

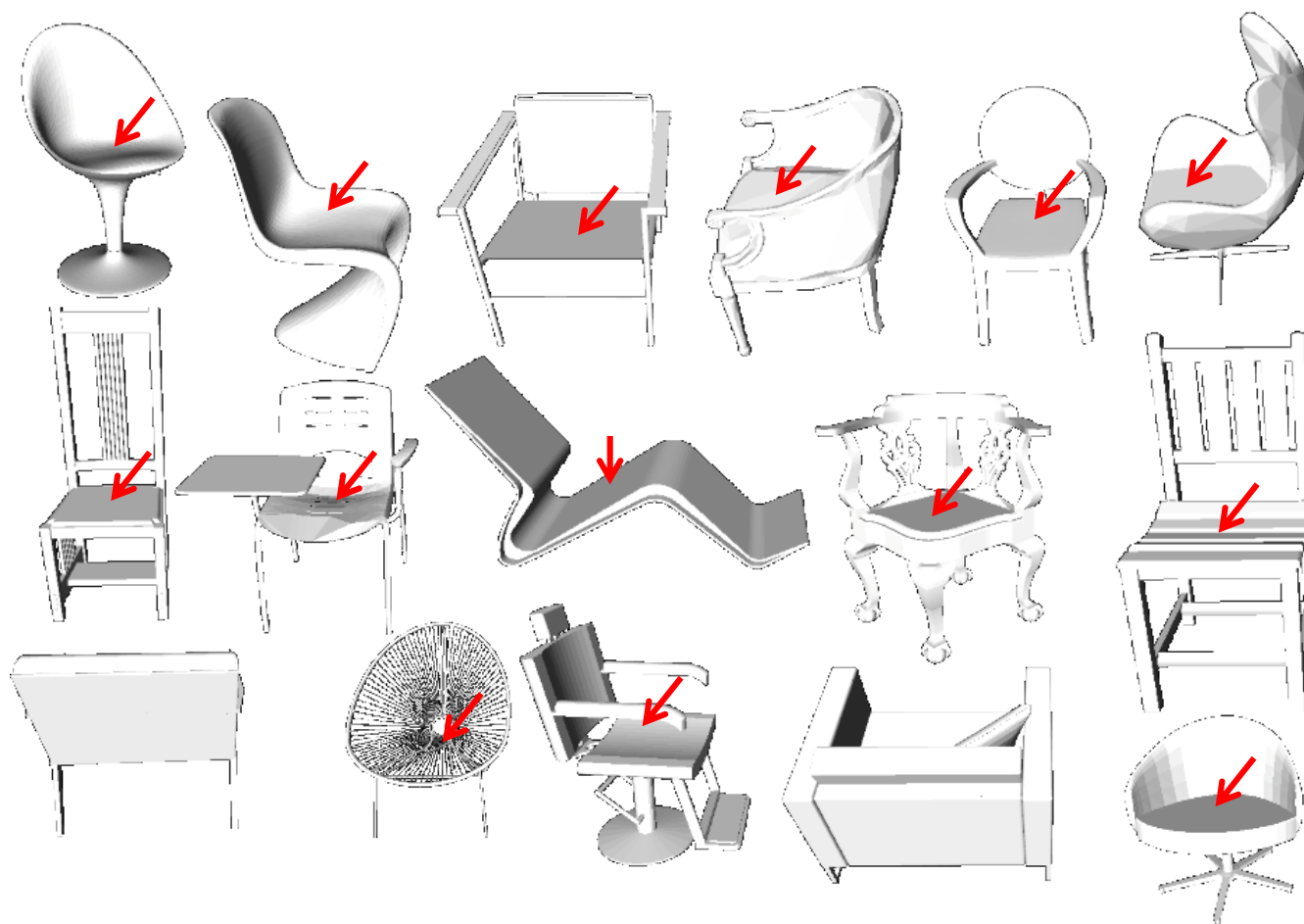


# **Finding Surface Correspondences With Shape Analysis**

Thomas Funkhouser  
COS 526, Fall 2016

# Motivation

Finding surface correspondences is important for understanding relationships in 3D data



# Motivation

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## Applications:

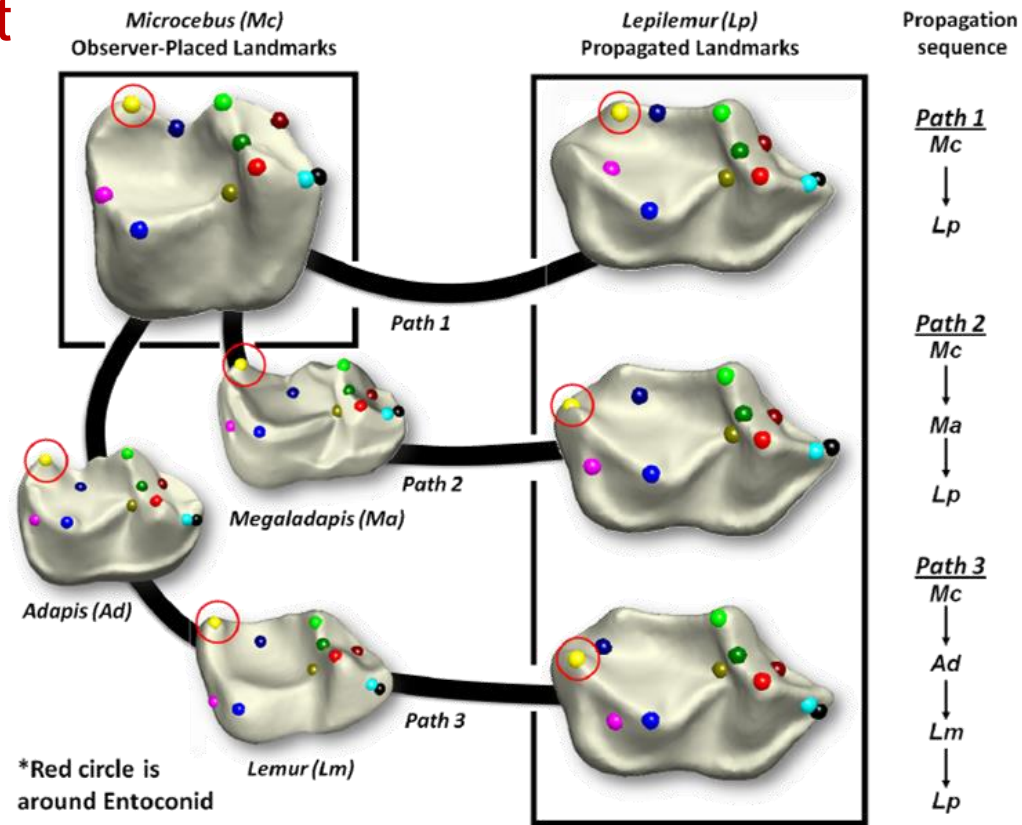
- Similarity measurement
- Collection exploration
- Surface interpolation
- Annotation transfer
- Surface registration
- Symmetry detection
- Saliency estimation
- Object recognition
- Visualization
- etc.

# Motivation

## Applications:

### ➤ Similarity measurement

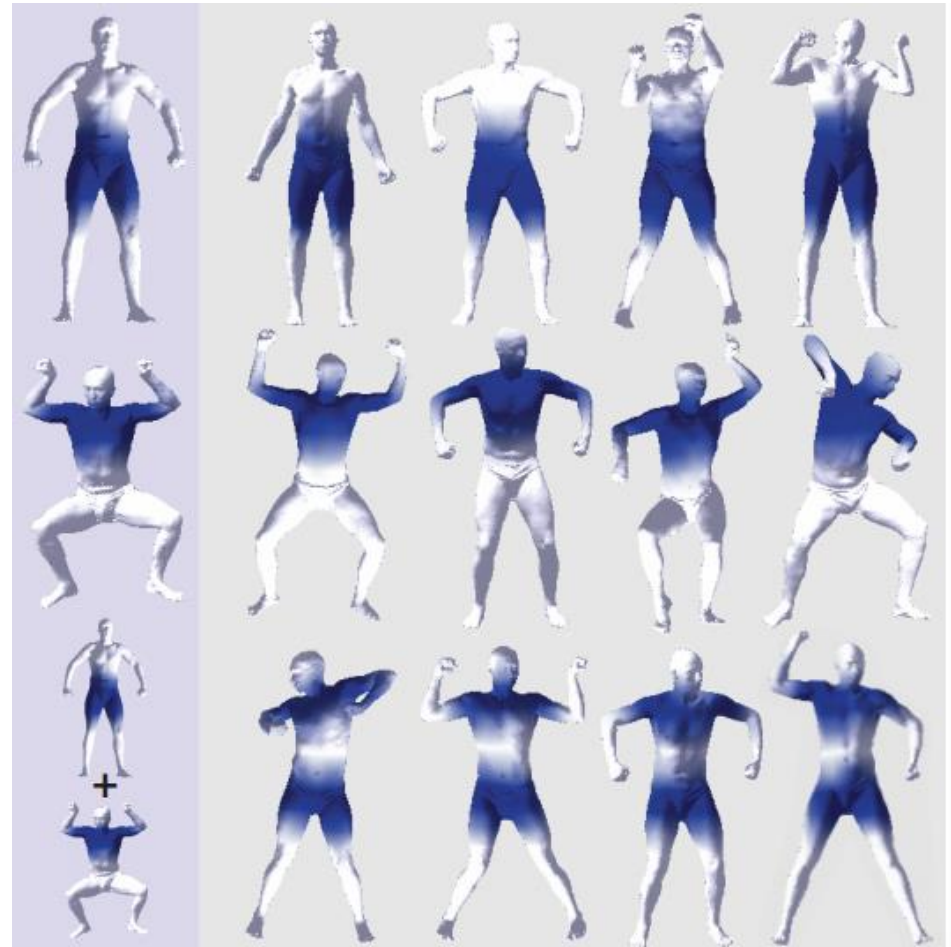
- Collection exploration
- Surface interpolation
- Annotation transfer
- Surface registration
- Symmetry detection
- Saliency estimation
- Object recognition
- Visualization
- etc.



# Motivation

## Applications:

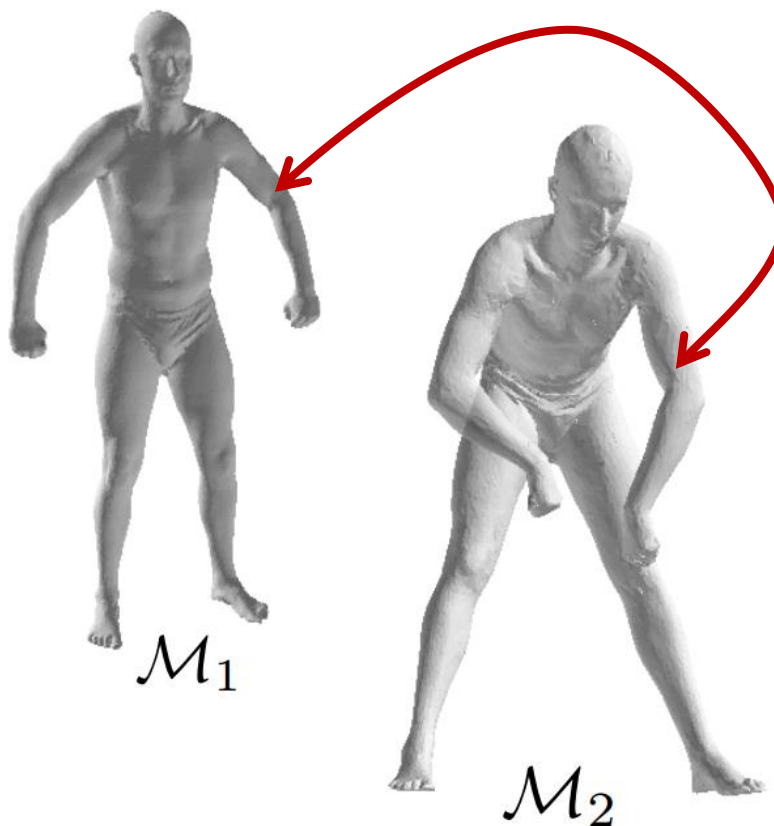
- Similarity measurement
- **Collection exploration**
- Surface interpolation
- Annotation transfer
- Surface registration
- Symmetry detection
- Saliency estimation
- Object recognition
- Visualization
- etc.



# Goal

Develop algorithms to find point correspondences

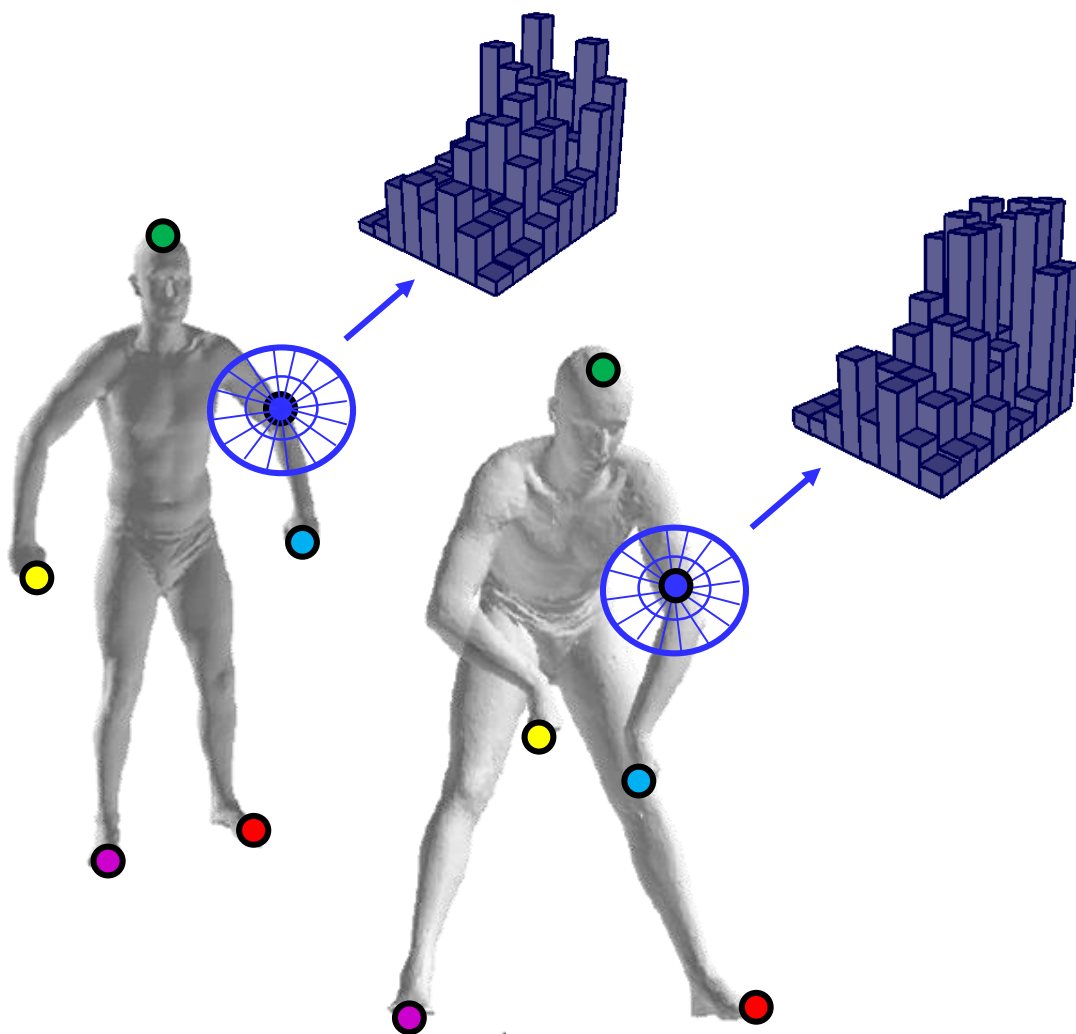
- Align “equivalent” features (semantic, functional, etc.)
- Consistent
- Robust
- Automatic
- Efficient



# Previous Work

Classical methods:

