

Deep Learning Basics Lecture 7: Factor Analysis

Princeton University COS 495

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Supervised v.s. Unsupervised

Math formulation for supervised learning

- Given training data $\{(x_i, y_i): 1 \le i \le n\}$ i.i.d. from distribution D
- Find $y = f(x) \in \mathcal{H}$ that minimizes $\hat{L}(f) = \frac{1}{n} \sum_{i=1}^{n} l(f, x_i, y_i)$
- s.t. the expected loss is small

 $L(f) = \mathbb{E}_{(x,y)\sim D}[l(f,x,y)]$

Unsupervised learning

- Given training data $\{x_i: 1 \le i \le n\}$ i.i.d. from distribution D
- Extract some "structure" from the data
- Do not have a general framework
- Typical unsupervised tasks:
 - Summarization: clustering, dimension reduction
 - Learning probabilistic models: latent variable model, density estimation

High dimensional data

• Example 1: images



Dimension: 300x300 = 90,000

High dimensional data

- Example 2: documents
- Features:
 - Unigram (count of each word): thousands
 - Bigram (co-occurrence contextual information): millions
- Netflix survey: 480189 users x 17770 movies

	Movie 1	Movie 2	Movie 3	Movie 4	Movie 5	Movie 6	•••
User 1	5	?	?	1	3	?	
User 2	?	?	3	1	2	5	
User 3	4	3	1	?	5	1	

Example from Nina Balcan

- Data analysis point of view: dimension reduction technique on a given set of high dimensional data $\{x_i : 1 \le i \le n\}$
- Math point of view: eigen-decomposition of the covariance (or singular value decomposition of the data)
- Classic, commonly used tool

- Extract hidden lower dimensional structure of the data
 - Try to capture the variance structure as much as possible
- Computation: solved by singular value decomposition (SVD)

• **Definition:** an orthogonal projection or transformation of the data into a (typically lower dimensional) subspace so that the variance of the projected data is maximized.



Figure from isomorphismes @stackexchange

- An illustration of the projection to 1 dim
- Pay attention to the variance of the projected points



Figure from amoeba@stackexchange

- Principal Components (PC) are directions that capture most of the variance in the data
- First PC: direction of greatest variability in data
 - Data points are most spread out when projected on the first PC compared to any other direction
- Second PC: next direction of greatest variability, orthogonal to first PC
- Third PC: next direction of greatest variability, orthogonal to first and second PC's

Math formulation

- Suppose the data are centered: $\sum_{i=1}^{n} x_i = 0$
- Then their projections on any direction v are centered: $\sum_{i=1}^{n} v^{T} x_{i} = 0$
- First PC: maximize the variance of the projections

$$\max_{v} \sum_{i=1}^{\infty} (v^{T} x_{i})^{2}, \qquad s.t. \ v^{T} v = 1$$

equivalent to

$$\max_{v} v^T X X^T v, \qquad s.t. \ v^T v = 1$$

where the columns of *X* are the data points

Math formulation

• First PC:

 $\max_{v} v^{T} X X^{T} v, \quad s.t. \quad v^{T} v = 1$ where the columns of *X* are the data points

• Solved by Lagrangian: exists λ , so that

$$\max_{v} v^{T} X X^{T} v - \lambda v^{T} v$$
$$\frac{\partial}{\partial v} = 0 \rightarrow (X X^{T} - \lambda I) v = 0 \rightarrow X X^{T} v = \lambda v$$

Computation: Eigen-decomposition

- First PC: $XX^T v = \lambda v$
- XX^T : covariance matrix
- v : eigen-vector of the covariance matrix
- First PC: first eigen-vector of the covariance matrix
- Top k PC's: similar argument shows they are the top k eigen-vectors

Computation: Eigen-decomposition

- Top k PC's: the top k eigen-vectors $XX^TU = \Lambda U$ where Λ is a diagonal matrix
- *U* are the left singular vectors of *X*
- Recall SVD decomposition theorem:
- An $m \times n$ real matrix M has factorization $M = U\Sigma V^T$ where U is an $m \times m$ orthogonal matrix, Σ is a $m \times n$ rectangular diagonal matrix with non-negative real numbers on the diagonal, and V is an $n \times n$ orthogonal matrix.

