

A Functional Space Model

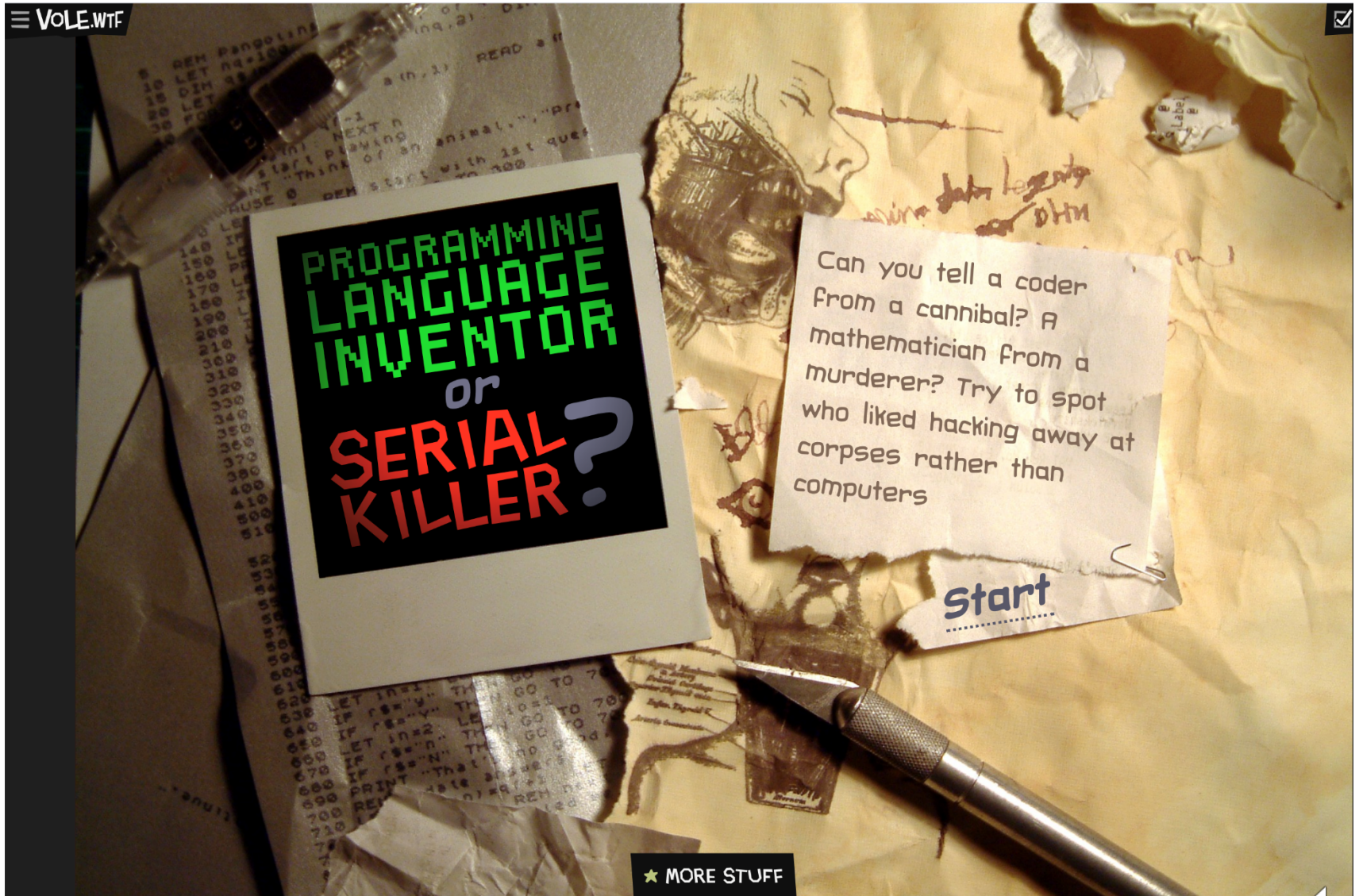
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COS 326

Princeton University



Interlude



<https://vole.wtf/coder-serial-killer-quiz/>



Space

Understanding the space complexity of functional programs

- At least two interesting components:
 - the amount of *live space* at any instant in time
 - the *rate of allocation*
 - a function call may not change the amount of live space by much but may allocate at a substantial rate
 - because functional programs act by generating new data structures and discarding old ones, they often allocate a lot
 - » OCaml garbage collector is optimized with this in mind
 - » *interesting fact*: at the assembly level, the number of writes by a functional program is roughly the same as the number of writes by an imperative program
- *What takes up space?*
 - conventional first-order data: tuples, lists, strings, datatypes
 - function representations (closures)
 - the call stack



CONVENTIONAL DATA



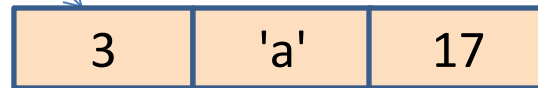
OCaml Representations for Data Structures

Type:

```
type triple = int * char * int
```

Representation:

(3, 'a', 17)



OCaml Representations for Data Structures

Type:

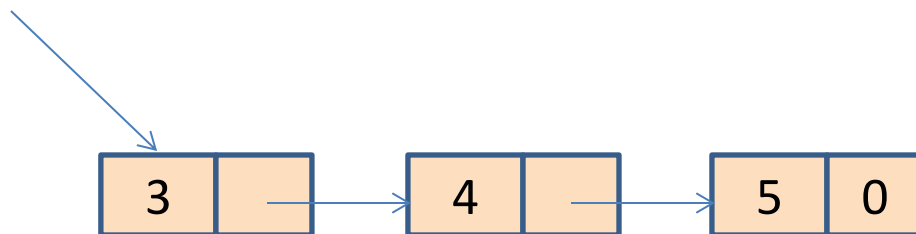
```
type mylist = int list
```

Representation:

[]

[3; 4; 5]

0



Space Model

Type:

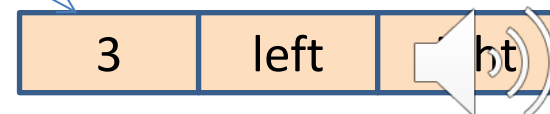
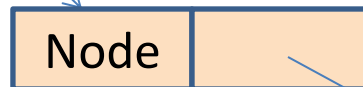
```
type tree = Leaf | Node of int * tree * tree
```

Representation:

Leaf

Node(3, left, right)

0



Actually like this in Ocaml:



Allocating space

8

In C, you allocate when you call “malloc”

In Java, you allocate when you call “new”

What about ML?



Allocating space

Whenever you *use a constructor*, space is allocated:

```
let rec insert (t:tree) (i:int) =
  match t with
  | Leaf -> Node (i, Leaf, Leaf)
  | Node (j, left, right) ->
    if i <= j then
      Node (j, insert left i, right)
    else
      Node (j, left, insert right i)
```



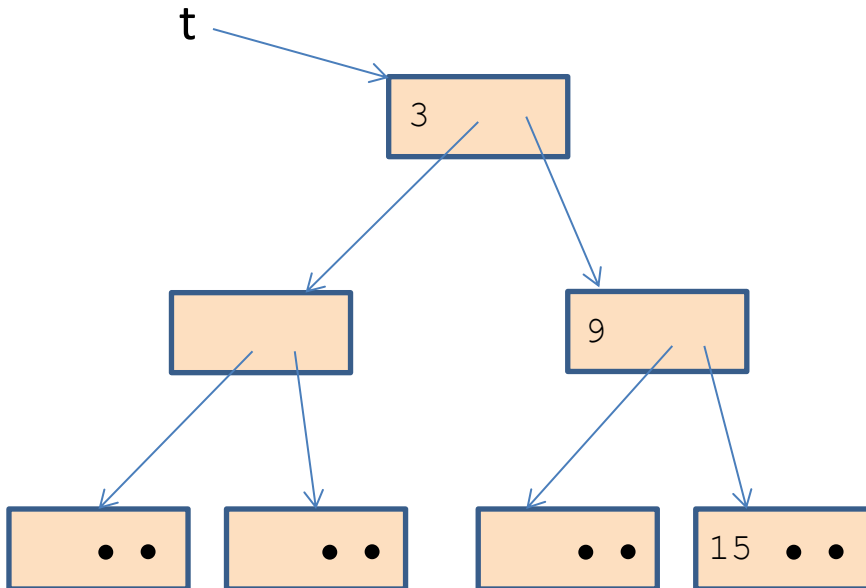
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Consider:

insert t 21



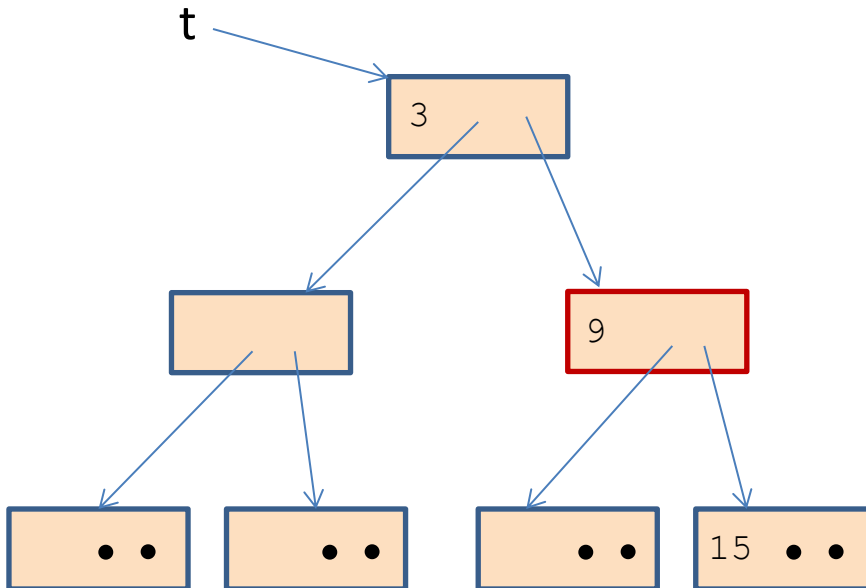
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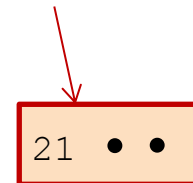
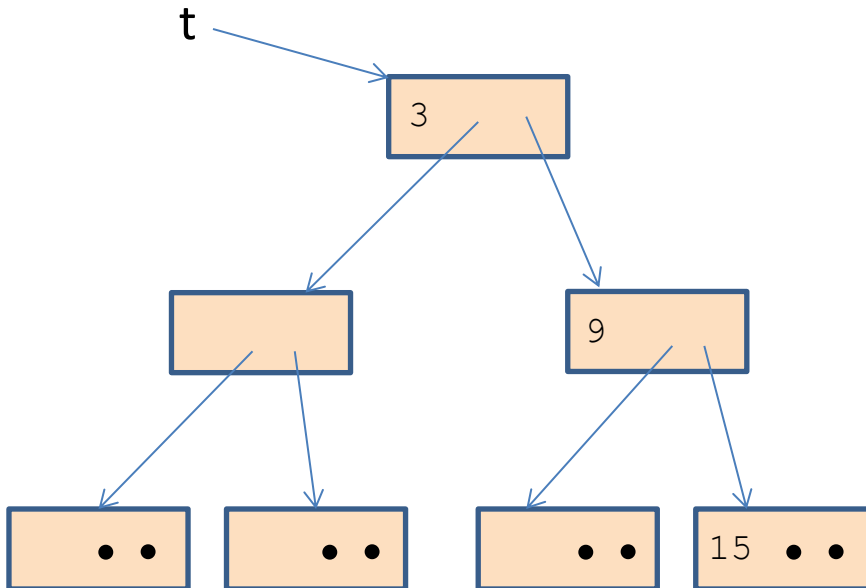
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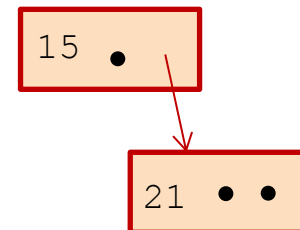
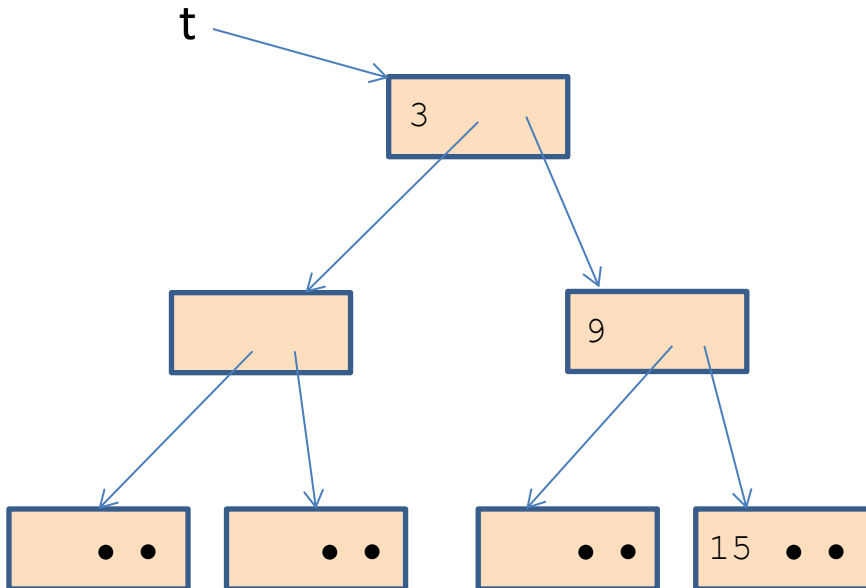
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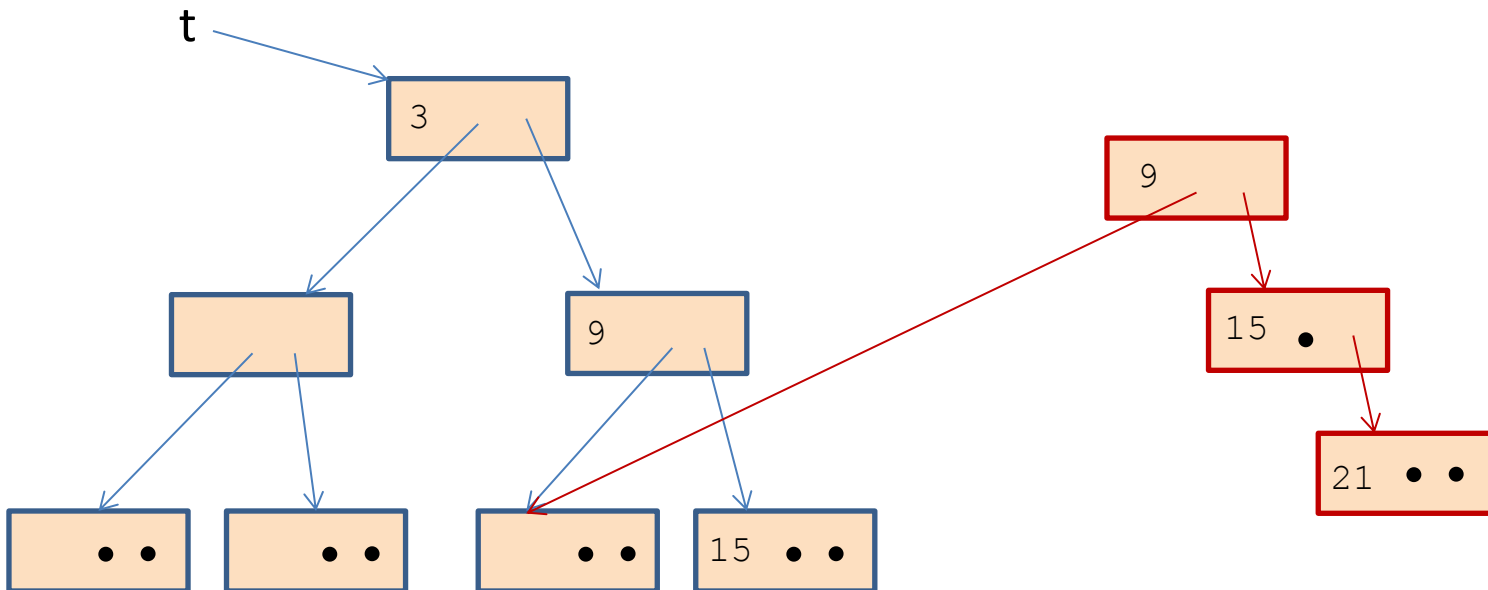


