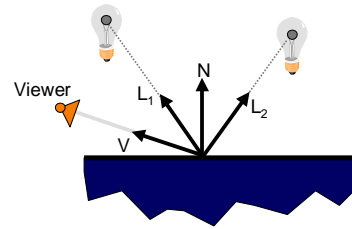


Global Illumination

Thomas Funkhouser
Princeton University
COS 526, Fall 2002

Direct Illumination

- Multiple light sources:



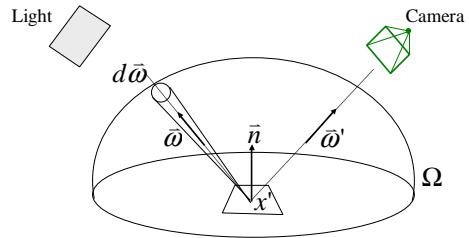
$$I = I_E + K_A I_{AL} + \sum_i (K_D (N \cdot L_i) I_i + K_S (V \cdot R_i)^n I_i)$$

Overview

- Global illumination
 - Rendering equation
- Solution methods
 - OpenGL
 - Ray tracing
 - Path tracing
 - Radiosity
- Path types
 - L(S|D)*E

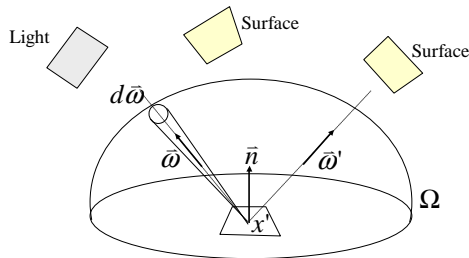
Direct Illumination

$$L_o(x', \bar{\omega}') = L_e(x', \bar{\omega}') + \int_{\Omega} f_r(x', \bar{\omega}, \bar{\omega}') L_i(x', \bar{\omega}) (\bar{\omega} \cdot \bar{n}) d\bar{\omega}$$



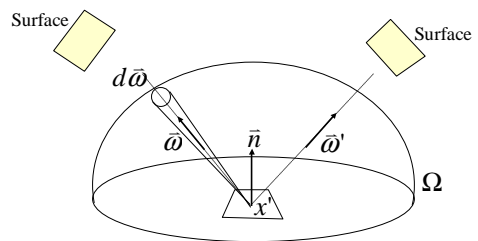
Global Illumination

$$L_o(x', \bar{\omega}') = L_e(x', \bar{\omega}') + \int_{\Omega} f_r(x', \bar{\omega}, \bar{\omega}') L_i(x', \bar{\omega}) (\bar{\omega} \cdot \bar{n}) d\bar{\omega}$$



Rendering Equation

$$L_o(x', \bar{\omega}') = L_e(x', \bar{\omega}') + \int_{\Omega} f_r(x', \bar{\omega}, \bar{\omega}') L_i(x', \bar{\omega}) (\bar{\omega} \cdot \bar{n}) d\bar{\omega}$$

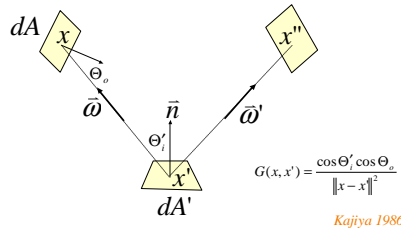


Kajiya 1986

Rendering Equation (2)



$$L(x' \rightarrow x'') = L_e(x' \rightarrow x'') + \int_{\mathcal{S}} f_r(x \rightarrow x' \rightarrow x'') L(x \rightarrow x') V(x, x') G(x, x') dA$$



Photorealistic Rendering

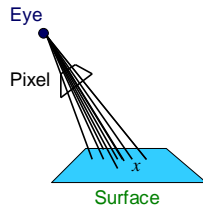


- Rendering = integration
 - Antialiasing
 - Soft shadows
 - Indirect illumination
 - Caustics

