



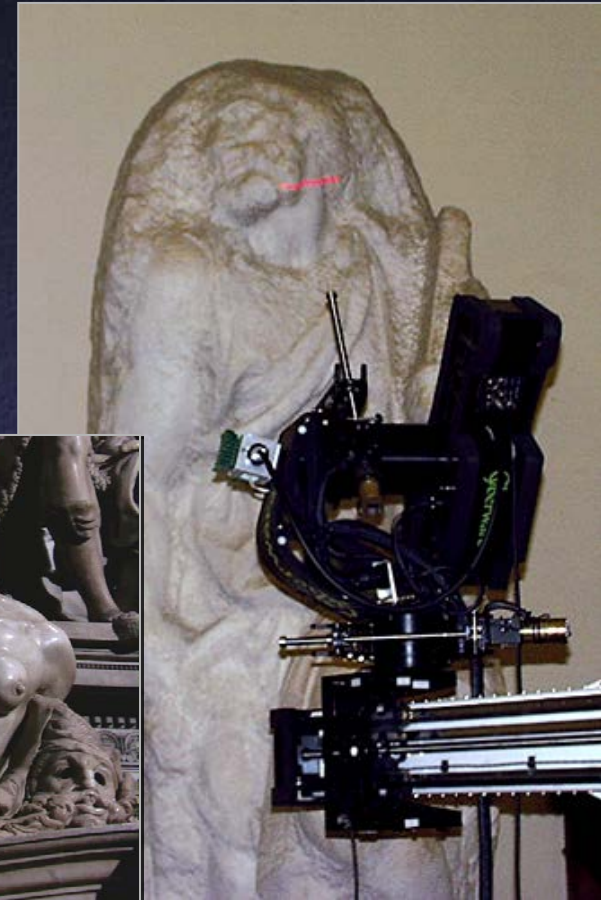
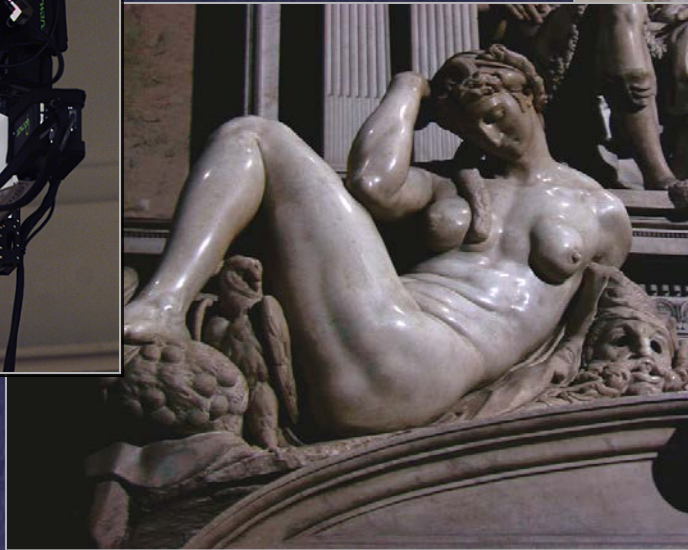
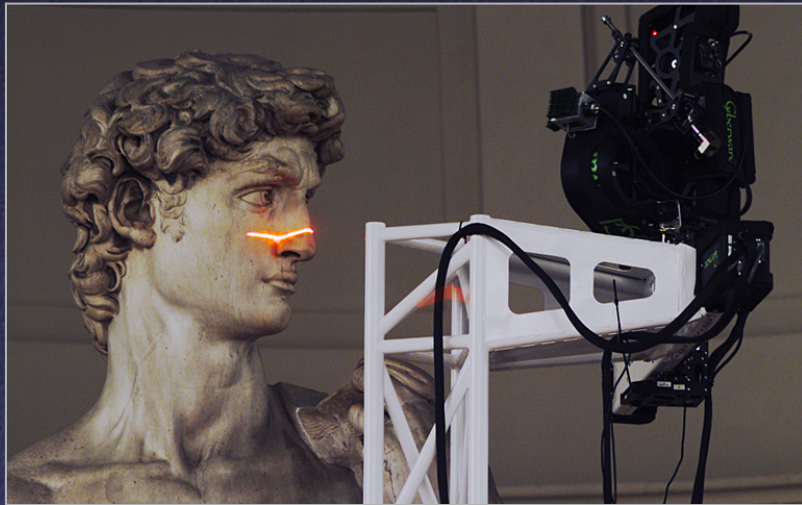
Point-Based Rendering of Large 3D Models

