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4.3 MINIMUM SPANNING TREES

- ▶ *introduction*
- ▶ *cut property*
- ▶ *edge-weighted graph API*
- ▶ *Kruskal's algorithm*
- ▶ *Prim's algorithm*



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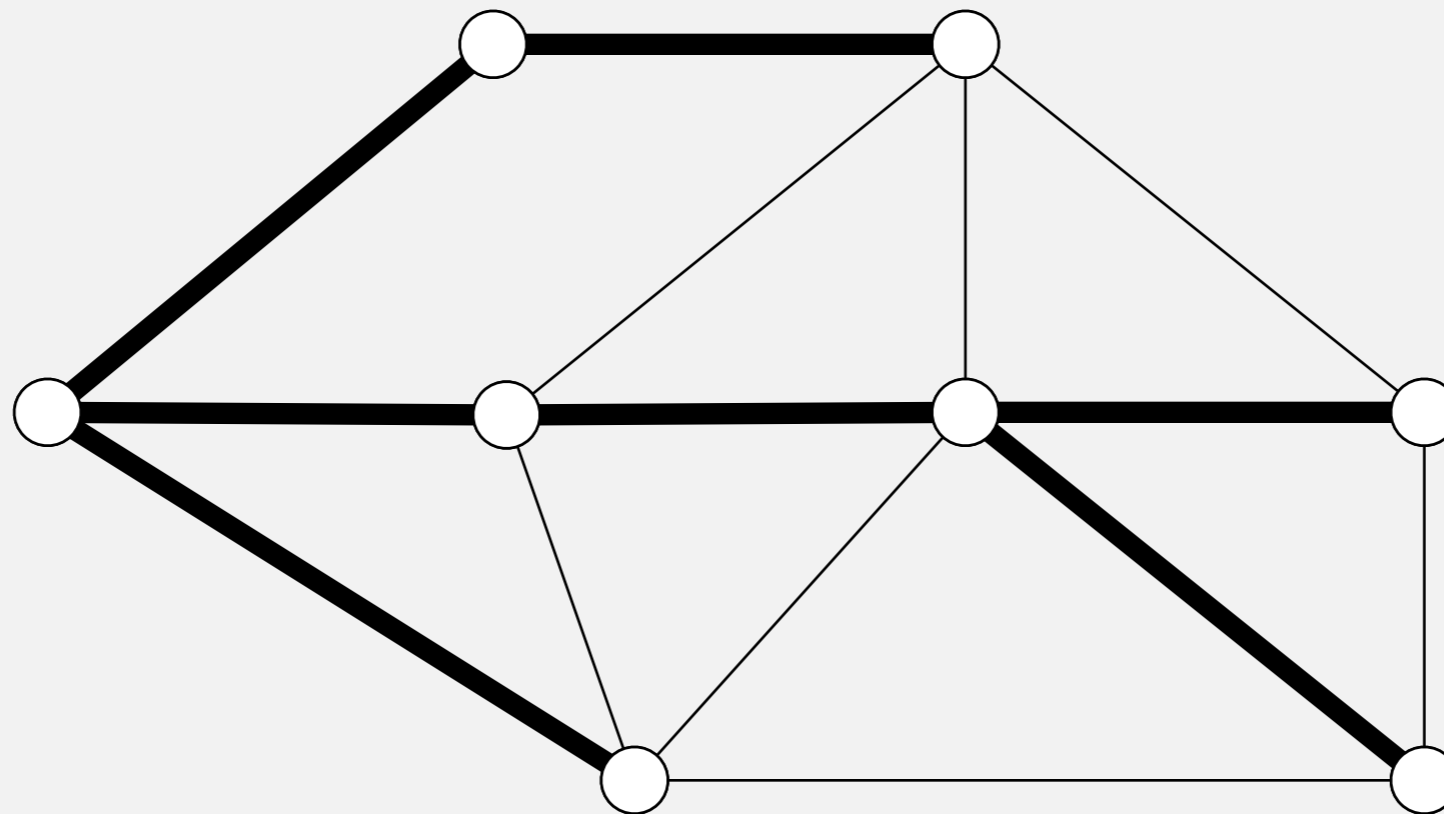
4.3 MINIMUM SPANNING TREES

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Spanning tree

Def. A **spanning tree** of G is a subgraph T that is:

- A tree: connected and acyclic.
- Spanning: includes all of the vertices.

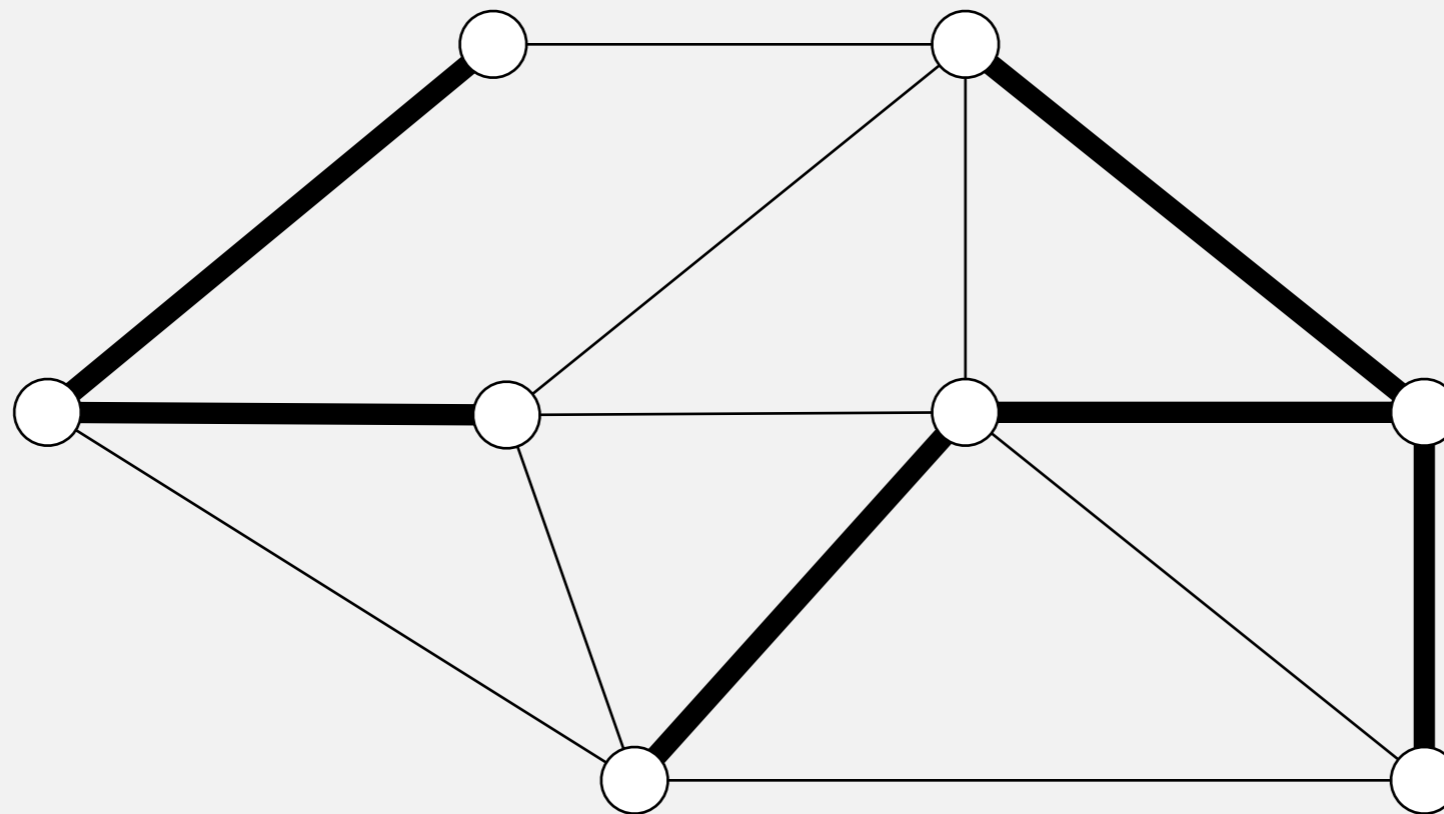


graph G
spanning tree T

Spanning tree

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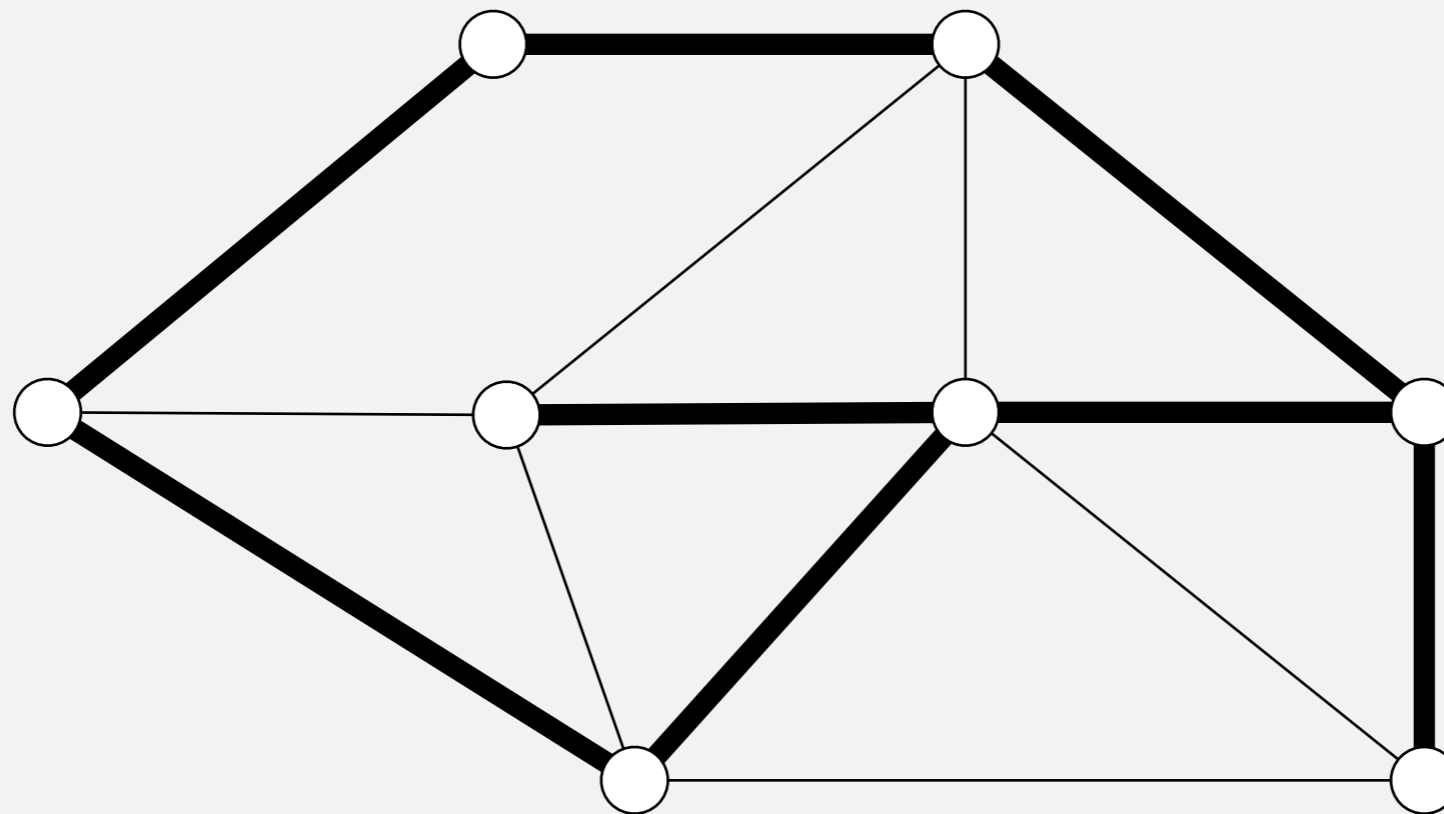


not connected

Spanning tree

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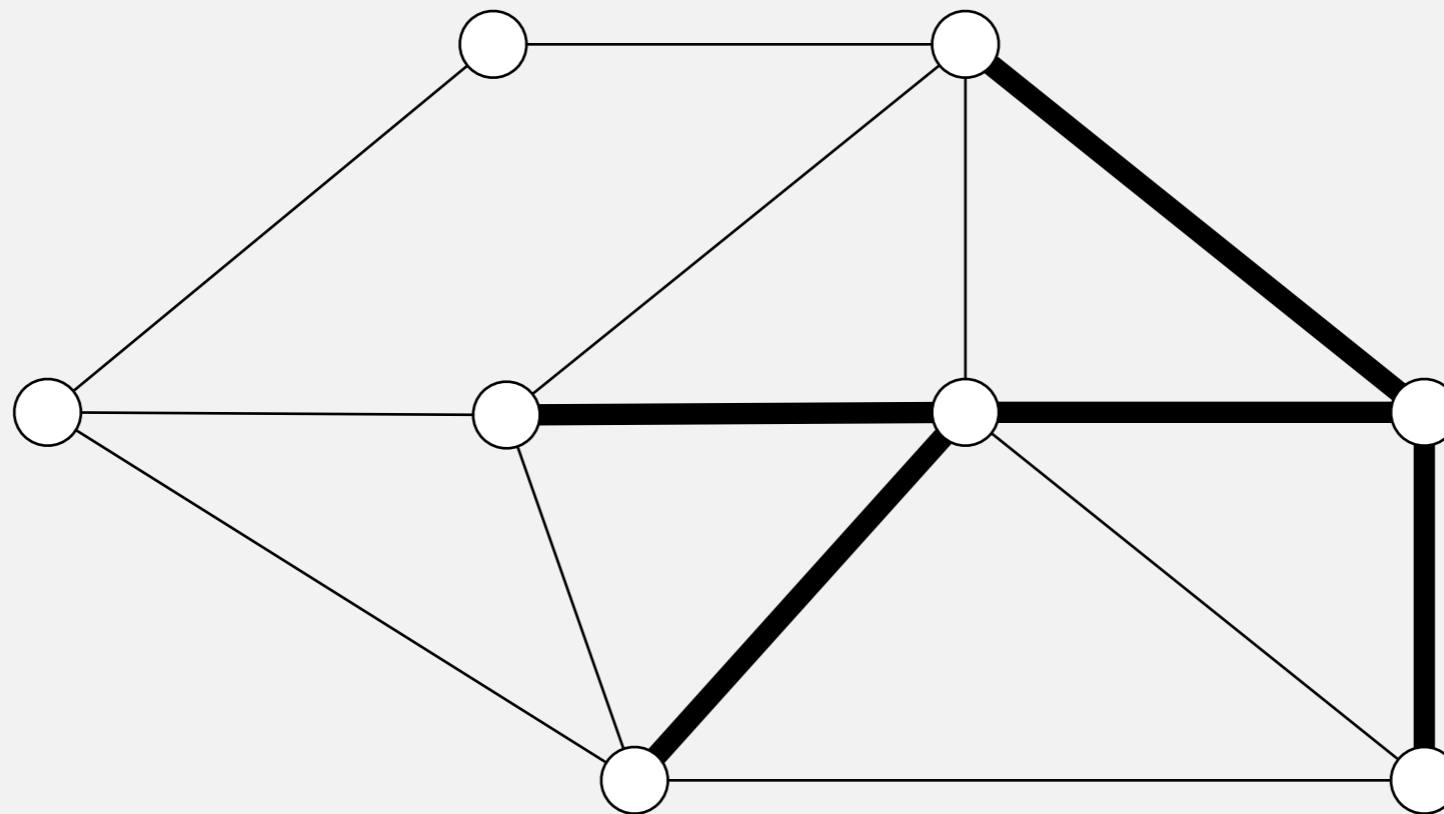


not acyclic

Spanning tree

Def. A **spanning tree** of G is a subgraph T that is:

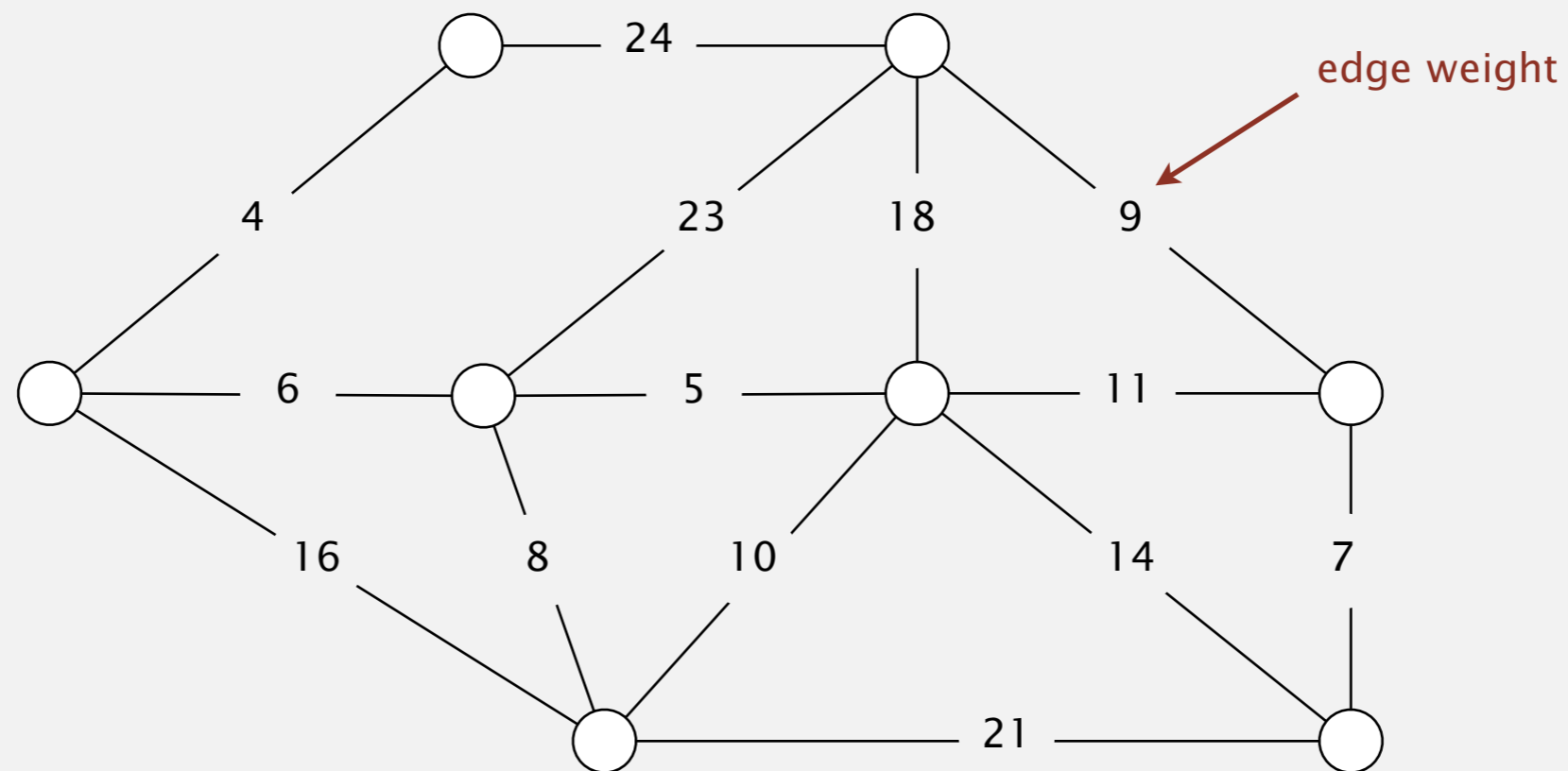
- A tree: connected and acyclic.
- Spanning: includes all of the vertices.



not spanning

Minimum spanning tree problem

Input. Connected, undirected graph G with positive edge weights.

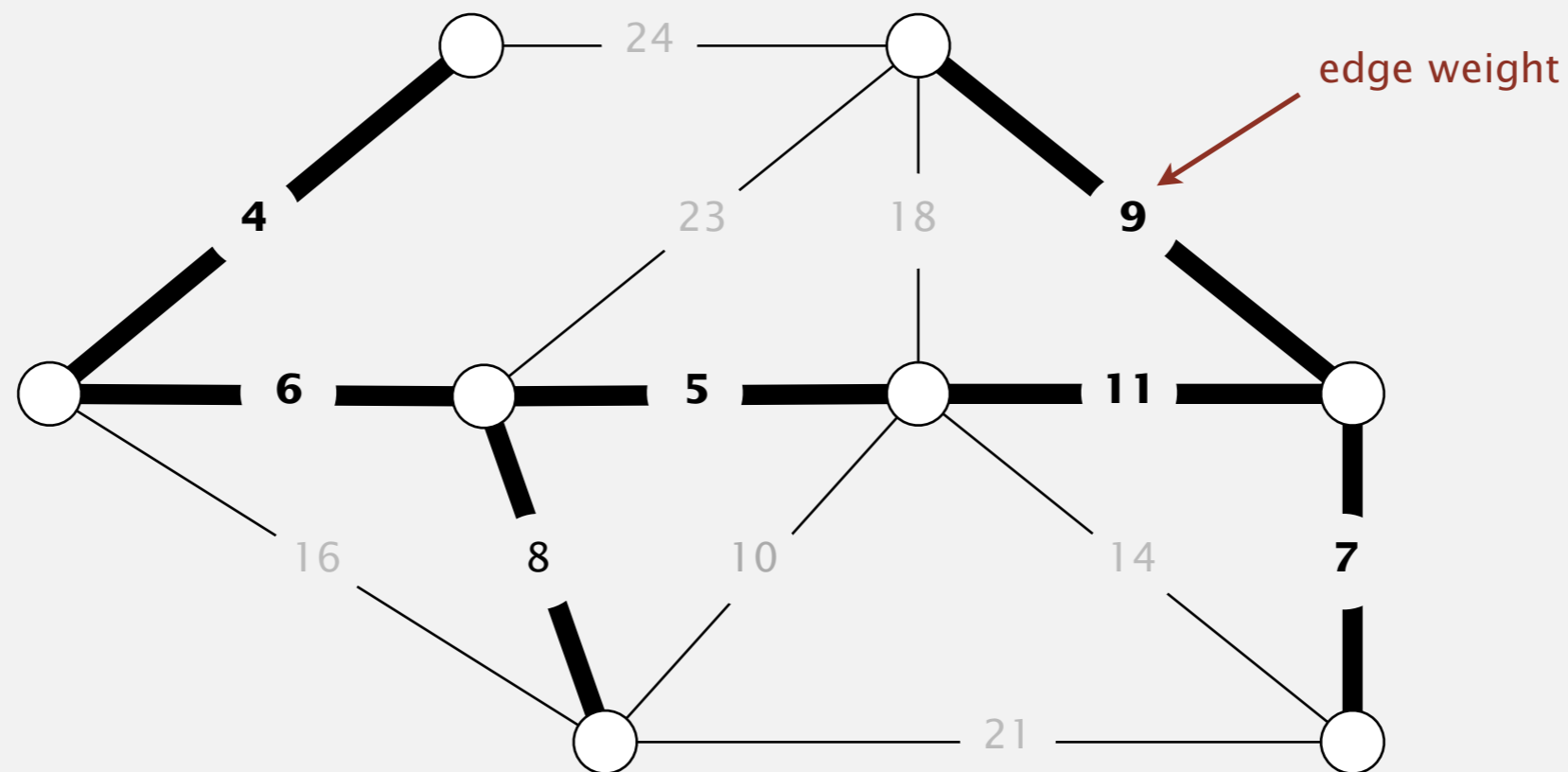


edge-weighted graph G

Minimum spanning tree problem

Input. Connected, undirected graph G with positive edge weights.

Output. A spanning tree of minimum weight.



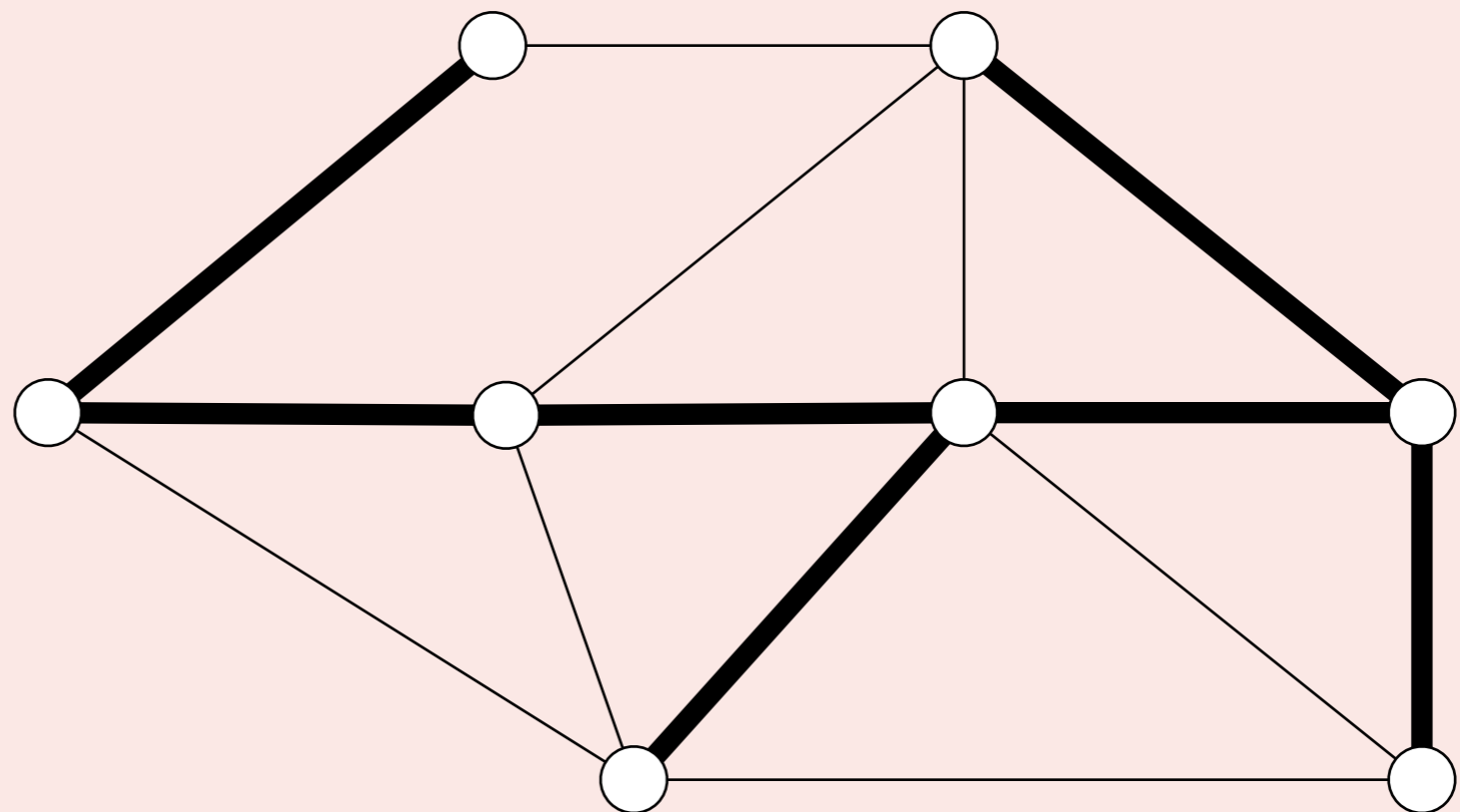
minimum spanning tree T
(weight = $50 = 4 + 6 + 5 + 8 + 9 + 11 + 7$)

Brute force. Try all spanning trees?



