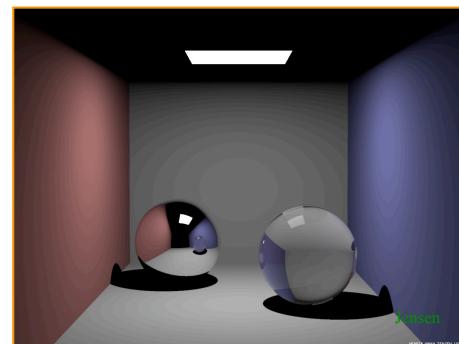




# Global Illumination

Adam Finkelstein  
Princeton University  
COS 526, Fall 2005

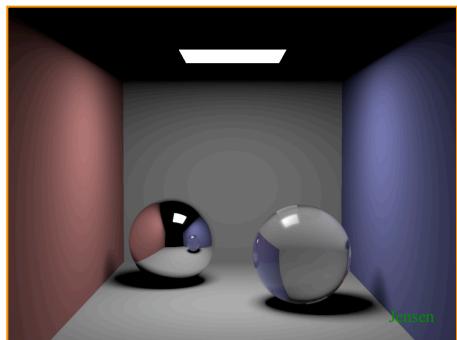
## Path Types



Ray tracing

Henrik Wann Jensen

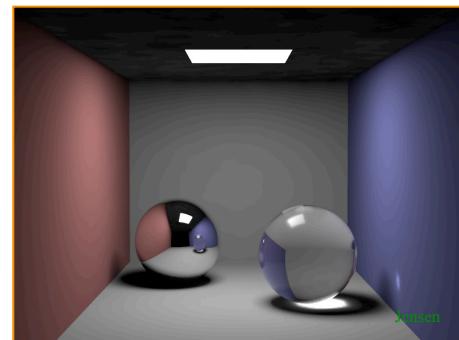
## Path Types



+ soft shadows

Henrik Wann Jensen

## Path Types



+ caustics

Henrik Wann Jensen

## Path Types



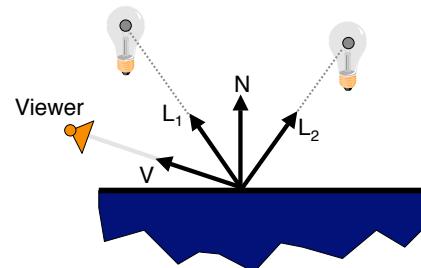
+ indirect diffuse illumination

Henrik Wann Jensen

## Direct Illumination



- Multiple light sources:



$$I = I_E + K_A I_{AL} + \sum_i (K_D (N \cdot L_i) I_i + K_S (V \cdot R_i)^n I_i)$$

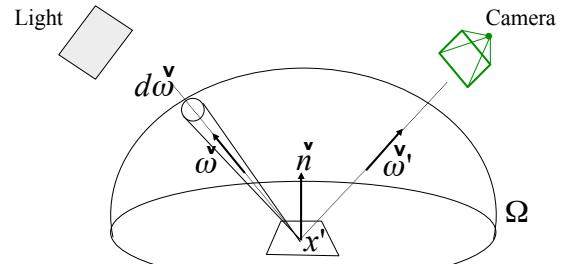
## Overview

- Global illumination
  - Rendering equation
- Solution methods
  - OpenGL
  - Ray tracing
  - Path tracing
  - Radiosity
- Path types
  - $L(SID)^*E$



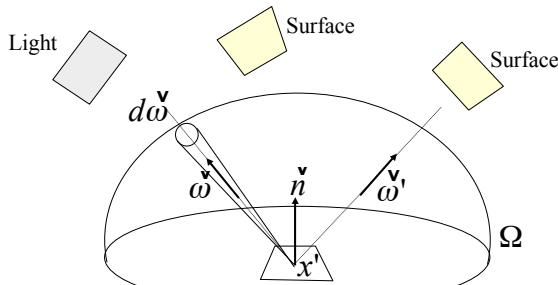
## Direct Illumination

$$L_o(x', \omega') = L_e(x', \omega') + \int_{\Omega_L} f_r(x', \omega, \omega') L_i(x', \omega) (\omega \cdot n) d\omega$$



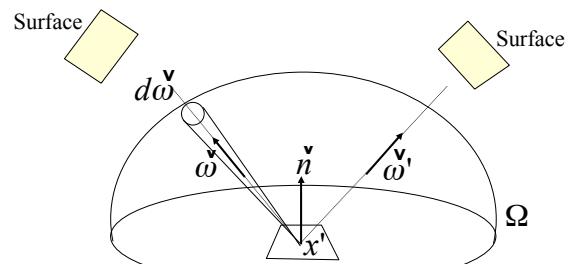
## Global Illumination

$$L_o(x', \omega') = L_e(x', \omega') + \int_{\Omega} f_r(x', \omega, \omega') L_i(x', \omega) (\omega \cdot n) d\omega$$



