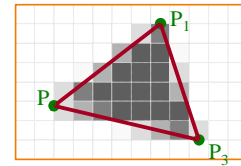
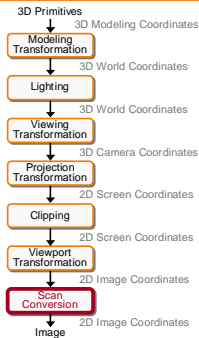


Scan Conversion & Shading

Thomas Funkhouser
Princeton University
COS 426, Spring 2004

3D Rendering Pipeline (for direct illumination)



Scan Conversion & Shading

Overview

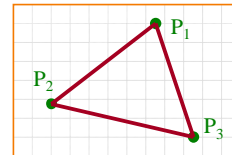
- Scan conversion
 - Figure out which pixels to fill
- Shading
 - Determine a color for each filled pixel

Scan Conversion

- Render an image of a geometric primitive by setting pixel colors

```
void SetPixel(int x, int y, Color rgba)
```

- Example: Filling the inside of a triangle

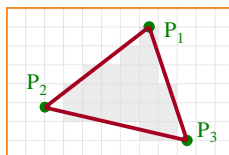


Scan Conversion

- Render an image of a geometric primitive by setting pixel colors

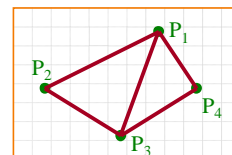
```
void SetPixel(int x, int y, Color rgba)
```

- Example: Filling the inside of a triangle



Triangle Scan Conversion

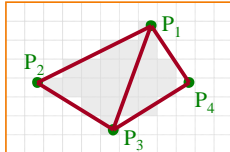
- Properties of a good algorithm
 - Symmetric
 - Straight edges
 - Antialiased edges
 - No cracks between adjacent primitives
 - MUST BE FAST!



Triangle Scan Conversion



- Properties of a good algorithm
 - Symmetric
 - Straight edges
 - Antialiased edges
 - No cracks between adjacent primitives
 - MUST BE FAST!

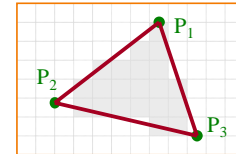


Simple Algorithm



- Color all pixels inside triangle

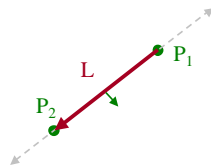
```
void ScanTriangle(Triangle T, Color rgba){
    for each pixel P at (x,y){
        if (Inside(T, P))
            SetPixel(x, y, rgba);
    }
}
```



Line defines two halfspaces



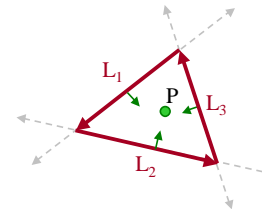
- Implicit equation for a line
 - On line: $ax + by + c = 0$
 - On right: $ax + by + c < 0$
 - On left: $ax + by + c > 0$



Inside Triangle Test



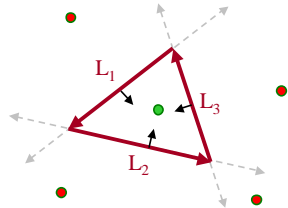
- A point is inside a triangle if it is in the positive halfspace of all three boundary lines
 - Triangle vertices are ordered counter-clockwise
 - Point must be on the left side of every boundary line



Inside Triangle Test



```
Boolean Inside(Triangle T, Point P)
{
    for each boundary line L of T {
        Scalar d = L.a*P.x + L.b*P.y + L.c;
        if (d < 0.0) return FALSE;
    }
    return TRUE;
}
```

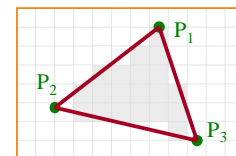


Simple Algorithm



- What is bad about this algorithm?