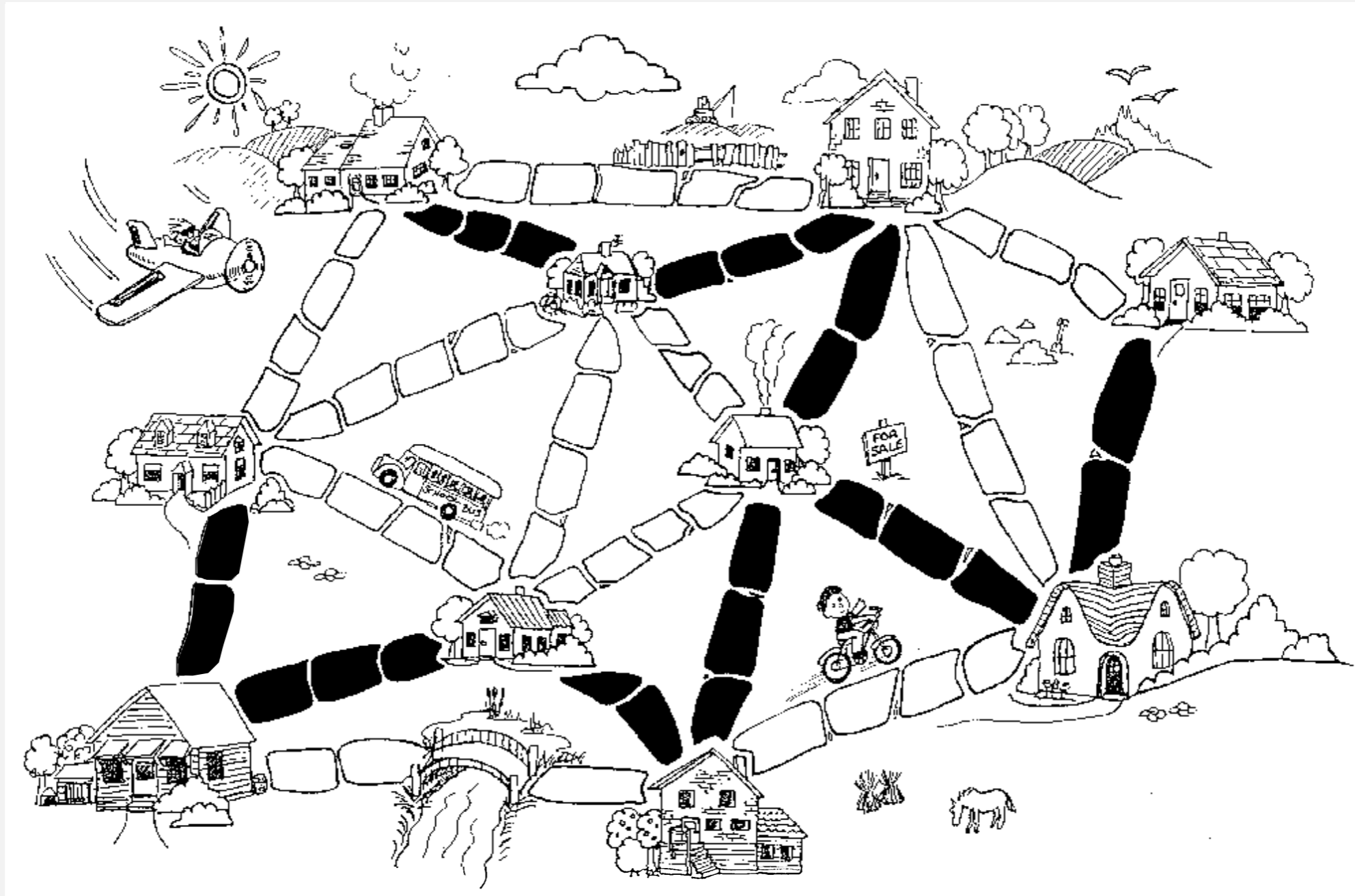
Let T be any spanning tree of a connected graph G with V vertices. Which of the following properties must hold?

- A.** T contains exactly $V - 1$ edges.
- B.** Removing any edge from T disconnects it.
- C.** Adding any edge to T creates a cycle.
- D.** All of the above.



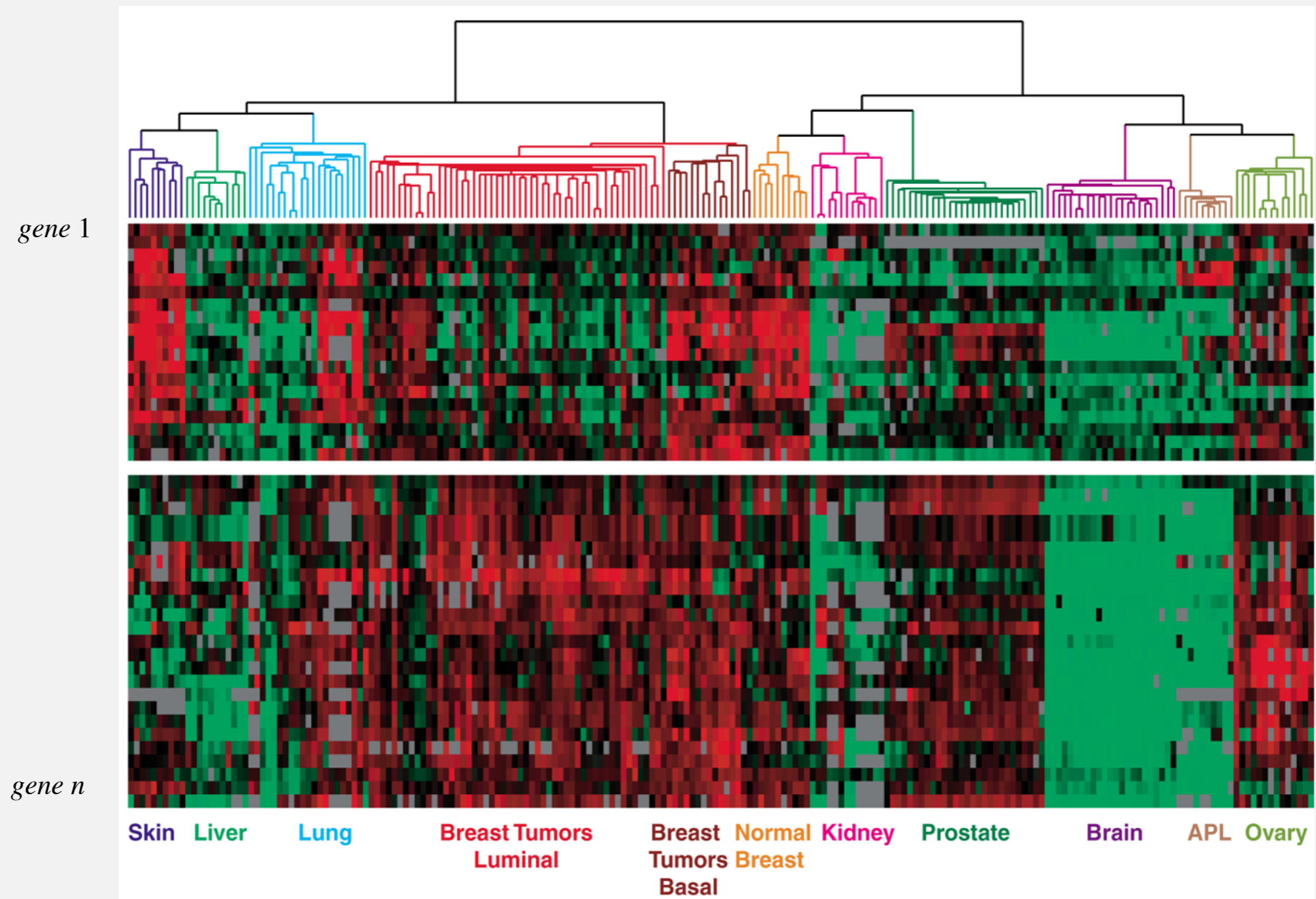
spanning tree T of graph G

Network design



<https://www.utdallas.edu/~besp/teaching/mst-applications.pdf>

Dendrogram of cancers in human



Reference: Botstein & Brown group

■ gene expressed
■ gene not expressed

Applications

MST is fundamental problem with diverse applications.

- Cluster analysis.
- Real-time face verification.
- LDPC codes for error correction.
- Image registration with Renyi entropy.
- Curvilinear feature extraction in computer vision.
- Find road networks in satellite and aerial imagery.
- Handwriting recognition of mathematical expressions.
- Measuring homogeneity of two-dimensional materials.
Model locality of particle interactions in turbulent fluid flows.
- Reducing data storage in sequencing amino acids in a protein.
- Autoconfig protocol for Ethernet bridging to avoid cycles in a network.
- Network design (communication, electrical, hydraulic, computer, road).
- Approximation algorithms for **NP**-hard problems (e.g., TSP, Steiner tree).

<http://www.ics.uci.edu/~eppstein/gina/mst.html>

<http://www.utdallas.edu/~besp/teaching/mst-applications.pdf>



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4.3 MINIMUM SPANNING TREES

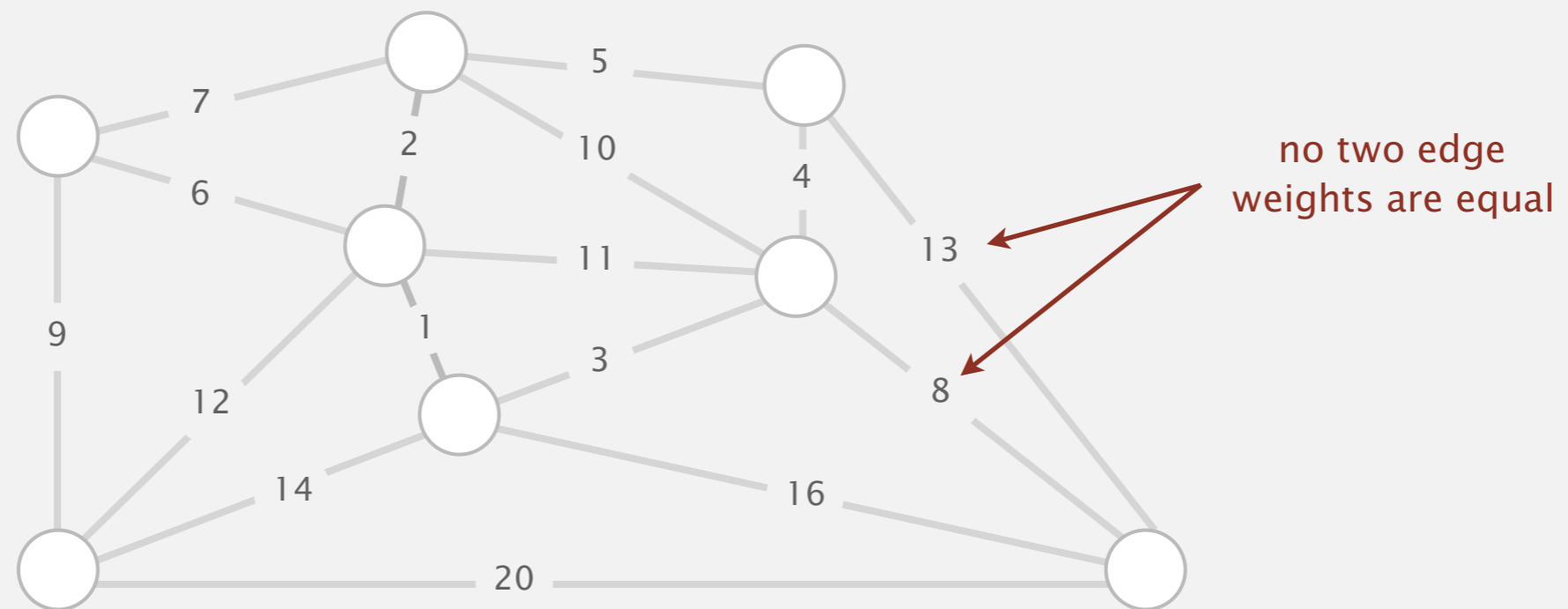
- ▶ *introduction*
- ▶ *cut property*
- ▶ *edge-weighted graph API*
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- ▶ *Prim's algorithm*

Simplifying assumptions

For simplicity, we assume:

- The graph is connected. \Rightarrow MST exists.
- The edge weights are distinct. \Rightarrow MST is unique. \leftarrow see Exercise 4.3.3

Note. Algorithms still work even if duplicate edge weights.

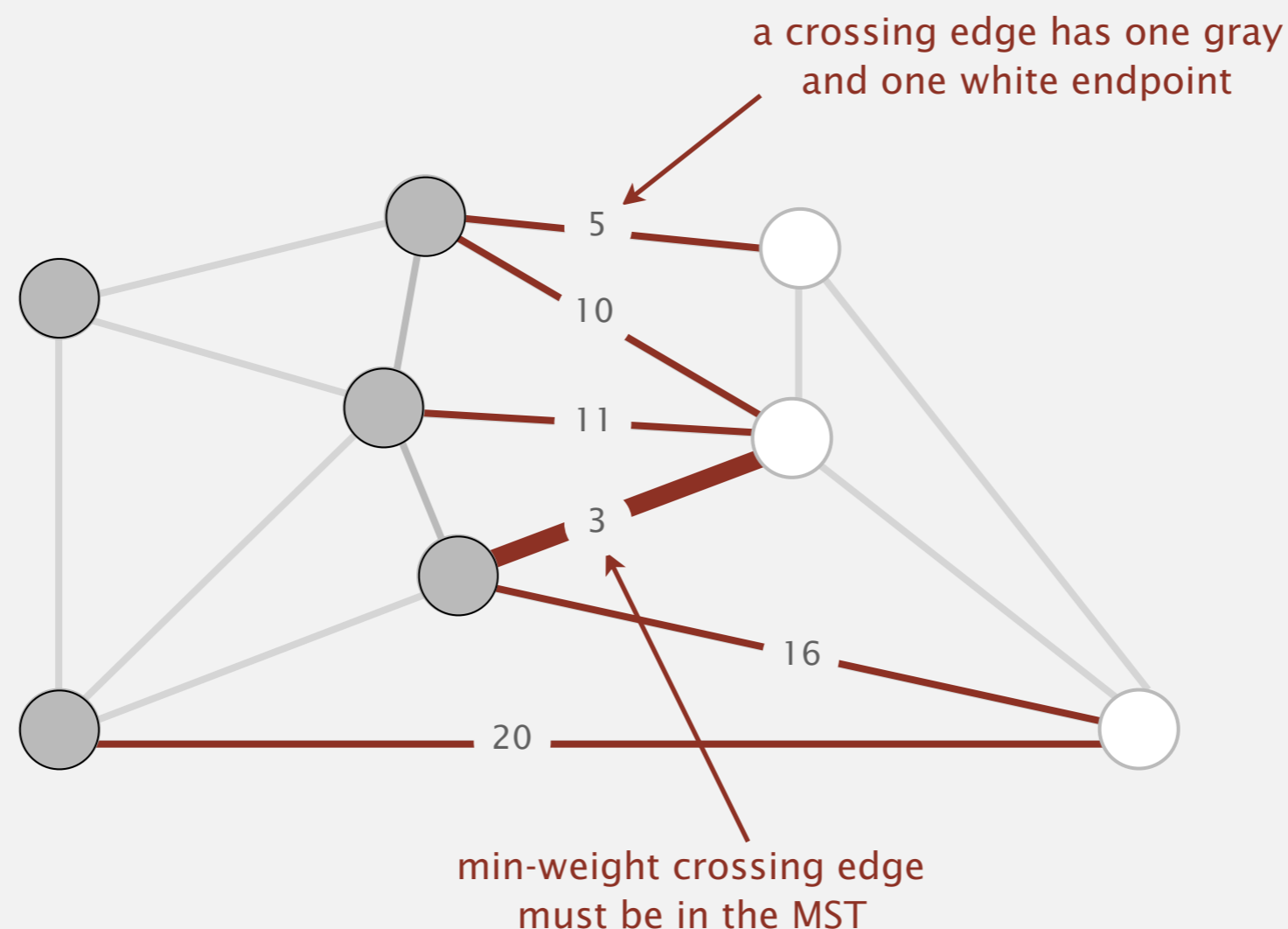


Cut property

Def. A **cut** in a graph is a partition of its vertices into two (nonempty) sets.