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Motivation

- 3D scanning makes it possible to capture large, detailed models of real-world objects



Motivation

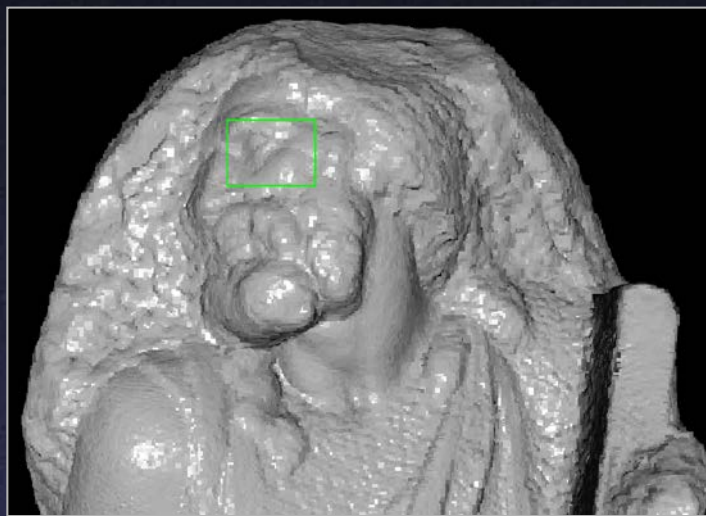
- Models may be dense
 - Hundreds of millions of samples
 - Can't decimate without losing detail



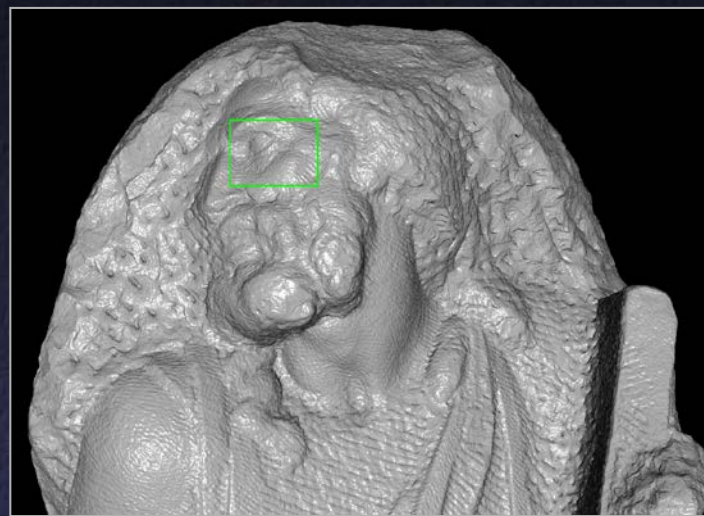
Goals

- An interactive viewer for large models ($10^8 - 10^9$ samples)
- Fast startup and progressive loading
- Maintains interactive frame rate
- Compact data structure
- Fast preprocessing

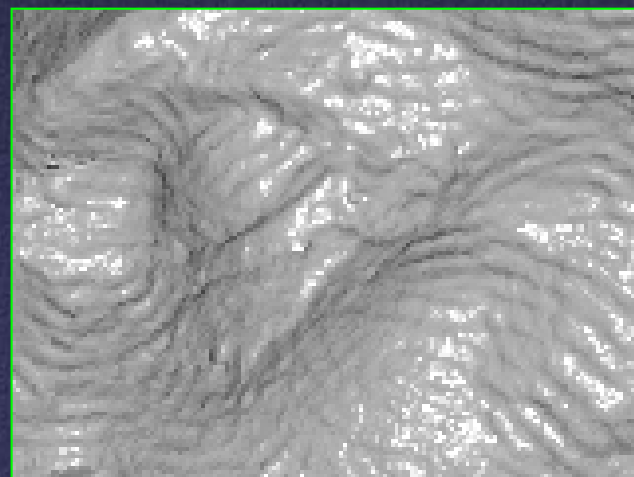
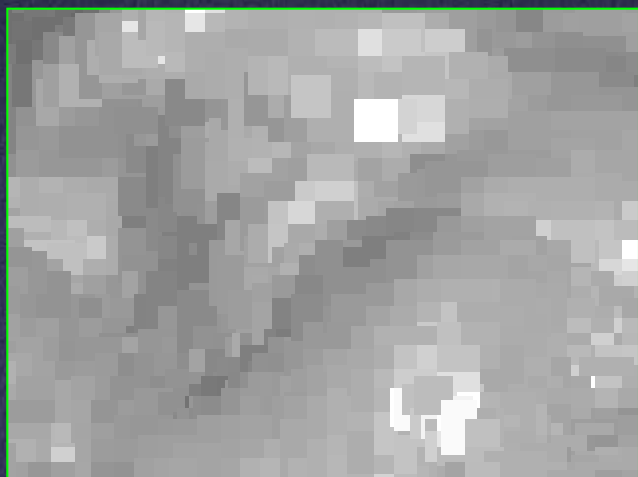
Sample Renderings of a 127-million-sample Model



