

COS320: Compiling Techniques

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April 30, 2019

- **Reminder: HW5 is due today**
- HW6 released Tuesday
 - Dataflow analysis
 - Dead code elimination
 - Alias analysis
 - Constant propagation
 - Register allocation
- Come to class Thursday prepared with questions

Compiling object-oriented languages

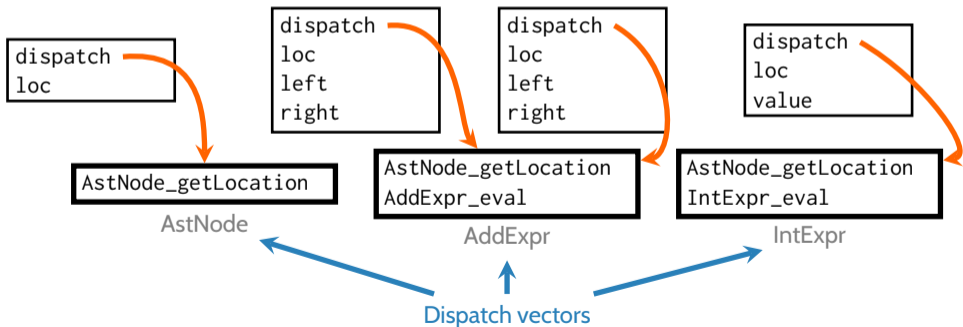
Objects

- An *object* consists of
 - Data (attributes) –
 - Behavior (methods) –
-

```
class AstNode {
    location loc;
    public AstNode(location nodeloc) { loc = nodeloc; }
    public location getLocation() { return loc; }
}
abstract class Expr extends AstNode {
    public abstract int eval(Env);
    public Expr(location loc) { super(loc); }
}
public class AddExpr extends Expr {
    public AddExpr(int loc, Expr x, Expr y) {
        super(loc); left = x; right = y;
    }
    public int eval(Env env) {
        return left.eval(env) + right.eval(env);
    }
}
```

Objected oriented languages

- Compiling OO languages with single inheritance:
 - Each class is associated with a *dispatch vector* (aka virtual table, vtable), which is a record of function pointers - one for each method
 - Each object is associated with a record, with one field for the dispatch vector of its class, and one field for each attriute



Implementing methods

Each method extended with an additional parameter for the current object

- Gives the method access to the attributes of the object
- Dispatch vector enables dynamic dispatch

```
location AstNode_getLocation(self) {  
    return self.loc;  
}  
int AddNode_eval(self, env) {  
    return self.dispatch.eval(self, self.left) + self.dispatch.eval(self, self.left);  
}  
int IntNode_eval(self, env) {  
    return self.value;  
}
```

Subtyping

- Recall the *Liskov substitution principle*: if s is a subtype of t , then terms of type t can be replaced with terms of type s without breaking type safety.
- If B extends A , then B is a subtype of A
- This works for the same reason that record width subtyping works:
 - If A has a method foo , it appears in the same position in A and B 's dispatch vector
 - If A has an attribute x , then A objects and B objects place x in the same position in object records

RECORDWIDTH

$$\frac{}{\vdash \{\mathit{lab}_1 : s_1; \dots; \mathit{lab}_m : s_m\} <: \{\mathit{lab}_1 : s_1; \dots; \mathit{lab}_n : s_n\}} \quad n < m$$

Testing class membership

- Some OO languages support testing whether an object belongs to a given class, and performing (checked) downcasts
- To implement, we need a run-time representation class of the class hierarchy
- Possible solution:
 - The dispatch table serves as a type tag
(i.e., `typeof(o) == AddExpr` \iff `o.dispatch == DispatchVector(AddExpr)`)
 - The first member of each dispatch table is a pointer to parent type
 - To check `o instanceof C`, walk up the class hierarchy
 - `o.dispatch == DispatchVector(C)`, or
 - `o.dispatch != DispatchVector(Object)` and `o.dispatch.parent == DispatchVector(C)`, or
 - `o.dispatch != DispatchVector(Object)` and `o.dispatch.parent != DispatchVector(Object)` and `o.dispatch.parent.parent == DispatchVector(C)`, or
 - ...
 - Checked downcasting: if `o instanceof c` then bitcast, otherwise throw run-time exception.

