



Lecture 5: Hardness within P

- ▶ “Fine-Grained Hardness”
- ▶ The Assumptions
- ▶ Hardness of Diameter



Resources



P, NP, and all that...

P = efficient?

The Model Matters

You studied Turing Machines in CS240

The RAM Model

All basic arithmetic/logical operations on
numbers in $[1, n^{100}]$ in 1 step.
 $\underbrace{\hspace{1.5cm}}$
 $O(\log n)$ bits

Aside: We've already been working in the RAM Model

What's the runtime of Dinitz-Edmonds-Karp really?

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What's the runtime of Dinitz-Edmonds-Karp really?

We said $O(m^2 n)$. But what's the dependence on the size of the input numbers?

Real time complexity: $O(m^2 n) \cdot \underbrace{\tilde{O}(B + \log n)}_{\text{\# bits in any input number}}$

What do we do when we fail to find a fast algorithm?

e.g., longest common subsequence

Input: A B C D length
 A C B A D n each

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n each

(A B) (A C) (A D) (B D)
(C D)
(A B D) (A C D).

dynamic programming: $O(n^2)$ time

Is there a better algorithm? $O(n^{1.99})$?

How can we show there *doesn't* exist a better algorithm

Dream: $P \neq NP \stackrel{??}{\Rightarrow} \text{LCS not in time } n^{1.99}$

Backup Dream

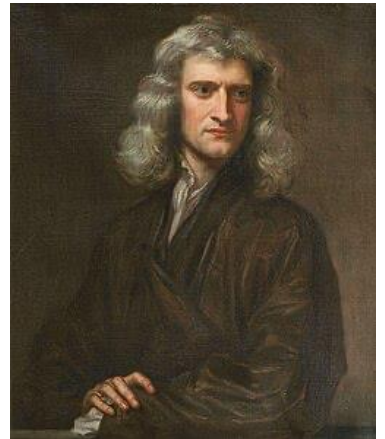
Make one or two fixed assumptions
Derive many hardness consequences.

Backup Dream

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Derive many hardness consequences.

“We are to admit no more causes of natural things than such as are both true and sufficient to explain their appearances.”

“Occam’s Razor”



Backup Dream

The *SETH*

The 3-SUM Assumption

The APSP Assumption

The k -Clique Assumption

FINE GRAINED COMPLEXITY



Reductions

Problem A
Instance x
size n

Reduction
Time $R(n)$

Problem B
Instance y
size $s(n)$

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y is a YES
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\rightarrow usually dominates

$T(n)$ time algo for B $\Rightarrow T(s(n)) + R(n)$ algo for A.

Reductions

Prob A, size n $\xrightarrow[\text{R}(n) \text{ time}]{\text{reduction}}$ Prob B, size $S(n)$

x is a YES
instance of A



y is a YES
instance of B

\nearrow usually dominates

$T(n)$ time algo for B $\Rightarrow T(S(n)) + R(n)$ algo for A.

no $T(S(n)) + R(n)$
time algo for A \Rightarrow No time $T(n)$ time
algo for B

Reductions

More generally, you could design an algo. that uses a subroutine for B to give an algorithm for A.

ETH, SETH

Input: A CNF-Formula (AND OF ORs) in n truth variables $(x_1 \vee \bar{x}_2 \vee x_{50} \vee \bar{x}_{21} \dots) \wedge \dots$

Goal: sat truth assignment?

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Brute Force: $O(2^n \cdot m)$. For 3SAT: best 1.31^n .

SETH: $\forall \epsilon > 0$, CNF-SAT with m clauses & n variables requires $2^{(1-\epsilon)n} \cdot \text{poly}(m)$ time

Hardness of Computing Diameter

Computing Diameter

Input: undirected graph G n vts
 m edges

Goal: Compute $\text{diam}(G)$

$\equiv \max_{u,v} \text{dist}(u,v)$
"length of a shortest path"

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Runtime: $O(mn)$

Computing Diameter

OPEN Q: FASTER THAN $O(mn)$ TIME?

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[ACIM'96], [Roditty-Vassilevska'13]
 $\tilde{O}(m\sqrt{n})$ time algo. Factor $\frac{2}{3}$ -approx.

Computing Diameter

OPEN Q: FASTER THAN $O(mn)$ TIME?

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 $\tilde{O}(m\sqrt{n})$ time algo. Factor $\frac{2}{3}$ -approx.