## Rendering Equation

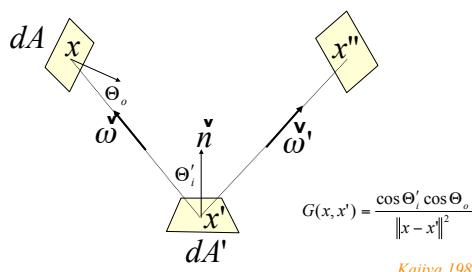
$$L_o(x', \omega') = L_e(x', \omega') + \int_{\Omega} f_r(x', \omega, \omega') L_i(x', \omega) (\omega \cdot n) d\omega$$



Kajiya 1986

## Rendering Equation (2)

$$L(x' \rightarrow x'') = L_e(x' \rightarrow x'') + \int_S f_r(x \rightarrow x' \rightarrow x'') L(x \rightarrow x') V(x, x') G(x, x') dA$$



## Photorealistic Rendering

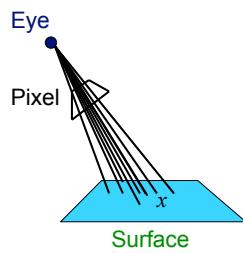
- Rendering = integration
  - Antialiasing
  - Soft shadows
  - Indirect illumination
  - Caustics



## Photorealistic Rendering



- Rendering = integration
  - Antialiasing
  - Soft shadows
  - Indirect illumination
  - Caustics

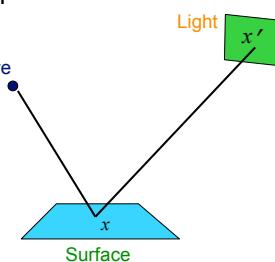


$$L_p = \int_S L(x \rightarrow e) dA$$

## Photorealistic Rendering



- Rendering = integration
  - Antialiasing
  - Soft shadows
  - Indirect illumination
  - Caustics



$$L(x, \omega) = L_e(x, x \rightarrow e) + \int_S f_r(x, x' \rightarrow x, x \rightarrow e) L(x' \rightarrow x) V(x, x') G(x, x') dA$$

## Photorealistic Rendering



- Rendering = integration
  - Antialiasing
  - Soft shadows
  - Indirect illumination
  - Caustics

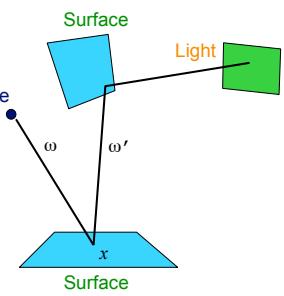


$$L(x, \omega) = L_e(x, x \rightarrow e) + \int_S f_r(x, x' \rightarrow x, x \rightarrow e) L(x' \rightarrow x) V(x, x') G(x, x') dA$$

## Photorealistic Rendering



- Rendering = integration
  - Antialiasing
  - Soft shadows
  - Indirect illumination
  - Caustics



$$L_o(x, \omega) = L_e(x, \omega) + \int_{\Omega} f_r(x, \omega', \omega) L_i(x, \omega') (\omega' \cdot \hat{n}) d\omega'$$

## Photorealistic Rendering



- Rendering = integration
  - Antialiasing
  - Soft shadows
  - Indirect illumination
  - Caustics

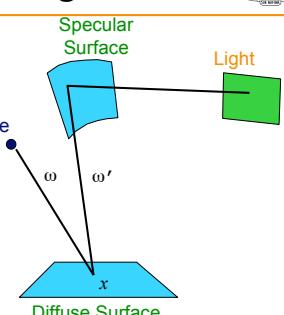


$$L_o(x, \omega) = L_e(x, \omega) + \int_{\Omega} f_r(x, \omega', \omega) L_i(x, \omega') (\omega' \cdot \hat{n}) d\omega'$$

## Photorealistic Rendering



- Rendering = integration
  - Antialiasing
  - Soft shadows
  - Indirect illumination
  - Caustics

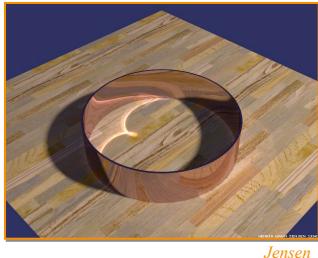


$$L_o(x, \omega) = L_e(x, \omega) + \int_{\Omega} f_r(x, \omega', \omega) L_i(x, \omega') (\omega' \cdot \hat{n}) d\omega'$$

