

Distributed Hash Tables & Chord

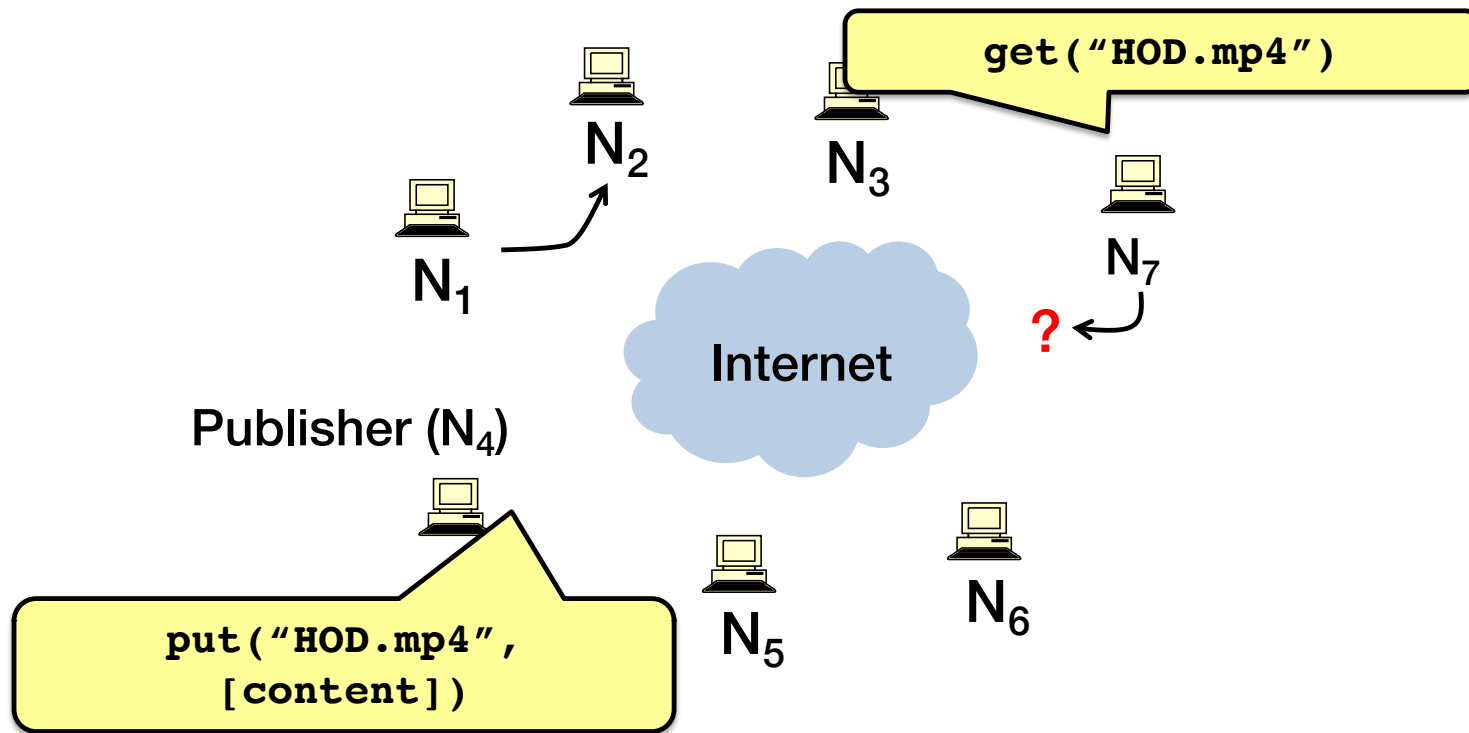


COS 418/518: Distributed Systems

Lecture 8

Wyatt Lloyd

The lookup problem: locate the data



What is a DHT (and why)?

- **Distributed Hash Table: an abstraction of hash table in a distributed setting**

`key = hash(data)`

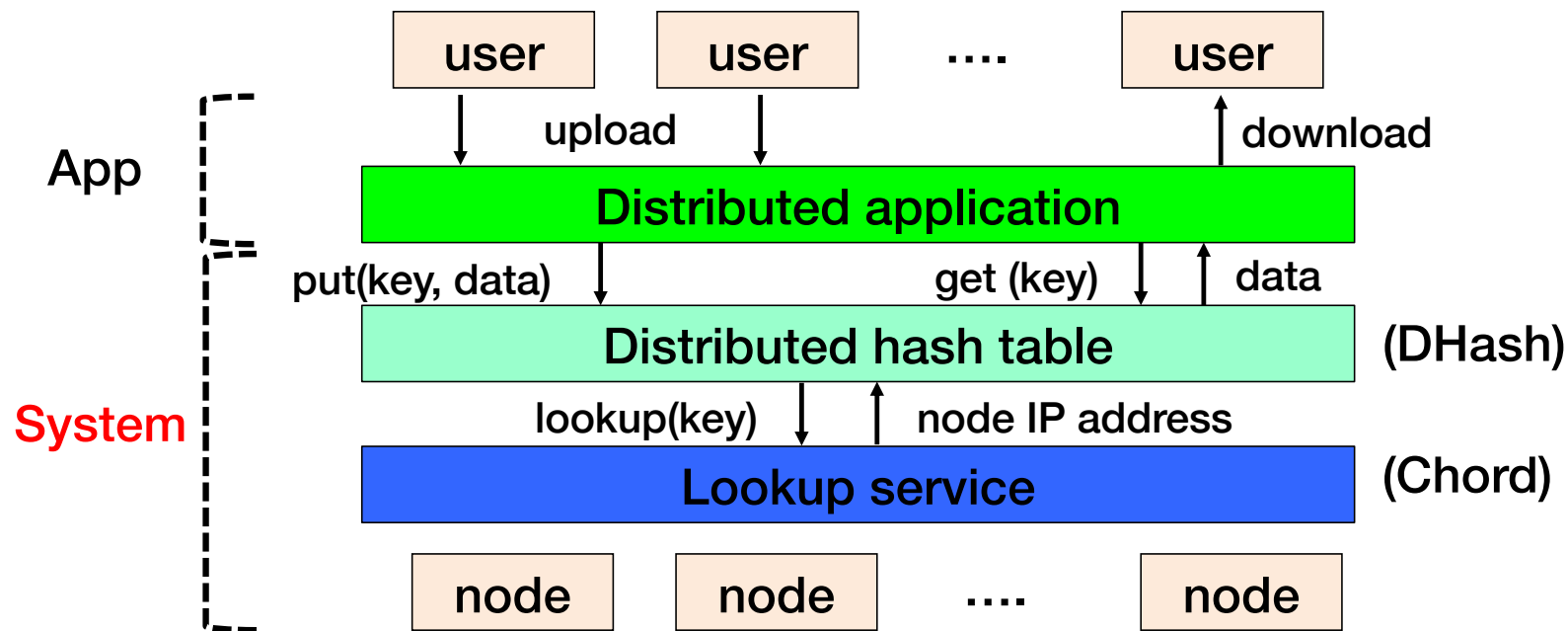
`lookup(key) → IP addr (Chord lookup service)`

`send-RPC(IP address, put, key, data)`

`send-RPC(IP address, get, key) → data`

- **Partitioning data in large-scale distributed systems**
 - Tuples in a global database engine
 - Data blocks in a global file system
 - Files in a P2P file-sharing system