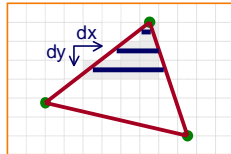
```
void ScanTriangle(Triangle T, Color rgba){
    for each pixel P at (x,y){
        if (Inside(T, P))
            SetPixel(x, y, rgba);
    }
}
```



Triangle Sweep-Line Algorithm



- Take advantage of spatial coherence
 - Compute which pixels are inside using horizontal spans
 - Process horizontal spans in scan-line order
- Take advantage of edge linearity
 - Use edge slopes to update coordinates incrementally

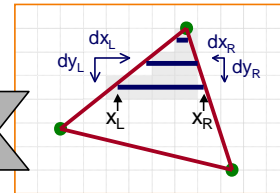


Triangle Sweep-Line Algorithm



```
void ScanTriangle(Triangle T, Color rgba){
    for each edge pair {
        initialize  $x_L$ ,  $x_R$ ;
        compute  $dx_L/dy_L$  and  $dx_R/dy_R$ ;
        for each scanline at y
            for (int x =  $x_L$ ; x <=  $x_R$ ; x++)
                SetPixel(x, y, rgba);
             $x_L$  +=  $dx_L/dy_L$ ;
             $x_R$  +=  $dx_R/dy_R$ ;
    }
}
```

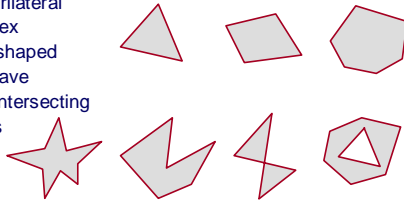
Bresenham's algorithm works the same way, but uses only integer operations!



Polygon Scan Conversion



- Fill pixels inside a polygon
 - Triangle
 - Quadrilateral
 - Convex
 - Star-shaped
 - Concave
 - Self-intersecting
 - Holes

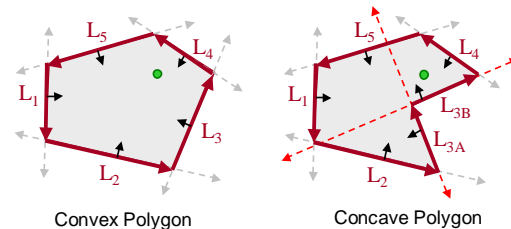


What problems do we encounter with arbitrary polygons?

Polygon Scan Conversion



- Need better test for points inside polygon
 - Triangle method works only for convex polygons



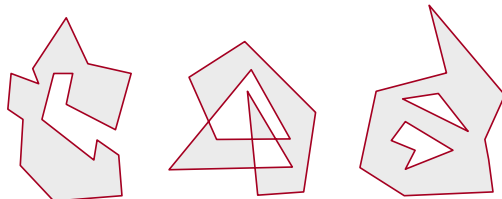
Convex Polygon

Concave Polygon

Inside Polygon Rule



- What is a good rule for which pixels are inside?



Concave

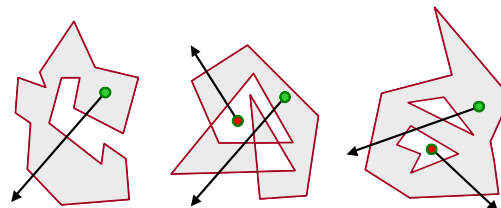
Self-Intersecting

With Holes

Inside Polygon Rule



- Odd-parity rule
 - Any ray from P to infinity crosses odd number of edges



Concave

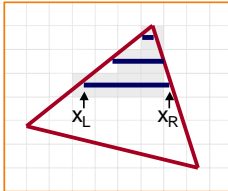
Self-Intersecting

With Holes

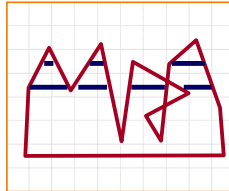
Polygon Sweep-Line Algorithm



- Incremental algorithm to find spans, and determine insideness with odd parity rule
 - Takes advantage of scanline coherence



Triangle

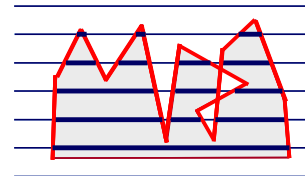


Polygon

Polygon Sweep-Line Algorithm



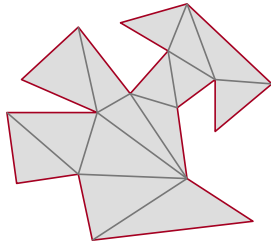
```
void ScanPolygon(Triangle T, Color rgba){
    sort edges by maxy
    make empty "active edge list"
    for each scanline (top-to-bottom) {
        insert/remove edges from "active edge list"
        update x coordinate of every active edge
        sort active edges by x coordinate
        for each pair of active edges (left-to-right)
            SetPixels(xi, xi+1, Y, rgba);
    }
}
```