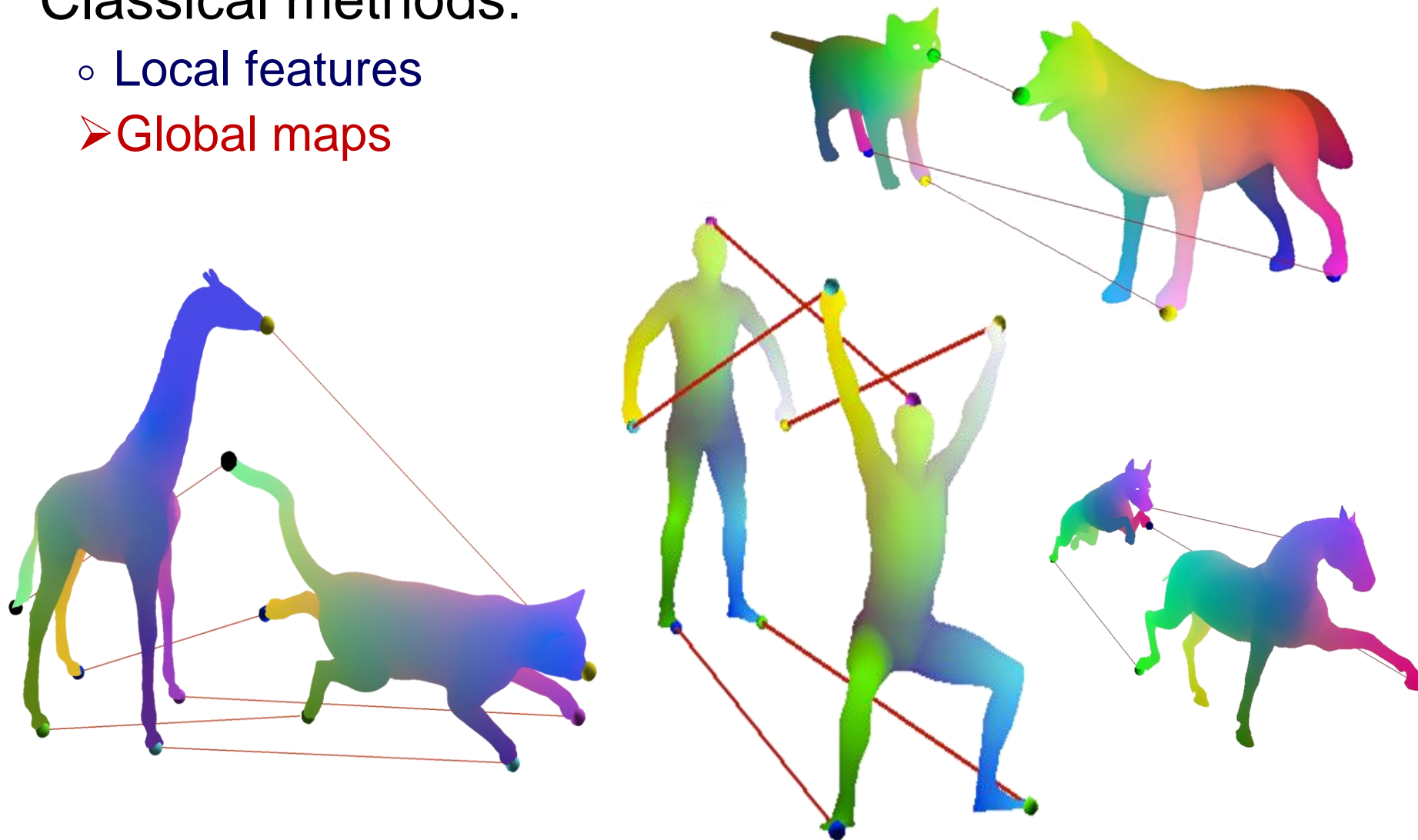
- Local features
- Global maps



# Previous Work

Classical methods:

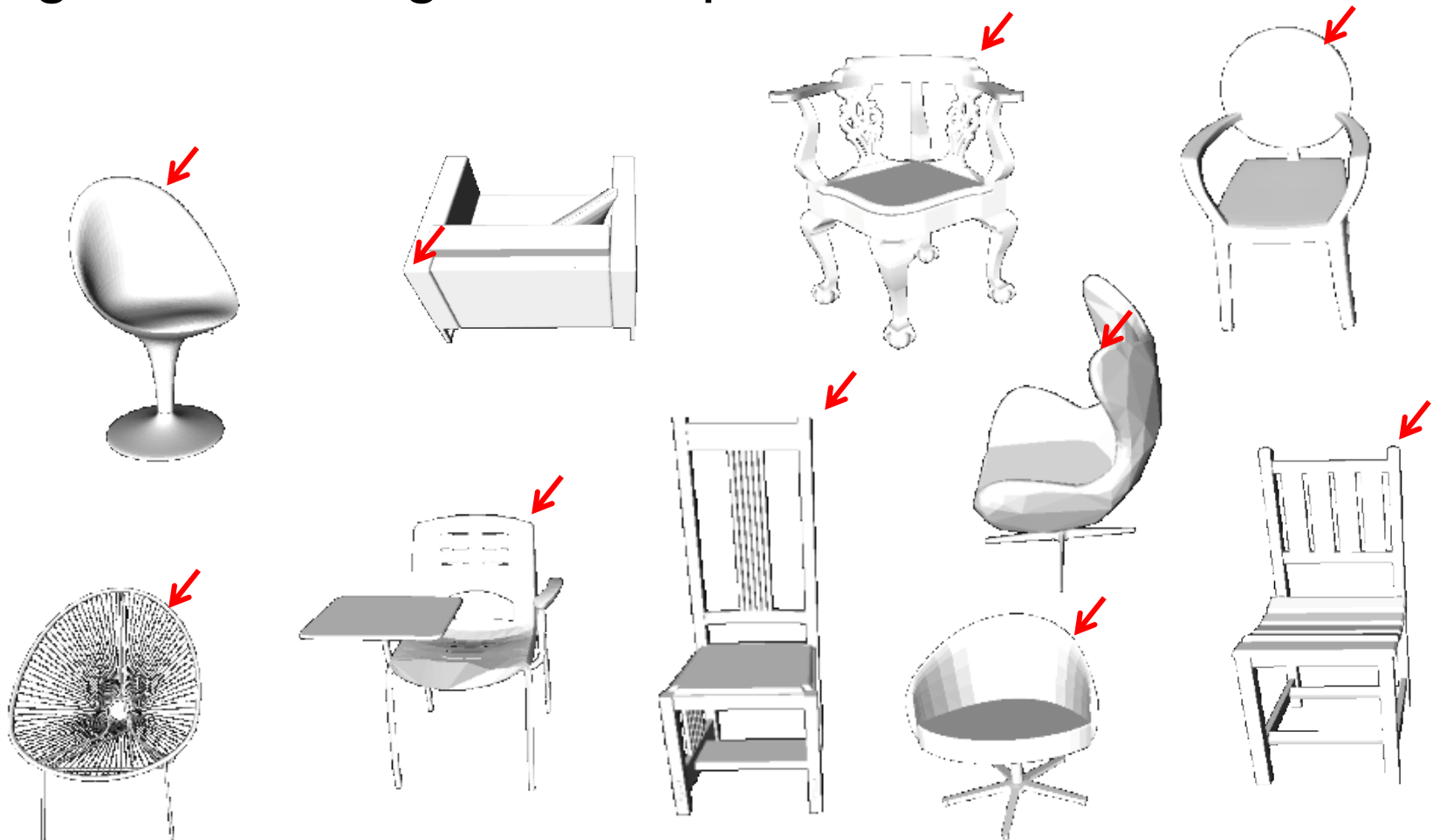
- Local features
- Global maps





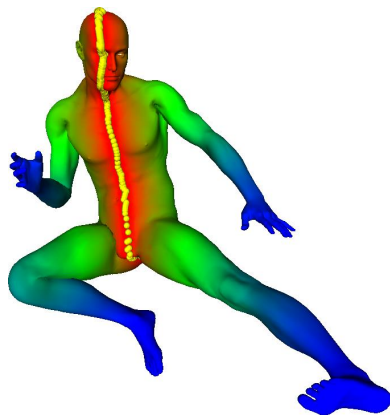
# Challenge

Classical methods don't work well for shapes with large local and global shape differences

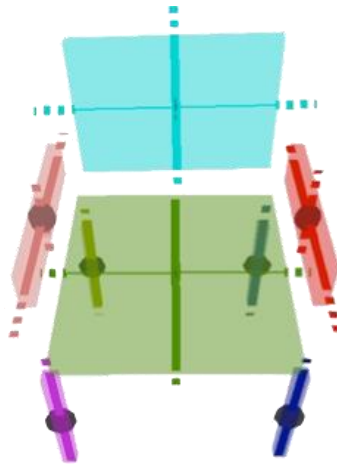


# Hypothesis

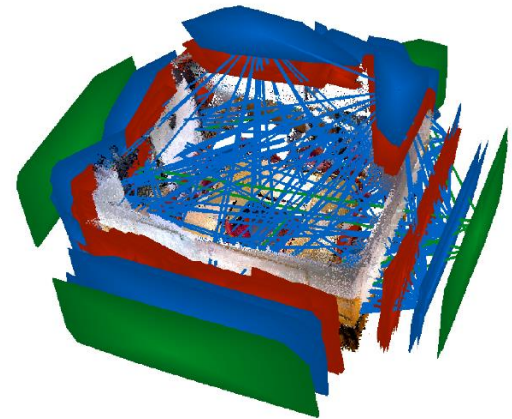
Discovering latent structure can be helpful for finding surface correspondences



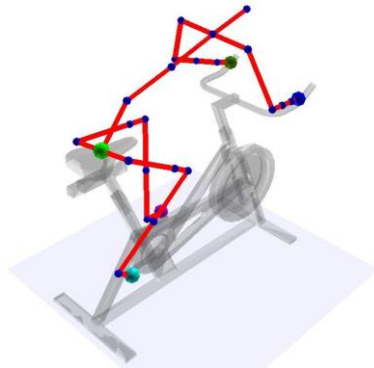
Symmetries



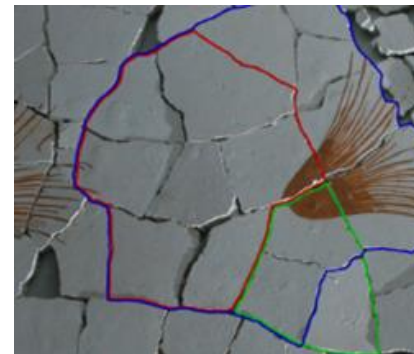
Parts



Constraints



Affordances



Assemblies

# Outline of Talk

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Introduction

Latent structures

- Symmetries
- Parts
- Affordances
- Constraints
- Assemblies

Conclusion

# Outline of Talk

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Introduction

Latent structures

➤ Symmetries

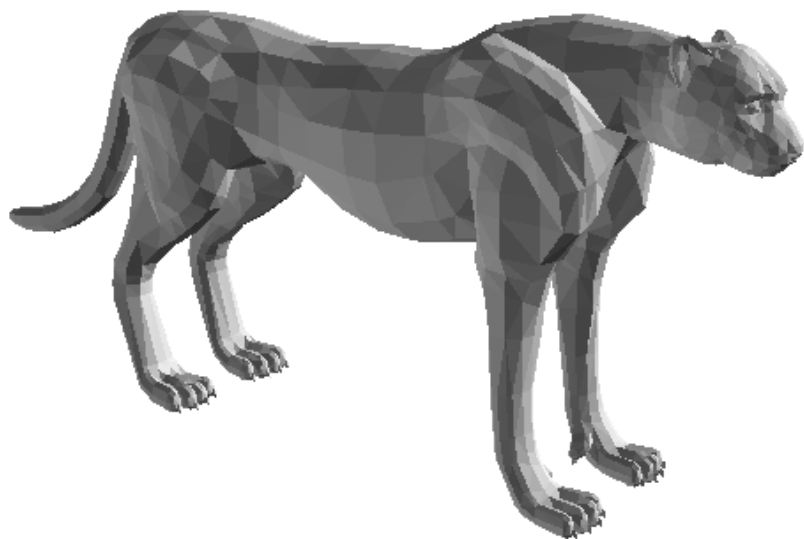
- Parts
- Affordances
- Constraints
- Assemblies

Conclusion

# Symmetry-Aware Correspondences

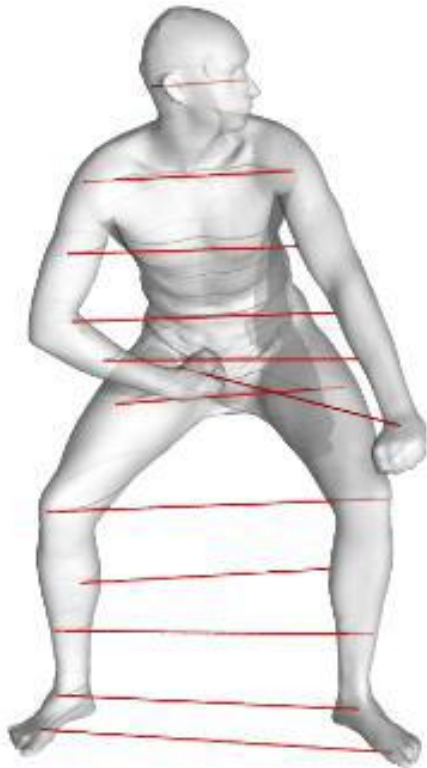
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Observation 1: symmetry is ubiquitous in natural shapes



