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DYNAMIC PROGRAMMING

- ▶ *introduction*
- ▶ *Fibonacci numbers*
- ▶ *interview problems*
- ▶ *shortest paths in DAGs*
- ▶ *seam carving*



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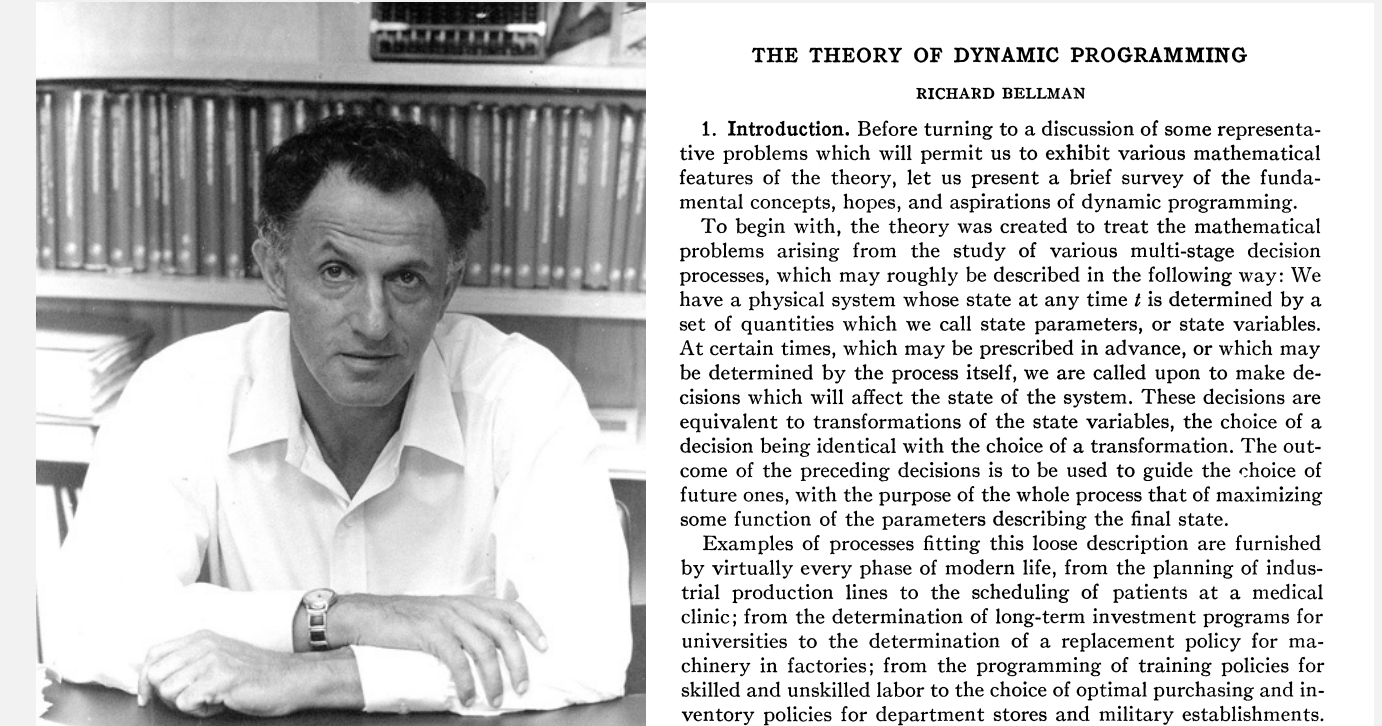
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Dynamic programming

Algorithm design paradigm.

- Break up a problem into a series of overlapping subproblems.
- Build up solutions to larger and larger subproblems.
(caching solutions to subproblems for later reuse)



Richard Bellman, *46

Application areas.

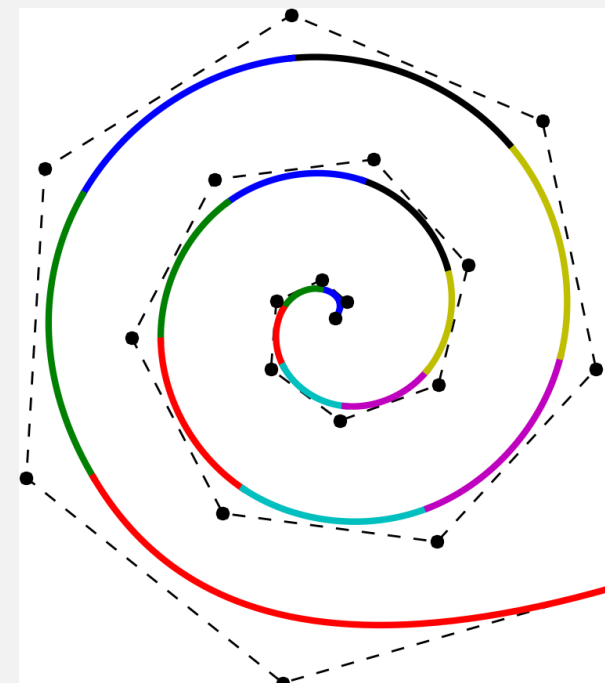
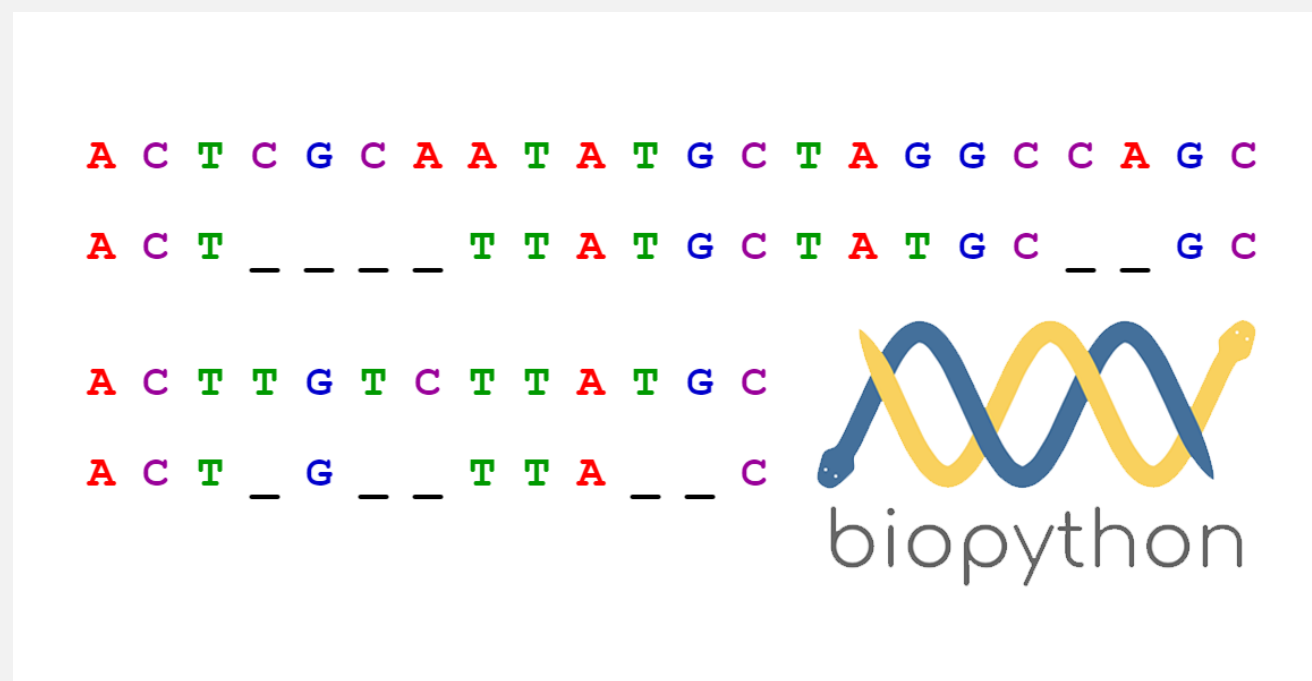
- Operations research: multistage decision processes, control theory, optimization, ...
- Computer science: AI, compilers, systems, graphics, databases, robotics, theory,
- Economics.
- Bioinformatics.
- Information theory.
- Tech job interviews.

Bottom line. Powerful technique; broadly applicable.