## Photorealistic Rendering



- Rendering = integration
  - Antialiasing
  - Soft shadows
  - Indirect illumination
  - Caustics



Jensen

$$L_o(x, \vec{w}) = L_e(x, \vec{w}) + \int_{\Omega} f_r(x, \vec{w}, \vec{w}') L_i(x, \vec{w}') (\vec{w}' \cdot \vec{n}) d\vec{w}$$

## Challenge



- Rendering integrals are difficult to evaluate
  - Recursion:  $L = f(L)$
  - Multiple dimensions
  - Discontinuities
    - » Partial occluders
    - » Highlights
    - » Caustics



Jensen

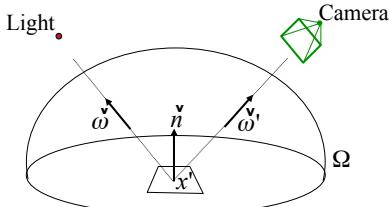
$$L(x, \vec{w}) = L_e(x, x \rightarrow e) + \int_S f_r(x, x' \rightarrow x, x \rightarrow e) L(x' \rightarrow x) V(x, x') G(x, x') dA$$

## OpenGL



$$L_o(x', \vec{\omega}') = L_e(x', \vec{\omega}') + \int_{\Omega} f_r(x', \vec{\omega}, \vec{\omega}') L_i(x', \vec{\omega}) (\vec{\omega} \cdot \vec{n}) d\vec{\omega}$$

Assume direct illumination from point lights and ignore visibility

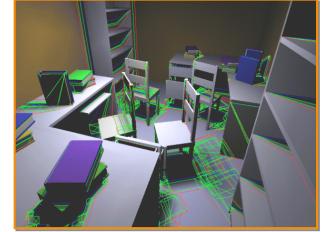


$$L_o(x', \vec{\omega}') = L_e(x', \vec{\omega}') + \sum_{i=1}^{n_{lights}} f_r(x', \vec{\omega}, \vec{\omega}') L_i(x', \vec{\omega}) (\vec{\omega} \cdot \vec{n})$$

## Challenge



- Rendering integrals are difficult to evaluate
  - Recursion:  $L = f(L)$
  - Multiple dimensions
  - Discontinuities
    - » Partial occluders
    - » Highlights
    - » Caustics



Drettakis

$$L(x, \vec{w}) = L_e(x, x \rightarrow e) + \int_S f_r(x, x' \rightarrow x, x \rightarrow e) L(x' \rightarrow x) V(x, x') G(x, x') dA$$

## Overview

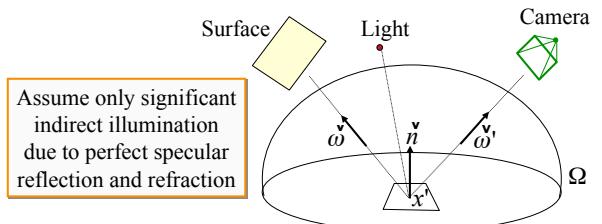


- Global illumination
  - Rendering equation
- Solution methods
  - OpenGL
  - Ray tracing
  - Path tracing
  - Radiosity
- Path types
  - $L(SID)^*E$

## Ray Tracing



$$L_o(x', \vec{\omega}') = L_e(x', \vec{\omega}') + \int_{\Omega} f_r(x', \vec{\omega}, \vec{\omega}') L_i(x', \vec{\omega}) (\vec{\omega} \cdot \vec{n}) d\vec{\omega}$$



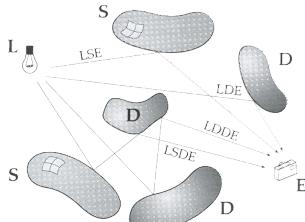
$$L_o(x', \vec{\omega}') = L_e(x', \vec{\omega}') + \sum_{i=1}^{n_{lights}} f_r(x', \vec{\omega}, \vec{\omega}') L_i(x', \vec{\omega}) (\vec{\omega} \cdot \vec{n}) + \text{specular}$$

## Monte Carlo Path Tracing



$$L_o(x', \omega') = L_e(x', \omega') + \int_{\Omega} f_r(x', \omega, \omega') L_i(x', \omega) (\omega \cdot n) d\omega$$

Estimate integral  
for each pixel  
by random sampling



Also:

- Depth of field
- Motion blur
- etc.