Def. A **crossing edge** is an edge that has one endpoint in each set.

Cut property. For any cut, the min-weight crossing edge is in the MST.





Which is the min-weight edge crossing the cut $\{2, 3, 5, 6\}$?

A. 0–7 (0.16)

B. 2–3 (0.17)

C. 0–2 (0.26)

D. 5–7 (0.28)

0–7 0.16

2–3 0.17

1–7 0.19

0–2 0.26

5–7 0.28

1–3 0.29

1–5 0.32

2–7 0.34

4–5 0.35

1–2 0.36

4–7 0.37

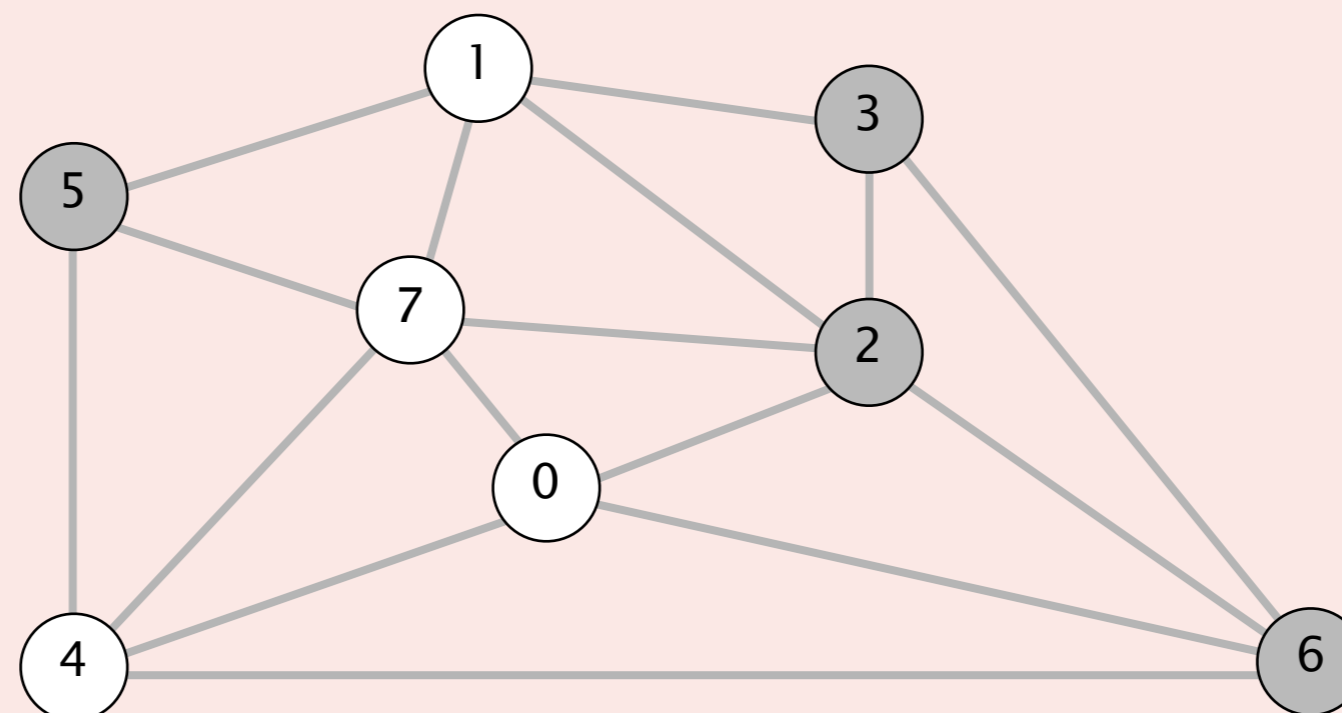
0–4 0.38

6–2 0.40

3–6 0.52

6–0 0.58

6–4 0.93



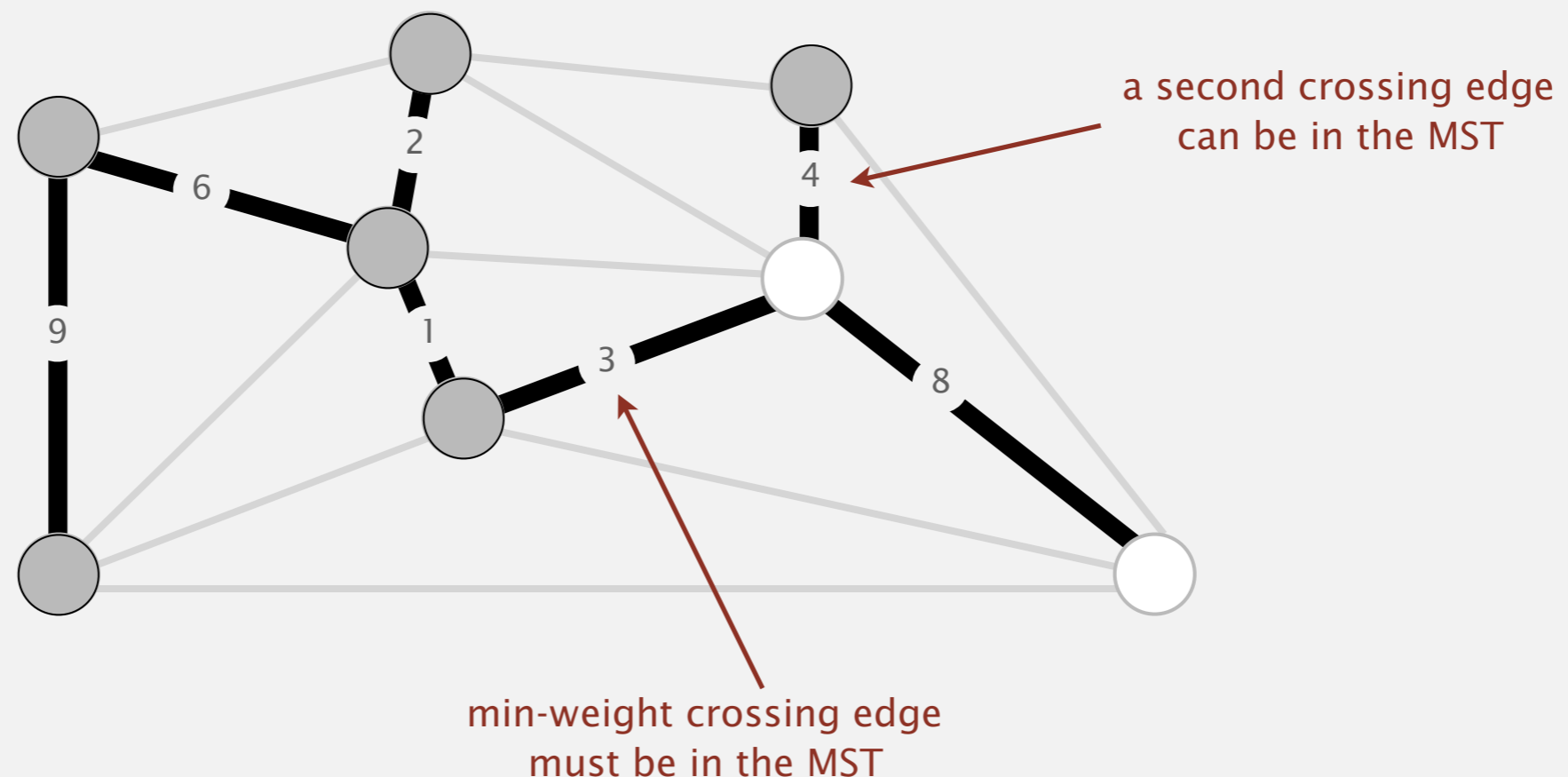
Cut property

Def. A **cut** in a graph is a partition of its vertices into two (nonempty) sets.

Def. A **crossing edge** is an edge that has one endpoint in each set.

Cut property. For any cut, the min-weight crossing edge e is in the MST.

Note. A cut may have multiple edges in the MST.



Cut property: correctness proof

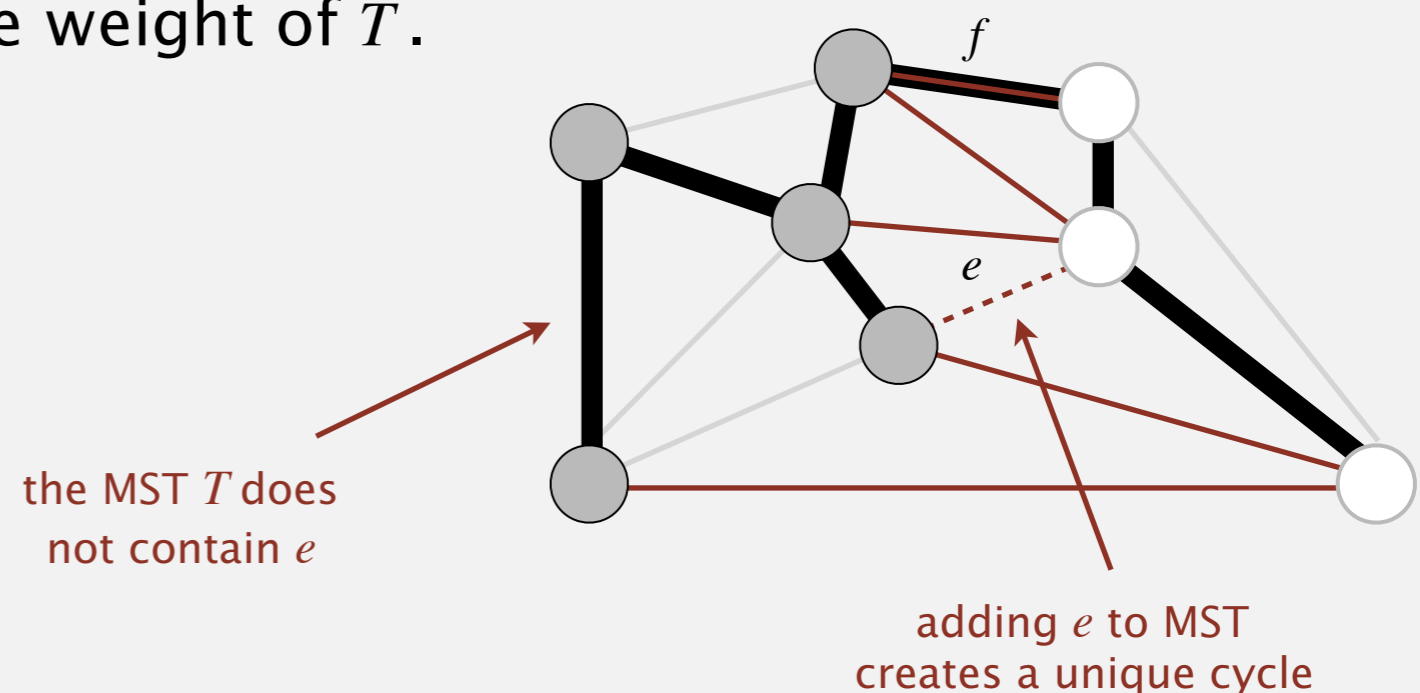
Def. A **cut** in a graph is a partition of its vertices into two (nonempty) sets.

Def. A **crossing edge** is an edge that has one endpoint in each set.

Cut property. For any cut, the min-weight crossing edge e is in the MST.

Pf. [by contradiction] Suppose e is not in the MST T .

- Adding e to the MST creates a cycle.
- Some other edge f in cycle must be a crossing edge.
- Removing f and adding e yields a different spanning tree T' .
- Since weight of e is less than the weight of f , the weight of T' is less than the weight of T .
- Contradiction. ■



Framework for minimum spanning tree algorithm

Generic algorithm (to compute MST)

$T = \emptyset$.

Repeat until T is a spanning tree: $\leftarrow V - 1$ edges

- Find a cut in G .
 - $e \leftarrow$ min-weight crossing edge.
 - $T \leftarrow T \cup \{e\}$.
-

Efficient implementations.

- Which cut? $\leftarrow 2^{V-2}$ distinct cuts
- How to compute min-weight crossing edge.

Ex 1. Kruskal's algorithm.

Ex 2. Prim's algorithm.

Ex 3. Borůvka's algorithm.



