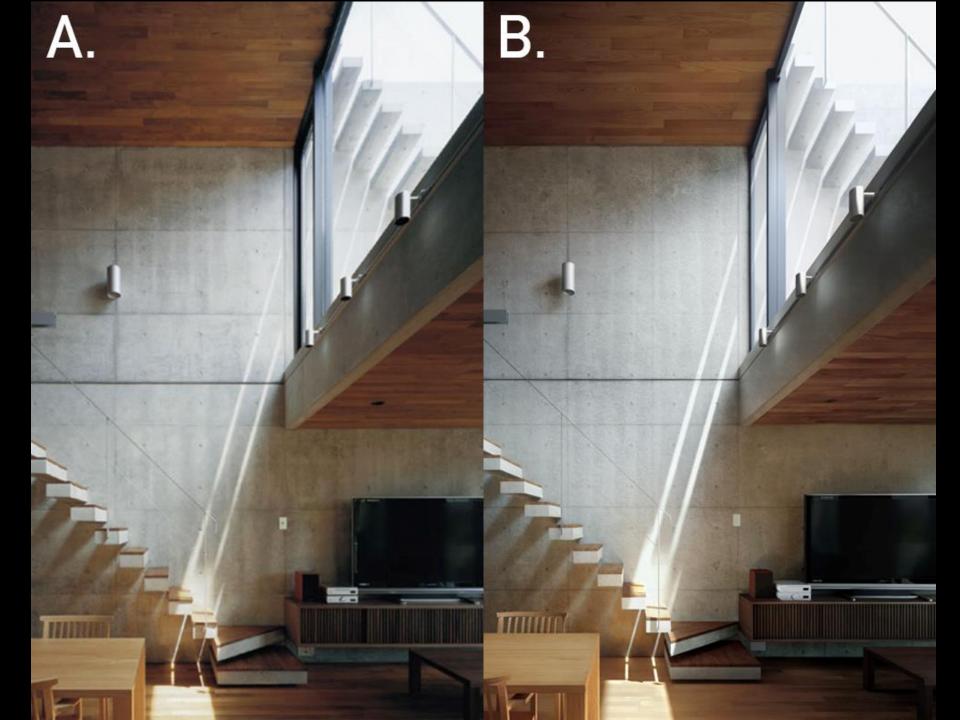


Global Illumination

COS 426, Spring 2021 Felix Heide Princeton University



Overview

- Direct Illumination
 - Emission at light sources
 - Scattering at surfaces
- Global illumination
 - Shadows
 - Inter-object reflections
 - Rendering equation
 - Recursive ray tracing
 - More advanced ray tracing
 - Radiosity



Greg Ward

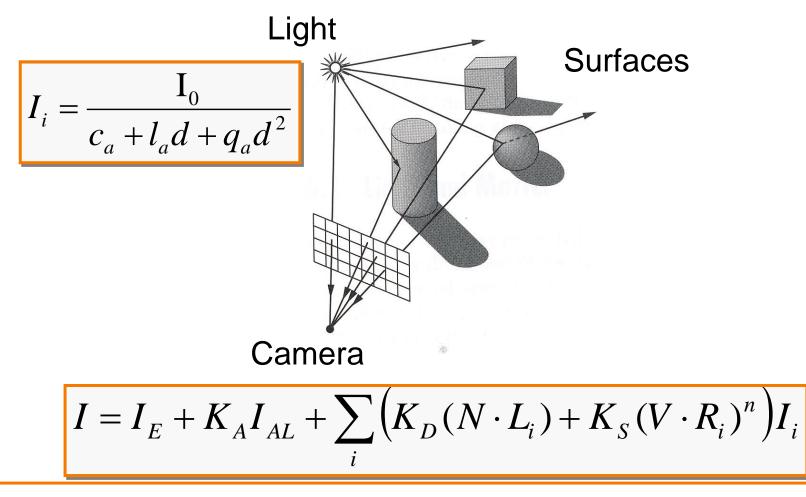


Direct Illumination (last lecture)



For each ray traced from camera

• Sum radiance reflected from each light



Direct illumination example



Direct Lighting Only



Overview

- Direct Illumination
 - Emission at light sources
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Global illumination

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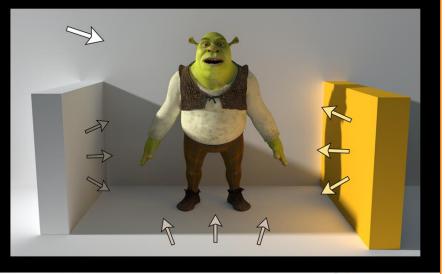
Global illumination example

DET LINE NUMBER

Direct Lighting Only



Direct + Indirect Lighting



SIGGRAPH2010

DREAMWORKS Ø SIGGRAPH2010

DREAMWORKS

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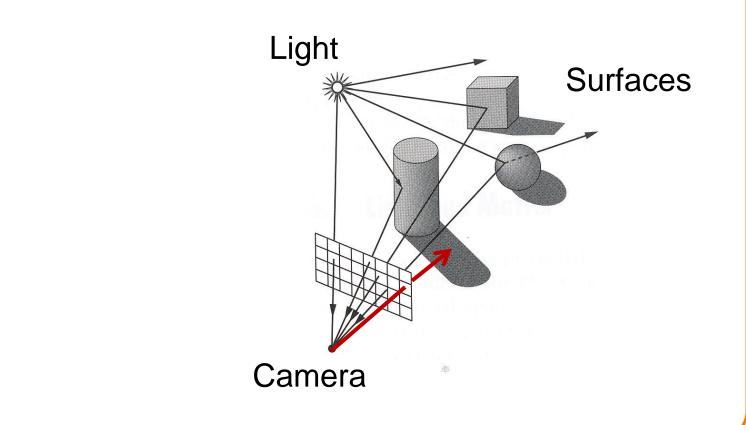