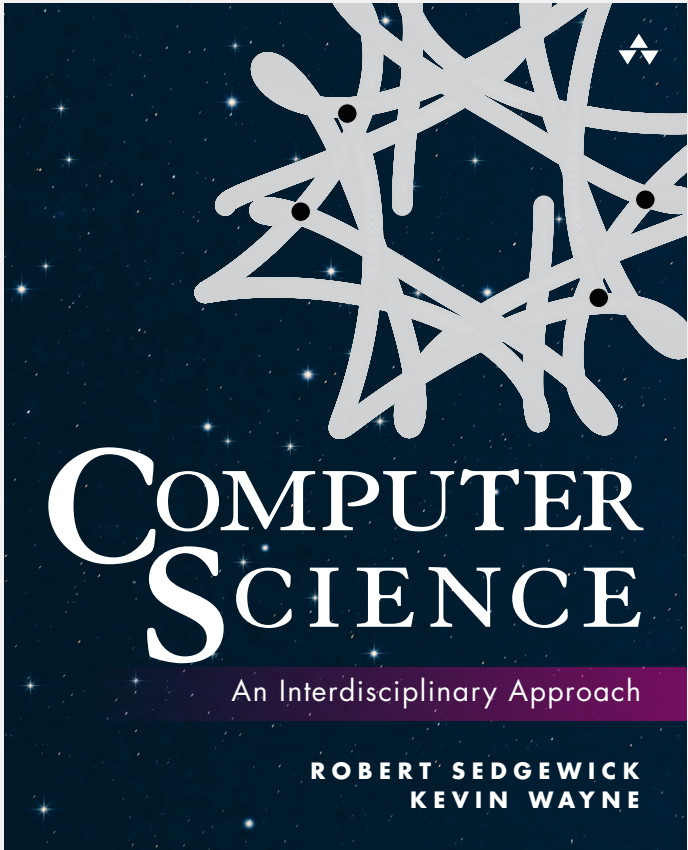
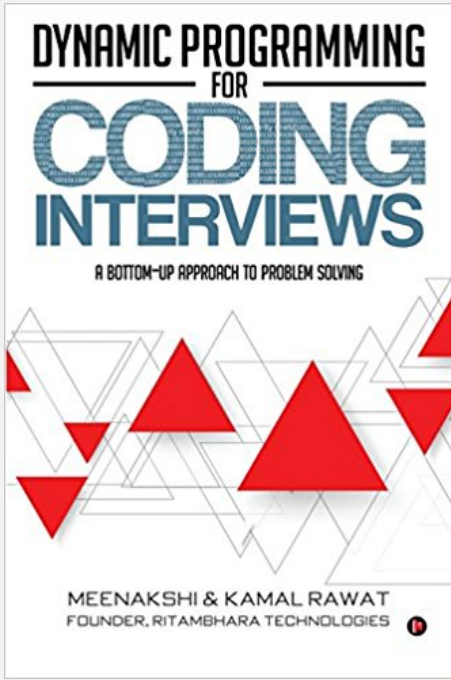
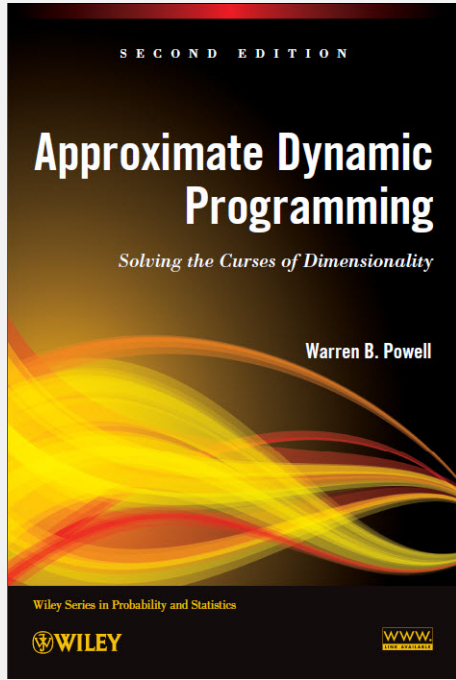
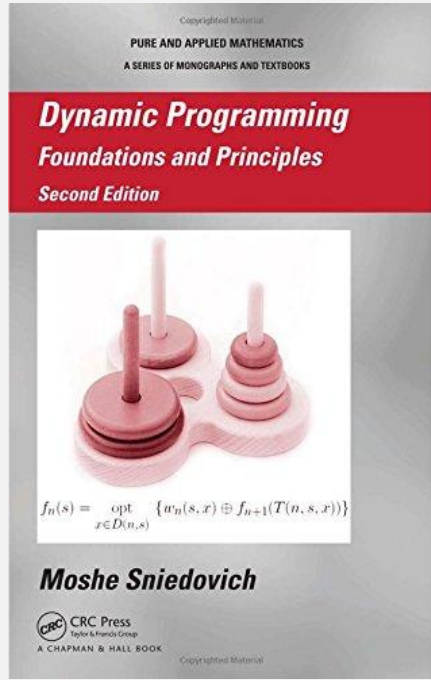
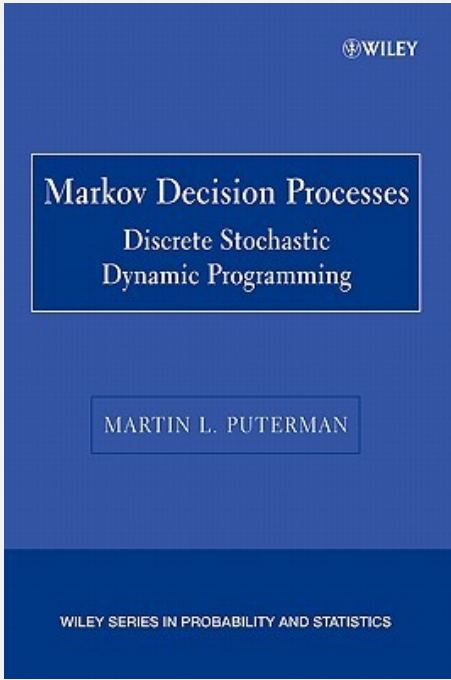
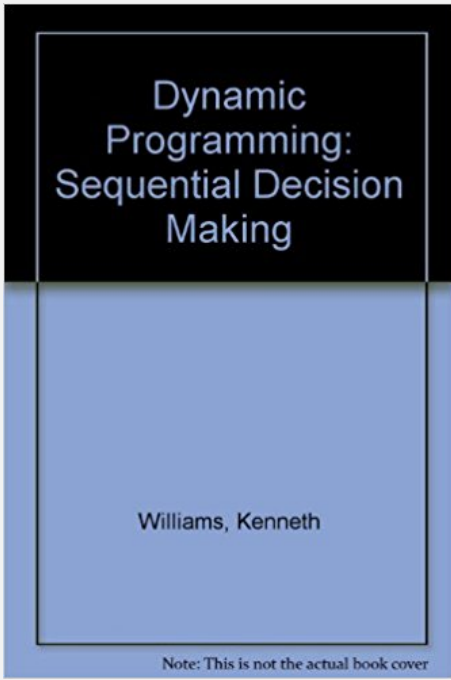
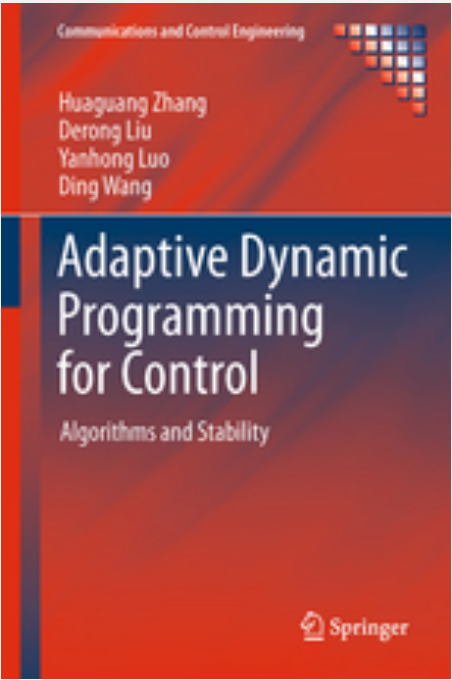
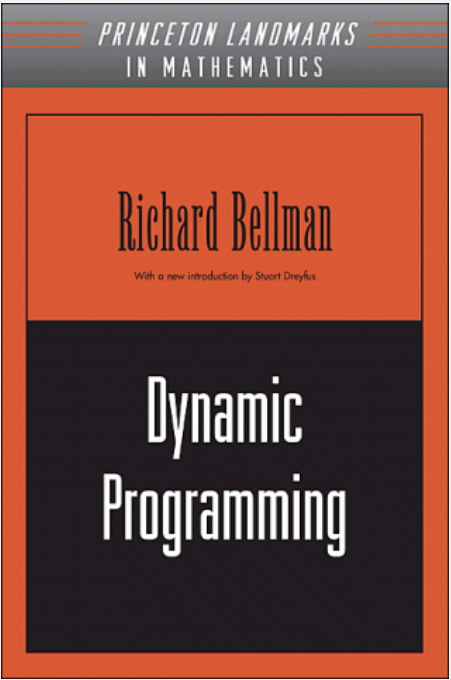
Dynamic programming algorithms

Some famous examples.

