# Replication State Machines via Primary-Backup Replication

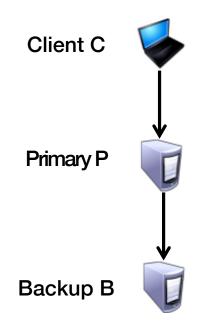


COS 418: Distributed Systems
Lecture 11

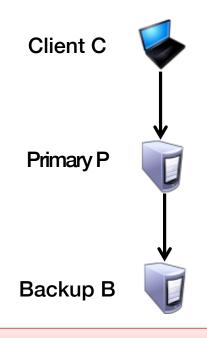
Wyatt Lloyd

# From eventual to strong consistency

- Eventual consistency
  - Multi-master: Any node can accept operation
  - Asynchronously, nodes synchronize state
- Eventual consistency inappropriate for many applications
  - Imagine bank ledger as eventually consistent
- Stronger consistency makes applications easier to write
  - (More on downsides later)



- Mechanism: Replicate and separate servers
- Goal #1: Provide a highly reliable service (despite failures)
- Goal #2: Servers should behave just like a single, more reliable server



- Nominate one replica primary, other backup
  - Clients send all ops to current primary
  - Primary orders clients' operations
- Only one primary at a time

Need to keep clients, primary, and backup in sync: who is primary and who is backup

# State machine replication

- Idea: A replica is essentially a state machine
  - Set of (key, value) pairs is state
  - Operations transition between states
- Need an op to be executed on all replicas, or none at all
  - i.e., we need distributed all-or-nothing atomicity
  - If op is deterministic, replicas will end in same state
- Key assumption: Operations are deterministic

#### More reading: ACM Computing Surveys, Vol. 22, No. 4, December 1990 (pdf)

#### Implementing Fault-Tolerant Services Using the State Machine Approach: A Tutorial

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The state machine approach is a general method for implementing fault-tolerant services in distributed systems. This paper reviews the approach and describes protocols for two different failure models—Byzantine and fail stop. System reconfiguration techniques for removing faulty components and integrating repaired components are also discussed.

Categories and Subject Descriptors: C.2.4 [Computer-Communication Networks]: Distributed Systems—network operating systems; D.2.10 [Software Engineering]: Design—methodologies; D.4.5 [Operating Systems]: Reliability—fault tolerance; D.4.7 [Operating Systems]: Organization and Design—interactive systems, real-time systems

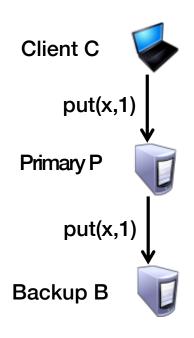
General Terms: Algorithms, Design, Reliability

Additional Key Words and Phrases: Client-server, distributed services, state machine approach

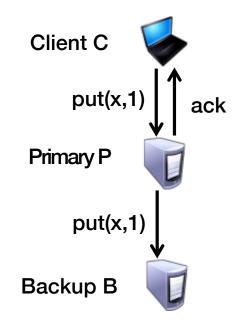
#### INTRODUCTION

Distributed software is often structured in terms of *clients* and *services*. Each service comprises one or more *servers* and exports *operations* that clients invoke by making *requests*. Although using a single, centralized, server is the simplest way to imple-

service by replicating servers and coordinating client interactions with server replicas. The approach also provides a framework for understanding and designing replication management protocols. Many protocols that involve replication of data or software—be it for masking failures or simply to facilitate cooperation without

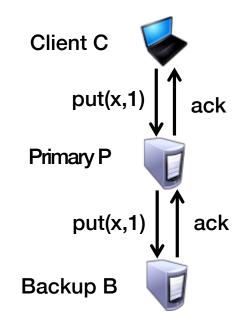


- 1. Primary gets operations
- 2. Primary orders ops into log
- 3. Replicates log of ops to backup
- 4. Backup exec's ops or writes to log