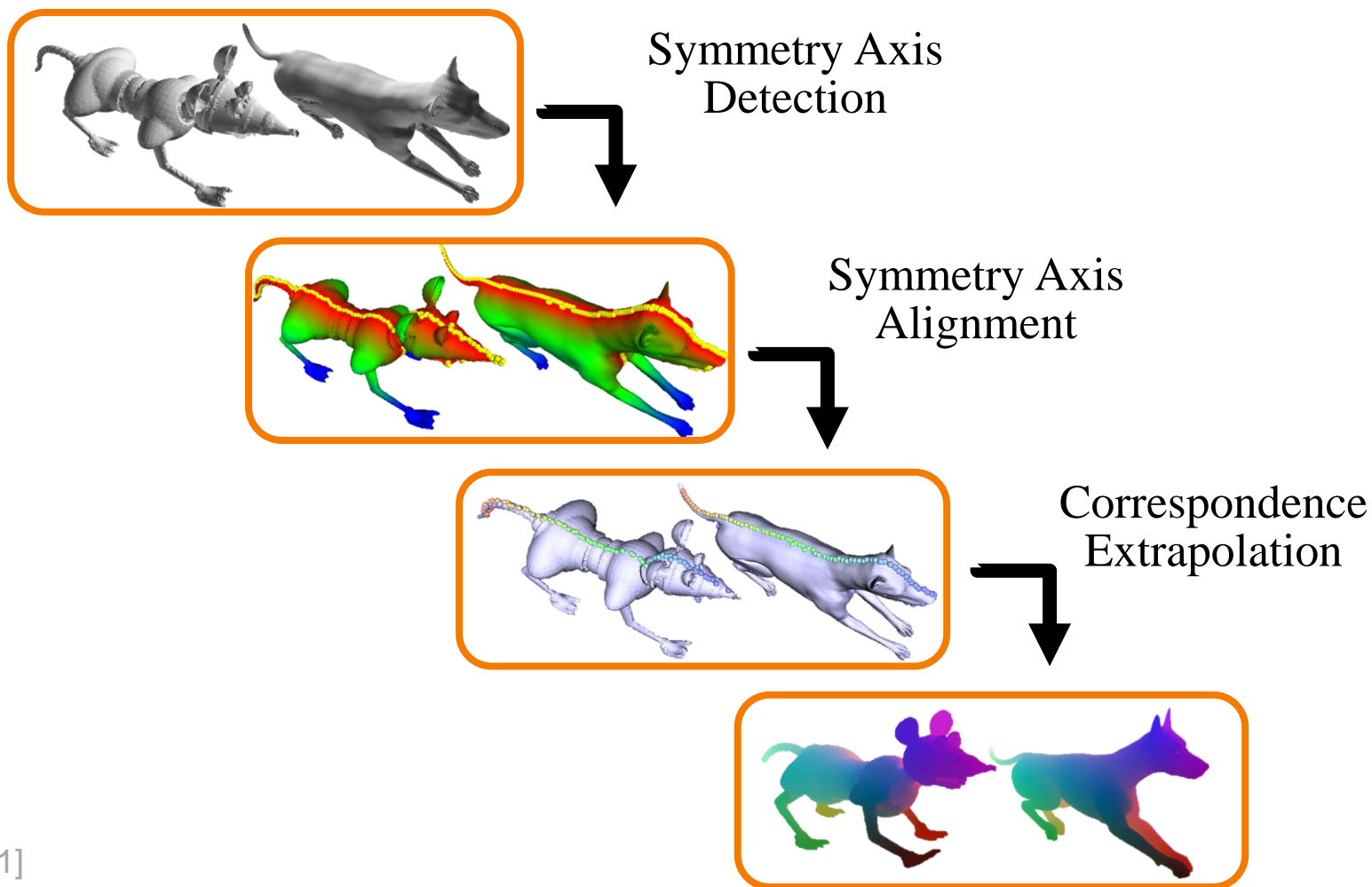
# Symmetry-Aware Correspondences

Observation 2: detecting symmetries is easier than finding correspondences



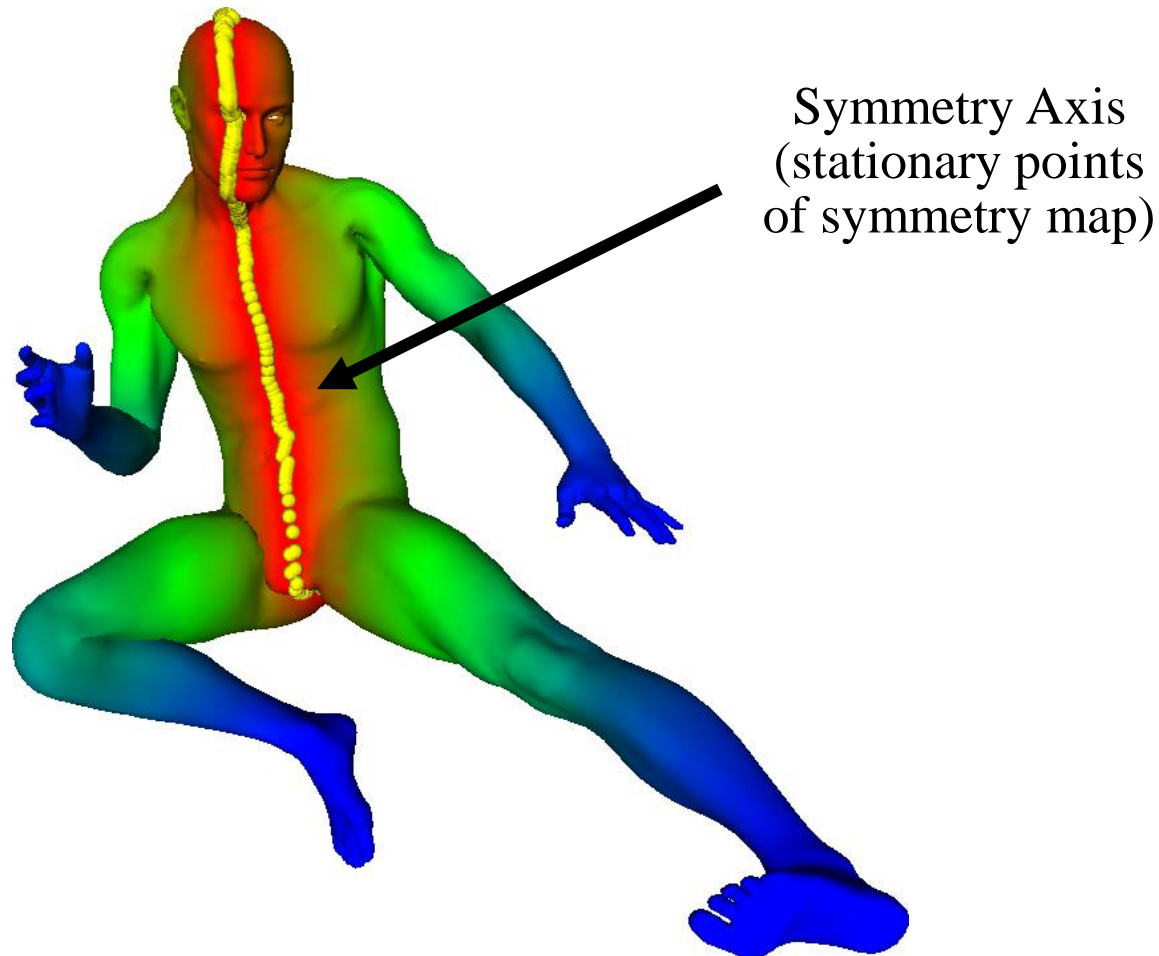
# Symmetry-Aware Correspondences

Approach: detect reflective symmetry axes and use them to find correspondences



# Symmetry Axis Detection

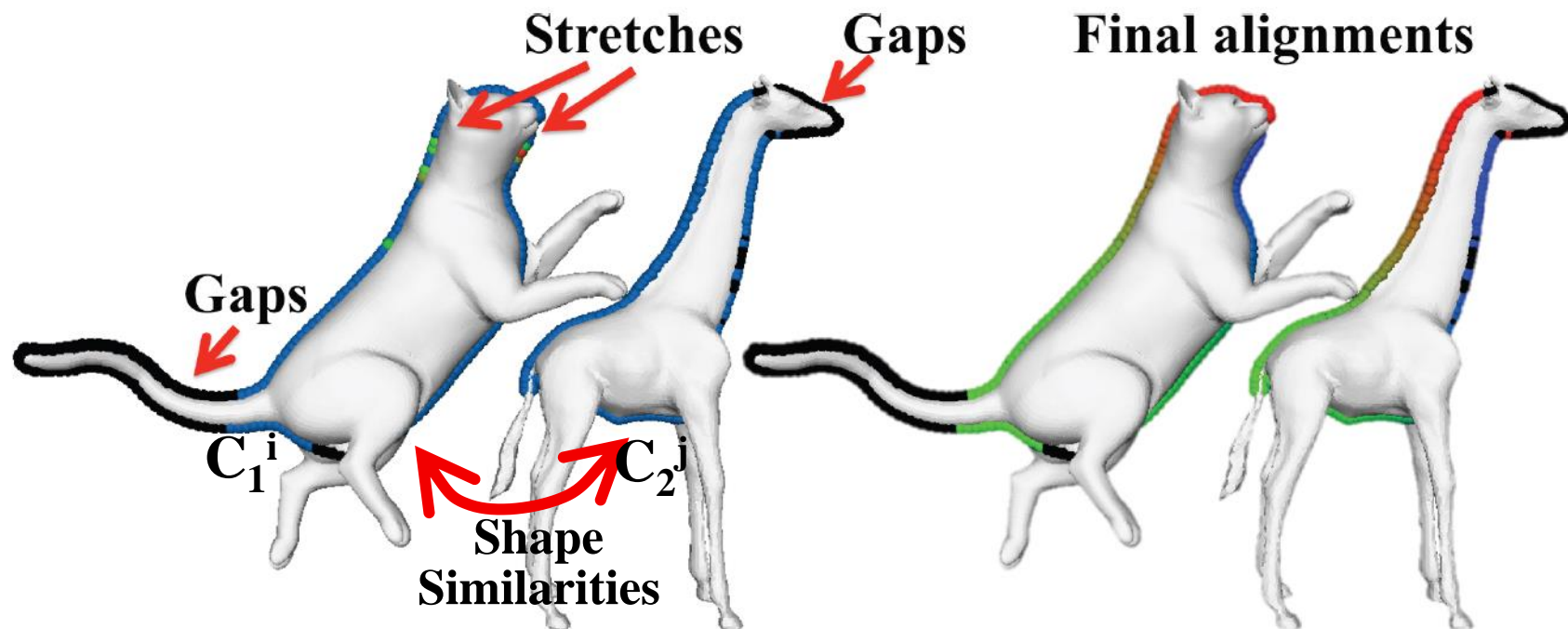
Given a mesh, extract potential symmetry axes





# Symmetry Axis Alignment

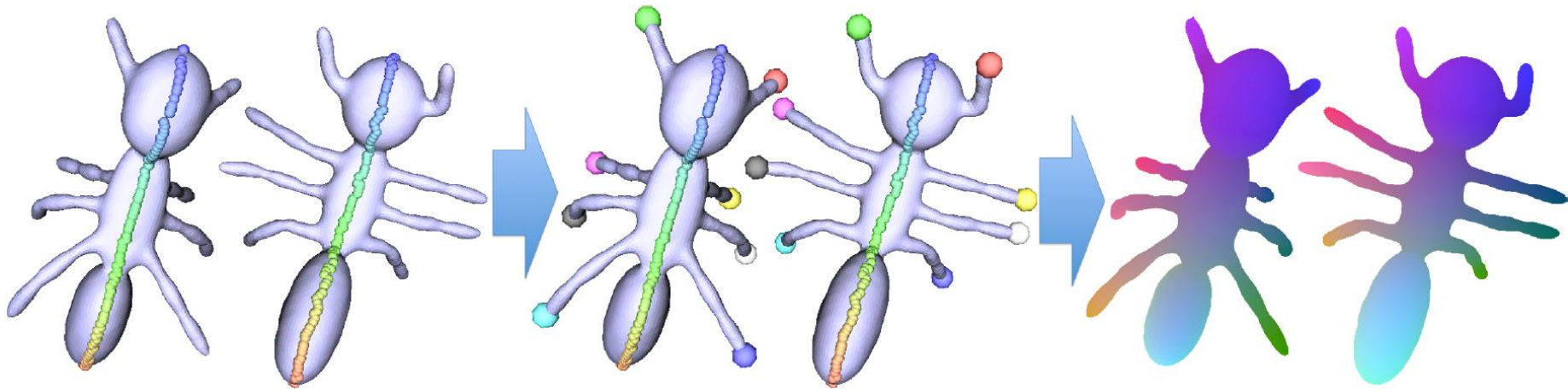
For every pair of symmetry axes, find optimal alignment for every pair of starting points



$$Q(C_1^i, C_2^j, c) = Q_{Axis}(C_1^i) \cdot Q_{Axis}(C_2^j) \cdot Q_{Align}(C_1^i, C_2^j, c)$$

# Correspondence Extrapolation

Given an alignment between symmetry axes, extrapolate correspondences to rest of surfaces



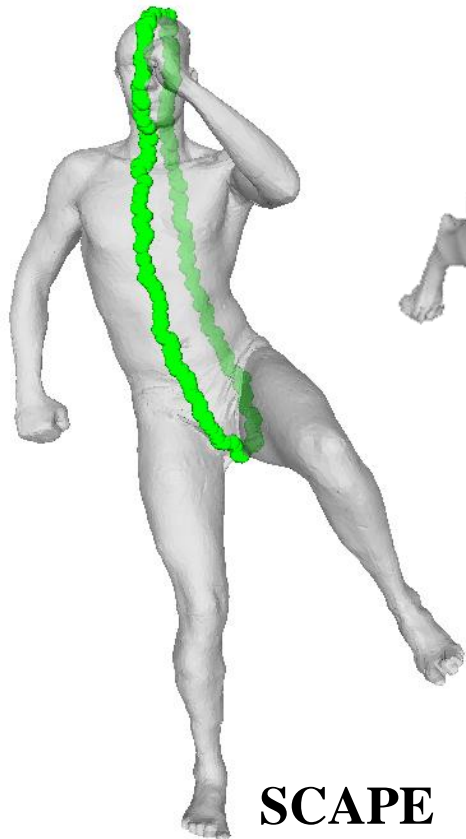
Aligned  
Symmetry Axes

Aligned Extremal  
Feature Points

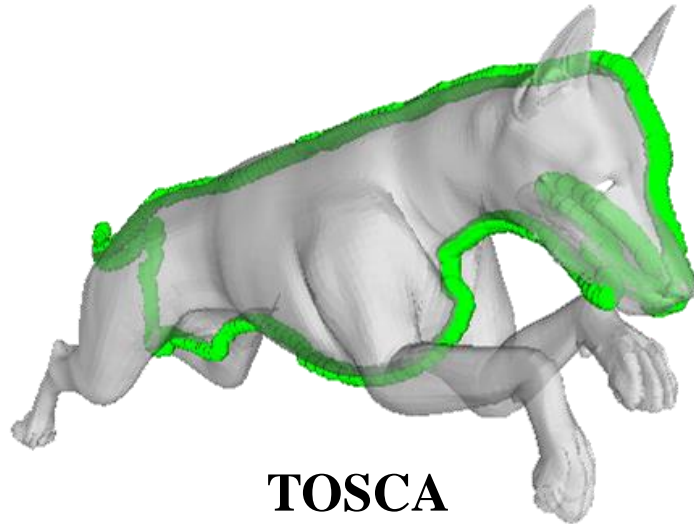
Full  
Surface Map

# Symmetry-Aware Correspondence Evaluation

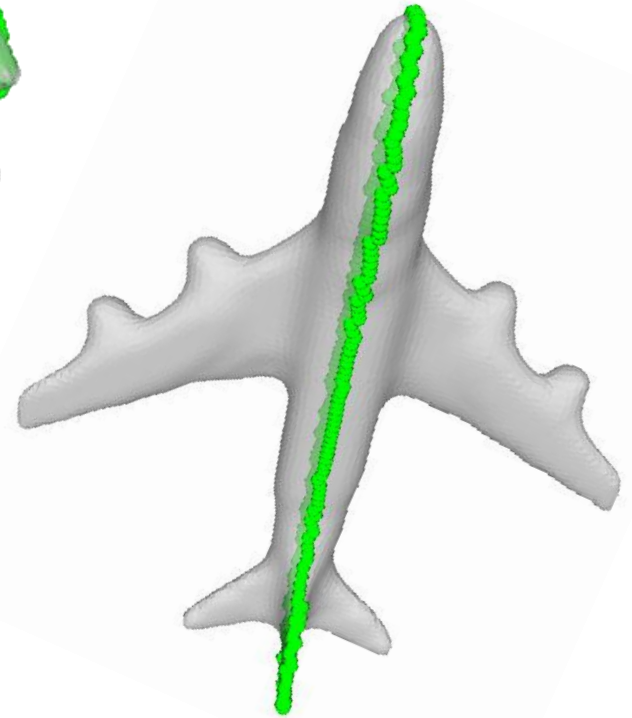
## Surface Correspondence Benchmark [Kim 2011]



**SCAPE**  
[Anguelov et al., 2004]



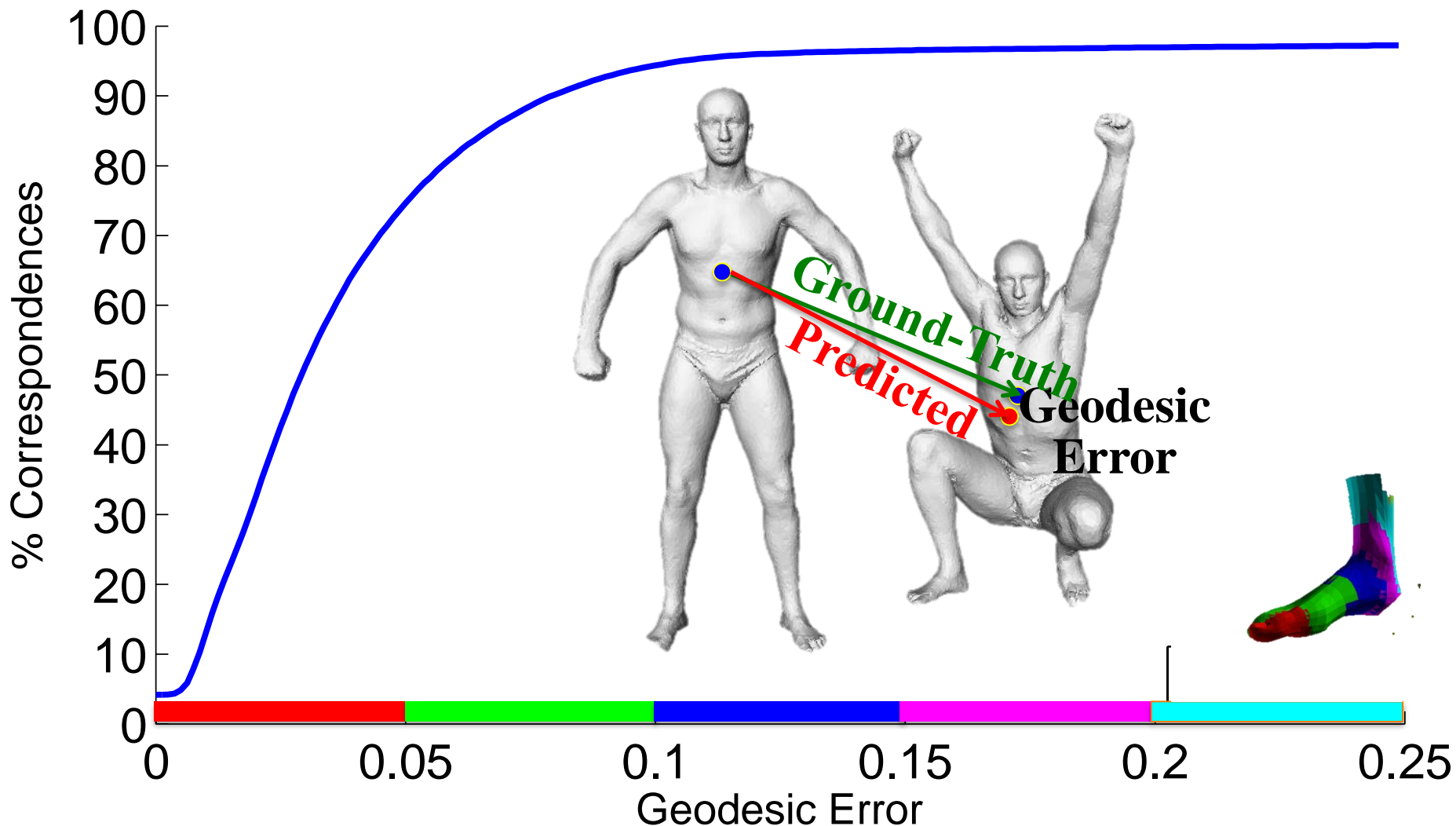
**TOSCA**  
[Bronstein et al., 2008]