Greg Ward



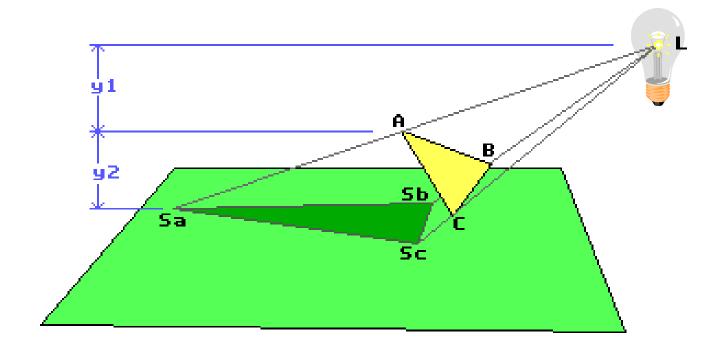


• Hard shadows from point light sources



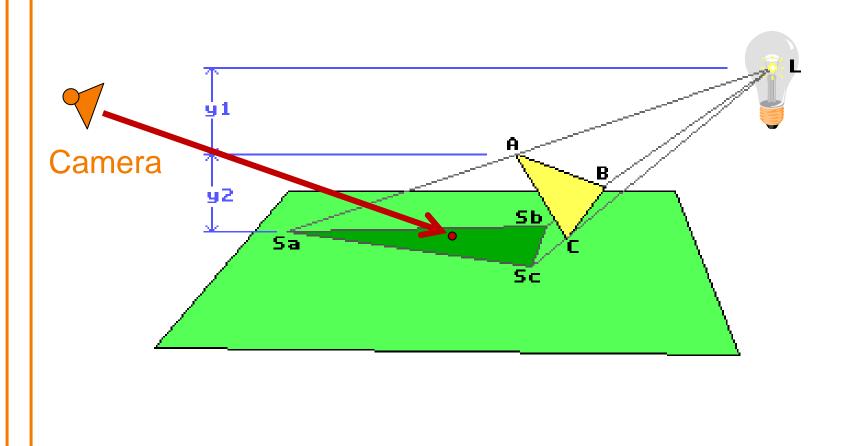


Hard shadows from point light sources



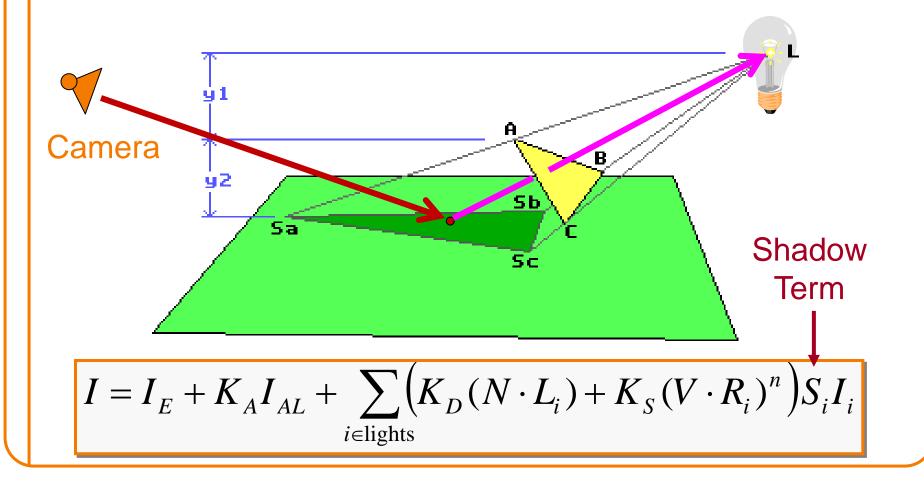


• Hard shadows from point light sources





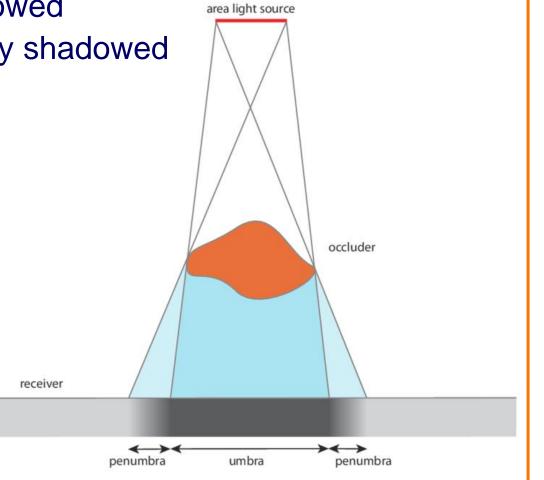
Hard shadows from point light sources
 Cast ray towards light; S₁=0 if blocked, S₁=1 otherwise



Shadows in 2D



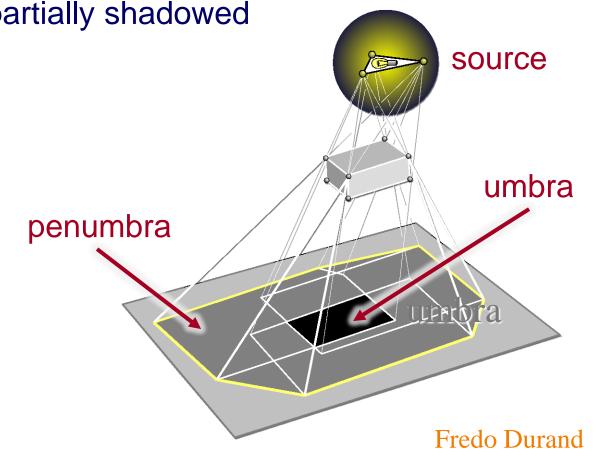
- Soft shadows from area light sources
 - Umbra = fully shadowed
 - Penumbra = partially shadowed