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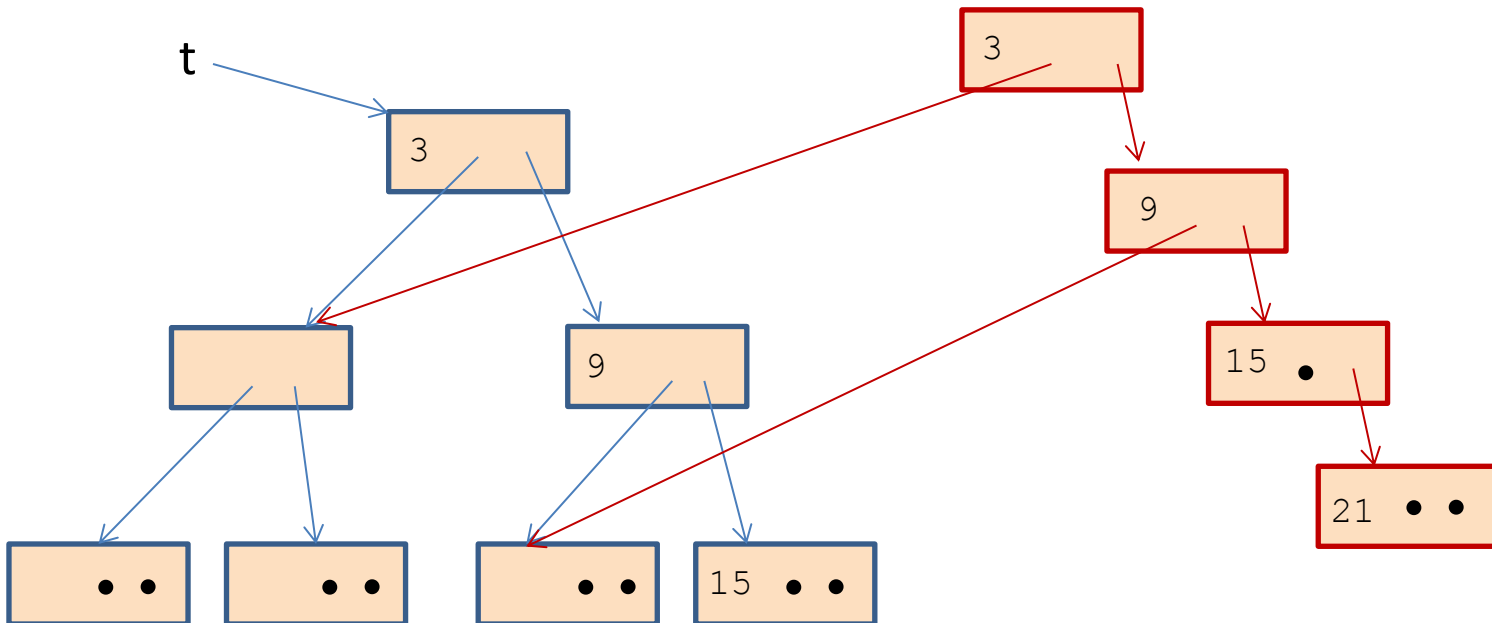