Equivalent view: low rank approximation

- First PC maximizes variance: $\max_{v} v^{T} X X^{T} v, \quad s.t. \quad v^{T} v = 1$
- Alternative viewpoint: find vector v such that the projection yields minimum MSE reconstruction

$$\min_{v} \frac{1}{n} \sum_{i=1}^{n} ||x_i - vv^T x_i||^2, \quad s.t. \ v^T v = 1$$

Equivalent view: low rank approximation

• Alternative viewpoint: find vector v such that the projection yields minimum MSE reconstruction

$$\min_{v} \frac{1}{n} \sum_{i=1}^{n} ||x_i - vv^T x_i||^2, \quad s.t. \ v^T v = 1$$

 $blue^2 + green^2 = black^2$

black² is fixed (it's just the data)

So, maximizing blue² is equivalent to minimizing green²



Figure from Nina Balcan

Summary

- PCA: orthogonal projection that maximizes variance
- Low rank approximation: orthogonal projection that minimizes error
- Eigen-decomposition/SVD
- All equivalent for centered data

A latent variable view of PCA

- Let $h_i = v^T x_i$
- Data point viewed as $x_i = vh_i + noise$





A latent variable view of PCA

- Consider top *k* PC's *U*
- Let $h_i = U^T x_i$
- Data point viewed as $x_i = Uh_i + noise$



A latent variable view of PCA

- Consider top *k* PC's *U*
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PCA structure assumption: *h* low dimension. What about other assumptions?

h

U

 $\boldsymbol{\chi}$

- Structure assumption: h is sparse, i.e., $|h|_0$ is small
- Dimension of *h* can be large



• Latent variable probabilistic model view:

$$p(x|h) = Wh + N\left(0, \frac{1}{\beta}I\right), h \text{ is sparse},$$

• E.g., from Laplacian prior: $p(h) = \frac{\lambda}{2} \exp(-\frac{\lambda}{2}|h|_1)$



• Suppose W is known. MLE on h is

$$h^* = \arg \max_{h} \log p(h|x)$$
$$h^* = \arg \min_{h} \lambda ||h||_1 + \beta ||x - Wh||_2^2$$

- Suppose both W, h unknown.
 - Typically alternate between updating *W*, *h*

- Historical note: study on visual system
- Bruno A Olshausen, and David Field. "Emergence of simple-cell receptive field properties by learning a sparse code for natural images." *Nature* 381.6583 (1996): 607-609.

Project paper list

Supervised learning

- AlexNet: <u>ImageNet Classification with Deep Convolutional Neural</u>
 <u>Networks</u>
- GoogLeNet: <u>Going Deeper with Convolutions</u>
- Residue Network: <u>Deep Residual Learning for Image Recognition</u>

Unsupervised learning

- Deep belief networks: <u>A fast learning algorithm for deep belief nets</u>
- <u>Reducing the Dimensionality of Data with Neural Networks</u>
- Variational autoencoder: <u>Auto-Encoding Variational Bayes</u>
- <u>Generative Adversarial Nets</u>

Recurrent neural networks

- Long-short term memory
- <u>Memory networks</u>
- <u>Sequence to Sequence Learning with Neural Networks</u>

You choose the paper that interests you!

- Need to consult with TA
 - Heavier responsibility on the student side if customize the project
- Check recent papers in the conferences <u>ICML</u>, <u>NIPS</u>, <u>ICLR</u>
- Check papers by leading researchers: Hinton, Lecun, Bengio, etc
- Explore whether deep learning can be applied to your application
- Not recommend arXiv: too many deep learning papers