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1 Bounding Error on Mean

Given a set of examples $x_i = [0, 1]$ $i = \{1...m\}$ drawn from a distribution D we would like to calculate the observed mean \hat{p}

$$\hat{p} = \frac{1}{m} \sum_{i=1}^{m} x_i \tag{1}$$

and compare that to the real mean of D, call it p. It is useful to define the quantity

$$q \equiv p + \epsilon. \tag{2}$$

We could weakly bound the probability of \hat{p} being greater than q using Markov's inequality:

$$\Pr[x \ge kEX] \le 1/k \tag{3}$$

$$\Pr[\hat{p} \ge s] \le p/s \tag{4}$$

$$\Pr[\hat{p} \ge q] \le p/q < 1. \tag{5}$$

However, we can do better than that, in fact **THEOREM**

$$\Pr[\hat{p} \ge q] \le \exp(-\operatorname{RE}(q||p)m) \tag{6}$$

where

$$\operatorname{RE}(q||p) = p \ln\left(\frac{p}{q}\right) + (1-p) \ln\left(\frac{1-p}{1-q}\right)$$
(7)

PROOF

$$\Pr[\hat{p} \ge q] = \Pr[e^{\lambda \hat{p}m} \ge e^{\lambda qm}] \le e^{-\lambda qm} E[e^{\lambda \hat{p}m}]$$
(8)

$$= e^{-\lambda qm} E\left[e^{\lambda \sum x_i}\right] = e^{-\lambda qm} E\left[\prod_{i=1}^m e^{\lambda x_i}\right]$$
(9)

now because each x_i is an independent measurement

$$e^{-\lambda qm} \prod_{i=1}^{m} \mathbf{E}[e^{\lambda x_i}].$$
(10)

Now note that

$$e^{\lambda x} \le 1 - x + e^{\lambda} x \ \forall x \in [0, 1]$$
(11)

which we can use to show that

$$e^{-\lambda qm} \prod_{i=1}^{m} \mathbf{E}[e^{\lambda x_i}] \le e^{-\lambda qm} \prod_{i=1}^{m} \mathbf{E}[1 - x_i + e^{\lambda} x_i]$$
(12)

$$=e^{-\lambda qm}\prod_{i=1}^{m}\left(1-p+e^{\lambda}p\right)=e^{-\lambda qm}\left(1-p+e^{\lambda}p\right)^{m}$$
(13)

$$= \left(e^{-\lambda q} \left(1 - p + e^{\lambda} p\right)\right)^m.$$
(14)

Now if we minimize this probability with respect to lambda you get

$$\lambda_{min} = \ln\left(\frac{q(1-p)}{(1-q)p}\right).$$
(15)

Plugging that back into the probability you get the desired bound

$$\Pr[\hat{p} \ge q] \le \exp(-\operatorname{RE}(q||p)m) \tag{16}$$

Note that by defining $y_i = 1 - x_i$ we can prove the symmetric result that

$$\Pr[\hat{p} \ge p - \epsilon] \le \exp(-\operatorname{RE}(p - \epsilon || p)m) \tag{17}$$

This theorem can also be used to prove corollaries

$$\Pr[\hat{p} \ge p + \alpha p] \le e^{-mp\alpha^2/3} \tag{18}$$

$$\Pr[\hat{p} \le p - \alpha p] \le e^{-mp\alpha^2/2} \tag{19}$$

This is done by plugging in $\epsilon = \alpha p$ and then bounding $\operatorname{RE}(q||p)$.

Thinking back to the double-sample proof: m(h) was the number of mistakes on S'. Thus $\hat{p} = m(h)/m$ and $p = \epsilon$ and so

$$\Pr[m(h) < m\epsilon/2] = \Pr[\hat{p} < p - p/2] \le e^{-mp/8}.$$
(20)

If $m \geq 8/\epsilon$ then

$$\Pr[m(h) < m\epsilon/2] \le e^{-1} < 1/2.$$
(21)

2 McDiarmid's Inequality

Let

$$f(x_1,\ldots,x_m) \tag{22}$$

be any function such that for all $x_1, \ldots, x_m; x'_i$,

$$\left|f(x_1,\ldots,x_i,\ldots,x_m) - f(x_1,\ldots,x_i',\ldots,x_m)\right| \le c_i.$$

$$(23)$$

In other words, changing x_i can never change f by more than c_i . Let $X_1...X_m$ be independent but not necessarily identically distributed.