Thm [Roditty-Vassilevska'13] $\xrightarrow{\text{\# edges}}$
CNF-SETH \Rightarrow No $O(MN^{1-\varepsilon})$ time \wedge $\xrightarrow{\text{\# vertices}}$ exact algo

SETH Implies no better algorithm for exact diameter

THM:

CNF-SETH \Rightarrow No $O(MN^{1-\epsilon})$ time ^{exact} algo

SETH Implies no better algorithm for exact diameter

THM:

CNF-SETH \Rightarrow No $O(MN^{1-\epsilon})$ time \wedge algo ^{exact}

PROOF: "reduction"

CNF-SAT

$$\phi = (x_1 \vee x_0 \vee \bar{x}_{50} \vee x_{20}) \wedge \dots$$

n vars, m clauses

TIME: $2^{\frac{n}{2}} \cdot \text{poly}(m)$
reduction

GRAPH G

$$N = 2^{n/2} + m + 2$$

$$M = O(m) \cdot 2^{n/2}$$

ϕ sat $\Rightarrow \text{diam}(G) = 3$, ϕ unsat $\Rightarrow \text{diam}(G) = 2$

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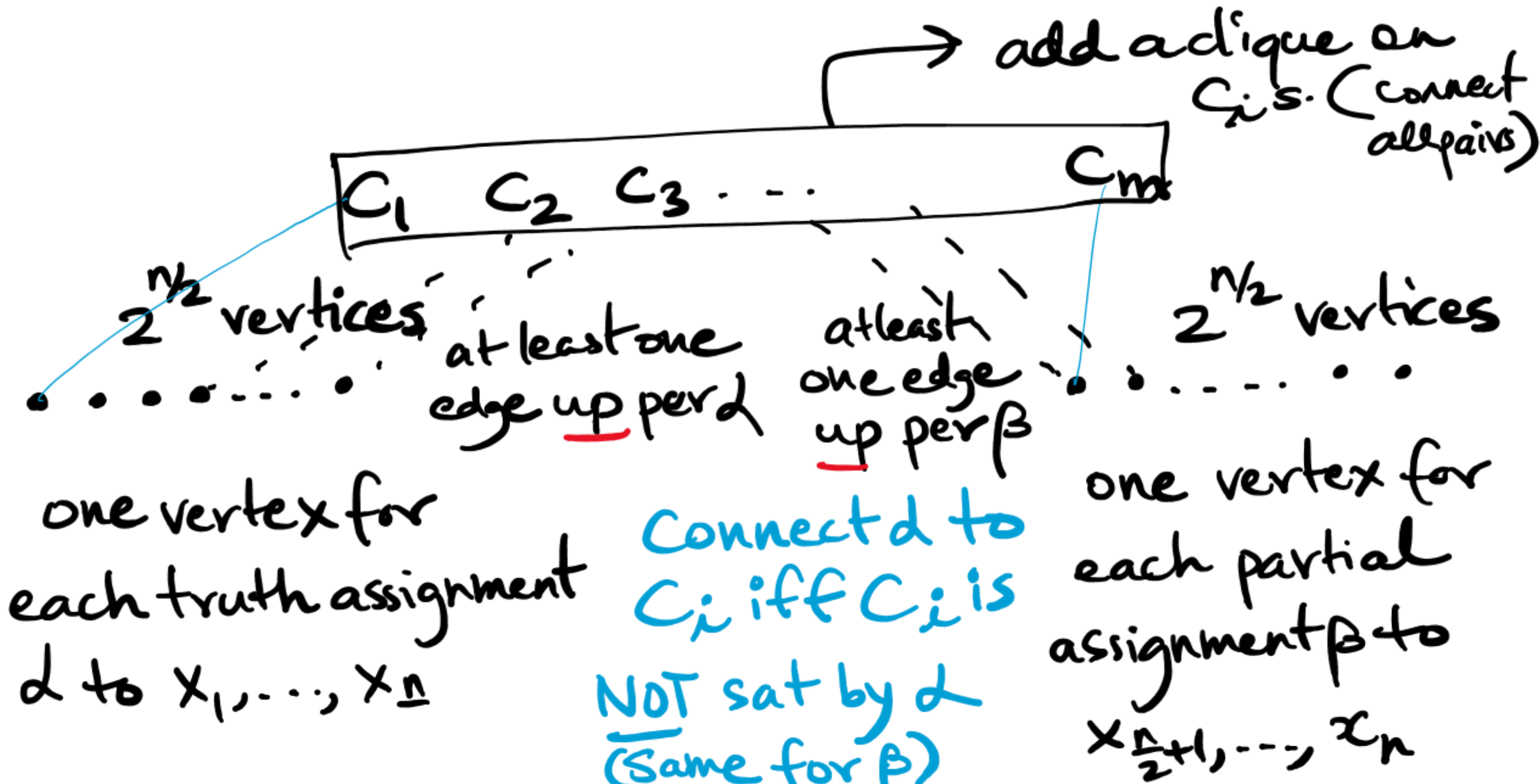
THM:
CNF-SETH \Rightarrow No $O(MN^{1-\epsilon})$ time ^{exact} algo