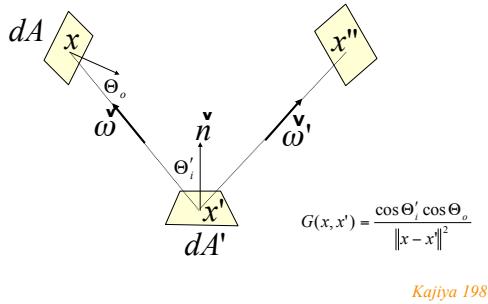
## Indirect Diffuse Illumination



## Rendering Equation



$$L(x' \rightarrow x'') = L_e(x' \rightarrow x'') + \int_S f_r(x \rightarrow x' \rightarrow x'') L(x \rightarrow x') V(x, x') G(x, x') dA$$



## Radiosity Equation



$$L(x' \rightarrow x'') = L_e(x' \rightarrow x'') + \int_S f_r(x \rightarrow x' \rightarrow x'') L(x \rightarrow x') V(x, x') G(x, x') dA$$

Assume everything  
is Lambertian

$$\rho(x') = f_r(x \rightarrow x' \rightarrow x'') \pi$$

$$L(x') = L_e(x') + \frac{\rho(x')}{\pi} \int_S L(x) V(x, x') G(x, x') dA$$

Convert to  
Radiosities

$$B = \int_{\Omega} L_o \cos \theta d\omega$$

$$L = \frac{B}{\pi}$$

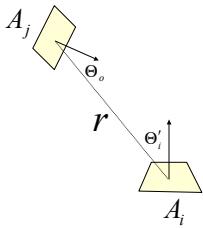
$$B(x') = B_e(x') + \frac{\rho(x')}{\pi} \int_S B(x) V(x, x') G(x, x') dA$$

## Radiosity Approximation



$$B(x') = B_e(x') + \frac{\rho(x')}{\pi} \int_S B(x) V(x, x') G(x, x') dA$$

Discretize the surfaces  
into "elements"



$$B_i = E_i + \rho_i \sum_{j=1}^N B_j F_{ij}$$

$$\text{where } F_{ij} = \frac{1}{A_i A_j} \int \int \frac{V_{ij} \cos \Theta'_i \cos \Theta_o}{\pi r^2} dA_j dA_i$$

## System of Equations



$$B_i = E_i + \rho_i \sum_{j=1}^N B_j F_{ij}$$

$$E_i = B_i - \rho_i \sum_{j=1}^N B_j F_{ij}$$

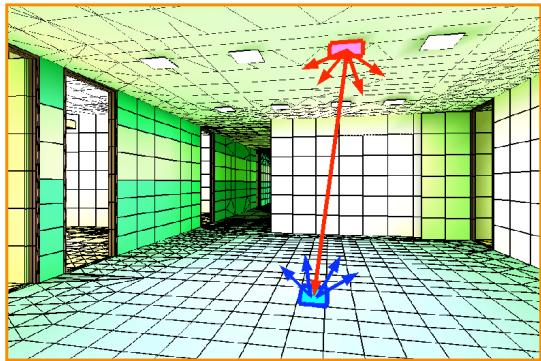
$$B_i - \rho_i \sum_{j=1}^N B_j F_{ij} = E_i$$

$$\begin{bmatrix} 1 - \rho_1 F_{1,1} & \dots & \dots & -\rho_1 F_{1,n} \\ -\rho_2 F_{2,1} & 1 - \rho_2 F_{2,2} & \dots & -\rho_2 F_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ -\rho_{n-1} F_{n-1,1} & \dots & \dots & 1 - \rho_{n-1} F_{n-1,n} \\ -\rho_n F_{n,1} & \dots & \dots & -\rho_n F_{n,n} \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \\ \vdots \\ B_n \end{bmatrix} = \begin{bmatrix} E_1 \\ E_2 \\ \vdots \\ E_n \end{bmatrix}$$

$$(1 - \rho_i \sum_{j=1}^N F_{ij}) B_i - \rho_i \sum_{j=1}^N F_{ij} B_j = E_i$$

$$B_i A_i = E_i A_i + \rho_i \sum_{j=1}^N F_{ji} B_j A_j \quad \leftarrow \text{energy balance equation}$$

## Radiosity Intuition



## Radiosity



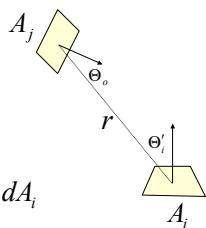
- Issues

- Computing form factors
- Selecting basis functions for radiosities
- Solving linear system of equations
- Meshing surfaces into elements
- Rendering images