Interactive (8 frames/sec)



High quality (8 sec)



Previous Systems for Rendering Large Models

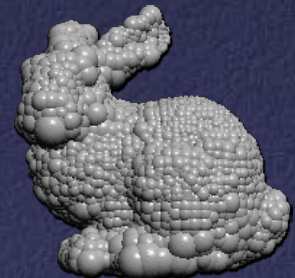
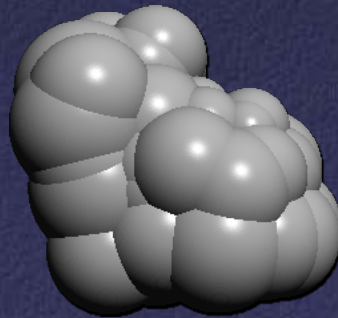
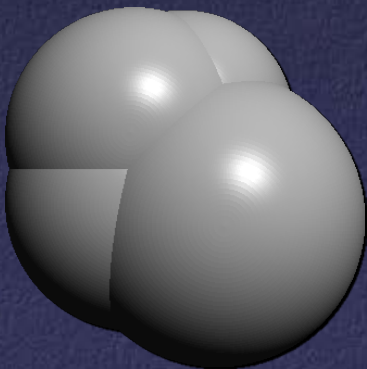
- Level of detail control in architectural walkthrough, terrain rendering systems [Funkhouser 93, Duchaineau 97]
- Progressive meshes [Hoppe 96, Hoppe 97]
- These systems often have expensive data structures or high preprocessing costs

Outline

- Data structure: bounding sphere hierarchy
- Rendering algorithm: traverse tree and splat
- Point rendering: when is it appropriate?

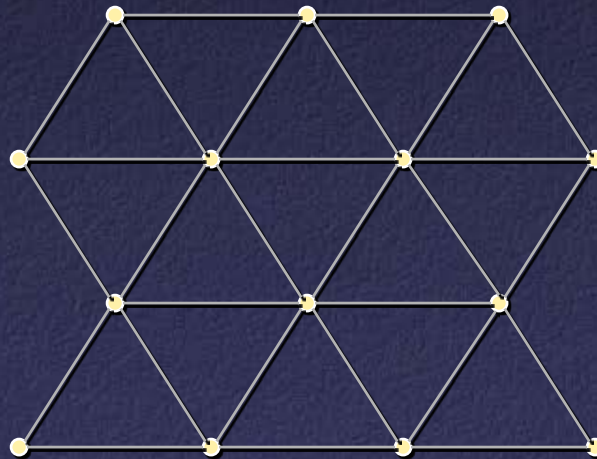
QSplat Data Structure

- Key observation: a single bounding sphere hierarchy can be used for
 - Hierarchical frustum and backface culling
 - Level of detail control
 - Splat rendering [Westover 89]



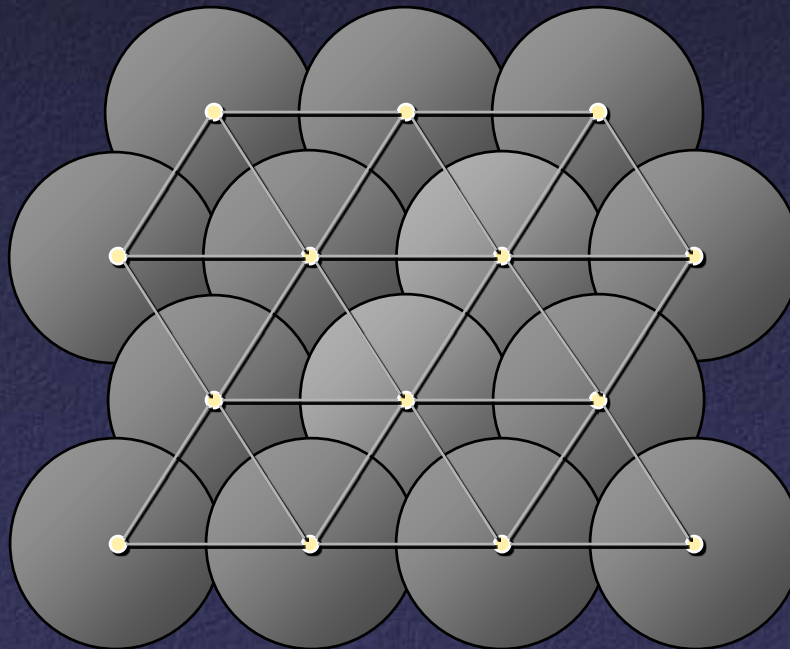
Creating the Data Structure

- Start with a triangle mesh produced by aligning and integrating scans [Curless 96]



