

# **Routing Convergence**

Lecture 10 Kyle Jamieson COS 461: Computer Networks

## **Routing Changes**



- Topology changes: new route to the same place
- Host mobility: route to a different place

## **Topology Changes**

# **Two Types of Topology Changes**

- Planned
  - Maintenance: shut down a node or link
  - Energy savings: shut down a node or link
  - Traffic engineering: change routing configuration
- Unplanned Failures
  - Fiber cut,
     faulty equipment,
     power outage,
     software bugs, ...



# **Detecting Topology Changes**

#### Beaconing

- Periodic "hello" messages in both directions
- Detect a failure after a few missed "hellos"



- Performance trade-offs
  - Detection delay
  - Overhead on link bandwidth and CPU
  - Likelihood of false detection

Routing Convergence: Link-State Routing

#### Convergence

- Control plane
  - All nodes have consistent information
- Data plane
  - All nodes forward packets in a consistent way



## **Transient Disruptions**

- Detection delay
  - A node does not detect a failed link immediately
  - ... and forwards data packets into a "blackhole"
  - Depends on timeout for detecting lost hellos



## **Transient Disruptions**

- Inconsistent link-state database
  - Some routers know about failure before others
  - Inconsistent paths cause transient forwarding loops



# **Convergence Delay**

- Sources of convergence delay
  - Detection latency
  - Updating control-plane information
  - Computing and install new forwarding tables
- Performance during convergence period
  - Lost packets due to blackholes and TTL expiry
  - Looping packets consuming resources
  - Out-of-order packets reaching the destination
- Very bad for VoIP, online gaming, and video

Slow Convergence in Distance-Vector Routing

- Link cost decreases and recovery
  - Node updates the distance table



- Rule: Least-cost path's cost changed? notify neighbors

t₁

D<sup>Y</sup> = Distances known to Y

 $\mathbf{t}_2$ 



- Link cost decreases and recovery
  - Node updates the distance table
- 50
- **Rule:** Least-cost path's cost changed? notify neighbors

 $D^{Y}$  = Distances known to Y



- Link cost decreases and recovery
  - Node updates the distance table



Rule: Least-cost path's cost changed? notify neighbors

"good news travels fast"



Link cost increases and failures

 "Count to infinity" problem!



$$\frac{\overset{V}{D}}{\operatorname{to:} X} \begin{array}{c} \overset{V a}{4} & \overset{D^{Y}}{6} & \overset{X}{X} \begin{array}{c} z \\ \hline x \\ \hline d \\ 6 \end{array} \begin{array}{c} \overset{D^{Y}}{4} & \overset{X}{2} \\ \hline x \\ \hline d \\ 6 \end{array} \begin{array}{c} \overset{D^{Y}}{60} & \overset{X}{60} \end{array} \begin{array}{c} \overset{V a}{60} \\ \hline & & & & \\ \hline \end{array} \begin{array}{c} \overset{V a}{50} \\ \hline \end{array} \begin{array}{c} \overset{D^{Z}}{5} & \overset{V a}{X} \\ \hline \end{array} \begin{array}{c} \overset{V a}{50} \\ \hline \end{array} \begin{array}{c} \overset{D^{Z}}{5} \\ \hline \end{array} \begin{array}{c} \overset{X}{5} \\ \hline \end{array} \begin{array}{c} \overset{V a}{50} \\ \hline \end{array} \begin{array}{c} \overset{D^{Z}}{5} \\ \hline \end{array} \begin{array}{c} \overset{X}{5} \\ \hline \end{array} \begin{array}{c} \overset{V a}{50} \\ \hline \end{array} \begin{array}{c} \overset{C (X,Y)}{5} \\ \hline \end{array} \begin{array}{c} \overset{C (X,Y)}{t_{1}} \\ \hline \end{array} \begin{array}{c} \overset{L }{t_{2}} \\ \hline \end{array} \begin{array}{c} \overset{L }{t_{3}} \end{array} \begin{array}{c} \overset{L }{t_{4}} \end{array} \begin{array}{c} \overset{L }{t_{4}} \end{array} \begin{array}{c} \overset{L }{t_{4}} \end{array} \begin{array}{c} \overset{L }{t_{4}} \end{array}$$

Link cost increases and failures

 "Count to infinity" problem!