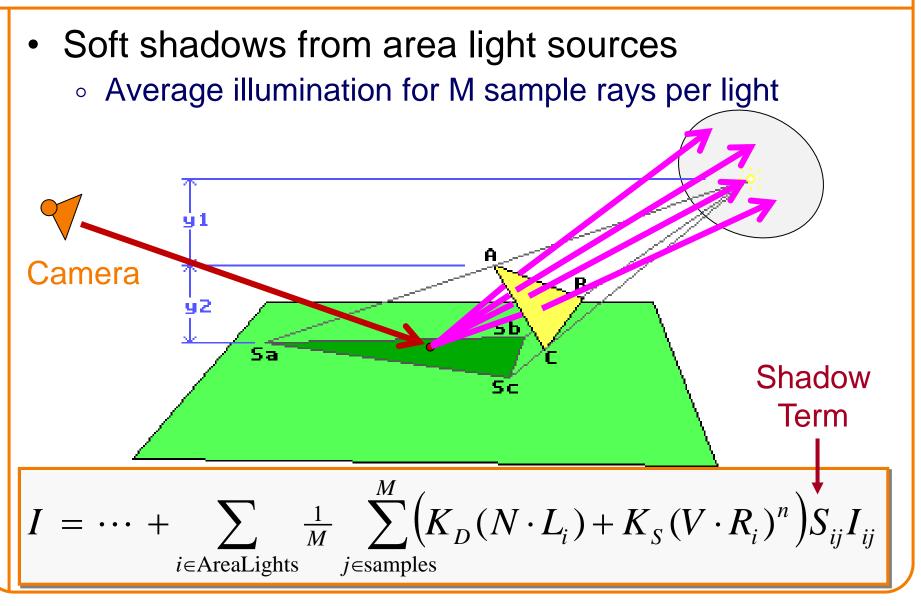
Shadows in 3D



- Soft shadows from area light sources
 - Umbra = fully shadowed
 - Penumbra = partially shadowed



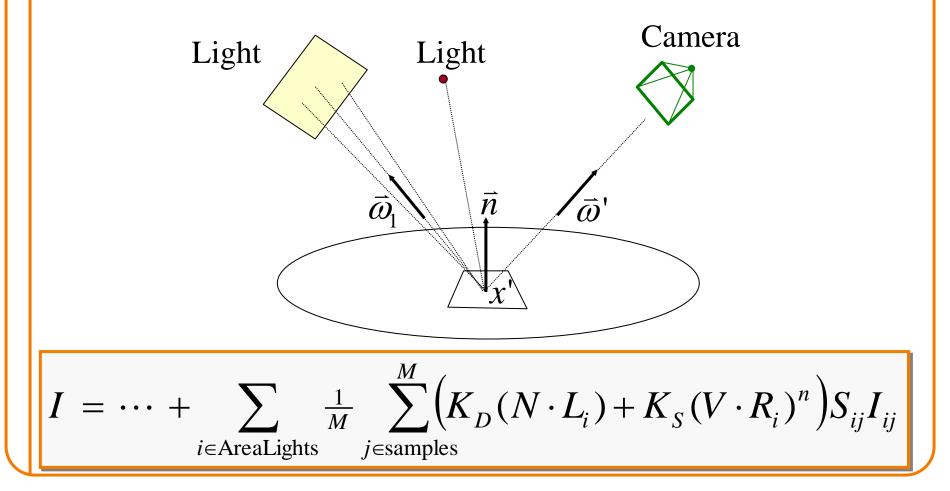




Direct Illumination



Illumination from polygonal area light sources
 Average illumination for M sample rays per light





- Soft shadows from circular area light sources
 - Average illumination for M sample rays per light

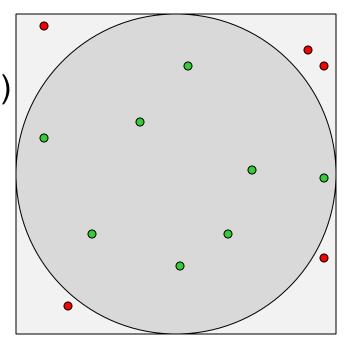
 $\sum \frac{1}{M} \sum_{i=1}^{M} \left(K_D(N \cdot L_i) + K_S(V \cdot R_i)^n \right) S_{ij} I_{ij}$

 Generate M random sample points on area light (e.g., with rejection sampling)

j∈samples

- Compute illumination for every sample
- Average

i∈AreaLights



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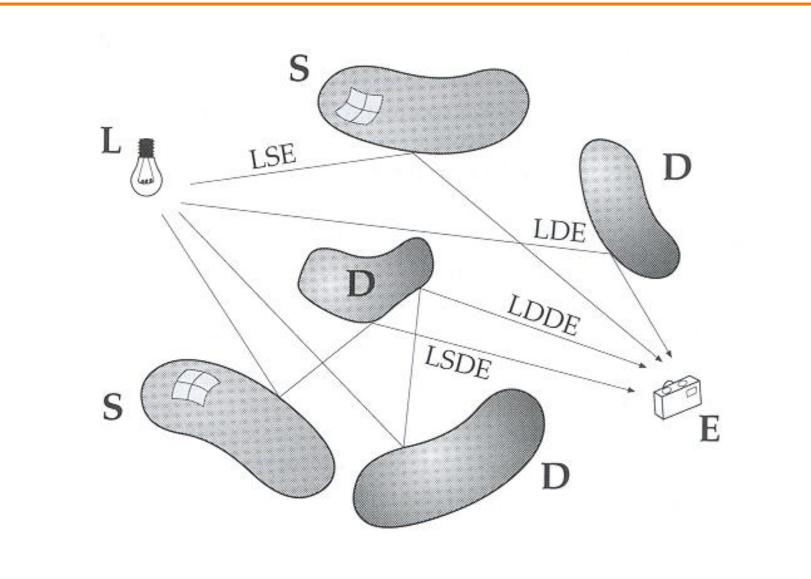






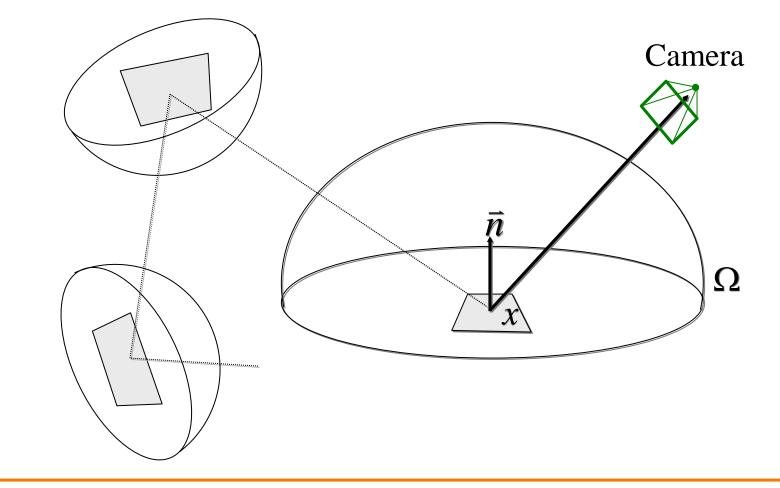
Inter-Object Reflection





Inter-Object Reflection

- Radiance leaving point *x* on surface is sum of reflected irradiance arriving from other surfaces



Solid Angle

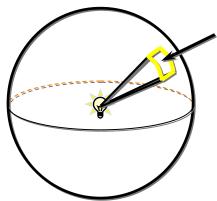


• Angle in radians

Length lAngle $\theta = l/r$

(Full circle is 2π radians.)