Photorealistic Rendering



- Rendering = integration
 - Antialiasing
 - Soft shadows
 - Indirect illumination
 - Caustics

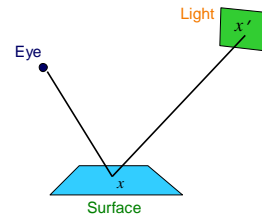


$$L_p = \int_{\mathcal{S}} L(x \rightarrow e) dA$$

Photorealistic Rendering



- Rendering = integration
 - Antialiasing
 - Soft shadows
 - Indirect illumination
 - Caustics



$$L(x, \bar{w}) = L_e(x, x \rightarrow e) + \int_{\mathcal{S}} f_r(x, x' \rightarrow x, x \rightarrow e) L(x' \rightarrow x) V(x, x') G(x, x') dA$$

Photorealistic Rendering



- Rendering = integration
 - Antialiasing
 - Soft shadows
 - Indirect illumination
 - Caustics



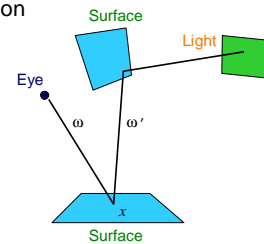
Herf

$$L(x, \bar{w}) = L_e(x, x \rightarrow e) + \int_{\mathcal{S}} f_r(x, x' \rightarrow x, x \rightarrow e) L(x' \rightarrow x) V(x, x') G(x, x') dA$$

Photorealistic Rendering



- Rendering = integration
 - Antialiasing
 - Soft shadows
 - Indirect illumination
 - Caustics



$$L_o(x, \bar{w}) = L_e(x, \bar{w}) + \int_{\Omega} f_r(x, \bar{w}', \bar{w}) L_i(x, \bar{w}') (\bar{w}' \cdot \bar{n}) d\bar{w}'$$

Photorealistic Rendering



- Rendering = integration
 - Antialiasing
 - Soft shadows
 - Indirect illumination
 - Caustics



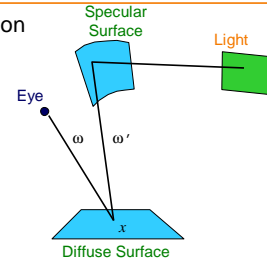
Debevec

$$L_o(x, \vec{\omega}) = L_e(x, \vec{\omega}) + \int_{\Omega} f_r(x, \vec{\omega}', \vec{\omega}) L_i(x, \vec{\omega}') (\vec{\omega}' \cdot \vec{n}) d\vec{\omega}'$$

Photorealistic Rendering



- Rendering = integration
 - Antialiasing
 - Soft shadows
 - Indirect illumination
 - Caustics

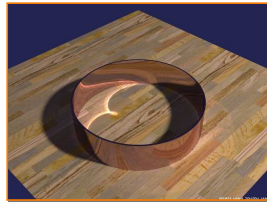


$$L_o(x, \vec{\omega}) = L_e(x, \vec{\omega}) + \int_{\Omega} f_r(x, \vec{\omega}', \vec{\omega}) L_i(x, \vec{\omega}') (\vec{\omega}' \cdot \vec{n}) d\vec{\omega}'$$

Photorealistic Rendering



- Rendering = integration
 - Antialiasing
 - Soft shadows
 - Indirect illumination
 - Caustics



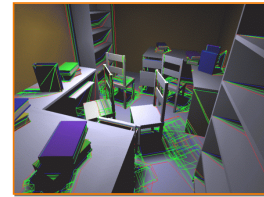
Jensen

$$L_o(x, \vec{\omega}) = L_e(x, \vec{\omega}) + \int_{\Omega} f_r(x, \vec{\omega}', \vec{\omega}) L_i(x, \vec{\omega}') (\vec{\omega}' \cdot \vec{n}) d\vec{\omega}'$$