Cooperative storage with a DHT



DHT is expected to be

- **Decentralized:** no central authority
- **Scalable:** low network traffic overhead
- **Efficient:** find items quickly (latency)
- **Dynamic:** nodes fail, new nodes join

Chord identifiers

- **Hashed values (integers) using the same hash function**
 - Key identifier = SHA-1(key)
 - Node identifier = SHA-1(IP address)
- **How does Chord partition data?**
 - i.e., map key IDs to node IDs
- **Why hash key and address?**
 - Uniformly distributed in the ID space
 - Hashed key → load balancing; hashed address → independent failure

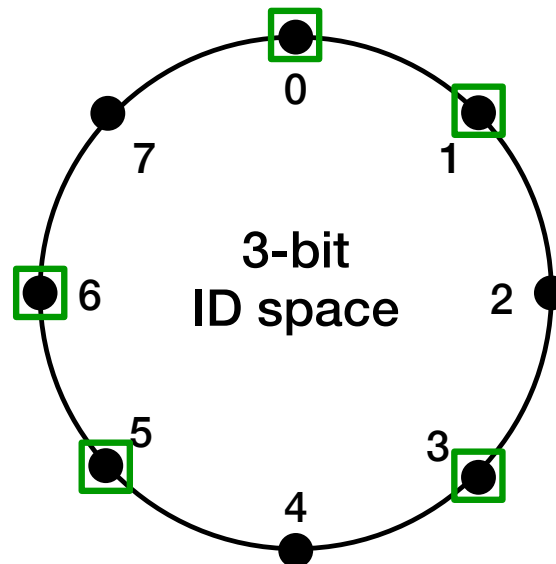
Consistent hashing [Karger '97] – data partition

Identifiers have $m = 3$ bits

Key space: $[0, 2^3-1]$

● Identifiers/key space

□ Node



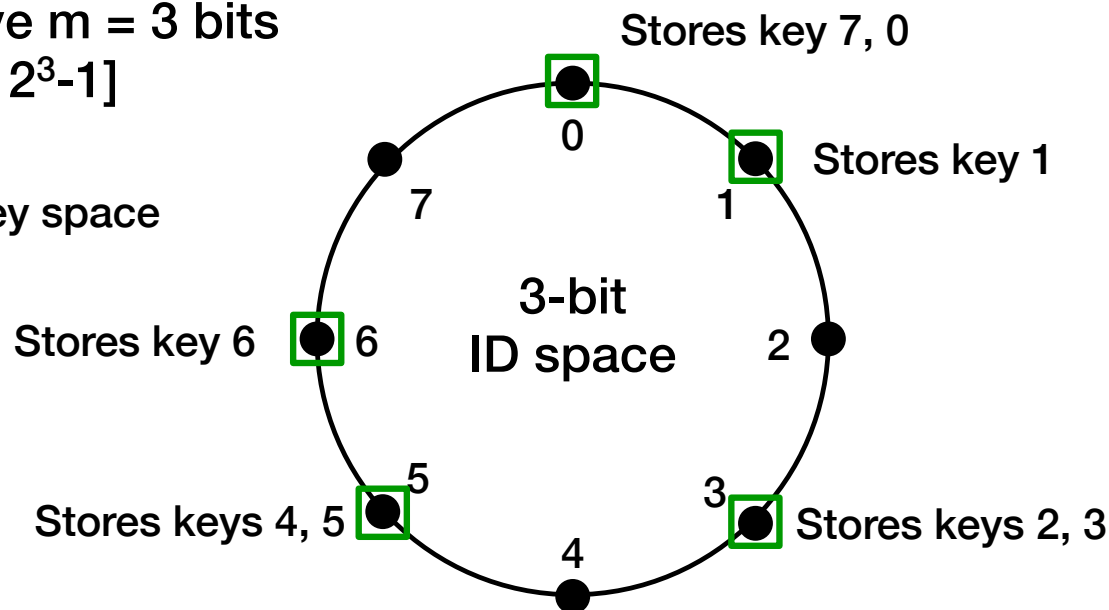
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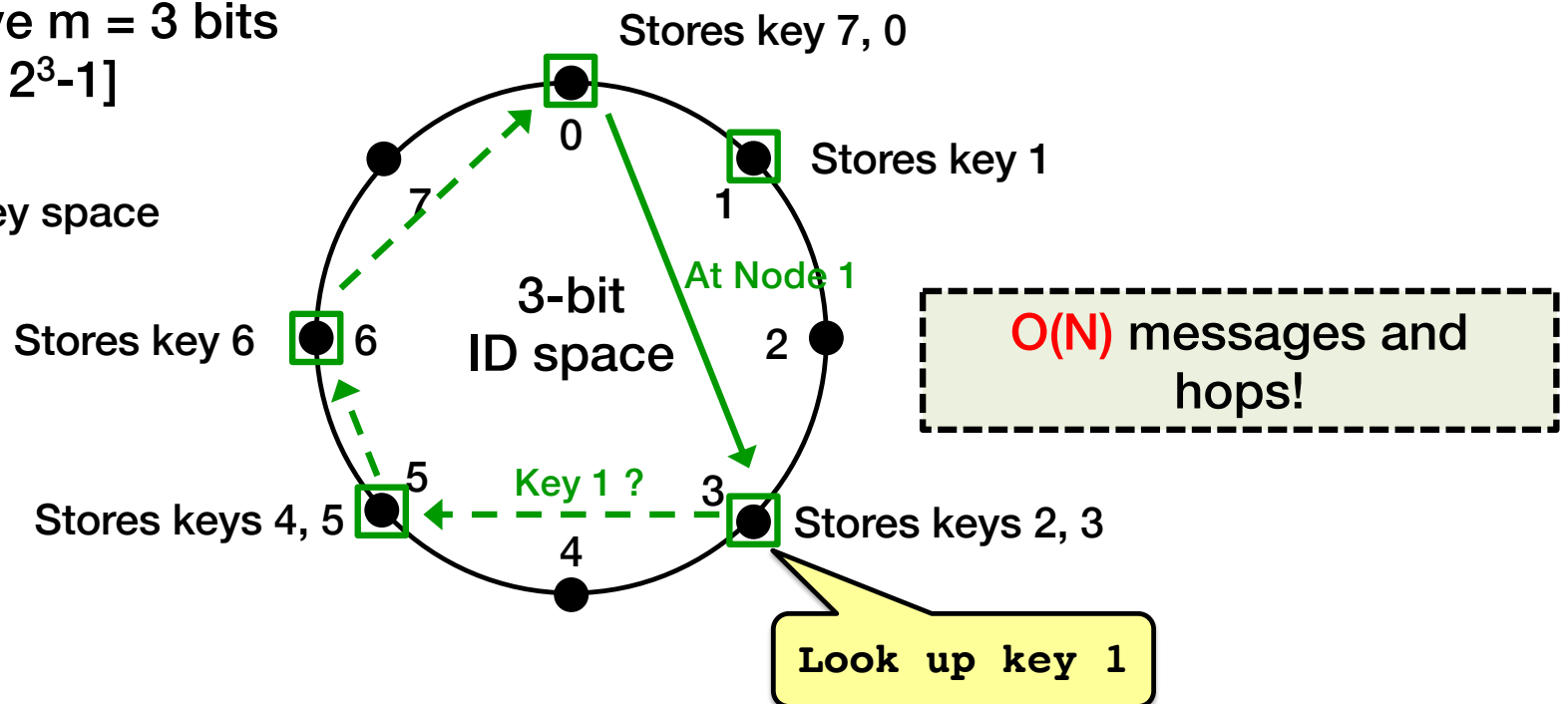