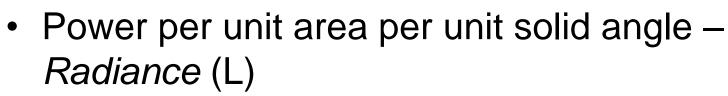
Solid angle in steradians



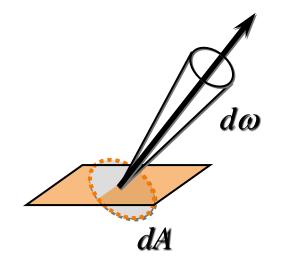
• Area A
Solid angle
$$\omega = A/r^2$$

(Full sphere is 4π steradians.)

Light Emitted from a Surface



Measured in W/m²/sr



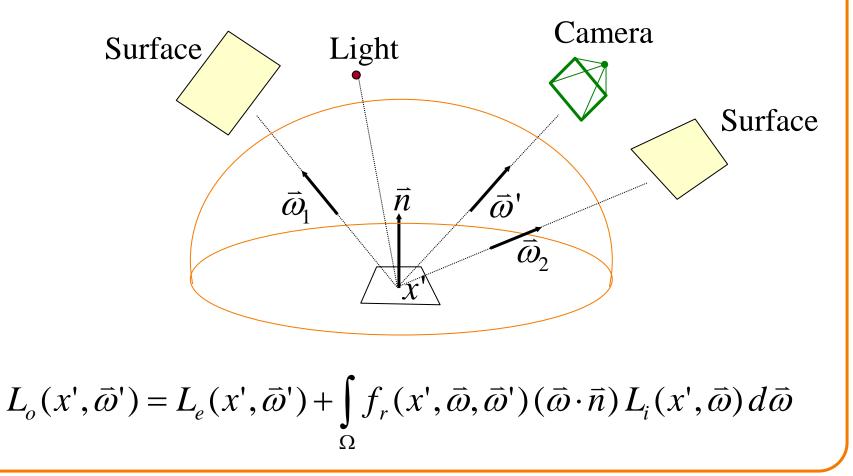
$$L = \frac{d\Phi}{dA\,d\omega}$$



Rendering Equation [Kajiya 86]



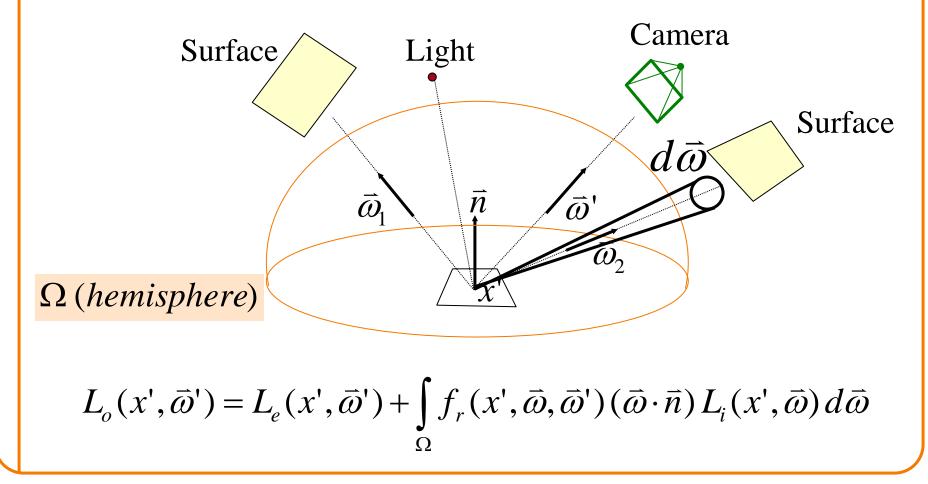
 Compute radiance in outgoing direction by integrating reflections over all incoming directions



Rendering Equation [Kajiya 86]



 Compute radiance in outgoing direction by integrating reflections over all incoming directions



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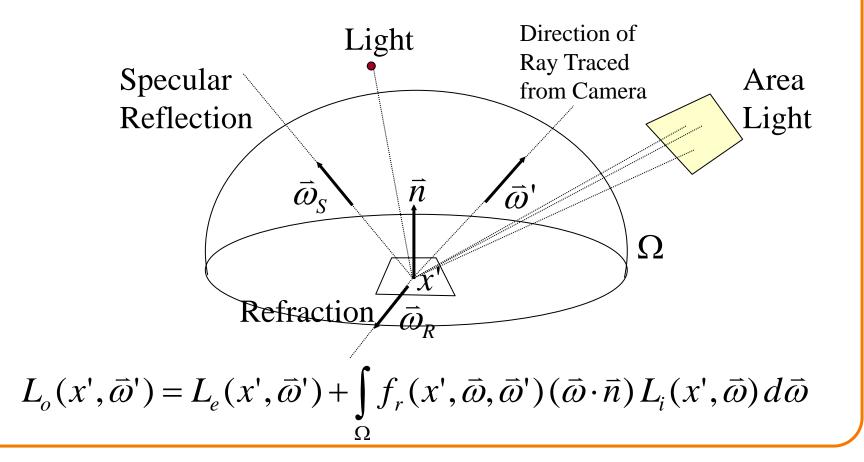