Challenge



- Rendering integrals are difficult to evaluate
 - Multiple dimensions
 - Discontinuities
 - » Partial occluders
 - » Highlights
 - » Caustics



Drettakis

$$L(x, \vec{\omega}) = L_e(x, x \rightarrow e) + \int_{\Omega} f_r(x, x' \rightarrow x, x \rightarrow e) L(x' \rightarrow x) V(x, x') G(x, x') dA$$

Challenge



- Rendering integrals are difficult to evaluate
 - Multiple dimensions
 - Discontinuities
 - » Partial occluders
 - » Highlights
 - » Caustics



Jensen

$$L(x, \vec{\omega}) = L_e(x, x \rightarrow e) + \int_{\Omega} f_r(x, x' \rightarrow x, x \rightarrow e) L(x' \rightarrow x) V(x, x') G(x, x') dA$$

Overview



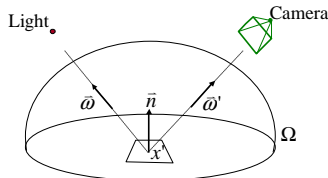
- Global illumination
 - Rendering equation
- Solution methods
 - OpenGL
 - Ray tracing
 - Path tracing
 - Radiosity
- Path types
 - L(S|D)*E

OpenGL



$$L_o(x', \omega') = L_e(x', \omega') + \int_{\Omega} f_r(x', \omega, \omega') L_i(x', \omega) (\omega \cdot \bar{n}) d\omega$$

Assume direct illumination from point lights and ignore visibility



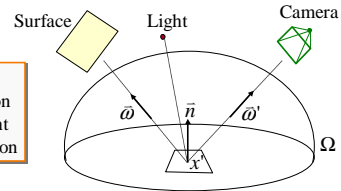
$$L_o(x', \omega') = L_e(x', \omega') + \sum_{i=1}^{nlights} f_r(x', \omega, \omega') L_i(x', \omega) (\omega \cdot \bar{n})$$

Ray Tracing



$$L_o(x', \omega') = L_e(x', \omega') + \int_{\Omega} f_r(x', \omega, \omega') L_i(x', \omega) (\omega \cdot \bar{n}) d\omega$$

Assume specular reflection is only significant indirect illumination



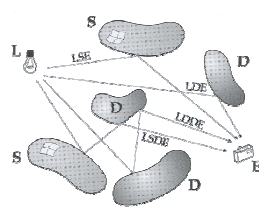
$$L_o(x', \omega') = L_e(x', \omega') + \sum_{i=1}^{nlights} f_r(x', \omega, \omega') L_i(x', \omega) (\omega \cdot \bar{n}) + specular$$

Monte Carlo Path Tracing



$$L_o(x', \omega') = L_e(x', \omega') + \int_{\Omega} f_r(x', \omega, \omega') L_i(x', \omega) (\omega \cdot \bar{n}) d\omega$$

Estimate integral for each pixel by random sampling



Also:

- Depth of field
- Motion blur
- etc.

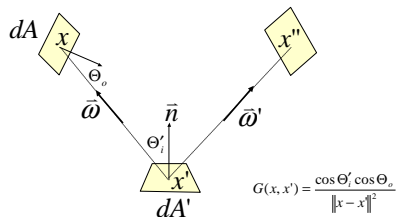
Indirect Diffuse Illumination



Rendering Equation



$$L(x \rightarrow x'') = L_e(x \rightarrow x'') + \int_{\mathcal{S}} f_r(x \rightarrow x' \rightarrow x'') L(x \rightarrow x') V(x, x') G(x, x') dA$$



$$G(x, x') = \frac{\cos \Theta'_i \cos \Theta_o}{\|x - x'\|^2}$$

Kajiya 1986

Radiosity Equation



$$L(x \rightarrow x'') = L_e(x \rightarrow x'') + \int_{\mathcal{S}} f_r(x \rightarrow x' \rightarrow x'') L(x \rightarrow x') V(x, x') G(x, x') dA$$