Key is stored at its **successor**: node with next-higher ID

Consistent hashing [Karger '97] – basic lookup

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- Identifiers/key space
- Node
- > Successor pointer



Chord – finger tables

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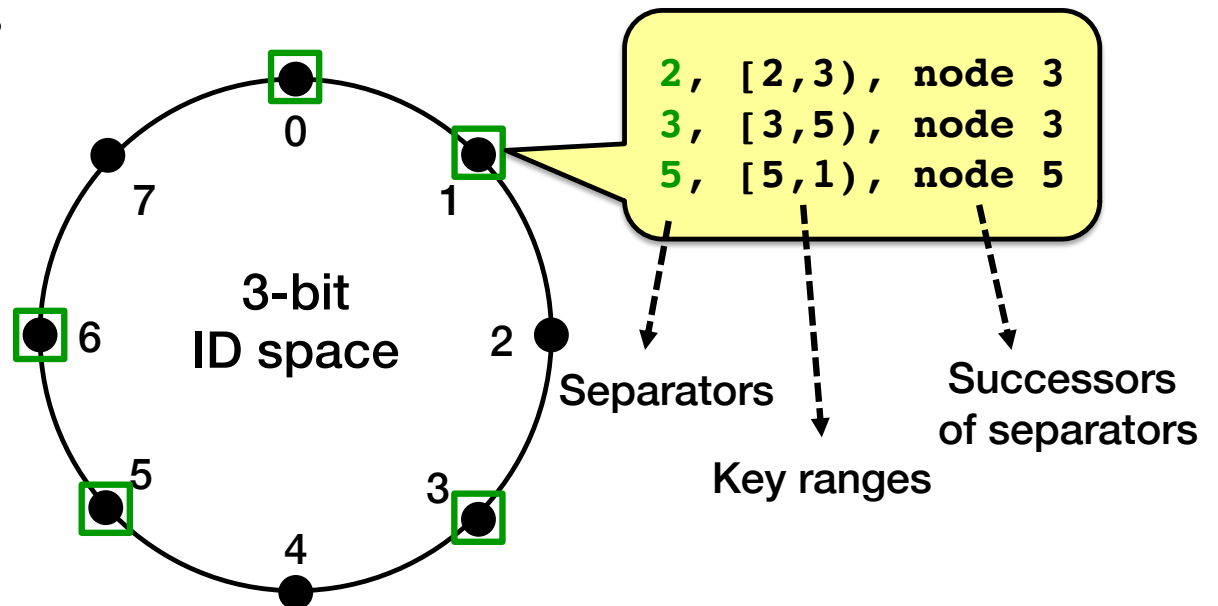
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Each node keeps m states

Key space $\rightarrow m$ ranges via
 $(N+2^{k-1}) \bmod 2^m, 1 \leq k \leq m$



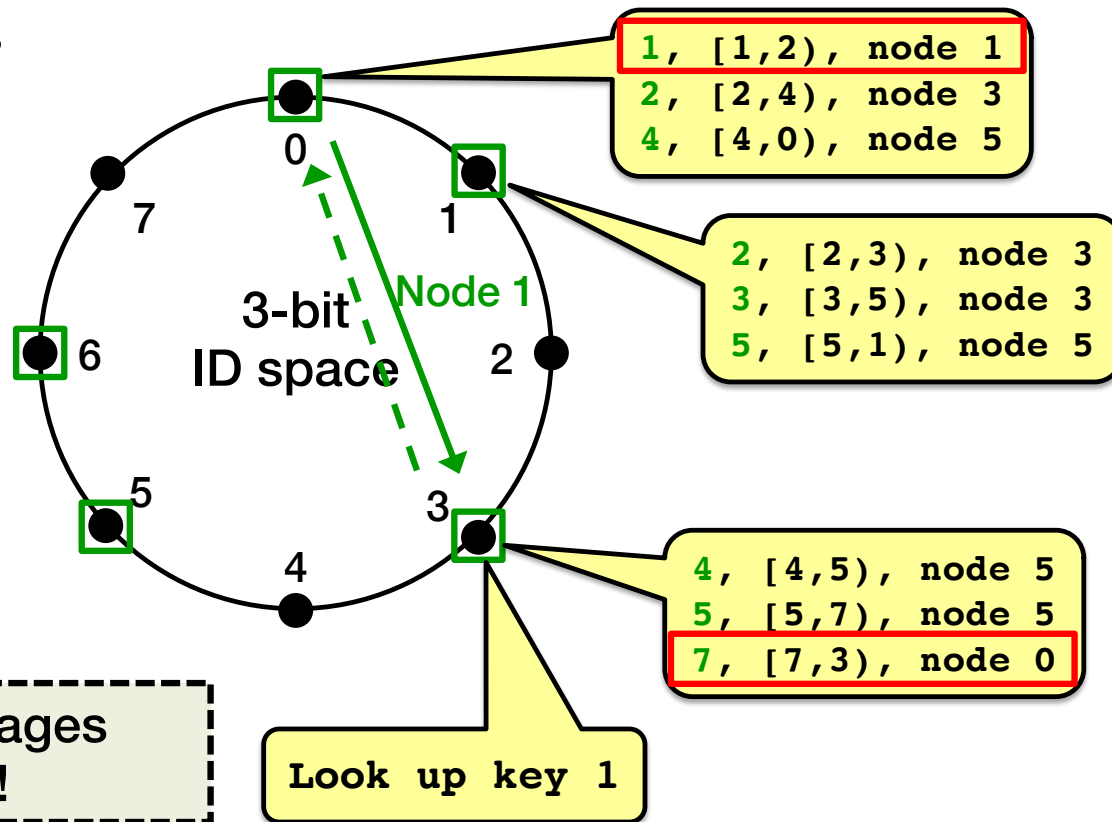
Chord – finger tables

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 Key space $\rightarrow m$ ranges via
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$O(\log N)$ messages
 and hops!



Implication of finger tables

- A **binary lookup tree** rooted at every node
 - Threaded through other nodes' finger tables
- Better than arranging nodes in a single tree
 - Every node acts as a root
 - So there's **no root hotspot**
 - **No single point** of failure
 - But a **lot more state** in total