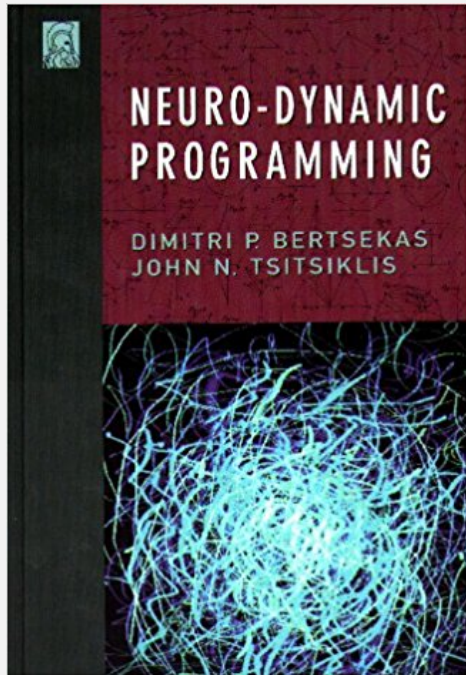
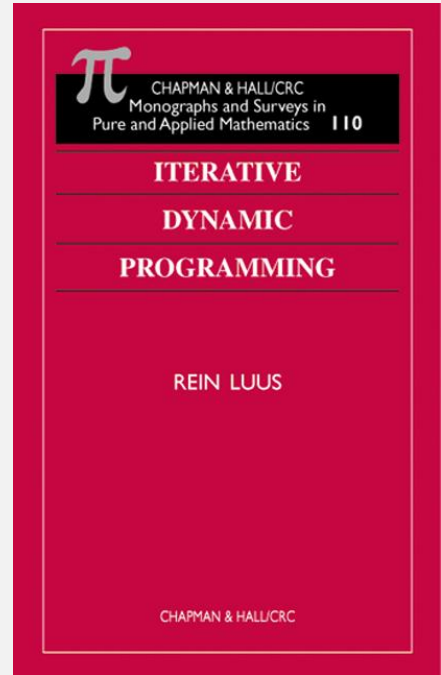
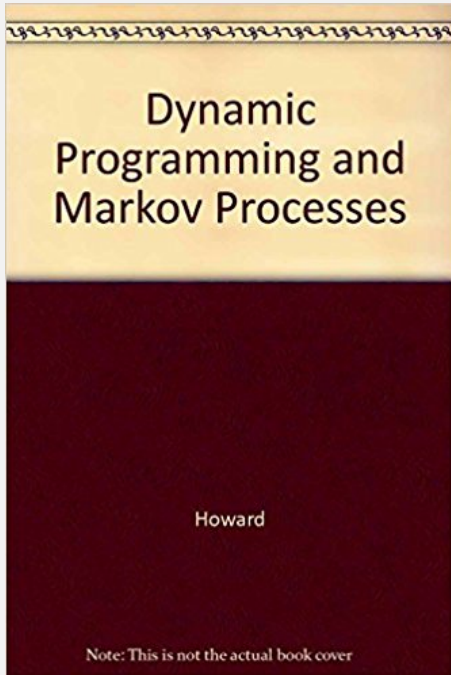
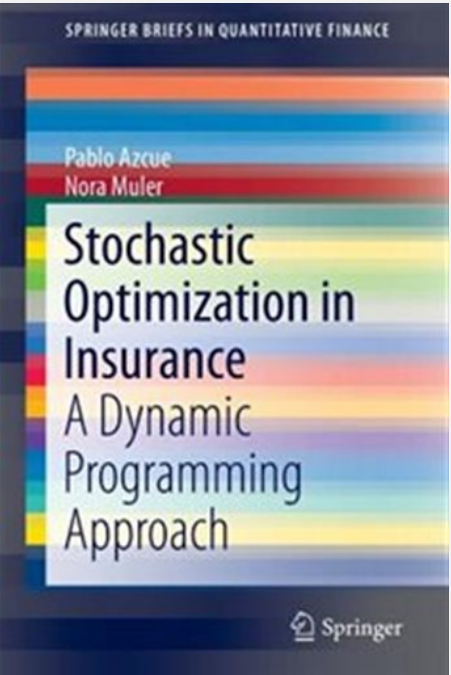
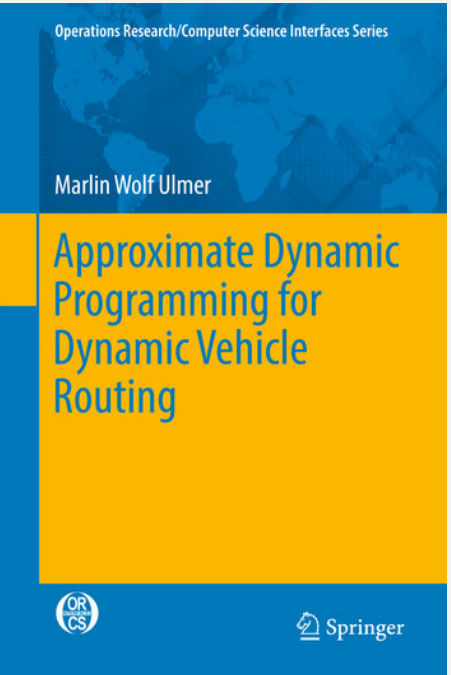
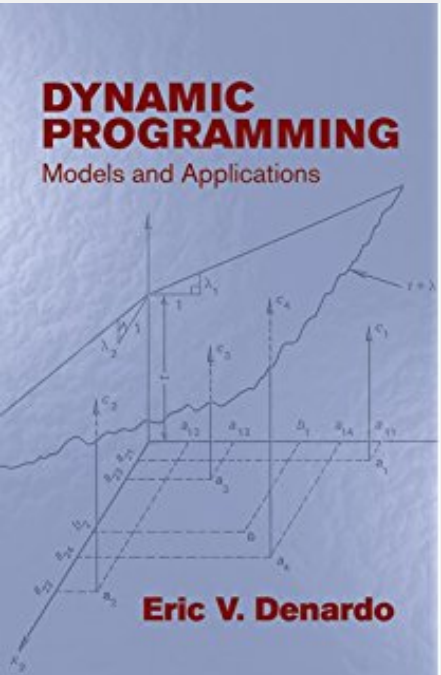
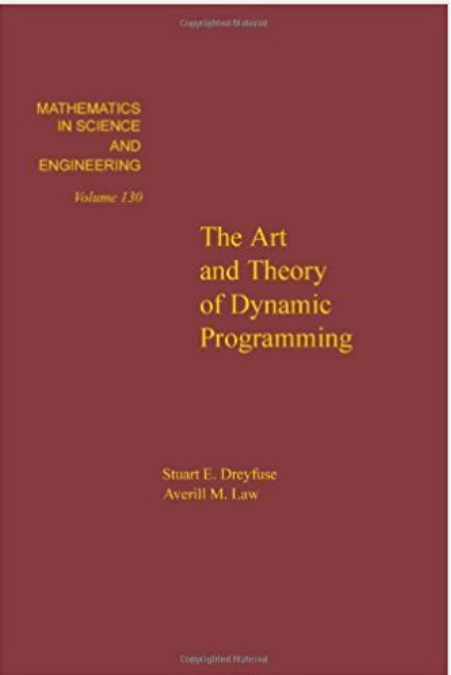
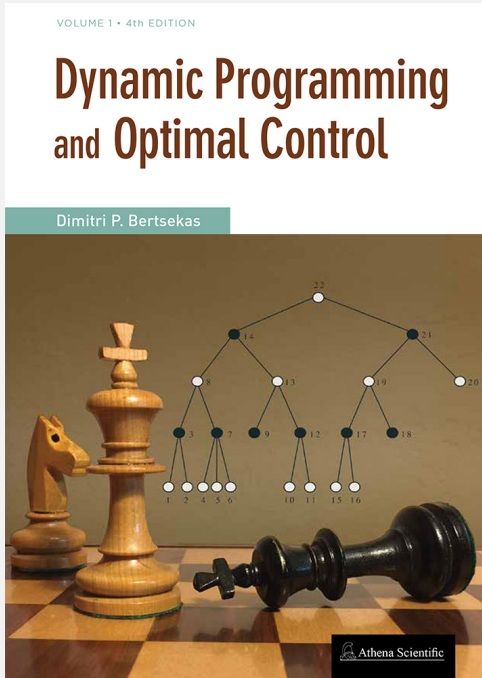
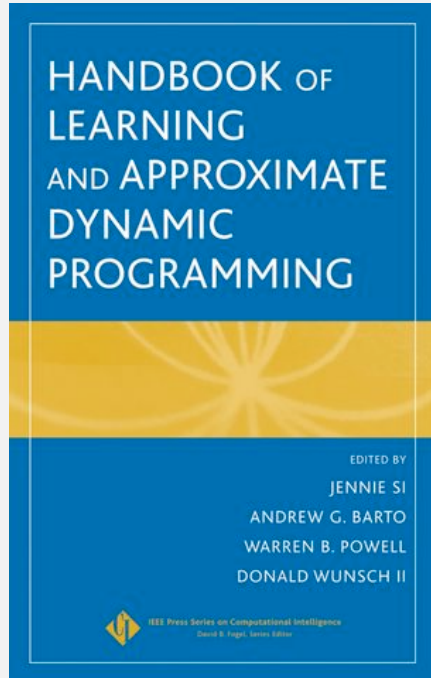
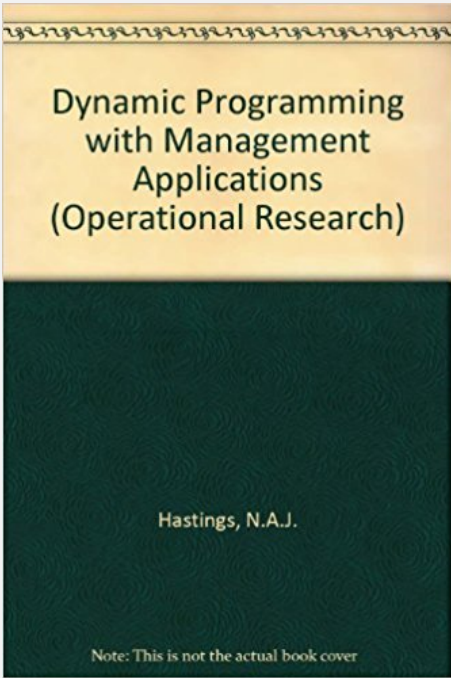
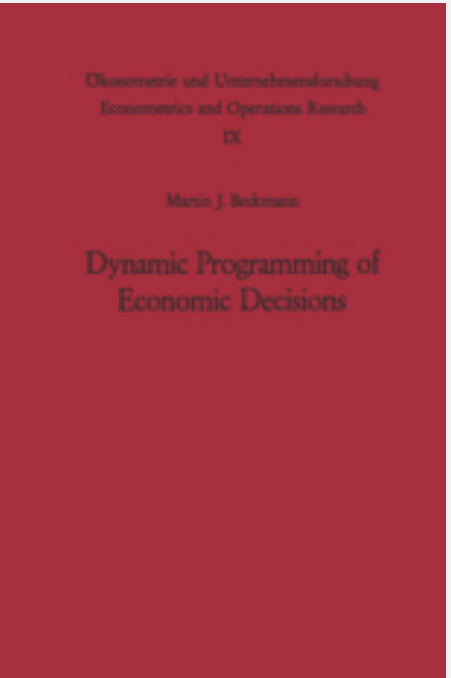
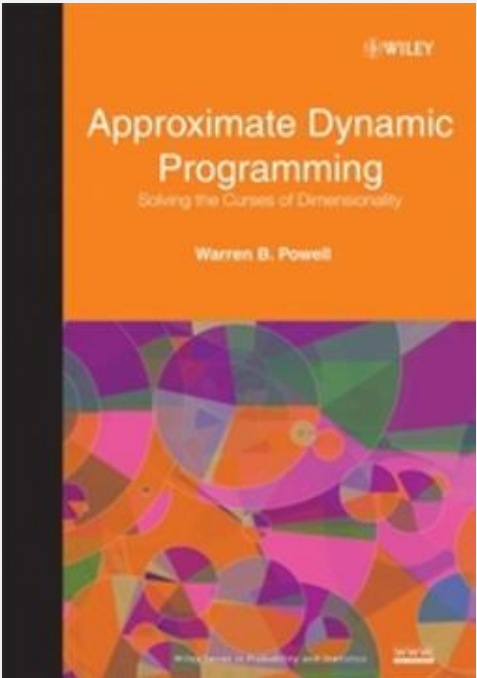
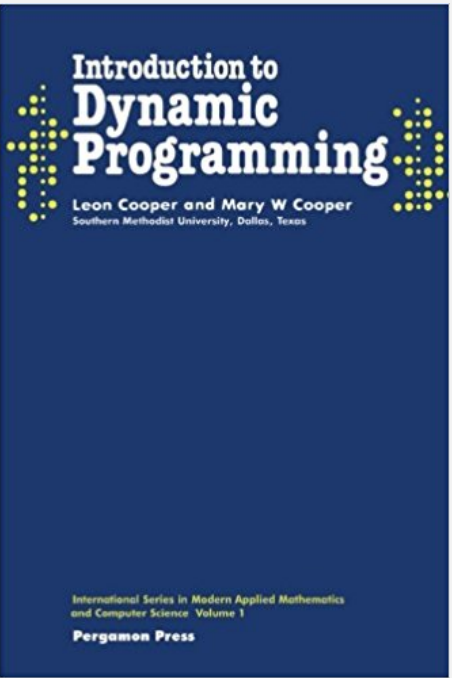
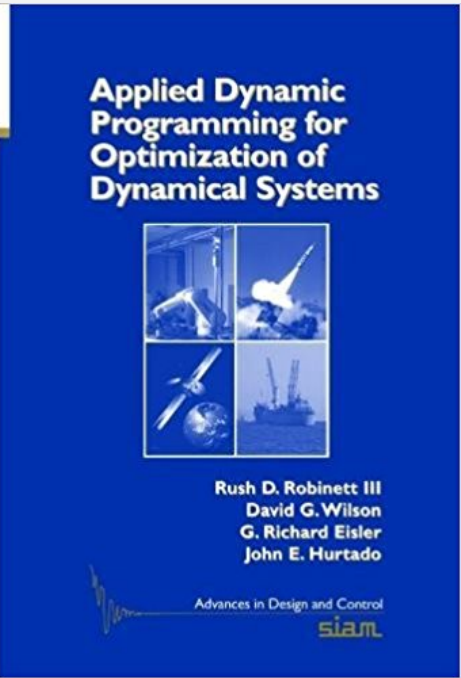
- System R algorithm for optimal join order in relational databases.
- Needleman–Wunsch/Smith–Waterman for sequence alignment.
- Cocke–Kasami–Younger for parsing context-free grammars.
- Bellman–Ford–Moore for shortest path.
- De Boor for evaluating spline curves.
- Viterbi for hidden Markov models.
- Unix diff for comparing two files.
- Avidan–Shamir for seam carving. ← see Assignment 6
- **NP**-complete graph problems on trees (vertex color, vertex cover, independent set, ...).
- ...

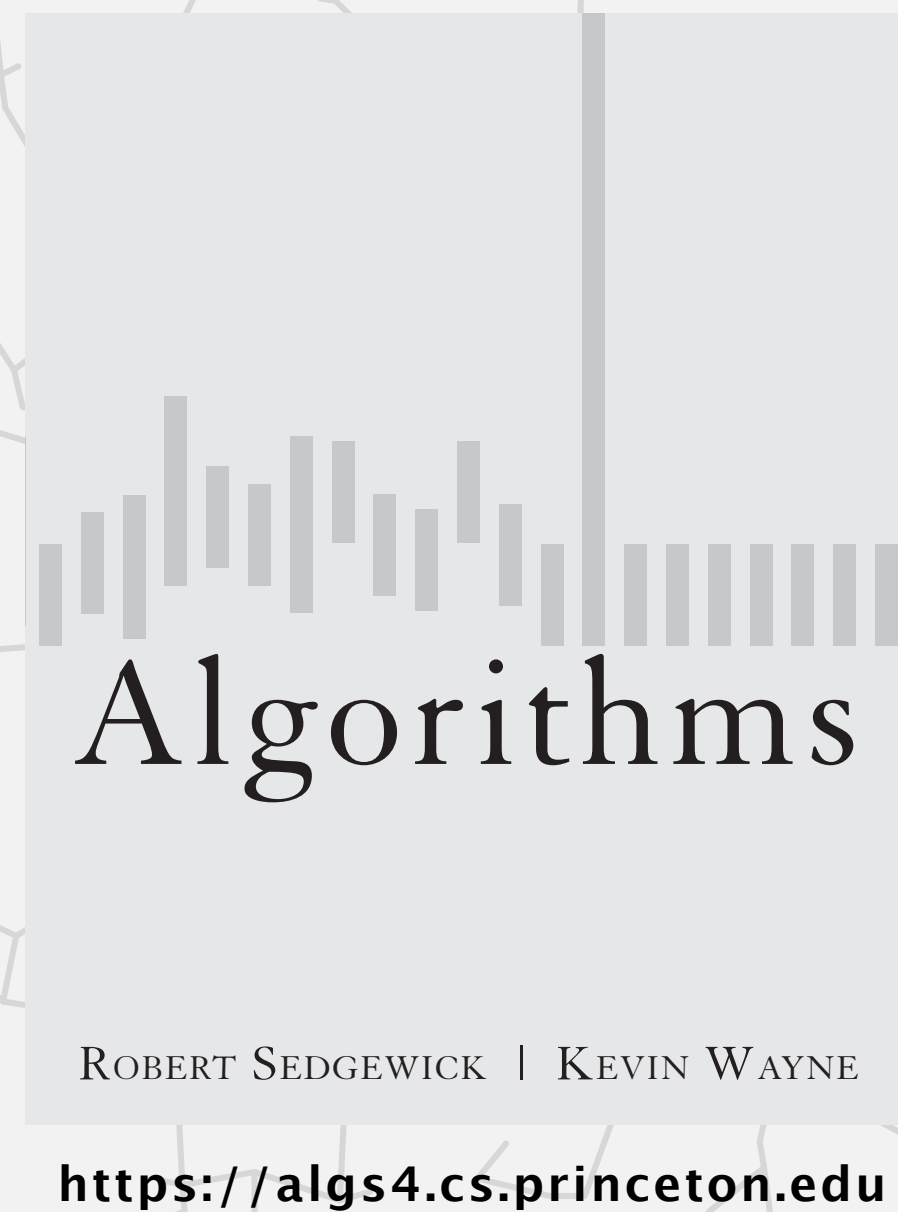


Dynamic programming books



pp. 284–289





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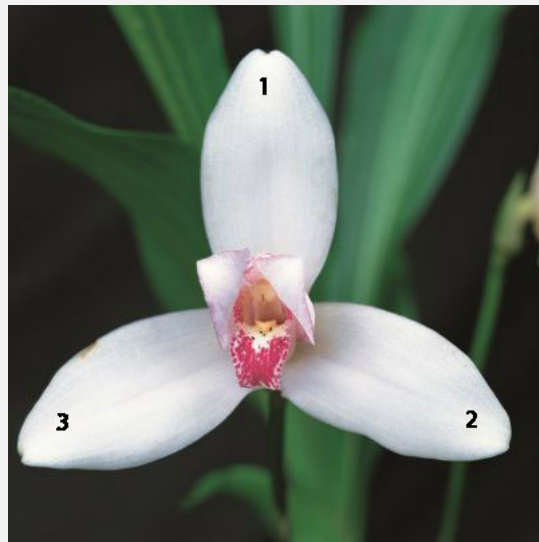
Fibonacci numbers