Assume everything is Lambertian

$$\rho(x') = f_r(x \rightarrow x' \rightarrow x'') \pi$$

$$L(x') = L_e(x') + \frac{\rho(x')}{\pi} \int_{\mathcal{S}} L(x) V(x, x') G(x, x') dA$$

Convert to Radiosities

$$B = \int_{\Omega} L_o \cos \theta d\omega \quad L = \frac{B}{\pi}$$

$$B(x'') = B_e(x'') + \frac{\rho(x'')}{\pi} \int_{\mathcal{S}} B(x) V(x, x'') G(x, x'') dA$$

Radiosity Approximation

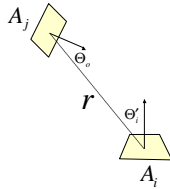


$$B(x') = B_e(x') + \frac{\rho(x')}{\pi} \int_S B(x) V(x, x') G(x, x') dA$$

Discretize the surfaces into "elements"

$$B_i = E_i + \rho_i \sum_{j=1}^N B_j F_{ij}$$

where $F_{ij} = \frac{1}{A_i} \iint_{A_i, A_j} \frac{V_{ij} \cos \Theta'_i \cos \Theta_o}{\pi r^2} dA_j dA_i$



System of Equations



$$B_i = E_i + \rho_i \sum_{j=1}^N B_j F_{ij}$$

$$E_i = B_i - \rho_i \sum_{j=1}^N B_j F_{ij}$$

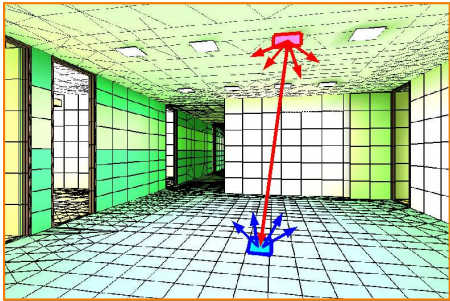
$$B_i - \rho_i \sum_{j=1}^N B_j F_{ij} = E_i$$

$$\begin{bmatrix} 1 - \rho_1 F_{1,1} & \dots & \dots & -\rho_1 F_{1,n} \\ -\rho_2 F_{2,1} & 1 - \rho_2 F_{2,2} & \dots & -\rho_2 F_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ -\rho_n F_{n,1} & \dots & \dots & 1 - \rho_n F_{n,n} \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \\ \vdots \\ B_n \end{bmatrix} = \begin{bmatrix} E_1 \\ E_2 \\ \vdots \\ E_n \end{bmatrix}$$

$$(1 - \rho_i \sum_{j=1}^N F_{ij}) B_i - \rho_i \sum_{j=1}^N F_{ij} B_j = E_i$$

$$B_i A_i = E_i A_i + \rho_i \sum_{j=1}^N F_{ij} B_j A_j \quad \leftarrow \text{This is an energy balance equation}$$

Radiosity Intuition



Radiosity



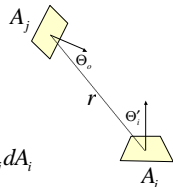
- Issues
 - Computing form factors
 - Selecting basis functions for radiosity
 - Solving linear system of equations
 - Meshing surfaces into elements
 - Rendering images

Form Factor



- Fraction of energy leaving element i that arrives at element j

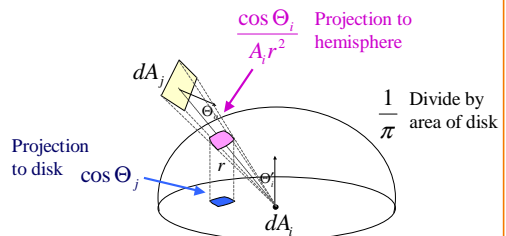
$$F_{ij} = \frac{1}{A_i} \iint_{A_i, A_j} \frac{V_{ij} \cos \Theta'_i \cos \Theta_o}{\pi r^2} dA_j dA_i$$