**SHREC Watertight 2007**  
[Giorgi et al., 2007]

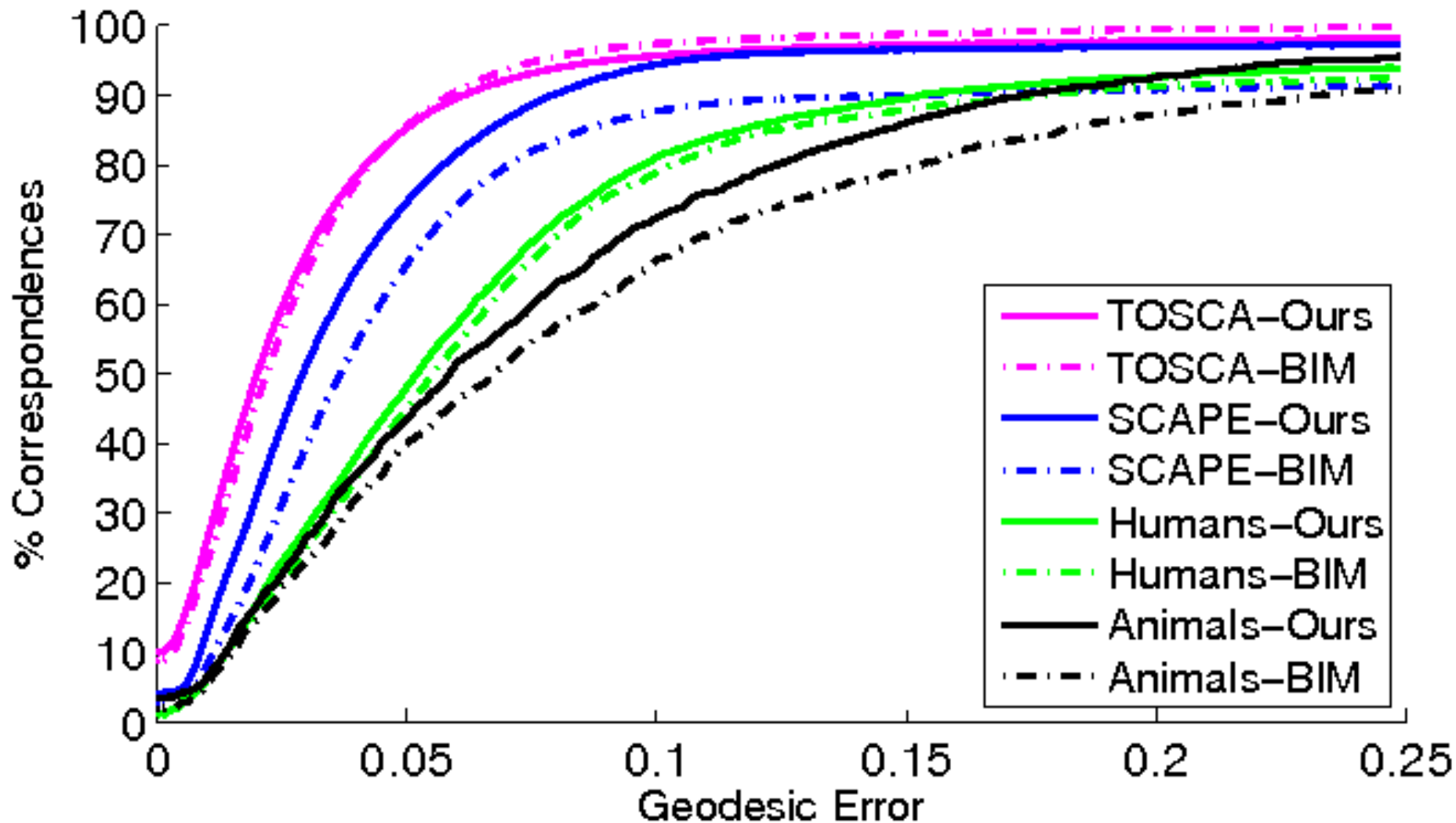
# Symmetry-Aware Correspondence Results

Evaluation methodology



# Symmetry-Aware Correspondence Results

Comparison to Blended Intrinsic Maps [Kim 2011]



# Outline of Talk

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Introduction

Latent structures

- Symmetries
- **Parts**
- Affordances
- Constraints
- Assemblies

Conclusion

# Part-Aware Correspondences

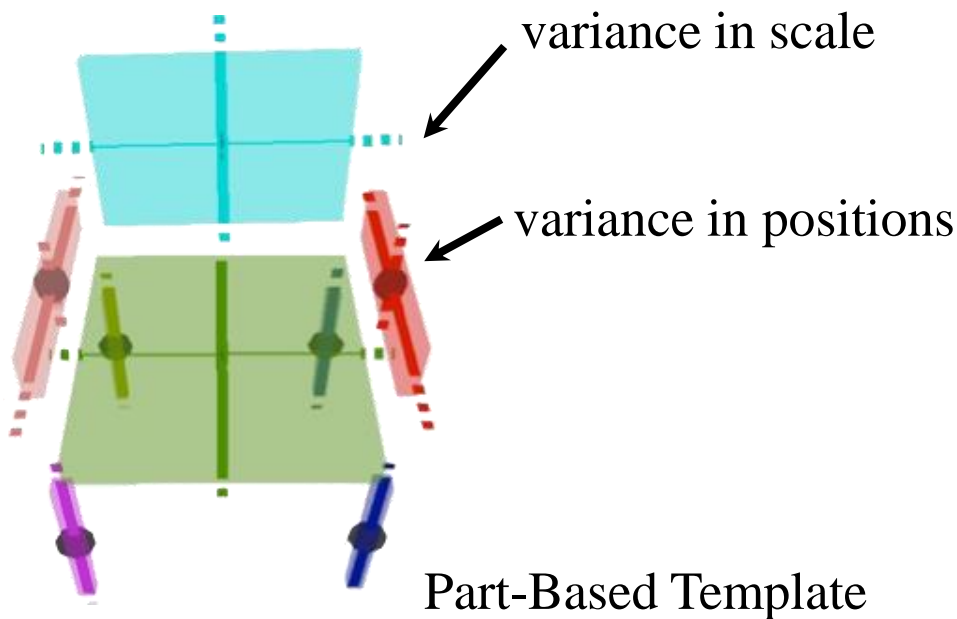
Observation: semantic correspondences are often based on parts



Consistent segmentation

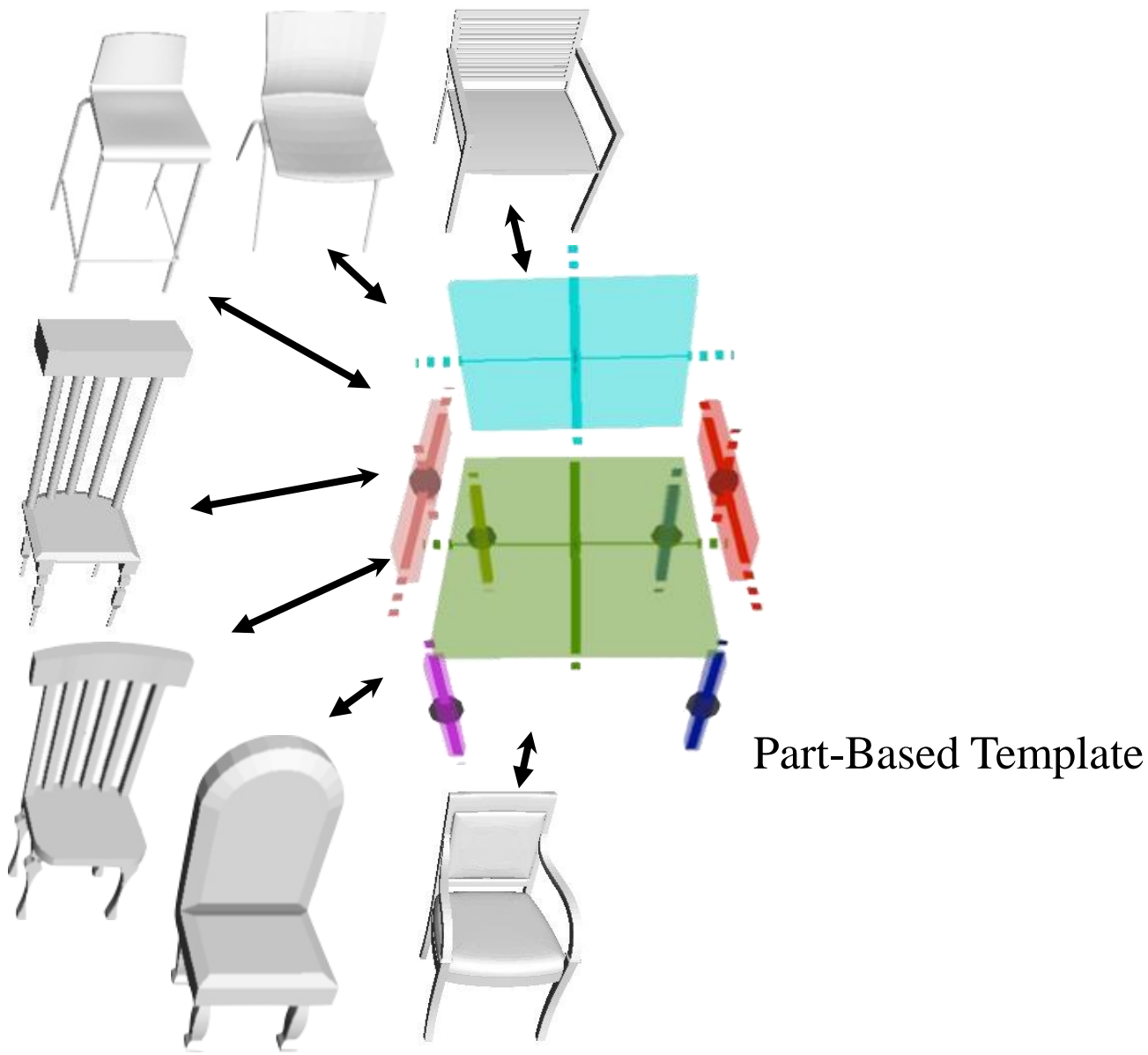
# Part-Aware Correspondences

Approach: learn part-based templates for collection of models and use them to find correspondences