Creating the Data Structure

- Place a sphere at each node, large enough to touch neighbor spheres

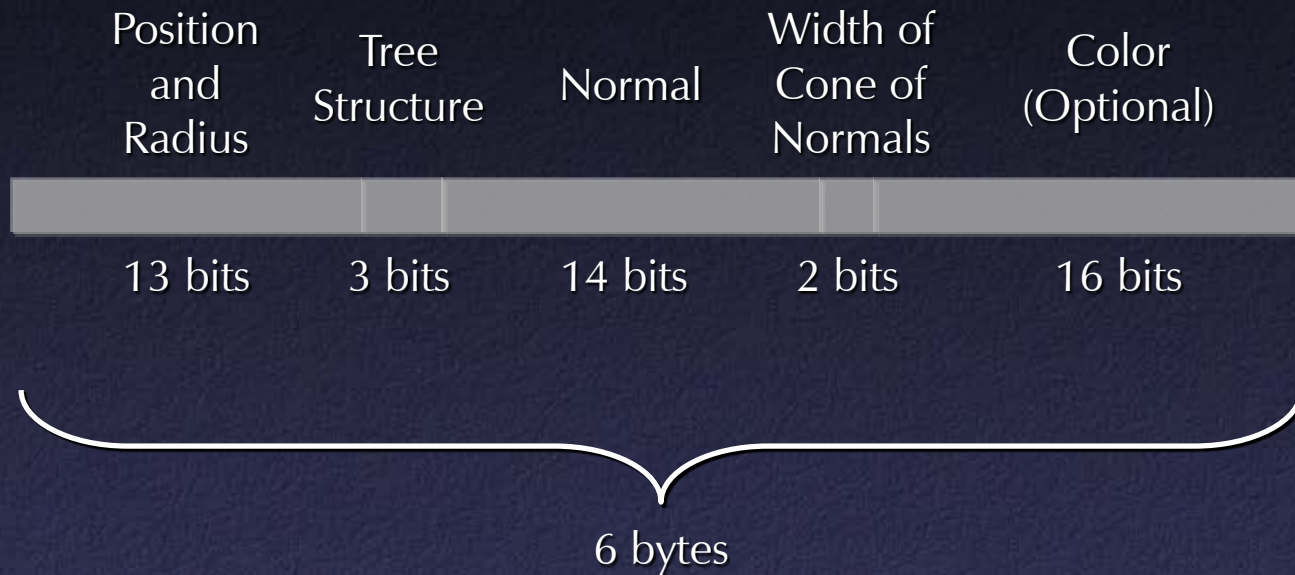


Creating the Data Structure

- Build up hierarchy



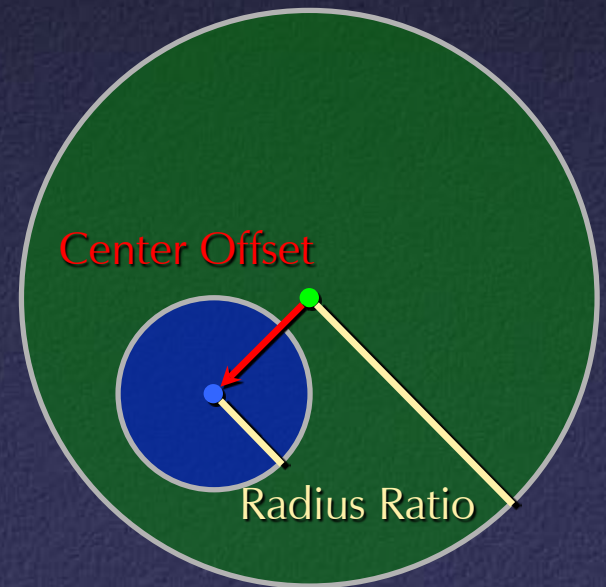
QSplat Node Structure



QSplat Node Structure



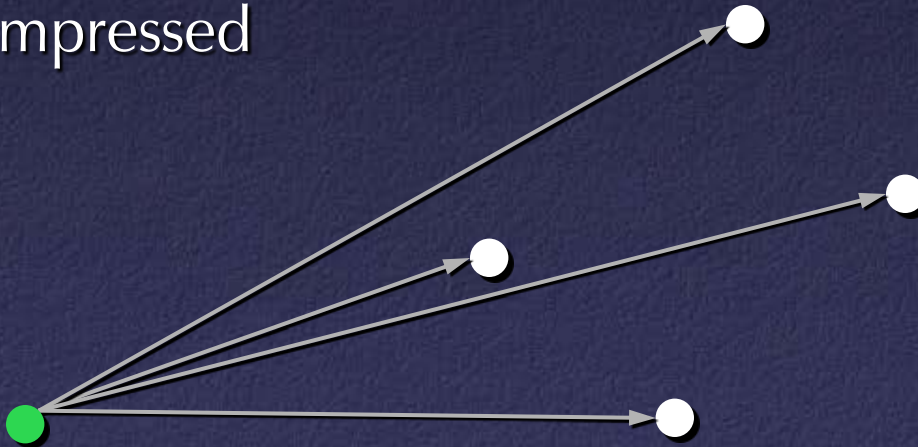