#### **Asynchronous Replication**

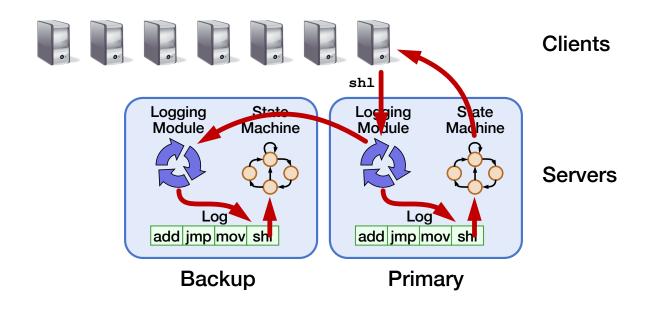
- 1. Primary gets operations
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#### **Synchronous Replication**

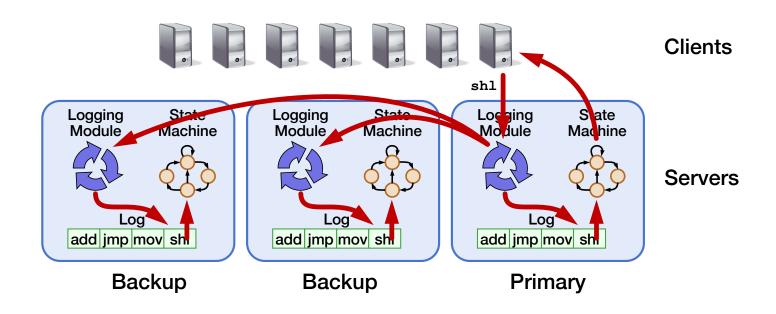
- 1. Primary gets operations
- 2. Primary orders ops into log
- 3. Replicates log of ops to backup
- 4. Backup exec's op or writes to log
- 5. Primary gets ack, execs ops

#### Why does this work? Synchronous Replication



- Replicated log => replicated state machine
  - All servers execute same commands in same order

#### Why does this work? Synchronous Replication



- Replicated log => replicated state machine
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#### Need determinism? Make it so!

- Operations are deterministic
  - No events with ordering based on local clock
    - Convert timer, network, user into logged events
  - Nothing using random inputs

- Execution order of ops is identical
  - Most RSMs are single threaded

# Example: Make random() deterministic

Almost all module functions depend on the basic function <code>random()</code>, which generates a random float uniformly in the semi-open range [0.0, 1.0). Python uses the Mersenne Twister as the core generator. It produces 53-bit precision floats and has a period of 2\*\*19937-1. The underlying implementation in C is both fast and threadsafe. The Mersenne Twister is one of the most extensively tested random number generators in existence. However, being completely deterministic, it is not suitable for all purposes, and is completely unsuitable for cryptographic purposes.

#### random. **seed**(a=None)

Initialize internal state of the random number generator.

None or no argument seeds from current time or from an operating system specific randomness source if available (see the os.urandom() function for details on availability).

#### random. getstate()

Return an object capturing the current internal state of the generator. This object can be passed to setstate() to restore the state.

# Example: Make random() deterministic

- Primary:
  - Initiates PRNG with OS-supplied randomness, gets initial seed
  - Sends initial seed to to backup
- Backup
  - Initiates PRNG with seed from primary

#### random. seed(a=None)

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#### Case study

# The design of a practical system for fault-tolerant virtual machines

D. Scales, M. Nelson, G. Venkitachalam, VMWare

SIGOPS Operating Systems Review 44(4), Dec. 2010 (pcf)

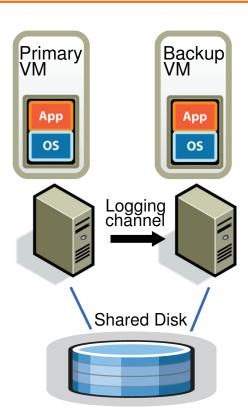
# VMware vSphere Fault Tolerance (VM-FT)

#### Goals:

- 1. Replication of the whole virtual machine
- 2. Completely transparent to apps and clients
- 3. High availability for any existing software

# vSphere Overview

- Two virtual machines (primary, backup) on different bare metal
- Logging channel runs over network
- Shared disk via fiber channel



#### Virtual Machine I/O

#### VM inputs

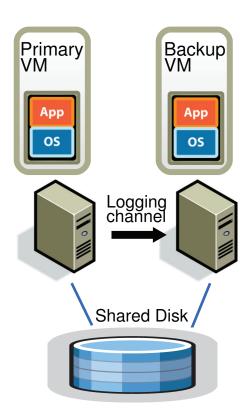
- Incoming network packets
- Disk reads
- Keyboard and mouse events
- Clock timer interrupt events