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Weighted edge API

Edge abstraction for weighted edges.

```
public class Edge implements Comparable<Edge>
```

```
    Edge(int v, int w, double weight)    create a weighted edge v-w
```

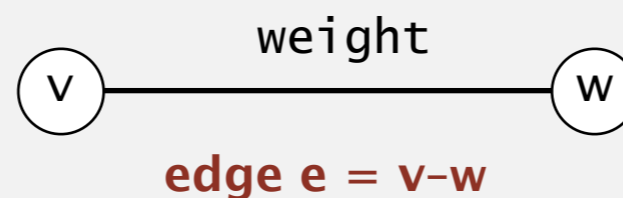
```
    int either()                        either endpoint
```

```
    int other(int v)                   the endpoint that's not v
```

```
    int compareTo(Edge that)          compare edges by weight
```

```
    ⋮
```

```
    ⋮
```



Idiom for processing an edge *e*. `int v = e.either(), w = e.other(v).`

Weighted edge: Java implementation

```
public class Edge implements Comparable<Edge>
{
```

```
    private final int v, w;
    private final double weight;
```

```
    public Edge(int v, int w, double weight)
    {
        this.v = v;
        this.w = w;
        this.weight = weight;
    }
```

← constructor

```
    public int either()
    { return v; }
```

← either endpoint

```
    public int other(int vertex)
    {
        if (vertex == v) return w;
        else return v;
    }
```

← other endpoint

compare edges by weight

```
    public int compareTo(Edge that)
    { return Double.compare(this.weight, that.weight); }
```

```
}
```

Edge-weighted graph API

API. Same as Graph and Digraph, except with explicit Edge objects.

```
public class EdgeWeightedGraph
```

```
    EdgeWeightedGraph(int V)
```

create an empty graph with V vertices

```
    void addEdge(Edge e)
```

add weighted edge e to this graph

```
    Iterable<Edge> adj(int v)
```

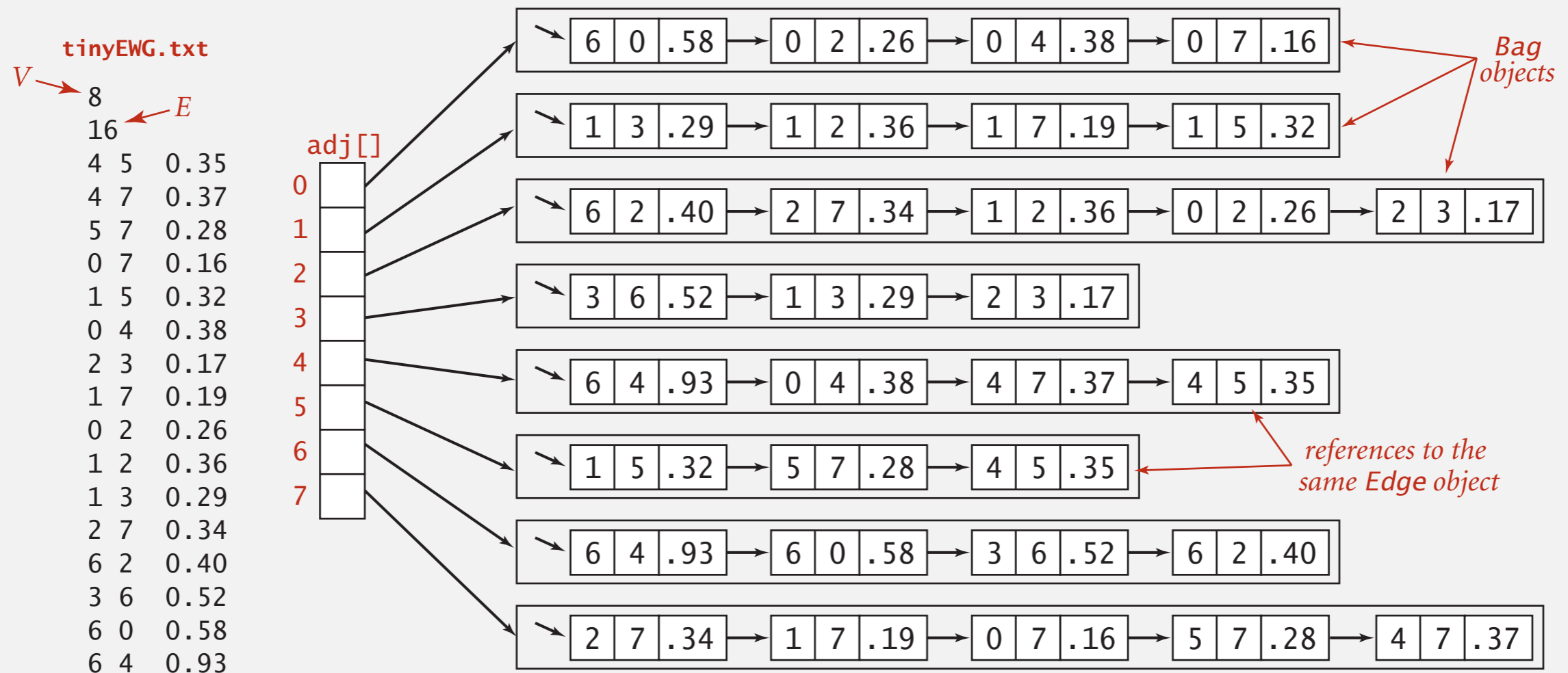
edges incident to v

```
    ⋮
```

```
    ⋮
```

Edge-weighted graph: adjacency-lists representation

Representation. Maintain vertex-indexed array of Edge lists.



Edge-weighted graph: adjacency-lists implementation

```
public class EdgeWeightedGraph  
{
```

```
    private final int V;  
    private final Bag<Edge>[] adj;
```

← same as Graph, but
adjacency lists of Edge objects

```
    public EdgeWeightedGraph(int V)  
    {  
        this.V = V;  
        adj = (Bag<Edge>[]) new Bag[V];  
        for (int v = 0; v < V; v++)  
            adj[v] = new Bag<Edge>();  
    }
```

← constructor

```
    public void addEdge(Edge e)  
    {  
        int v = e.either(), w = e.other(v);  
        adj[v].add(e);  
        adj[w].add(e);  
    }
```

← add same Edge object
to both adjacency lists

```
    public Iterable<Edge> adj(int v)  
    { return adj[v]; }
```

```
}
```

Minimum spanning tree API

Q. How to represent the MST?

A. Technically, an MST is an edge-weighted graph.
For convenience, we represent it as a set of edges.

```
public class MST
```

```
    MST(EdgeWeightedGraph G)
```

constructor

```
    Iterable<Edge> edges()
```

edges in MST

```
    double weight()
```

weight of MST



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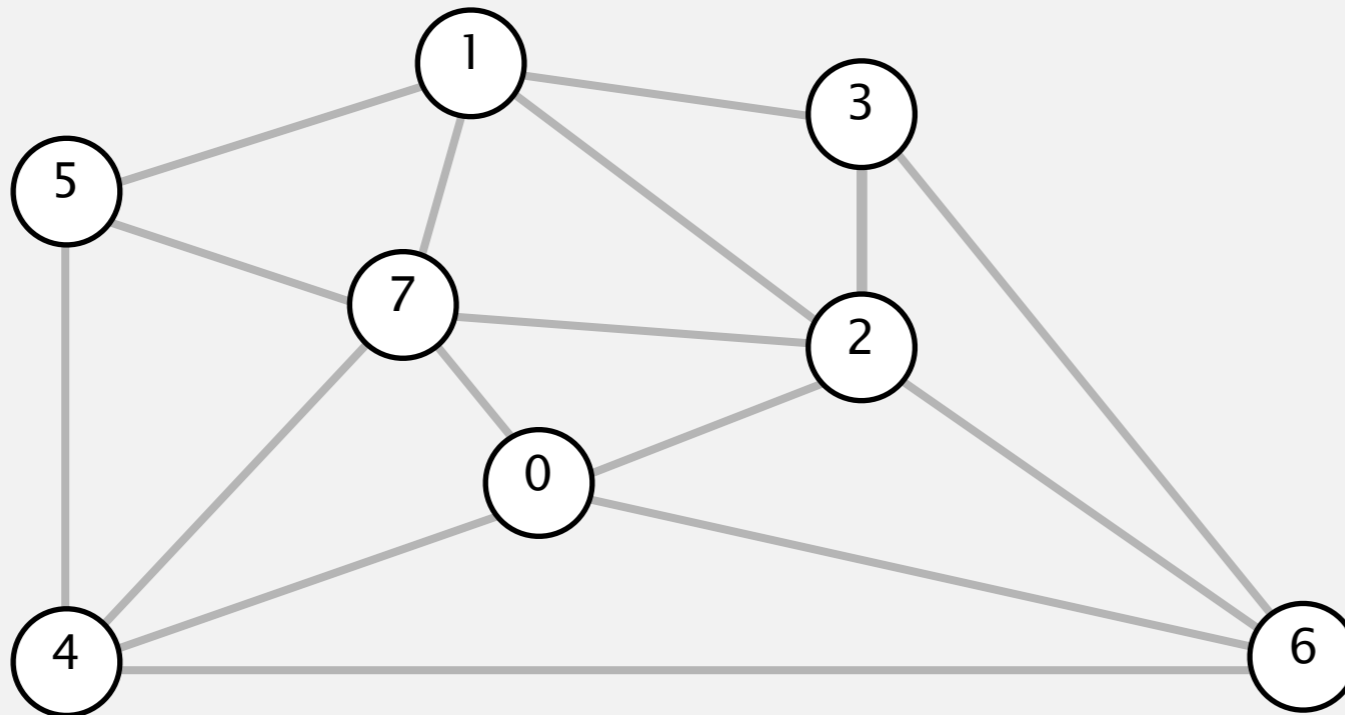
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Kruskal's algorithm demo

Consider edges in ascending order of weight.

- Add next edge to T unless doing so would create a cycle.



an edge-weighted graph

graph edges
sorted by weight

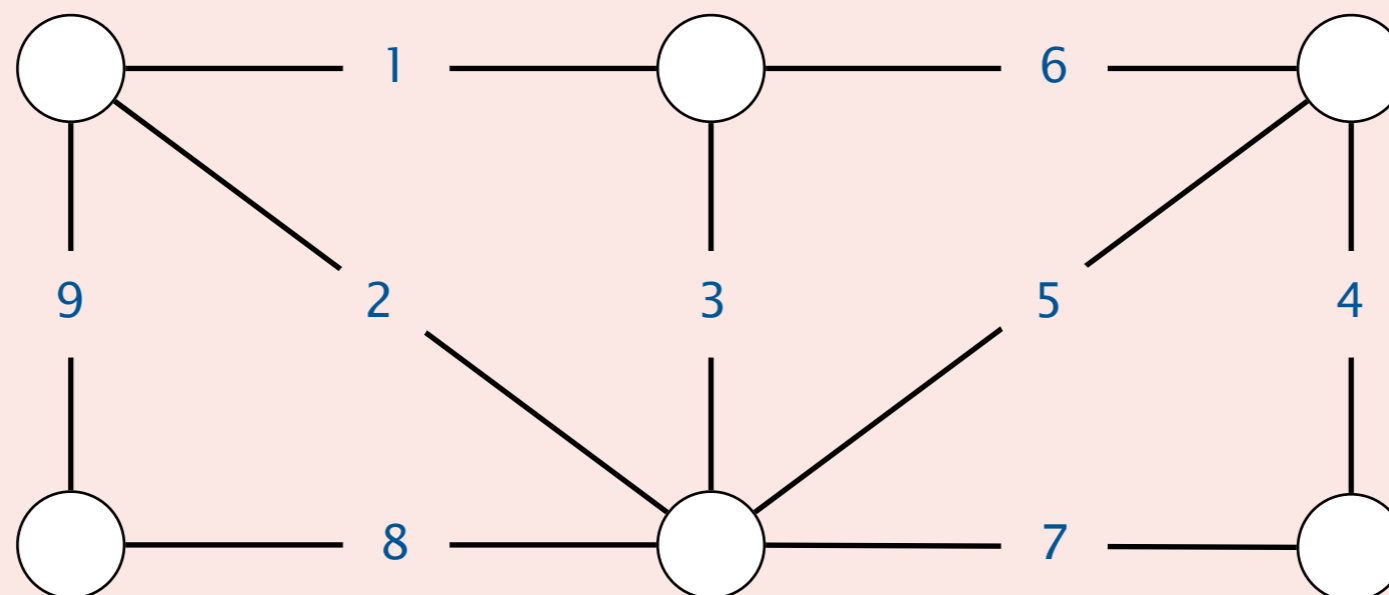
↓

0-7	0.16
2-3	0.17
1-7	0.19
0-2	0.26
5-7	0.28
1-3	0.29
1-5	0.32
2-7	0.34
4-5	0.35
1-2	0.36
4-7	0.37
0-4	0.38
6-2	0.40
3-6	0.52
6-0	0.58
6-4	0.93

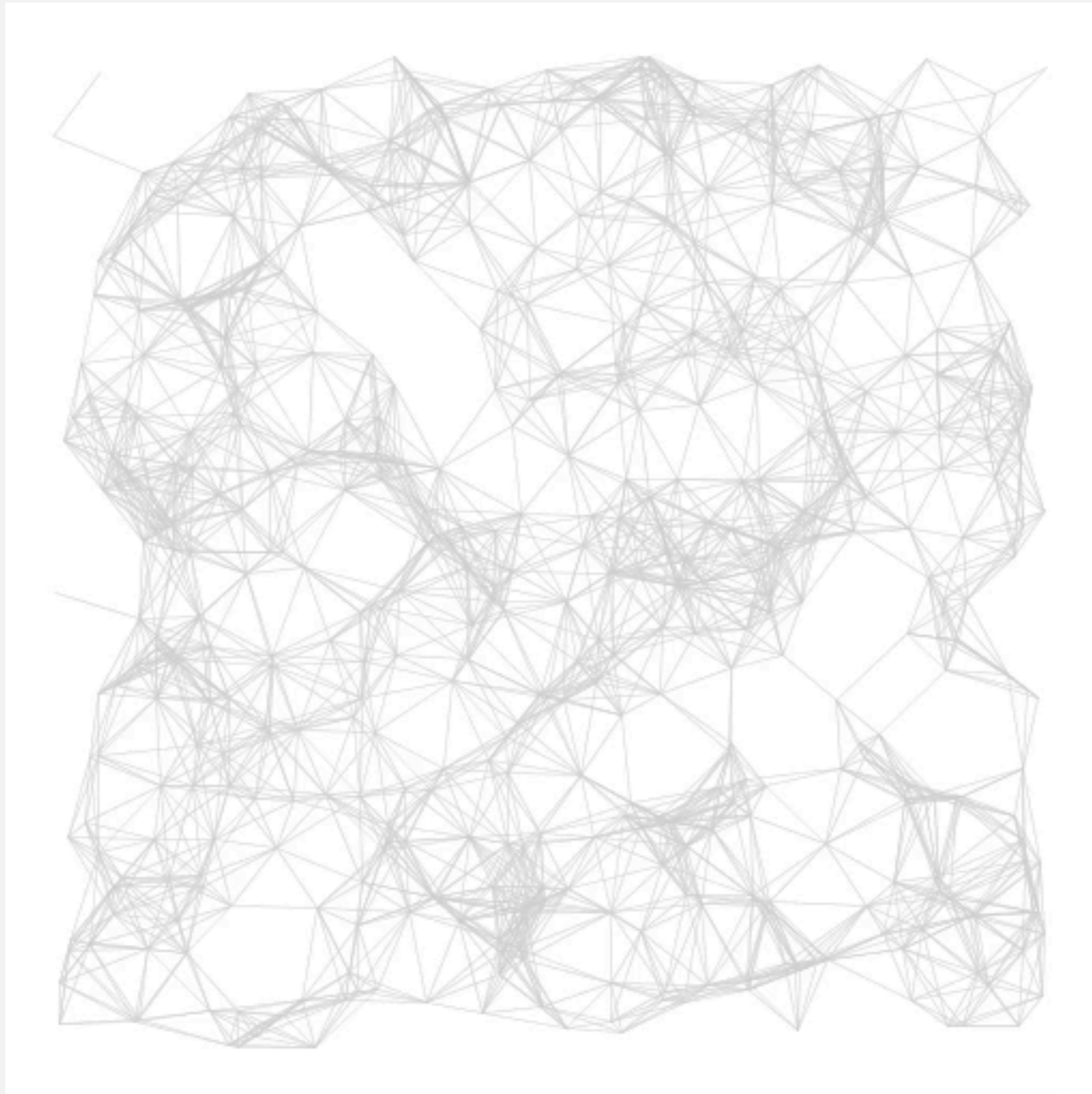


In which order does Kruskal's algorithm select edges in MST?

