

**Final Solutions****1. Initialization.**

*Don't forget to do this.*

**2. Empirical running time.**

16,000,  $\Theta(V^2E)$

*When  $V$  doubles, the running time goes up by a factor of 4, so the exponent for  $V$  is  $\log_2 4 = 2$ . When  $E$  quadruples, the running time goes up by a factor of 4, so the exponent for  $E$  is  $\log_4 4 = 1$ . Thus, the order of growth of the running time is  $\Theta(V^2E)$ .*

**3. Depth-first search.**

(a) 0 2 5 8 1 3 7 9 6 4

(b) 5 1 7 9 3 6 8 2 4 0

(c) yes

*The digraph is a DAG. So, the reverse postorder provides a topological order.*

**4. Minimum spanning trees.**

(a) 0 10 20 30 50 60 110

(b) 30 0 20 50 60 10 110

**5. Shortest paths.**

(a) 0 7 58 13 3 1

(b) 0 4 5

## 6. Maxflows and mincuts.

(a)  $31 = 8 + 5 + 18$

(b)  $34 = 13 + 21$

(c) 31

*The net flow across any cut is equal to the value of the flow.*

(d)  $A \rightarrow F \rightarrow B \rightarrow G \rightarrow H$

(e) 3

*The edge  $B \rightarrow G$  is the bottleneck.*

## 7. Data structures.

(a) **F** *C would not be inserted at index 3 with index 0 empty.***T** *The second one would arise if the keys were inserted in the order A B C D E.***T** *The third one would arise if the keys were inserted in the order B A E D C.*

(b)  $(10, 10), (12, 9)$

*The constraints of the 2d-tree imply that, for any point  $(x, y)$  in  $T$ , we must have both  $9 \leq x < 13$  and  $8 \leq y < 14$ .*

(c)  $\Theta(n^2), \Theta(n)$

*In the worst case (repeatedly removing the first element), each call to `remove()` takes time proportional to number of elements remaining. This leads to a running time of  $n + (n - 1) + \dots + 1$ , which is  $\Theta(n^2)$ .**In the best case (repeatedly removing the last element), each call to `remove()` takes  $\Theta(1)$  time. Also, each call to `append()` takes  $\Theta(1)$  amortized time. So, the overall running time is  $\Theta(n)$ .*

8. **Dynamic programming.**

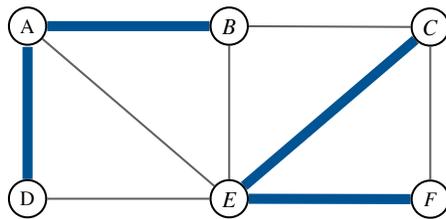
A C E H H L or C A E H H L

```
int[][] opt = new int[m+1][n+1];
for (int i = 1; i <= m; i++) {
    for (int j = 1; j <= n; j++) {
        if (times[j] > i) {
            opt[i][j] = opt[i][j-1];
        }
        else {
            opt[i][j] = Math.max(opt[i][j-1], points[j] + opt[i - times[j]][j-1]);
        }
    }
}
```

9. **Karger’s algorithm.**

(a) A B D

*It runs Kruskal’s algorithm (using the random edge weights), adding the edges C—E, E—F, A—D, and A—B to T, until T contains exactly two connected components.*



(b) 4

*The edges that cross the cut are A—E, B—C, B—E, and D—E.*

10. **Multiplicative weights.**

T F F F F F

11. **Intractability.**

N Y Y Y Y Y N

**12. Princeton path game.**

(a) To determine whether the orange player has already won:

- Build an edge-weighted graph  $G'$  containing only the orange edges.
- Run BFS (or DFS) to determine whether there is a directed path from  $s$  to  $t$  in  $G'$ .
- If such a path exists, declare orange the winner.

(b) To determine whether the black player has already won:

- Build an edge-weighted graph  $G''$  containing the orange and uncolored edges (but not the black edges).
- Run BFS (or DFS) to determine whether there is a directed path from  $s$  to  $t$  in  $G''$ .
- If no such path exists, declare black the winner.

(c) **The game cannot end in a tie.**

*Let's suppose the game continues until all edges are colored either orange or black. We'll see that exactly one player must win.*

- *If there is a directed path  $P$  from  $s$  to  $t$  containing only orange edges, then orange wins (and black cannot simultaneously win because there are no black edges in  $P$ ).*
- *Otherwise, consider the subset of vertices  $S$  reachable from  $s$  via orange edges, and let  $T$  be the remaining vertices. Note that  $s \in S$  and  $t \in T$ . All edges that go from  $S$  to  $T$  are black and every directed path from  $s$  to  $t$  must use one (or more) of these edges. Thus, black wins.*

13. Princeton minimum spanning trees.

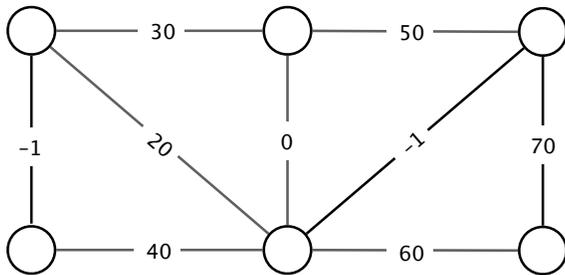
The main idea is to change the weight of all of the orange edges to a small value, smaller than the weight of any of the black edges. That way, the MST will prefer the orange edges to the black edges.

Step 1. Construct  $G'$ :

- Create an edge-weighted graph  $G'$  that has the same vertices and edges as  $G$ .
- Let  $w(e)$  and  $w'(e)$  denote the weight of edge  $e$  in  $G$  and  $G'$ , respectively.
- If edge  $e$  is black, set  $w'(e) = w(e)$ .
- If edge  $e$  is orange, set  $w'(e) = \min_e w(e) - 1$ .

Step 2. Compute the MST  $T'$  of  $G'$  via Prim or Kruskal.

- If  $T'$  contains all of the orange edges, then return  $T'$ .
- Otherwise, report *no Princeton-MST exists*.



**Alternate solution (to determine whether Princeton MST exists).**

- Create a graph  $G''$  containing all of the orange edges in  $G$ .
- Determine whether  $G''$  contains a cycle using DFS.
- If  $G''$  contains a cycle, then report *no Princeton-MST exists*.

**Alternate solution (to find MST).** Create a graph  $G'$  formed by *contracting* all of the orange edges in  $G$ ; compute the MST in  $G'$ ; and return the corresponding edges in  $G$ . Some care is needed to contract the edges efficiently, which we won't describe here.

