Princeton COS 495: Introduction to Deep Learning Homework 1

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1. (Math) Let D be the distribution over the data points (x, y), and let \mathcal{H} be the hypothesis class, in which one would like to find a function f that has small expected loss L(f) by minimizing the empirical loss $\hat{L}(f)$. A few definitions/terminologies:

• The best function among all (measurable) functions is called Bayes hypothesis:

$$f^* = \arg\inf_f L(f).$$

• The best function in the hypothesis class is denoted as

$$f_{opt} = \arg \inf_{f \in \mathcal{H}} L(f)$$

• The function that minimizes the empirical loss in the hypothesis class is denoted as

$$\hat{f}_{opt} = \arg \inf_{f \in \mathcal{H}} \hat{L}(f)$$

- The function output by the algorithm is denoted as \hat{f} . (It can be different from \hat{f}_{opt} since the optimization may not find the best solution.)
- The difference between the loss of f^* and f_{opt} is called approximation error:

$$\epsilon_{app} = L(f_{opt}) - L(f^*)$$

which measures the error introduced in building the model/hypothesis class.

• The difference between the loss of f_{opt} and \hat{f}_{opt} is called estimation error:

$$\epsilon_{est} = L(\hat{f}_{opt}) - L(f_{opt})$$

which measures the error introduced by using finite data to approximate the distribution D.

• The difference between the loss of \hat{f}_{opt} and \hat{f} is called optimization error:

$$\epsilon_{opt} = L(\hat{f}) - L(\hat{f}_{opt})$$

which measures the error introduced in optimization.

• The difference between the loss of f^* and \hat{f} is called excess risk:

$$\epsilon_{exc} = L(\hat{f}) - L(f^*)$$

which measures the distance from the output of the algorithm to the best solution possible.

(1) Show that $\epsilon_{exc} = \epsilon_{app} + \epsilon_{est} + \epsilon_{opt}$.

Comments: This means that to get better performance, one can think of: 1) building a hypothesis class closer to the ground truth; 2) collecting more data; 3) improving the optimization.

(2) Typically, when one has enough data, the empirical loss concentrates around the expected loss: there exists $\epsilon_{con} > 0$, such that for any $f \in \mathcal{H}$, $|\hat{L}(f) - L(f)| \leq \epsilon_{con}$. Show that in this case, $\epsilon_{est} \leq 2\epsilon_{con}$.

Comments: This means that to get small estimation error, the number of data points should be large enough so that concentration happens. The number of data points needed to get concentration ϵ_{con} is called sample complexity, which is an important topic in learning theory and statistics.

2. (Math) Recall that the logistic regression uses the logistic sigmoid function $\sigma(a) = 1/(1 + \exp(-a))$ to model the conditional distribution p(y|x) and then apply maximum likelihood estimation. One can use the probit function (instead of the logistic function):

$$\Phi(a) = \int_{-\infty}^{a} N(\theta|0, 1) d\theta$$

where $N(\theta|0,1)$ is the standard normal distribution. Derive the negative conditional loglikelihood loss for probit regression.

Comments: No need to simplify the expression.

3. (Coding) Generate 100 synthetic data points (x, y) as follows: x is uniform over $[0, 1]^{10}$ and $y = \sum_{i=1}^{10} i * x_i + 0.1 * N(0, 1)$ where N(0, 1) is the standard normal distribution. Implement full gradient descent and stochastic gradient descent, and test them on linear regression over the synthetic data points.

Comments: The initialization, the learning rate, and the stop criterion are left for you to explore. Think about the reasons why you use a particular strategy for these; comments in the code on them are not required but will be appreciated.

4. (Coding) Implement the Perceptron algorithm and run it on the following synthetic data sets in \mathbf{R}^{10} : pick $w^* = [1, 0, 0, \dots, 0]$; generate 1000 points x by sampling uniformly at random over the unit sphere and then removing those that have margin γ smaller than 0.1; generate label $y = \operatorname{sign}((w^*)^{\top} x)$.