#### **Distance Vector: Poison Reverse**

 If Z routes through Y to X, then Z tells Y its (Z's) distance to X is ∞

(so Y won't route to X via Z)





#### **Distance Vector: Poison Reverse**

• Can still have problems in larger networks



- 1. A and B use ACD and BCD, so A and B both "poison" to C.
- 2. But when CD withdrawn (cost goes to infinity), B switches to BACD, so BC no longer poisoned to C.
- 3. C then starts using CBACD. Loop.

# **Redefining Infinity**

Avoid "counting to infinity"

– By making "infinity" smaller!

- Routing Information Protocol (RIP)
  - All links have cost 1
  - Valid path distances of 1 through 15
  - ... with 16 representing infinity
- Used mainly in small networks

# Reducing Convergence Time With Path-Vector Routing

(e.g.: Border Gateway Protocol)

## **Path-Vector Routing**

- Extension of distance-vector routing
  - Support flexible routing policies
  - Avoid count-to-infinity problem
- Key idea: advertise the entire path
  - Distance vector: send distance metric per dest d
  - Path vector: send the entire path for each dest d



#### Faster Loop Detection

- Node can easily detect a loop
  - Look for its own node identifier in the path
  - E.g., node 1 sees itself in the path "3, 2, 1"
- Node can simply discard paths with loops
  - E.g., node 1 simply discards the advertisement



# **BGP Session Failure**

- BGP runs over TCP
  - BGP only sends updates when changes occur
  - TCP doesn't detect lost connectivity on its own
- Detecting a failure

  Keep-alive: 60 seconds
  Hold timer: 180 seconds

  Reacting to a failure

  Discard all routes learned from neighbor
  - Send new updates for any routes that change

### **Routing Change: Before and After**



# **Routing Change: Path Exploration**

- AS 1
  - Delete the route (1,0)
  - Switch to next route (1,2,0)
  - Send route (1,2,0) to AS 3
- AS 3
  - Sees (1,2,0) replace (1,0)
  - Compares to route (2,0)
  - Switches to using AS 2



# **Routing Change: Path Exploration**

1,0)

(1,2,0)

(1,3,0)

- Initial: All AS use direct
- Then destination 0 dies
  - All ASes lose direct path
  - All switch to longer paths
  - Eventually withdrawn
- How many intermediate routes following (2,0) withdrawal until no route known to 2?

 $(2,0) \rightarrow (2,1,0) \rightarrow (2,3,0) \rightarrow (2,1,3,0) \rightarrow \mathsf{null}$ 

2 (3,1,0)

2,0)

(2,1,0)

(2,3,0)

(2,1,3,0)

# **BGP Converges Slowly**

- Path vector avoids count-to-infinity
  - But, ASes still must explore many alternate paths to find highest-ranked available path
- Fortunately, in practice
  - Most popular destinations have stable BGP routes
  - Most instability lies in a few unpopular destinations
- Still, lower BGP convergence delay is a goal
   Can be tens of seconds to tens of minutes

#### **BGP** Instability

# Stable Paths Problem (SPP) Instance

- Node
  - BGP-speaking routerNode 0 is destination
- Edge
   BGP adjacency
- Permitted paths
  - Set of routes to 0 at each node
  - Ranking of the paths



## **SPP** Solution

#### • Solution is:

- Path assignments per node
  - Can be the "null" path
- If node u has path uwP
  - {u,w} is edge in graph
  - w is assigned path wP
- Each node is assigned

- Highest ranked path consistent with its neighbors



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## Stable Paths Problem (SPP) Instance

- 1 will use a direct path to 0
  (Y) True (M) False
- 5 has a path to 0
  (Y) True (M) False



## Stable Paths Problem (SPP) Instance

- 1 will use a direct path to 0 210 (M) False (Y) True 20 2 5 has a path to 0 0
  - (Y) True (M) False



#### An SPP May Have No Solution



# **Avoiding BGP Instability**

- Detecting conflicting policies
  - Computationally expensive
  - Requires too much cooperation
- Detecting oscillations
  - Observing the repetitive BGP routing messages
- Restricted routing policies and topologies

– Policies based on business relationships

## Conclusion

- The only constant is change
  - Planned topology and configuration changes
  - Unplanned failure and recovery
- Routing-protocol convergence
  - Transient period of disagreement
  - Blackholes, loops, and out-of-order packets
- Routing instability
  - Permanent conflicts in routing policy
  - Leading to bi-stability or oscillation