- A.** 1, 2, 4, 5, 6
- B.** 1, 2, 4, 5, 8
- C.** 1, 2, 5, 4, 8
- D.** 8, 2, 1, 5, 4



Kruskal's algorithm: visualization



Kruskal's algorithm: correctness proof

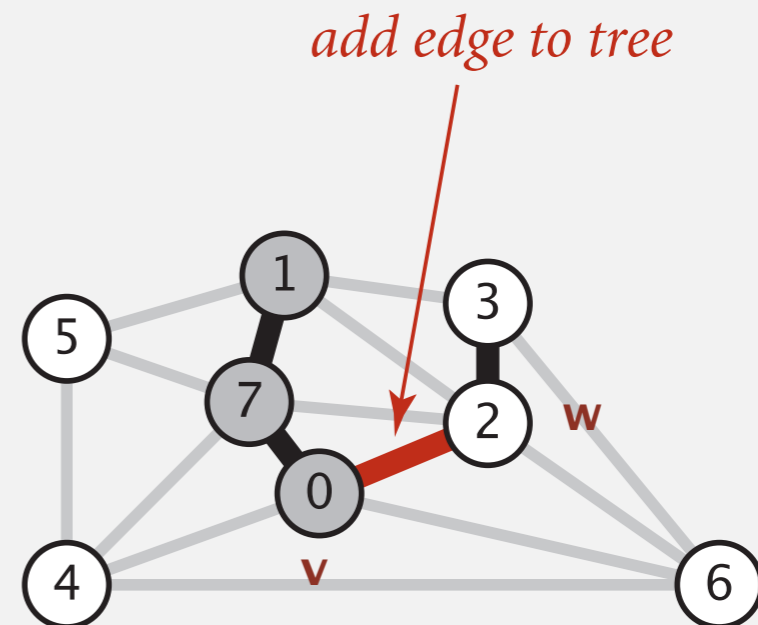
Proposition. [Kruskal 1956] Kruskal's algorithm computes the MST.

Pf. Let T be tree at some point during execution, and let e be next edge.

[Case 1] Kruskal's algorithm adds edge $e = v-w$ to T .

recall: consider edges
in ascending order
by weight

- Vertices v and w are in different connected components of T .
- Cut = set of vertices connected to v in T .
- By construction of cut, no edge crossing cut is currently in T .
- No edge crossing cut has lower weight. Why?
- Cut property \Rightarrow edge e is in the MST.



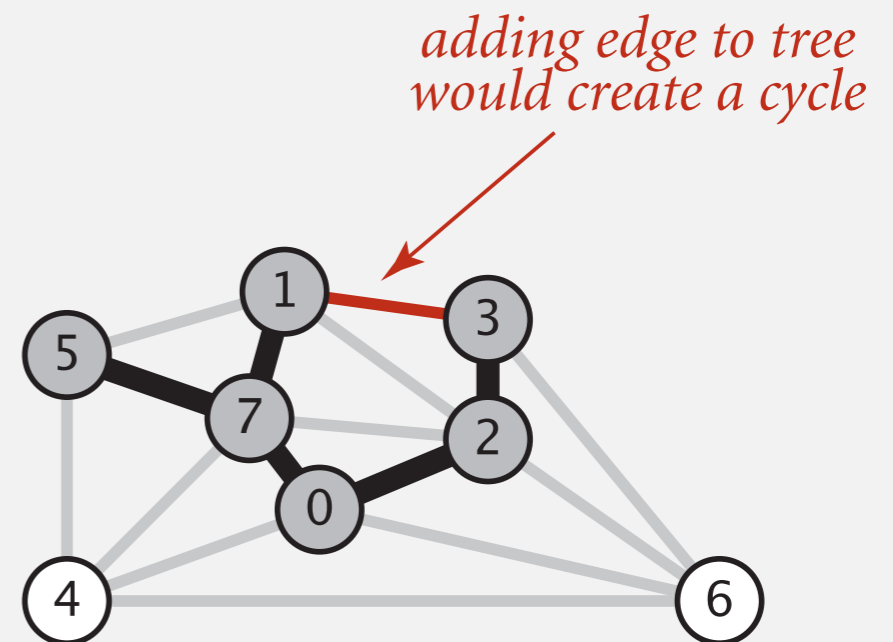
Kruskal's algorithm: correctness proof

Proposition. [Kruskal 1956] Kruskal's algorithm computes the MST.

Pf. Let T be tree at some point during execution, and let e be next edge.

[Case 2] Kruskal's algorithm discards edge $e = v-w$.

- From Case 1, all edges in T are in the MST.
- The MST can't contain a cycle. ■

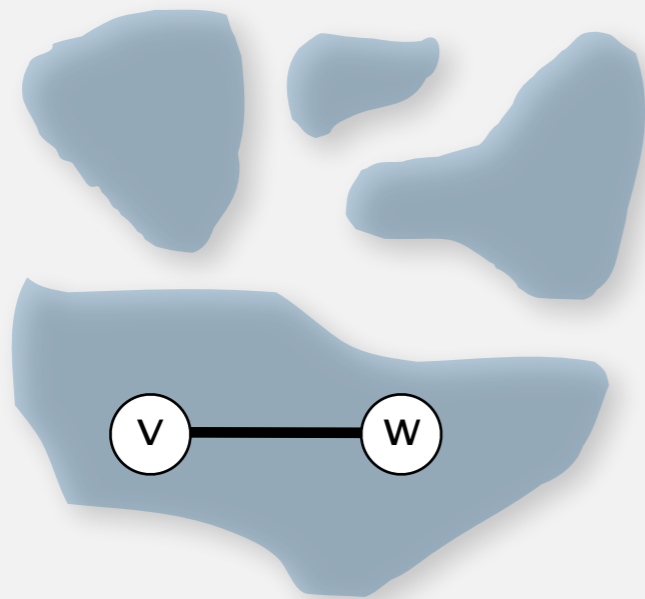


Kruskal's algorithm: implementation challenge

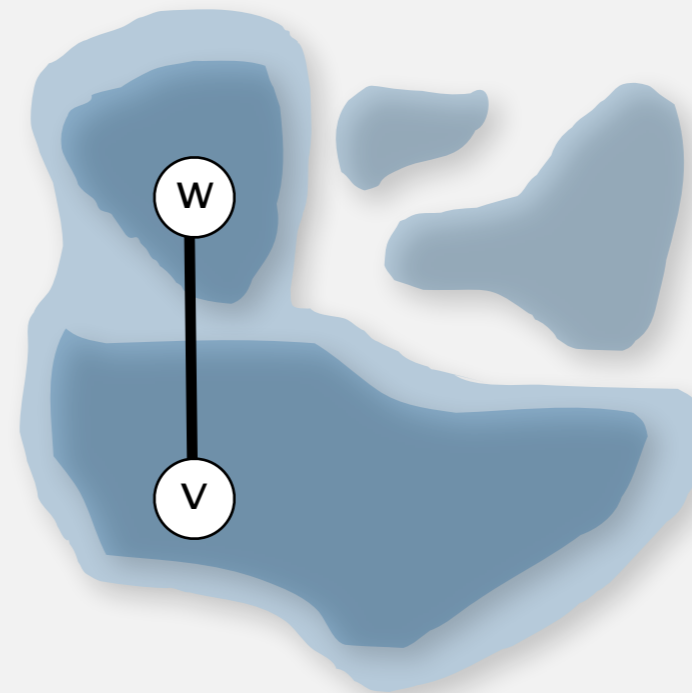
Challenge. Would adding edge $v-w$ to tree T create a cycle? If not, add it.

Efficient solution. Use the **union-find** data structure.

- Maintain a set for each connected component in T .
- If v and w are in same set, then adding $v-w$ would create a cycle.
- To add $v-w$ to T , merge sets containing v and w .



Case 2: adding $v-w$ creates a cycle



Case 1: add $v-w$ to T and merge sets containing v and w

Kruskal's algorithm: Java implementation

```
public class KruskalMST
{
    private Queue<Edge> mst = new Queue<Edge>();

    public KruskalMST(EdgeWeightedGraph G)
    {
        DirectedEdge[] edges = G.edges();
        Arrays.sort(edges);
        UF uf = new UF(G.V());

        for (int i = 0; i < G.E(); i++)
        {
            Edge e = edges[i];
            int v = e.either(), w = e.other(v);
            if (uf.find(v) != uf.find(w))
            {
                mst.enqueue(e);
                uf.union(v, w);
            }
        }

        public Iterable<Edge> edges()
        { return mst; }
    }
}
```

← edges in the MST

← sort edges by weight

← maintain connected components

← optimization: stop as soon as $V-1$ edges in T

← greedily add edges to MST

← edge $v-w$ does not create cycle

← add edge e to MST

← merge connected components

Kruskal's algorithm: running time

Proposition. In the worst case, Kruskal's algorithm computes MST in time proportional to $E \log E$.

Pf.

- Bottlenecks are sort and union–find operations.

operation	frequency	time per op
SORT	1	$E \log E$
UNION	$V - 1$	$\log V^\dagger$
FIND	$2 E$	$\log V^\dagger$

† using weighted quick union

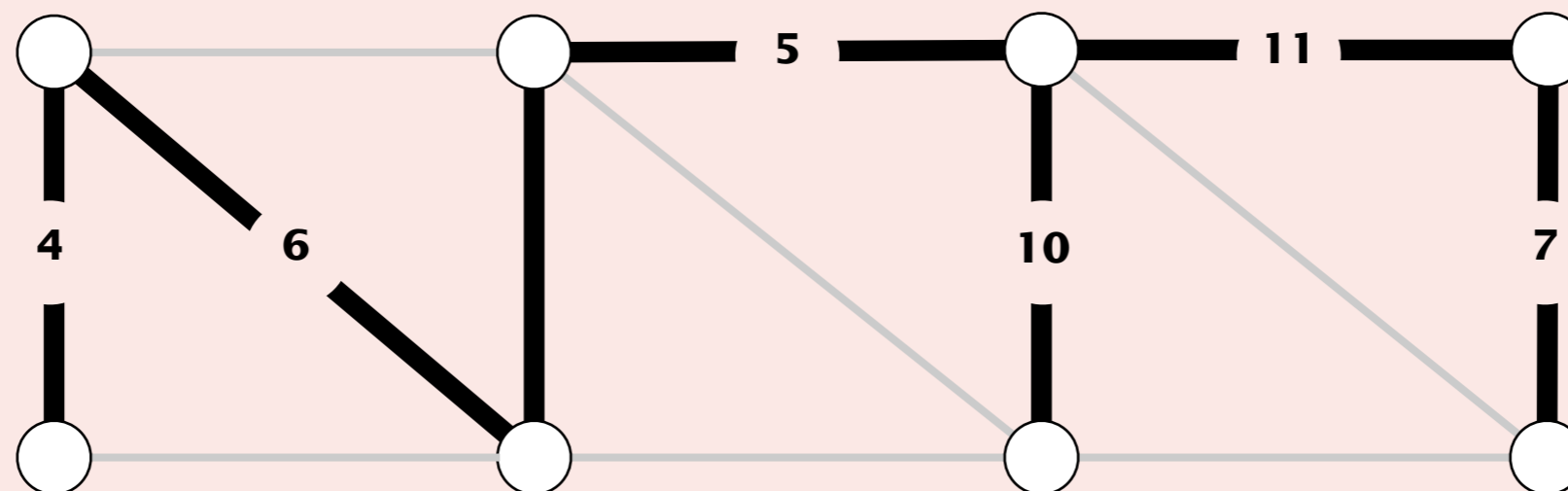
- Total. $V \log V + E \log V + E \log E$.


dominated by $E \log E$
since graph is connected



Given a graph with positive edge weights, how to find a spanning tree that minimizes the sum of the squares of the edge weights?