#### VM outputs

- Outgoing network packets
- Disk writes

#### **Overview**

- Primary sends inputs to backup
- Backup outputs dropped
- Primary-backup heartbeats
  - If primary fails, backup takes over



#### VM-FT: Challenges

1. Making the backup an exact replica of primary

2. Making the system behave like a single server

3. Avoiding two primaries (Split Brain)

# Log-based VM replication

- Step 1: Hypervisor at primary logs causes of non-determinism
  - 1. Log results of input events
    - Including current program counter value for each
  - 2. Log results of non-deterministic instructions
    - e.g. log result of timestamp counter read

# Log-based VM replication

- Step 2: Primary hypervisor sends log entries to backup
- Backup hypervisor replays the log entries
  - Stops backup VM at next input event or nondeterministic instruction
    - Delivers same input as primary
    - Delivers same non-deterministic instruction result as primary

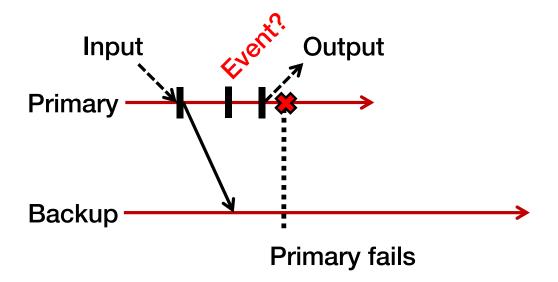
# VM-FT Challenges

- 1. Making the backup an exact replica of primary
- 2. Making the system behave like a single server
  - -FT Protocol
- 3. Avoiding two primaries (Split Brain)

#### Primary to backup failover

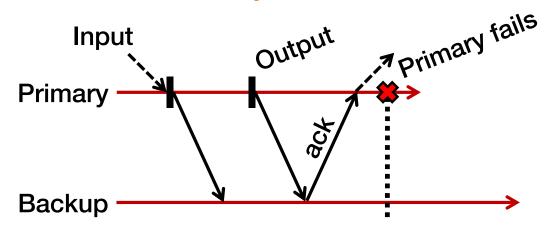
- When backup takes over, non-determinism makes it execute differently than primary would have
  - -This is okay!
- Output requirement
  - When backup takes over, execution is consistent with outputs the primary has already sent

# The problem of inconsistency



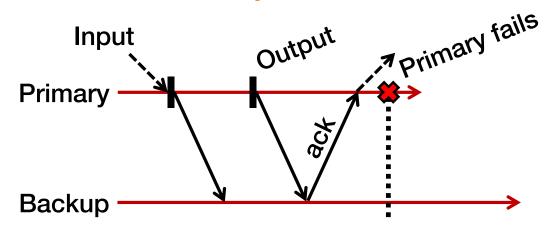
# VM-FT protocol

- Primary logs each output operation
- Delays sending output until Backup acknowledges it
  - But does not need to delay execution



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- Primary logs each output operation
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  - But does not need to delay execution



Restart execution at last output event

#### VM-FT Backup Promotion Process #1

- Backup switches from backup mode to primary mode at the last output event in the log
- Should it resend the last output event (packet)?
  - Not sending same as the network dropping it
    - · Okay to not send
  - Resending same as sending a duplicate packet, which TCP does
    - Okay to send
  - Paper doesn't specify
    - (My take: resend TCP packets, don't resend UDP packets)

# VM-FT: Challenges

- 1. Making the backup an exact replica of primary
- 2. Making the system behave like a single server
- 3. Avoiding two primaries (Split Brain)
  - Logging channel may break

# Detecting and responding to failures

- Primary and backup each run UDP heartbeats, monitor logging traffic from their peer
- Before "going live" execute atomic test-and-set on variable in shared storage
- If the replica finds variable already set, it aborts (and halts)

# **Backup Promotion Additional Work**

- Advertise same MAC address as primary was using
- Startup a new backup

- If the primary detects the backup failed
  - It starts a new backup

- State-machine replication: same input, deterministic processing => identical replicas
- VM-FT: we can do this with whole machines!
  - Determinism tricky, but doable
  - Primary delays output until acked by backup
  - Use atomic test-and-set on shared disk to avoid split brain