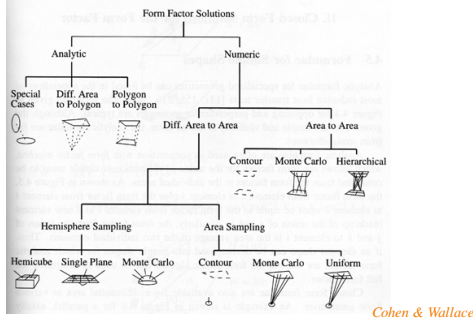
Form Factor Intuition



$$F_{di-dj} = \frac{1}{A_i} \frac{V_{ij} \cos \Theta_i \cos \Theta_j}{\pi r^2}$$



Computing Form Factors



Solving the System of Equations



- Challenges:
 - Size of matrix
 - Cost of computing form factors
 - Computational complexity

$$\begin{bmatrix} 1 - \rho_1 F_{1,1} & \cdot & \cdot & \cdot & -\rho_1 F_{1,n} \\ -\rho_2 F_{2,1} & 1 - \rho_2 F_{2,2} & \cdot & \cdot & -\rho_2 F_{2,n} \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ -\rho_{n-1} F_{n-1,1} & \cdot & \cdot & \cdot & -\rho_{n-1} F_{n-1,n} \\ -\rho_n F_{n,1} & \cdot & \cdot & \cdot & 1 - \rho_n F_{n,n} \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \\ \cdot \\ \cdot \\ B_n \end{bmatrix} = \begin{bmatrix} E_1 \\ E_2 \\ \cdot \\ \cdot \\ E_n \end{bmatrix}$$

A **x** = **b**

Solving the System of Equations



- Solution methods:
 - ~~Invert the matrix~~ – $O(n^3)$
 - Iterative methods – $O(n^2)$
 - Hierarchical methods – $O(n)$

$$\begin{bmatrix} 1 - \rho_1 F_{1,1} & \cdot & \cdot & \cdot & -\rho_1 F_{1,n} \\ -\rho_2 F_{2,1} & 1 - \rho_2 F_{2,2} & \cdot & \cdot & -\rho_2 F_{2,n} \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ -\rho_{n-1} F_{n-1,1} & \cdot & \cdot & \cdot & -\rho_{n-1} F_{n-1,n} \\ -\rho_n F_{n,1} & \cdot & \cdot & \cdot & 1 - \rho_n F_{n,n} \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \\ \cdot \\ \cdot \\ B_n \end{bmatrix} = \begin{bmatrix} E_1 \\ E_2 \\ \cdot \\ \cdot \\ E_n \end{bmatrix}$$

A **x** = **b**

Gauss-Seidel Iteration



- for all i
- $B_i = E_i$
- while not converged
- for each i in turn
- $B_i = E_i + \rho_i \sum_{j \neq i} B_j F_{ij}$
- display the image using B_i as the intensity of patch i .

Gauss-Seidel Iteration



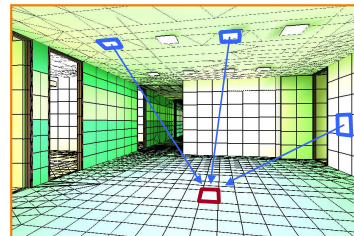
- Two interpretations:
 - Iteratively relax rows of linear system
 - Iteratively gather radiosity to elements

$$\begin{bmatrix} 1 - \rho_1 F_{1,1} & \cdot & \cdot & \cdot & -\rho_1 F_{1,n} \\ -\rho_2 F_{2,1} & 1 - \rho_2 F_{2,2} & \cdot & \cdot & -\rho_2 F_{2,n} \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ -\rho_{n-1} F_{n-1,1} & \cdot & \cdot & \cdot & -\rho_{n-1} F_{n-1,n} \\ -\rho_n F_{n,1} & \cdot & \cdot & \cdot & 1 - \rho_n F_{n,n} \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \\ \cdot \\ \cdot \\ B_n \end{bmatrix} = \begin{bmatrix} E_1 \\ E_2 \\ \cdot \\ \cdot \\ E_n \end{bmatrix}$$