THEOREM

$$\Pr\left[f(x_1...x_m) \ge \operatorname{E}[f(x_1...x_m)] + \epsilon\right] \le \exp\left(\frac{-2\epsilon^2}{\sum c_i^2}\right)$$
(24)

3 Hoeffding

Hoeffding's inequality

$$\Pr[\hat{p} \ge p + \epsilon] \le e^{-2\epsilon^2 m} \tag{25}$$

is a special case of McDiarmid. Let

$$f(x_1...x_m) = \frac{1}{m} \sum_{i=1}^m x_i.$$
 (26)

 $E[f] = p, c_i = 1/m$ (for $0 \le x \le 1$). So making use of McDiarmid's Inequality,

$$\Pr[\hat{p} \ge p + \epsilon] \le \exp\left(\frac{-2\epsilon^2}{\sum 1/m^2}\right) = \exp(-2\epsilon^2 m)$$
(27)

4 General Strategy

Let

$$err(h) = Pr_{x,y\sim D}[y \neq h(x)]$$
(28)

$$e\hat{r}r(h) = \frac{1}{m} |\{i : y_i \neq h(x_i)\}|$$
(29)

Minimize $e\hat{r}r(h)$. Show close to true error, thus effectively minimizing the true error.

5 Finite Example

THEOREM Assume |H| finite. Given *m* random examples, with probability $1 - \delta$

$$\forall h \epsilon H : |err(h) - e\hat{r}r(h)| < \epsilon \tag{30}$$

if
$$m \ge O\left(\frac{\ln|H| + \ln(1/\delta)}{\epsilon^2}\right)$$
 (31)

PROOF

Fix an h.

$$X_i = \{1 \text{ if } h(x_i) \neq y_i, 0 \text{ else}\}.$$
 (32)

$$\mathbf{E}[X_i] = err(h) \tag{33}$$

$$\frac{1}{m}\sum_{i=1}^{m}X_{i} = e\hat{r}r(h) \tag{34}$$

$$\Pr[\hat{p} \ge p + \epsilon] \le e^{-2\epsilon^2 m} \tag{35}$$

$$\Pr[\hat{err}(h) \ge err(h) + \epsilon] \le e^{-2\epsilon^2 m}$$
(36)

$$\Pr[|\hat{err}(h) - err(h)| \ge \epsilon] \le 2e^{-2\epsilon^2 m}$$
(37)

Now using union bound we can bound the probability for all h.

$$\Pr[\exists h \epsilon H : |err(h) - e\hat{r}r(h)| \ge \epsilon] \le 2|H|e^{-2\epsilon^2 m}$$
(38)

So by increasing m we can bound the probability. So in order to make the probability less than δ we need

$$m \ge \frac{\ln(2|H|) + \ln(1/\delta)}{\epsilon^2} \tag{39}$$

Note that this bound is weaker than before, it requires more examples for smaller errors (grows like $1/\epsilon^2$ vs $1/\epsilon$).

6 Overfitting

$$err(h) \le e\hat{r}r(h) + O\left(\sqrt{\frac{\ln(|H|) + \ln(1/\delta)}{m}}\right)$$

$$(40)$$

$$err(h) \le \hat{err}(h) + O\left(\sqrt{\frac{|h| + \ln(1/\delta)}{m}}\right)$$
(41)

As h gets more complex, the training error $e\hat{r}r(h)$ tends to go down while the complexity |h| increases, so the true error err(h) may at first go down but then increase, as in the figure. This is called overfitting.



Solutions: (1) Cross Validation, which means, hold out some of the training data and use it to determine when to stop training. (2) Treat bound as real and optimize in |h|. This is called structural risk minimization. (3) Build algorithms that are resistant to overfitting.