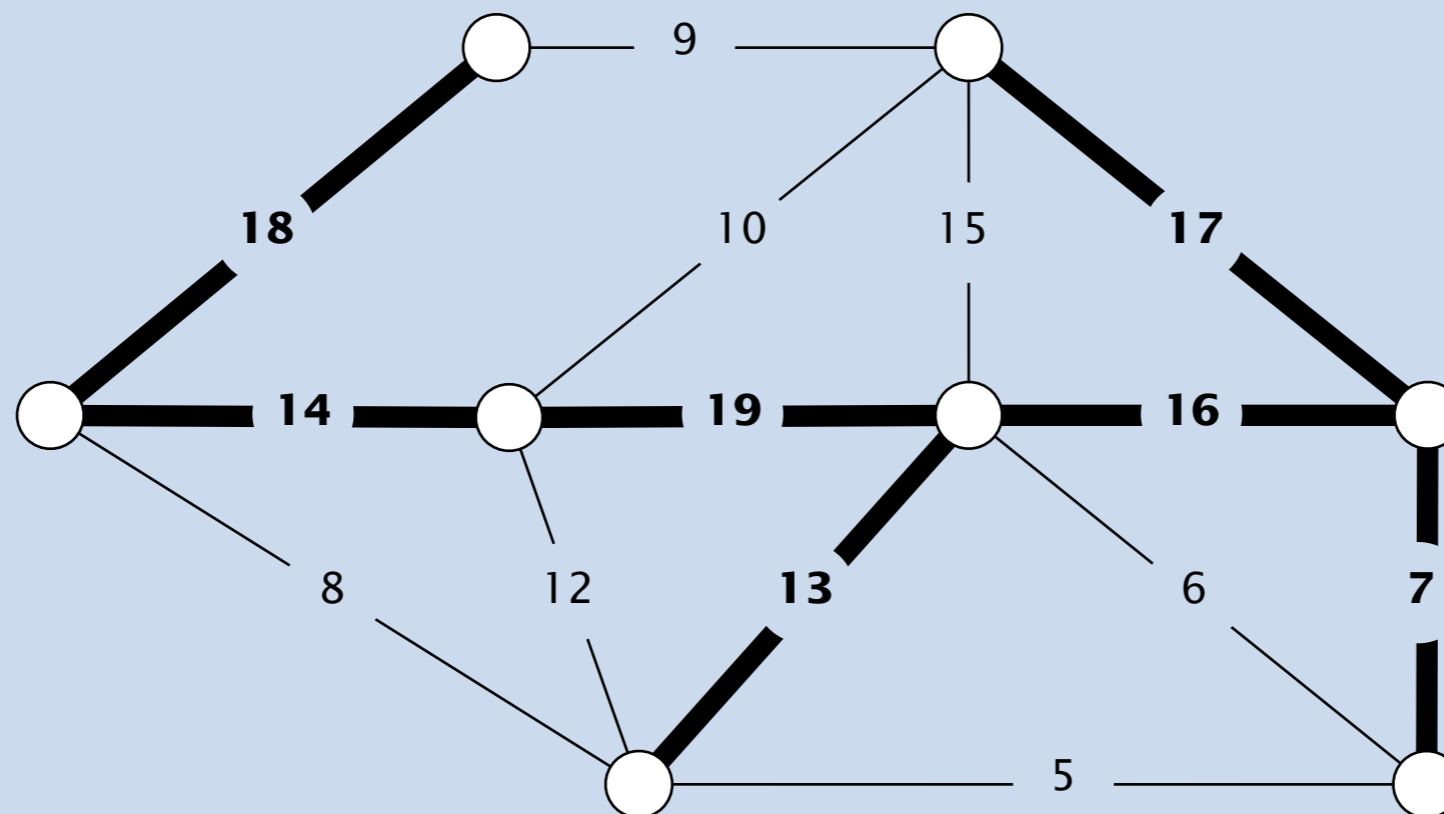
- A. Run Kruskal's algorithm using the **original** edge weights.
- B. Run Kruskal's algorithm using the **squares** of the edge weights.
- C. Run Kruskal's algorithm using the **square roots** of the edge weights.
- D. All of the above.



$$\text{sum of squares} = 4^2 + 6^2 + 5^2 + 10^2 + 11^2 + 7^2 = 347$$



Goal. Design algorithm with $E \log E$ running time.



37

Greed is good



**Gordon Gecko (Michael Douglas) evangelizing the importance of greed (in algorithm design?)
Wall Street (1986)**



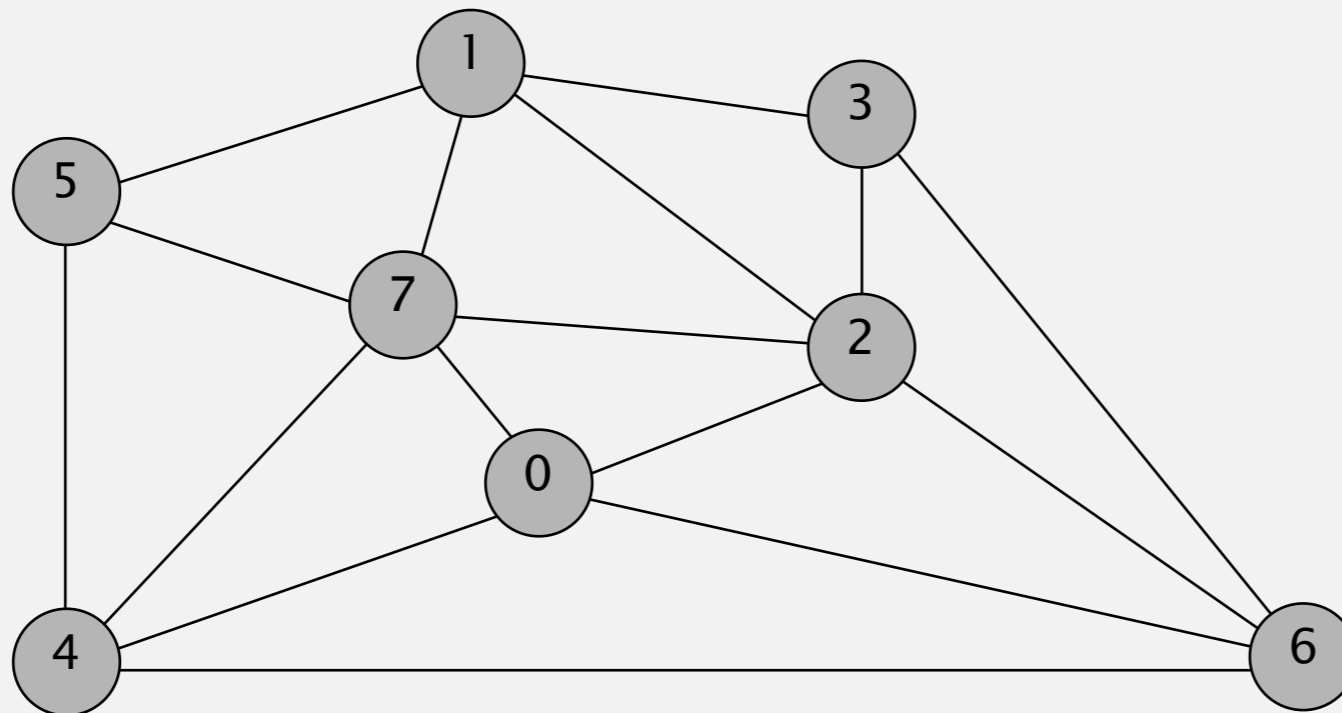
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Prim's algorithm demo

- Start with vertex 0 and grow tree T .
- Repeat until $V - 1$ edges:
 - add to T the min-weight edge with exactly one endpoint in T



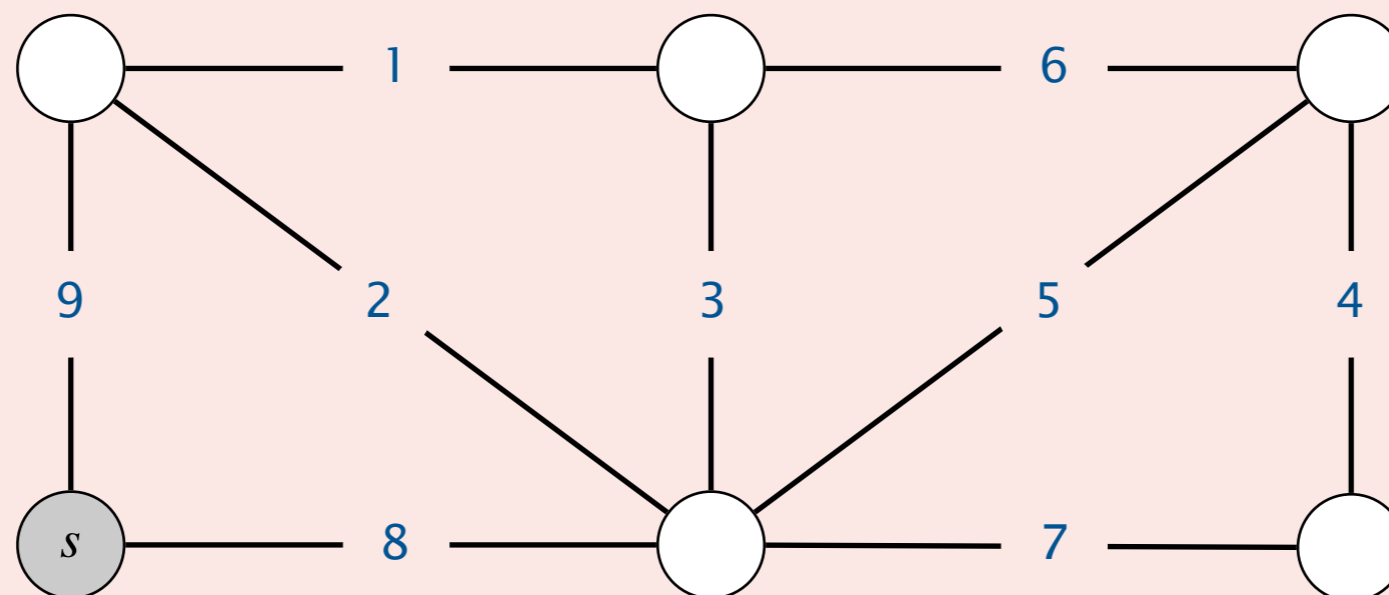
an edge-weighted graph

0-7	0.16
2-3	0.17
1-7	0.19
0-2	0.26
5-7	0.28
1-3	0.29
1-5	0.32
2-7	0.34
4-5	0.35
1-2	0.36
4-7	0.37
0-4	0.38
6-2	0.40
3-6	0.52
6-0	0.58
6-4	0.93

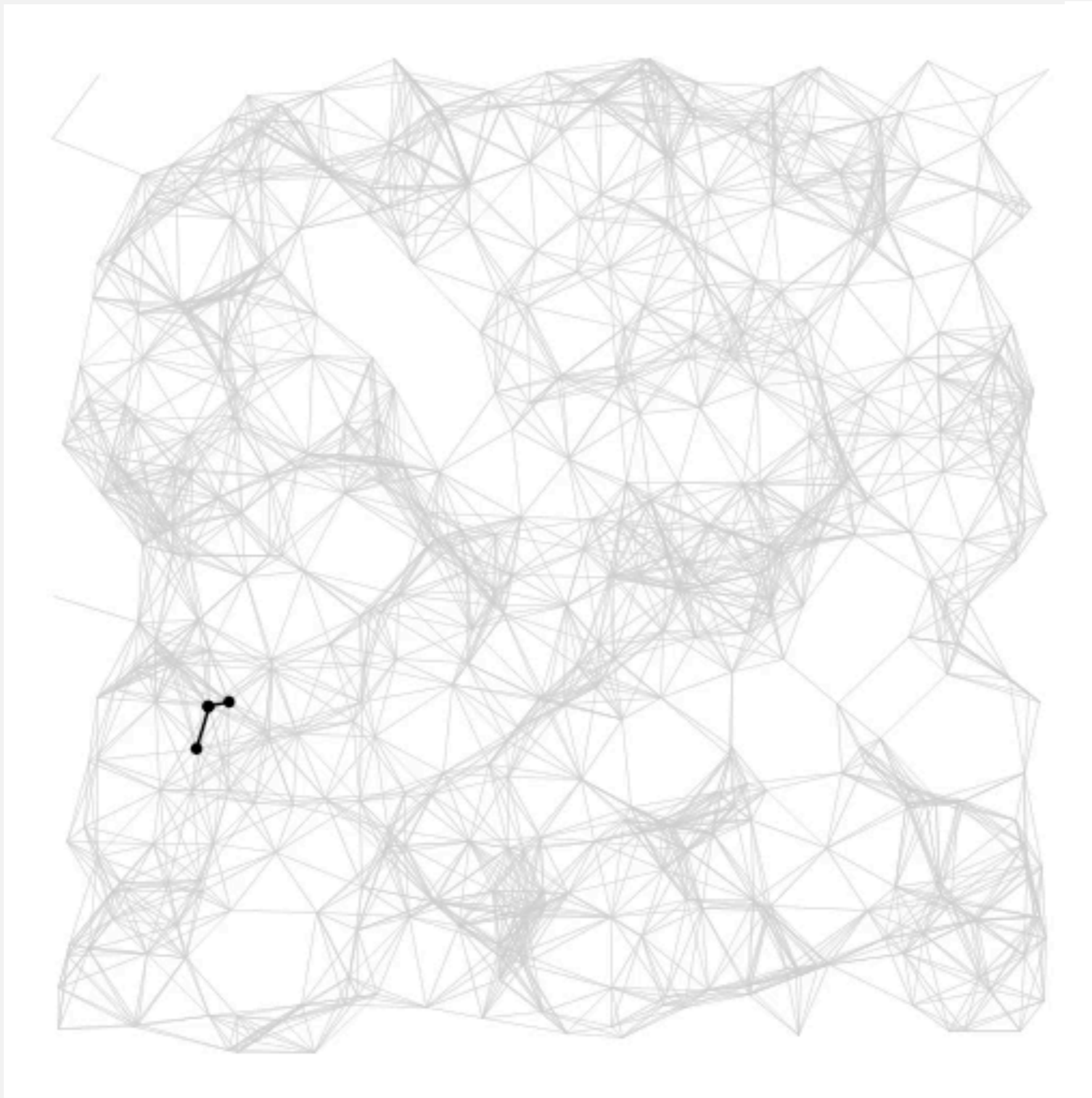


In which order does Prim's algorithm select edges in the MST?
Assume it starts from vertex s .

- A. 1, 2, 3, 4, 5
- B. 1, 2, 5, 4, 8
- C. 8, 2, 1, 5, 4
- D. 8, 5, 4, 2, 1



Prim's algorithm: visualization



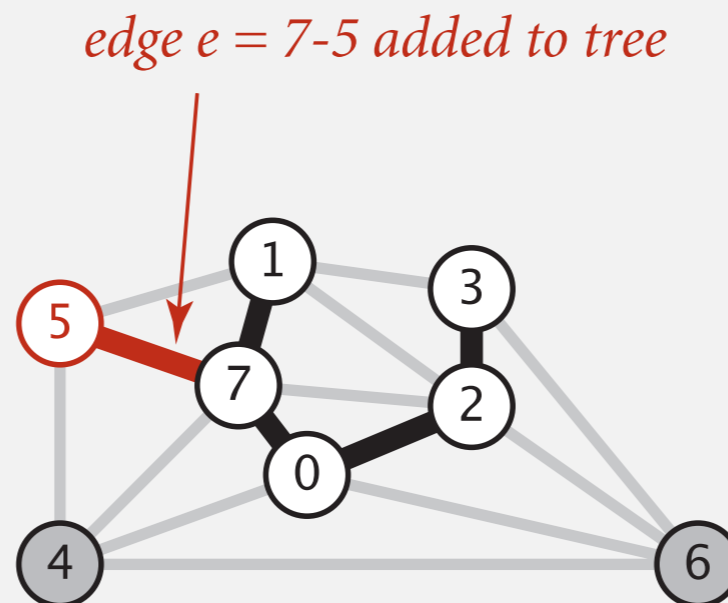
Prim's algorithm: proof of correctness

Proposition. [Jarník 1930, Dijkstra 1957, Prim 1959]

Prim's algorithm computes the MST.

Pf. Let e = min-weight edge with exactly one endpoint in T .