Hardware Scan Conversion



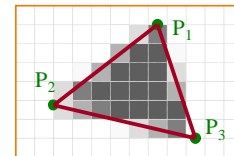
- Convert everything into triangles
 - Scan convert the triangles



Hardware Antialiasing



- Supersample pixels
 - Multiple samples per pixel
 - Average subpixel intensities (box filter)
 - Trades intensity resolution for spatial resolution



Overview



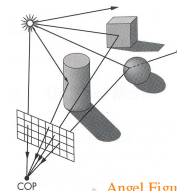
- Scan conversion
 - Figure out which pixels to fill
- Shading
 - Determine a color for each filled pixel

Shading



- How do we choose a color for each filled pixel?
 - Each illumination calculation for a ray from the eyepoint through the view plane provides a radiance sample
 - How do we choose where to place samples?
 - How do we filter samples to reconstruct image?

Emphasis on methods that can be implemented in hardware

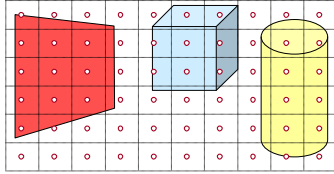


Angel Figure 6.34

Ray Casting



- Simplest shading approach is to perform independent lighting calculation for every pixel
 - When is this unnecessary?

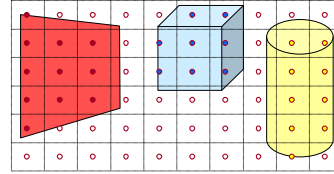


$$I = I_E + K_A I_{AL} + \sum_i (K_D (N \cdot L_i) I_i + K_S (V \cdot R_i)^n I_i)$$

Polygon Shading



- Can take advantage of spatial coherence
 - Illumination calculations for pixels covered by same primitive are related to each other



$$I = I_E + K_A I_{AL} + \sum_i (K_D (N \cdot L_i) I_i + K_S (V \cdot R_i)^n I_i)$$

Polygon Shading Algorithms



- Flat Shading
- Gouraud Shading
- Phong Shading

Polygon Shading Algorithms

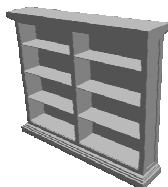


- **Flat Shading**
- Gouraud Shading
- Phong Shading

Flat Shading



- What if a faceted object is illuminated only by directional light sources and is either diffuse or viewed from infinitely far away

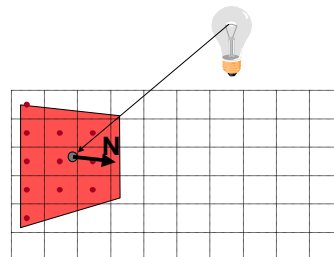


$$I = I_E + K_A I_{AL} + \sum_i (K_D (N \cdot L_i) I_i + K_S (V \cdot R_i)^n I_i)$$

Flat Shading



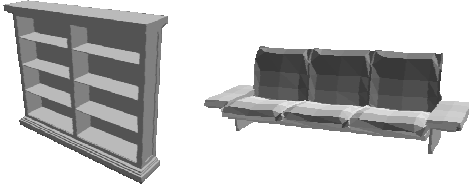
- One illumination calculation per polygon
 - Assign all pixels inside each polygon the same color



Flat Shading



- Objects look like they are composed of polygons
 - OK for polyhedral objects
 - Not so good for smooth surfaces



Polygon Shading Algorithms

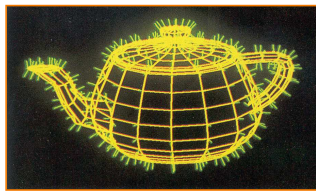


- Flat Shading
- **Gouraud Shading**
- Phong Shading

Gouraud Shading



- What if smooth surface is represented by polygonal mesh with a normal at each vertex?