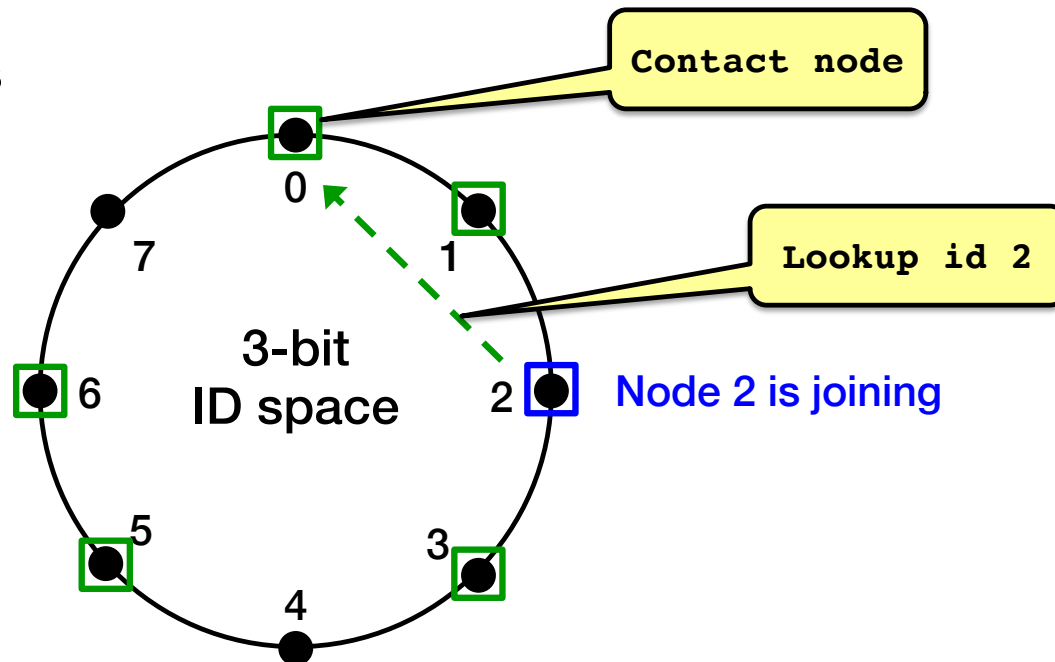
Chord lookup algorithm properties

- **Interface:** lookup(key) → IP address
- **Efficient:** $O(\log N)$ messages per lookup
 - N is the total number of nodes (peers)
- **Scalable:** $O(\log N)$ state per node
- **Robust:** survives massive failures

Chord – node joining

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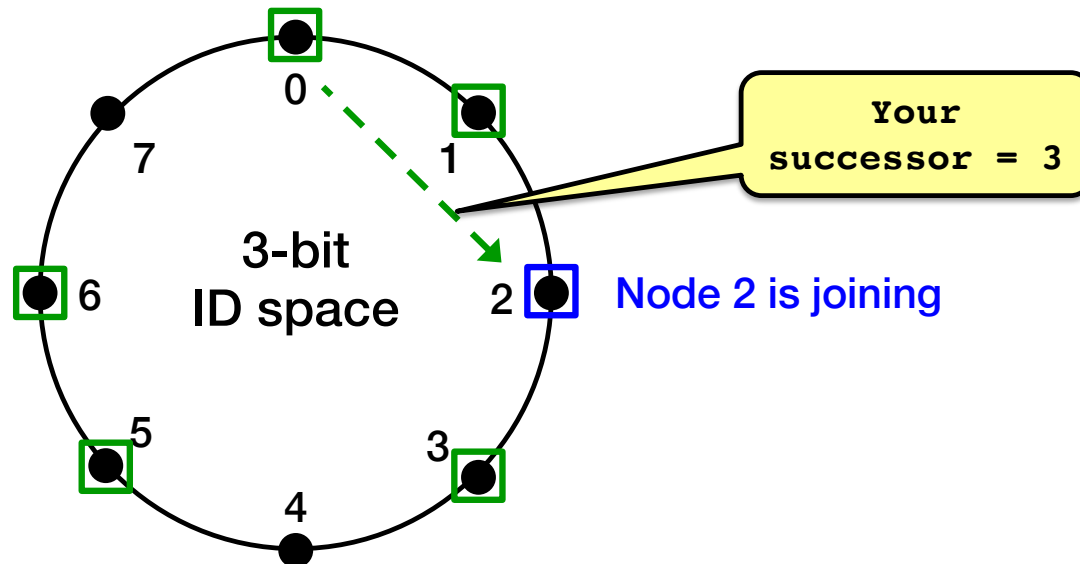
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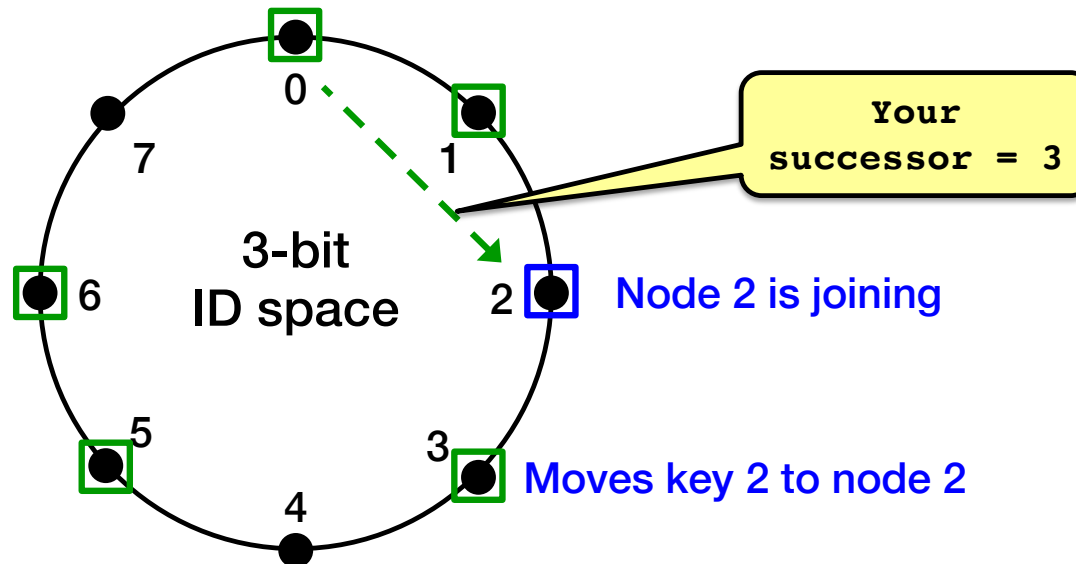
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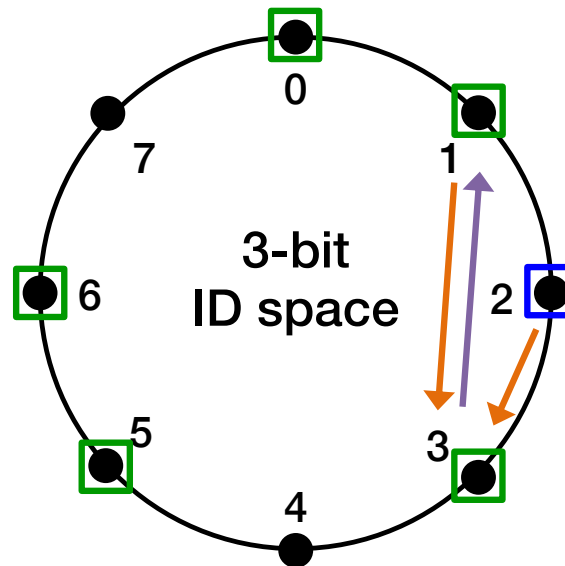
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● Identifiers/key space