## Form Factor



- Fraction of energy leaving element i that arrives at element j

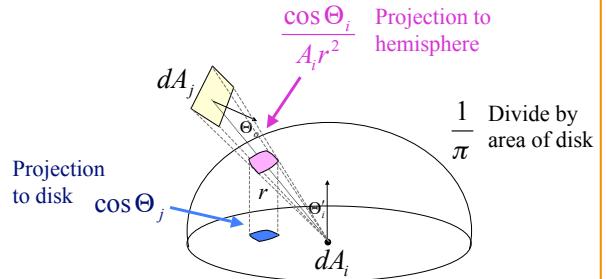


$$F_{ij} = \frac{1}{A_i} \int \int \frac{V_{ij} \cos \Theta'_i \cos \Theta_o}{\pi r^2} dA_j dA_i$$

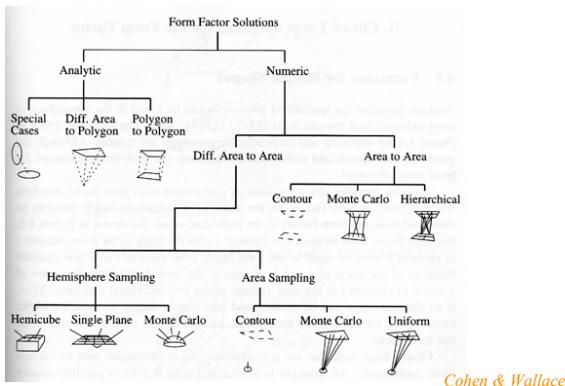
## Form Factor Intuition



$$F_{di-dj} = \frac{1}{A_i} \frac{V_{ij} \cos \Theta_i \cos \Theta_j}{\pi r^2}$$



## Computing Form Factors



## Solving the System of Equations



- Challenges:

- Size of matrix
- Cost of computing form factors
- Computational complexity

$$\begin{bmatrix} 1 - \rho_1 F_{1,1} & \cdot & \cdot & \cdot & -\rho_1 F_{1,n} \\ -\rho_2 F_{2,1} & 1 - \rho_2 F_{2,2} & \cdot & \cdot & -\rho_2 F_{2,n} \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ -\rho_{n-1} F_{n-1,1} & \cdot & \cdot & \cdot & -\rho_{n-1} F_{n-1,n} \\ -\rho_n F_{n,1} & \cdot & \cdot & \cdot & 1 - \rho_n F_{n,n} \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \\ \vdots \\ \vdots \\ B_n \end{bmatrix} = \begin{bmatrix} E_1 \\ E_2 \\ \vdots \\ \vdots \\ E_n \end{bmatrix}$$

**A**

**x** = **b**

## Solving the System of Equations



- Solution methods:

- Invert the matrix* –  $O(n^3)$

- Iterative methods* –  $O(n^2)$

- Hierarchical methods* –  $O(n)$

$$\begin{bmatrix} 1 - \rho_1 F_{1,1} & \cdot & \cdot & \cdot & -\rho_1 F_{1,n} \\ -\rho_2 F_{2,1} & 1 - \rho_2 F_{2,2} & \cdot & \cdot & -\rho_2 F_{2,n} \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ -\rho_{n-1} F_{n-1,1} & \cdot & \cdot & \cdot & -\rho_{n-1} F_{n-1,n} \\ -\rho_n F_{n,1} & \cdot & \cdot & \cdot & 1 - \rho_n F_{n,n} \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \\ \vdots \\ \vdots \\ B_n \end{bmatrix} = \begin{bmatrix} E_1 \\ E_2 \\ \vdots \\ \vdots \\ E_n \end{bmatrix}$$

**A**

**x** = **b**

## Gauss-Seidel Iteration



- for all  $i$
- $B_i = E_i$
- while not converged
- for each  $i$  in turn
- $B_i = E_i + \rho_i \sum_{j \neq i} B_j F_{ij}$
- display the image using  $B_i$  as the intensity of patch  $i$ .

## Gauss-Seidel Iteration



- Two interpretations:

- Iteratively relax rows of linear system*

- Iteratively gather radiosity to elements*

$$\begin{bmatrix} 1 - \rho_1 F_{1,1} & \cdot & \cdot & \cdot & -\rho_1 F_{1,n} \\ -\rho_2 F_{2,1} & 1 - \rho_2 F_{2,2} & \cdot & \cdot & -\rho_2 F_{2,n} \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ -\rho_{n-1} F_{n-1,1} & \cdot & \cdot & \cdot & -\rho_{n-1} F_{n-1,n} \\ -\rho_n F_{n,1} & \cdot & \cdot & \cdot & 1 - \rho_n F_{n,n} \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \\ \vdots \\ \vdots \\ B_n \end{bmatrix} = \begin{bmatrix} E_1 \\ E_2 \\ \vdots \\ \vdots \\ E_n \end{bmatrix}$$

