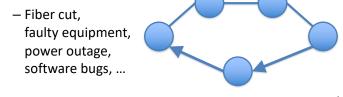


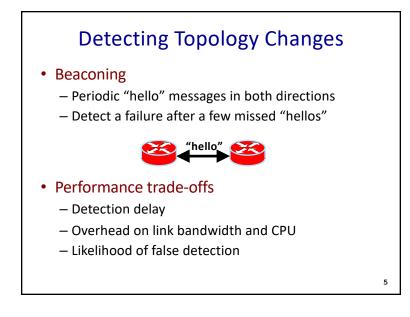
# Two Types of Topology Changes

#### • Planned

- Maintenance: shut down a node or link
- Energy savings: shut down a node or link
- Traffic engineering: change routing configuration

#### • Unplanned Failures





# Routing Convergence: Link-State Routing

### Convergence

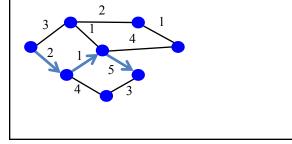
• Control plane

- All nodes have consistent information

• Data plane

- All nodes forward packets in a consistent way

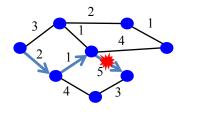
7



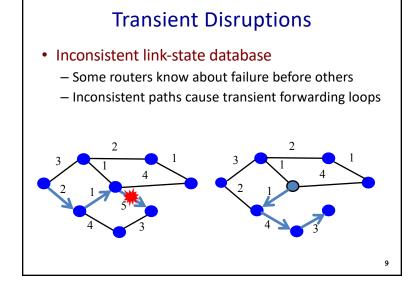
# Transient Disruptions

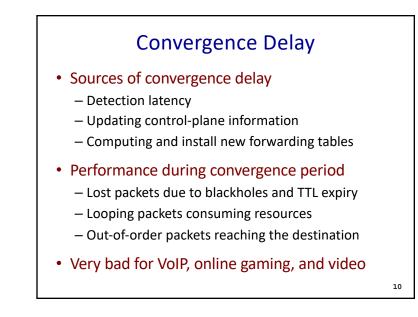
#### • Detection delay

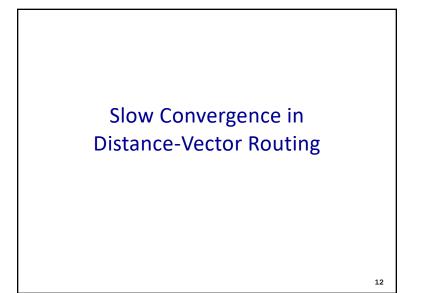
- A node does not detect a failed link immediately
- $\hdots$  and forwards data packets into a "blackhole"
- Depends on timeout for detecting lost hellos