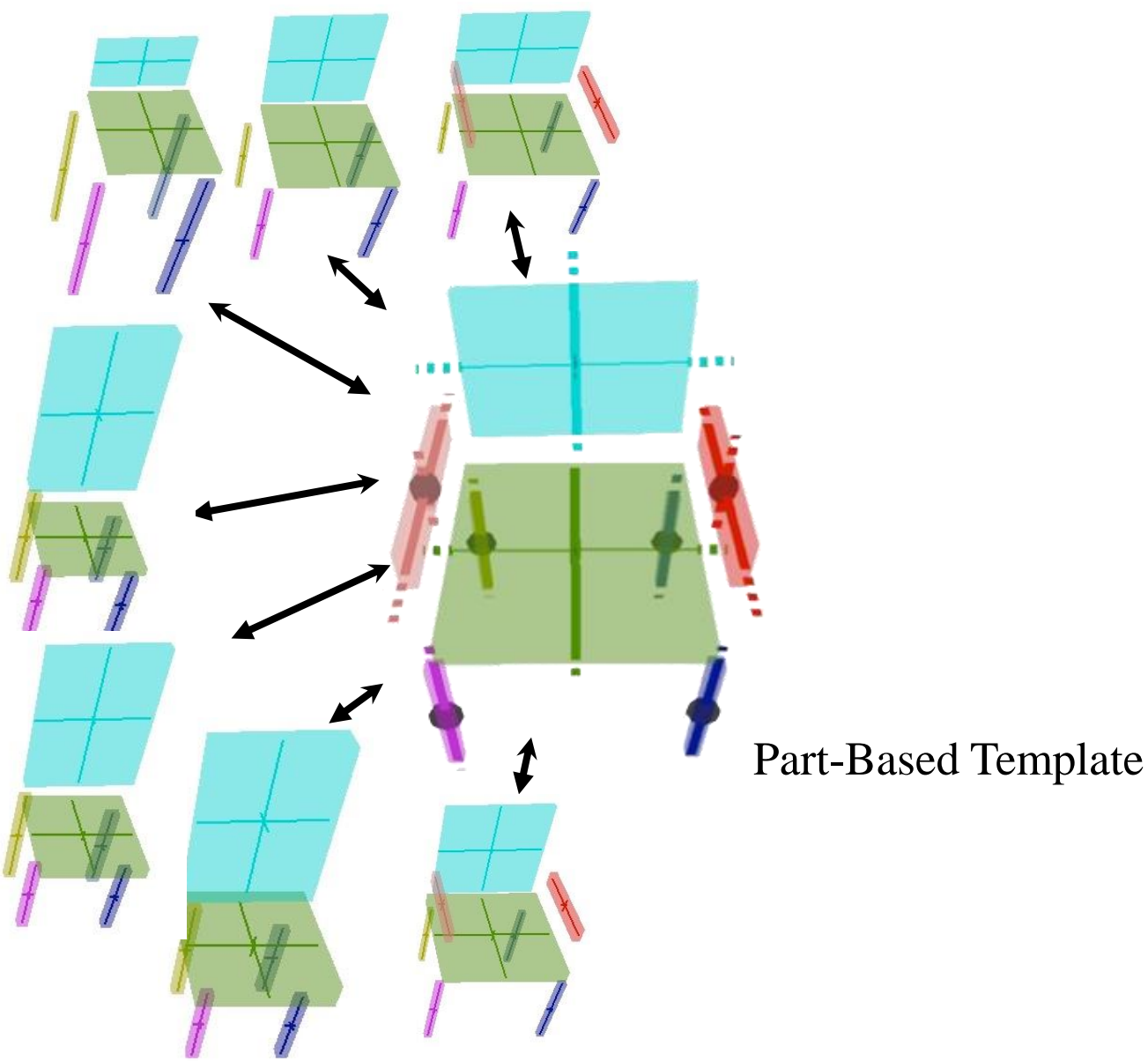




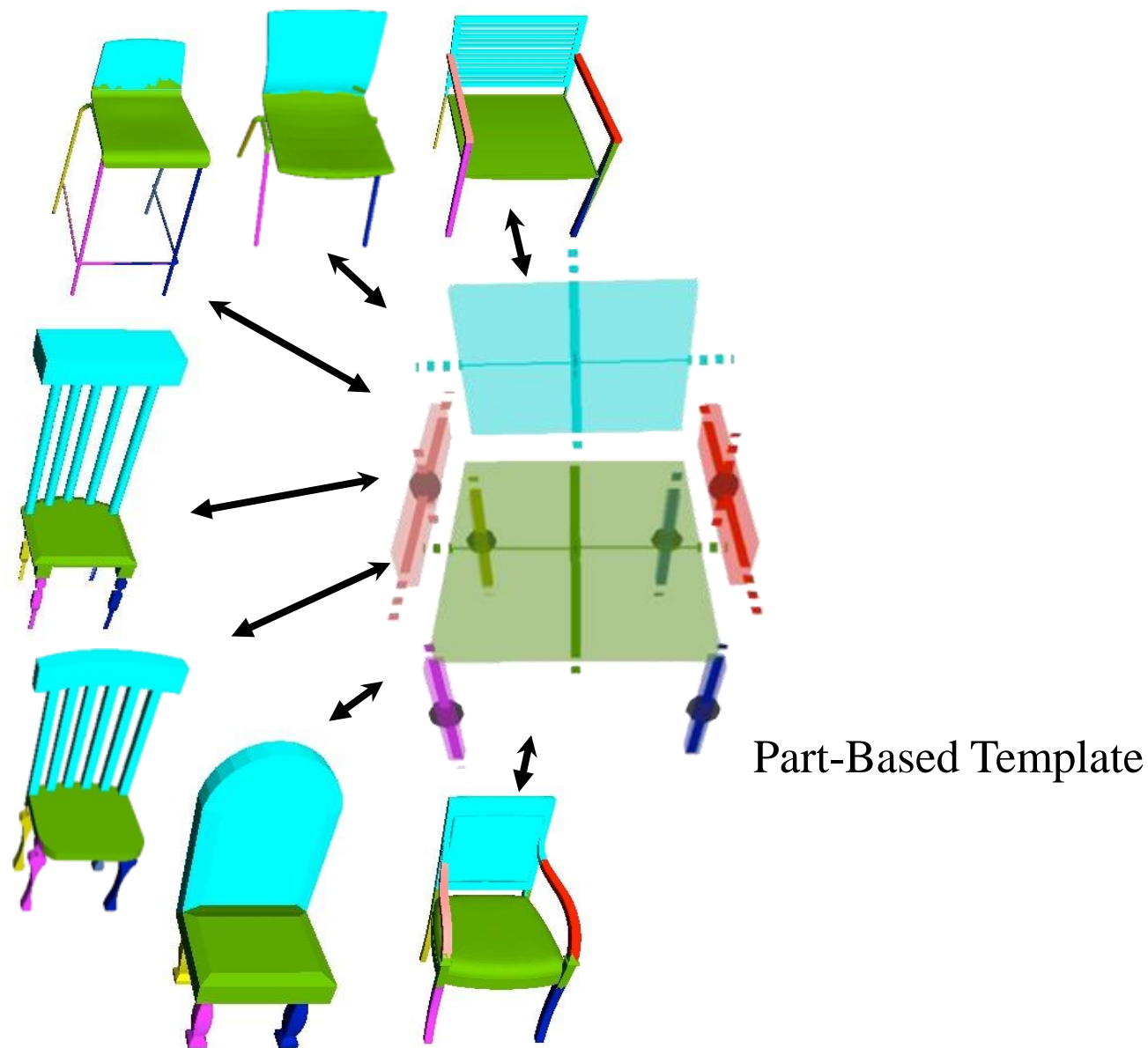
# Part-Aware Correspondences



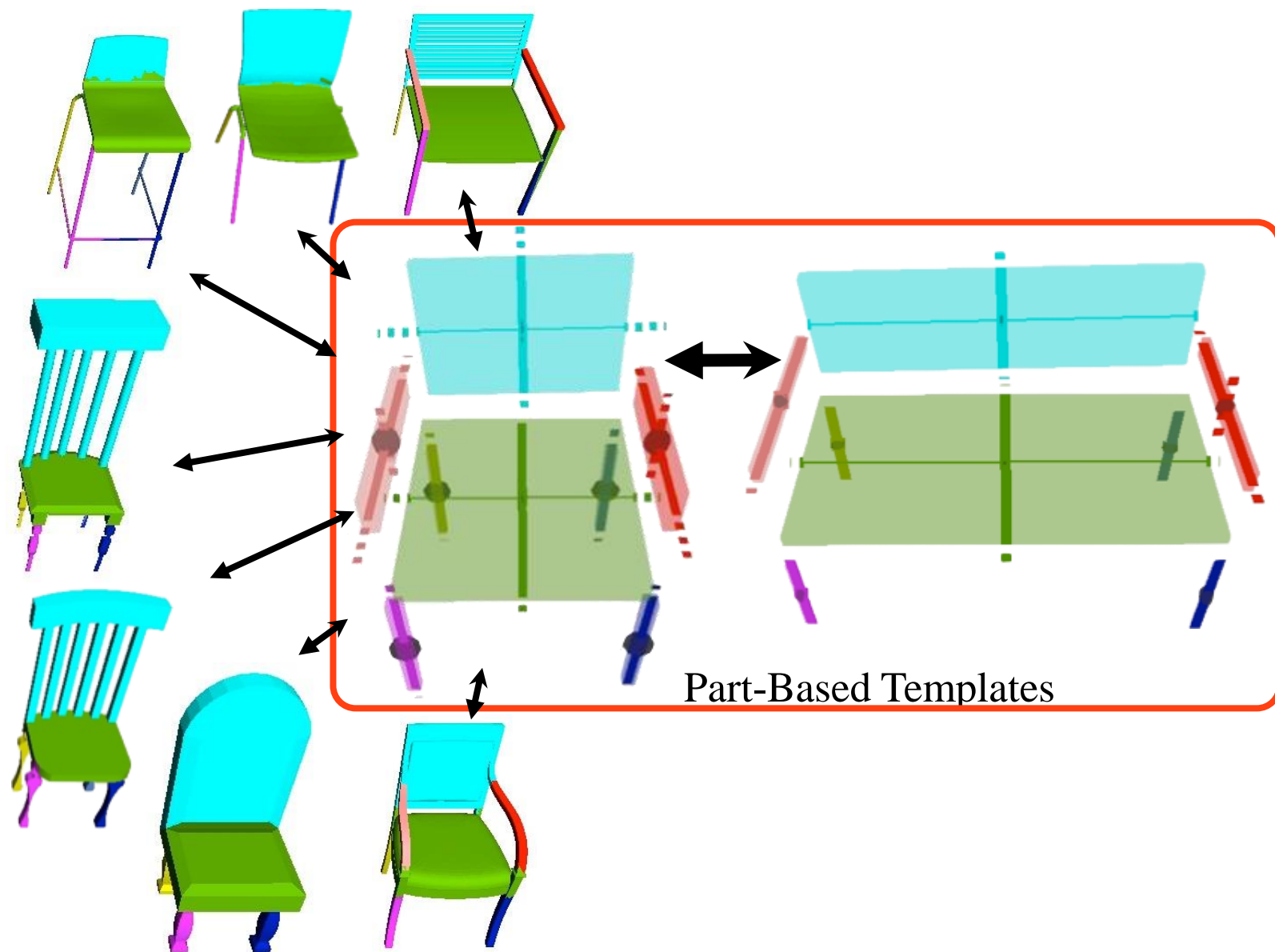
# Part-Aware Correspondences



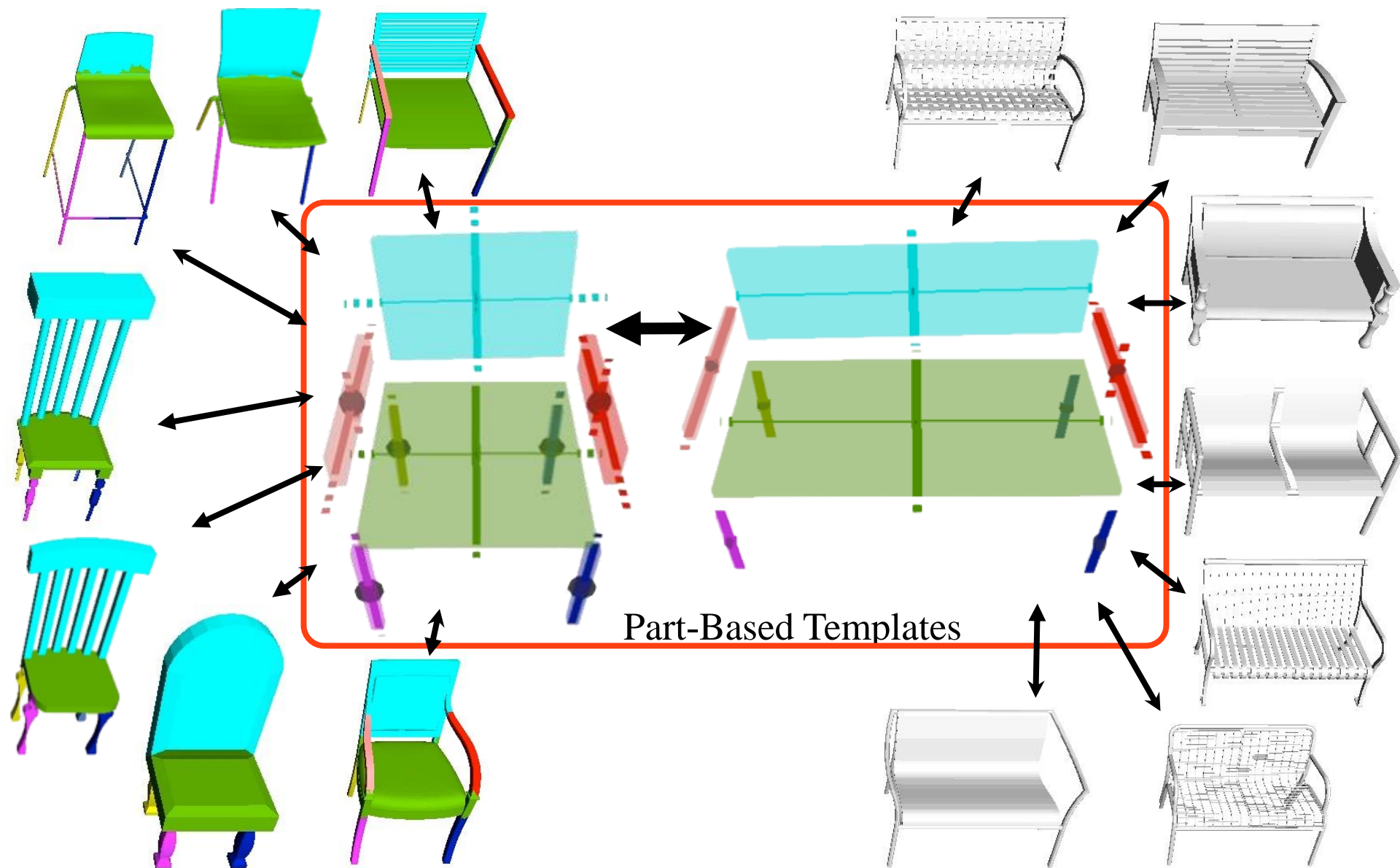
# Part-Aware Correspondences



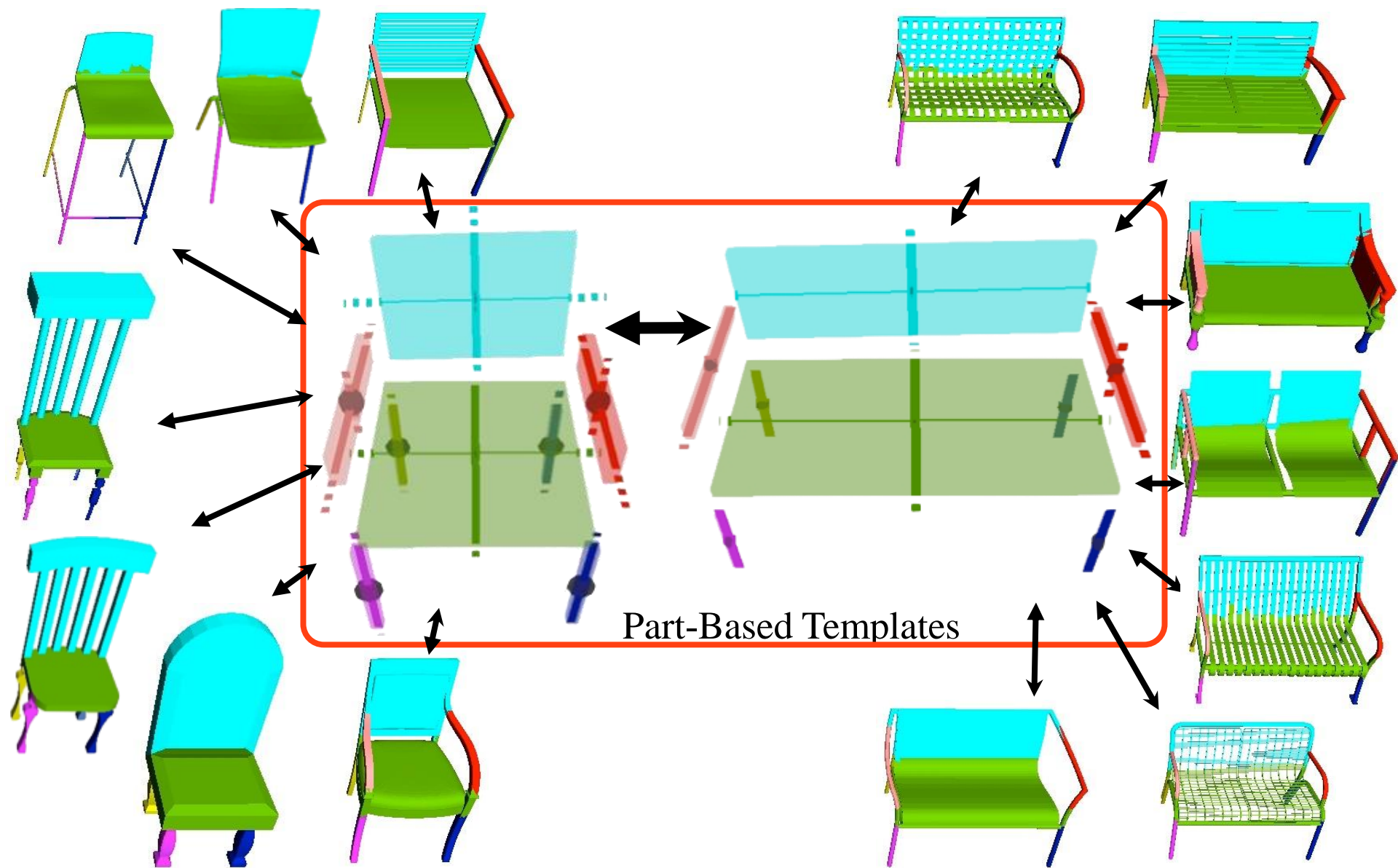
# Part-Aware Correspondences



# Part-Aware Correspondences

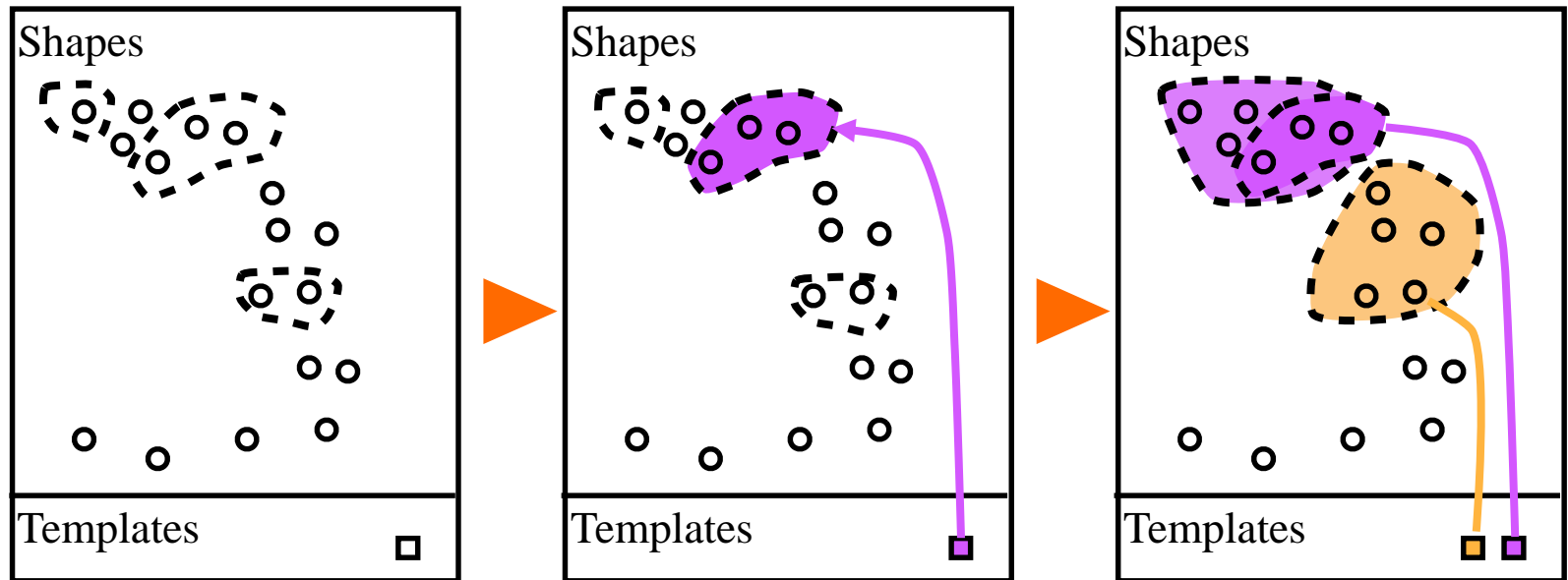


# Part-Aware Correspondences



# Part-Aware Correspondence Algorithm

Search for a set of templates that best explains a collection of models



Template  
Initialization

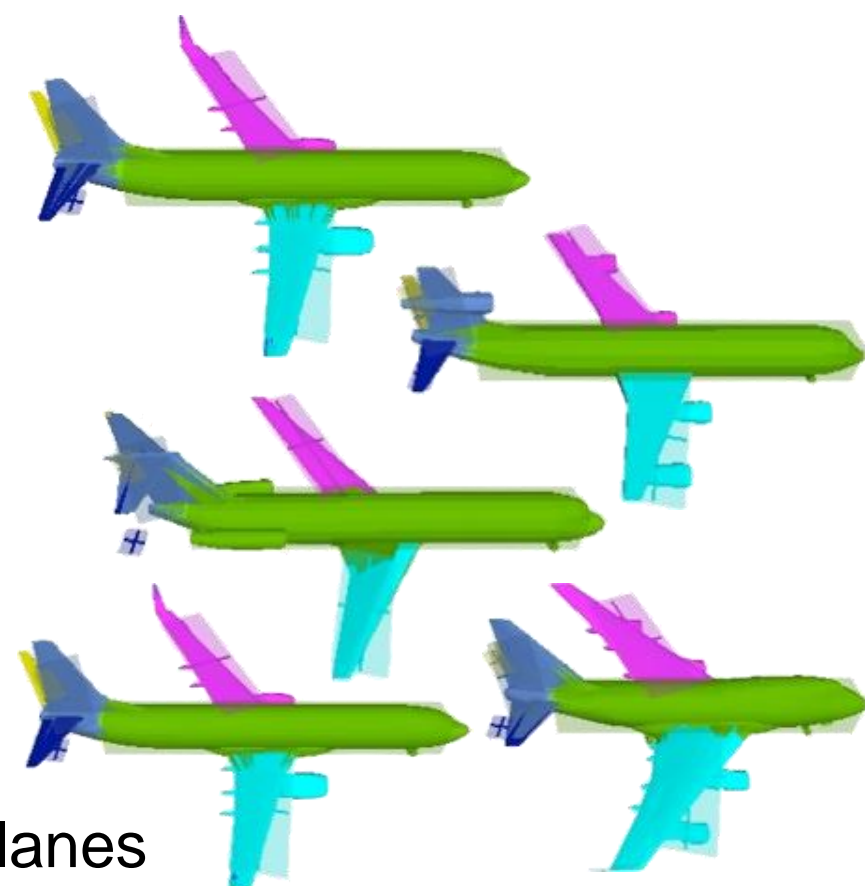
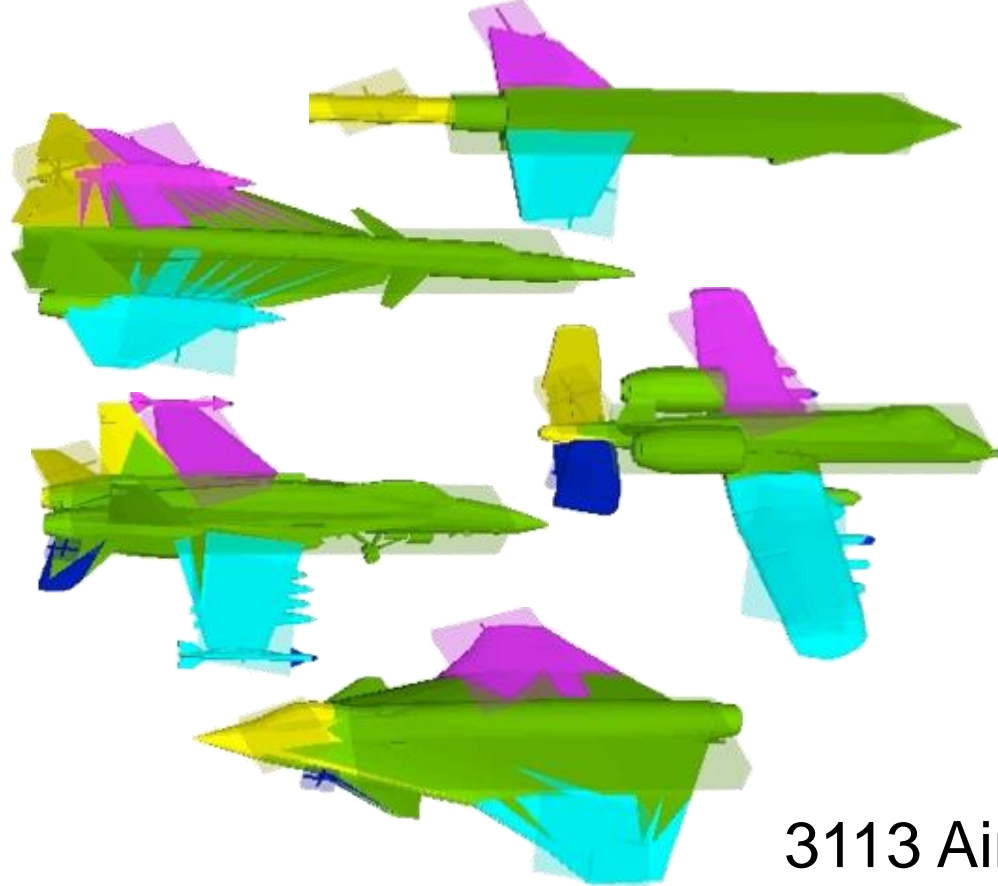
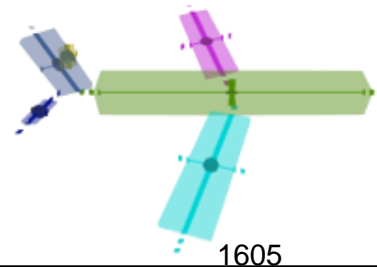