□ Node



→ Points to successor
→ Points to predecessor

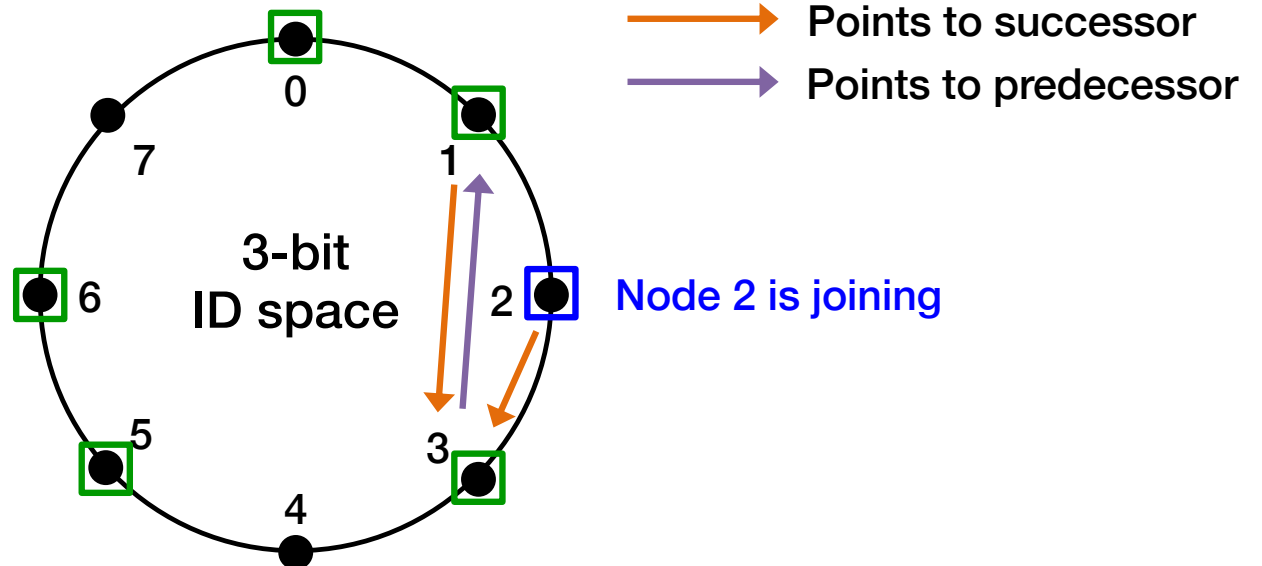
Node 2 is joining

Periodic stabilization messages from each node to its successor maintain node positions

Chord – node joining

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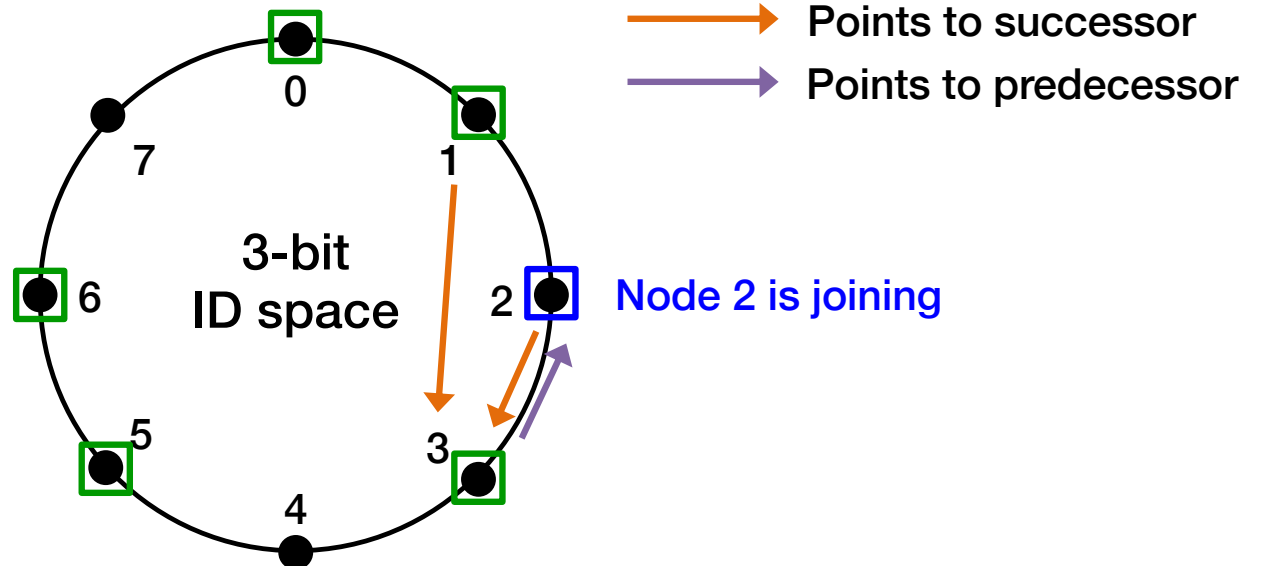
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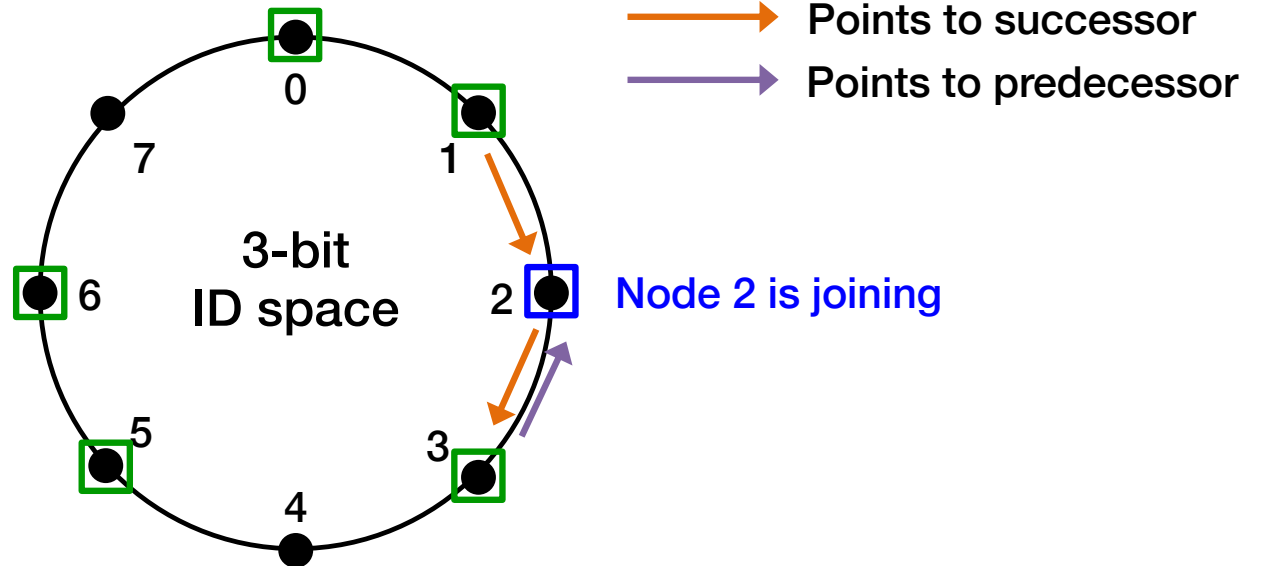
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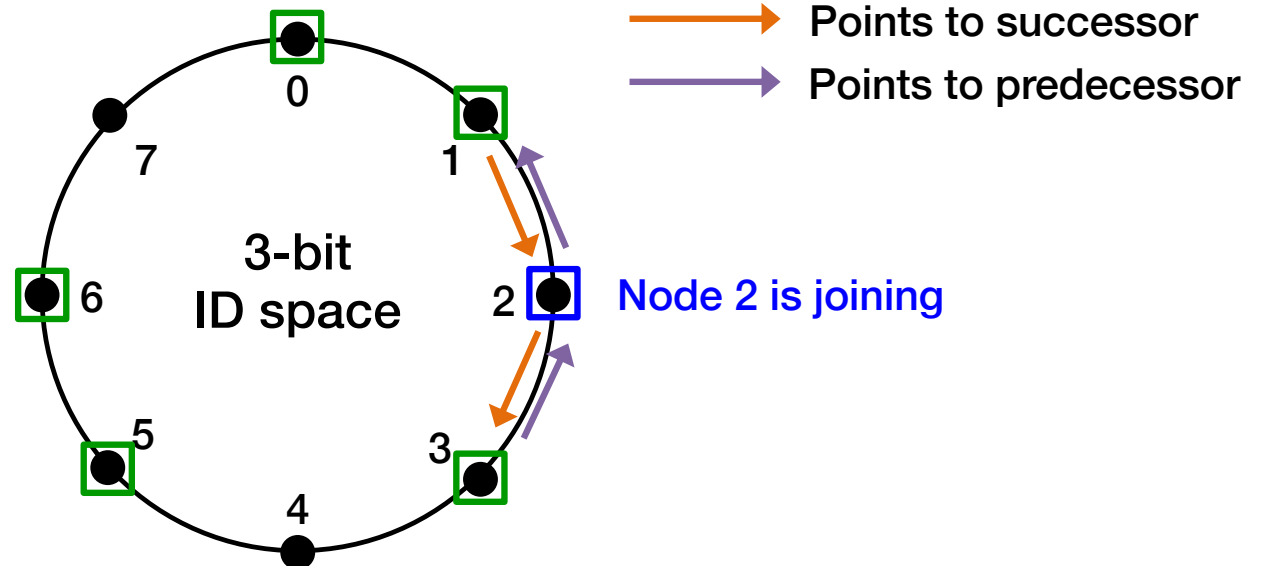
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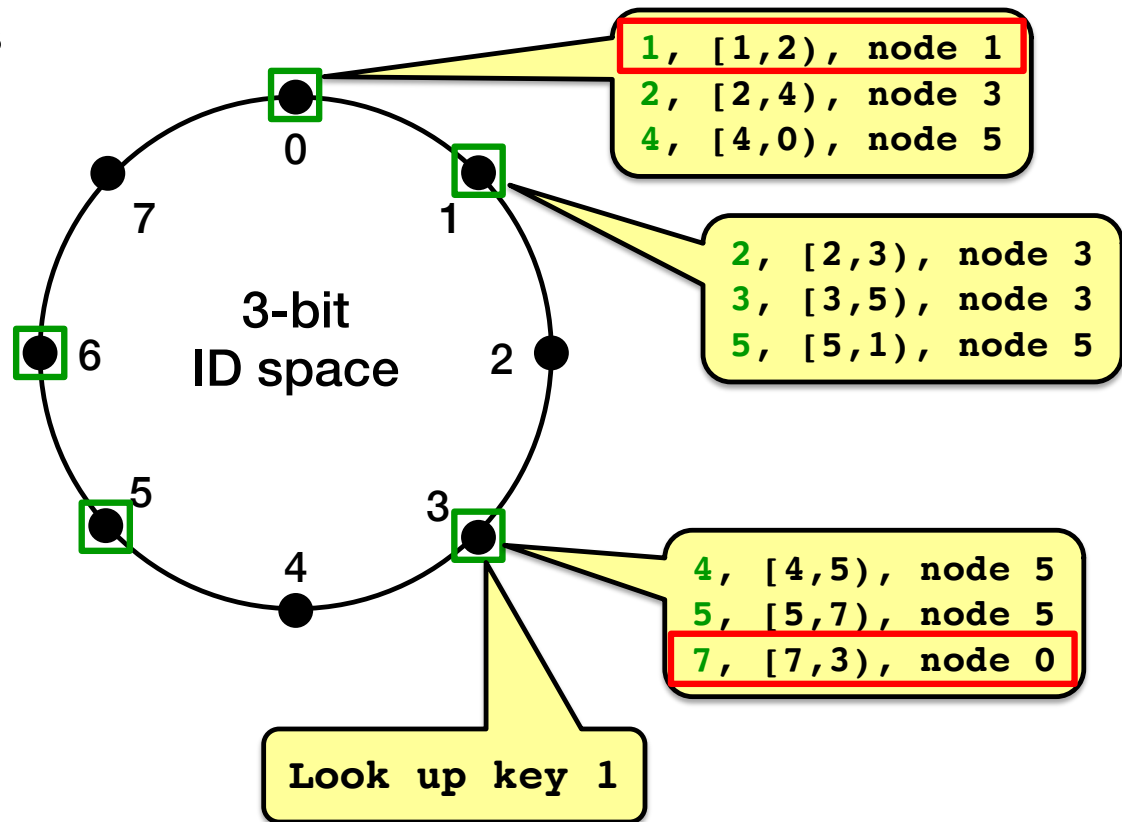
Chord – failures and successor list