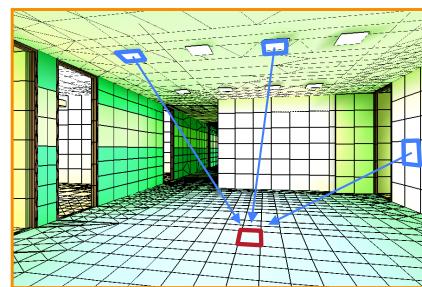
## Gauss-Seidel Iteration



- Two interpretations:

- Iteratively relax rows of linear system*

- Iteratively gather radiosity to elements*

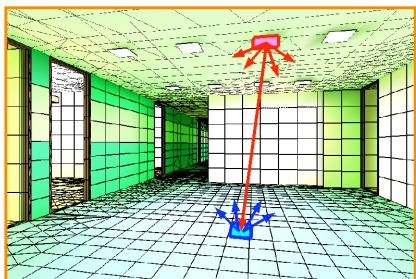


## Progressive Radiosity



- Interpretation:

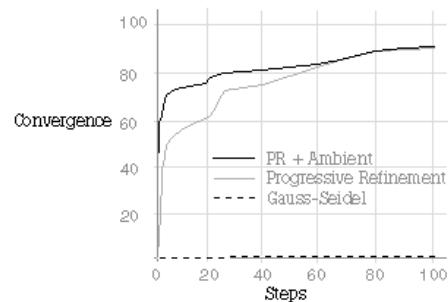
- Iteratively shoot “unshot” radiosity from elements*
- Select shooters in order of unshot radiosity*



## Progressive Radiosity



- Adaptive refinement



Year

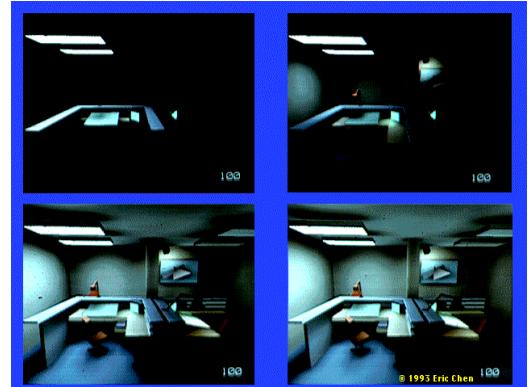
## Progressive Radiosity



### PROGRESSIVE SOLUTION

The above images show increasing levels of global diffuse illumination. From left to right: 0 bounces, 1 bounce, 3 bounces.

## Progressive Radiosity



## Surface Meshing



- Store radiosity across surface
  - Few elements
  - Represents function well
  - Few visible artifacts

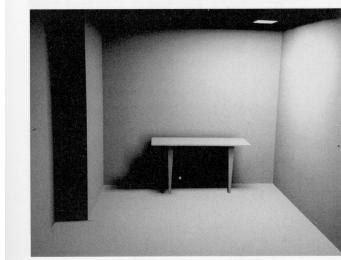


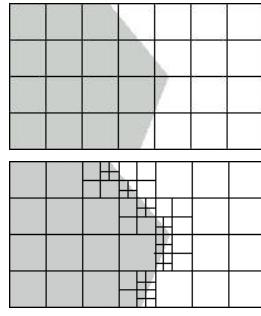
Figure 6.2: A radiosity image computed using a uniform mesh.

Cohen & Wallace

## Adaptive Meshing

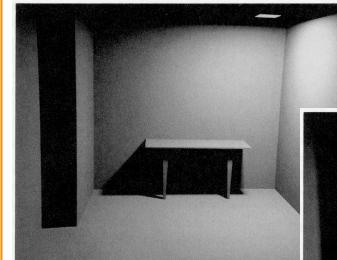


- Refine mesh in areas of high residual

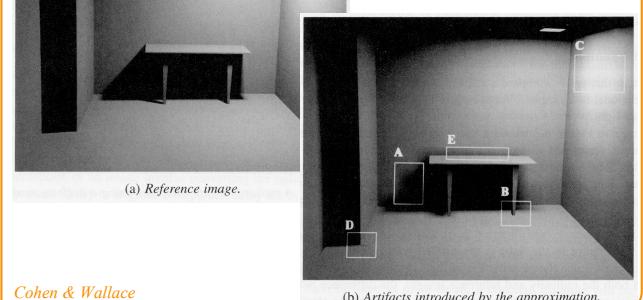


Yeap

## Artifacts of Bad Surface Meshing

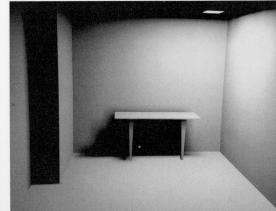


(a) Reference image.