- Position and radius encoded relative to parent node
 - Hierarchical coding vs. delta coding along a path for vertex positions



QSplat Node Structure



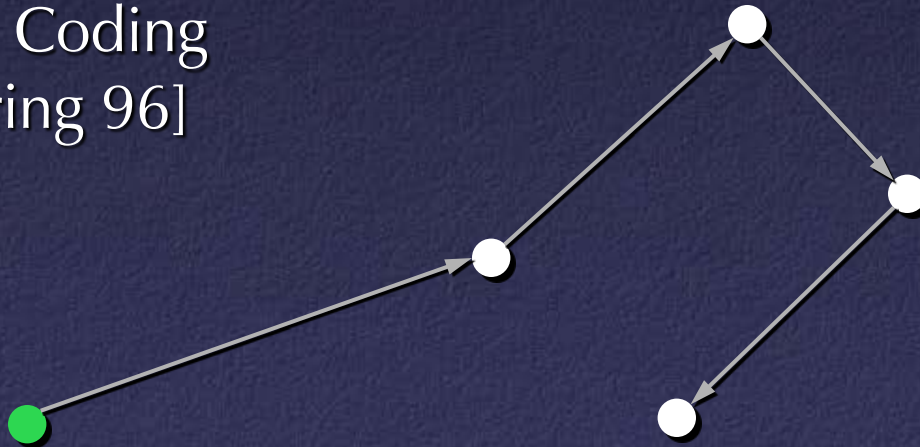
Uncompressed



QSplat Node Structure



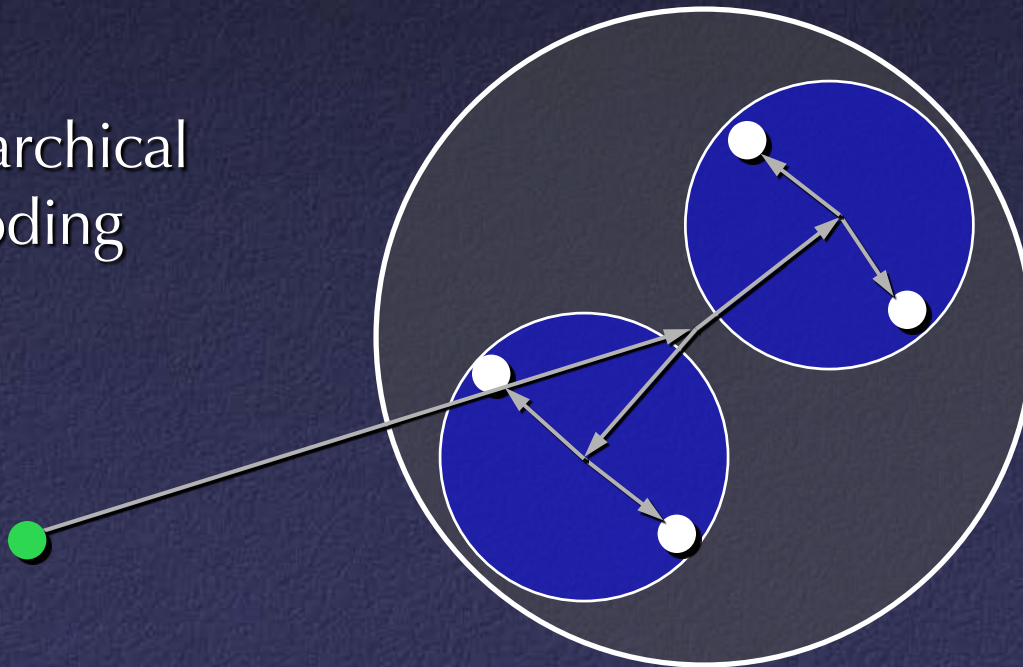
Delta Coding
[Deering 96]