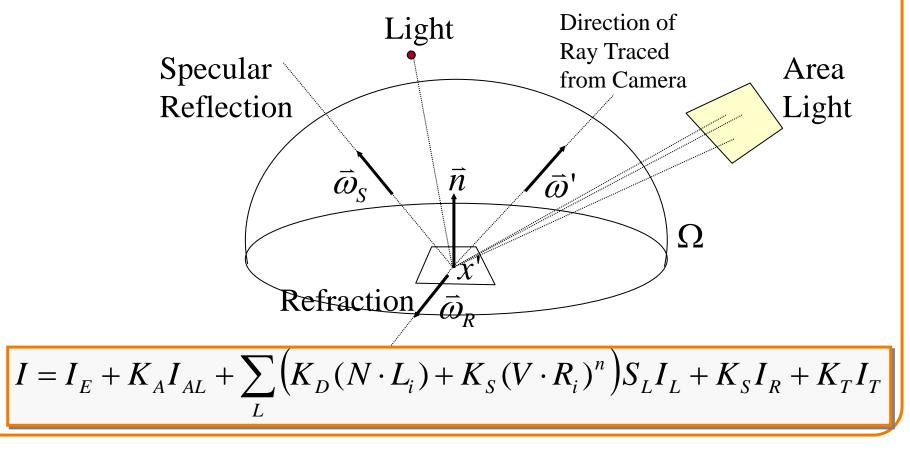


• Assume only significant irradiance is in directions of light sources, specular reflection, and refraction



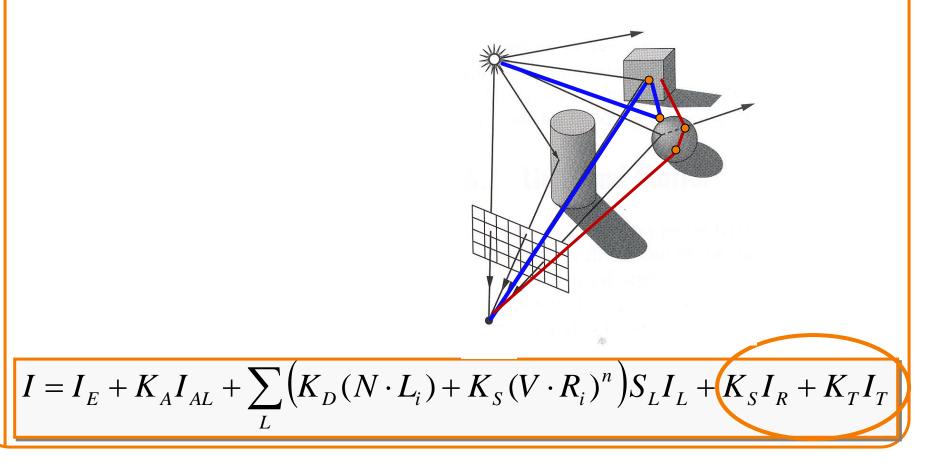


 Compute radiance in outgoing direction by summing reflections from directions of lights specular reflections, and refractions





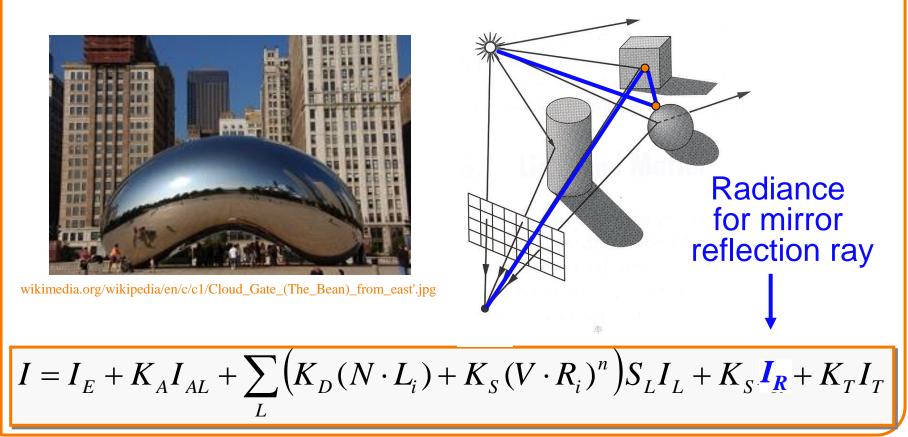
 Same as ray casting, but trace secondary rays for specular (mirror) reflection and refraction



Specular Reflection



 Trace secondary ray in direction of mirror reflection
 Evaluate radiance along secondary ray and include it into illumination model

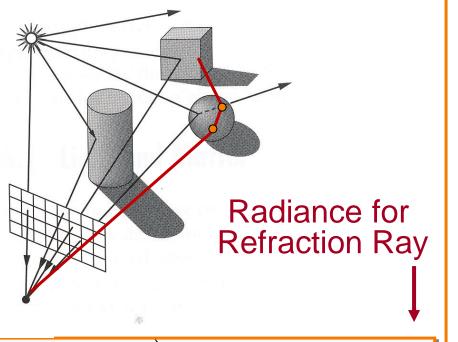


Refraction



 Trace secondary ray in direction of refraction
 Evaluate radiance along secondary ray and include it into illumination model





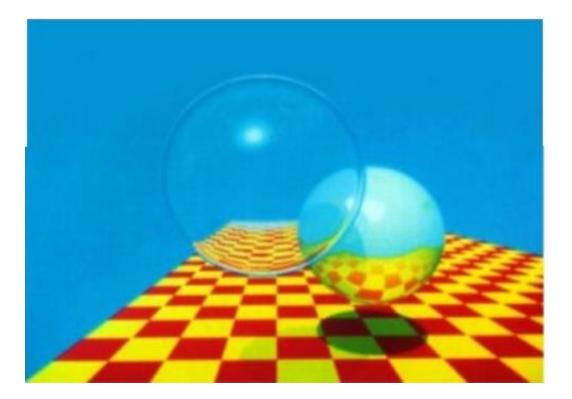
 $I = I_{E} + K_{A}I_{AL} + \sum \left(K_{D}(N \cdot L_{i}) + K_{S}(V \cdot R_{i})^{n}\right)S_{L}I_{L} + K_{S}I_{R} + K_{T}I_{T}$



