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## 4.3 MINIMUM SPANNING TREES

---

- ▶ *introduction*
- ▶ *cut property*
- ▶ *edge-weighted graph API*
- ▶ *Kruskal's algorithm*
- ▶ *Prim's algorithm*



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## 4.3 MINIMUM SPANNING TREES

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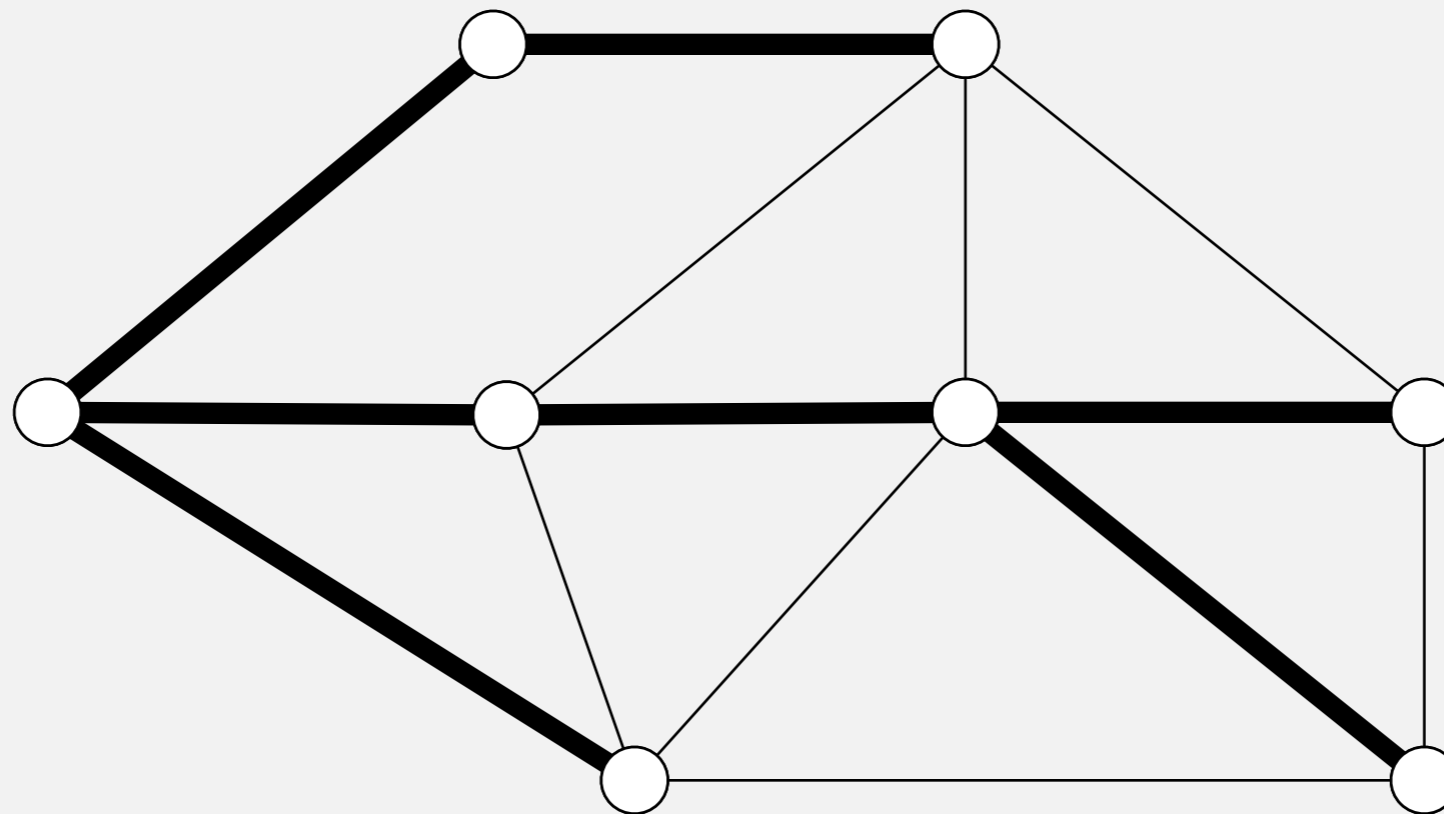
- ▶ *introduction*
- ▶ *cut property*
- ▶ *edge-weighted graph API*
- ▶ *Kruskal's algorithm*
- ▶ *Prim's algorithm*

# Spanning tree

---

**Def.** A **spanning tree** of  $G$  is a subgraph  $T$  that is:

- A tree: connected and acyclic.
- Spanning: includes all of the vertices.



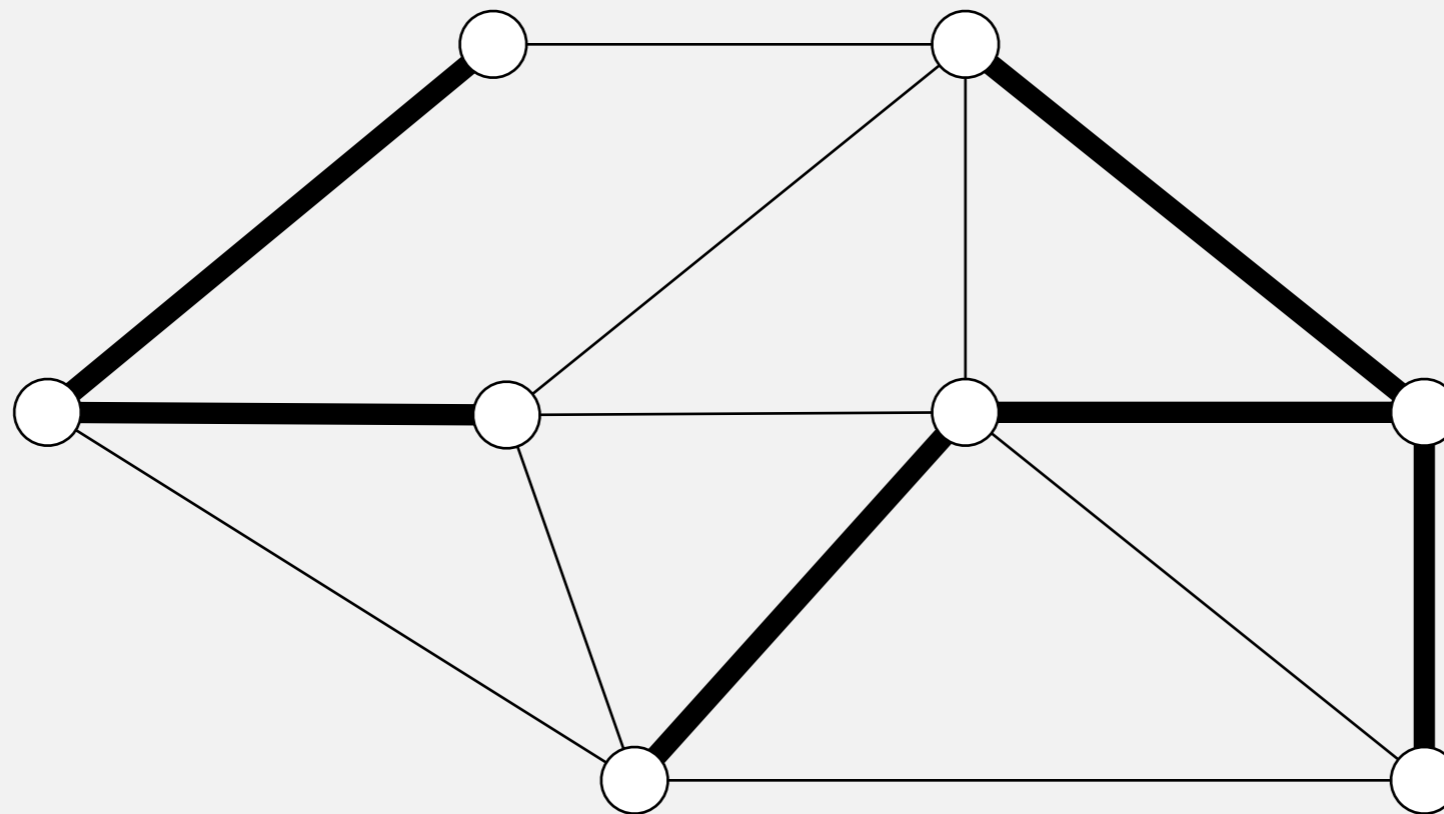
graph  $G$   
spanning tree  $T$

# Spanning tree

---

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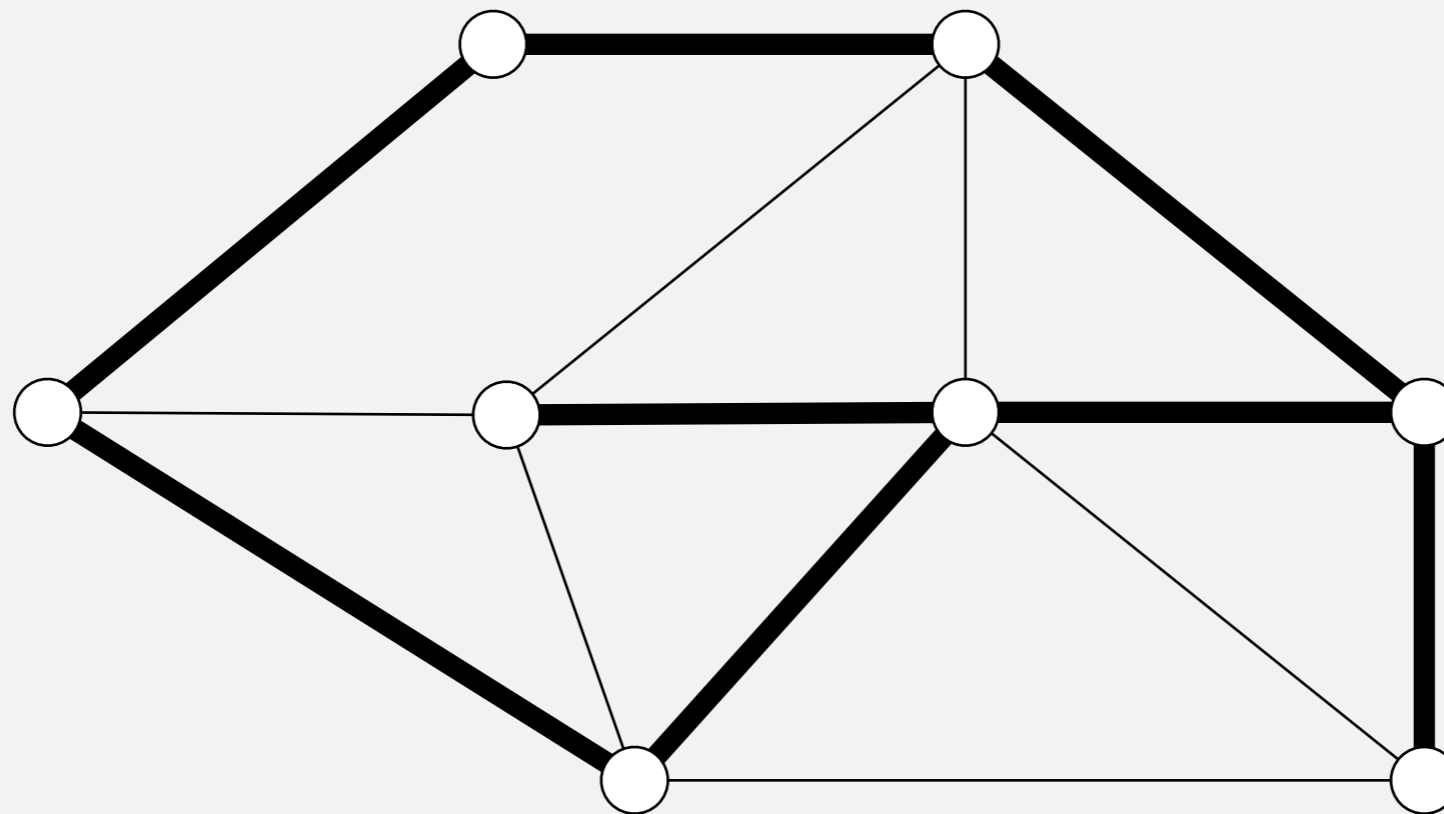
not connected

# Spanning tree

---

**Def.** A **spanning tree** of  $G$  is a subgraph  $T$  that is:

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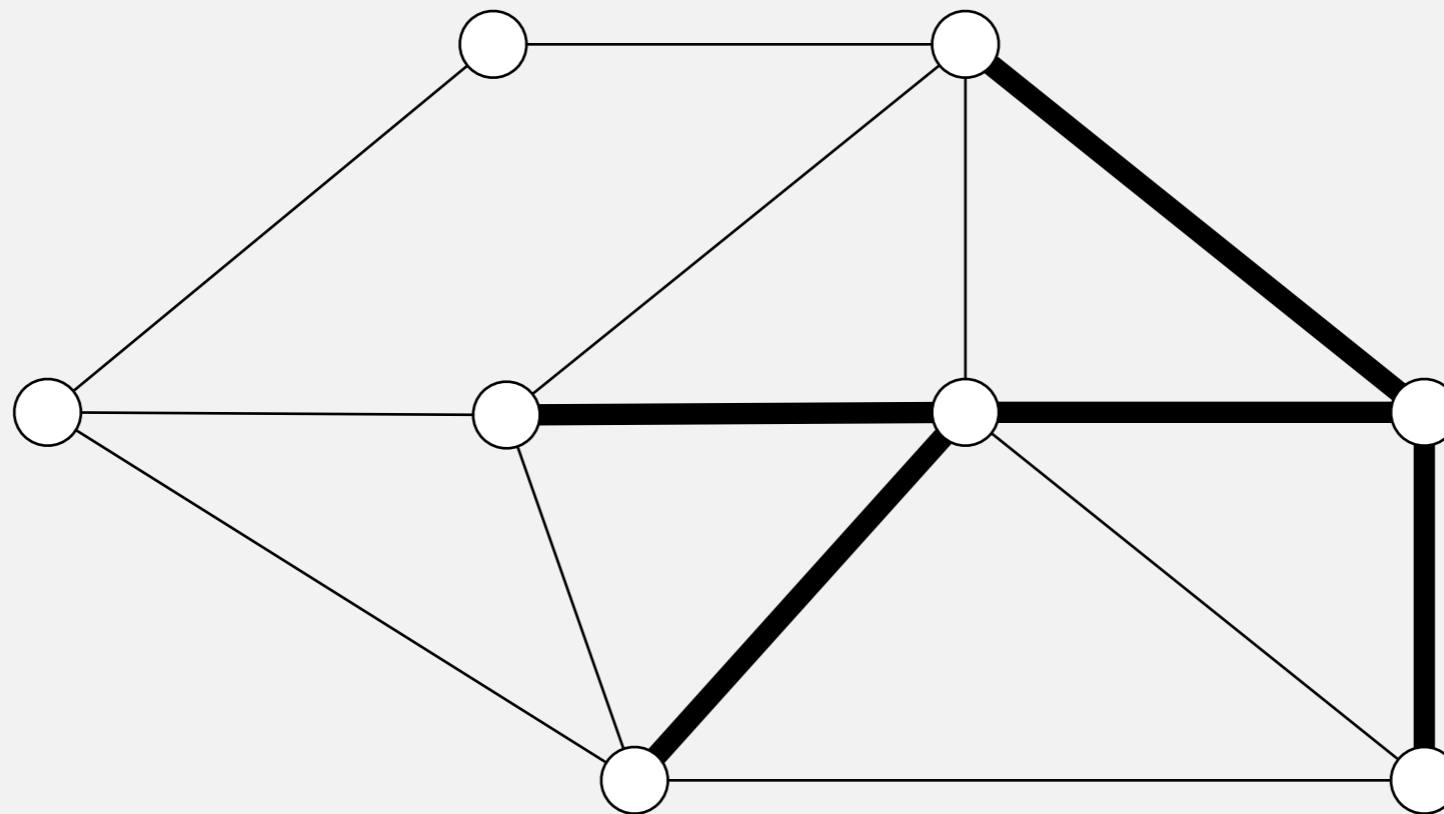
not a tree (cyclic)

# Spanning tree

---

**Def.** A **spanning tree** of  $G$  is a subgraph  $T$  that is:

- A tree: connected and acyclic.
- Spanning: includes all of the vertices.

