

Project 2
Non-Preemptive
Scheduling

COS 318

General Suggestions

- Use an IDE
 - Eclipse
 - Built into lab machines
 - Help -> Install New Software...
 - Download a specific Eclipse package for C/C++ from eclipse.org
 - Others
- Start as soon as you can and get as much done as possible by design review time
- bochsdbg / bochs-gdb

Good News

No more segments!

Overview

- Add multiprogramming to the kernel
 - Non-preemptive scheduler
 - 5 threads, 3 processes
 - Process Control Blocks
 - Context switching
 - Timing
 - Mutual exclusion
 - Lock

Non-Preemptive

- What does it mean?
- yield & exit
 - do_yield() & do_exit() within the kernel (kernel threads can call these directly)
 - yield() & exit() for processes
 - dispatches a desire to call do_yield() or do_exit() to the kernel

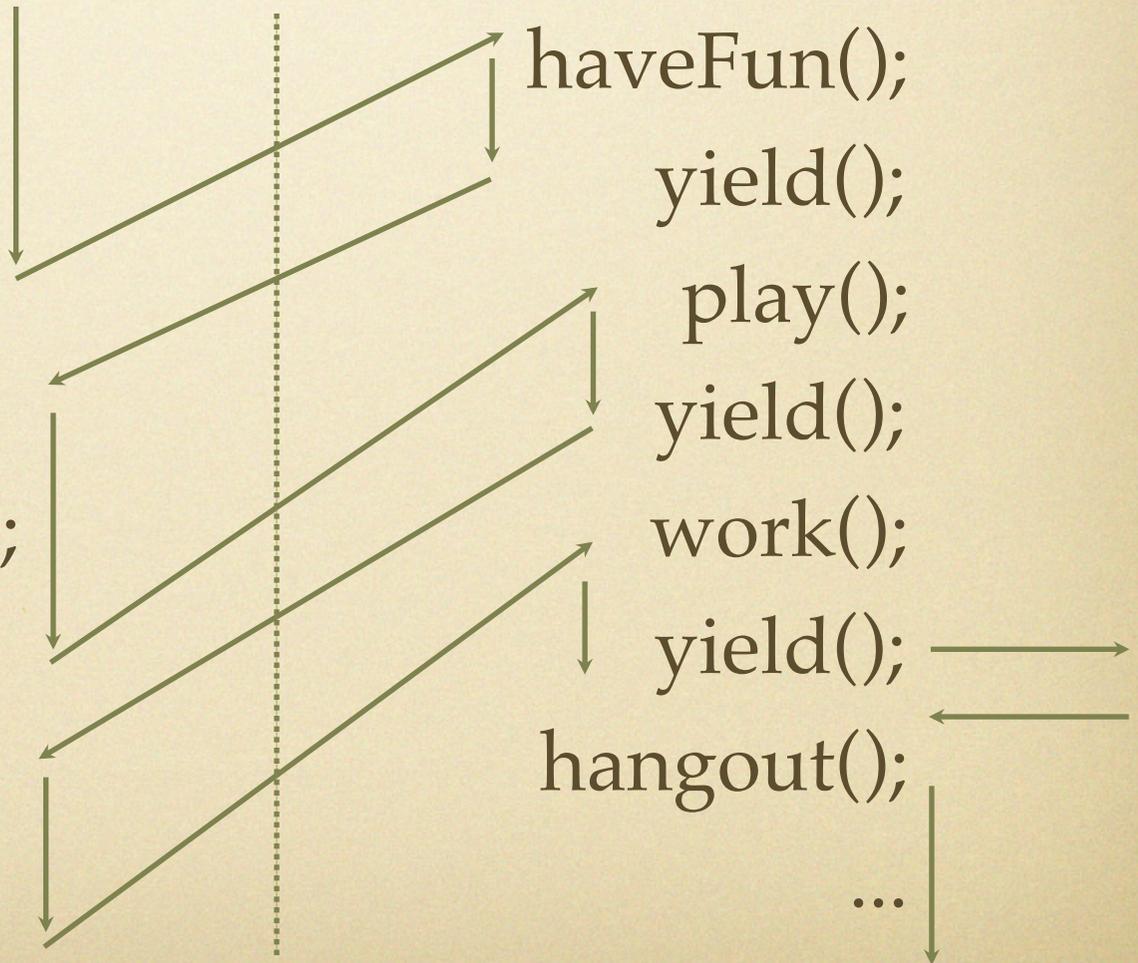
Non-Preemptive Scheduling Example

COS 318

Brain

Life

goToClass();
goToPrecept();
yield();
coding();
designReview();
yield();
coding();
exit();