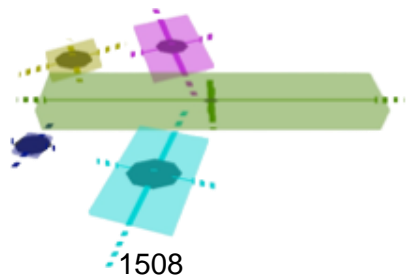
Template  
Fitting

Template  
Refinement

repeat until convergence

# Part-Aware Correspondence Results

2 Templates

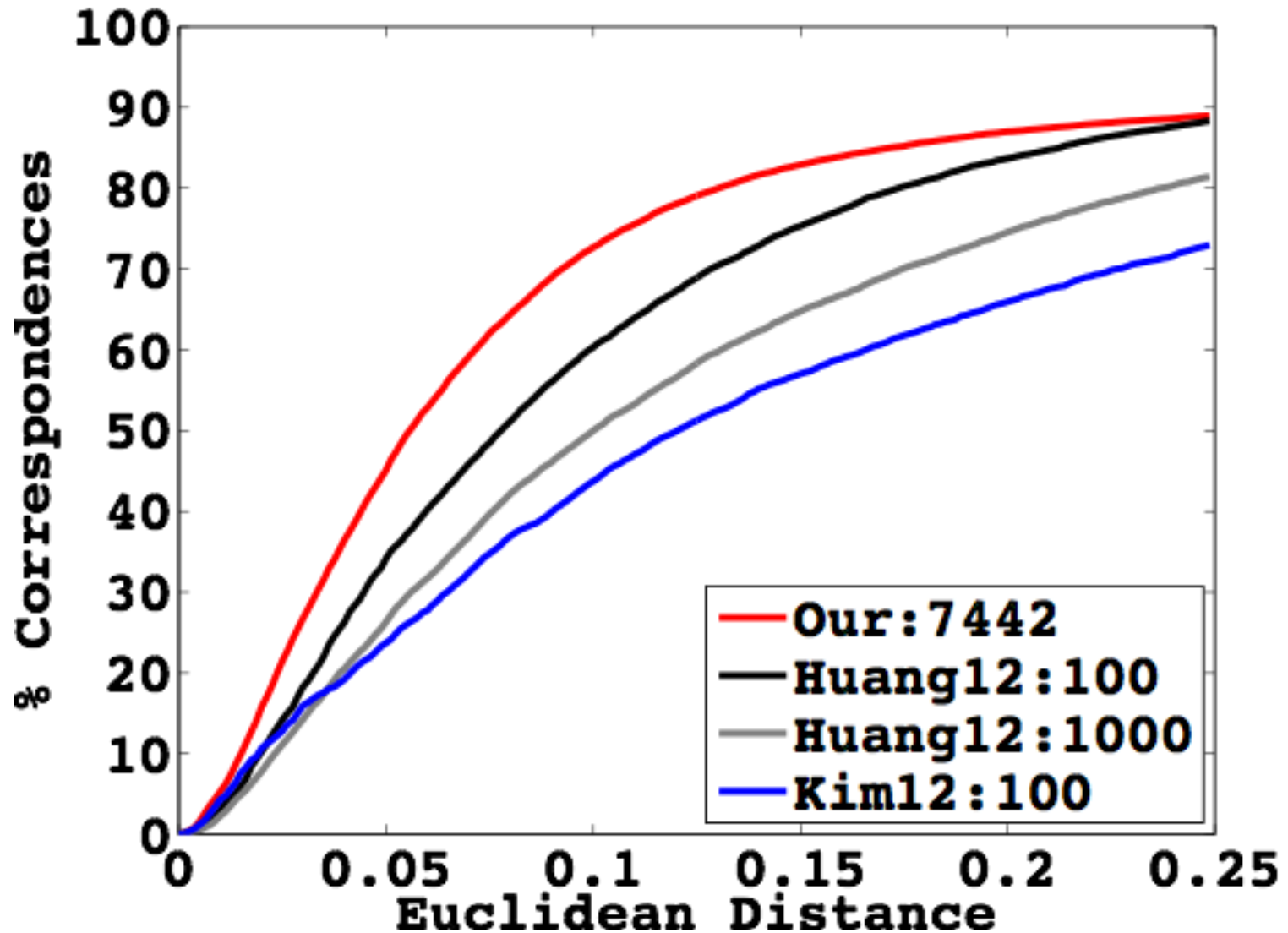


3113 Airplanes



# Part-Aware Correspondence Results

Correspondence benchmark (7442 seats)



# Outline of Talk

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Introduction

Latent structures

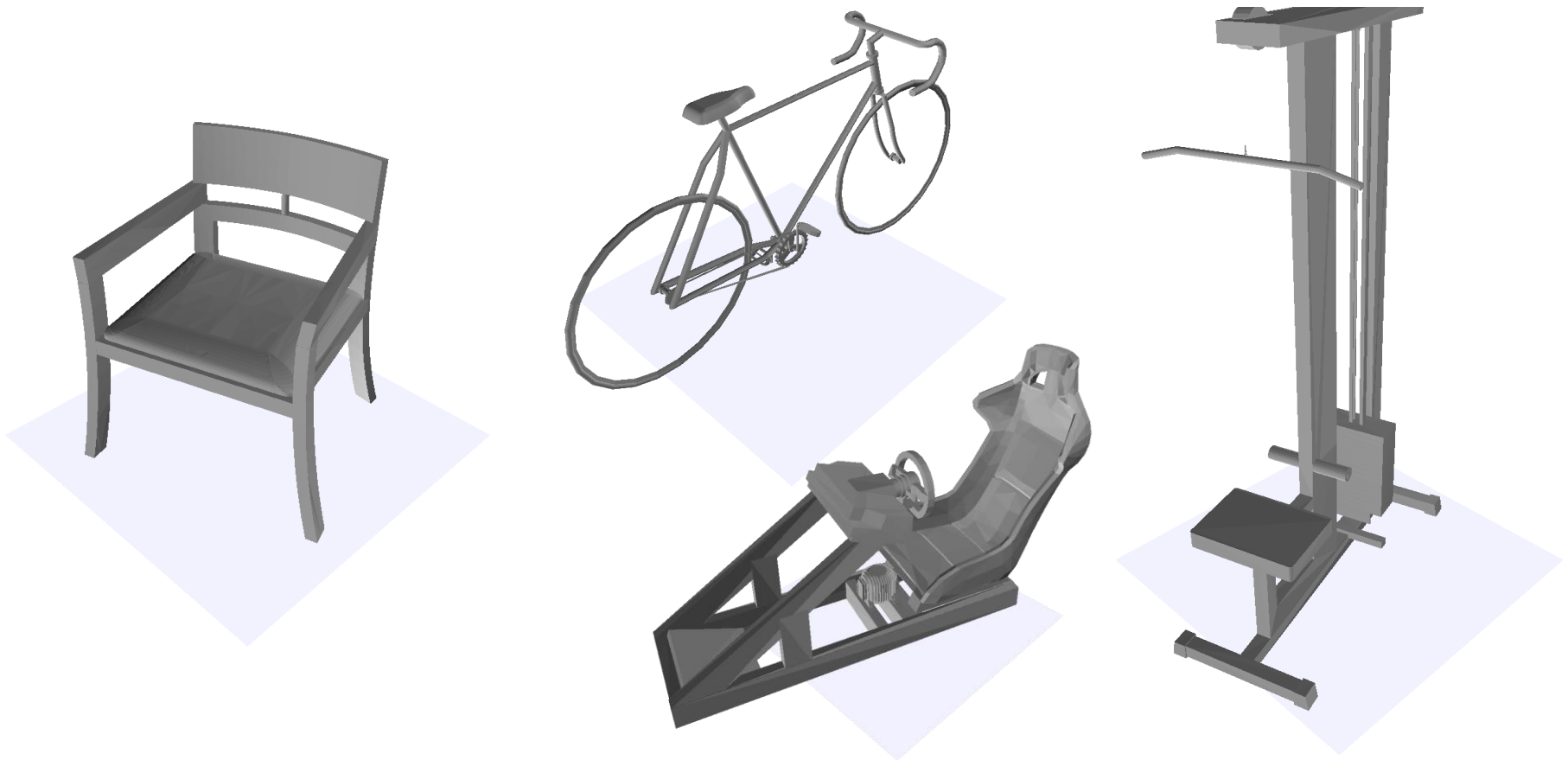
- Symmetries
- Parts
- Affordances
- Constraints
- Assemblies

Conclusion

# Affordance-Aware Correspondences

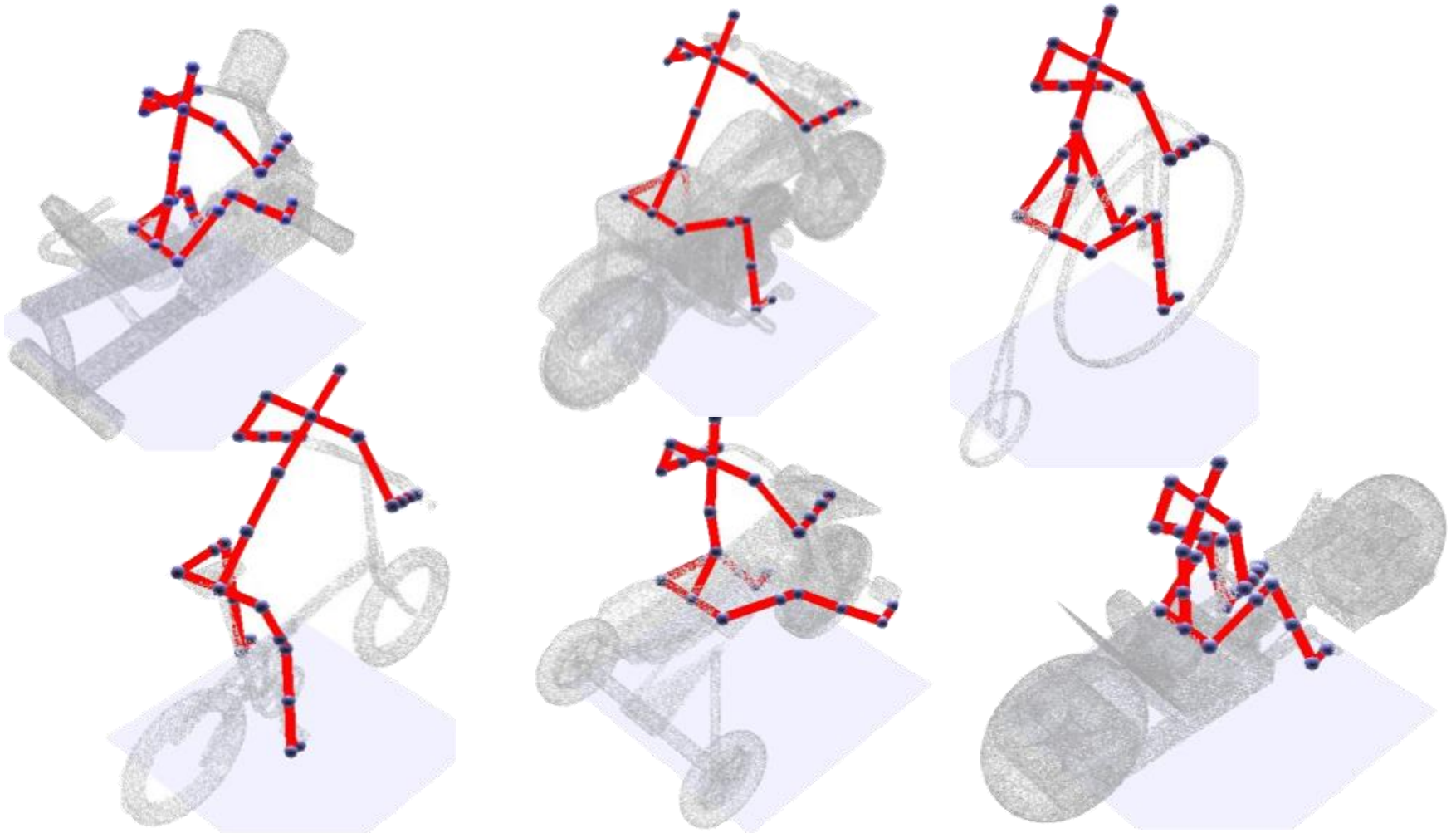
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Observation 1: almost all man-made objects are used by people