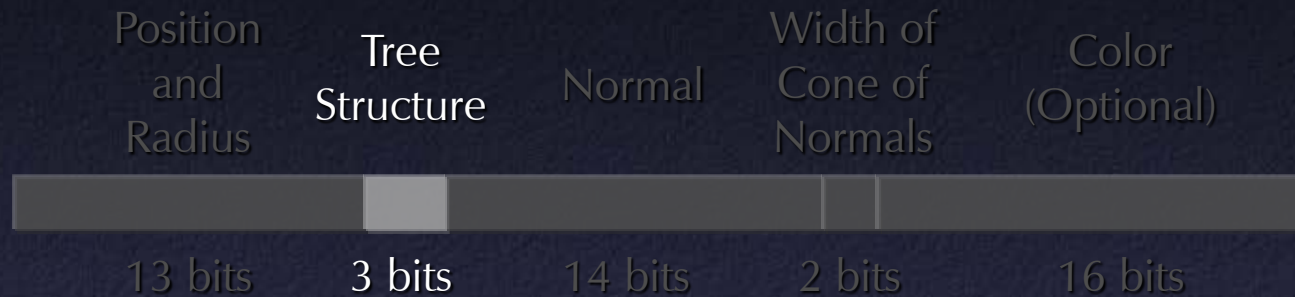
QSplat Node Structure



Hierarchical
Coding

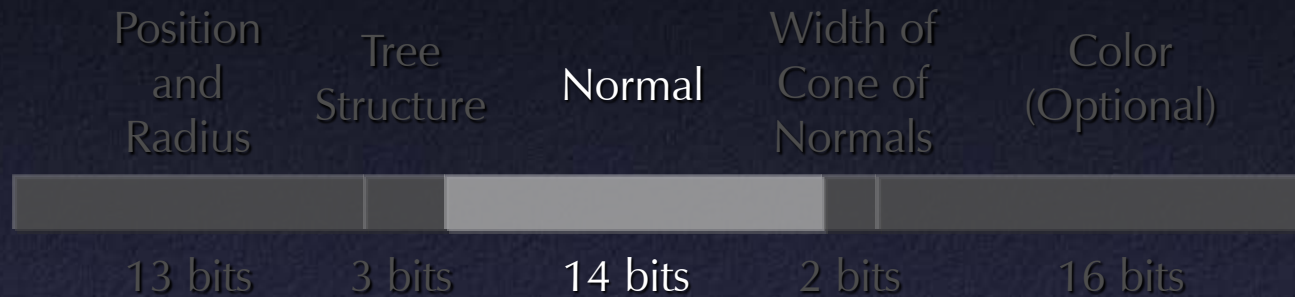


QSplat Node Structure

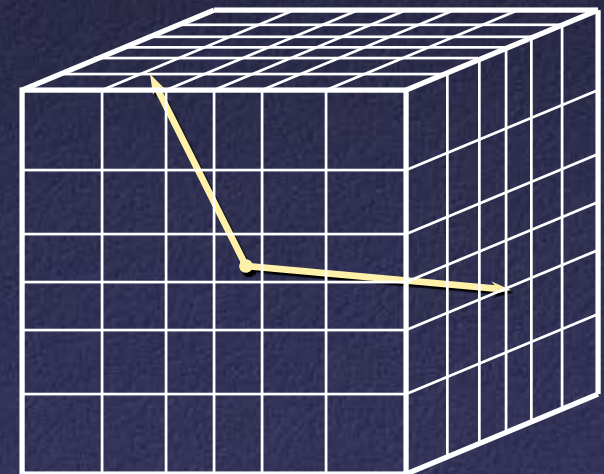


- Number of children (0, 2, 3, or 4) – 2 bits
- Presence of grandchildren – 1 bit