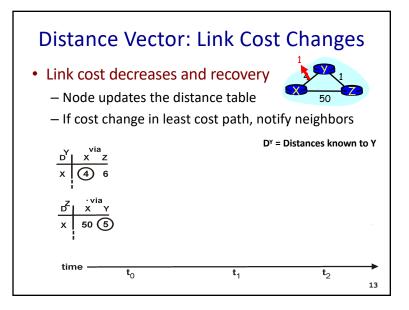


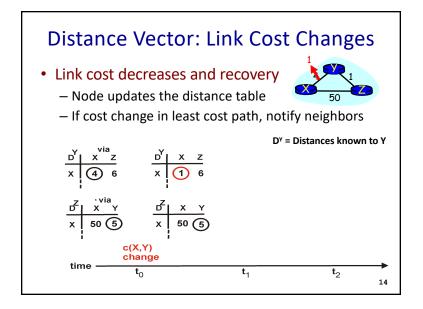
6

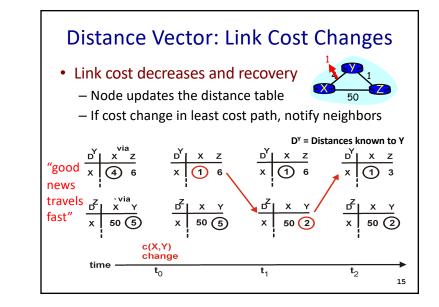


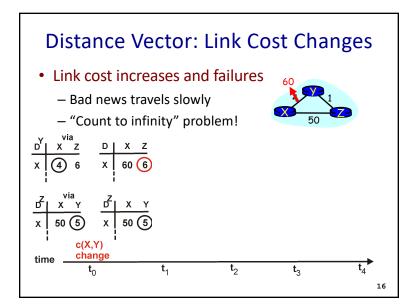


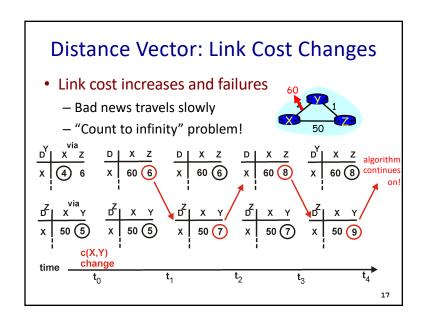


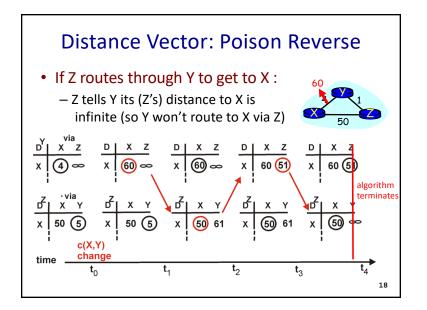


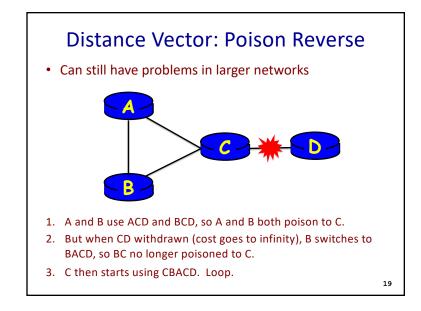












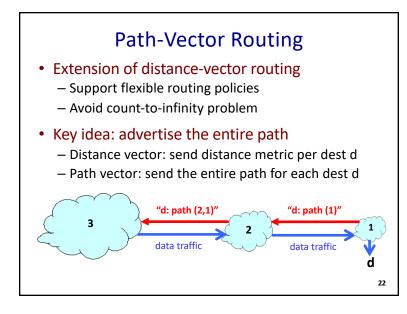
## **Redefining Infinity**

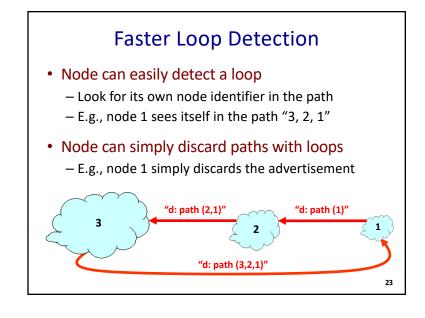
- Avoid "counting to infinity"
  - By making "infinity" smaller!
- Routing Information Protocol (RIP)
  - All links have cost 1
  - Valid path distances of 1 through 15

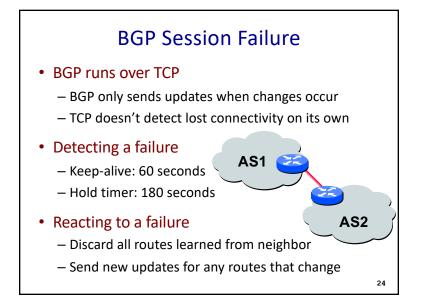
20

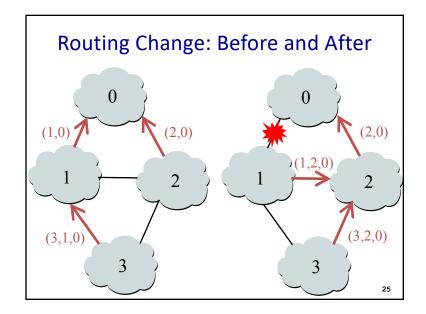
- ... with 16 representing infinity
- Used mainly in small networks

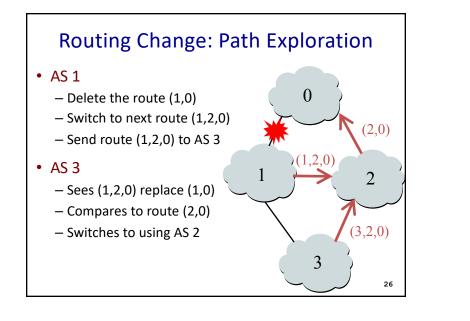
Reducing Convergence Time With Path-Vector Routing (e.g., Border Gateway Protocol)

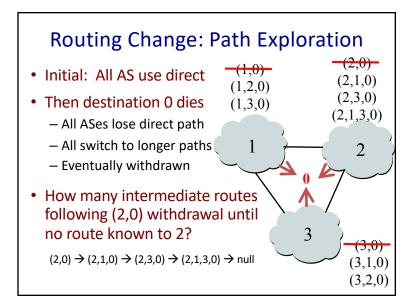












## BGP Converges Slowly

- Path vector avoids count-to-infinity
  - But, ASes still must explore many alternate paths to find highest-ranked available path
- Fortunately, in practice
  - Most popular destinations have stable BGP routes
  - Most instability lies in a few unpopular destinations
- Still, lower BGP convergence delay is a goal
  - Can be tens of seconds to tens of minutes

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