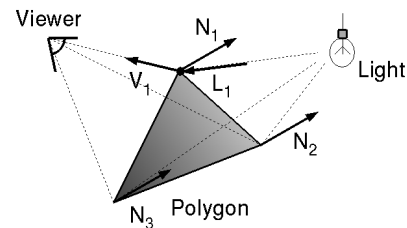
Watt Plate 7

$$I = I_E + K_A I_{AL} + \sum_i (K_D (N \cdot L_i) I_i + K_S (V \cdot R_i)^n I_i)$$

Gouraud Shading



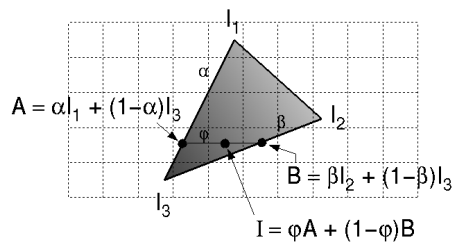
- Method 1: One lighting calculation per vertex
 - Assign pixels inside polygon by interpolating colors computed at vertices



Gouraud Shading



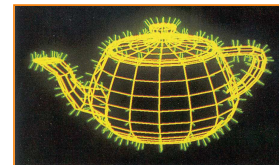
- Bilinearly interpolate colors at vertices down and across scan lines



Gouraud Shading



- Smooth shading over adjacent polygons
 - Curved surfaces
 - Illumination highlights
 - Soft shadows



Mesh with shared normals at vertices

Watt Plate 7

Gouraud Shading



- Produces smoothly shaded polygonal mesh
 - Piecewise linear approximation
 - Need fine mesh to capture subtle lighting effects



Flat Shading

Gouraud Shading

Polygon Shading Algorithms

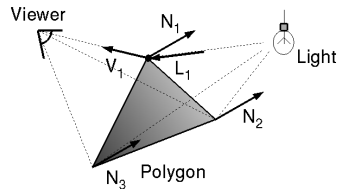


- Flat Shading
- Gouraud Shading
- **Phong Shading**

Phong Shading



- What if polygonal mesh is too coarse to capture illumination effects in polygon interiors?

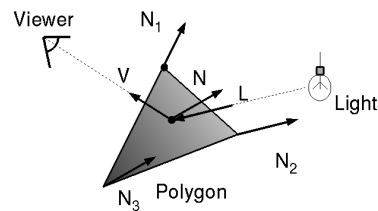


$$I = I_E + K_A I_{AL} + \sum_i (K_D (N \cdot L_i) I_i + K_S (V \cdot R_i)^n I_i)$$

Phong Shading



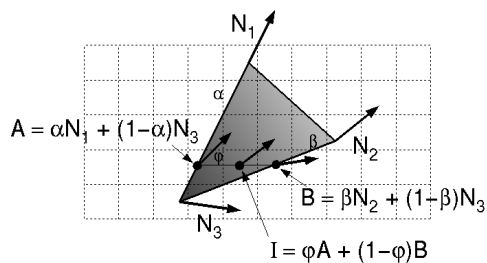
- Method 2: One lighting calculation per pixel
 - Approximate surface normals for points inside polygons by bilinear interpolation of normals from vertices



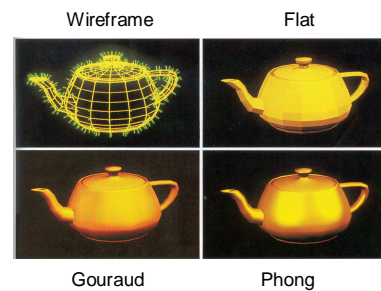
Phong Shading



- Bilinearly interpolate surface normals at vertices down and across scan lines



Polygon Shading Algorithms



Gouraud

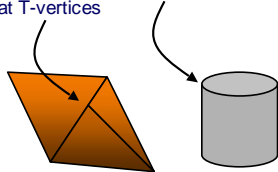
Phong

Watt Plate 7

Shading Issues



- Problems with interpolated shading:
 - Polygonal silhouettes
 - Perspective distortion
 - Orientation dependence (due to bilinear interpolation)
 - Problems computing shared vertex normals
 - Problems at T-vertices



Summary



- 2D polygon scan conversion
 - Paint pixels inside primitive
 - Sweep-line algorithm for polygons
- Polygon Shading Algorithms
 - Flat
 - Gouraud
 - Phong
 - Ray casting
- Key ideas:
 - Sampling and reconstruction
 - Spatial coherence

↑ Less expensive
↓ More accurate