

# DENOTATIONAL SEMANTICS

Syntax

Num  $n ::= 0 | 1 | 2 | 3 | \dots$

Var  $x ::= x | y | z | \dots$

Exp  $e ::= n | x | e_1 + e_2 | \text{let } x := e_1 \text{ in } e_2$

Prog  $p ::= e$

Val =  $\mathbb{Z}$

Env = Var  $\rightarrow$  Val

$\mathcal{N} : \text{Num} \rightarrow \text{Val}$

$\mathcal{E} : \text{Exp} \rightarrow \text{Env} \rightarrow \text{Val}$

$\mathcal{D} : \text{Prog} \rightarrow \text{Val}$

$\mathcal{E}[n] = \lambda p. \mathcal{N}[n]$

$\mathcal{E}[x] = \lambda p. p x$

$\mathcal{E}[e_1 + e_2] = \lambda p. \mathcal{E}[e_1] p + \mathcal{E}[e_2] p$

$\mathcal{E}[\text{let } x := e_1 \text{ in } e_2] = \lambda p. \mathcal{E}[e_2](\text{upd}(p, x, \mathcal{E}[e_1] p))$

$\text{upd}(p, x, v) = \lambda y. \text{if } x = y \text{ then } v \text{ else } p y$

$\mathcal{D}[e] = \mathcal{E}[e](\lambda x. 0)$

$\mathcal{E}(\text{NUM } n) = \lambda p. \mathcal{N}(n)$

$\mathcal{E}(\text{VAR } x) = \lambda p. p x$

$\mathcal{E}(\text{PLUS } e_1 e_2) = \dots$

# STRUCTURED CONTROL FLOW

Cmd  $c ::= x := e \mid c_1 ; c_2 \mid \text{if } e \text{ then } c_1 \text{ else } c_2 \mid \text{while } e \text{ do } c$

$\mathcal{C} : \text{Cmd} \rightarrow (\text{Env} \rightarrow \text{Env})$

$\mathcal{C} \llbracket x := e \rrbracket \rho = \text{upd}(\rho, x, \mathcal{E} \llbracket e \rrbracket \rho)$

$\mathcal{C} \llbracket c_1 ; c_2 \rrbracket \rho = \mathcal{C} \llbracket c_2 \rrbracket (\mathcal{C} \llbracket c_1 \rrbracket \rho)$

$\mathcal{C} \llbracket \text{if } e \text{ then } c_1 \text{ else } c_2 \rrbracket \rho = \text{if } \mathcal{E} \llbracket e \rrbracket \rho \neq 0 \text{ then } \mathcal{C} \llbracket c_1 \rrbracket \rho \text{ else } \mathcal{C} \llbracket c_2 \rrbracket \rho$

$\mathcal{C} \llbracket \text{while } e \text{ do } c \rrbracket \rho = (\text{rec } f(\rho) = \text{if } \mathcal{E} \llbracket e \rrbracket \rho \neq 0 \text{ then } f(\mathcal{C} \llbracket c \rrbracket \rho) \text{ else } \rho) \rho$

# UNSTRUCTURED CONTROL FLOW

Cmd  $c ::= x := e \mid c_1 ; c_2 \mid \text{if } e \text{ then } c \mid \text{loop } c \mid \text{continue} \mid \text{break}$

A

$K = \text{Env} \rightarrow A$

~~$\mathcal{C} : \text{Cmd} \rightarrow (K \rightarrow K \rightarrow K \rightarrow K)$~~   $\mathcal{C} : \text{Cmd} \rightarrow (K \rightarrow K \rightarrow K \rightarrow K)$

$\mathcal{C} \llbracket x := e \rrbracket k_1 k_2 k_3 = \lambda \rho. k_1(\text{upd}(\rho, x, \mathcal{E} \llbracket e \rrbracket \rho))$

$\mathcal{C} \llbracket \text{if } e \text{ then } c \rrbracket k_1 k_2 k_3 = \lambda \rho. \text{if } \mathcal{E} \llbracket e \rrbracket \rho \neq 0 \text{ then } \mathcal{C} \llbracket c \rrbracket k_1 k_2 k_3 \rho \text{ else } k_1 \rho$

$\mathcal{C} \llbracket \text{loop } c \rrbracket k_1 k_2 k_3 = (\text{rec } f(k) = \mathcal{C} \llbracket c \rrbracket (f k) (f k) k_1) k_1$

$\mathcal{C} \llbracket \text{continue} \rrbracket k_1 k_2 k_3 = k_2$

$\mathcal{C} \llbracket \text{break} \rrbracket k_1 k_2 k_3 = k_3$

A = Val

$\mathcal{P} : \text{Cmd} \rightarrow A$

$\mathcal{P} \llbracket c \rrbracket = \mathcal{C} \llbracket c \rrbracket (\lambda \rho. \rho(x_0)) (\lambda \rho. 0) (\lambda \rho. 0) (\lambda x. 0)$