Gauss-Seidel Iteration



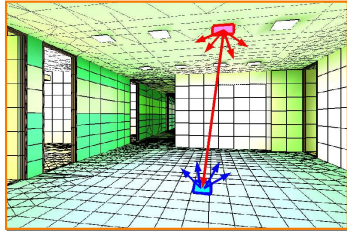
- Two interpretations:
 - Iteratively relax rows of linear system
 - Iteratively gather radiosity to elements



Progressive Radiosity



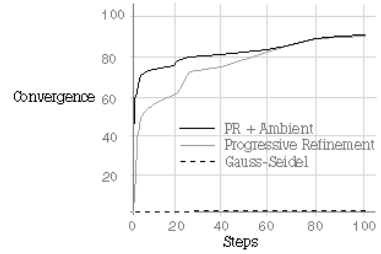
- Interpretation:
 - Iteratively shoot “unshot” radiosity from elements
 - Select shooters in order of unshot radiosity



Progressive Radiosity



- Adaptive refinement



Yeap

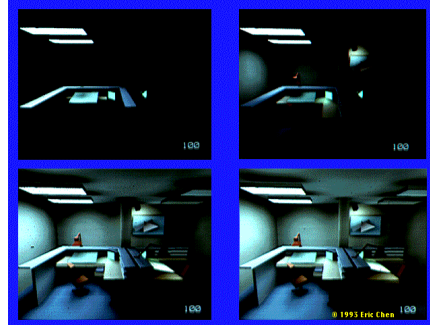
Progressive Radiosity



PROGRESSIVE SOLUTION

The above images show increasing levels of global diffuse illumination. From left to right: 0 bounces, 1 bounce, 3 bounces.

Progressive Radiosity



Surface Meshing



- Store radiosity across surface
 - Few elements
 - Represents function well
 - Few visible artifacts

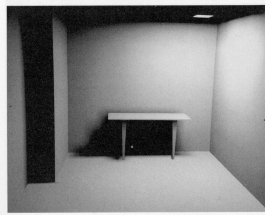
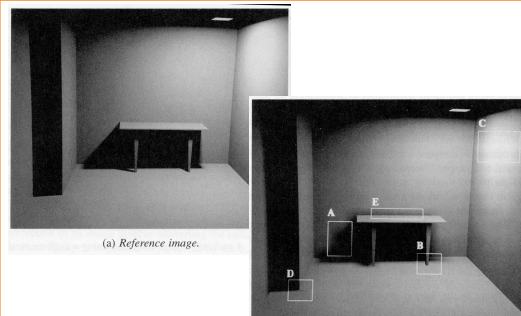


Figure 6.2: A radiosity image computed using a uniform mesh.

Cohen & Wallace

Artifacts of Bad Surface Meshing



(a) Reference image.

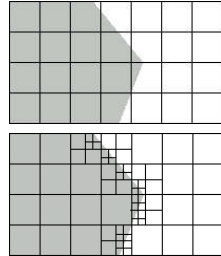
(b) Artifacts introduced by the approximation.

Cohen & Wallace

Adaptive Meshing

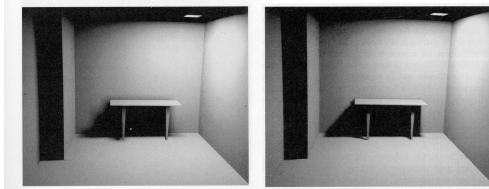


- Refine mesh in areas of high residual



Yeap

Adaptive Meshing



Uniform mesh

Adaptive mesh

Cohen & Wallace

Error Comparison

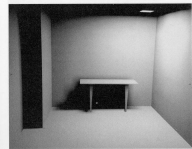


Figure 6.2. A radiosity image computed using a uniform mesh.