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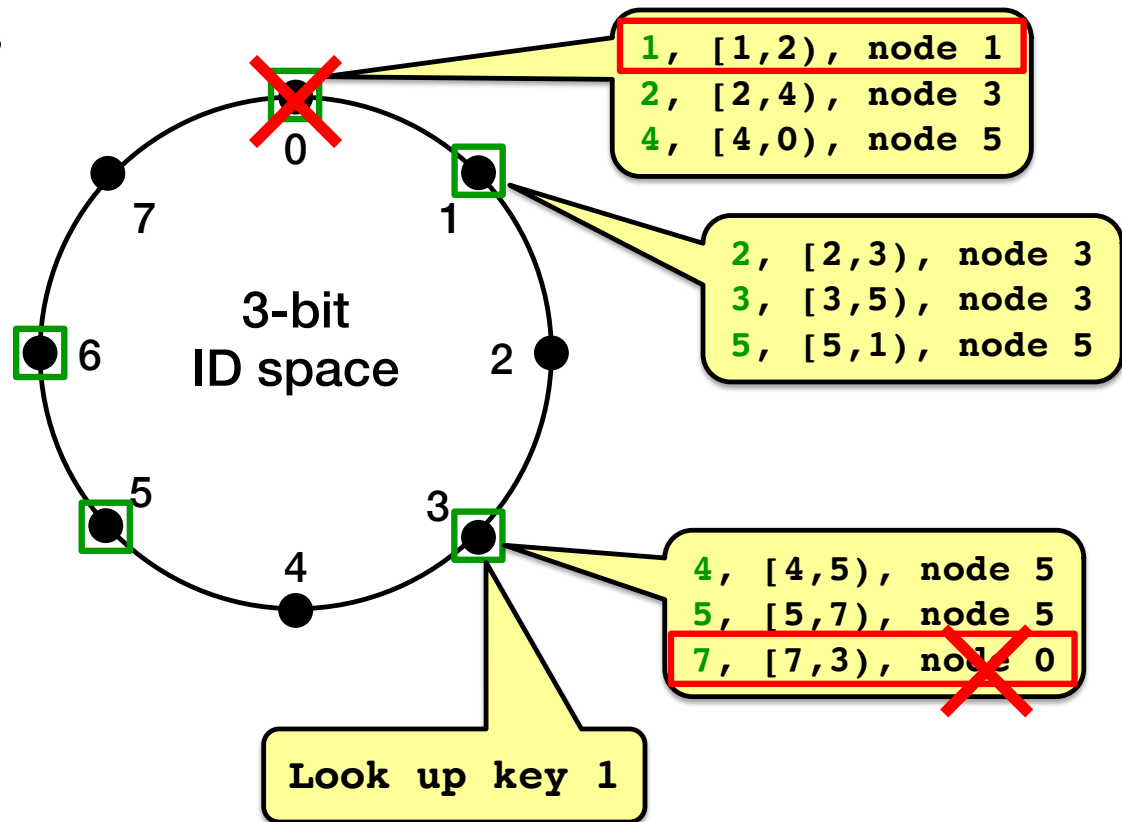
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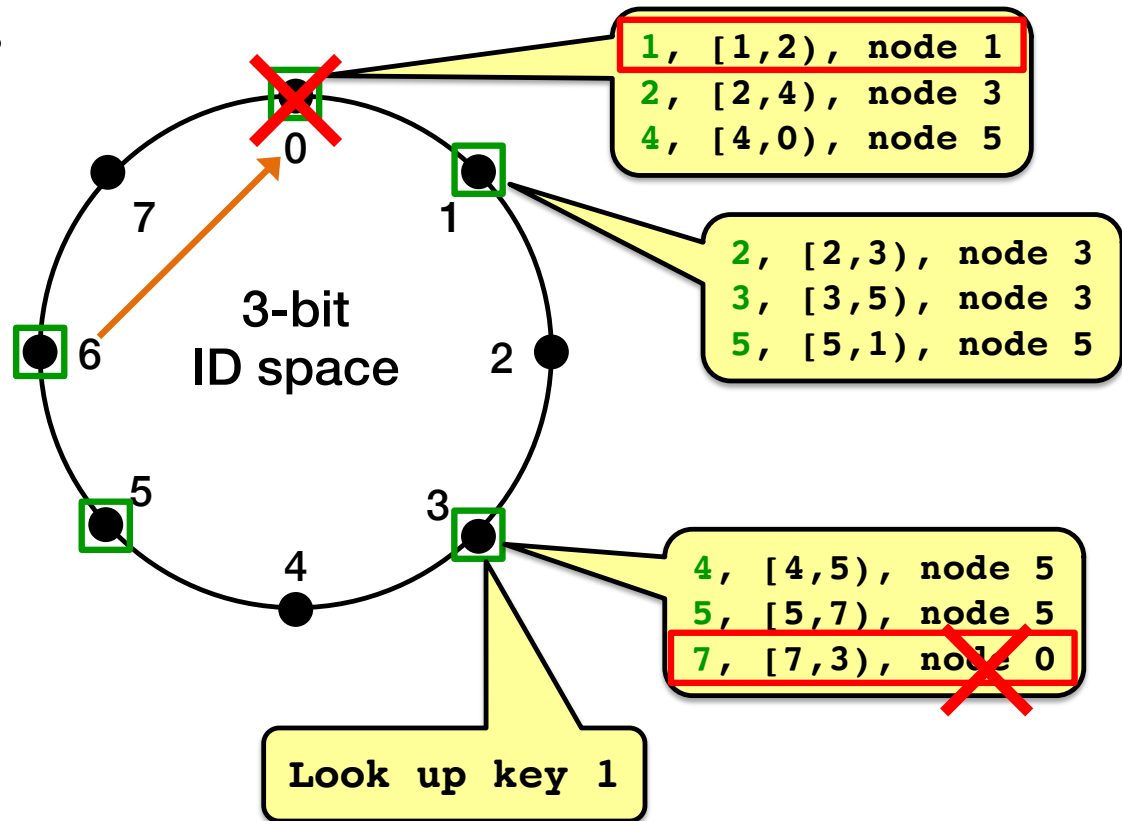
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→ Points to successor