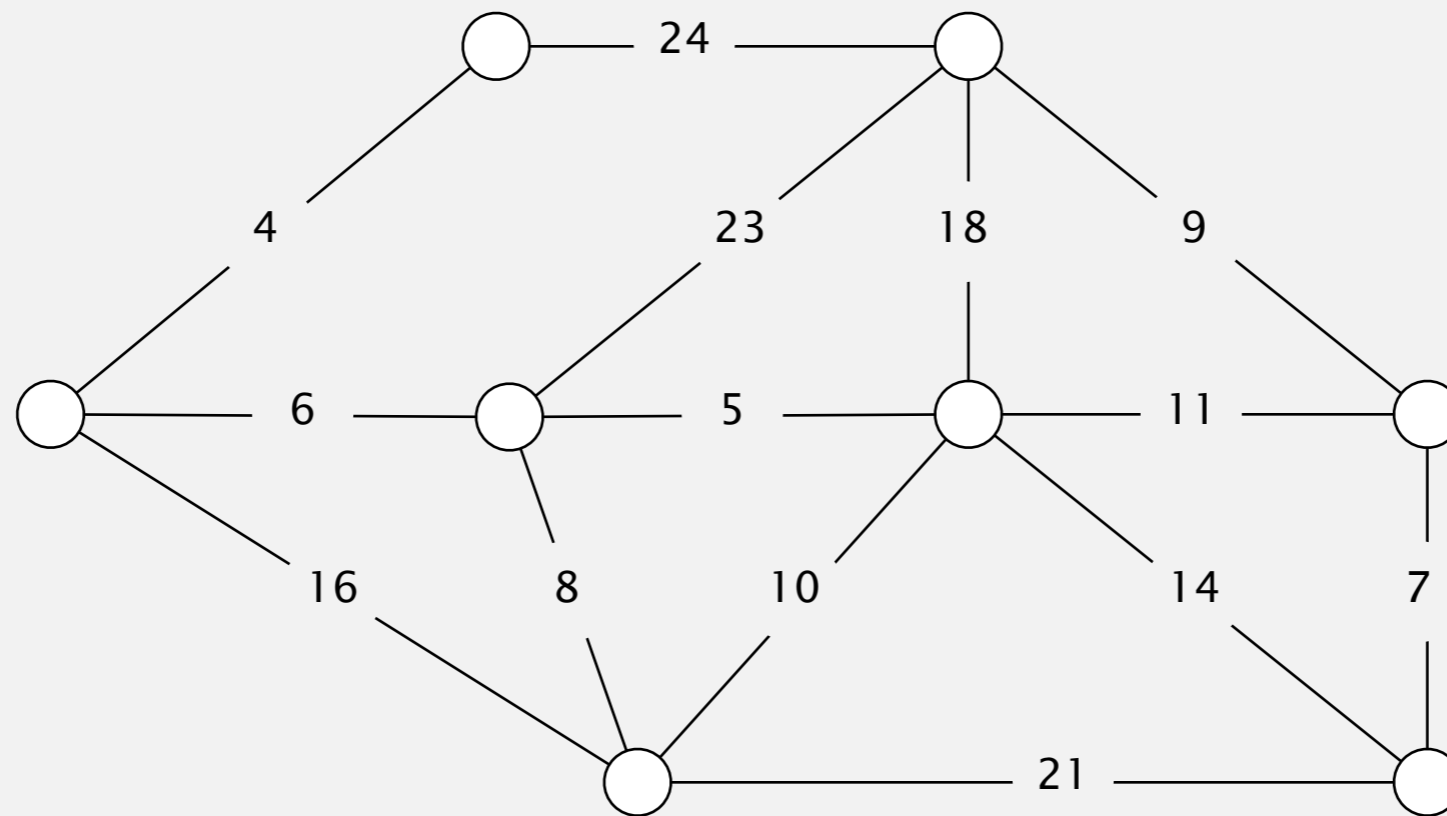


**not spanning**

# Minimum spanning tree problem

---

**Input.** Connected, undirected graph  $G$  with positive edge weights.



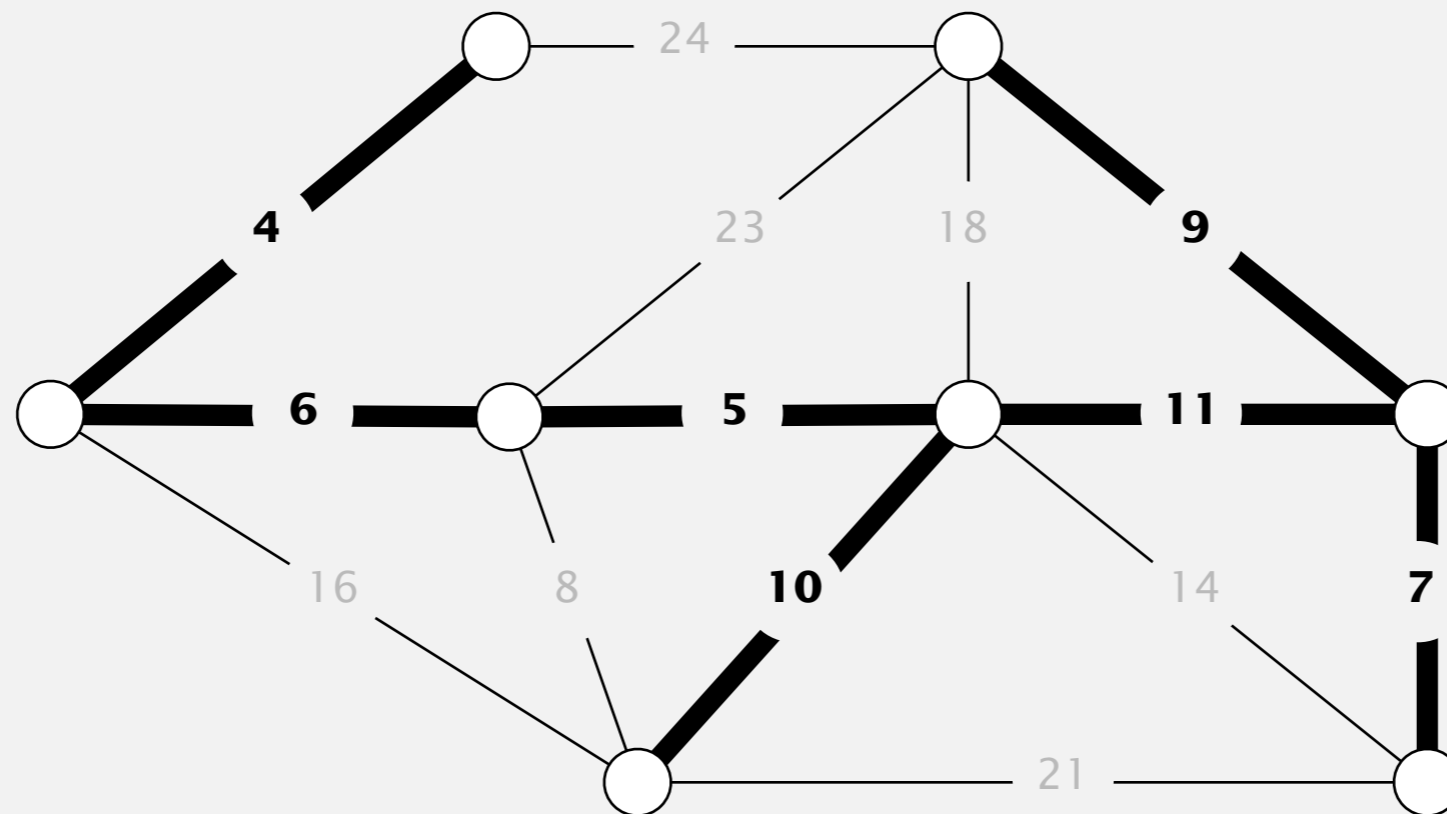
**edge-weighted graph  $G$**

# Minimum spanning tree problem

---

**Input.** Connected, undirected graph  $G$  with positive edge weights.

**Output.** A spanning tree of minimum weight.



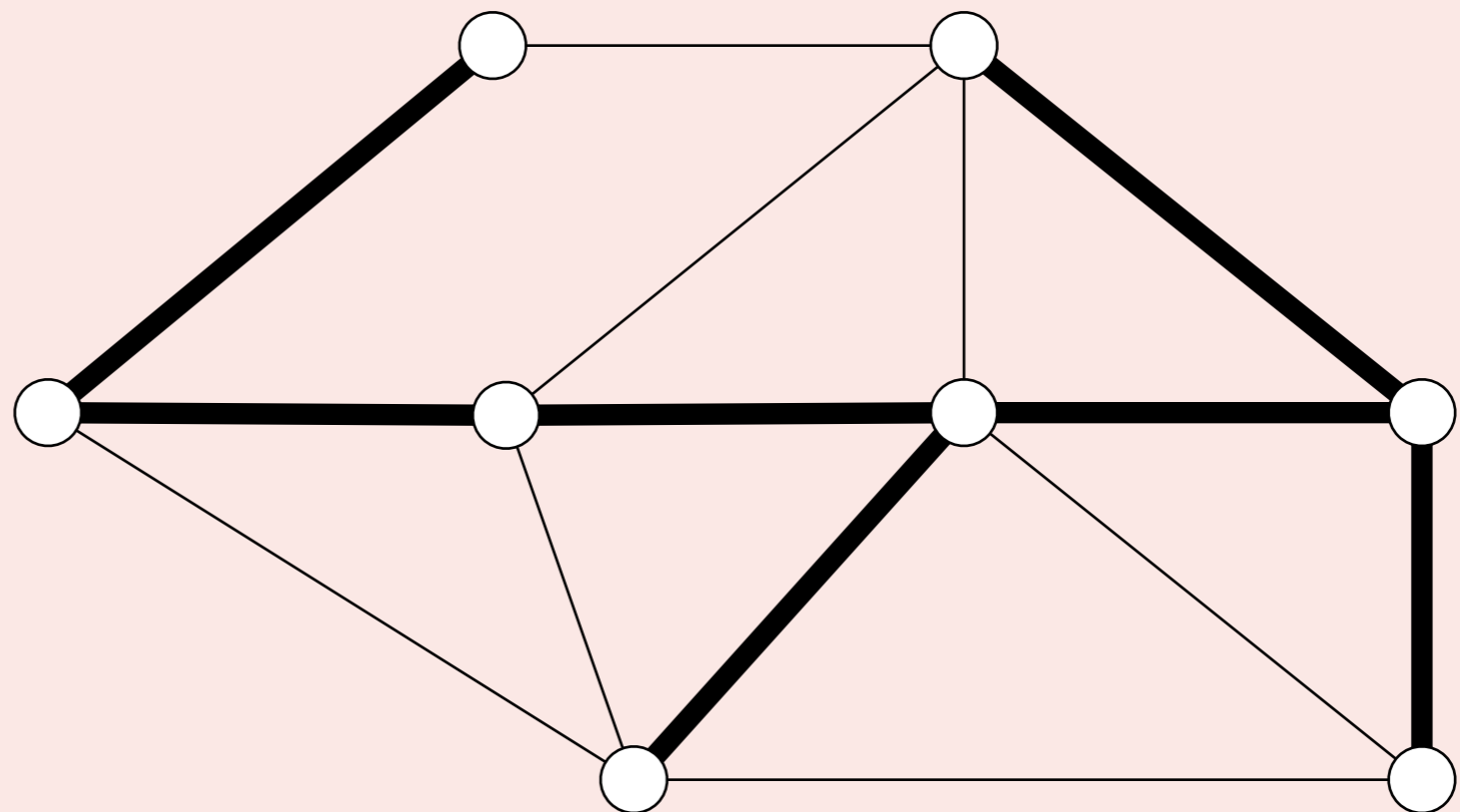
**minimum spanning tree  $T$**   
(weight = 52 = 4 + 6 + 10 + 5 + 11 + 9 + 7)

**Brute force.** Try all spanning trees?



Let  $T$  be a spanning tree of a connected graph  $G$  with  $V$  vertices.  
Which of the following statements are true?

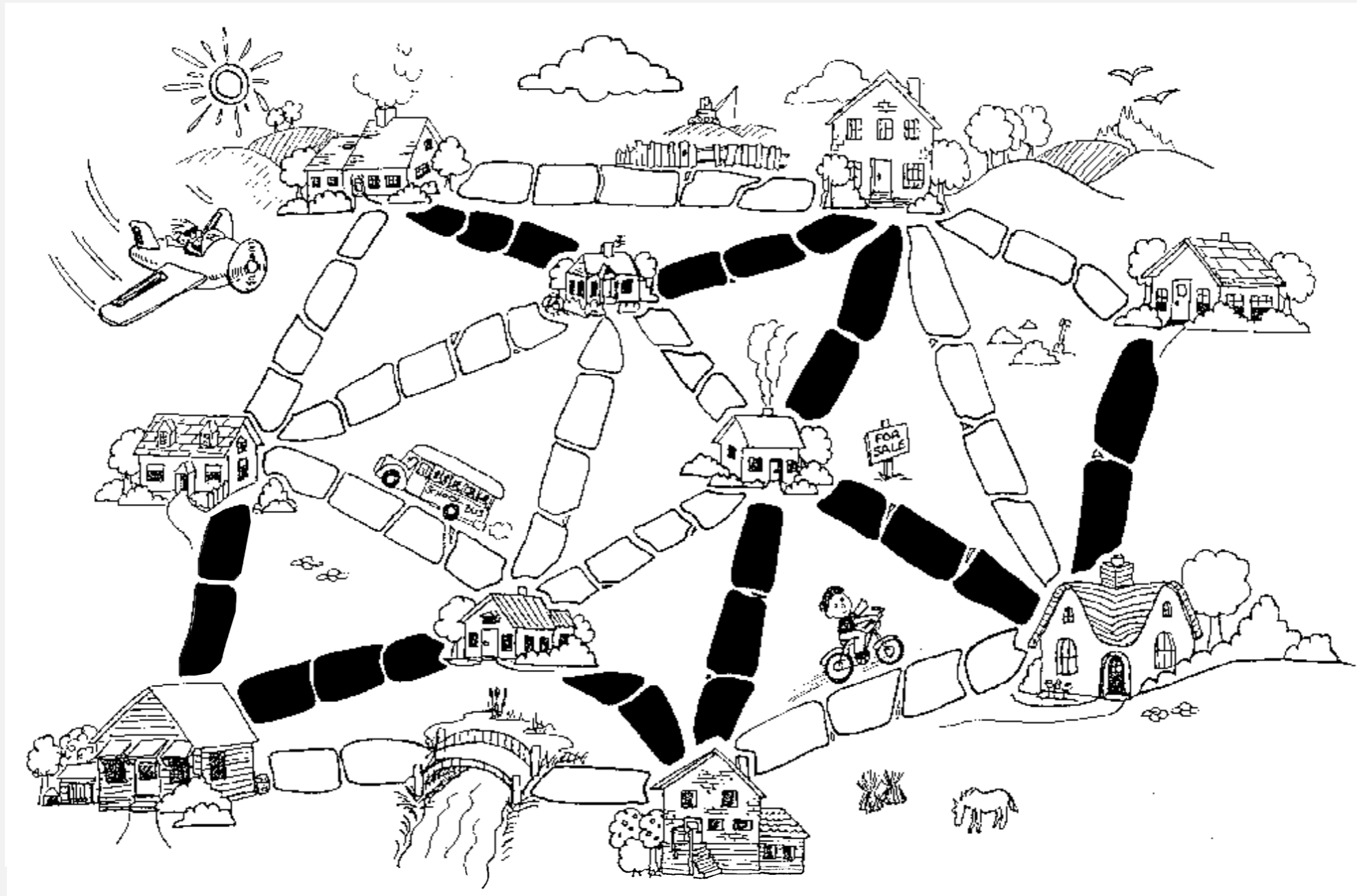
- A.**  $T$  contains exactly  $V - 1$  edges.
- B.** Removing any edge from  $T$  disconnects it.
- C.** Adding any edge to  $T$  creates a cycle.
- D.** All of the above.