• ComputeRadiance is called recursively



• Specular reflection and refraction -- LD(SR)*E





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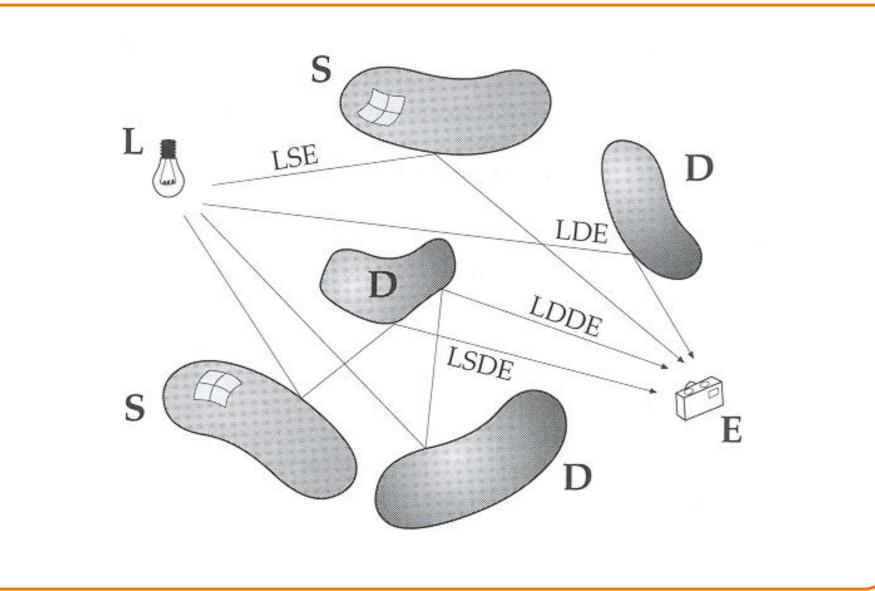


Greg Ward



Beyond Recursive Ray Tracing

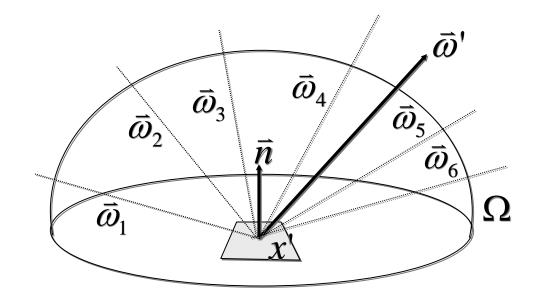




Distributed Ray Tracing



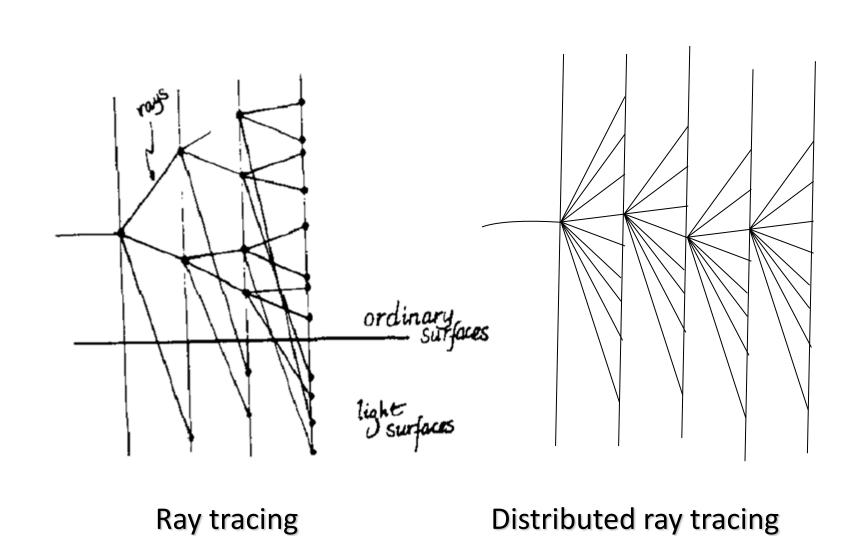
 Estimate integral for each reflection by sampling incoming directions



 $L_o(x',\bar{\omega}') = L_e(x',\bar{\omega}') + \sum_{\text{samples}} f_r(x',\bar{\omega},\bar{\omega}')(\bar{\omega}\cdot\bar{n}) L_i(x',\bar{\omega}) d\bar{\omega}$

Ordinary Ray Tracing vs. Distribution Ray Tracing



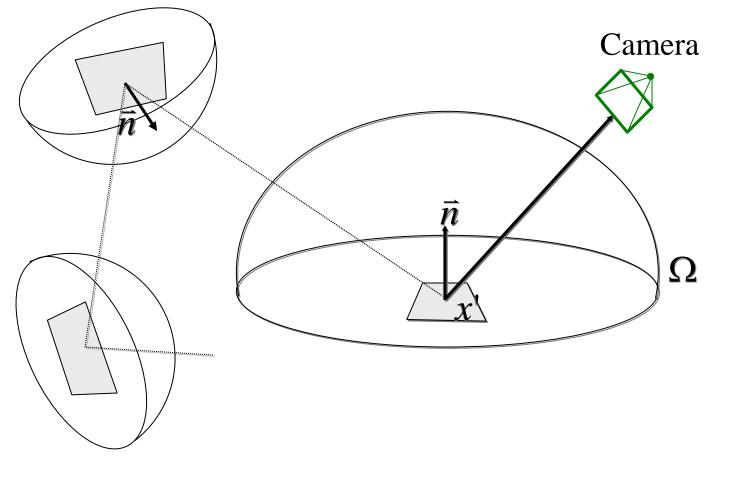


Kajiya

Monte Carlo Path Tracing



• Estimate integral for each pixel by sampling paths from camera



Ray Tracing vs. Path Tracing يتخلق т^р ordinary surfaces * - _ light D surfaces Ray tracing Path tracing Kajiya

