A Functional Space Model

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Space

Understanding the space complexity of functional programs

- At least two interesting components:
 - the amount of *live space* at any instant in time
 - the *rate of allocation*
 - a function call may not change the amount of live space by much but may allocate at a substantial rate
 - because functional programs act by generating new data structures and discarding old ones, they often allocate a lot
 - » OCaml garbage collector is optimized with this in mind
 - » interesting fact: at the assembly level, the number of writes by a functional program is roughly the same as the number of writes by an imperative program

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 - » interesting fact: at the assembly level, the number of writes by a functional program is roughly the same as the number of writes by an imperative program

– What takes up space?

- conventional first-order data: tuples, lists, strings, datatypes
- function representations (closures)
- the call stack

CONVENTIONAL DATA

OCaml Representations for Data Structures

Type:

type triple = int * char * int

Representation:

(3, 'a', 17)



OCaml Representations for Data Structures

Type:

type mylist = int list

Representation:

0

[] [3; 4; 5]



Space Model

Type:

type tree = Leaf | Node of int * tree * tree

Representation:



In C, you allocate when you call "malloc"

In Java, you allocate when you call "new"

What about ML?

```
let rec insert (t:tree) (i:int) =
match t with
Leaf -> Node (i, Leaf, Leaf)
| Node (j, left, right) ->
if i <= j then
Node (j, insert left i, right)
else
Node (j, left, insert right i)</pre>
```





































Whenever you use a constructor, space is allocated:



Total space allocated is proportional to the height of the tree.

~ log n, if tree with n nodes is balanced



Net space allocated

The garbage collector reclaims unreachable data structures on the heap.

let fiddle (t: tree) =
 insert t 21





The garbage collector reclaims

unreachable data structures on the heap.



The garbage collector reclaims

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let fiddle (t: tree) =

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unreachable data structures on the heap.

Net new space allocated: 1 node

(just like "imperative" version of binary search trees)



<u>Net</u> space allocated

But what if you want to keep the old tree?



Net space allocated

But what if you want to keep the old tree?



```
let check_option (o:int option) : int option =
  match o with
    Some _ -> o
    None -> failwith "found none"
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```
allocates nothing when arg is Some i
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allocates an option when arg is Some i

```
let cadd (c1:int*int) (c2:int*int) : int*int =
    let (x1,y1) = c1 in
    let (x2,y2) = c2 in
    (x1+x2, y1+y2)
```

```
let double (c1:int*int) : int*int =
  let c2 = c1 in
  cadd c1 c2
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no allocation here (1 pair allocated in cadd)

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allocates 2 pairs here (unless the compiler happens to optimize...)

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    let (x1,y1) = c1 in
    let (x2,y2) = c2 in
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```



FUNCTION CLOSURES

Closures (A reminder)

Nested functions like bar often contain free variables:

Here's bar on its own:



To implement bar, the compiler creates a *closure*, which is a pair of code for the function plus an environment holding the free variables.

But what about nested, higher-order functions?

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bar again:

let bar
$$x = x + y$$

bar's representation:



But what about nested, higher-order functions?

To estimate the (heap) space used by a program, we often need to estimate the (heap) space used by its closures.



Our estimate will include the cost of the pair:

- two pointers = 2 words (8 bytes each, or 4 bytes each on some machines)
- the cost of the environment (1 word in this case).
- but not: the cost of the code (because the same code is reused in every closure of this function)

Space Model Summary

Understanding space consumption in FP involves:

- understanding the difference between
 - live space
 - rate of allocation
- understanding where allocation occurs
 - any time a constructor is used
 - whenever closures are created
- understanding the costs of
 - data types (fairly similar to Java)
 - costs of closures (pair + environment)

WHY IT'S IMPORTANT TO PRUNE CLOSURE ENVIRONMENTS

A remark about homework 4

```
let zeros i = if i=0 then [] else 0 :: s(i-1)
```

```
let h (n: int) : int =
  let f x =
    let k = List.length x in
    fun () -> k
  in
  let rec g i : (unit->int) list =
    if i=0 then [] else f (zeros n) :: g (i-1)
  in let bigdata = g n
  in List.fold_left (fun s u -> u()+s) 0 bigdata
```

let $a = h \ 1000$

let zeros i = if i=0 then [] else 0 :: s(i-1)

let $a = h \ 1000$



You *could* build a closure environment with all the variables currently in scope.

```
let zeros i = if i=0 then [] else 0 :: s(i-1)
```

```
let h (n: int) : int =
   let f x =
    let k = List.length x in
   fun () -> k
   What are the free variables of this function?
   in
   let rec g i : (unit->int) list =
      if i=0 then [] else f (zeros n) :: g (i-1)
   in let bigdata = g n
   in List.fold_left (fun s u -> u()+s) 0 bigdata
```

let $a = h \ 1000$

5 words of memory versus 3 words, what's the big deal?



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    let k = List.length x in
    fun () -> k
  in
  let rec g i : (unit->int) list =
    if i=0 then [] else f (zeros n) :: g (i-1)
  in let bigdata = g n Run the program to here, and what is in memory?
  in List.fold_left (fun s u -> u()+s) 0 bigdata
```

```
let a = h 1000

h

bigdata

k_{u_1}

k_{u_2}

k_{u_1}

k_{
```

```
let zeros i = if i=0 then [] else 0 :: s(i-1)
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```
let zeros i = if i=0 then [] else 0 :: s(i-1)
```



Therefore

Closures should represent *only* the free variables of a function (not *all the variables currently in scope*),

otherwise the compiled program may use asymptotically more space,

such as O(n²) instead of O(n)