Fibonacci numbers. 0, 1, 1, 2, 3, 5, 8, 13, 21, 34, 55, 89, ...

$$F_i = \begin{cases} 0 & \text{if } i = 0 \\ 1 & \text{if } i = 1 \\ F_{i-1} + F_{i-2} & \text{if } i > 1 \end{cases}$$



Leonardo Fibonacci



3



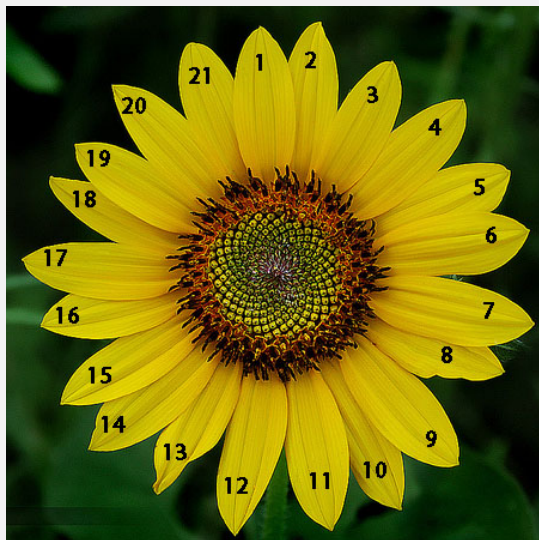
5



8



13



21



34



55



89

Fibonacci numbers: naïve recursive approach

Fibonacci numbers. 0, 1, 1, 2, 3, 5, 8, 13, 21, 34, 55, 89, ...

$$F_i = \begin{cases} 0 & \text{if } i = 0 \\ 1 & \text{if } i = 1 \\ F_{i-1} + F_{i-2} & \text{if } i > 1 \end{cases}$$

Goal. Given n , compute F_n .

Naïve recursive approach:

```
public static long fib(int i)
{
    if (i == 0) return 0;
    if (i == 1) return 1;
    return fib(i-1) + fib(i-2);
}
```



How long to compute $\text{fib}(80)$ using the naïve recursive algorithm?

- A.** Less than 1 second.
- B.** About 1 minute.
- C.** More than 1 hour.
- D.** Overflows a 64-bit long integer.

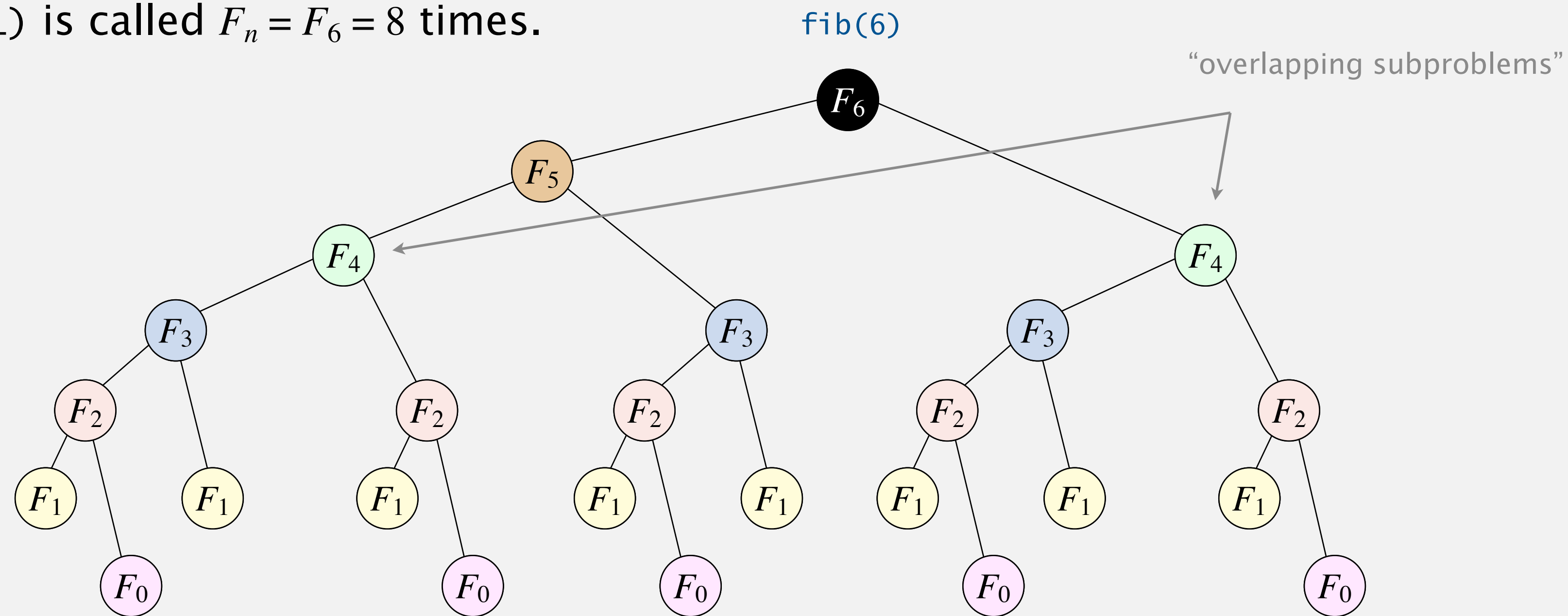
Fibonacci numbers: recursion tree and exponential growth

Exponential waste. Same **overlapping subproblems** are solved repeatedly.

Ex. To compute `fib(6)`:

- `fib(5)` is called 1 time.
- `fib(4)` is called 2 times.
- `fib(3)` is called 3 times.
- `fib(2)` is called 5 times.
- `fib(1)` is called $F_n = F_6 = 8$ times.

$$F_n \sim \phi^n, \quad \phi = \frac{1 + \sqrt{5}}{2} \approx 1.618$$



running time = # subproblems $\times$ cost per subproblem

Fibonacci numbers: top-down dynamic programming

Memoization.

- Maintain an **array** (or **symbol table**) to remember all computed values.
- If value to compute is known, just return it;
otherwise, compute it; remember it; and return it.

```
public static long fib(int i)
{
    if (i == 0) return 0;
    if (i == 1) return 1;
    if (f[i] == 0) f[i] = fib(i-1) + fib(i-2);
    return f[i];
}
```

assume global long array f[], initialized to 0 (unknown)

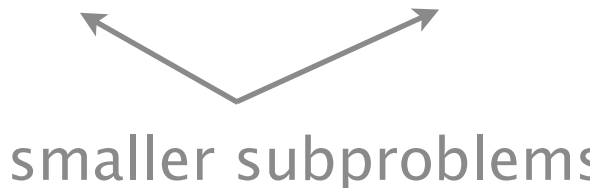
Impact. Solves each subproblem F_i only once; $\Theta(n)$ time to compute F_n .

Fibonacci numbers: bottom-up dynamic programming

Bottom-up dynamic programming.

- Build computation from the “bottom up.”
- Solve small subproblems and save solutions.
- Use those solutions to solve larger subproblems.

```
public static long fib(int n)
{
    long[] f = new long[n+1];
    f[0] = 0;
    f[1] = 1;
    for (int i = 2; i <= n; i++)
        f[i] = f[i-1] + f[i-2];
    return f[n];
}
```



Impact. Solves each subproblem F_i only once; $\Theta(n)$ time to compute F_n ; no recursion.

Fibonacci numbers: further improvements

Performance improvements.

- Save space by saving only two most recent Fibonacci numbers.

```
public static long fib(int n) {  
    int f = 0, g = 1;  
    for (int i = 0; i < n; i++) {  
        g = f + g;  
        f = g - f;  
    }  
    return f;  
}
```

← f and g are consecutive
Fibonacci numbers

- Exploit additional properties of problem:

$$F_n = \left\lfloor \frac{\phi^n}{\sqrt{5}} \right\rfloor, \quad \phi = \frac{1 + \sqrt{5}}{2}$$

$$\begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}^n = \begin{pmatrix} F_{n+1} & F_n \\ F_n & F_{n-1} \end{pmatrix}$$

Dynamic programming recap

Dynamic programming.

- Divide a complex problem into a number of simpler **overlapping subproblems**.
[define $n + 1$ subproblems, where subproblem i is computing the i^{th} Fibonacci number]
- Define a **recurrence relation** to solve larger subproblems from smaller subproblems.
[easy to solve subproblem i if we know solutions to subproblems $i - 1$ and $i - 2$]

$$F_i = \begin{cases} 0 & \text{if } i = 0 \\ 1 & \text{if } i = 1 \\ F_{i-1} + F_{i-2} & \text{if } i > 1 \end{cases}$$

- **Store solutions** to each of these subproblems, solving each subproblem only once.
[use an array, storing subproblem i in $f[i]$]
- Use stored solutions to solve the original problem.
[subproblem n is original problem]

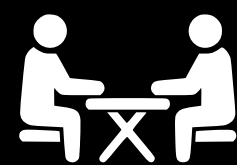


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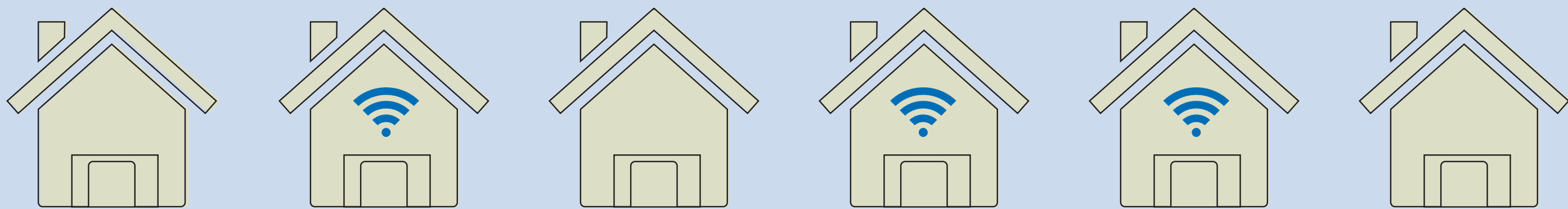
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ROUTER INSTALLATION PROBLEM



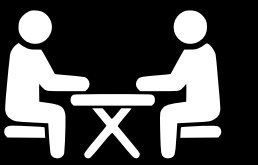
- Goal. Install WiFi routers in a row of n houses so that:
- Minimize total cost, where $cost(i)$ = cost to install a router at house i .
 - Requirement: no two consecutive houses without a router.



i	1	2	3	4	5	6
$cost(i)$	1	4	12	8	9	11

cost to install router at house i
(4 + 8 + 9 = 21)

ROUTER INSTALLATION PROBLEM: DYNAMIC PROGRAMMING FORMULATION



Goal. Install WiFi routers in a row of n houses so that:

- Minimize total cost, where $cost(i)$ = cost to install a router at house i .
- Requirement: no two consecutive houses without a router.

Subproblems.

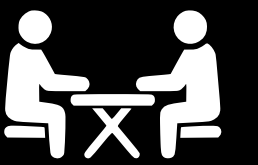
- $yes(i)$ = min cost to install router at houses $1, \dots, i$ **with router at i .**
- $no(i)$ = min cost to install router at houses $1, \dots, i$ **with no router at i .**
- Optimal cost = $\min \{ yes(n), no(n) \}$.