QSplat Node Structure

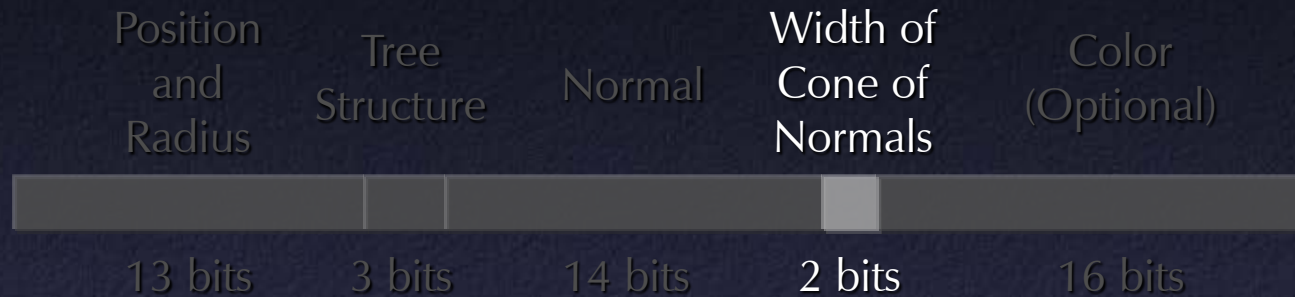


- Normal quantized to grid on faces of a cube



52×52×6

QSplat Node Structure



- Each node contains bounding cone of children's normals
- Hierarchical backface culling [Kumar 96]