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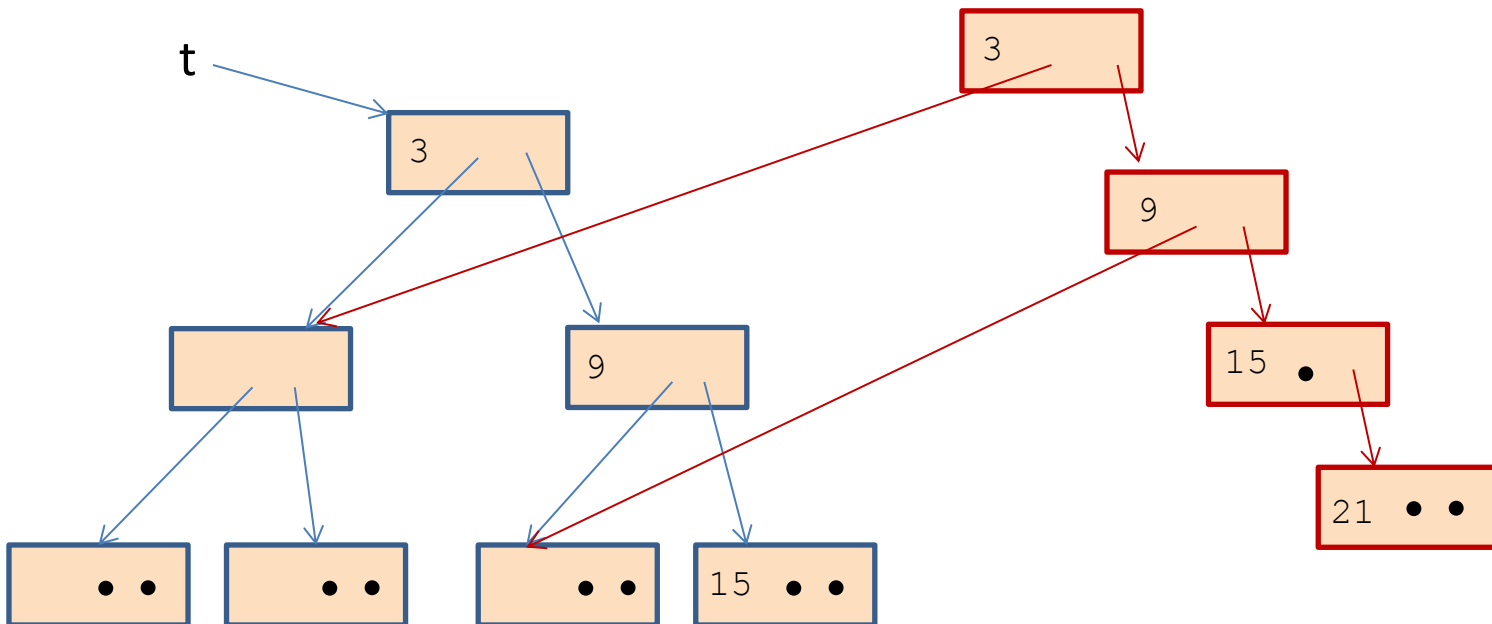
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```

Total space allocated is
proportional to the
height of the tree.

$\sim \log n$, if tree with n
nodes is balanced



Net space allocated

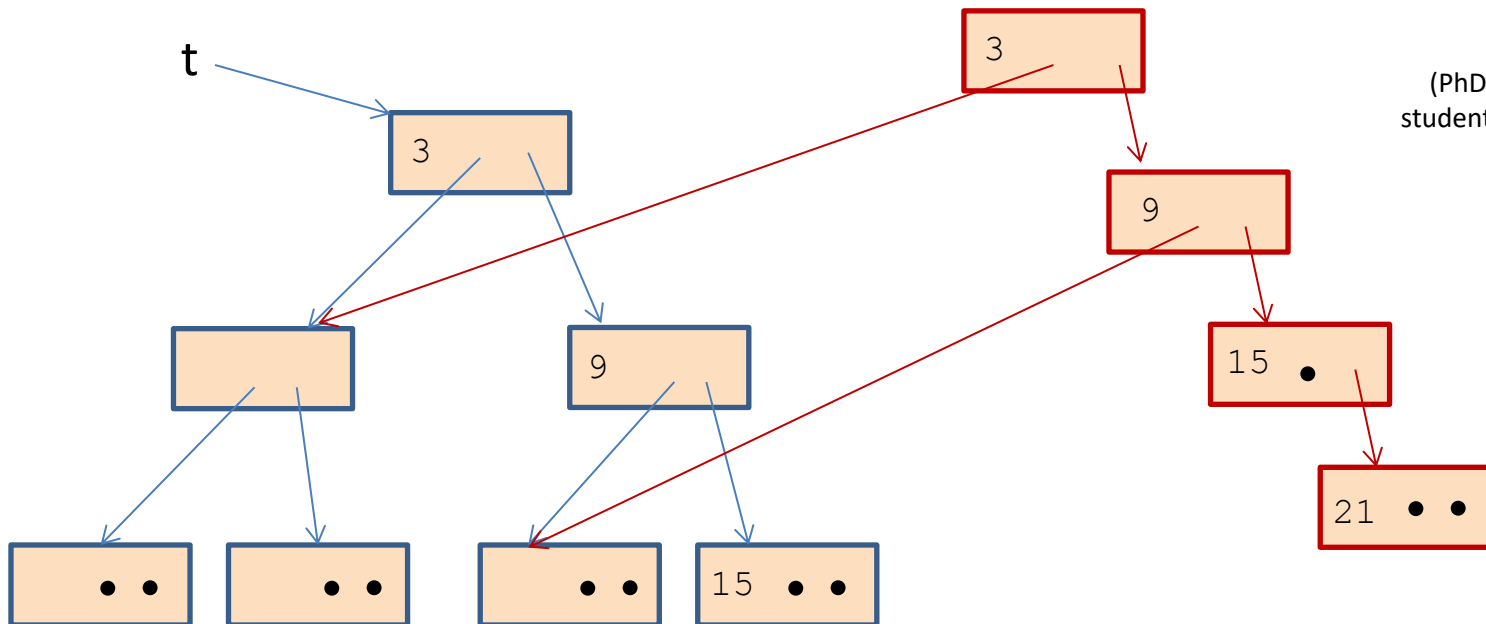
The garbage collector reclaims unreachable data structures on the heap.

```
let fiddle (t: tree) =  
  insert t 21
```



John McCarthy
invented GC
1960

(PhD Princeton 1951,
student of Alonzo Church)