spanning tree  $T$  of graph  $G$

# Network design

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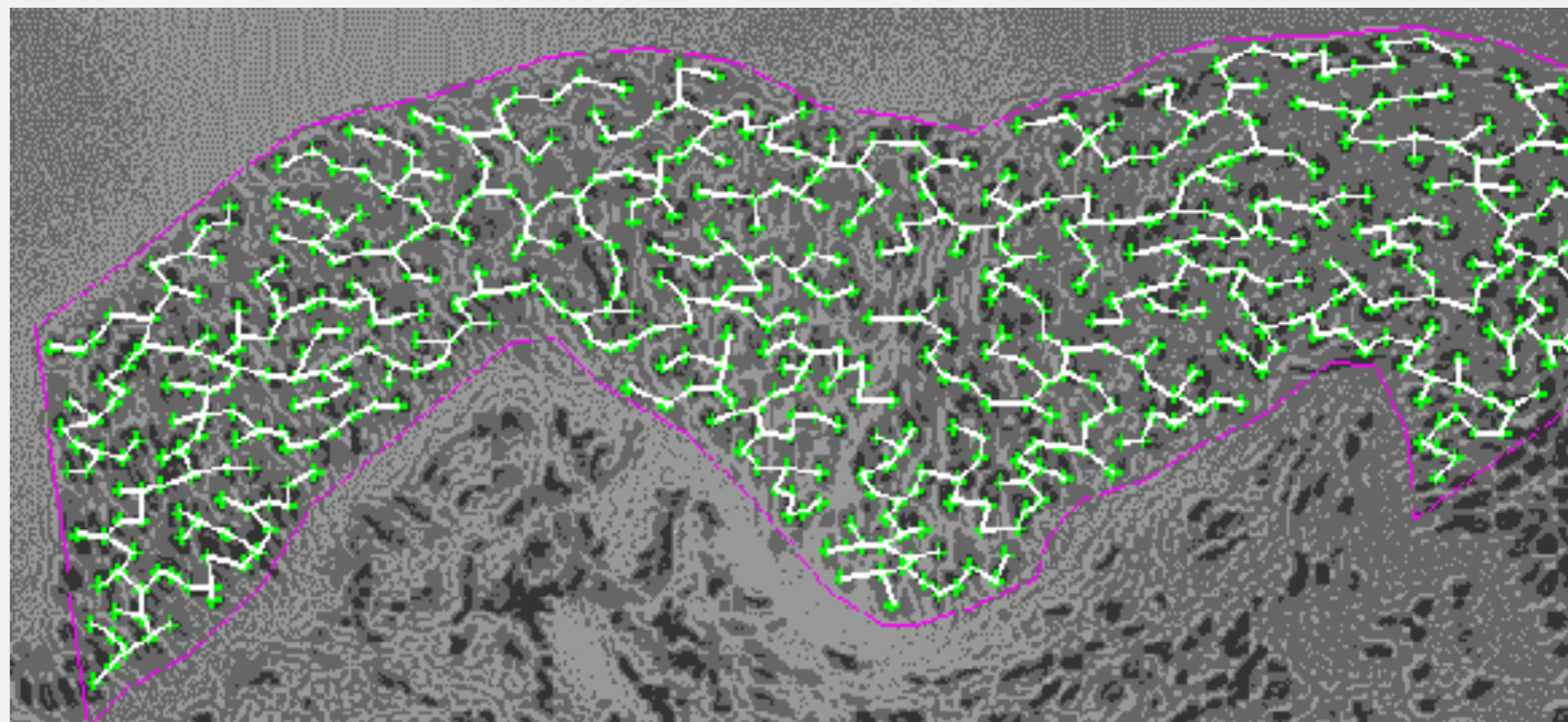
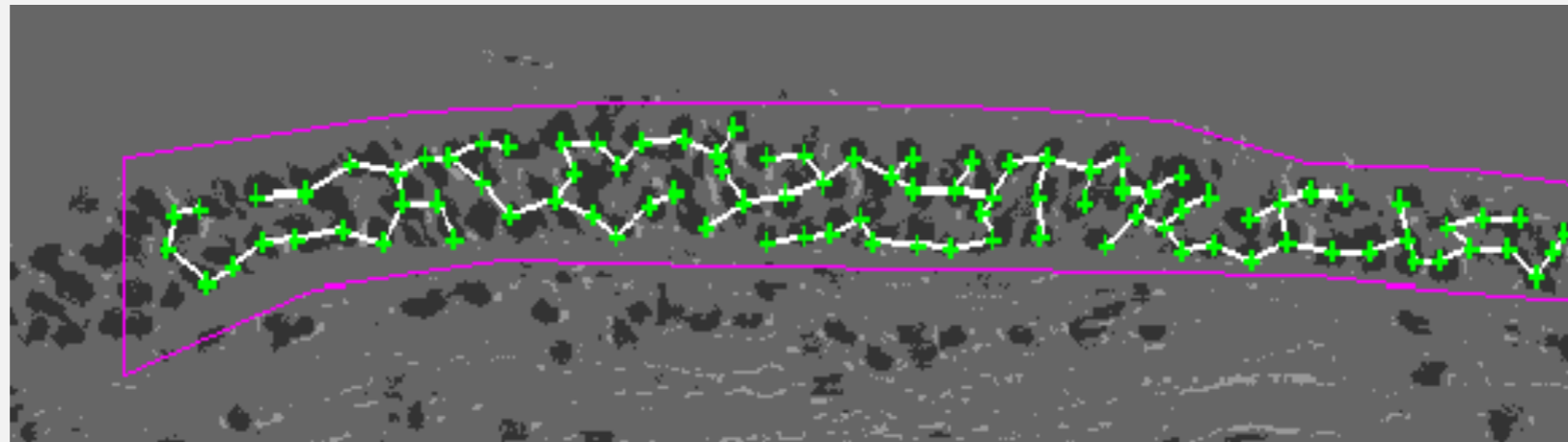


<http://www.utdallas.edu/~besp/teaching/mst-applications.pdf>

# Medical image processing

---

**MST describes arrangement of nuclei in the epithelium for cancer research**



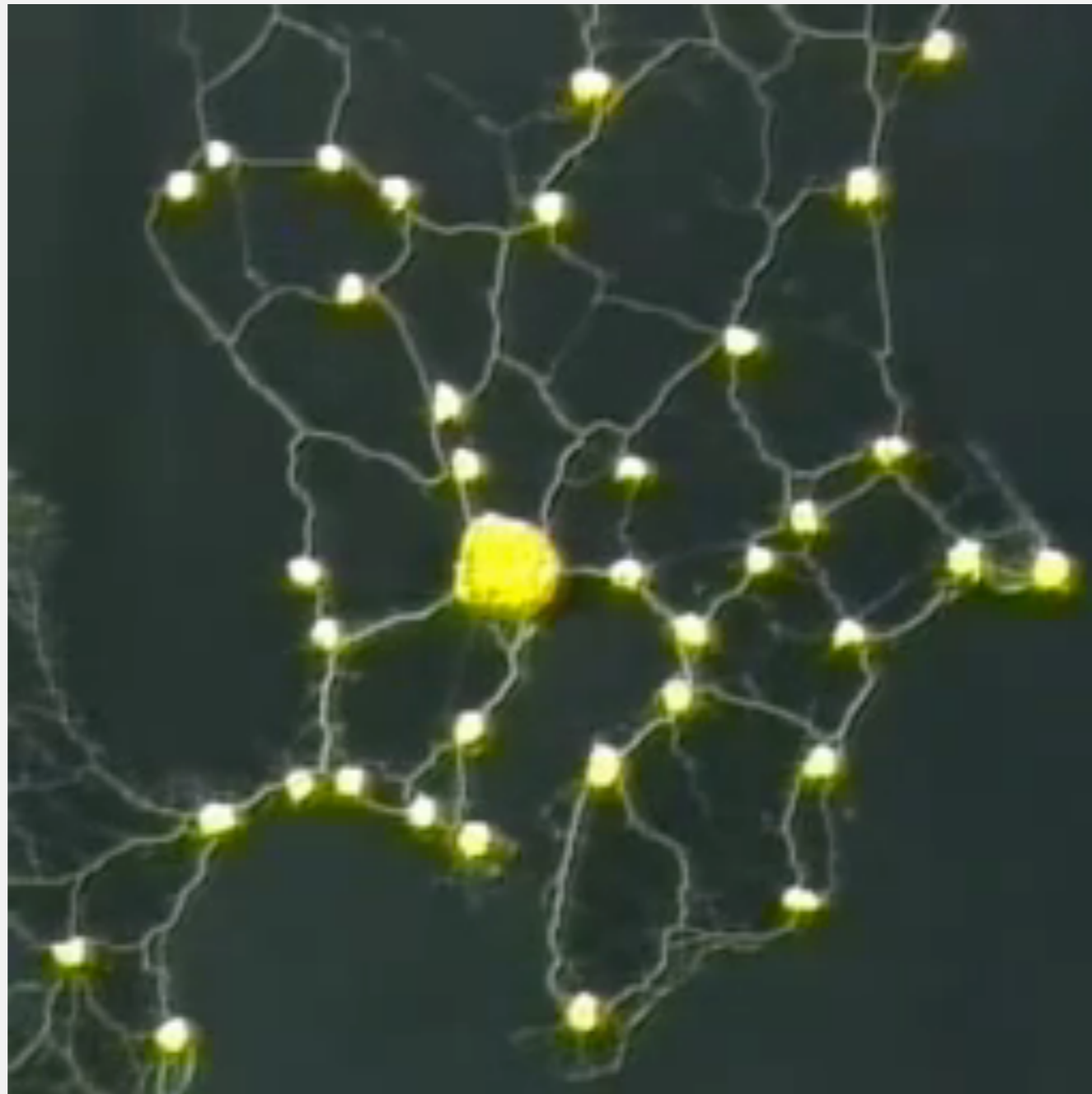
[http://www.bccrc.ca/ci/ta01\\_archlevel.html](http://www.bccrc.ca/ci/ta01_archlevel.html)

# Slime mold grows network just like Tokyo rail system

---

## Rules for Biologically Inspired Adaptive Network Design

Atsushi Tero,<sup>1,2</sup> Seiji Takagi,<sup>1</sup> Tetsu Saigusa,<sup>3</sup> Kentaro Ito,<sup>1</sup> Dan P. Bebber,<sup>4</sup> Mark D. Fricker,<sup>4</sup> Kenji Yumiki,<sup>5</sup> Ryo Kobayashi,<sup>5,6</sup> Toshiyuki Nakagaki<sup>1,6\*</sup>



<https://www.youtube.com/watch?v=GwKuFREOgmo>

# Applications

---

MST is fundamental problem with diverse applications.

- Cluster analysis.
- Real-time face verification.
- LDPC codes for error correction.
- Image registration with Renyi entropy.
- Curvilinear feature extraction in computer vision.
- Find road networks in satellite and aerial imagery.
- Handwriting recognition of mathematical expressions.
- Measuring homogeneity of two-dimensional materials.  
Model locality of particle interactions in turbulent fluid flows.
- Reducing data storage in sequencing amino acids in a protein.
- Autoconfig protocol for Ethernet bridging to avoid cycles in a network.
- Network design (communication, electrical, hydraulic, computer, road).
- Approximation algorithms for **NP**-hard problems (e.g., TSP, Steiner tree).

<http://www.ics.uci.edu/~eppstein/gina/mst.html>

<http://www.utdallas.edu/~besp/teaching/mst-applications.pdf>



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## 4.3 MINIMUM SPANNING TREES

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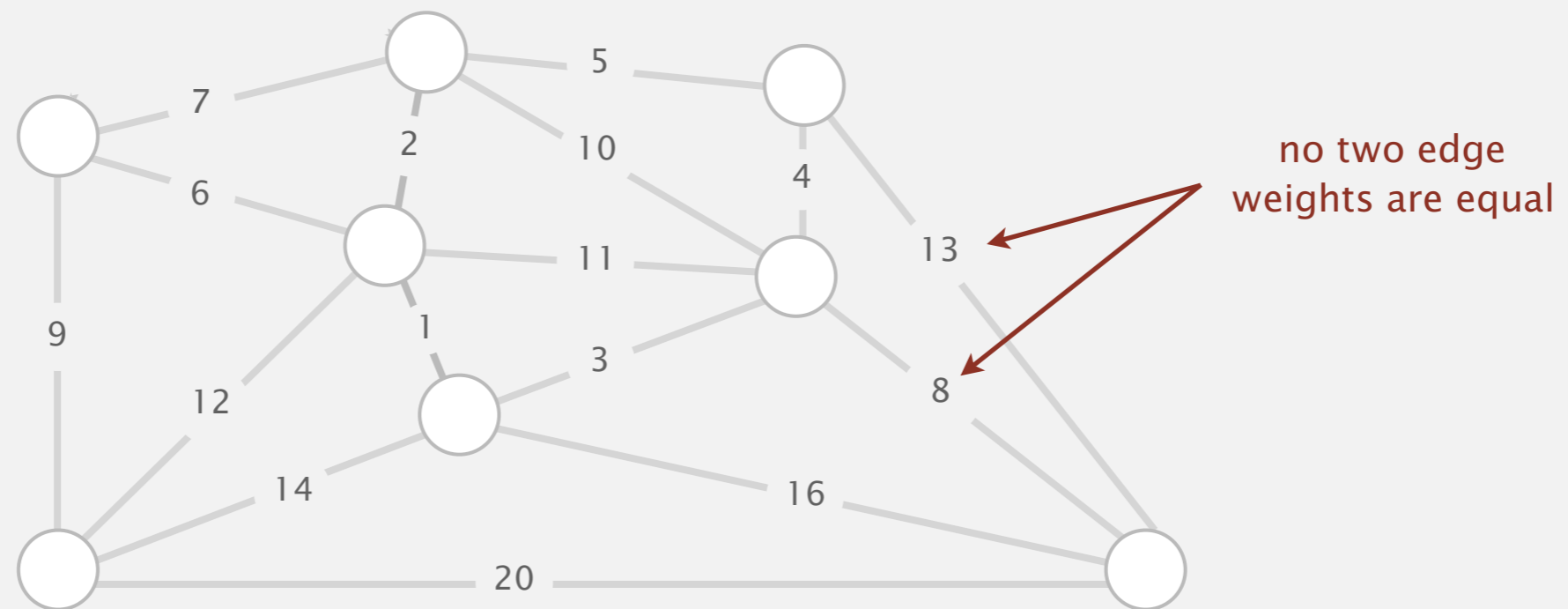
# Simplifying assumptions

---

For simplicity, we assume:

- No parallel edges.
- The graph is connected.  $\Rightarrow$  MST exists.
- The edge weights are distinct.  $\Rightarrow$  MST is unique.  $\leftarrow$  see Exercise 4.3.3

**Note.** Algorithms still work even if parallel edges or duplicate edge weights.



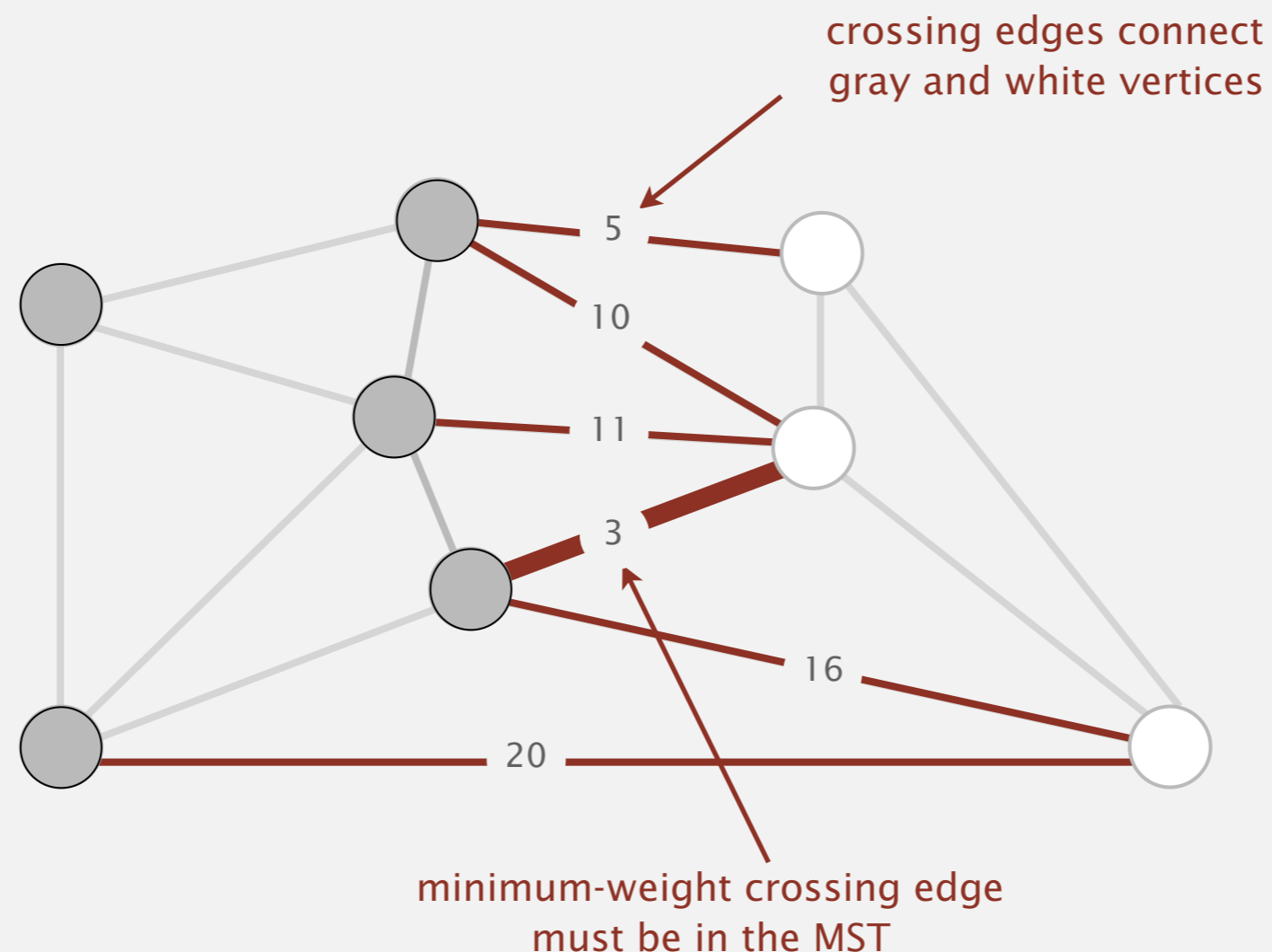
# Cut property

---

**Def.** A **cut** in a graph is a partition of its vertices into two (nonempty) sets.

**Def.** A **crossing edge** connects a vertex in one set with a vertex in the other.

**Cut property.** Given any cut, the crossing edge of min weight is in the MST.





Which is the min weight edge crossing the cut  $\{2, 3, 5, 6\}$  ?