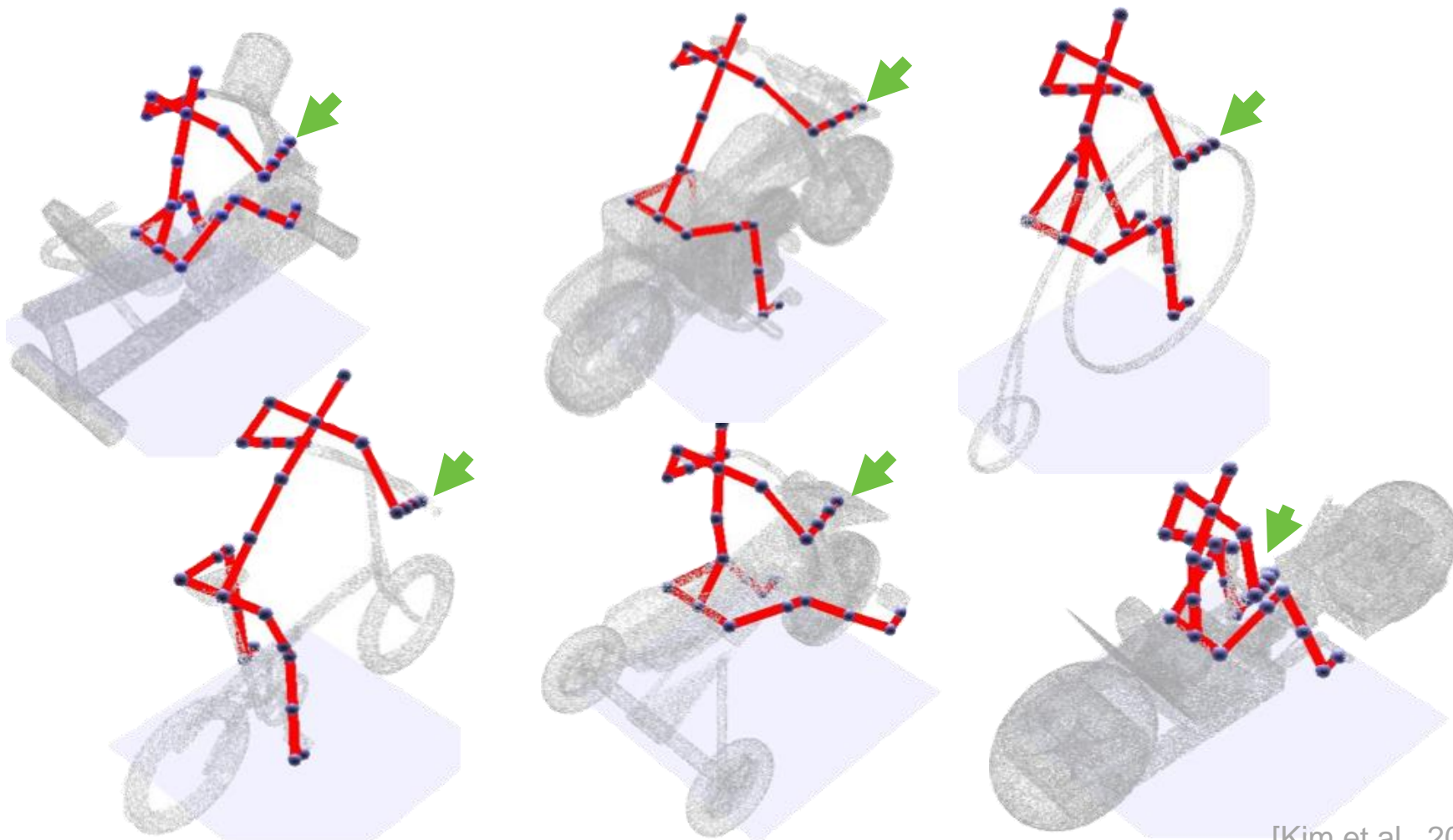
# Affordance-Aware Correspondences

Observation 2: the poses people take when using objects reveal functional correspondences



# Affordance-Aware Correspondences

Approach: predict poses of people and use them to find correspondences



# Pose Prediction Algorithm

## Pose Parameters

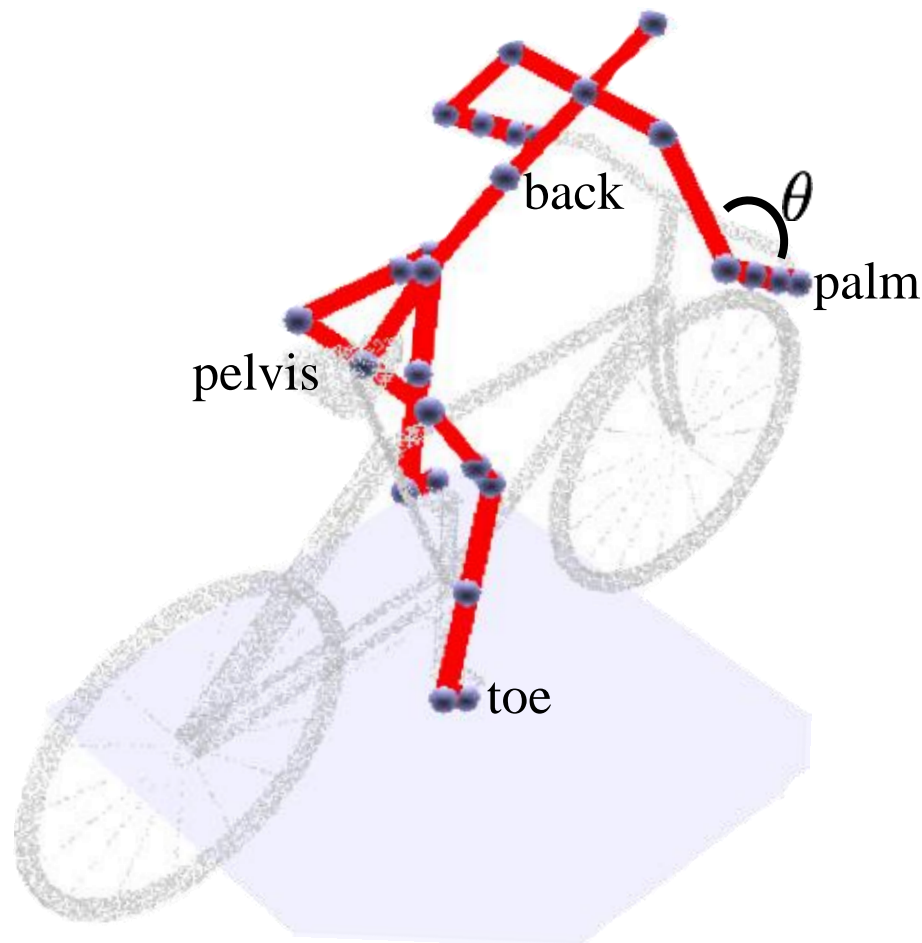
- Contact points
- Joint Angles

## Energy Function

- Contact Distance
- Feature Compatibility
- Pose Prior
- Symmetry
- Surface intersections

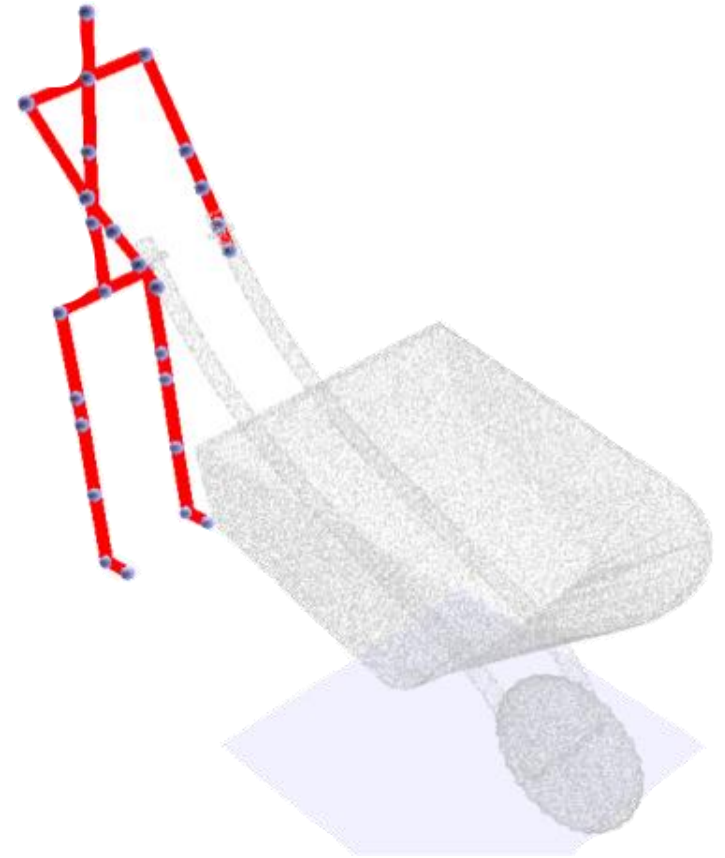
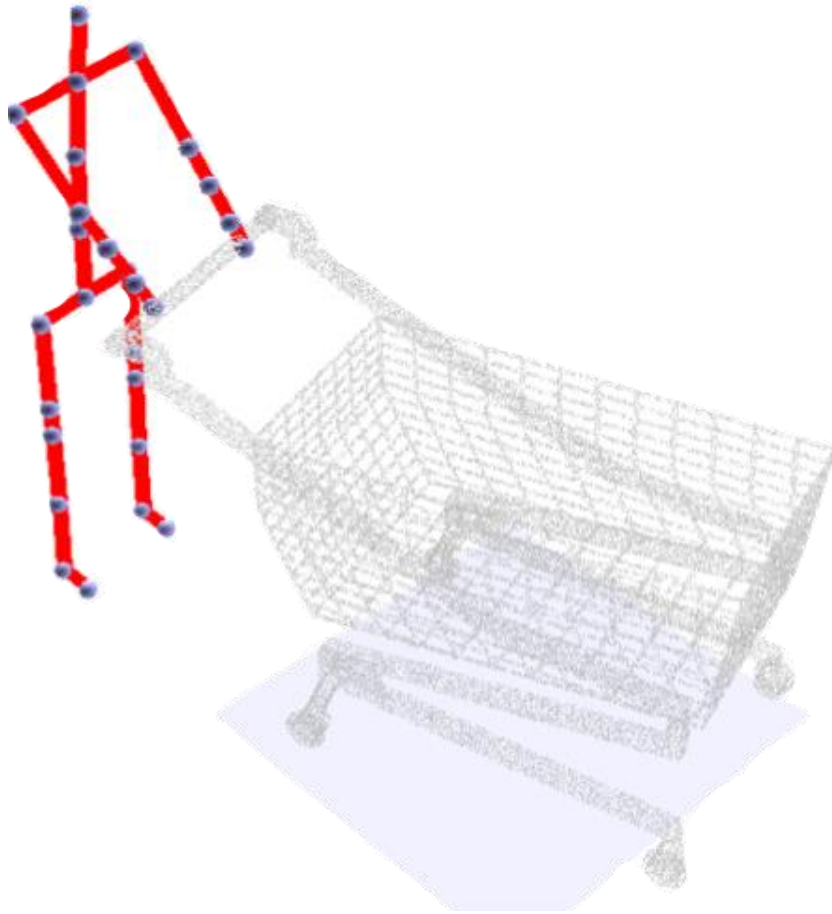
## Search Procedure

- Sample pose parameters
- Solve contact points or joint angles (inverse kinematics)
- Evaluate energy function



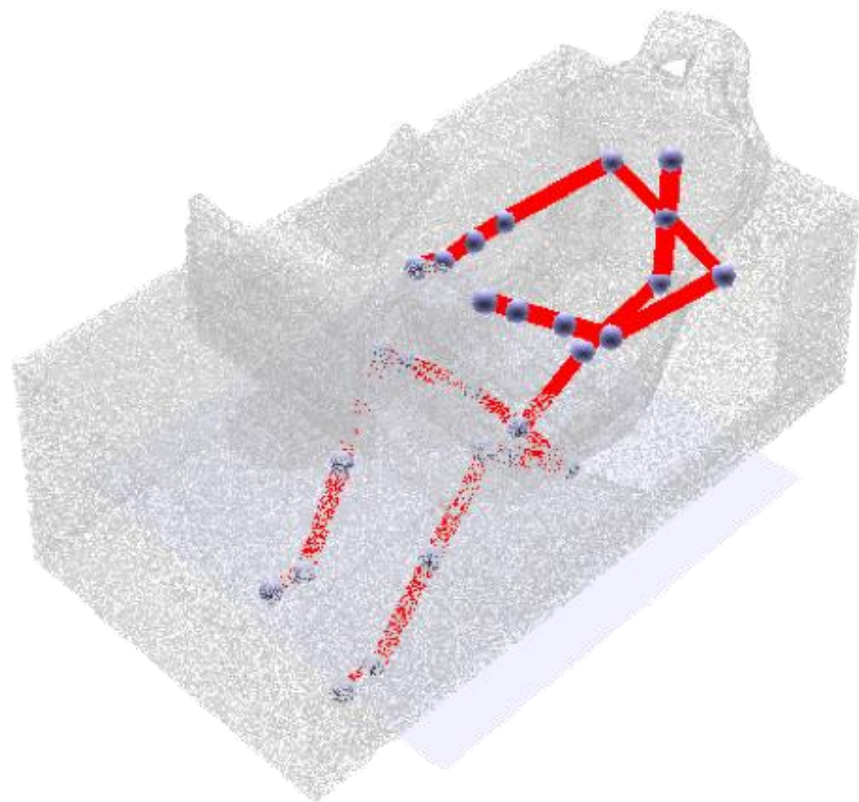
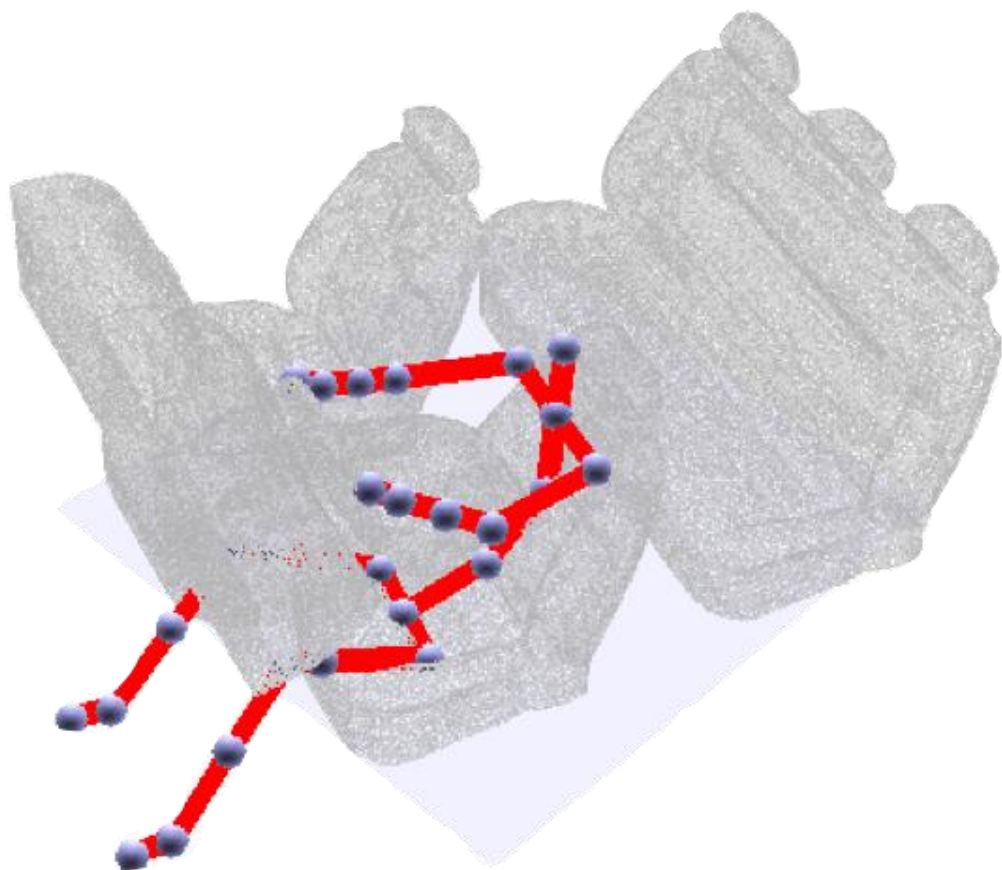
# Pose Prediction Results