Chord – failures and successor list

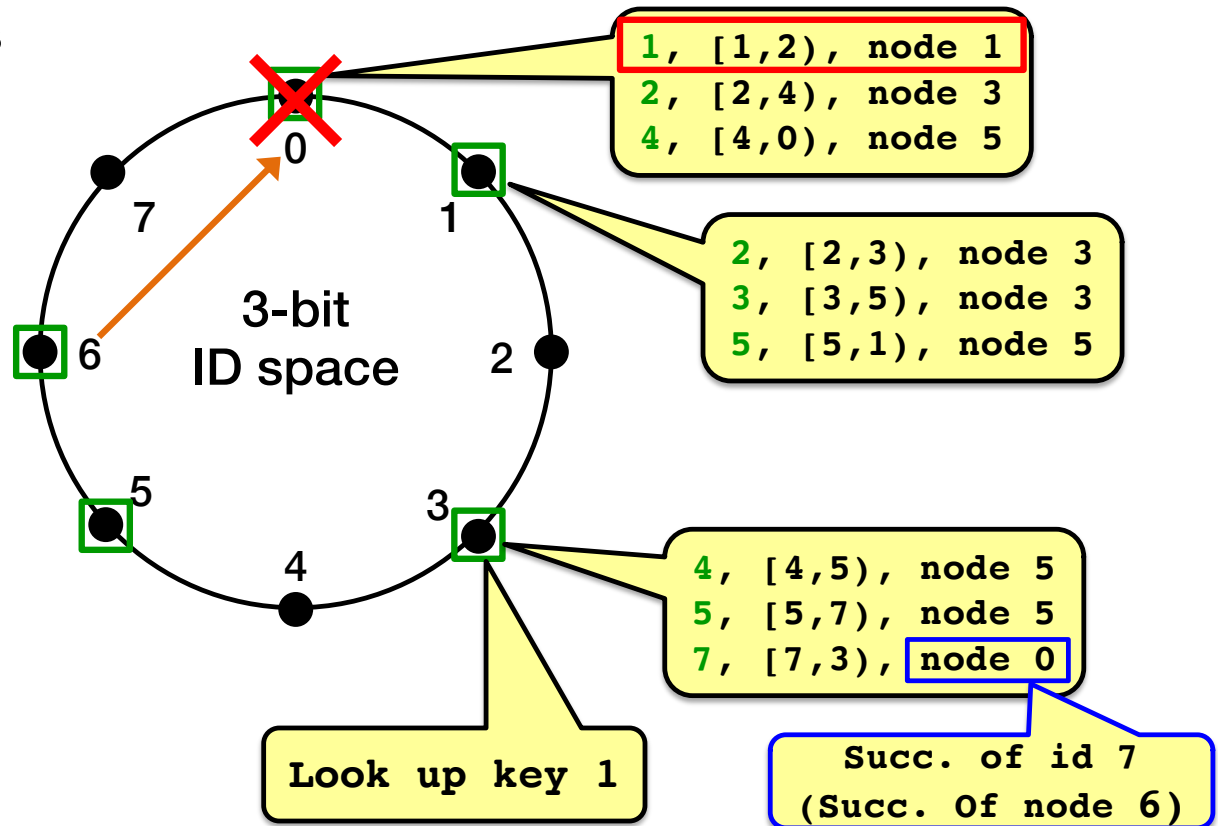
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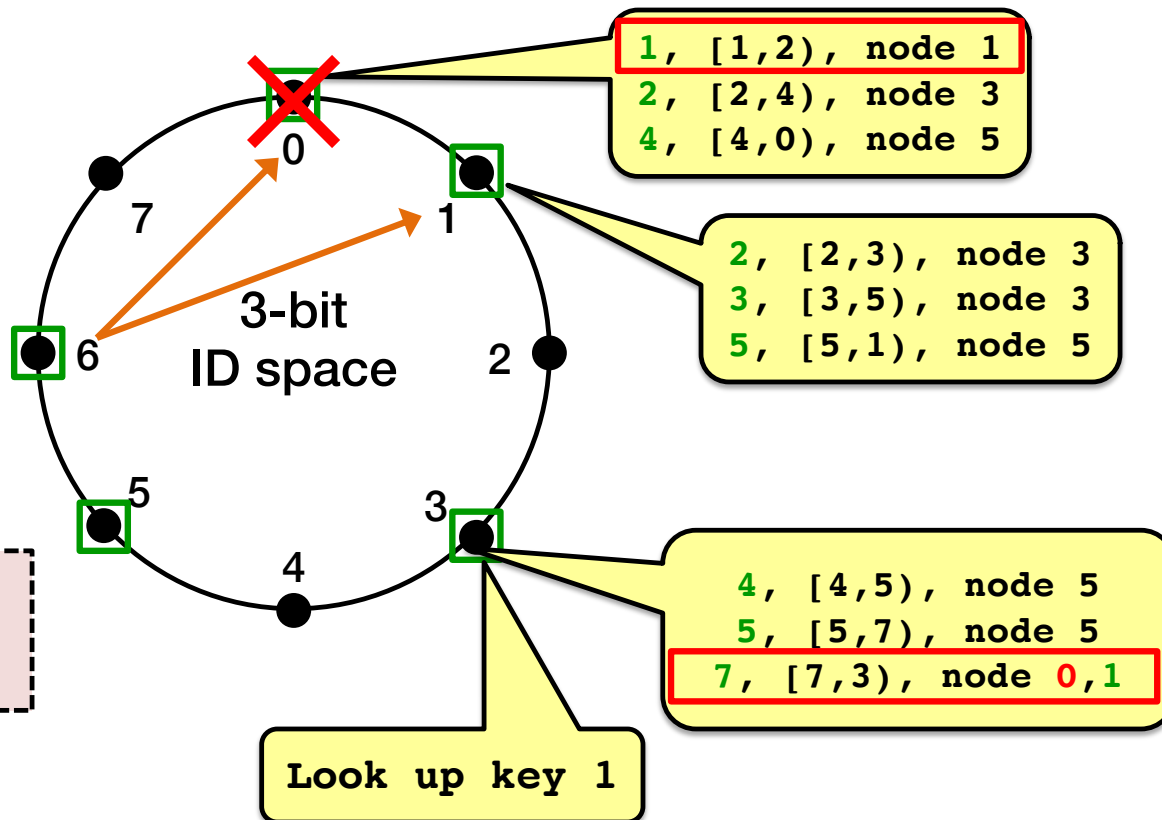
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→ Points to successor

