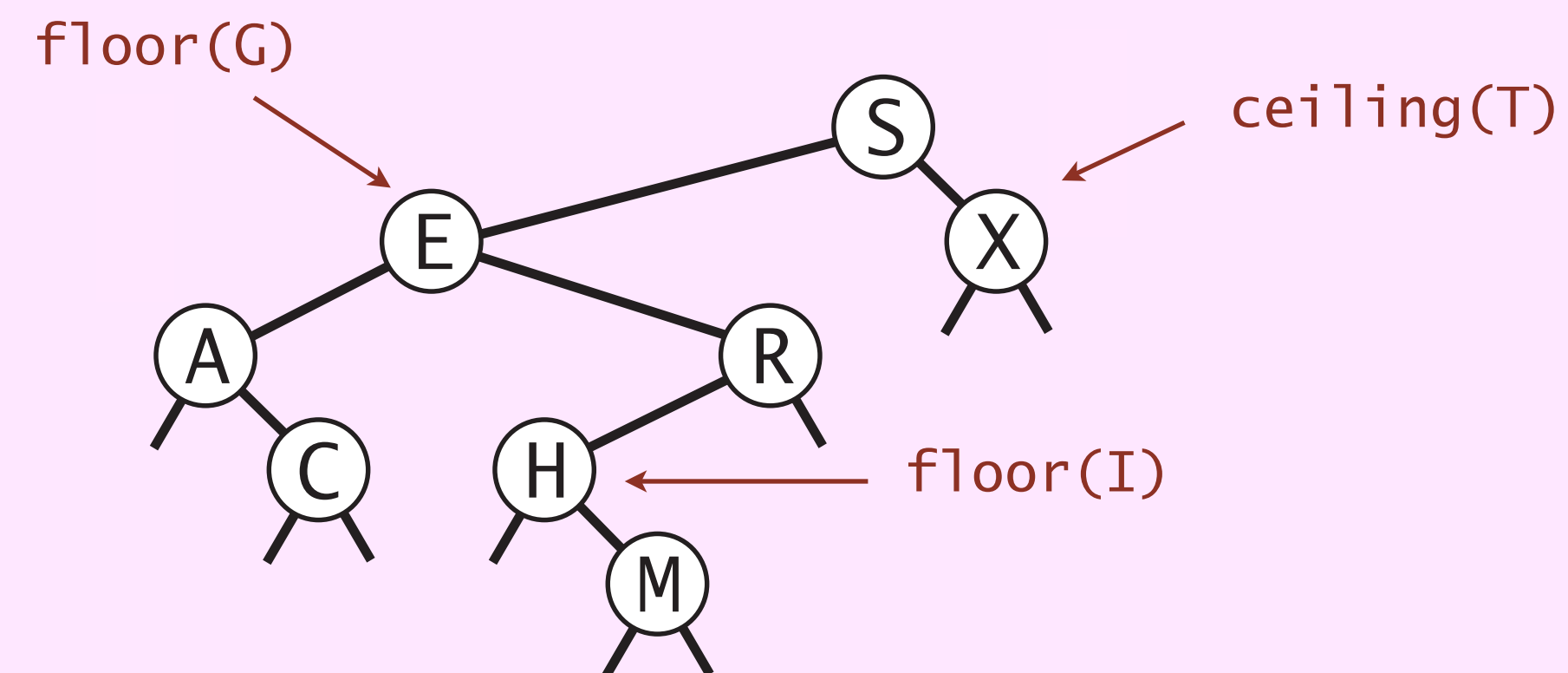


**Floor.** Largest key in BST  $\leq$  query key.

**Ceiling.** Smallest key in BST  $\geq$  query key.

**Key idea.**

- To compute `floor(key)` or `ceiling(key)`, search for `key`.
- Both `floor(key)` and `ceiling(key)` are on search path.
- Moreover, as you go down search path, any candidates get better and better.