A. 0–7 (0.16)

B. 2–3 (0.17)

C. 0–2 (0.26)

D. 5–7 (0.28)

0–7 0.16

2–3 0.17

1–7 0.19

0–2 0.26

5–7 0.28

1–3 0.29

1–5 0.32

2–7 0.34

4–5 0.35

1–2 0.36

4–7 0.37

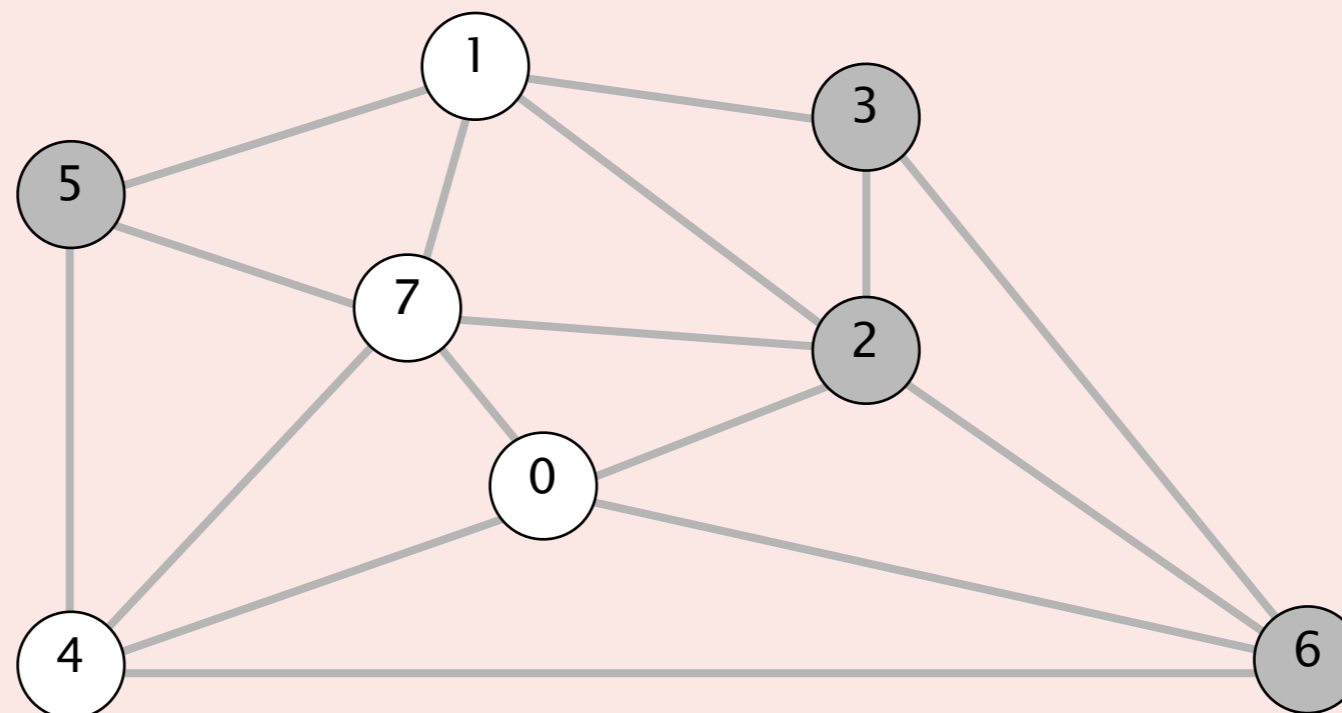
0–4 0.38

6–2 0.40

3–6 0.52

6–0 0.58

6–4 0.93



# Cut property: correctness proof

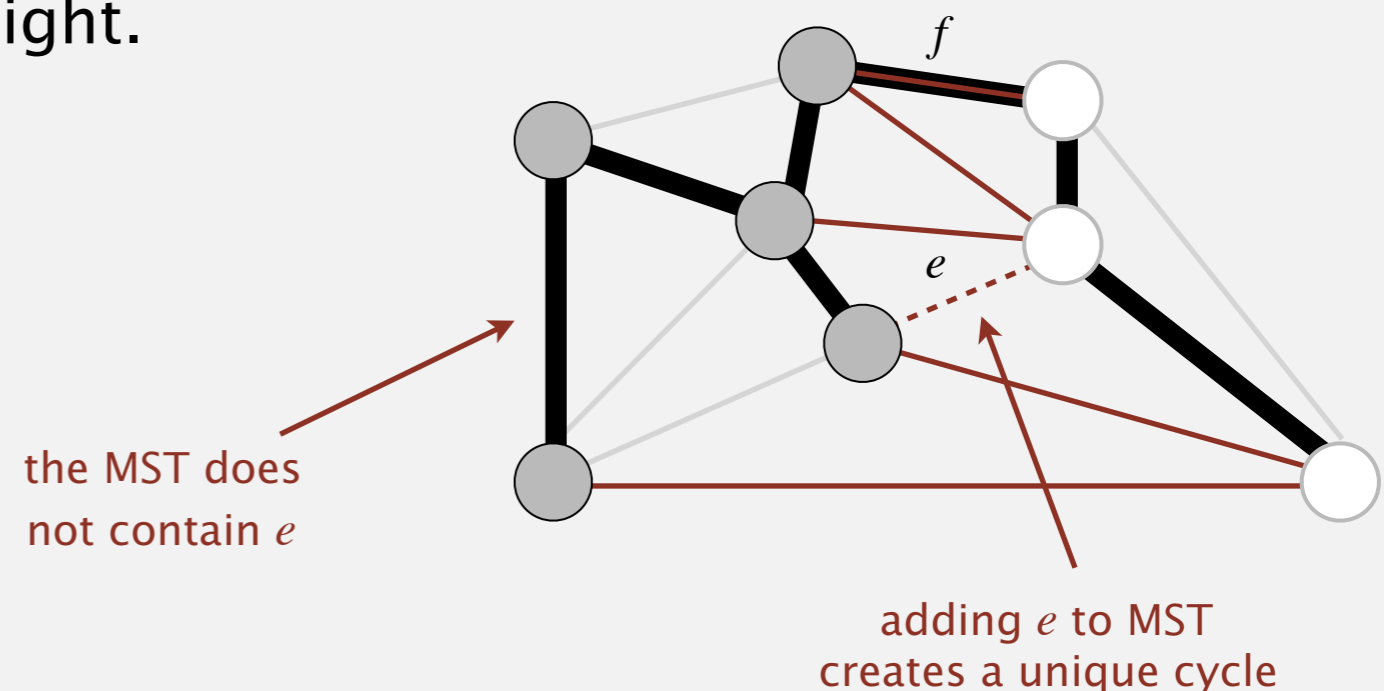
**Def.** A **cut** is a partition of a graph's vertices into two (nonempty) sets.

**Def.** A **crossing edge** connects two vertices in different sets.

**Cut property.** Given any cut, the min-weight crossing edge  $e$  is in the MST.

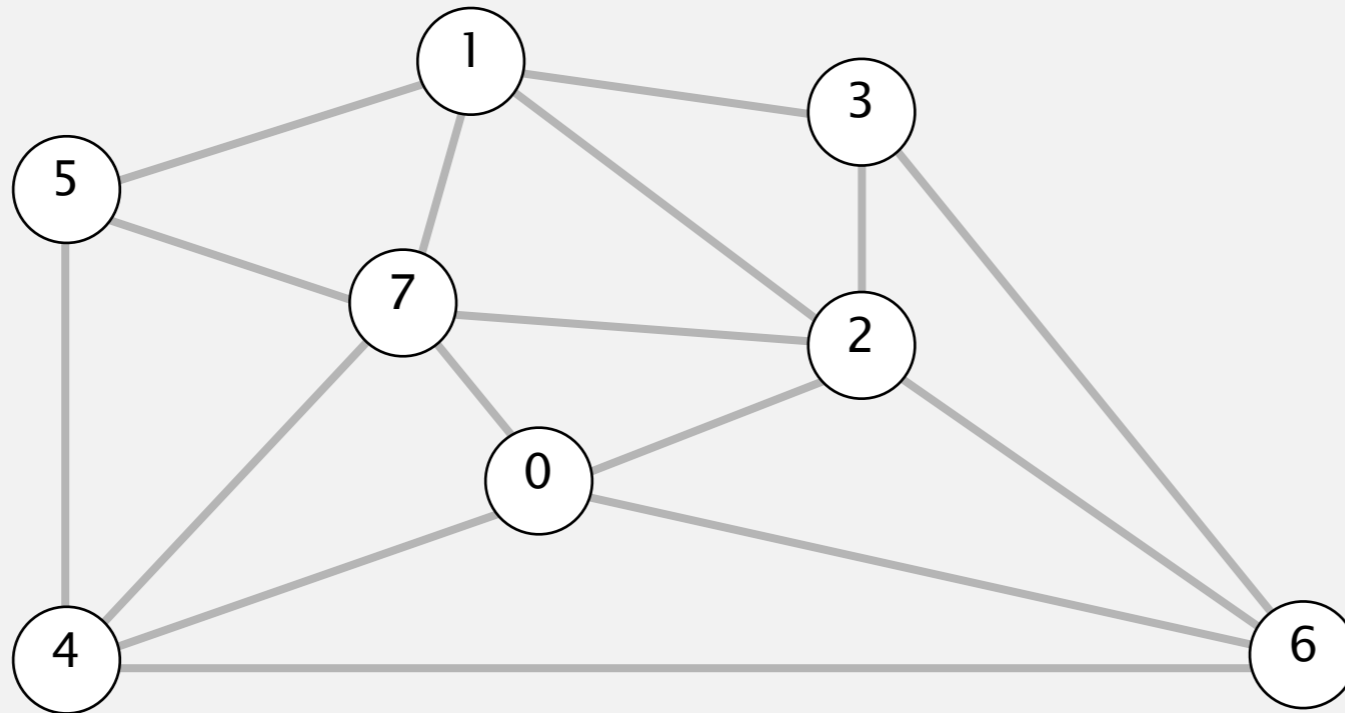
**Pf.** [by contradiction] Suppose  $e$  is not in the MST.

- Adding  $e$  to the MST creates a cycle.
- Some other edge  $f$  in cycle must be a crossing edge.
- Removing  $f$  and adding  $e$  is also a spanning tree.
- Since weight of  $e$  is less than the weight of  $f$ , that spanning tree has lower weight.
- Contradiction. ■



# Greedy MST algorithm demo

- Start with all edges colored gray.
- Find cut with no black crossing edges; color its min-weight edge black.
- Repeat until  $V - 1$  edges are colored black.



an edge-weighted graph

0-7	0.16
2-3	0.17
1-7	0.19
0-2	0.26
5-7	0.28
1-3	0.29
1-5	0.32
2-7	0.34
4-5	0.35
1-2	0.36
4-7	0.37
0-4	0.38
6-2	0.40
3-6	0.52
6-0	0.58
6-4	0.93

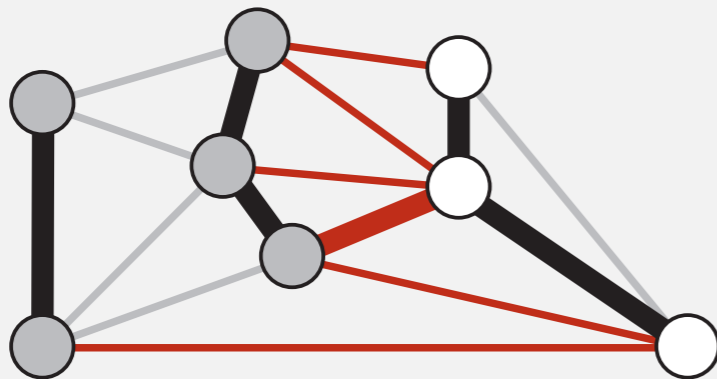
# Greedy MST algorithm: correctness proof

---

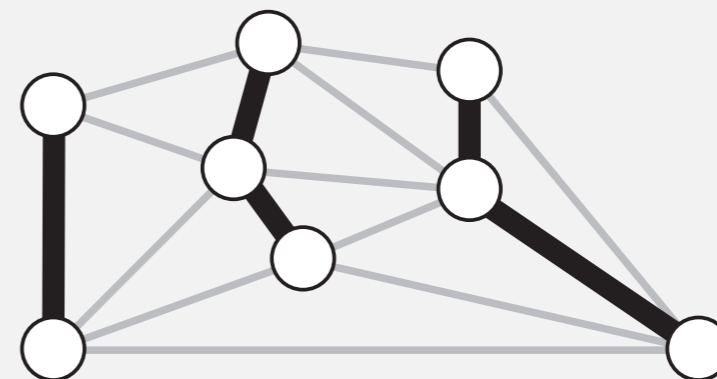
**Proposition.** The greedy algorithm computes the MST.

**Pf.**

- Any edge colored black is in the MST (via cut property).
- Fewer than  $V - 1$  black edges  $\Rightarrow$  cut with no black crossing edges.  
(consider cut whose vertices are any one connected component)



a cut with no black crossing edges



fewer than  $V - 1$  edges colored black

# Greedy MST algorithm: efficient implementations

---

**Proposition.** The greedy algorithm computes the MST.

**Efficient implementations.** Find cut? Find min-weight edge?

**Ex 1.** Kruskal's algorithm. [stay tuned]

**Ex 2.** Prim's algorithm. [stay tuned]

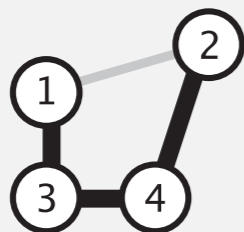
**Ex 3.** Borůvka's algorithm.

# Removing two simplifying assumptions

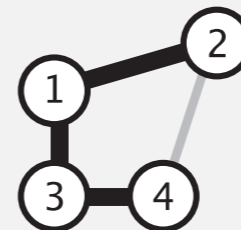
Q. What if edge weights are not all distinct?

A. Greedy MST algorithm still finds a MST!

(our correctness proof fails, but that can be fixed)



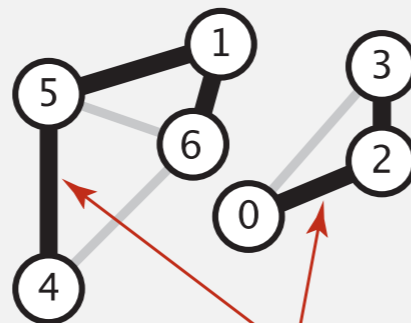
1	2	1.00
1	3	0.50
2	4	1.00
3	4	0.50



1	2	1.00
1	3	0.50
2	4	1.00
3	4	0.50

Q. What if graph is not connected?

A. Finds a minimum spanning forest = MST of each connected component.



4	5	0.61
4	6	0.62
5	6	0.88
1	5	0.11
2	3	0.35
0	3	0.6
1	6	0.10
0	2	0.22

*can independently compute  
MSTs of components*



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## 4.3 MINIMUM SPANNING TREES

---

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- ▶ *cut property*
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- ▶ *Prim's algorithm*

# Weighted edge API

---

Edge abstraction needed for weighted edges.

```
public class Edge implements Comparable<Edge>
```

```
    Edge(int v, int w, double weight) create a weighted edge v-w
```

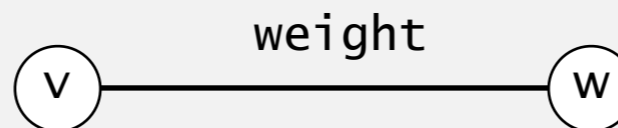
```
    int either() either endpoint
```

```
    int other(int v) the endpoint that's not v
```

```
    int compareTo(Edge that) compare this edge to that edge
```

```
    double weight() the weight
```

```
    String toString() string representation
```



Idiom for processing an edge e: `int v = e.either(), w = e.other(v);`

# Weighted edge: Java implementation

---

```
public class Edge implements Comparable<Edge>
{
```

```
    private final int v, w;
    private final double weight;
```

```
    public Edge(int v, int w, double weight)
```

```
    {
```

```
        this.v = v;
```

```
        this.w = w;
```

```
        this.weight = weight;
```

```
    }
```

```
    public int either()
```

```
    { return v; }
```

```
    public int other(int vertex)
```

```
    {
```

```
        if (vertex == v) return w;
```

```
        else return v;
```

```
    }
```

```
    public int compareTo(Edge that)
```

```
    {
```

```
        if (this.weight < that.weight) return -1;
```

```
        else if (this.weight > that.weight) return +1;
```

```
        else return 0;
```

```
    }
```

```
}
```

← constructor

← either endpoint

← other endpoint

← compare edges by weight

# Edge-weighted graph API

---

```
public class EdgeWeightedGraph
```

```
    EdgeWeightedGraph(int V)
```