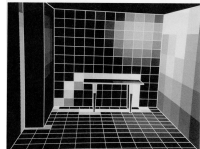
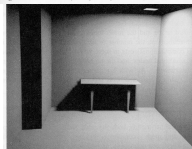


Figure 6.4. Error image.

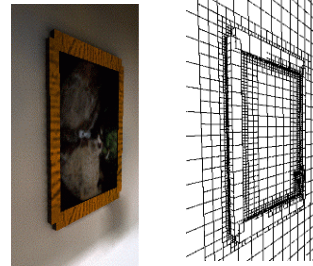


Cohen & Wallace

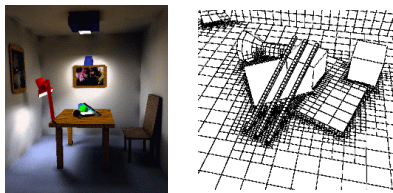
Adaptive subdivision. Compare to Figure 6.2.



Adaptive Meshing



Adaptive Meshing



Adaptive Meshing

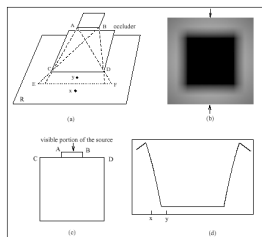


Baum et al.

Discontinuity Meshing



- Capture discontinuities in radiosity across a surface with explicit mesh boundaries



Lischinski et al.

Discontinuity Meshing



- Capture discontinuities in radiosity across a surface with explicit mesh boundaries



Discontinuity Mesh

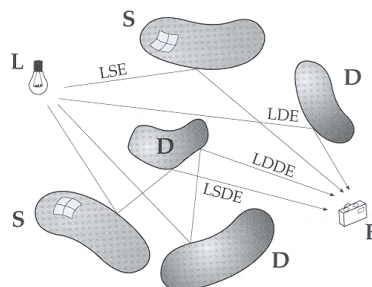
Lischinski et al.

Overview

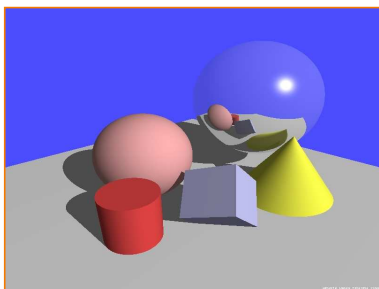


- Global illumination
 - Rendering equation
- Solution methods
 - OpenGL
 - Ray tracing
 - Path tracing
 - Radiosity
- Path types
 - $L(S|D)^*E$

Path Types

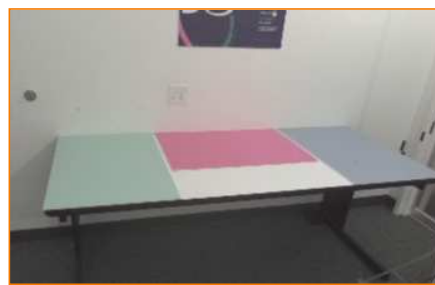


Path Types?



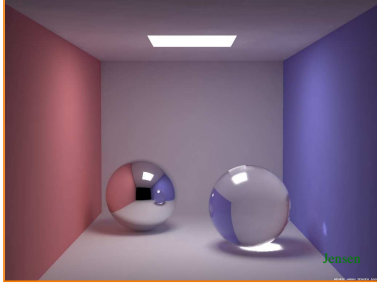
Henrik Wann Jensen

Path Types?



Paul Debevec

Path Types



+ indirect diffuse illumination

Henrik Wann Jensen

Summary



- Global illumination
 - Rendering equation
- Solution methods
 - OpenGL
 - Ray tracing
 - Radiosity
 - Path tracing
- Path types
 - $L(S|D)*E$