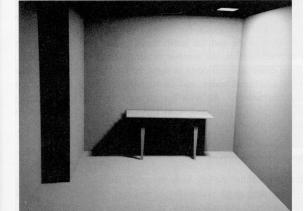


(b) Artifacts introduced by the approximation.

## Adaptive Meshing



Uniform mesh



Adaptive mesh

Cohen & Wallace

## Error Comparison

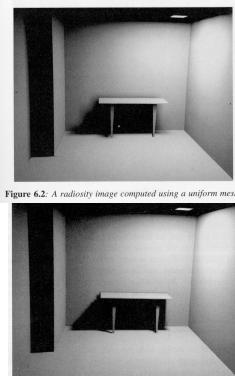


Figure 6.2: A radiosity image computed using a uniform mesh.

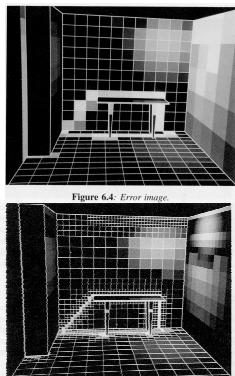
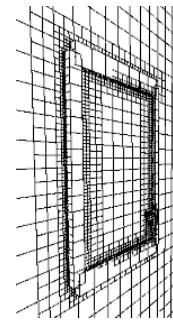


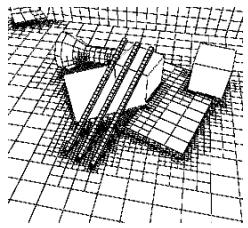
Figure 6.4: Error image.

Cohen & Wallace. Adaptive subdivision. Compare to Figure 6.2. Figure 6.24: Error image for adaptive subdivision. Compare to Figures 6.4 and

## Adaptive Meshing

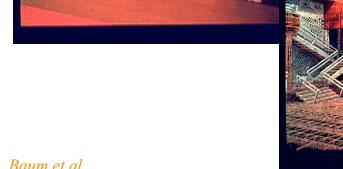


## Adaptive Meshing



(table top from different angle)

## Adaptive Meshing

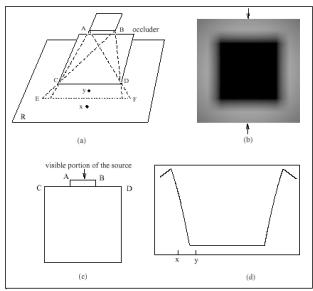


Baum et al.

## Discontinuity Meshing



- Capture discontinuities in radiosity across a surface with explicit mesh boundaries

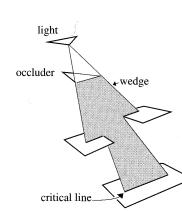


Lischinski et al.

## Discontinuity Meshing



- Capture discontinuities in radiosity across a surface with explicit mesh boundaries



Discontinuity  
Mesh

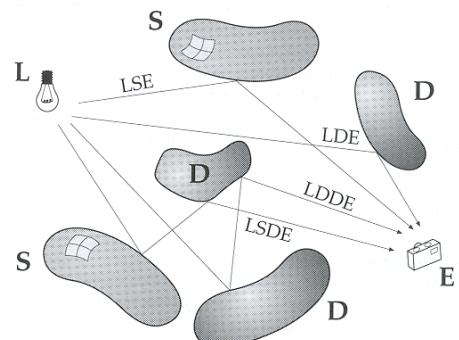
Lischinski et al.

## Overview

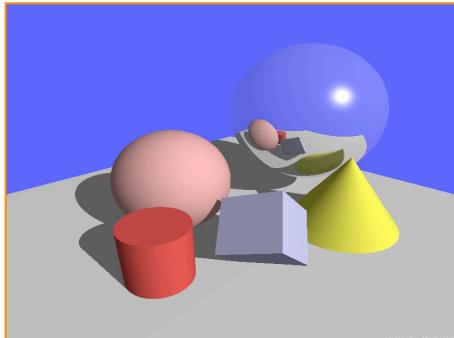
- Global illumination
  - Rendering equation
- Solution methods
  - OpenGL
  - Ray tracing
  - Path tracing
  - Radiosity
- Path types
  - $L(SID)^*E$



## Path Types



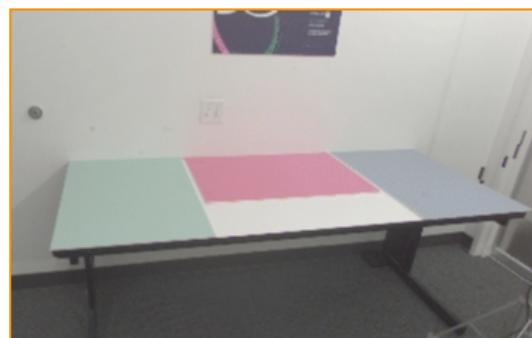
## Path Types?