Dynamic programming recurrence.

- $yes(0) = no(0) = 0$
- $yes(i) = cost(i) + \min \{ yes(i-1), no(i-1) \}$
- $no(i) = yes(i-1)$

← “optimal substructure”
(optimal solution can be constructed from
optimal solutions to smaller subproblems)

ROUTER INSTALLATION: NAÏVE RECURSIVE IMPLEMENTATION



A mutually recursive implementation.

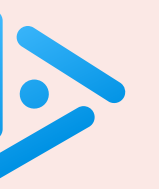
```
private int yes(int i)
{
    if (i == 0) return 0;
    return cost[i] + Math.min(yes(i-1), no(i-1));
}

private int no(int i)
{
    if (i == 0) return 0;
    return yes(i-1);
}

public int minCost()
{
    return Math.min(yes(n), no(n));
}
```

← $yes(i) = cost(i) + \min \{ yes(i-1), no(i-1) \}$

← $no(i) = yes(i-1)$



What is running time of the naïve recursive algorithm as a function of n ?

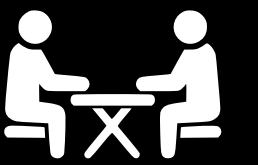
- A. $\Theta(n)$
- B. $\Theta(n^2)$
- C. $\Theta(c^n)$ for some $c > 1$.
- D. $\Theta(n!)$

*“ Those who cannot remember the
past are condemned to repeat it. ”*

— Dynamic Programming

(Jorge Agustín Nicolás Ruiz de Santayana y Borrás)

ROUTER INSTALLATION: BOTTOM-UP IMPLEMENTATION



Bottom-up DP implementation.

```
int[] yes = new int[n+1];
int[] no  = new int[n+1];

for (int i = 1; i <= n; i++)
{
    yes[i] = cost[i] + Math.min(yes[i-1], no[i-1]);
    no[i]  = yes[i-1];
}

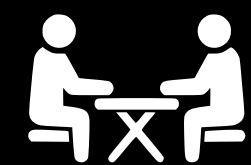
return Math.min(yes[n], no[n]);
```

$yes(i) = cost(i) + \min \{ yes(i-1), no(i-1) \}$
 $no(i) = yes(i-1)$

Proposition. Takes $\Theta(n)$ time and uses $\Theta(n)$ extra space.

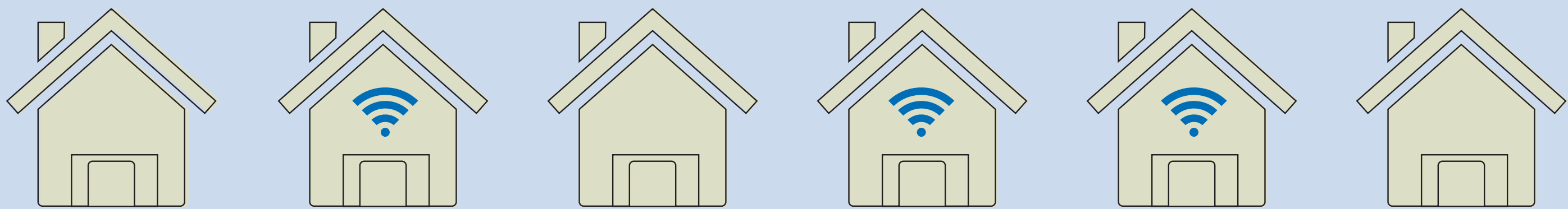
Remark. Could eliminate the `no[]` array by substituting identity `no[k] = yes[k-1]`.

ROUTER INSTALLATION: RECONSTRUCTING THE SOLUTION (BACKTRACE)



So far: we've computed the **value** of the optimal solution.

Still need: the **solution** itself (where to install routers).

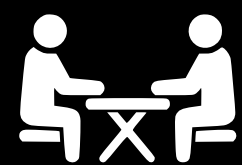


<i>i</i>	0	1	2	3	4	5	6
<i>yes(i)</i>	0	1	4	13	12	21	23
<i>no(i)</i>	0	0	1	4	13	12	21

$yes(i)$ = cost to install routers at houses 1, 2, ..., i with router at house i

$no(i)$ = cost to install routers at houses 1, 2, ..., i with router not at house i

COIN CHANGING



Problem. Given n coin denominations $\{ d_1, d_2, \dots, d_n \}$ and a target value V , find the fewest coins needed to make change for V (or report impossible).

Ex. Coin denominations = $\{1, 10, 25, 100\}$, $V = 130$.

Greedy (8 coins). $131¢ = 100 + 25 + 1 + 1 + 1 + 1 + 1 + 1$.

Optimal (5 coins). $131¢ = 100 + 10 + 10 + 10 + 1$.



8 coins
(131¢)



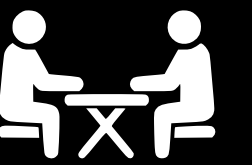
5 coins
(131¢)



vending machine
(out of nickels)

Remark. Greedy algorithm is optimal for U.S. coin denominations $\{1, 5, 10, 25, 100\}$.

COIN CHANGING: DYNAMIC PROGRAMMING FORMULATION



Problem. Given n coin denominations $\{d_1, d_2, \dots, d_n\}$ and a target value V , find the fewest coins needed to make change for V (or report impossible).

Subproblems. $OPT(v)$ = fewest coins needed to make change for amount v .

Optimal value. $OPT(V)$.

Multiway choice. To compute $OPT(v)$,

- Select a coin of denomination $d_i \leq v$ for some i .
- Use fewest coins to make change for $v - d_i$.

← take best

← optimal substructure

Dynamic programming recurrence.

$$OPT(v) = \begin{cases} 0 & \text{if } v = 0 \\ \min_{i : d_i \leq v} \{ 1 + OPT(v - d_i) \} & \text{if } v > 0 \end{cases}$$



In which order to compute $OPT(v)$ in bottom-up DP ?

A. Increasing i . ←

B. Decreasing i . ←

C. Either A or B.

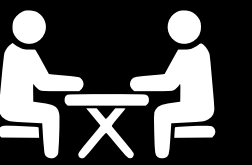
D. Neither A nor B.

```
for (int v = 1; v <= V; v++)  
    opt[v] = ...
```

```
for (int v = V; v >= 1; v--)  
    opt[v] = ...
```

$$OPT(v) = \begin{cases} 0 & \text{if } v = 0 \\ \min_{i : d_i \leq v} \{ 1 + OPT(v - d_i) \} & \text{if } v > 0 \end{cases}$$

COIN CHANGING: BOTTOM-UP IMPLEMENTATION



Bottom-up DP implementation.

```
int[] opt = new int[V+1];
opt[0] = 0;

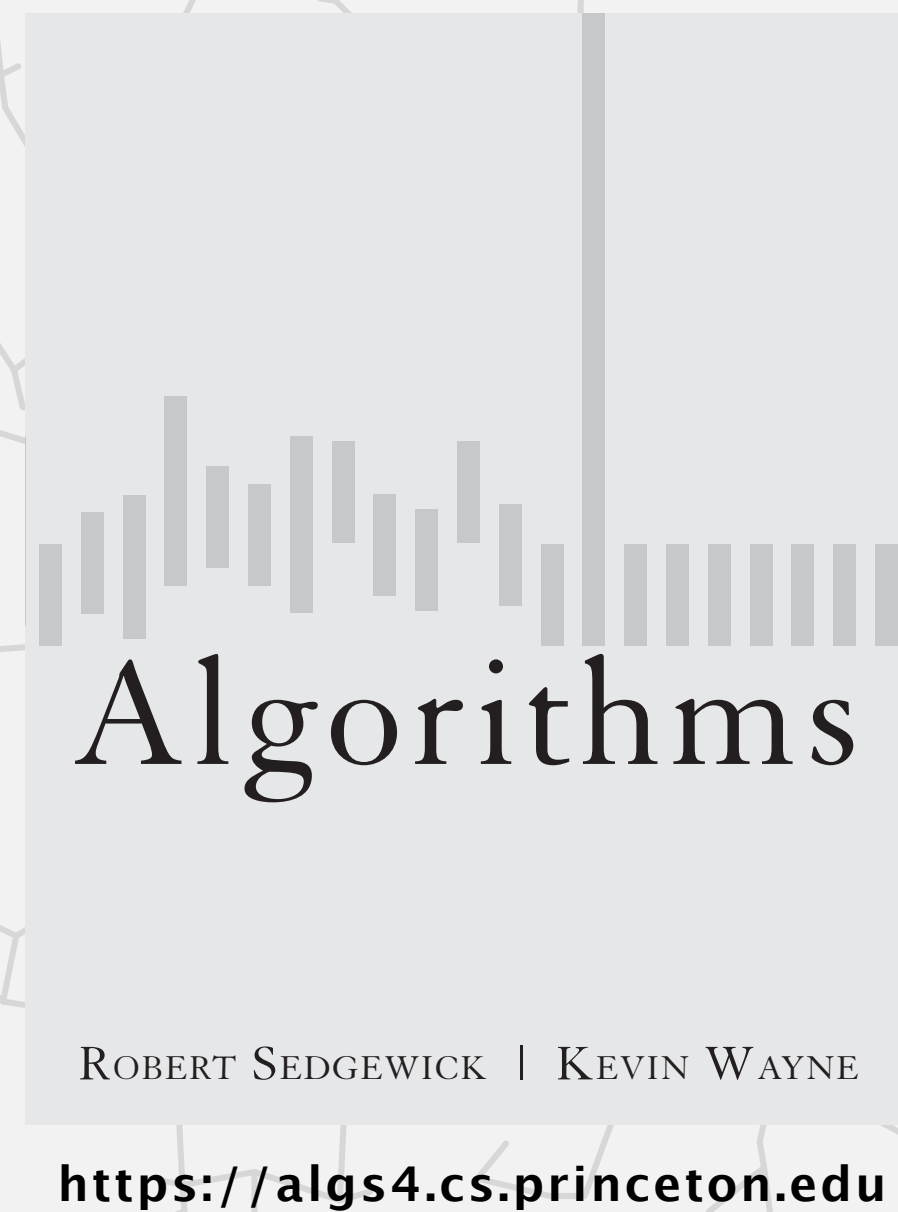
for (int v = 1; v <= V; v++)
{
    // opt[v] = min_i { 1 + opt[v - d[i]] }
    opt[v] = INFINITY;
    for (int i = 1; i <= n; i++)
        if (d[i] <= v)
            opt[v] = Math.min(opt[v], 1 + opt[v - d[i]]);
}
```

$$OPT(v) = \begin{cases} 0 & \text{if } v = 0 \\ \min_{i : d_i \leq v} \{ 1 + OPT(v - d_i) \} & \text{if } v > 0 \end{cases}$$

Proposition. DP algorithm takes $\Theta(n V)$ time and uses $\Theta(V)$ extra space.

Note. Not polynomial in input size; underlying problem is **NP**-complete.

$\nearrow$
 $n, \log V$



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Shortest paths in directed acyclic graphs: dynamic programming formulation

Problem. Given a DAG with positive edge weights, find shortest path from s to t .

Subproblems. $distTo(v)$ = length of shortest $s \rightsquigarrow v$ path.