# Computing the floor: Java implementation

**Invariant 1.** The floor is either **champ** or in subtree rooted at **x**.

**Invariant 2.** Node **x** is in the right subtree of node containing **champ**. ← assuming **champ** is not null

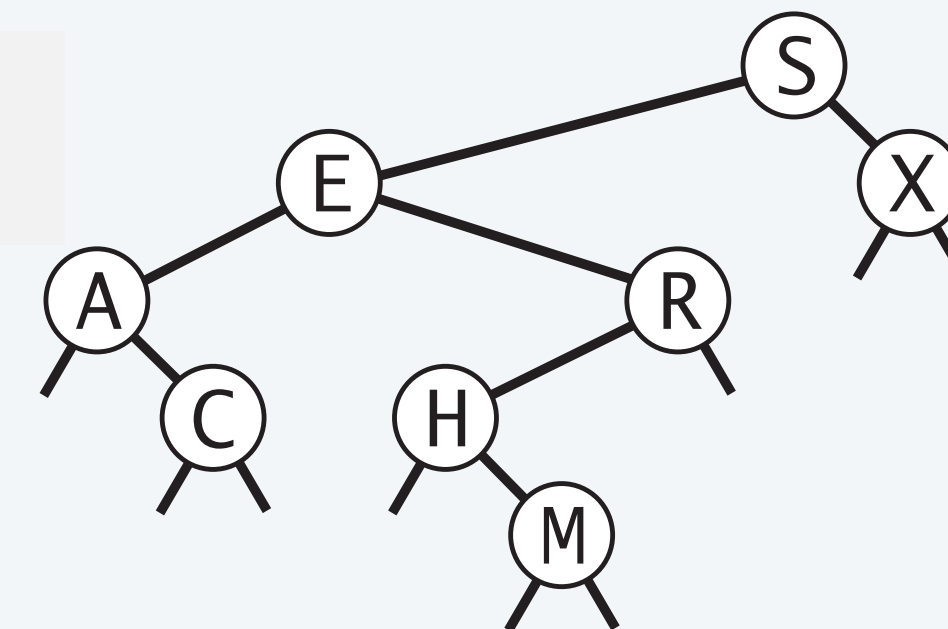
```
public Key floor(Key key) {  
    return floor(root, key, null);  
}
```

```
private Key floor(Node x, Key key, Key champ) {  
    if (x == null) return champ;  
    int cmp = key.compareTo(x.key);  
    if (cmp < 0) return floor(x.left, key, champ);  
    else if (cmp > 0) return floor(x.right, key, x.key);  
    else  
        return x.key;  
}
```



*champ must be floor*

*key in node x is too large  
(floor can't be in right subtree of x)*



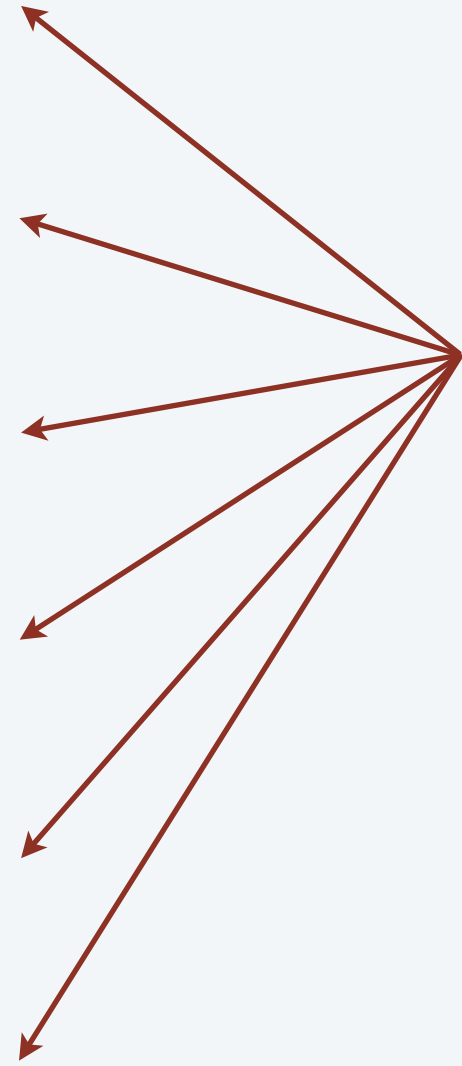
*key is in BST*

*key in node x is a candidate for floor  
(floor can't be in left subtree of x)*

*key in node x is better candidate than champ  
(because x is in the right subtree of champ)*

# BST: ordered symbol table operations summary

	sequential search	binary search	BST
<i>search</i>	$\Theta(n)$	$\Theta(\log n)$	$\Theta(h)$
<i>insert / delete</i>	$\Theta(n)$	$\Theta(n)$	$\Theta(h)$
<i>min / max</i>	$\Theta(n)$	$\Theta(1)$	$\Theta(h)$
<i>floor / ceiling</i>	$\Theta(n)$	$\Theta(\log n)$	$\Theta(h)$
<i>rank</i>	$\Theta(n)$	$\Theta(\log n)$	$\Theta(h)$
<i>select</i>	$\Theta(n)$	$\Theta(1)$	$\Theta(h)$



*h = height of BST*

worst-case running time of ordered symbol table operations

# ST implementations: summary

implementation	worst case		ordered ops?	key interface
	search	insert		
sequential search (unordered list)	$n$	$n$		<code>equals()</code>
binary search (sorted array)	$\log n$	$n$	✓	<code>compareTo()</code>
BST	$n$	$n$	✓	<code>compareTo()</code>
red-black BST	<div>log <math>n</math></div>	<div>log <math>n</math></div>	✓	<code>compareTo()</code>

next lecture: BST whose height is guarantee to be  $\Theta(\log n)$



# Credits

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image	source	license
<i>Inorder Traversal in a BST</i>	<u>Silicon Valley S4E5</u>	
<i>Binary Tree</i>	<u>Daniel Stori</u>	

# A final thought