Multiple inheritance

- Some languages (such as C++) support a class extending more than one base class
- Previous strategy does not work: bases classes have conflicting ideas about where methods are stored in vtable
- Solution: Use hash tables instead of records
- Cost can be reduced with optimizing compiler
 - Perform a conservative analysis to determine the class of (some) objects. If known statically, can replace dynamic dispatch with static dispatch
 - JIT compilation
 - At compile time, we have more precise information about object classes
 - Replace dynamic dispatch with static dispatch, optimize & compile the result.

Compiling functional languages

- First class functions: functions are values just like any other
 - can be passed as parameters (e.g., `map`)
 - can be returned (e.g. `(+) 1`)
- Functions that take functions as parameters are called *higher-order*
- A higher-order functional language is one with *nested functions* with *lexical scope*
- In higher-order functional languages, a function value is a *closure*, which consists of a function pointer *and* an environment
 - Environment is needed to interpret variables from enclosing scope

```
let compose =  
  fun (f : int -> int) ->  
    (fun (g : int -> int) ->  
      (fun (x : int) ->  
        f (g x)))  
let add10 = fun (x : int) -> x + 10  
let mul2 = fun (x : int) -> 2 * x  
let result = compose add10 mul2 100
```

compose →

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(fun f ->  
  (fun g ->  
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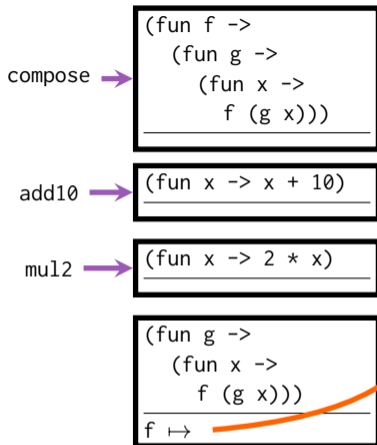
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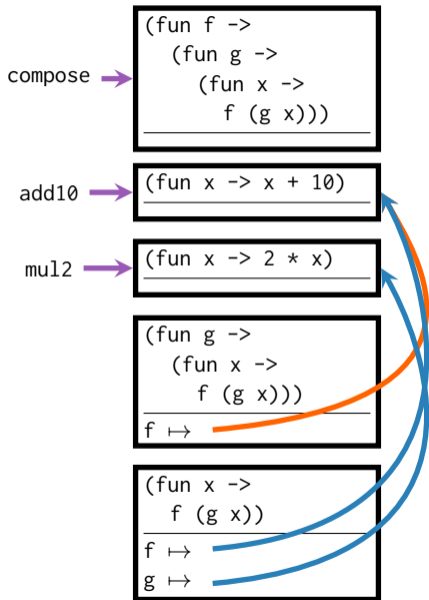
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Compiling closures

- fun expressions evaluate to a pair $(body, env)$ consisting of
 - *body*: A pointer to a function that implements the body of the closure
 - Takes an extra parameter, *env* (similarly to `self/this` in OO)
 - *env*: A pointer to the activation record of the enclosing function
- Functions are first-class values, so they may be returned from functions
 - I.e., a closure may outlive the activation record of the enclosing function
 - activation records must be heap-allocated!

Closure conversion

- *Closure conversion* transforms a program so that no function accesses free variables

```
let f(a,b,c) = let g = fun x -> x + a in (fun y -> g(g(y))), fun y -> y * c)
```