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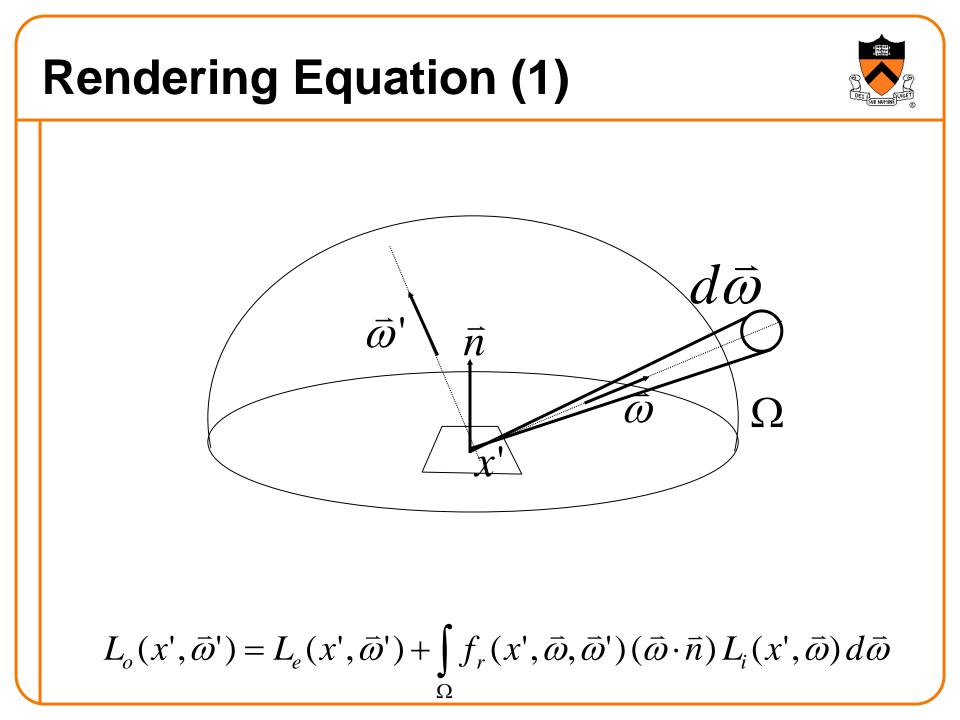


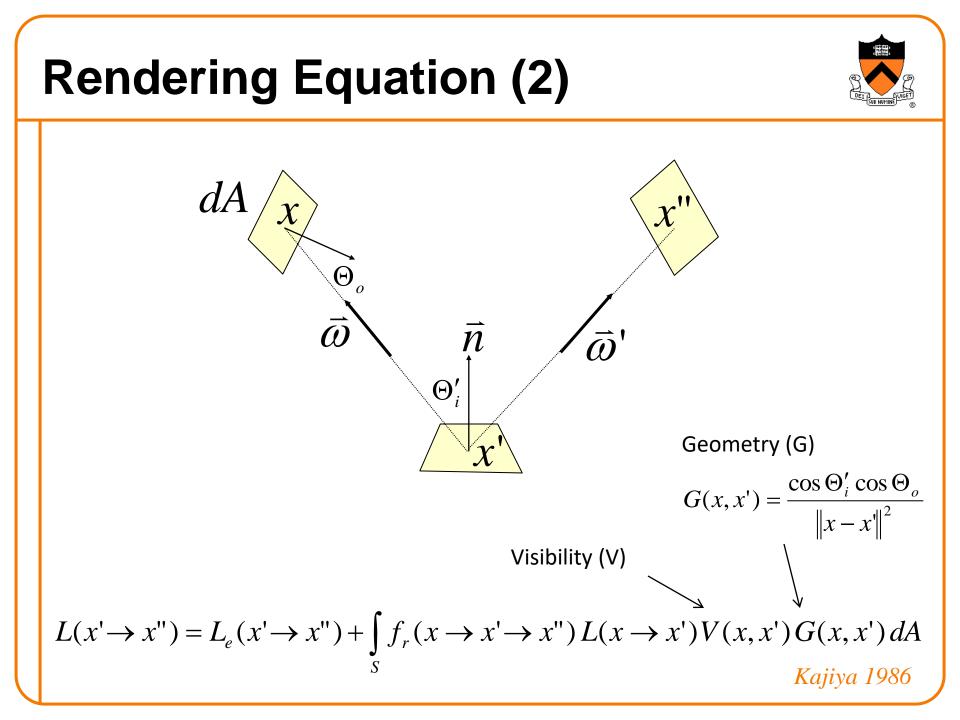
Radiosity



Indirect diffuse illumination – LD*E







Radiosity Equation



$$L(x' \to x'') = L_e(x' \to x'') + \int_S f_r(x \to x' \to x'') L(x \to x') V(x, x') G(x, x') dA$$

Assume everything is Lambertian

$$\rho(x') = f_r(x \to x' \to x'')\pi$$

$$L(x') = L_e(x') + \frac{\rho(x')}{\pi} \int_{S} L(x)V(x, x')G(x, x') dA$$

Convert to
Radiosities
$$B = \int_{\Omega} L_o \cos \theta \, d\omega \qquad L = \frac{B}{\pi}$$

$$B(x') = B_e(x') + \frac{\rho(x')}{\pi} \int_{S} B(x) V(x, x') G(x, x') dA$$

Radiosity Approximation



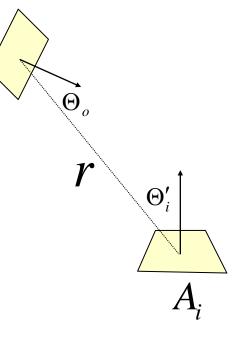
$$B(x') = B_e(x') + \frac{\rho(x')}{\pi} \int_{S} B(x) V(x, x') G(x, x') dA$$

Discretize the surfaces into "elements"

$$B_i = E_i + \rho_i \sum_{j=1}^N B_j F_{ij}$$

where "form factor" F is:

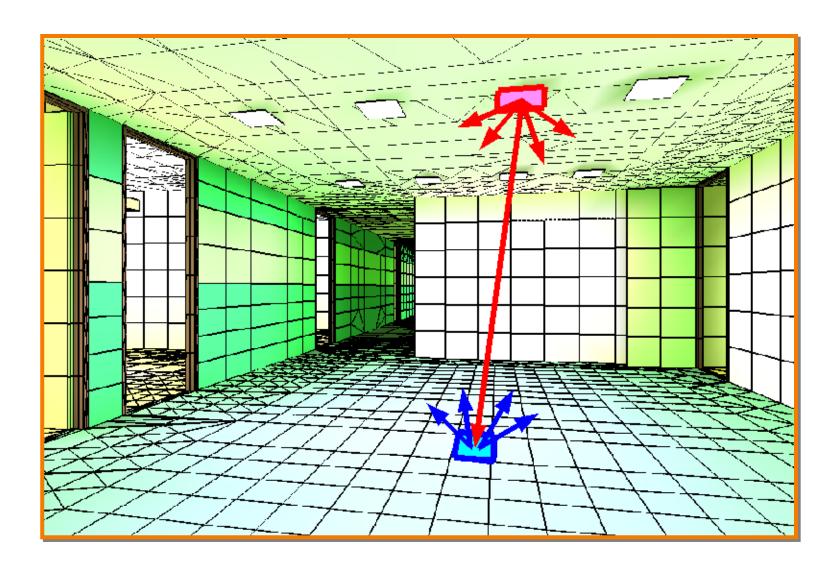
$$F_{ij} = \frac{1}{A_i} \int_{A_i} \int_{A_j} \frac{V_{ij} \cos \Theta_i' \cos \Theta_o}{\pi r^2} dA_j dA_i$$