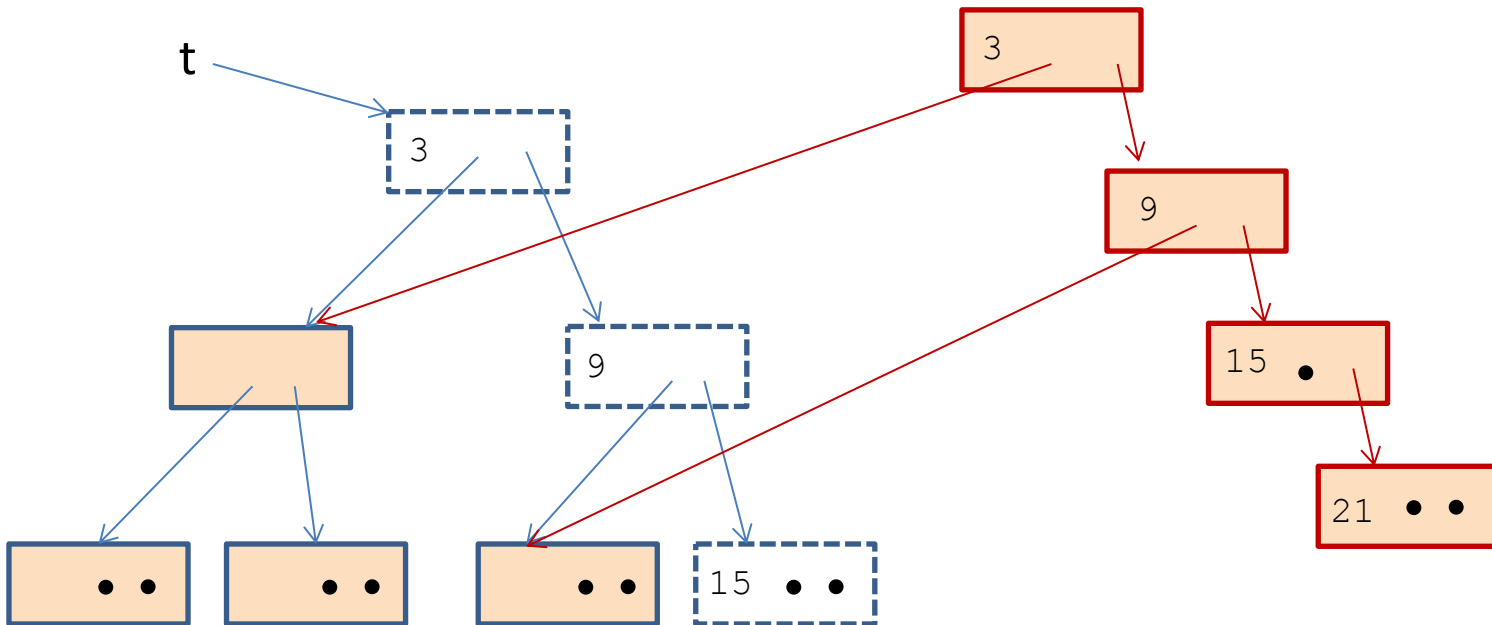
Net space allocated

The garbage collector reclaims
unreachable data structures on the heap.

```
let fiddle (t: tree) =  
  insert t 21
```

Net new space allocated:
1 node

(just like “imperative” version
of binary search trees)