- Cut = set of vertices in T .
- No crossing edge is in T .
- No crossing edge has lower weight.
- Cut property \Rightarrow edge e is in the MST. ■

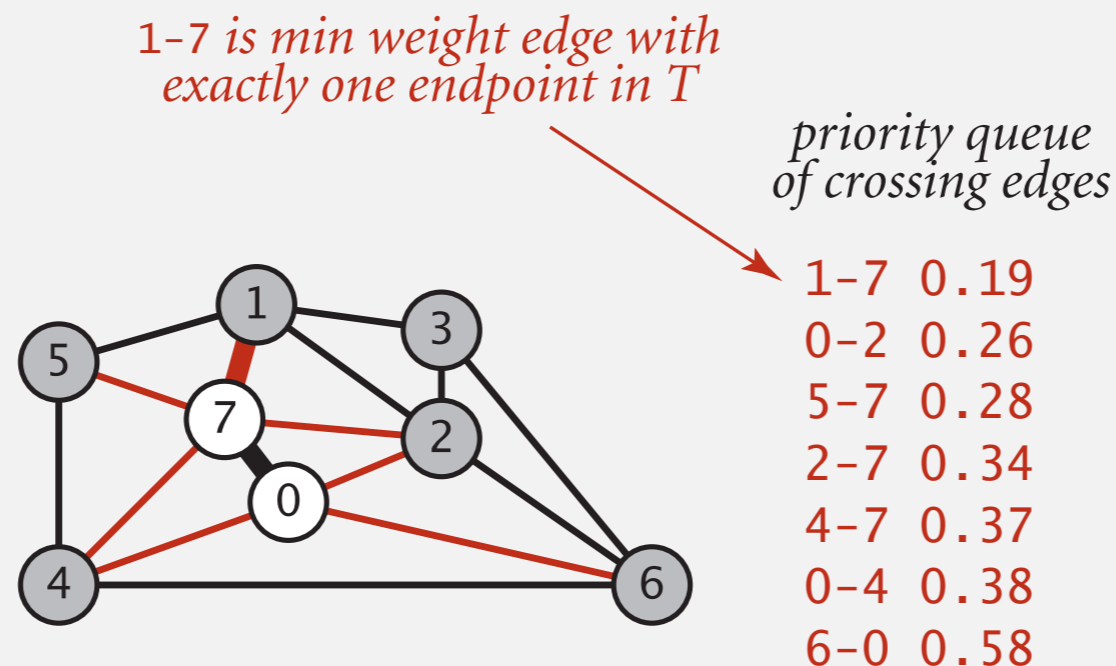


Prim's algorithm: lazy implementation

Challenge. Find the min-weight edge with exactly one endpoint in T .

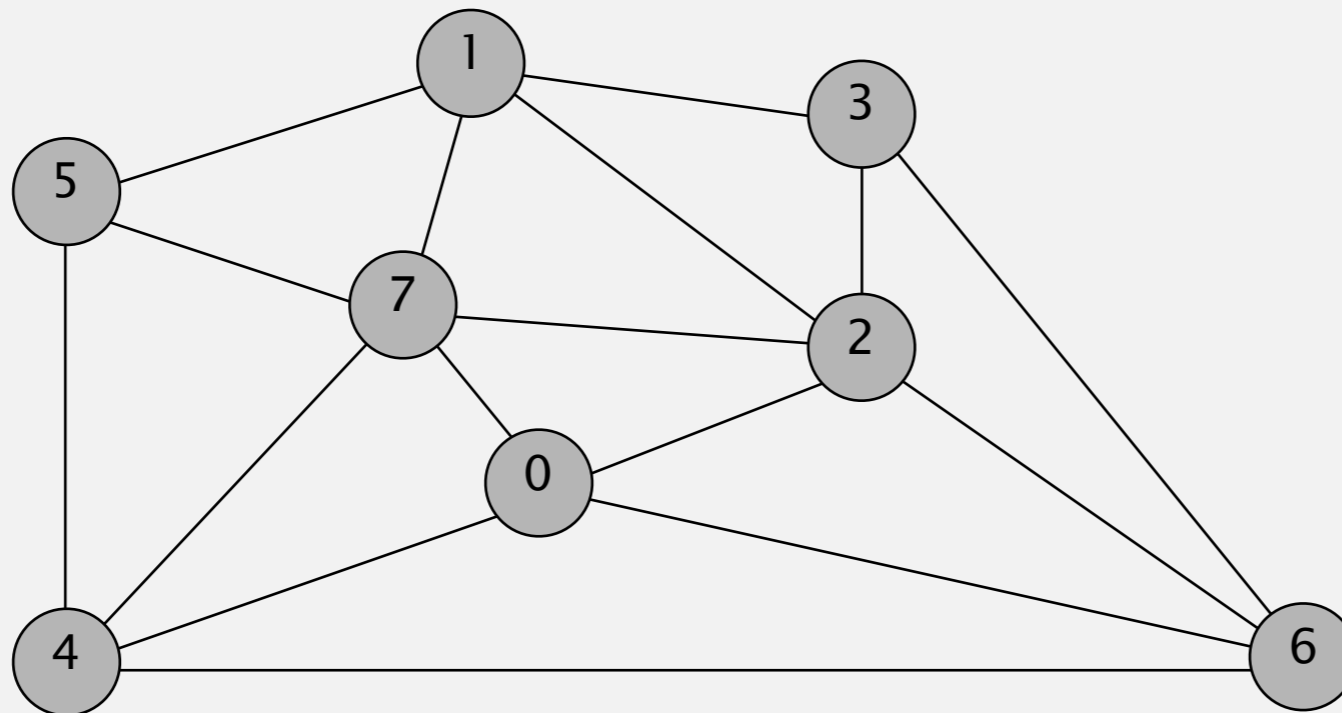
Lazy solution. Maintain a PQ of **edges** with (at least) one endpoint in T .

- Key = edge; priority = weight of edge.
- DELETE-MIN to determine next edge $e = v-w$ to add to T .
- If both endpoints v and w are marked (both in T), disregard.
- Otherwise, let w be the unmarked vertex (not in T):
 - add e to T and mark w
 - add to PQ any edge incident to w (assuming other endpoint not in T)



Prim's algorithm: lazy implementation demo

- Start with vertex 0 and grow tree T .
- Repeat until $V - 1$ edges:
 - add to T the min-weight edge with exactly one endpoint in T



an edge-weighted graph

0-7	0.16
2-3	0.17
1-7	0.19
0-2	0.26
5-7	0.28
1-3	0.29
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4-7	0.37
0-4	0.38
6-2	0.40
3-6	0.52
6-0	0.58
6-4	0.93

Prim's algorithm: lazy implementation

```
public class LazyPrimMST
{
    private boolean[] marked;    // MST vertices
    private Queue<Edge> mst;     // MST edges
    private MinPQ<Edge> pq;     // PQ of edges
```

```
    public LazyPrimMST(WeightedGraph G)
    {
```

```
        pq = new MinPQ<Edge>();
        mst = new Queue<Edge>();
        marked = new boolean[G.V()];
        visit(G, 0);
```

← assume graph G is connected

```
        while (!pq.isEmpty() && mst.size() < G.V() - 1)
        {
```

```
            Edge e = pq.delMin();
            int v = e.either(), w = e.other(v);
            if (marked[v] && marked[w]) continue;
            mst.enqueue(e);
            if (!marked[v]) visit(G, v);
            if (!marked[w]) visit(G, w);
        }
```

← repeatedly delete the min-weight edge $e = v-w$ from PQ

← ignore if both endpoints in tree T

← add edge e to tree T

← add either v or w to tree T

```
    }
}
```

Prim's algorithm: lazy implementation

```
private void visit(WeightedGraph G, int v)
{
    marked[v] = true;
    for (Edge e : G.adj(v))
        if (!marked[e.other(v)])
            pq.insert(e);
}
```

```
public Iterable<Edge> mst()
{ return mst; }
```

← add vertex v to tree T

← for each edge $e = v-w$:
add e to PQ if w not already in T

Lazy Prim's algorithm: running time

Proposition. In the worst case, lazy Prim's algorithm computes the MST in time proportional to $E \log E$ and extra space proportional to E .

can be improved to V with "eager" version

Pf.

- Bottlenecks are PQ operations.
- Each edge is added to PQ at most once.
- Each edge is deleted from PQ at most once.

operation	frequency	binary heap
INSERT	E	$\log E$
DELETE-MIN	E	$\log E$

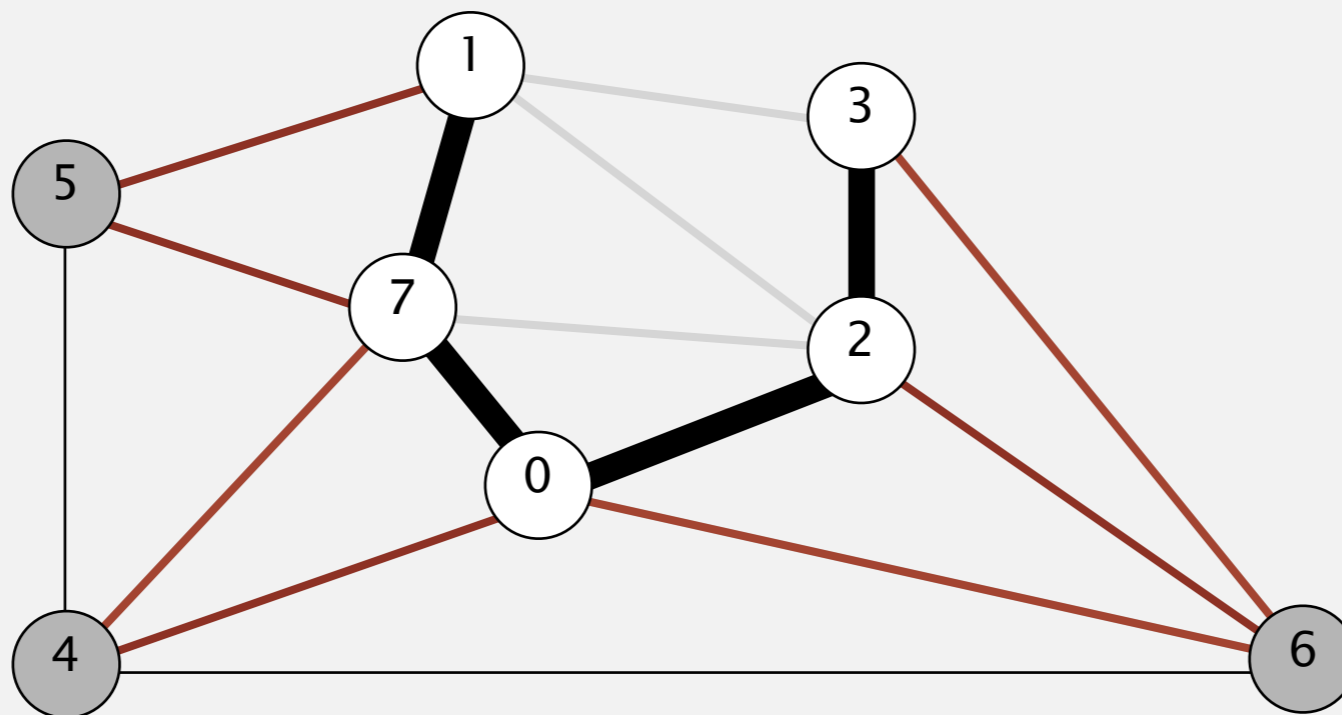
Prim's algorithm: eager implementation

Challenge. Find min-weight edge with exactly one endpoint in T .

Observation. For each vertex v , need only **min-weight** edge connecting v to T .

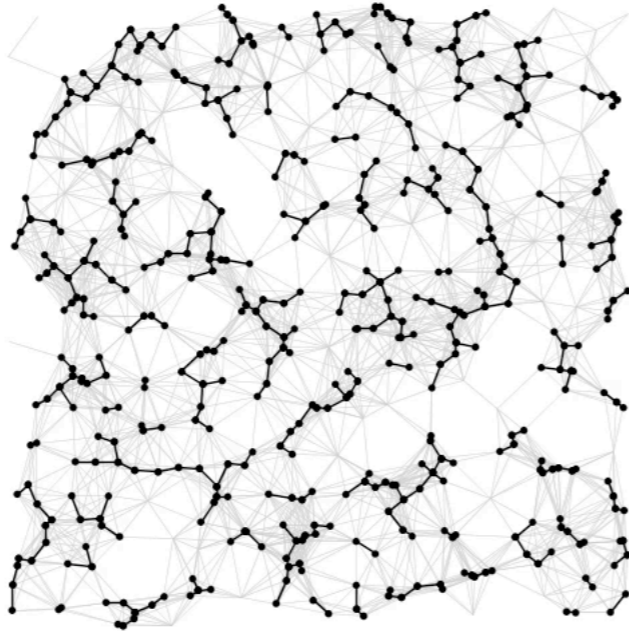
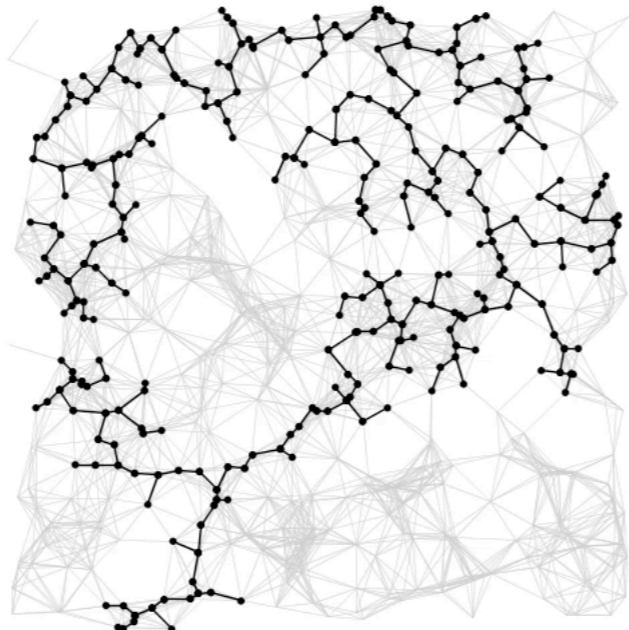
- MST includes at most one edge connecting v to T . Why?
- If MST includes such an edge, it must take lightest such edge. Why?

Impact. PQ of vertices; extra space at most V ; running time $E \log V$.



see textbook
for details

MST: algorithms of the day

algorithm	visualization	bottleneck	running time
Kruskal		sorting union-find	$E \log E$
Prim		priority queue	$E \log V$