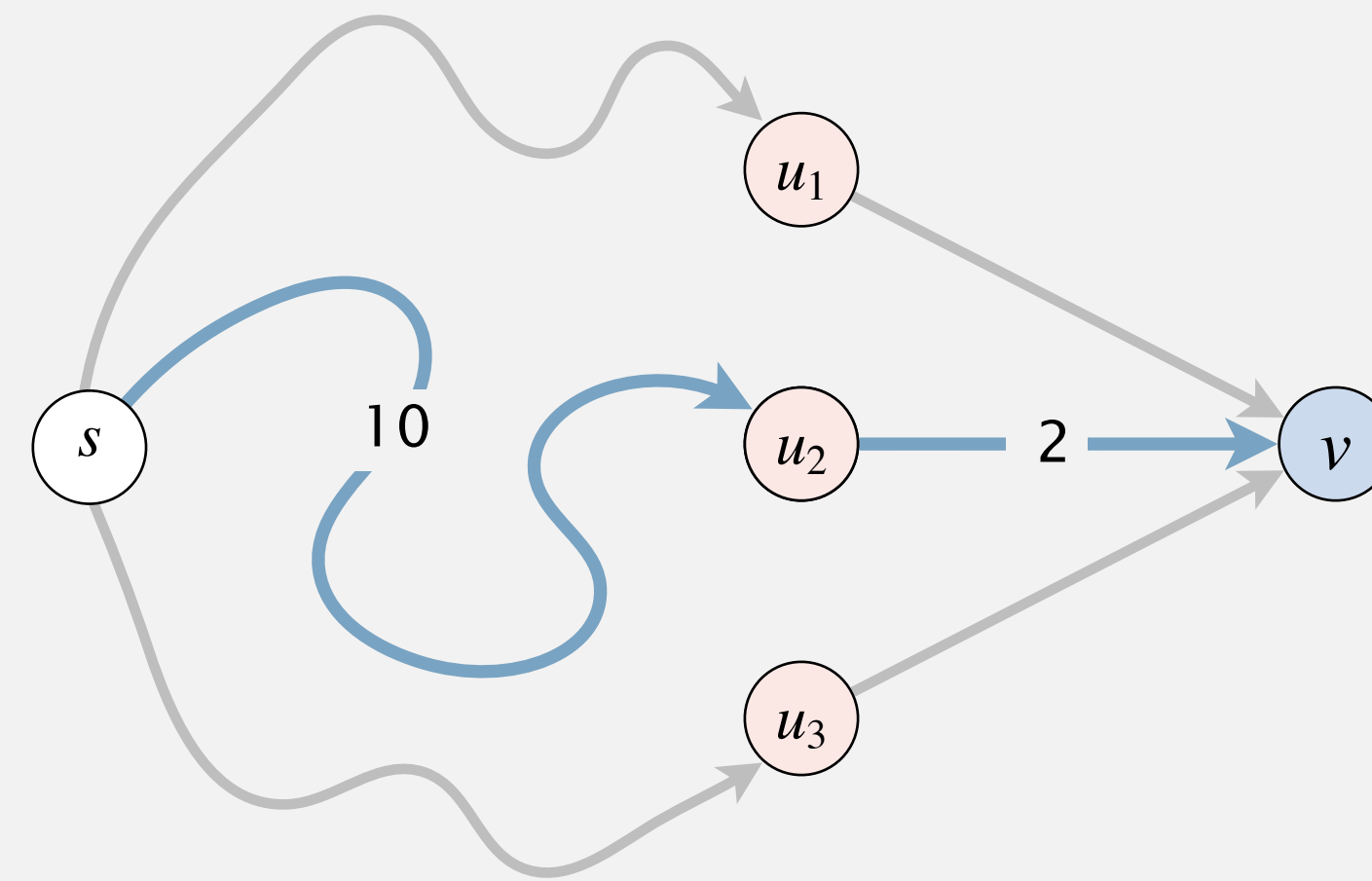
Goal. $distTo(t)$.

Multiway choice. To compute $distTo(v)$:

- Select an edge $e = u \rightarrow v$ entering v .
- Combine with shortest $s \rightsquigarrow u$ path.

↑
optimal substructure

← take best



Dynamic programming recurrence.

$$distTo(v) = \begin{cases} 0 & \text{if } v = s \\ \min_{e = u \rightarrow v} \{ distTo(u) + weight(e) \} & \text{if } v \neq s \end{cases}$$

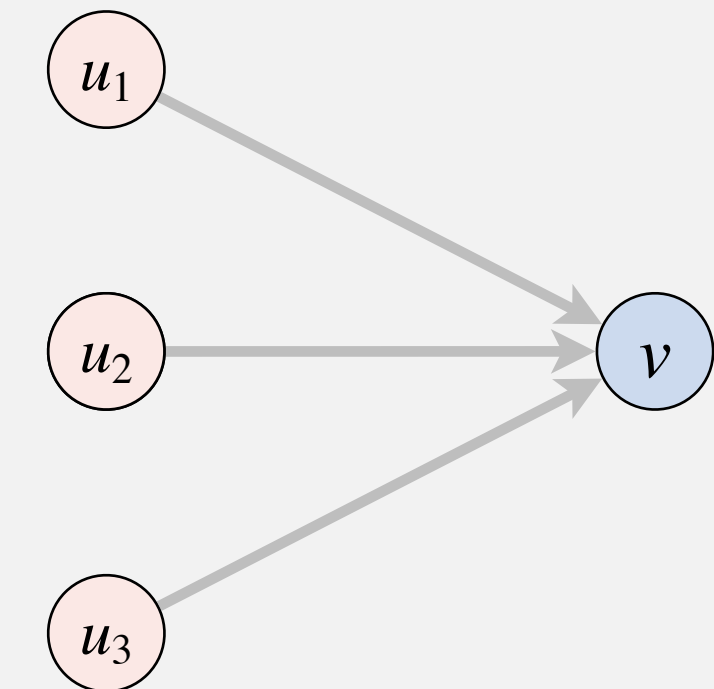
Shortest paths in directed acyclic graphs: bottom-up solution

Bottom-up DP algorithm. Takes $\Theta(E + V)$ time with two tricks:

- Solve subproblems in **topological order**. $\longleftarrow$ ensures that “small” subproblems are solved before “large” ones
- Form reverse digraph G^R (to support iterating over edges incident **to** vertex v).

Equivalent (but simpler) computation. Relax vertices in topological order.

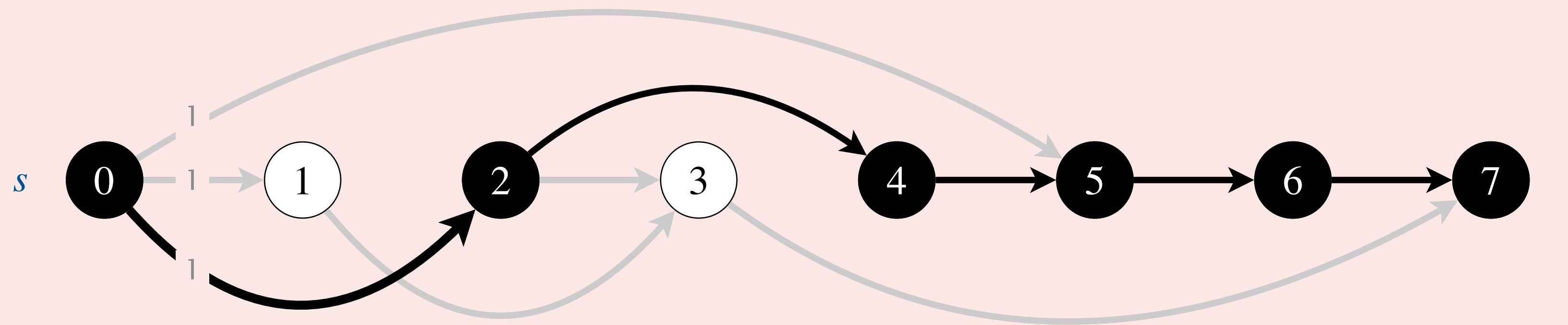
```
Topological topological = new Topological(G);  
for (int v : topological.order())  
    for (DirectedEdge e : G.adj(v))  
        relax(e);
```



Remark. Can find the shortest paths themselves by maintaining edgeTo[] array.



Given a DAG, how to find **longest path** from s to t in $\Theta(E + V)$ time?



longest path from s to t in a DAG (all edge weights = 1)

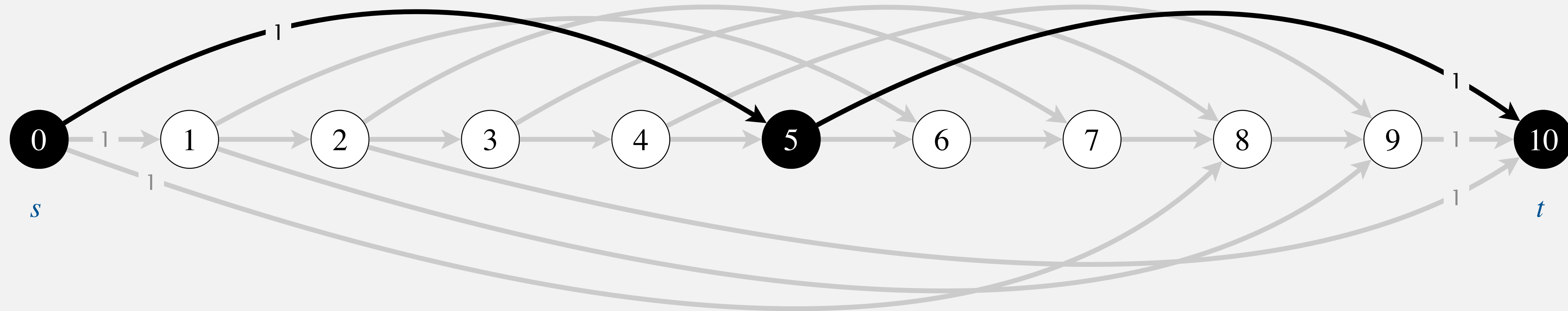
- A. Negate edge weights; use DP algorithm to find shortest path.
- B. Replace *min* with *max* in DP recurrence.
- C. Either A or B.
- D. No poly-time algorithm is known (**NP**-complete).

Shortest paths in DAGs and dynamic programming

DP subproblem dependency digraph.

- Vertex v for each subproblem v .
- Edge $v \rightarrow w$, if subproblem v must be solved before subproblem w .
- Digraph must be a DAG. Why?

Ex 1. Modeling the coin changing problem as a shortest path problem in a DAG.



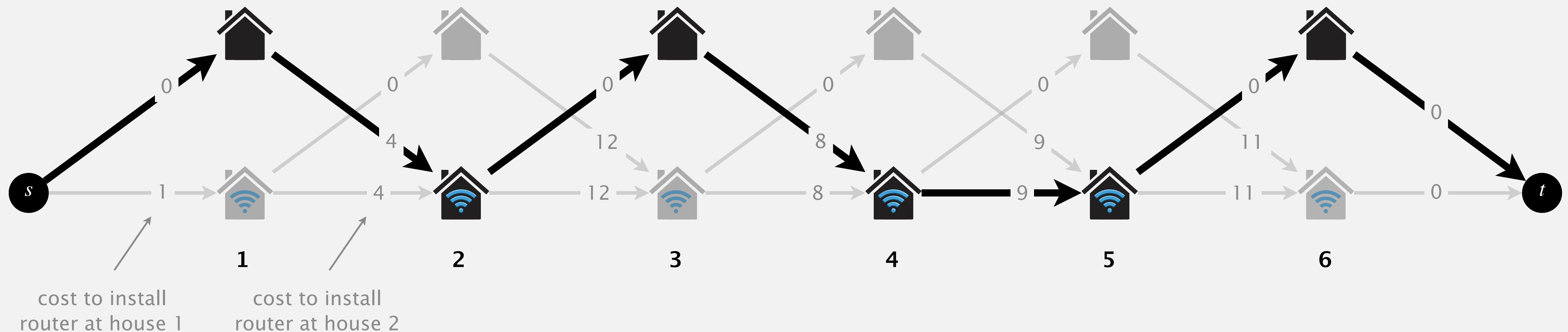
$V = 10$; coin denominations = $\{ 1, 5, 8 \}$