*create an empty graph with  $V$  vertices*

```
    void addEdge(Edge e)
```

*add weighted edge  $e$  to this graph*

```
    Iterable<Edge> adj(int v)
```

*edges incident to  $v$*

```
    Iterable<Edge> edges()
```

*all edges in this graph*

```
    int V()
```

*number of vertices*

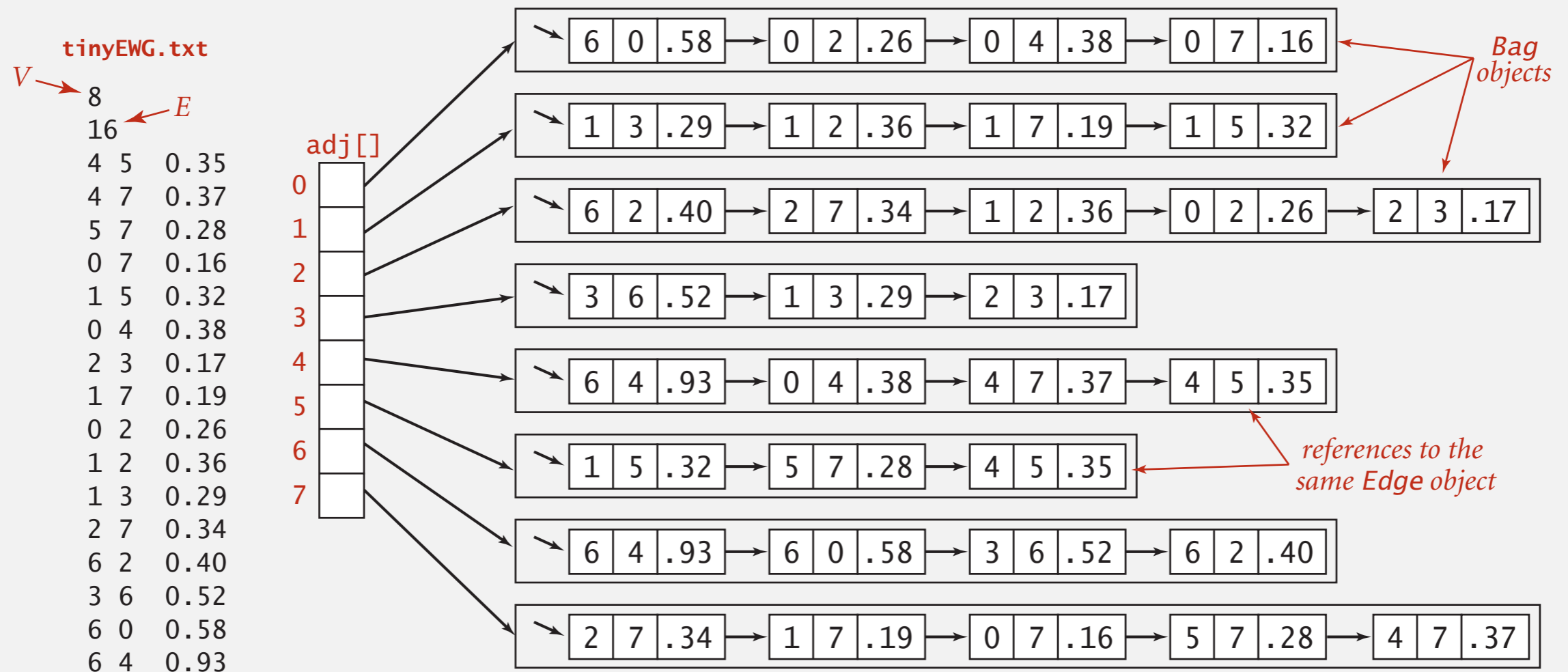
```
    int E()
```

*number of edges*

**Conventions.** Allow self-loops and parallel edges.

# Edge-weighted graph: adjacency-lists representation

Maintain vertex-indexed array of Edge lists.



# Edge-weighted graph: adjacency-lists implementation

---

```
public class EdgeWeightedGraph  
{
```

```
    private final int V;  
    private final Bag<Edge>[] adj;
```

← same as Graph, but adjacency lists of Edges instead of integers

```
    public EdgeWeightedGraph(int V)  
    {  
        this.V = V;  
        adj = (Bag<Edge>[]) new Bag[V];  
        for (int v = 0; v < V; v++)  
            adj[v] = new Bag<Edge>();  
    }
```

← constructor

```
    public void addEdge(Edge e)  
    {  
        int v = e.either(), w = e.other(v);  
        adj[v].add(e);  
        adj[w].add(e);  
    }
```

← add edge to both adjacency lists

```
    public Iterable<Edge> adj(int v)  
    { return adj[v]; }  
}
```

# Minimum spanning tree API

---

Q. How to represent the MST?

```
public class MST
```

```
    MST(EdgeWeightedGraph G)
```

*constructor*

```
    Iterable<Edge> edges()
```

*edges in MST*

```
    double weight()
```

*weight of MST*



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## 4.3 MINIMUM SPANNING TREES

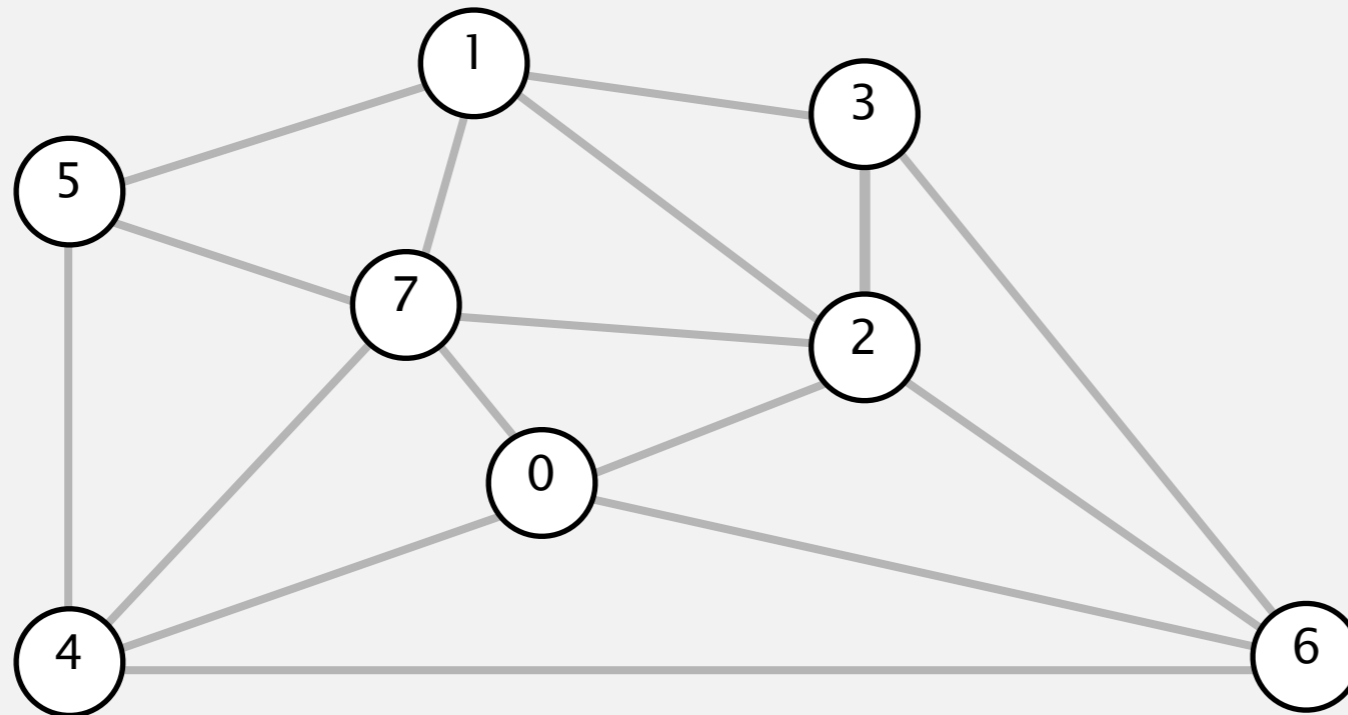
---

- ▶ *introduction*
- ▶ *cut property*
- ▶ *edge-weighted graph API*
- ▶ *Kruskal's algorithm*
- ▶ *Prim's algorithm*

# Kruskal's algorithm demo

Consider edges in ascending order of weight.

- Add next edge to tree  $T$  unless doing so would create a cycle.



an edge-weighted graph

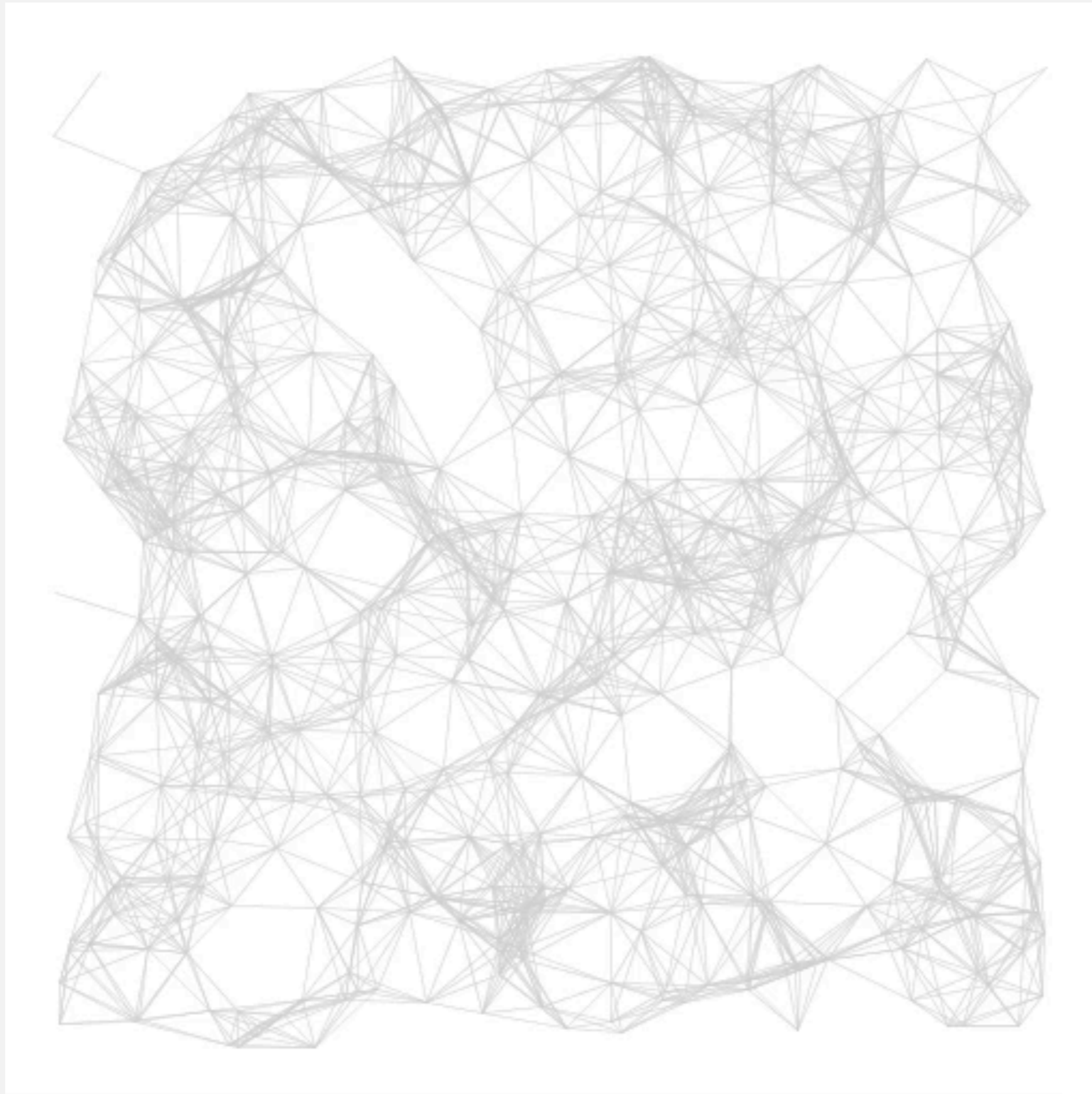
graph edges  
sorted by weight

↓

0-7	0.16
2-3	0.17
1-7	0.19
0-2	0.26
5-7	0.28
1-3	0.29
1-5	0.32
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6-2	0.40
3-6	0.52
6-0	0.58
6-4	0.93

# Kruskal's algorithm: visualization

---



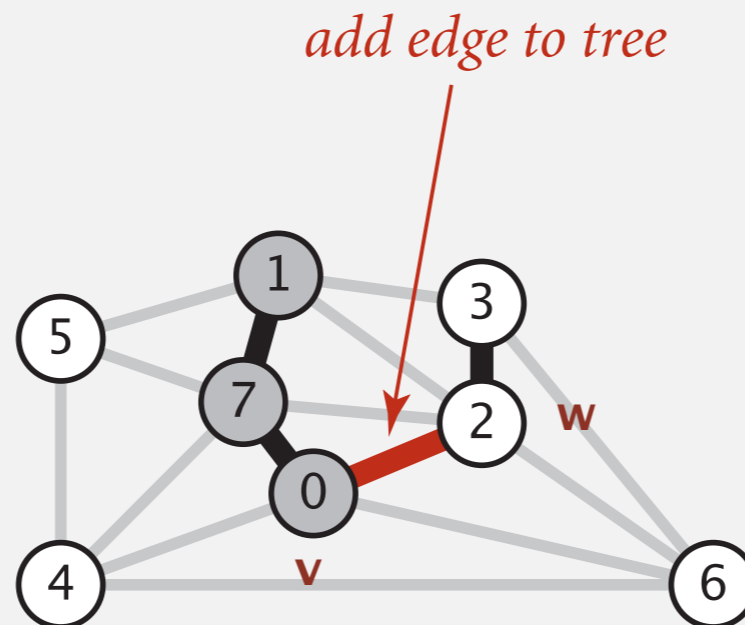
# Kruskal's algorithm: correctness proof

---

**Proposition.** [Kruskal 1956] Kruskal's algorithm computes the MST.

**Pf.** [Case 1] Kruskal's algorithm adds edge  $e = v-w$  to  $T$ .

- Vertices  $v$  and  $w$  are in different connected components of  $T$ .
- Cut = set of vertices connected to  $v$  in  $T$ .
- By construction of cut, no edge crossing cut is in  $T$ .
- No edge crossing cut has lower weight. Why?
- Cut property  $\Rightarrow$  edge  $e$  is in the MST.



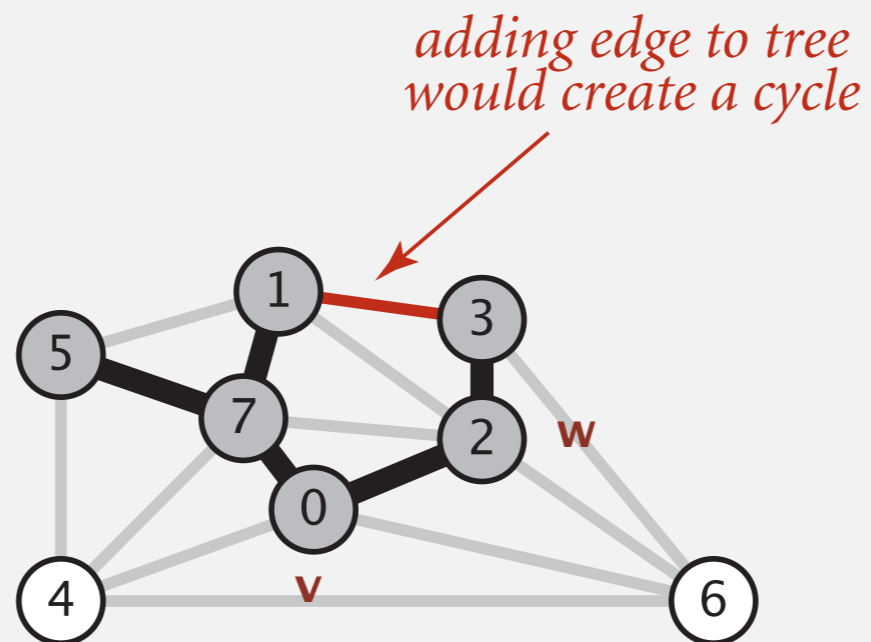
# Kruskal's algorithm: correctness proof

---

**Proposition.** [Kruskal 1956] Kruskal's algorithm computes the MST.

**Pf.** [Case 2] Kruskal's algorithm discards edge  $e = v-w$ .

- From Case 1, all edges in  $T$  are in the MST.
- The MST can't contain a cycle. ■

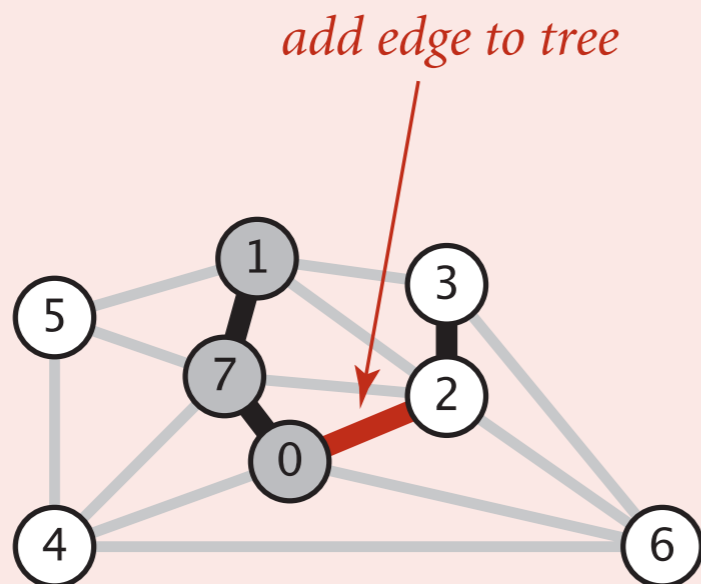




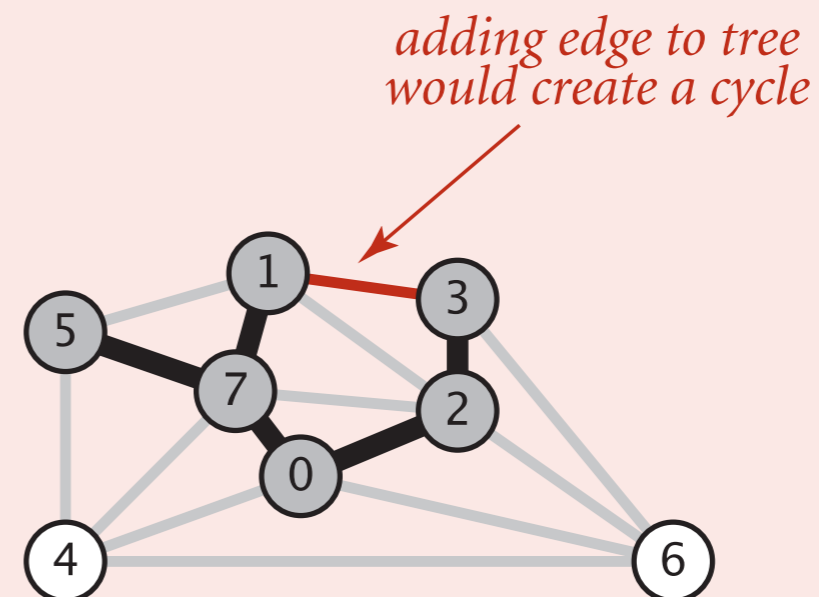
**Challenge.** Would adding edge  $v-w$  to tree  $T$  create a cycle? If not, add it.