r-nearest successors
($r = \log N$)



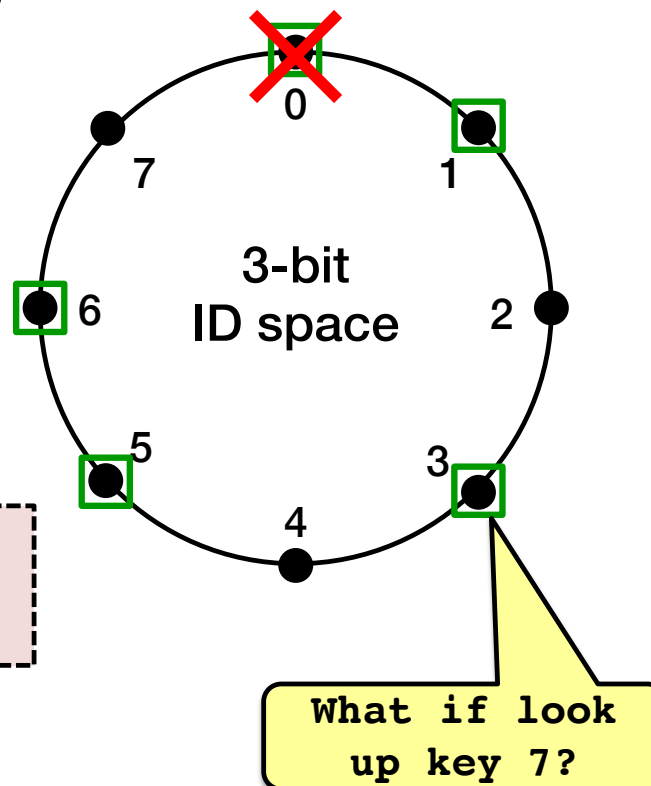
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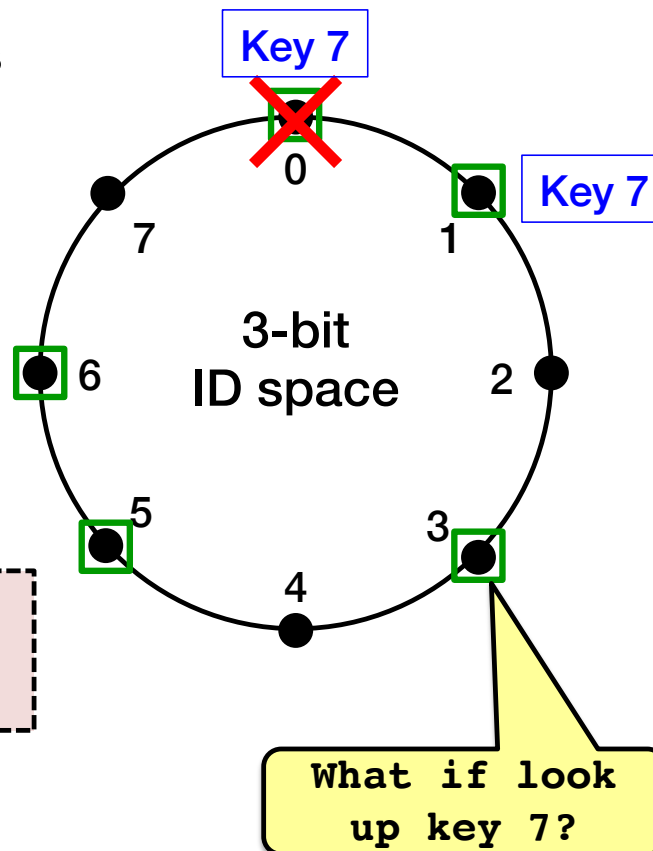
DHash replicates blocks at r successors

Identifiers have $m = 3$ bits

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● Identifiers/key space

□ Node



“Adjacent” nodes in the ring may be far away in the network
→ Independent failures

r-nearest successors
($r = \log N$)

What if look up key 7?

What DHTs got right

- **Consistent hashing**
 - Elegant way to divide a workload across machines
 - Very useful in clusters: actively used in Amazon Dynamo and other systems
- **Replication** for high availability, efficient recovery
- **Incremental scalability**
 - Peers join with capacity, CPU, network, etc.
- **Self-management:** minimal configuration