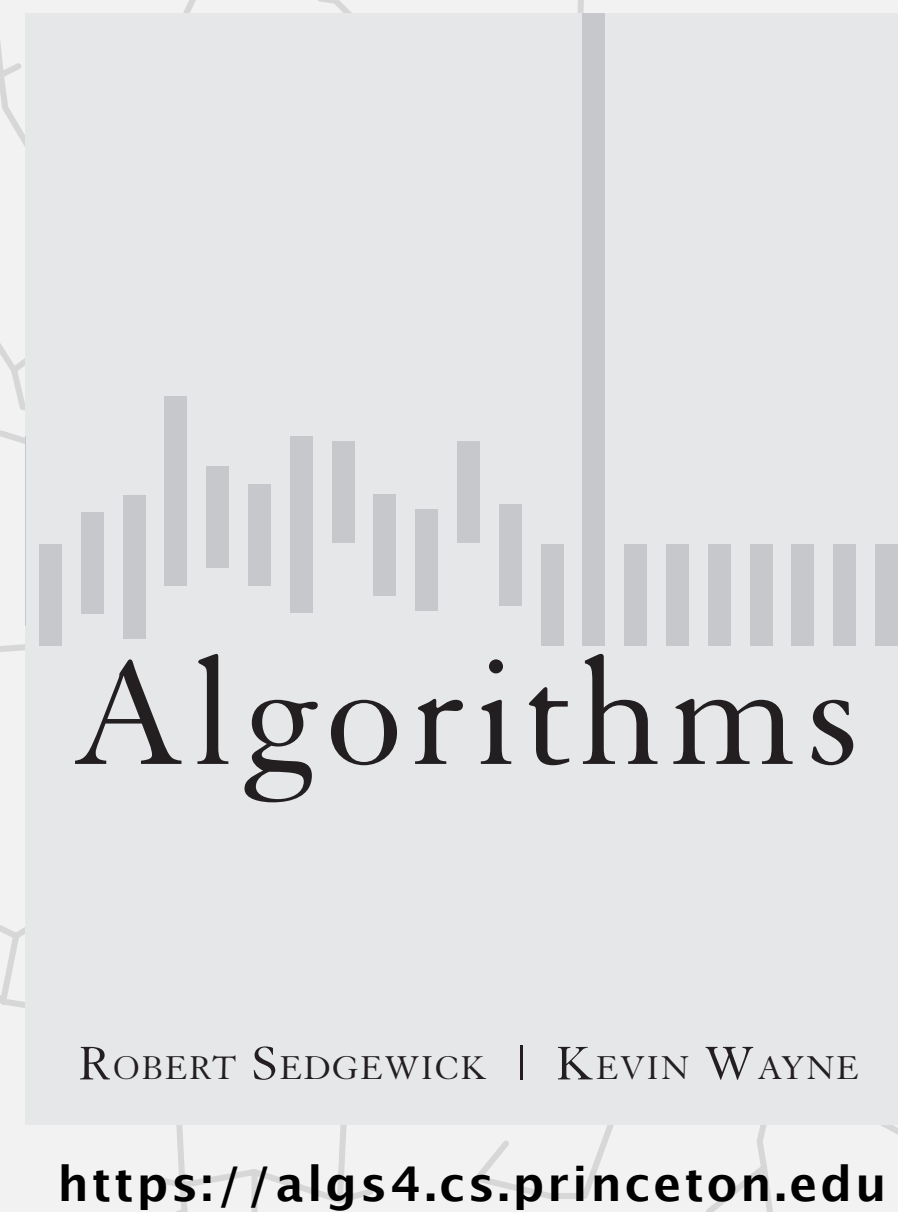
Shortest paths in DAGs and dynamic programming

DP subproblem dependency digraph.

- Vertex v for each subproblem v .
- Edge $v \rightarrow w$, if subproblem v must be solved before subproblem w .
- Digraph must be a DAG. Why?

Ex 2. Modeling the router installation problem as a shortest path problem in a DAG.





4.4 SHORTEST PATHS

- ▶ *introduction*
- ▶ *Fibonacci numbers*
- ▶ *interview problems*
- ▶ *shortest paths in DAGs*
- ▶ *seam carving*

Content-aware resizing

Seam carving. [Avidan–Shamir] Resize an image without distortion for display on cell phones and web browsers.



<https://www.youtube.com/watch?v=vIFCV2spKtg>

Content-aware resizing

Seam carving. [Avidan–Shamir] Resize an image without distortion for display on cell phones and web browsers.



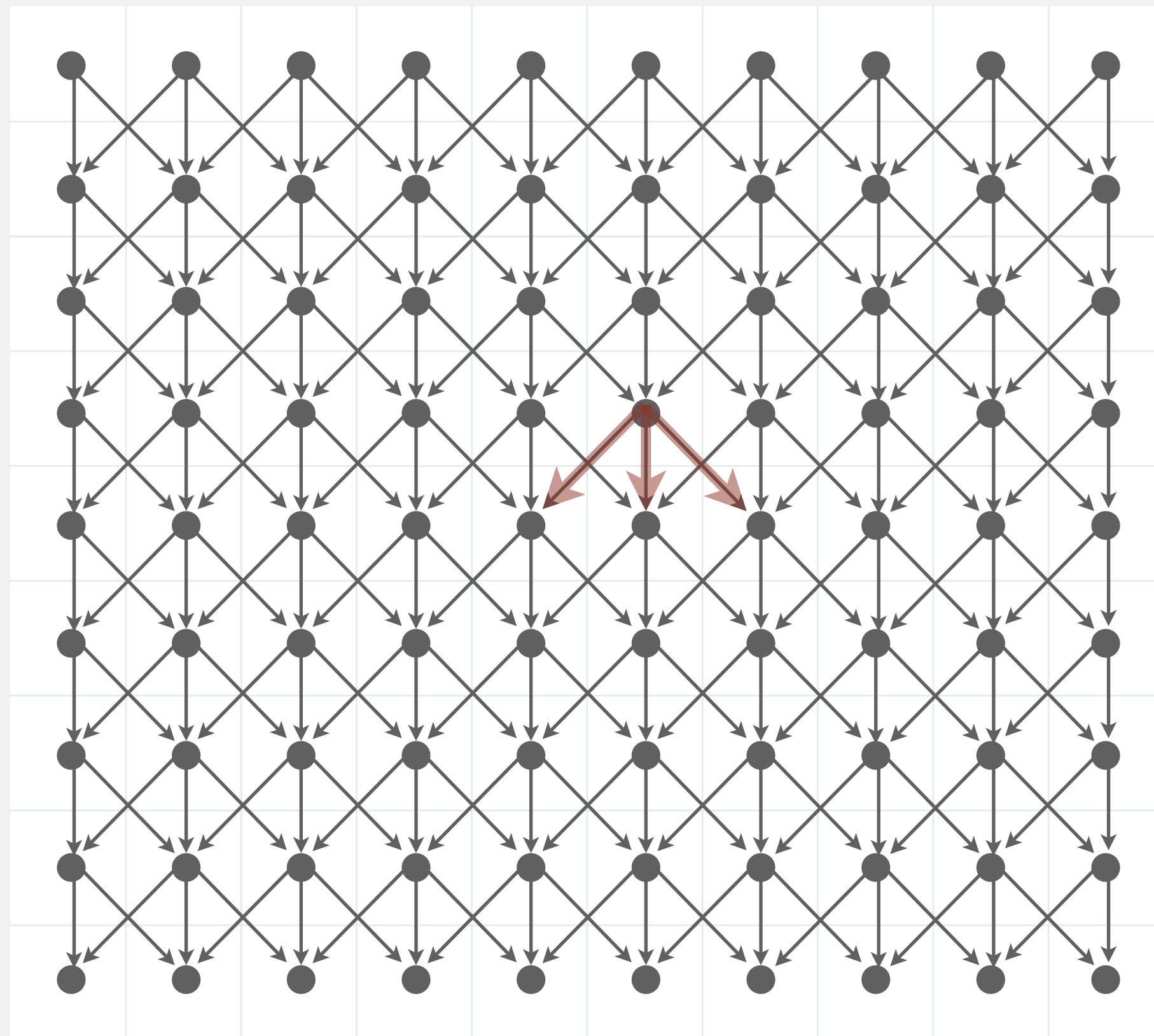
In the wild. Photoshop, ImageMagick, GIMP, ...



Content-aware resizing

To find vertical seam in a picture:

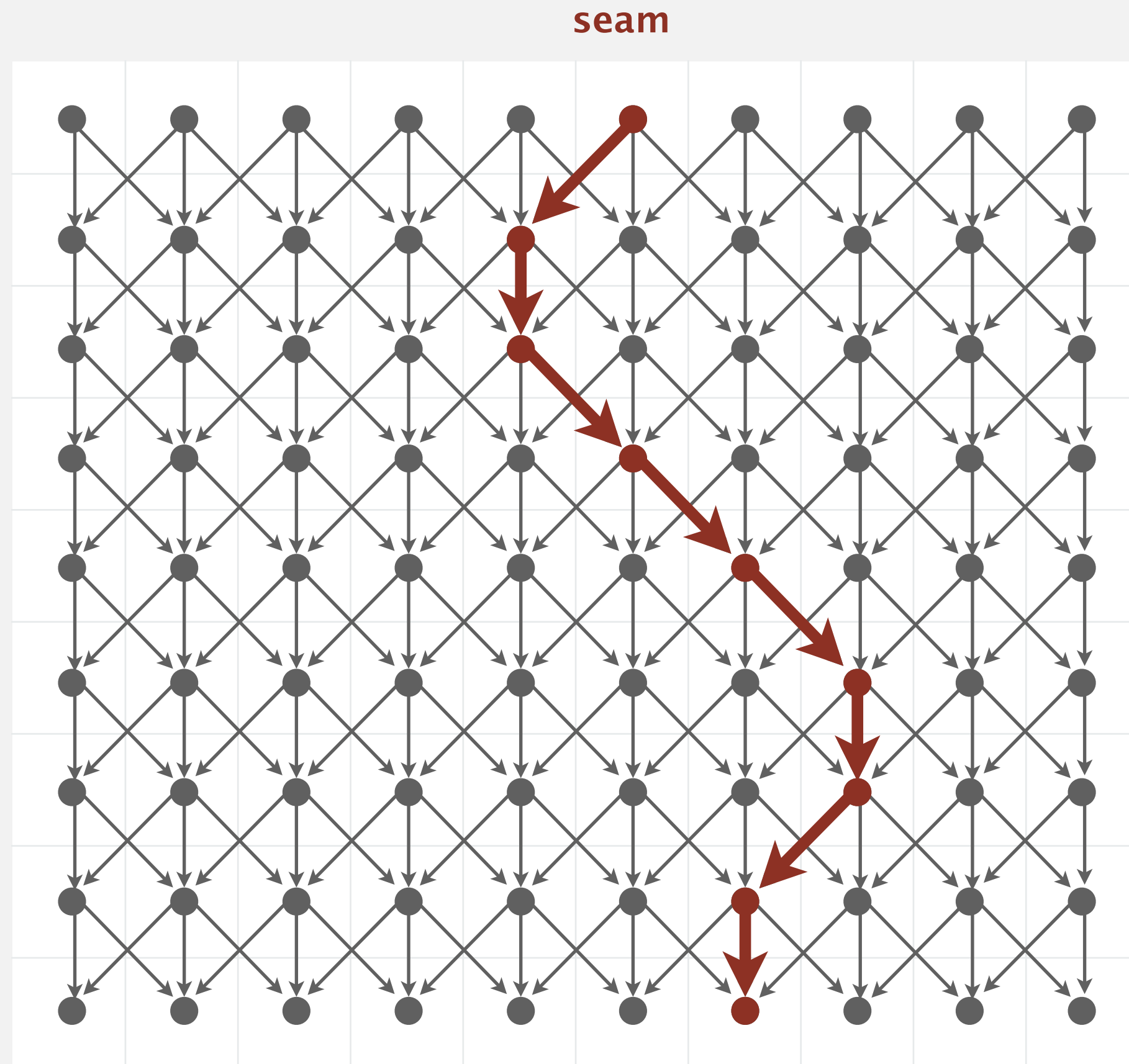
- Grid graph: vertex = pixel; edge = from pixel to 3 downward neighbors.
- Weight of pixel = “energy function” of 8 neighboring pixels.