PROOF: CNF-SAT $\xrightarrow[\text{reduction}]{\text{TIME: } 2^{\frac{n}{2}} \cdot \text{poly}(m)}$ **GRAPH G**
 n vars, m clauses
 $N = 2 \cdot 2^{n/2} + m$
 $M = O(m) \cdot 2^{n/2}$
 Φ sat $\Rightarrow \text{diam}(G) = 3$,
 Φ unsat $\Rightarrow \text{diam}(G) = 3$
 $O(M \cdot N^{1-\epsilon})$ time algo
 \Rightarrow CNFSAT in time $2^{n/2} \cdot \text{poly}(m) + \text{poly}(m) \cdot 2^{n/2} \cdot 2^{\frac{n}{2}(1-\epsilon)}$

Vertices: "Clause vertices": C_1, C_2, \dots, C_m
"partial assignment vertices": $d \in \{0, 1\}^{n/2}$
 $\beta \in \{0, 1\}^{n/2}$

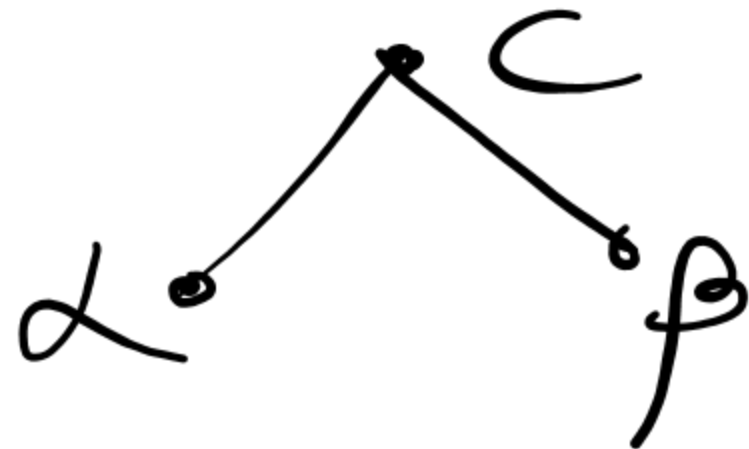
Edges: all possible edges betⁿ C_i s.
no edge betⁿ any d & any β .
Each d, β will have an edge to some C_i except in a corner case

If some d has no edges \rightarrow output any graph of diam 2



(α, C) edge: Connect α & C if α does NOT satisfy C . That is α does not set some literal in C to true

(β, C) edge: Connect β & C if β does NOT satisfy C .



Fix d . There is no (d, C) edge for all C iff d satisfies every constraint

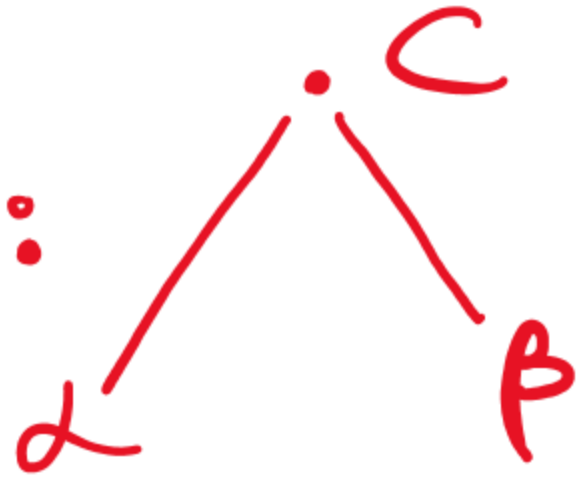
In that case we've discovered that the input formula is sat. In this corner case, output any graph with diam 3. (Similarly for β).

So far, time $\approx 2^{n/2}$ ($\text{poly}(n) \cdot 2^{n/2}$)

vertices, # edges ✓

$\text{diam}(G) \leq 3$

It will be 2 iff $\forall \alpha, \beta, \exists C:$



Analysis

If Φ is sat, $\text{diam}(G)=3$. If not $\text{diam}=2$.

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Key: (α, β) have dist 3 $\Leftrightarrow \forall C_i$ don't have



\Leftrightarrow either α or β sat $C_i \forall i$

\Leftrightarrow Combined assignment $\alpha + \beta$ sat $C_i \forall i$

\Leftrightarrow Combined assignment (α, β) sat Φ .

So. Φ is sat $\Leftrightarrow \exists (\alpha, \beta)$ at distance 3 $\Leftrightarrow \text{diam}(G)=3$