**How difficult to implement?**

- A.** 1
- B.**  $\log V$
- C.**  $V$
- D.**  $E + V$



Case 1:  $v$  and  $w$  in same component



Case 2:  $v$  and  $w$  in different components

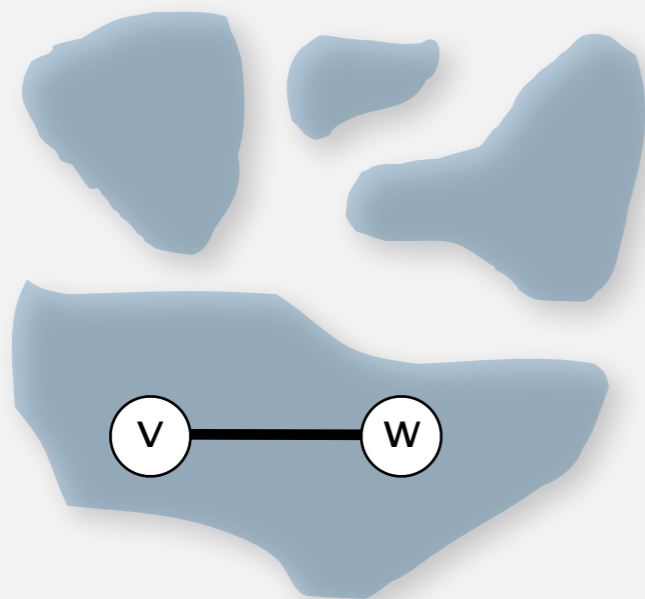
# Kruskal's algorithm: implementation challenge

---

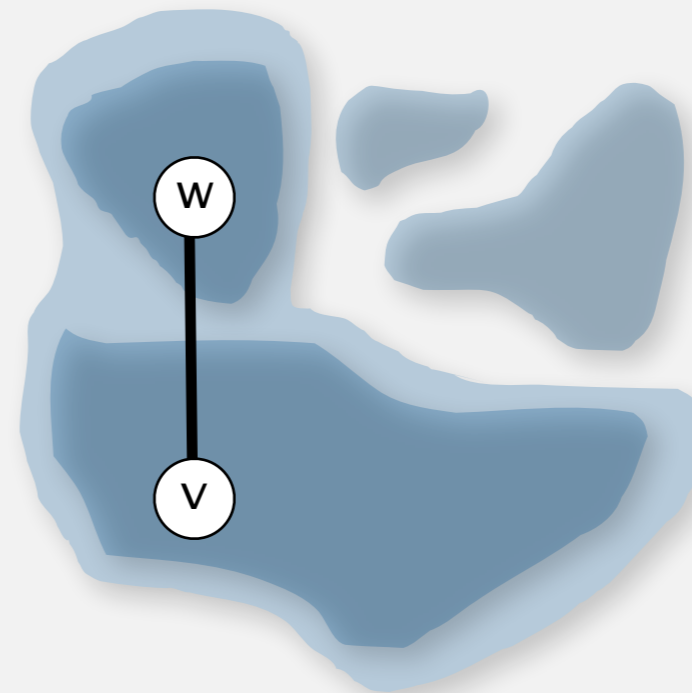
**Challenge.** Would adding edge  $v-w$  to tree  $T$  create a cycle? If not, add it.

**Efficient solution.** Use the **union-find** data structure.

- Maintain a set for each connected component in  $T$ .
- If  $v$  and  $w$  are in same set, then adding  $v-w$  would create a cycle.
- To add  $v-w$  to  $T$ , merge sets containing  $v$  and  $w$ .



Case 2: adding  $v-w$  creates a cycle



Case 1: add  $v-w$  to  $T$  and merge sets containing  $v$  and  $w$

# Kruskal's algorithm: Java implementation

---

```
public class KruskalMST
{
    private Queue<Edge> mst = new Queue<Edge>();

    public KruskalMST(EdgeWeightedGraph G)
    {
        DirectedEdge[] edges = G.edges();
        Arrays.sort(edges);
        UF uf = new UF(G.V());

        for (int i = 0; i < G.E(); i++)
        {
            Edge e = edges[i];
            int v = e.either(), w = e.other(v);
            if (uf.find(v) != uf.find(w))
            {
                uf.union(v, w);
                mst.enqueue(e);
            }
        }

        public Iterable<Edge> edges()
        { return mst; }
    }
}
```

← edges in the MST

← sort edges by weight

← maintain connected components

← greedily add edges to MST

← edge v-w does not create cycle

← merge connected components

← add edge e to MST

# Kruskal's algorithm: running time

---

**Proposition.** Kruskal's algorithm computes MST in time proportional to  $E \log V$  (in the worst case).

**Pf.**

operation	frequency	time per op
<b>SORT</b>	1	$E \log E$
<b>UNION</b>	$V - 1$	$\log V^\dagger$
<b>FIND</b>	$2 E$	$\log V^\dagger$

← same as  $E \log V$   
if no parallel edges

† using weighted quick union

# Greed is good

---



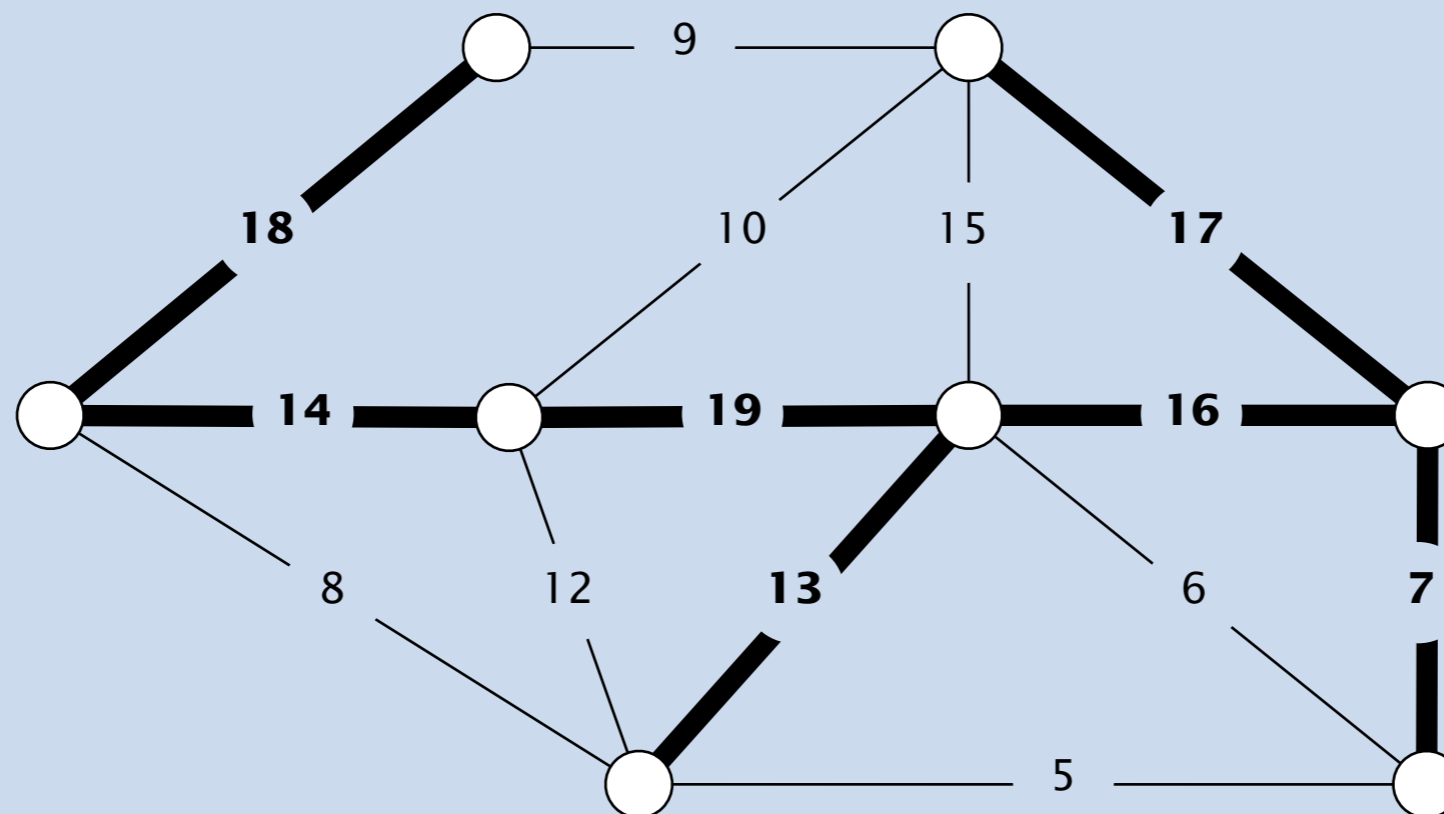
**Gordon Gecko (Michael Douglas) evangelizing the importance of greed (in algorithm design?)  
Wall Street (1986)**

# MAXIMUM SPANNING TREE



**Problem.** Given an undirected graph  $G$  with positive edge weights, find a spanning tree that **maximizes the sum** of the edge weights.

**Running time.**  $E \log E$  (or better).



maximum spanning tree  $T$  (weight = 104)



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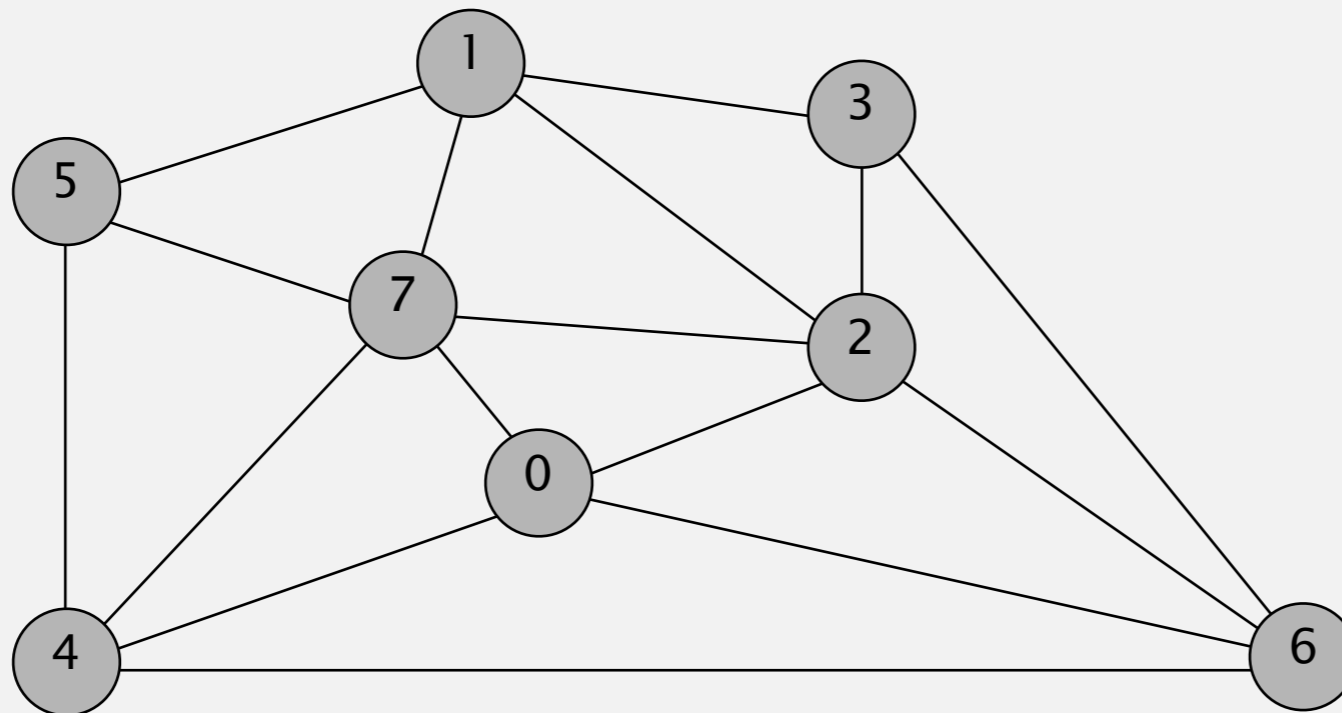
## 4.3 MINIMUM SPANNING TREES

---

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# Prim's algorithm demo

- Start with vertex 0 and greedily grow tree  $T$ .
- Add to  $T$  the min weight edge with exactly one endpoint in  $T$ .
- Repeat until  $V - 1$  edges.