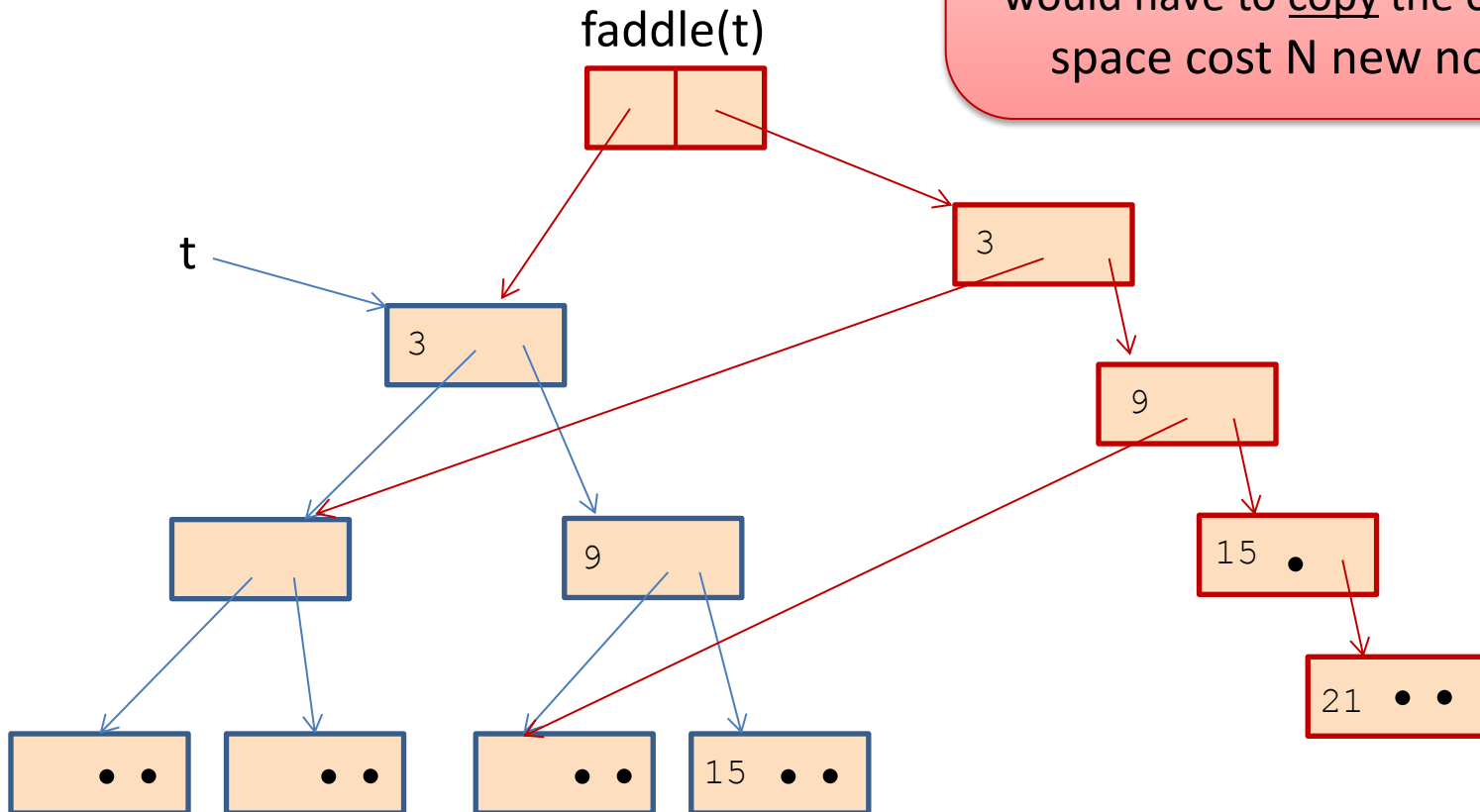
Net space allocated

But what if you want to keep the old tree?

```
let faddle (t: tree) =  
  (t, insert t 21)
```

Net new space allocated:
 $\log(N)$ nodes

but note: “imperative” version
would have to copy the old tree,
space cost N new nodes!



Compare

```
let check_option (o:int option) : int option =  
  match o with  
  | Some _ -> o  
  | None -> failwith "found none"
```

```
let check_option (o:int option) : int option =  
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Compare

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let check_option (o:int option) : int option =  
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```

allocates nothing
when arg is **Some i**

```
let check_option (o:int option) : int option =  
  match o with  
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```

allocates an option
when arg is **Some i**



Compare

```
let cadd (c1:int*int) (c2:int*int) : int*int =  
  let (x1,y1) = c1 in  
  let (x2,y2) = c2 in  
  (x1+x2, y1+y2)
```

```
let double (c1:int*int) : int*int =  
  let c2 = c1 in  
  cadd c1 c2
```

```
let double (c1:int*int) : int*int =  
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let double (c1:int*int) : int*int =  
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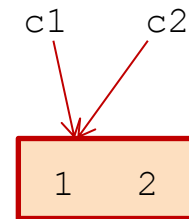
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Compare

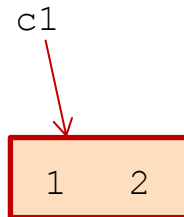
27

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Compare

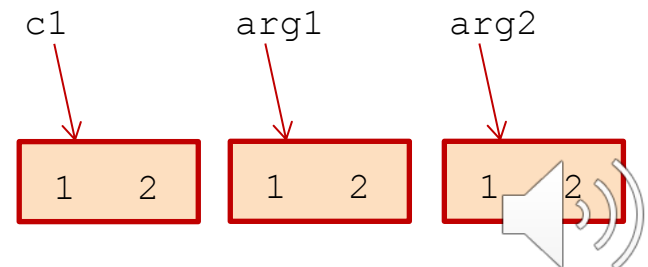
28

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```

no allocation

no allocation

allocates 2 pairs
(unless the compiler
happens to optimize.)



Compare

30

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```

```
let double (c1:int*int) : int*int =  
  let (x1,y1) = c1 in  
  cadd c1 c1
```

} double does not
allocate

← extracts components: it is a read



FUNCTION CLOSURES



Closures (A reminder)

Nested functions like bar often contain free variables:

```
let foo y =  
  let bar x = x + y in  
  bar
```

Here's bar on its own:

```
let bar x = x + y
```

y is *free* in the
definition of bar

To implement bar, the compiler creates a *closure*, which is a pair of code for the function plus an environment holding the free variables.

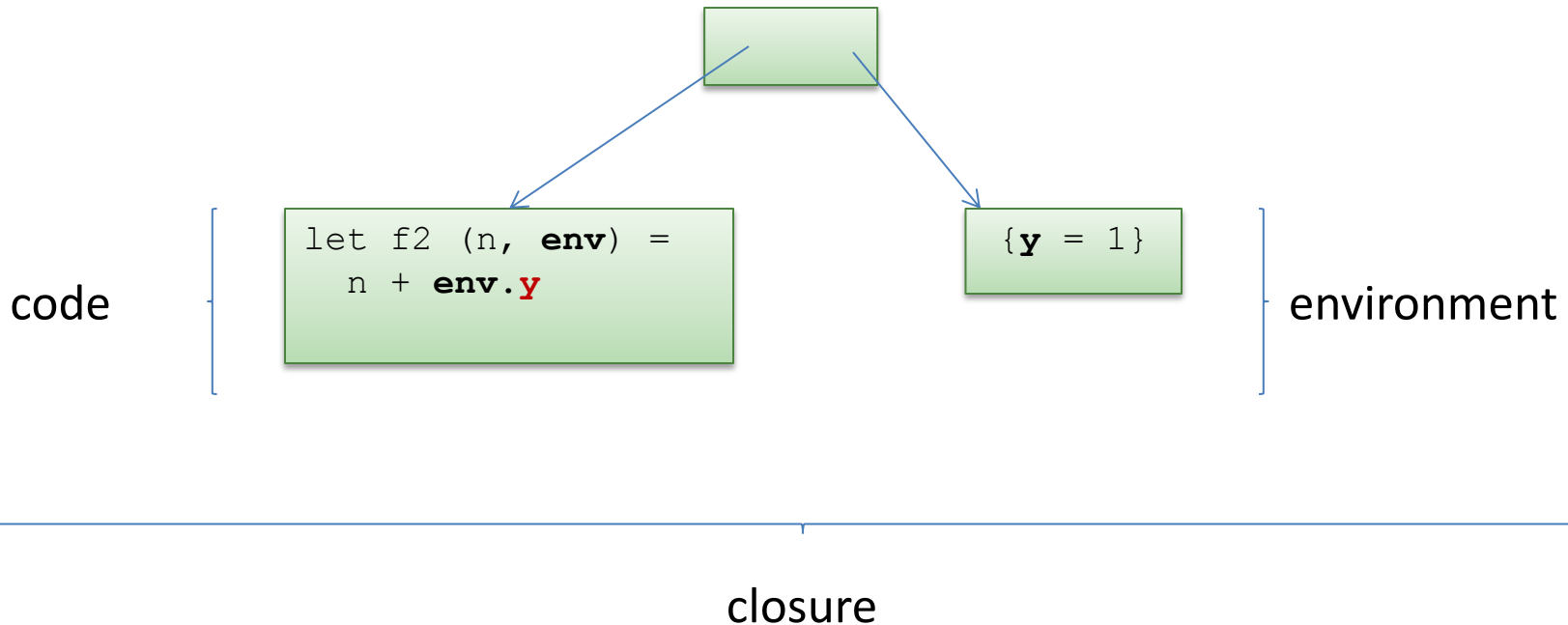


But what about nested, higher-order functions?

bar again:

```
let bar x = x + y
```

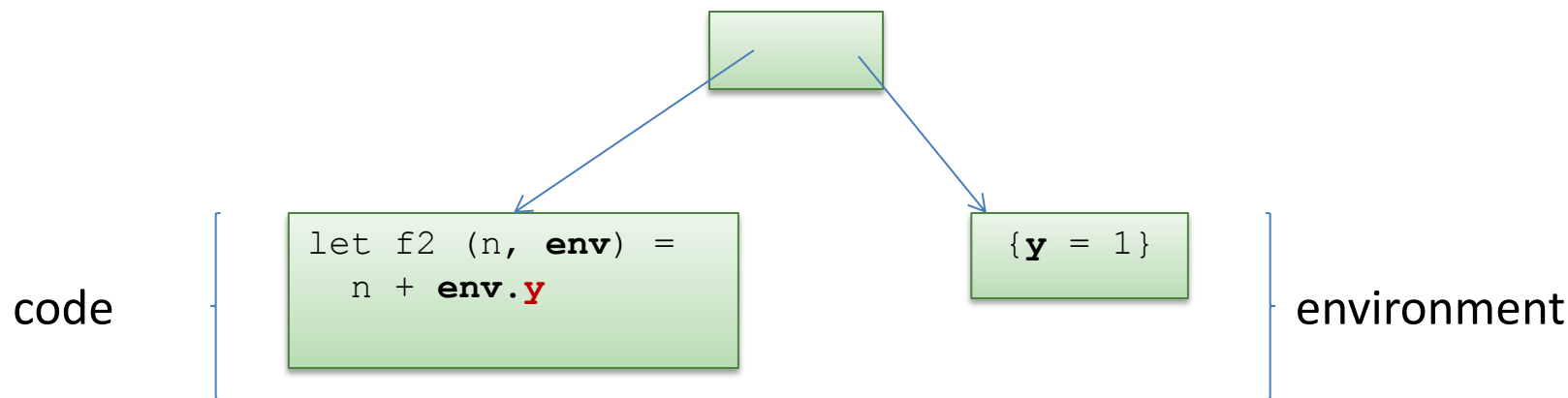
bar's representation:



But what about nested, higher-order functions?

34

To estimate the (heap) space used by a program, we often need to estimate the (heap) space used by its closures.



Our estimate will include the cost of the pair:

- two pointers = 2 words (8 bytes each, or 4 bytes each on some machines)
- the cost of the environment (1 word in this case).
- but not: the cost of the code (because the same code is reused in every closure of this function)



Space Model Summary

Understanding space consumption in FP involves:

- understanding the difference between
 - live space
 - rate of allocation
- understanding where allocation occurs
 - any time a constructor is used
 - whenever closures are created
- understanding the costs of
 - data types (fairly similar to Java)
 - costs of closures (cost of a pair of pointers + environment)



Exercise

36

```
let rec gen n =
  if n <= 0 then
    []
  else
    n::gen (n-1)

let rec goo n =
  if n <= 0 then
    []
  else
    (fun () -> gen n)::goo (n-1)

let rec gah n =
  let n <= 0 then
    []
  else
    let l = gen n in
    (fun () -> l)::goo (n-1)
```

Assume 8-byte words. Estimate the size of the data structure generated by a call to `goo` (respectively `gah`) in terms of their arguments `n`. Explain your work. Discuss.