- We say that a , c , and g *escape*: they appear free in the body of a nested function
 - Each escaping var must be stored in an environment. Non-escaping vars can be discarded.
 - First field in the environment is a pointer to enclosing environment.

```
let f(p,a,b,c) =  
  let r1 = (p,a,c) in  
  let g = (fun (p, x) -> x + (#1 p), r1) in  
  let r2 = (r1,g) in  
  let res1 = fun (p, y) ->  
    let g = #1 p in ((#0 g) (#1 g, y))  
  in  
  let res2 = fun (p, y) -> (y * (#2 (#0 p))) in  
  ((res1, r2), (res2, r2))
```

```
let root = ()
let compose =
  (fun (p, f) ->
    let r1 = (p, f) in
    (fun (p, g) ->
      let r2 = (p, g) in
      (fun (p, x) ->
        let g = #1 p in
        let f = #1 (#0 p) in
        ((#0 f) ((#1 f), (#0 g) (#1 g, x))))
        r2),
      r1),
    root)
let add10 = (fun (p, x) -> x + 10, root)
let mul2 = (fun (p, x) -> 2 * x, root)
let result =
  let compose_add10 = (#0 compose) (#1 compose, add10) in
  let compose_add10_mul2 = (#0 compose_add10) (#1 compose_add10, mul2) in
  ((#0 compose_add10_mul2) (#1 compose_add10_mul2, 100))
```

Functional optimizations

- **Tail call elimination**: functional languages favor recursion over loops, but loops are more efficient (need to allocate stack frame, push return address, save registers, ...)
 - Tail call elimination searches for the pattern

```
%x = call foo ...; ret %x
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and compiles the call as a jump instead of a callq

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- **Uncurrying**: in some functional languages (e.g., OCaml), functions always take a single argument at a time

- E.g., in `let f x y = ...`, `f` takes one argument `x`, and returns a closure which takes a second argument `y` and produces the result
- A single OCaml-level function call may result in *several* function calls and closure allocations
- *Uncurrying* is an optimization that determines when a function is always called with more than one parameter (`f 3 4`), and compiles it as a multi-parameter function.

Garbage collection

Garbage collection

- Many modern languages feature *garbage collectors*, which automatically reclaim memory that was allocated by a program but no longer used
- Garbage collection is usually the job of a language *runtime*
 - Usually, the most complicated part

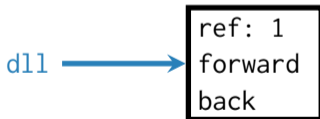
- A memory location is *garbage* if it will not be used in the remainder of the program
- Determining whether it will not be used is undecidable
 - *But*, we are happy with a conservative approximation: free memory if it *cannot possibly be used* in the remainder of the program
- Usually not a *static analysis*, but rather a *dynamic analysis*
 - *static analyses* collect information about a program without running it
 - *dynamic analyses* collect information about a program while running it

Reference counting

- Each memory location gets an extra int field to hold the number of active references to that memory
- Collect when count is zero

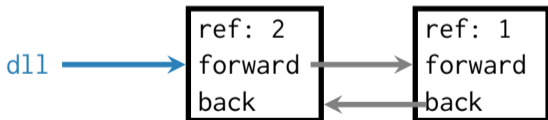
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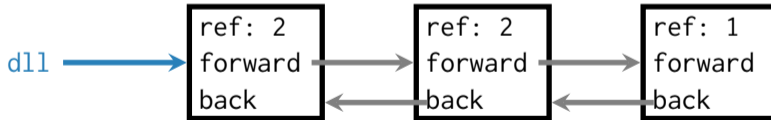
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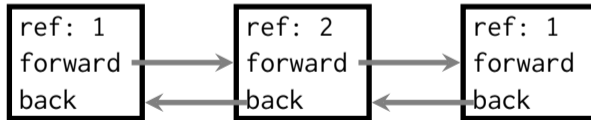
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Tracing-based GC

- *Tracing garbage collection*: a memory location is garbage if it is unreachable from the program's *roots*
 - *roots* = register, stack, global static data

Mark-and-sweep

- Each memory location gets an extra bit to hold a “mark”
- When there is no remaining free memory, run a DFS search from the roots, marking all memory locations
- Traverse the entire heap; unmarked nodes are collected
- **Generational GC**
 - Most memory becomes garbage quickly after allocation
 - Memory that does not quickly become garbage is likely to not be garbage for a very long time
 - So: maintain several heaps (“generations”) G_0, G_1, \dots
 - Allocate in G_0 , and scan frequently
 - Scan G_1 less frequently, G_2 less frequently than that, ...
 - After collecting garbage in G_i , *non*-garbage is promoted to G_{i+1}