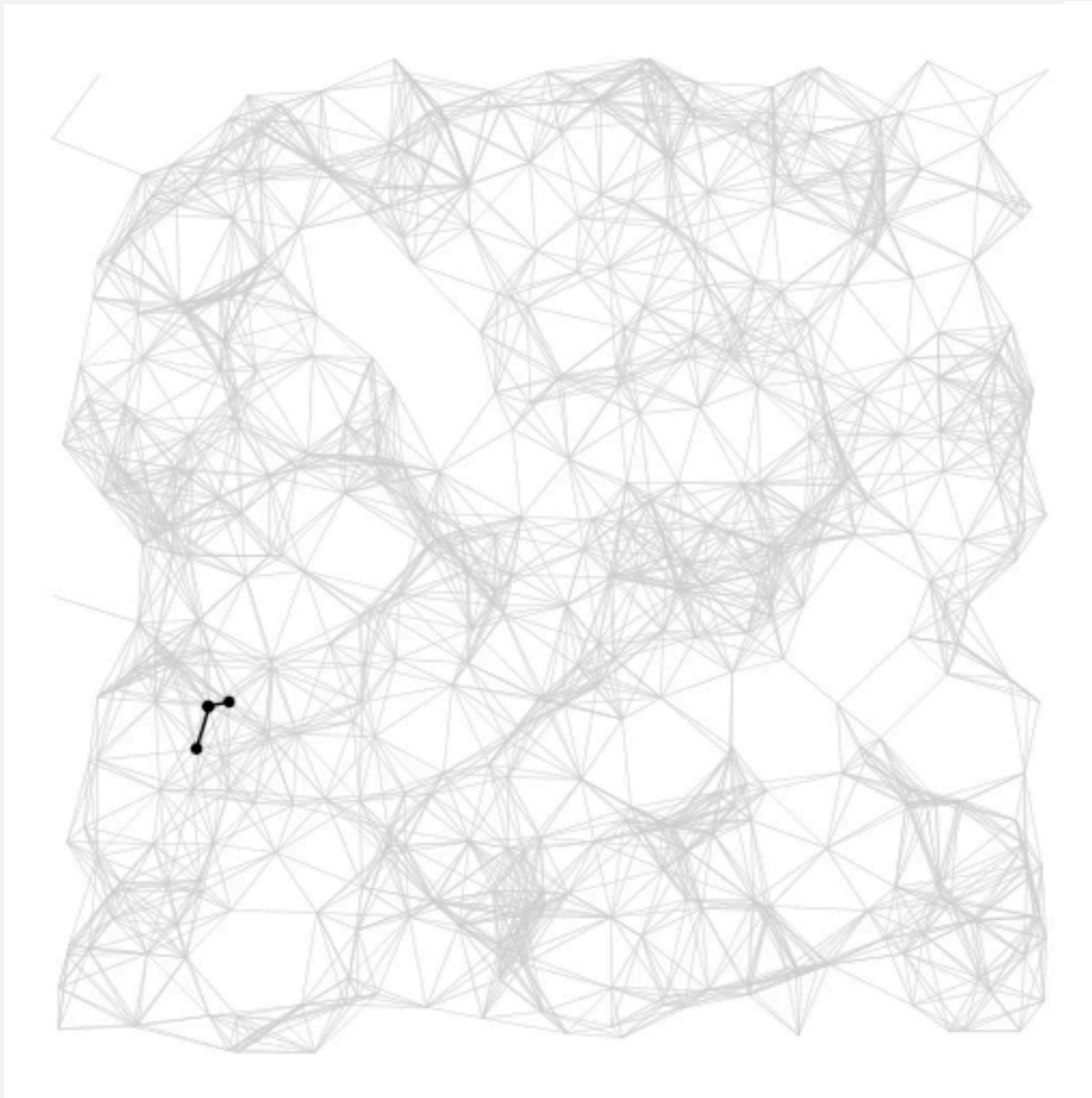


an edge-weighted graph

0-7	0.16
2-3	0.17
1-7	0.19
0-2	0.26
5-7	0.28
1-3	0.29
1-5	0.32
2-7	0.34
4-5	0.35
1-2	0.36
4-7	0.37
0-4	0.38
6-2	0.40
3-6	0.52
6-0	0.58
6-4	0.93

# Prim's algorithm: visualization

---



# Prim's algorithm: proof of correctness

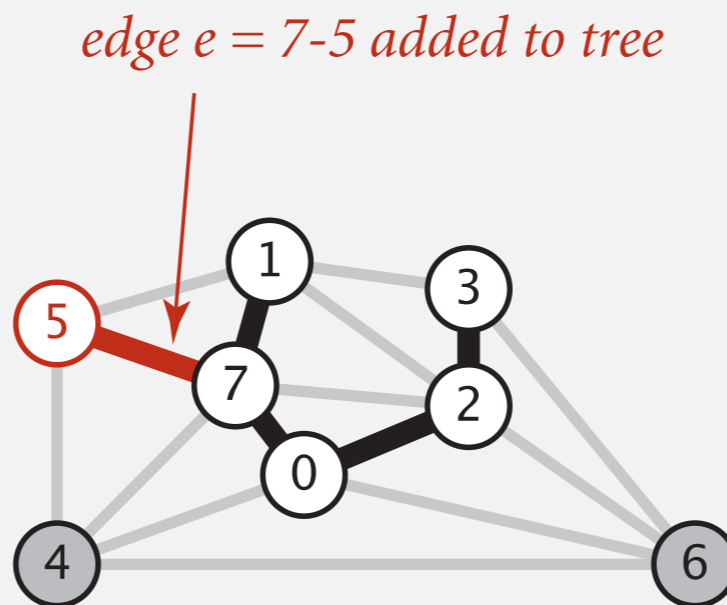
---

**Proposition.** [Jarník 1930, Dijkstra 1957, Prim 1959]

Prim's algorithm computes the MST.

**Pf.** Let  $e$  = min weight edge with exactly one endpoint in  $T$ .

- Cut = set of vertices in  $T$ .
- No crossing edge is in  $T$ .
- No crossing edge has lower weight.
- Cut property  $\Rightarrow$  edge  $e$  is in the MST. ■

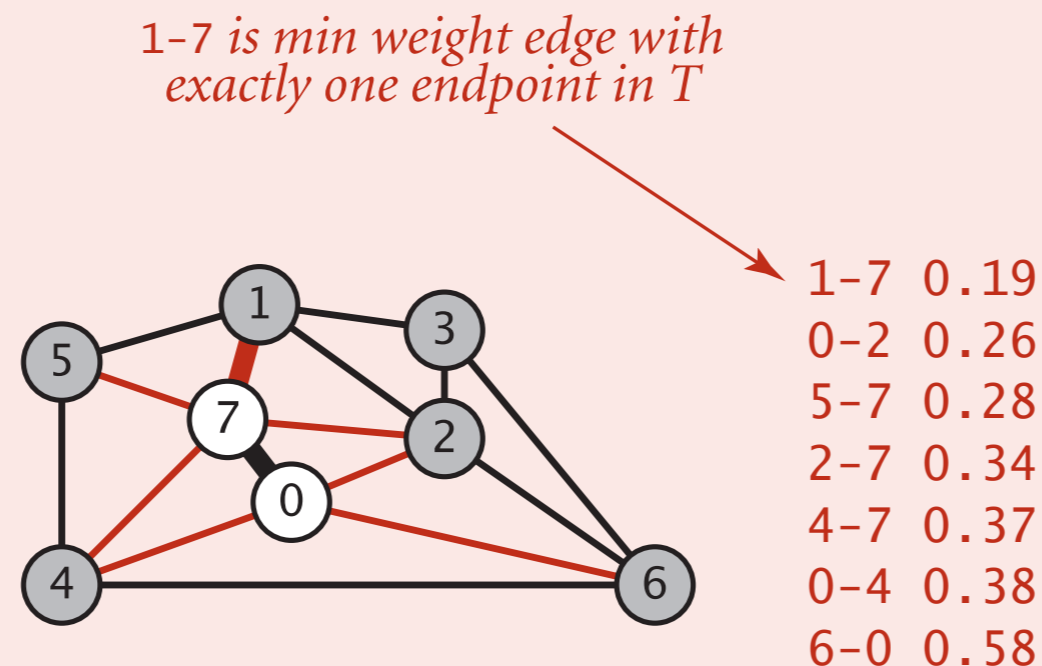




**Challenge.** Find the min weight edge with exactly one endpoint in  $T$ .

**How difficult to implement?**

- A. 1
- B.  $\log E$
- C.  $V$
- D.  $E$

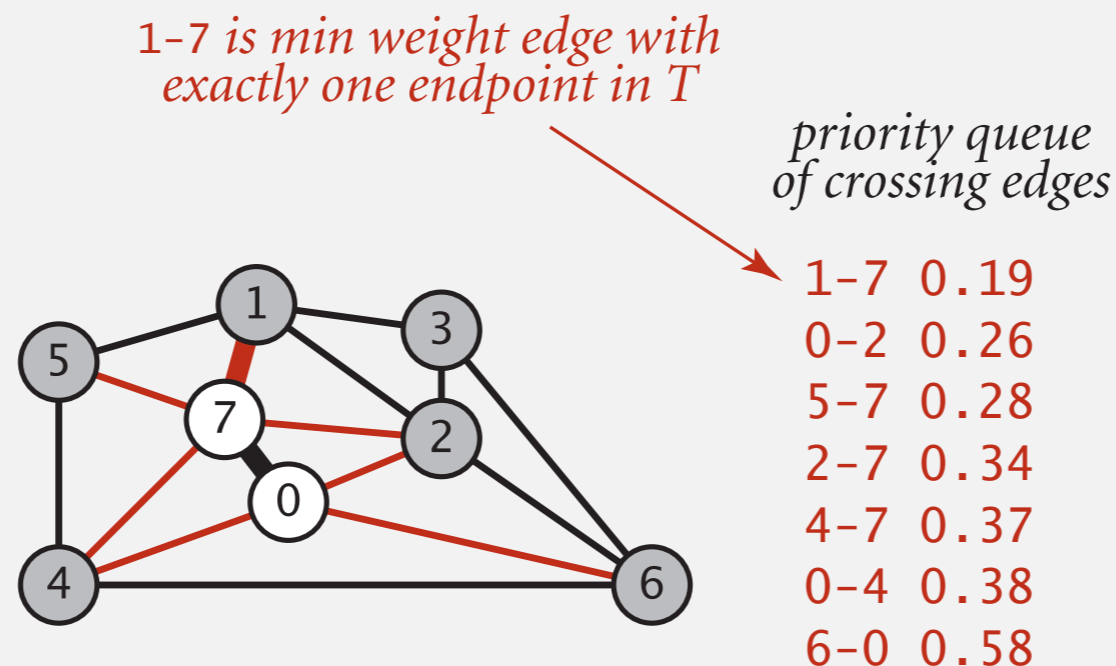


# Prim's algorithm: lazy implementation

**Challenge.** Find the min weight edge with exactly one endpoint in  $T$ .

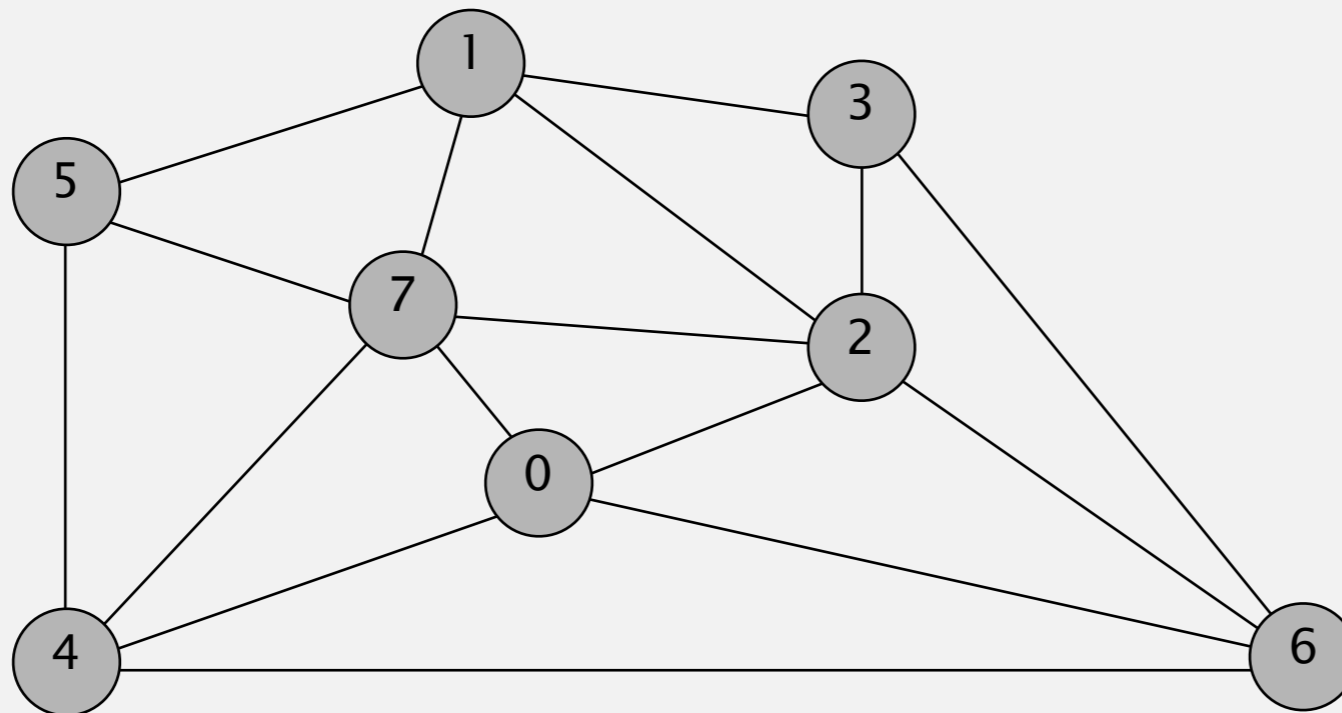
**Lazy solution.** Maintain a PQ of **edges** with (at least) one endpoint in  $T$ .

- Key = edge; priority = weight of edge.
- DELETE-MIN to determine next edge  $e = v-w$  to add to  $T$ .
- If both endpoints  $v$  and  $w$  are marked (both in  $T$ ), disregard.
- Otherwise, let  $w$  be the unmarked vertex (not in  $T$ ):
  - add  $e$  to  $T$  and mark  $w$
  - add to PQ any edge incident to  $w$  (assuming other endpoint not in  $T$ )



# Prim's algorithm: lazy implementation demo

- Start with vertex 0 and greedily grow tree  $T$ .
- Add to  $T$  the min weight edge with exactly one endpoint in  $T$ .
- Repeat until  $V - 1$  edges.



an edge-weighted graph

0-7	0.16
2-3	0.17
1-7	0.19
0-2	0.26
5-7	0.28
1-3	0.29
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4-7	0.37
0-4	0.38
6-2	0.40
3-6	0.52
6-0	0.58
6-4	0.93

# Prim's algorithm: lazy implementation

```
public class LazyPrimMST
{
    private boolean[] marked;    // MST vertices
    private Queue<Edge> mst;      // MST edges
    private MinPQ<Edge> pq;      // PQ of edges

    public LazyPrimMST(WeightedGraph G)
    {
        pq = new MinPQ<Edge>();
        mst = new Queue<Edge>();
        marked = new boolean[G.V()];
        visit(G, 0);

        while (!pq.isEmpty() && mst.size() < G.V() - 1)
        {
            Edge e = pq.delMin();
            int v = e.either(), w = e.other(v);
            if (marked[v] && marked[w]) continue;
            mst.enqueue(e);
            if (!marked[v]) visit(G, v);
            if (!marked[w]) visit(G, w);
        }
    }
}
```

← assume G is connected

← repeatedly delete the  
min weight edge  $e = v-w$  from PQ

← ignore if both endpoints in T

← add edge e to tree

← add either v or w to tree

# Prim's algorithm: lazy implementation

---

```
private void visit(WeightedGraph G, int v)
{
    marked[v] = true;
    for (Edge e : G.adj(v))
        if (!marked[e.other(v)])
            pq.insert(e);
}
```

```
public Iterable<Edge> mst()
{ return mst; }
```


← add v to T

← for each edge  $e = v-w$ , add to PQ if w not already in T

# Lazy Prim's algorithm: running time

---

**Proposition.** Lazy Prim's algorithm computes the MST in time proportional to  $E \log E$  and extra space proportional to  $E$  (in the worst case).

 minor defect

Pf.

operation	frequency	binary heap
DELETE-MIN	$E$	$\log E$
INSERT	$E$	$\log E$

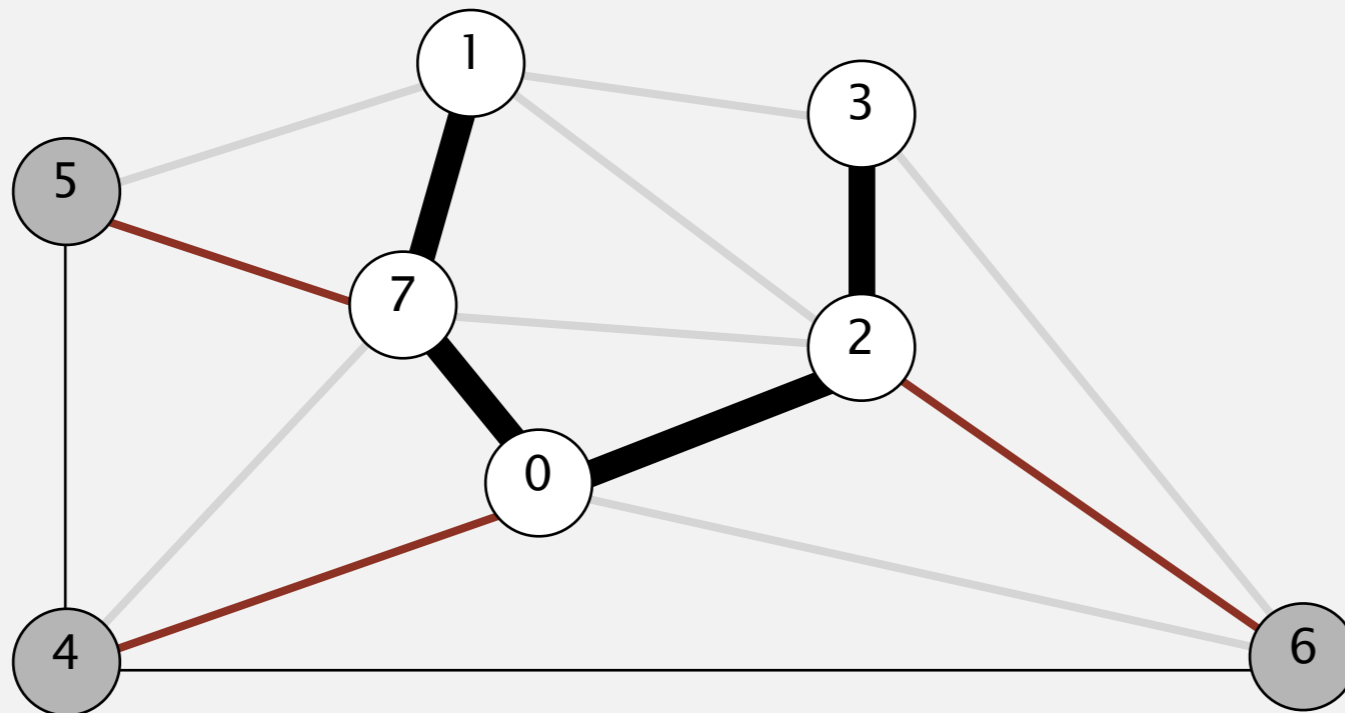
# Prim's algorithm: eager implementation