 \boldsymbol{A}

Radiosity Approximation





On the Form Factor between Two Polygons

Peter Schröder

Pat Hanrahan

Department of Computer Science Princeton University

Abstract

Form factors are used in radiosity to describe the fraction of diffusely reflected light leaving one surface and arriving at another. They are a fundamental geometric property used for computation. Many special configurations admit closed form solutions. However, the important case of the form factor between two polygons in three space has had no known closed form solution. We give such a solution for the case of general (planar, convex or concave, possibly containing holes) polygons.

CR Categories and Subject Descriptors: I.3.7 [Computer Graphics]: Three-Dimensional Graphics and Realism - Radiosity; J.2 [Physical Sciences and Engineering]: Engineering.

Additional Key Words and Phrases: Closed form solution; form factor; polygons.

Introduction

When using the radiosity techni factor plays a central role. It

In this paper we present a formula for the form factor integral between two general polygons. The derivation of this formula is quite involved, and the interested reader is referred to [9] for a detailed derivation. The purpose of this paper is to bring this result to the attention of the graphics community.

Closed form solution

The form factor integral can be reduced to a double contour integral by two applications of Stokes' theorem [6]

$$\pi A_1 F_{12} = \int_{A_1} \int_{A_2} \frac{\cos \theta_1 \cos \theta_2}{\|\vec{r}\|^2} \, dA_2 \, dA_1$$

= $\frac{1}{4} \int_{\partial A_1} \int_{\partial A_2} \ln(\vec{r} \cdot \vec{r}) \, d\vec{x}_2 \cdot d\vec{x}$

where θ_1 , θ_2 are the angles between the normal vector of the respective surface and a radius vector \vec{r} , which connects two points on the surfaces. The above equation holds for all surfaces such

he same contour of the

contour integral reduces

[5] HANRAHAN, P., SALZMAN, D., AND AUPPERLE, L. A Rapid Hierarchical Radiosity Algorithm. Computer Graphics 25, 4 (July 1991), 197-206.

- [6] HERMAN, R. A. A Treatise on Geometrical Optics. Cambridge University Press, 1900.
- [7] LAMBERT. Photometria sive de mensura et gradibus luminis, colorum et umbrae. 1760. German translation by E. Anding in Ostwald's Klassiker der Exakten Wissenschaften, Vol. 31-33, Leipzig, 1892.





Form Factor

System of Equations



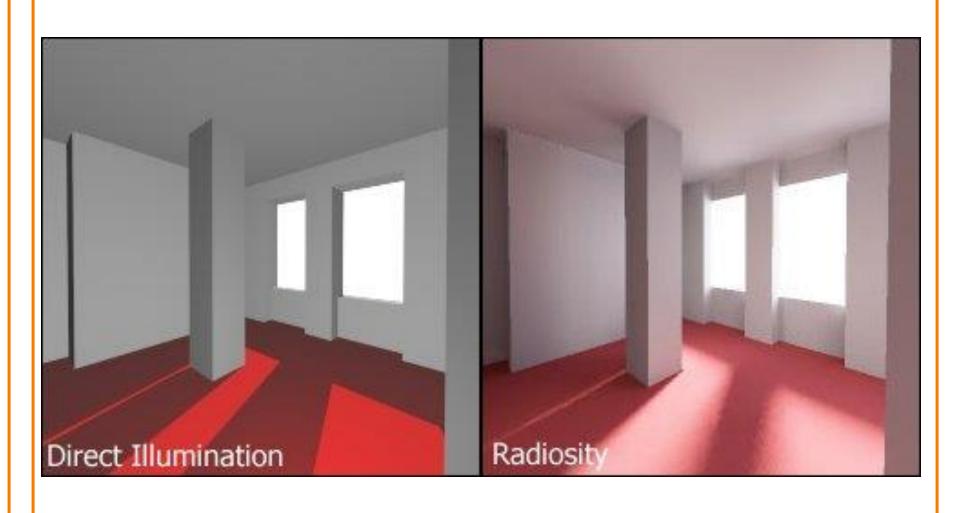
$$B_i = E_i + \rho_i \sum_{j=1}^N B_j F_{ij}$$
$$E_i = B_i - \rho_i \sum_{j=1}^N B_j F_{ij}$$

$$B_i - \rho_i \sum_{j=1}^N B_j F_{ij} = E_i$$

$$\begin{bmatrix} 1 - \rho_{1}F_{1,1} & . & . & . & -\rho_{1}F_{1,n} \\ - \rho_{2}F_{2,1} & 1 - \rho_{2}F_{2,2} & . & -\rho_{2}F_{2,n} \\ . & . & . & . & . \\ - \rho_{n-1}F_{n-1,1} & . & . & . & -\rho_{n-1}F_{n-1,n} \\ - \rho_{n}F_{n,1} & . & . & . & 1 - \rho_{n}F_{n,n} \end{bmatrix} \begin{bmatrix} B_{1} \\ B_{2} \\ . \\ . \\ B_{n} \end{bmatrix} = \begin{bmatrix} E_{1} \\ E_{2} \\ . \\ . \\ B_{n} \end{bmatrix}$$

Compare with Direct Illumination





Hugo Elias, Wikipedia

Radiosity

- Application
 - Interior lighting design
 - LD*E
- Issues
 - Computing form factors
 - Solving large linear system of equations
 - Meshing surfaces into elements
 - Rendering images

Summary

- Global illumination
 Rendering equation
- Solution methods
 - Sampling
 - Ray tracing
 - Distributed ray tracing
 - Monte Carlo path tracing
 - Discretization
 - Radiosity

Take-home message:

Photorealistic rendering with global illumination is an integration problem