Content-aware resizing

To find vertical seam in a picture:

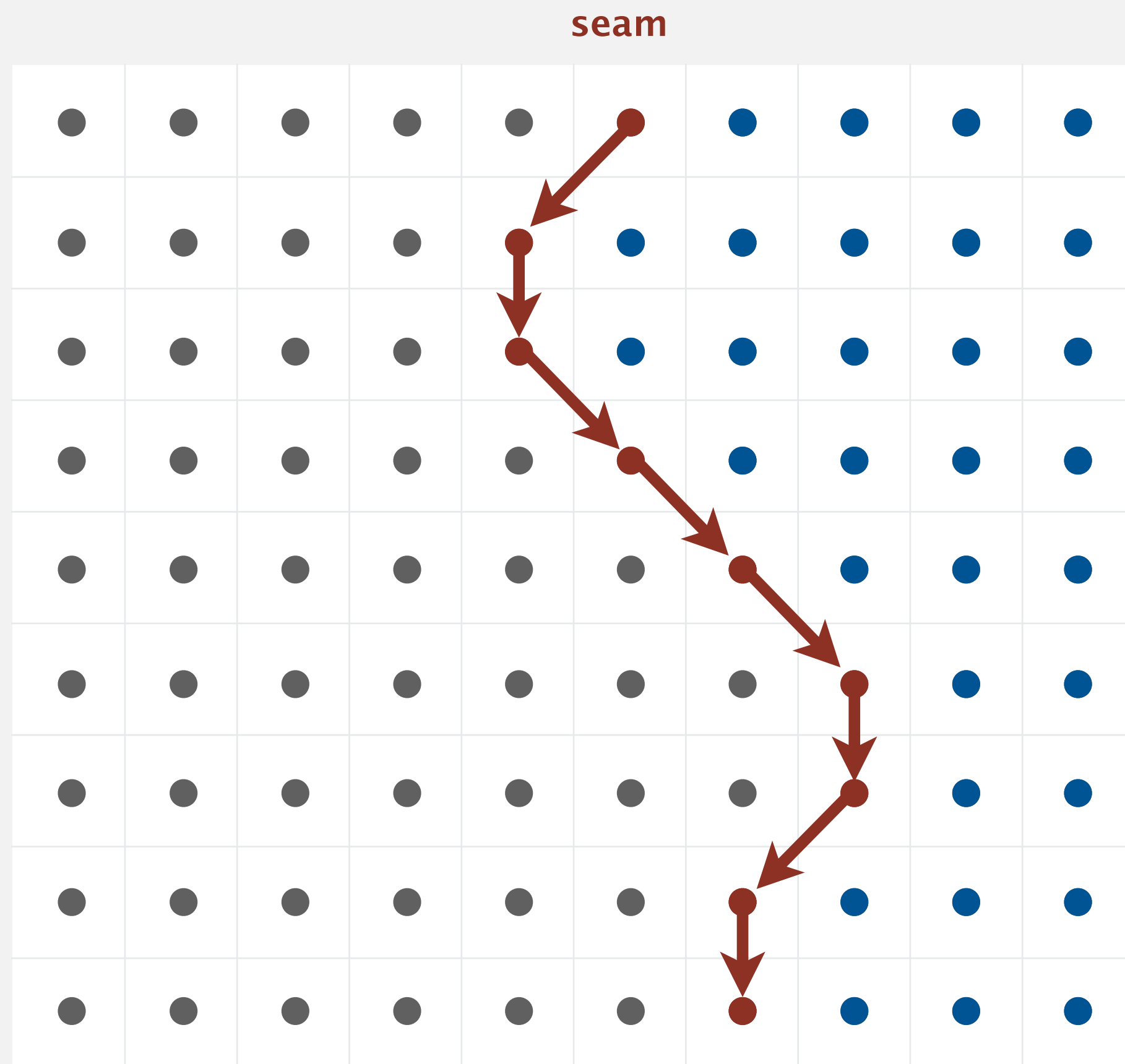
- Grid graph: vertex = pixel; edge = from pixel to 3 downward neighbors.
- Weight of pixel = “energy function” of 8 neighboring pixels.
- Seam = shortest path (sum of vertex weights) from top to bottom.



Content-aware resizing

To remove vertical seam in a picture:

- Delete pixels on seam (one in each row).

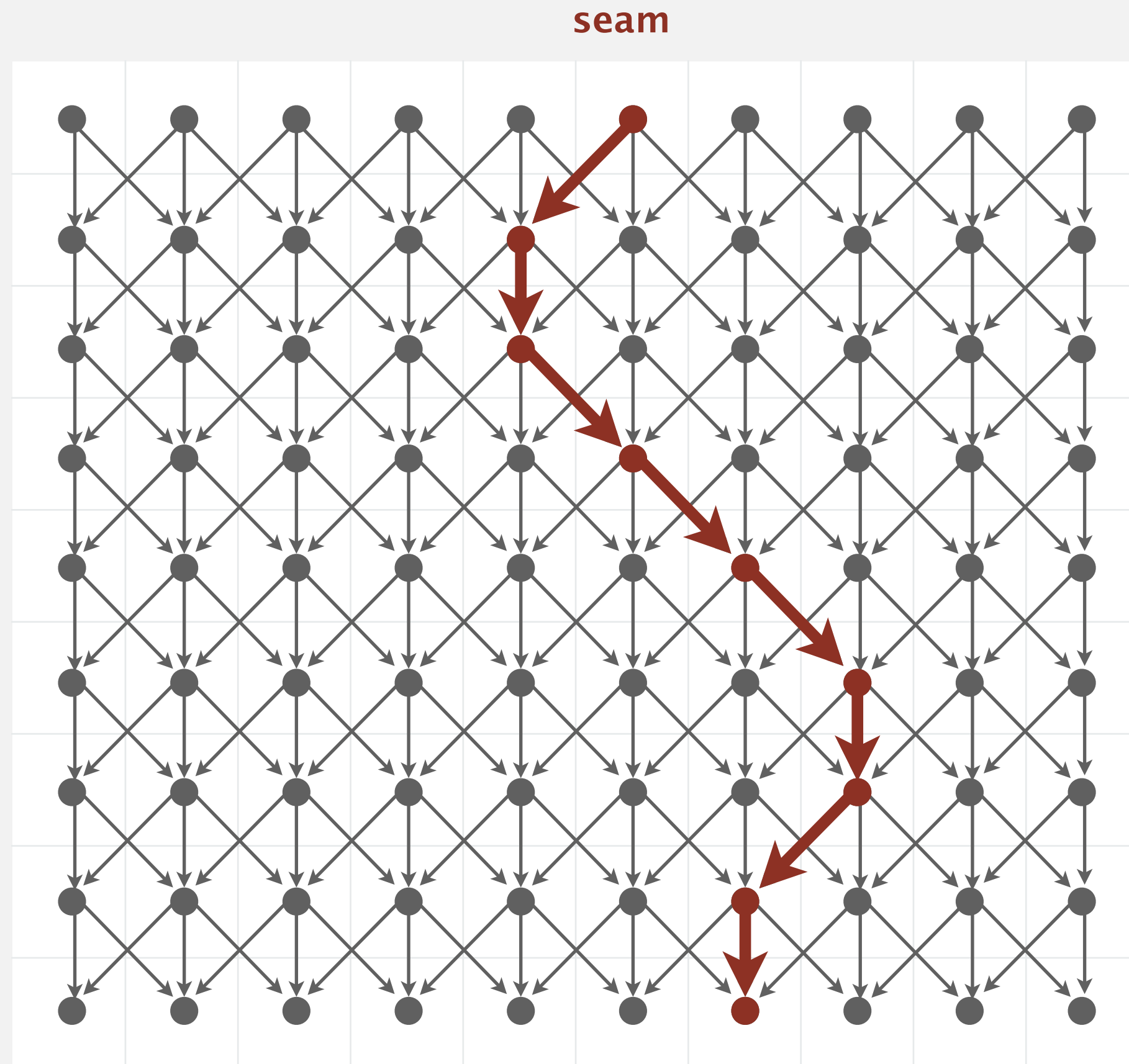


Content-aware resizing: dynamic programming formulation

Problem. Find a min energy path from top to bottom.

Subproblems. $distTo(col, row)$ = energy of min energy path from any top pixel to pixel (col, row) .

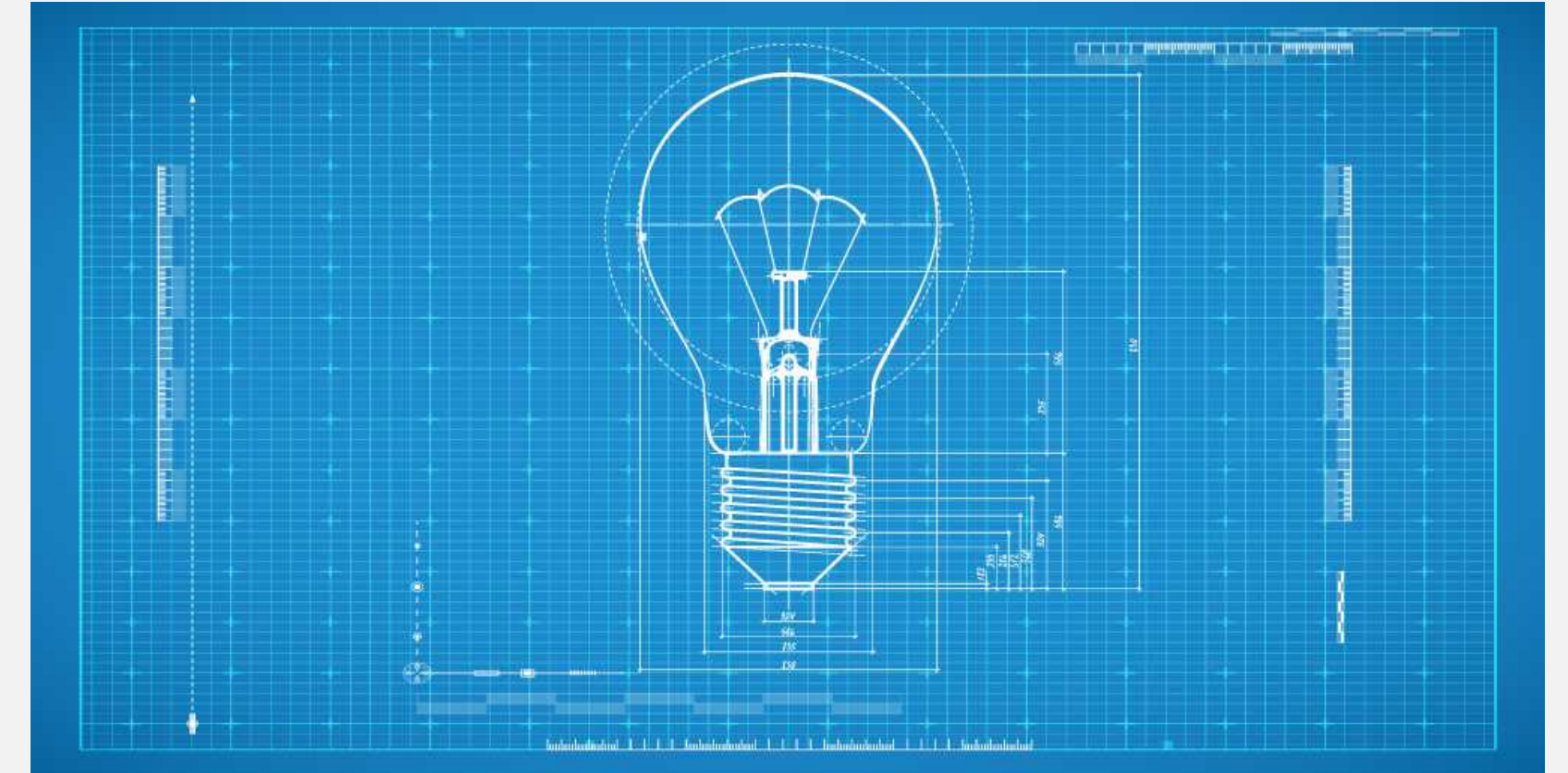
Goal. $\min \{ distTo(col, H-1) \}$.



Summary

How to design a dynamic programming algorithm.

- Find good subproblems. 💡
- Develop DP recurrence for optimal value.
 - optimal substructure
 - overlapping subproblems
- Determine order in which to solve subproblems.
- Cache computed results to avoid unnecessary re-computation.
- Reconstruct the solution: backtrace or save extra state.



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