Henrik Wann Jensen



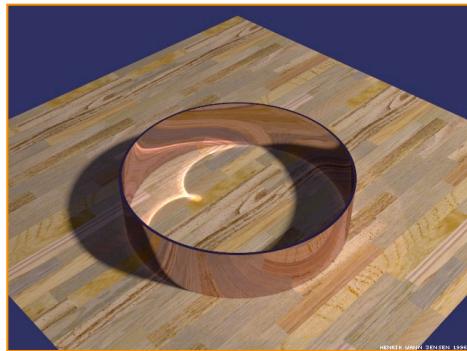
## Path Types?



Paul Debevec



## Path Types?



Henrik Wann Jensen



## Path Types?

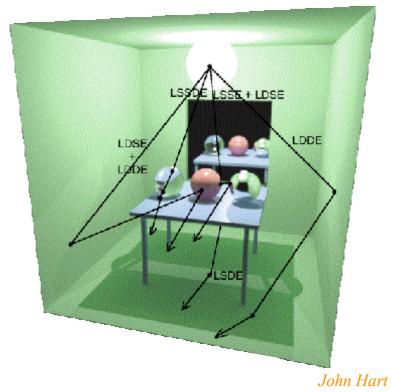


RenderPark



## Path Types

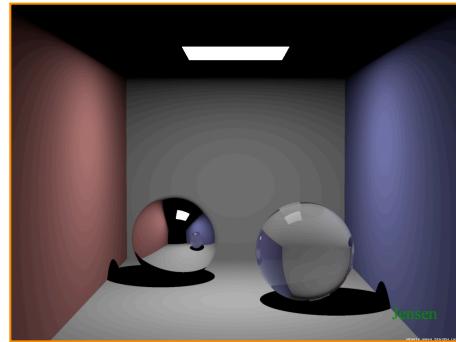
- OpenGL
  - LDE
- Ray tracing
  - LDS\*E
- Radiosity
  - LD\*E
- Path tracing
  - L(DIS)\*E



John Hart



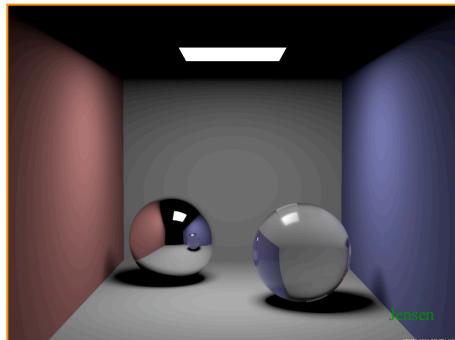
## Path Types



Ray tracing

Henrik Wann Jensen

## Path Types

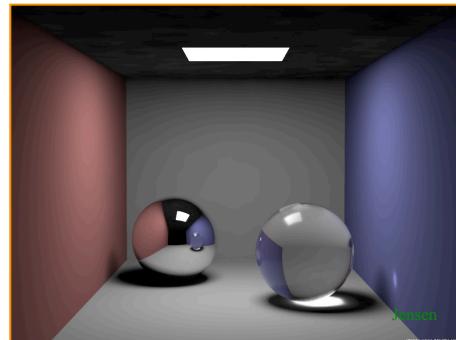


+ soft shadows

Henrik Wann Jensen



## Path Types

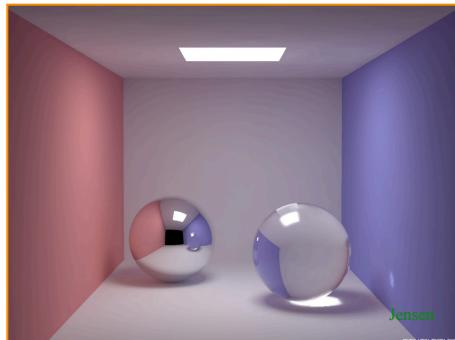


+ caustics

Henrik Wann Jensen



## Path Types



+ indirect diffuse illumination

Henrik Wann Jensen



## Summary

- Global illumination
  - Rendering equation
- Solution methods
  - OpenGL
  - Ray tracing
  - Radiosity
  - Path tracing
- Path types
  - L(SID)\*E