QSplat Node Structure



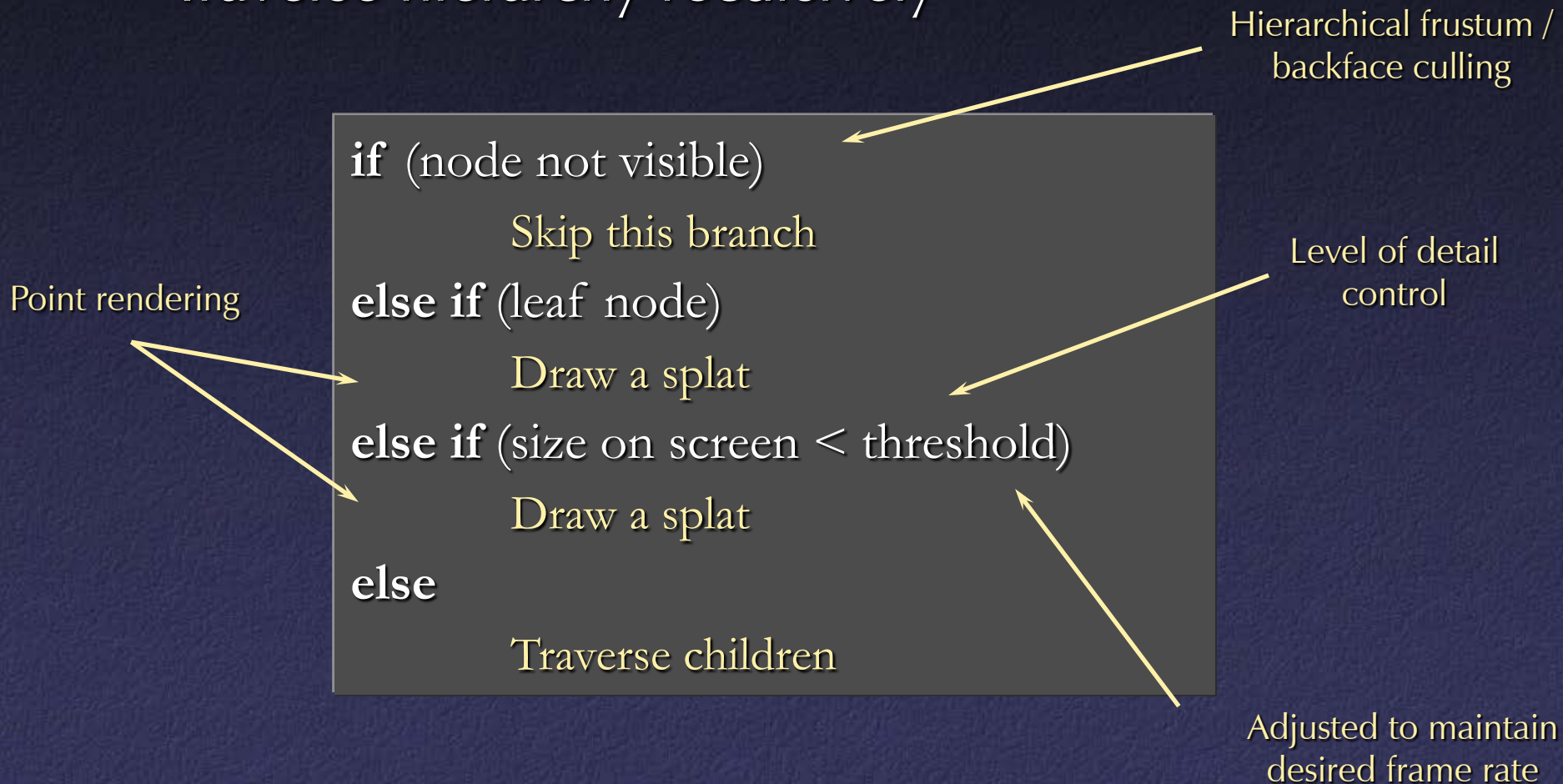
QSplat Node Structure



- Per-vertex color is quantized 5-6-5 (R-G-B)

QSplat Rendering Algorithm

- Traverse hierarchy recursively



Frame Rate Control

- Feedback-driven frame rate control
 - **During motion:** adjust recursion threshold based on time to render previous frame
 - **On mouse up:** redraw with smaller thresholds
 - **Consequence:** frame rate may vary
- Alternative:
 - Predictive control of detail [Funkhouser 93]

Loading Model from Disk

- Tree layout:
 - Breadth-first order in memory and on disk
- Working set management:
 - Memory mapping disk file
 - Consequence: lower detail for new geometry
 - Alternative: Active working set management with prefetching [Funkhouser 96, Aliaga 99]

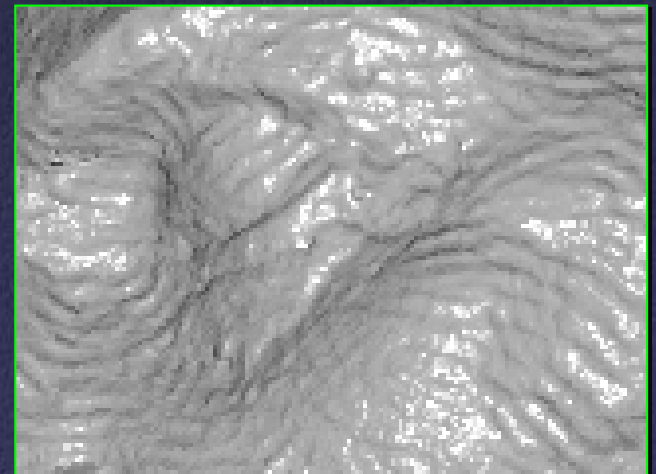
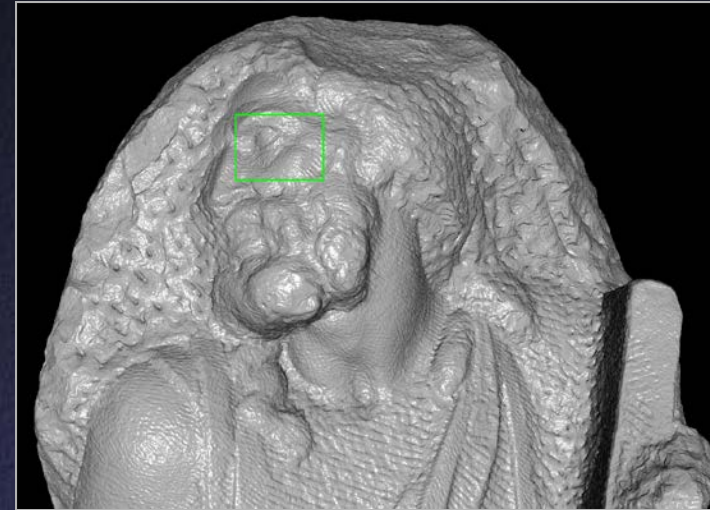
Tradeoffs of Splatting

- For rendering large 3D models, what are the tradeoffs of:

Polygons	QSplat
Good for large, flat or subtly curved regions	Good for models with detail everywhere
Highly-efficient rasterization with 3D graphics hardware	Higher per-pixel cost, but less slowdown in absence of 3D hardware
Decimation or creating LOD data structures is often expensive	Fast preprocessing

Demo – St. Matthew

- 3D scan of 2.7 meter statue at 0.25 mm
- 102,868,637 points
- File size: 644 MB
- Preprocessing time: 1 hour



Conclusion

- Non-polygonal rendering
 - Works well when $\# \text{ samples} \gg \# \text{ pixels}$
 - Lack of connectivity may = simpler algorithms
 - Bad for flat regions
- Time, space efficiency important for big data sets