What yield'ing does

- When yield is called, the “context” of a task (thread or process) must be saved
- Process Control Block
 - What does it contain?
 - eflags (pushfl, popfl)
- Will be done in assembly
- Once the context is saved, the scheduler is run to pick a new task

Picking a New Task

- All tasks are waiting in queue
- Pick the next one from the front of the ready queue
- Restore it's state from the PCB
- ret to where the task was executing before

cdecl

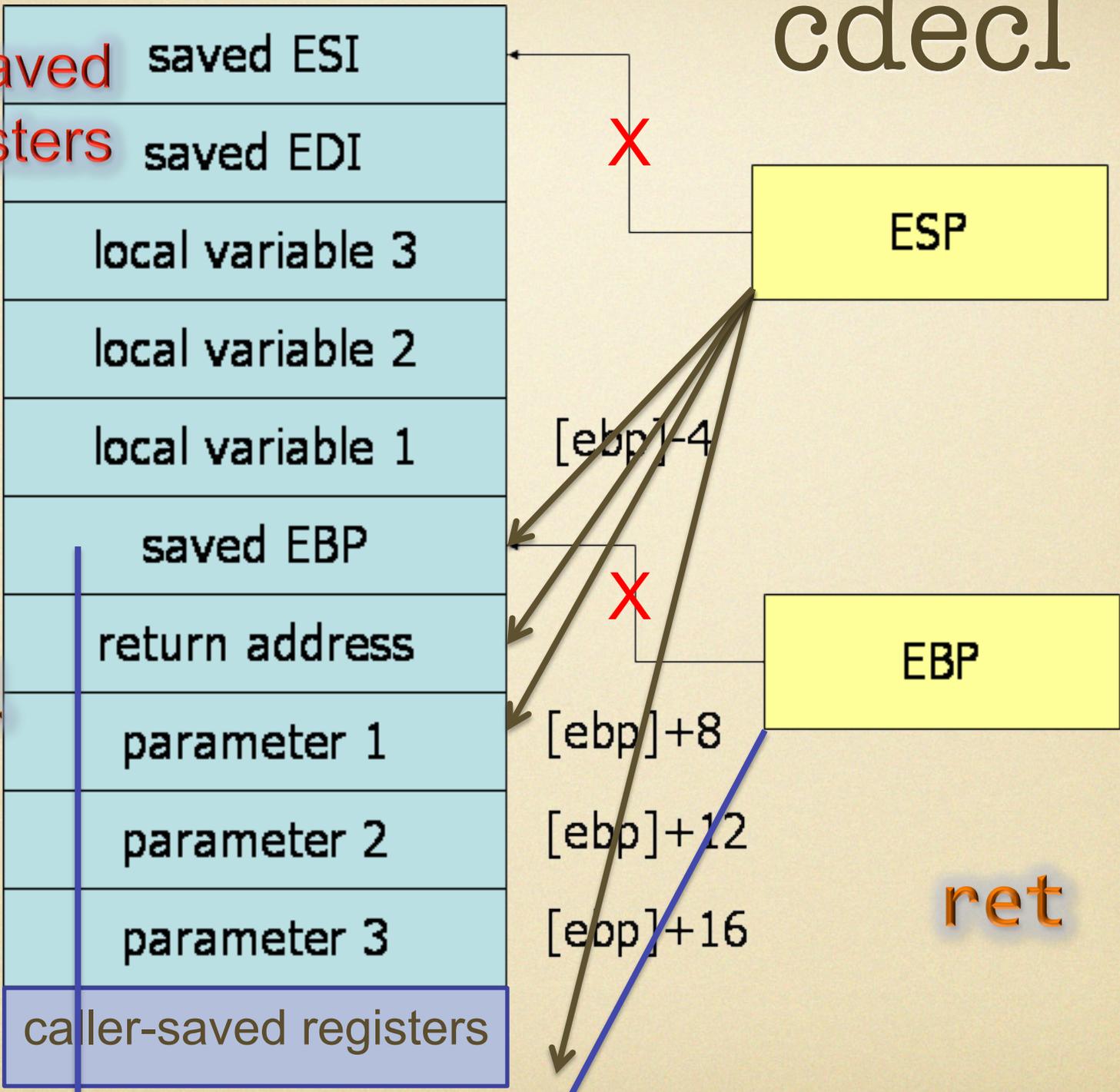
callee-saved registers

Stack Growth

Higher Addresses

call

ret



Why not just use `jmp`?

Mutual Exclusion

- Only one lock used by *threads*
- `lock_init(lock_t * l)`
- `lock_acquire(lock_t * l)`
- `lock_release(lock_t * l)`