---

**Challenge.** Find min weight edge with exactly one endpoint in  $T$ .

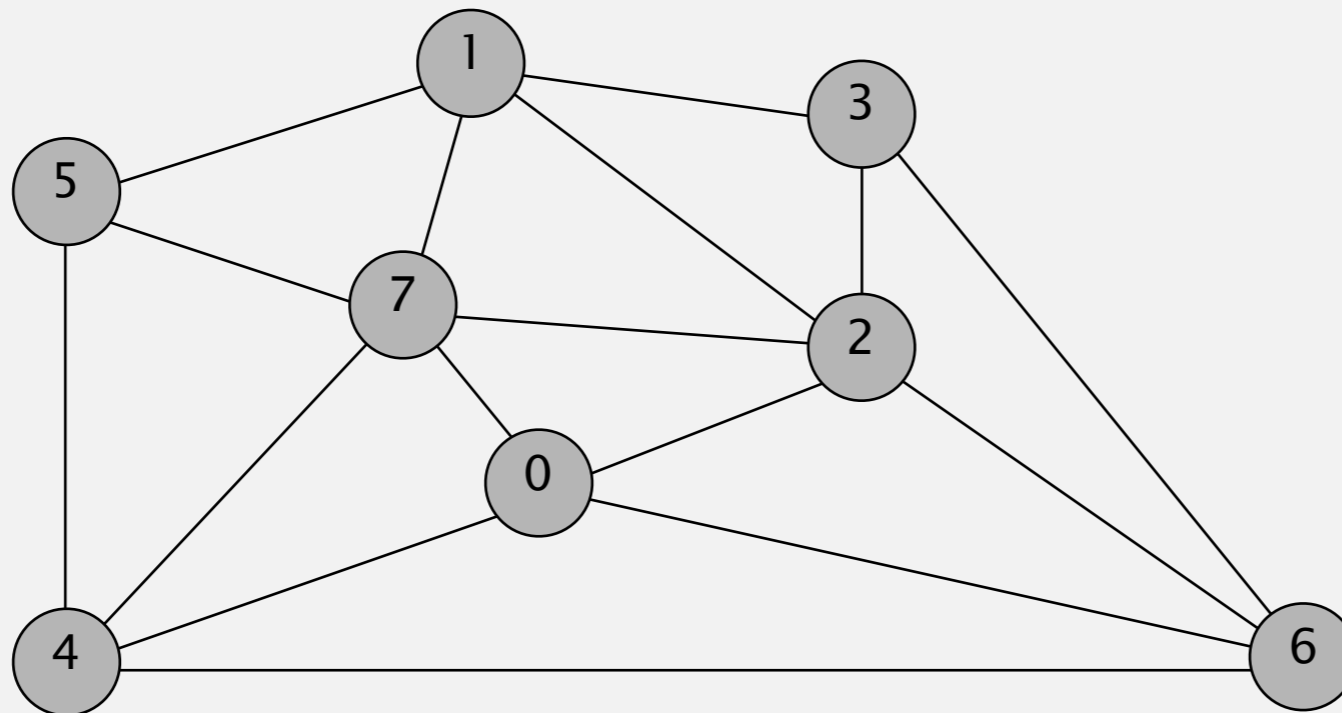
**Observation.** For each vertex  $v$ , need only **lightest** edge connecting  $v$  to  $T$ .

- MST includes at most one edge connecting  $v$  to  $T$ . Why?
- If MST includes such an edge, it must take lightest such edge. Why?



# Prim's algorithm: eager implementation demo

- Start with vertex 0 and greedily grow tree  $T$ .
- Add to  $T$  the min weight edge with exactly one endpoint in  $T$ .
- Repeat until  $V - 1$  edges.

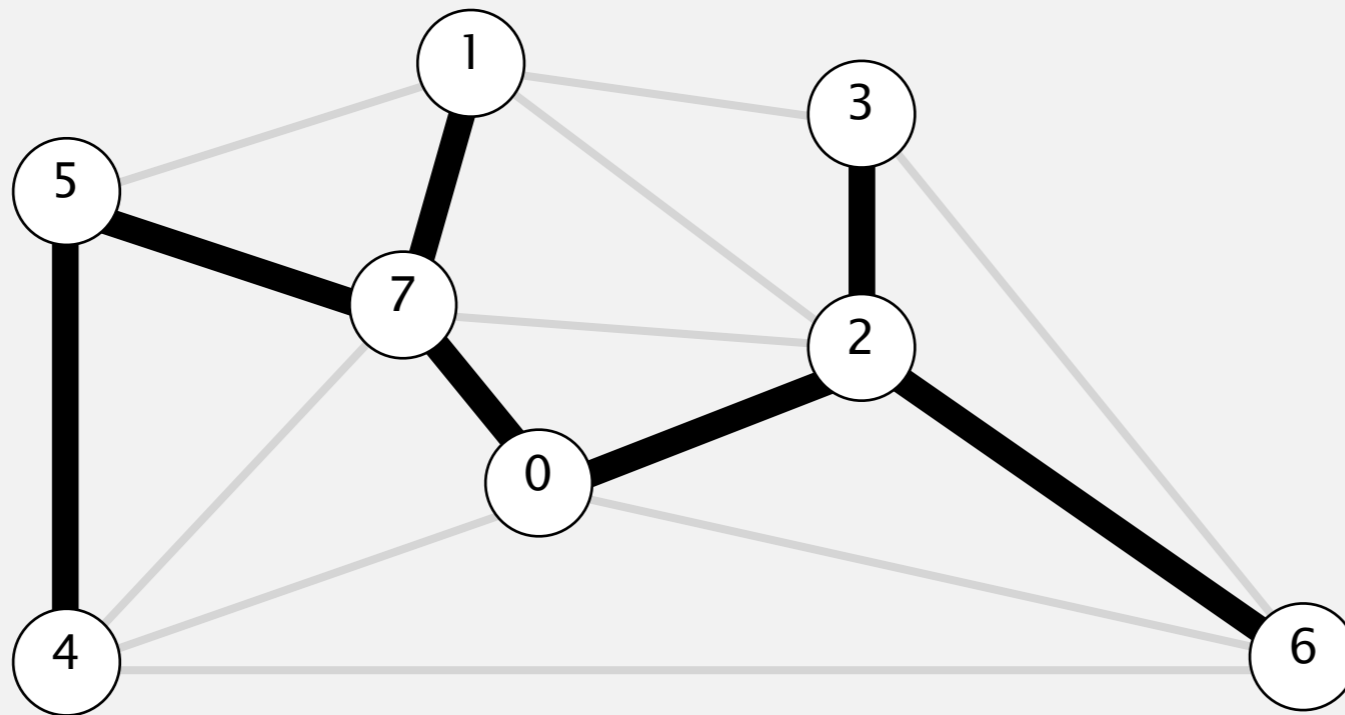


an edge-weighted graph

0-7	0.16
2-3	0.17
1-7	0.19
0-2	0.26
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0-4	0.38
6-2	0.40
3-6	0.52
6-0	0.58
6-4	0.93

# Prim's algorithm: eager implementation demo

- Start with vertex 0 and greedily grow tree  $T$ .
- Add to  $T$  the min weight edge with exactly one endpoint in  $T$ .
- Repeat until  $V - 1$  edges.



**MST edges**

0-7 1-7 0-2 2-3 5-7 4-5 6-2

v	edgeTo[]	distTo[]
0	-	-
7	0-7	0.16
1	1-7	0.19
2	0-2	0.26
3	2-3	0.17
5	5-7	0.28
4	4-5	0.35
6	6-2	0.40

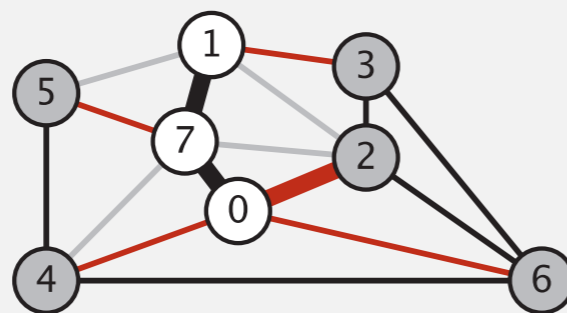
# Prim's algorithm: eager implementation

**Challenge.** Find min weight edge with exactly one endpoint in  $T$ .

↙ PQ has at most one entry per vertex

**Eager solution.** Maintain a PQ of **vertices** connected by an edge to  $T$ , where priority of vertex  $v$  = weight of lightest edge connecting  $v$  to  $T$ .

- Delete min vertex  $v$ ; add its associated edge  $e = v-w$  to  $T$ .
- Update PQ by considering all edges  $e = v-x$  incident to  $v$ 
  - ignore if  $x$  is already in  $T$
  - add  $x$  to PQ if not already on it
  - **decrease priority** of  $x$  if  $v-x$  becomes lightest edge connecting  $x$  to  $T$



0  
1 1-7 0.19  
2 0-2 0.26  
3 1-3 0.29  
4 0-4 0.38  
5 5-7 0.28  
6 6-0 0.58  
7 0-7 0.16

← red: on PQ


↑  
black: on MST

# Indexed priority queue

---

Associate an index between 0 and  $n - 1$  with each key in a priority queue.

- Insert a key associated with a given index.
- Delete a minimum key and return associated index.
- **Decrease the key** associated with a given index.

for Prim's algorithm:  $n = V$ ,  
index = vertex, key = weight

```
public class IndexMinPQ<Key extends Comparable<Key>>
```

```
    IndexMinPQ(int n)
```

*create indexed PQ with indices 0, 1, ...,  $n - 1$*

```
    void insert(int i, Key key)
```

*associate key with index i*

```
    int delMin()
```

*remove a minimal key and return its associated index*

```
    void decreaseKey(int i, Key key)
```

*decrease the key associated with index i*

```
    boolean contains(int i)
```

*is i an index on the priority queue?*

```
    boolean isEmpty()
```

*is the priority queue empty?*

```
    int size()
```

*number of keys in the priority queue*

# Indexed priority queue: implementation

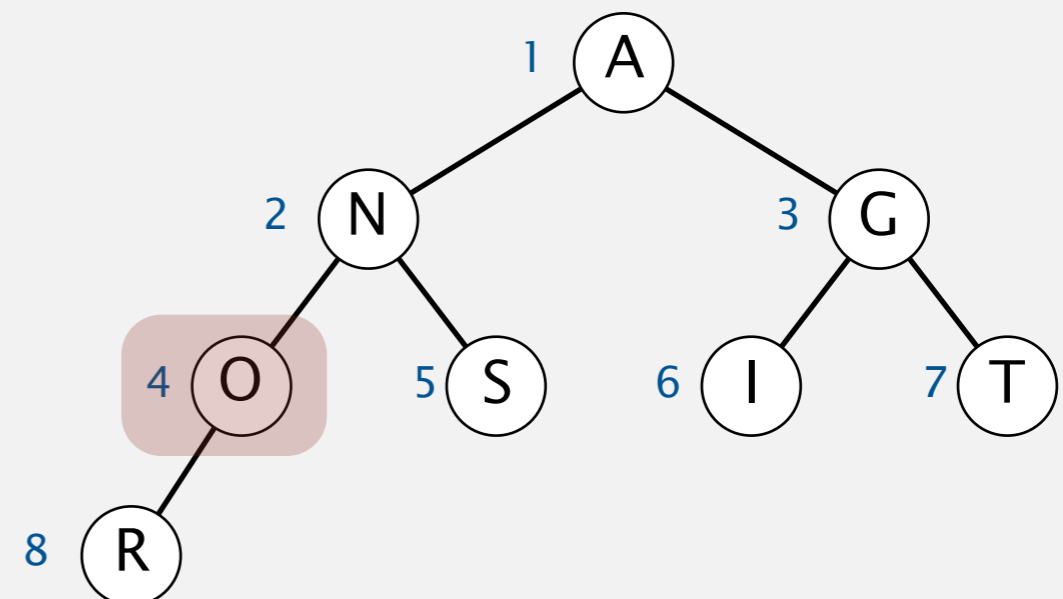
Binary heap implementation. [see Section 2.4 of textbook]

- Start with same code as MinPQ.
- Maintain parallel arrays so that:
  - $\text{keys}[i]$  is the priority of vertex  $i$
  - $\text{qp}[i]$  is the heap position of vertex  $i$
  - $\text{pq}[i]$  is the index of the key in heap position  $i$
- Use  $\text{swim}(\text{qp}[i])$  to implement  $\text{decreaseKey}(i, \text{key})$ .

$i$	0	1	2	3	4	5	6	7	8
$\text{keys}[i]$	A	S	0	R	T	I	N	G	-
$\text{qp}[i]$	1	5	4	8	7	6	2	3	-
$\text{pq}[i]$	-	0	6	7	2	1	5	4	3

vertex 2 is at  
heap index 4

decrease key of vertex 2 to C



# Prim's algorithm: which priority queue?

---

Depends on PQ implementation:  $V$  INSERT,  $V$  DELETE-MIN,  $\leq E$  DECREASE-KEY.

PQ implementation	INSERT	DELETE-MIN	DECREASE-KEY	total
unordered array	1	$V$	1	$V^2$
binary heap	$\log V$	$\log V$	$\log V$	$E \log V$
d-way heap	$\log_d V$	$d \log_d V$	$\log_d V$	$E \log_{E/V} V$
Fibonacci heap	$1^\dagger$	$\log V^\dagger$	$1^\dagger$	$E + V \log V$

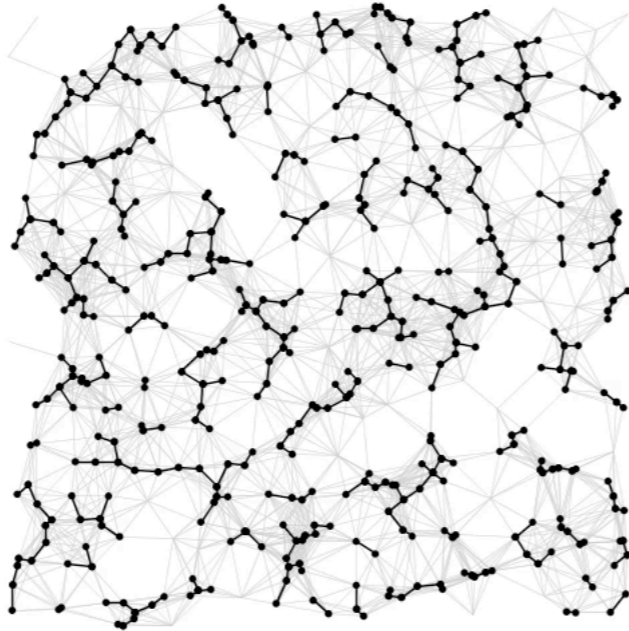
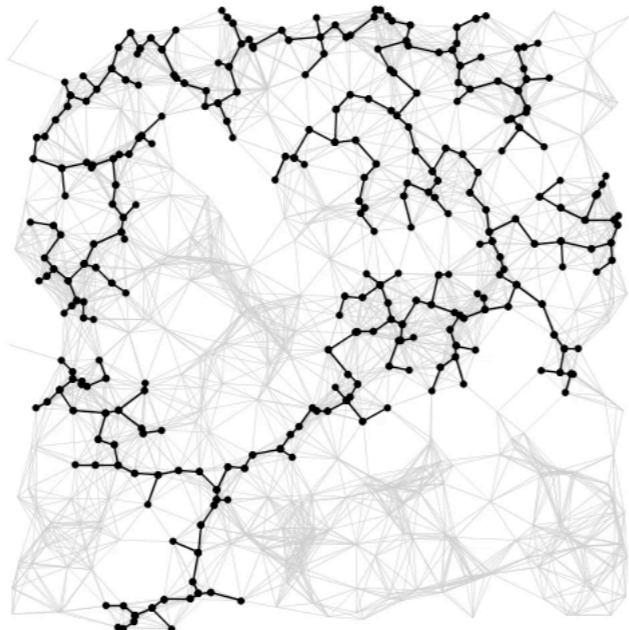
$^\dagger$  amortized

## Bottom line.

- Array implementation optimal for complete graphs.
- Binary heap much faster for sparse graphs.
- 4-way heap worth the trouble in performance-critical situations.
- Fibonacci heap best in theory, but not worth implementing.

# MST: algorithms of the day

---

algorithm	visualization	bottleneck	running time
Kruskal		sorting union-find	$E \log V$
Prim		priority queue	$E \log V$