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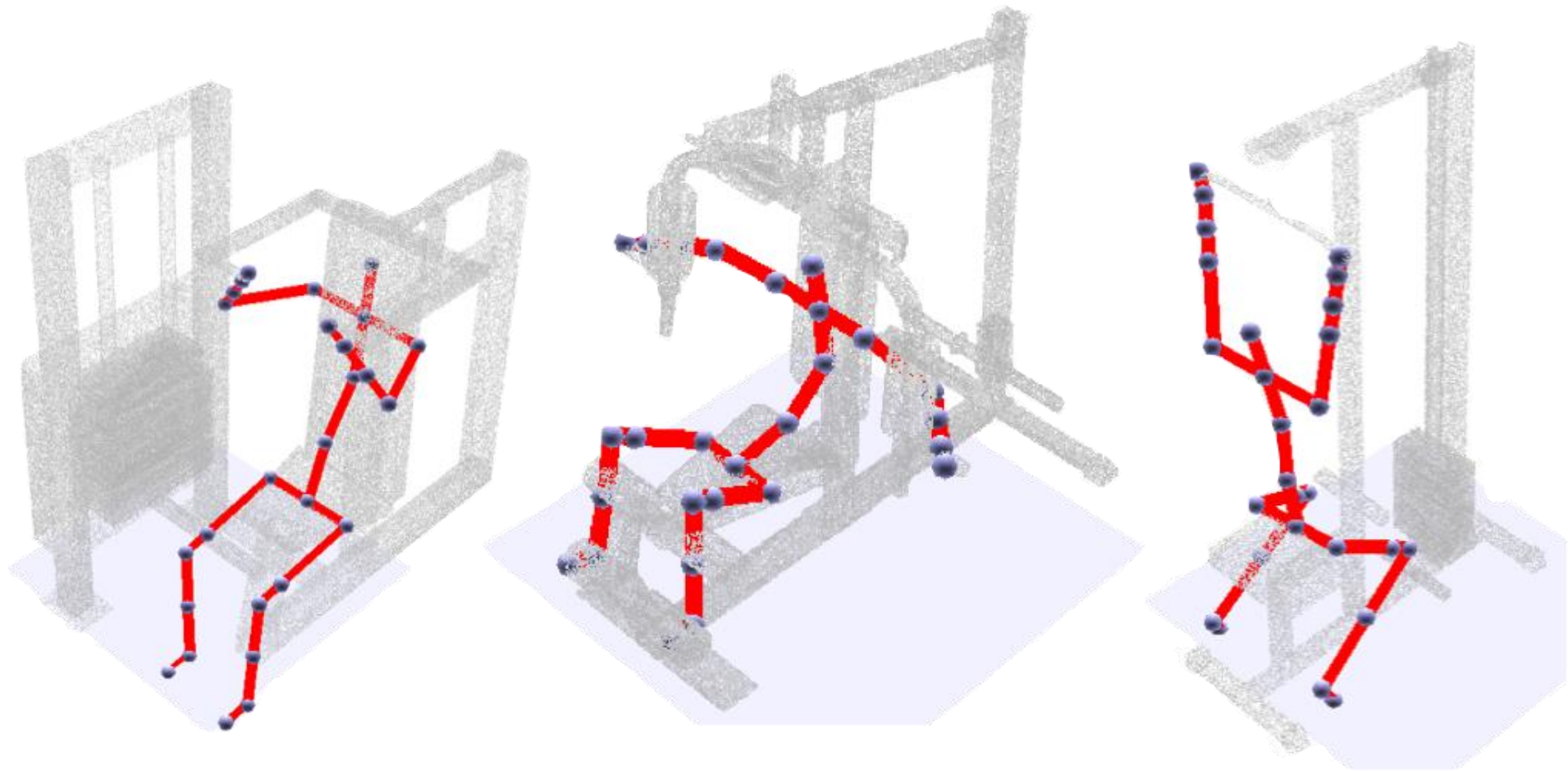
# Pose Prediction Results

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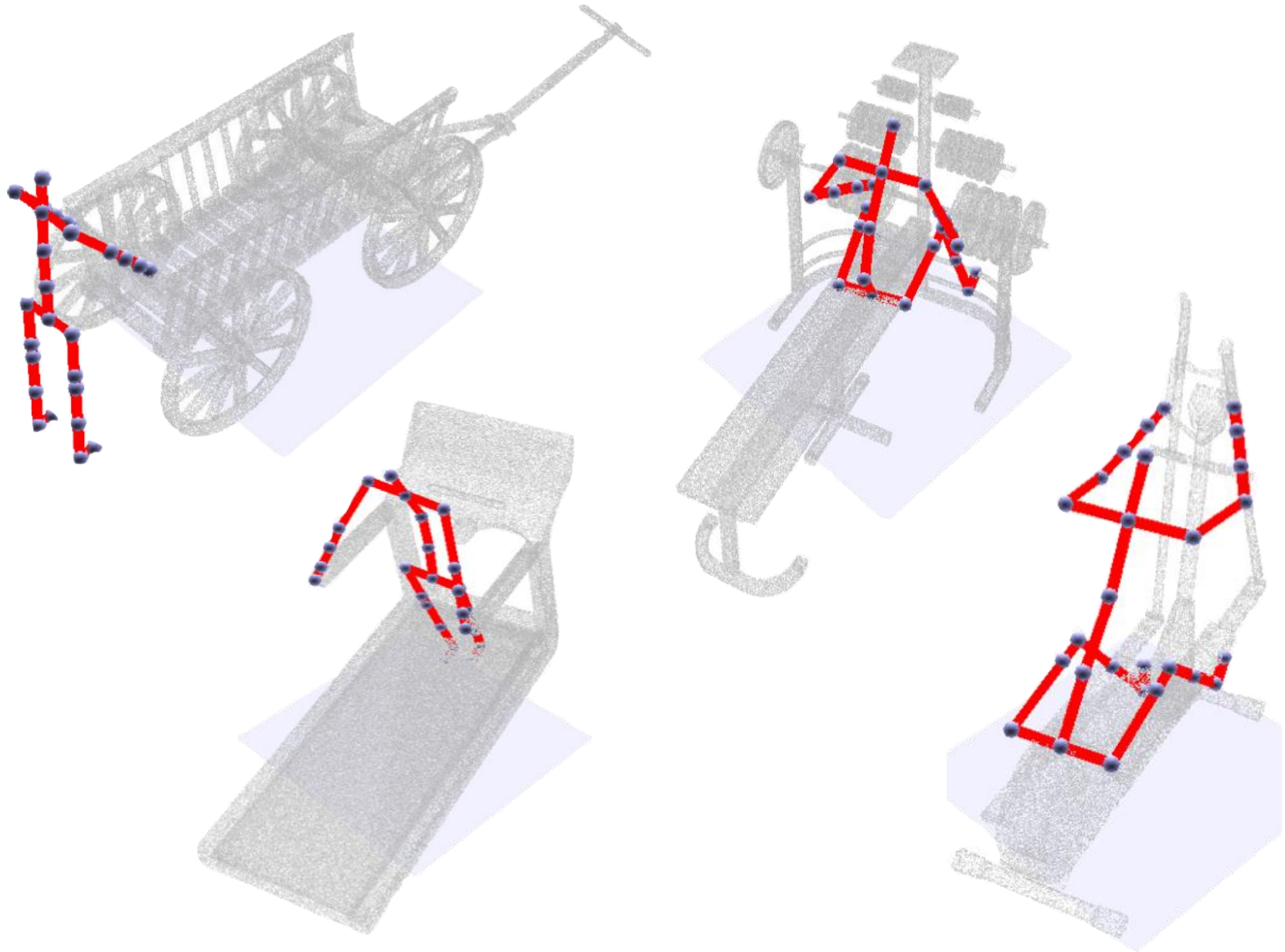




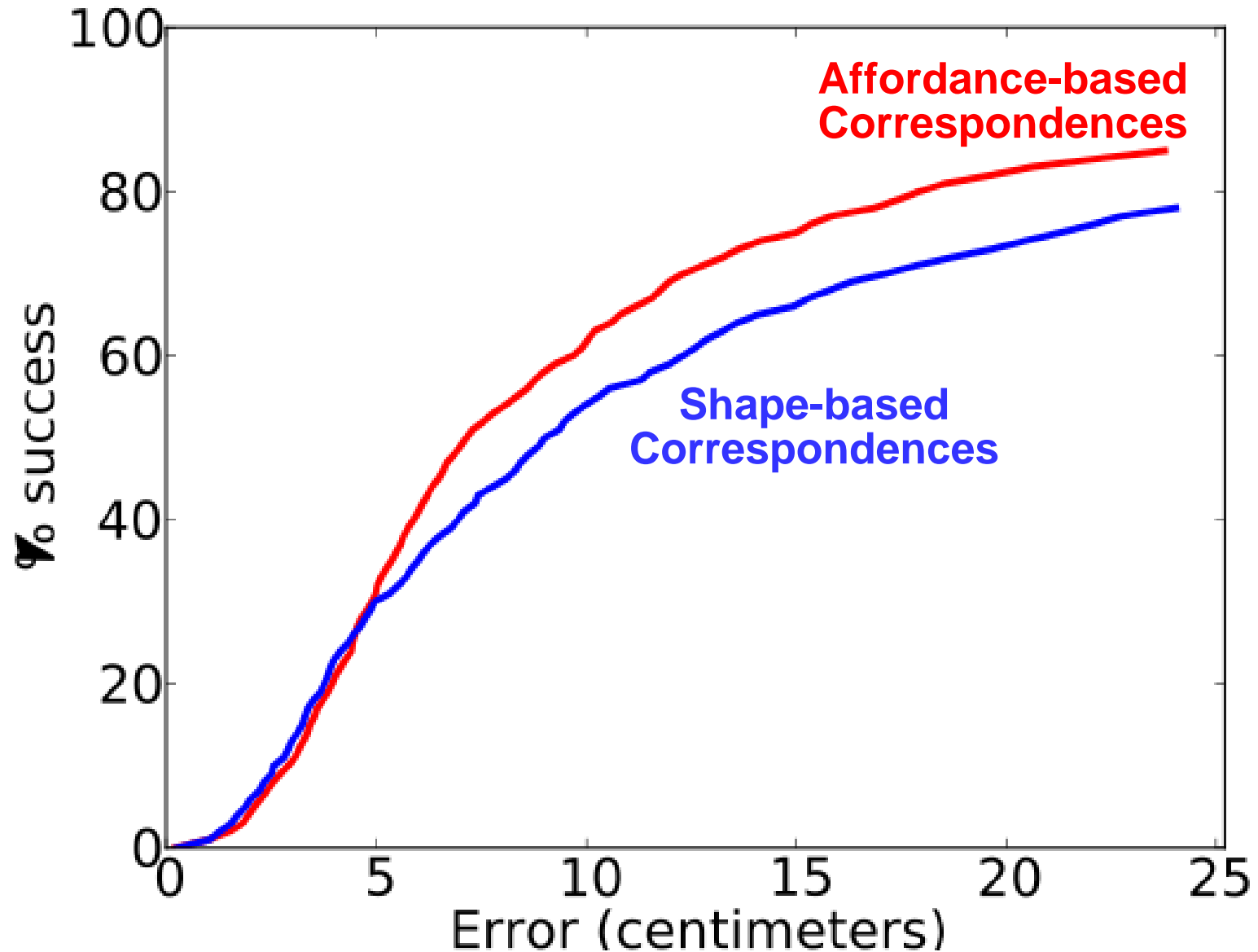
# Pose Prediction Results



# Pose Prediction Failures



# Affordance Correspondence Results



# Outline of Talk

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Introduction

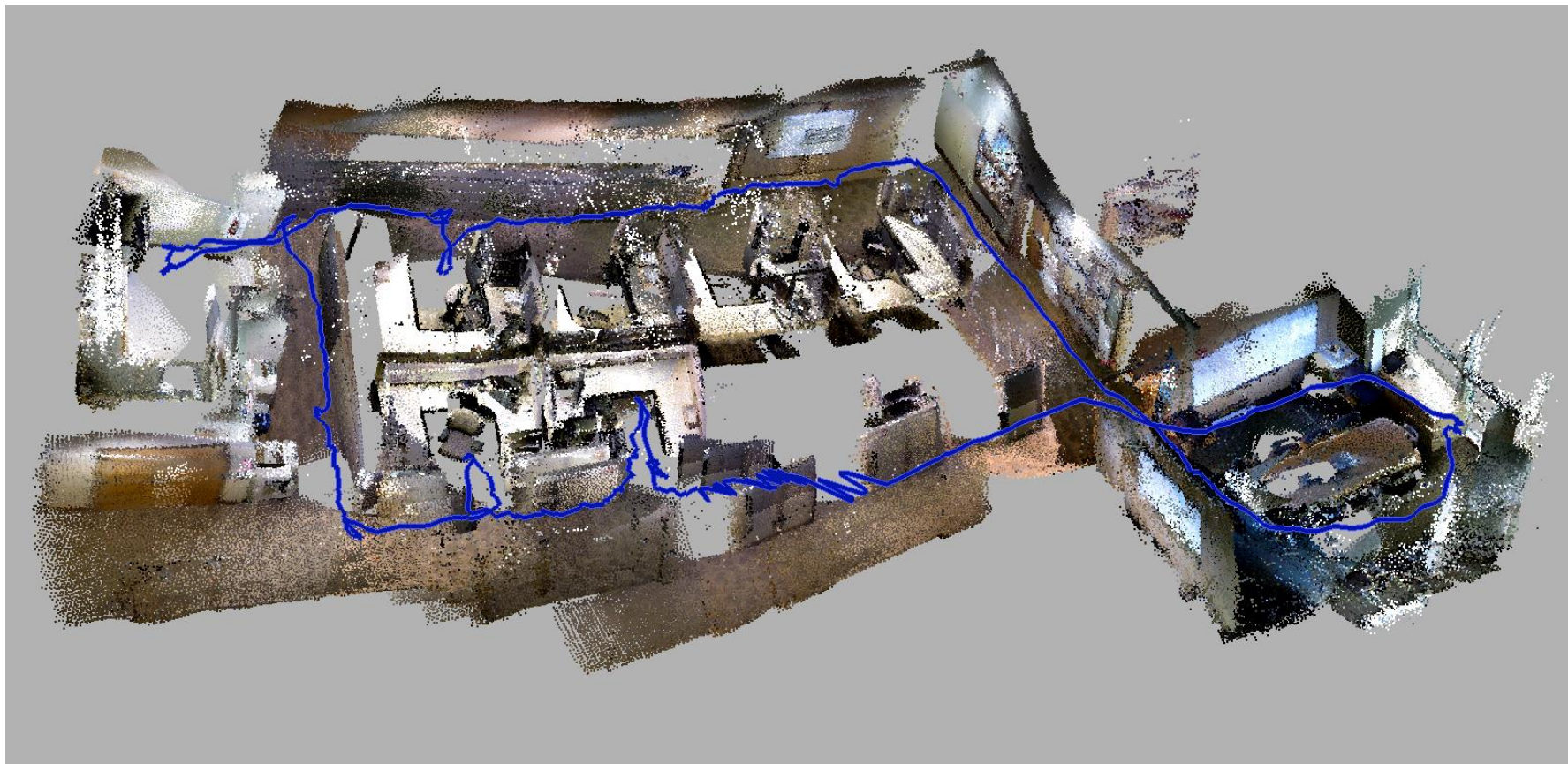
Latent structures

- Symmetries
- Parts
- Affordances
- **Constraints**
- Assemblies

Conclusion

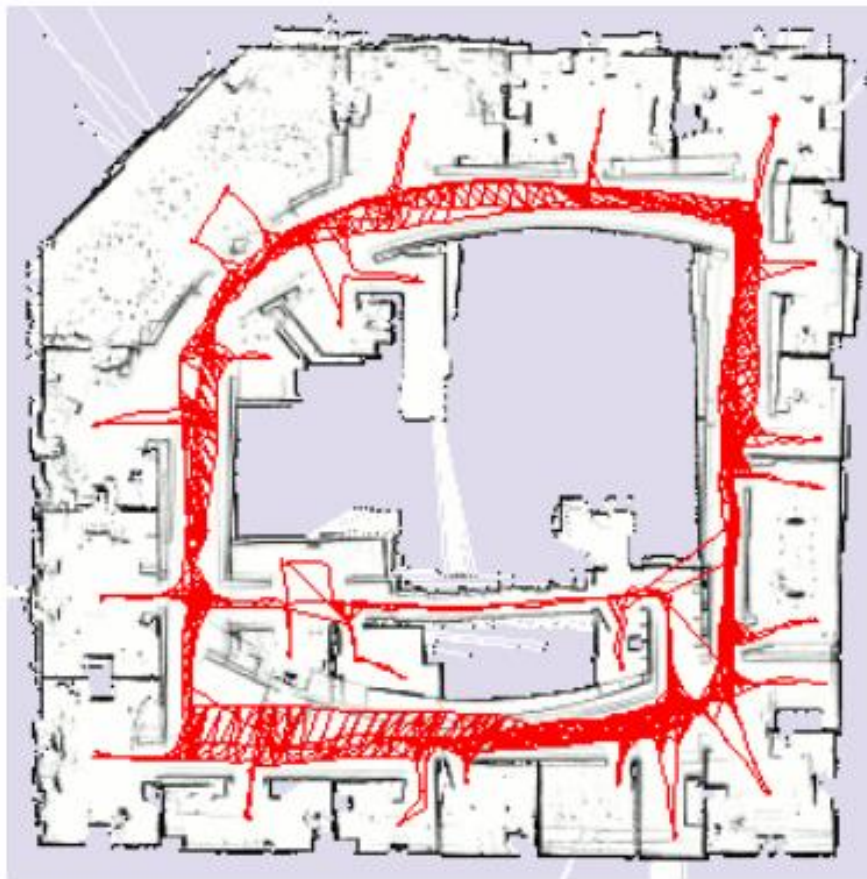
# Constraint-Aware Correspondences

Observation 1: global registration of RGB-D scans requires finding “loop closure” correspondences



# Constraint-Aware Correspondences

Observation 2: almost all indoor environments follow the Manhattan World assumption

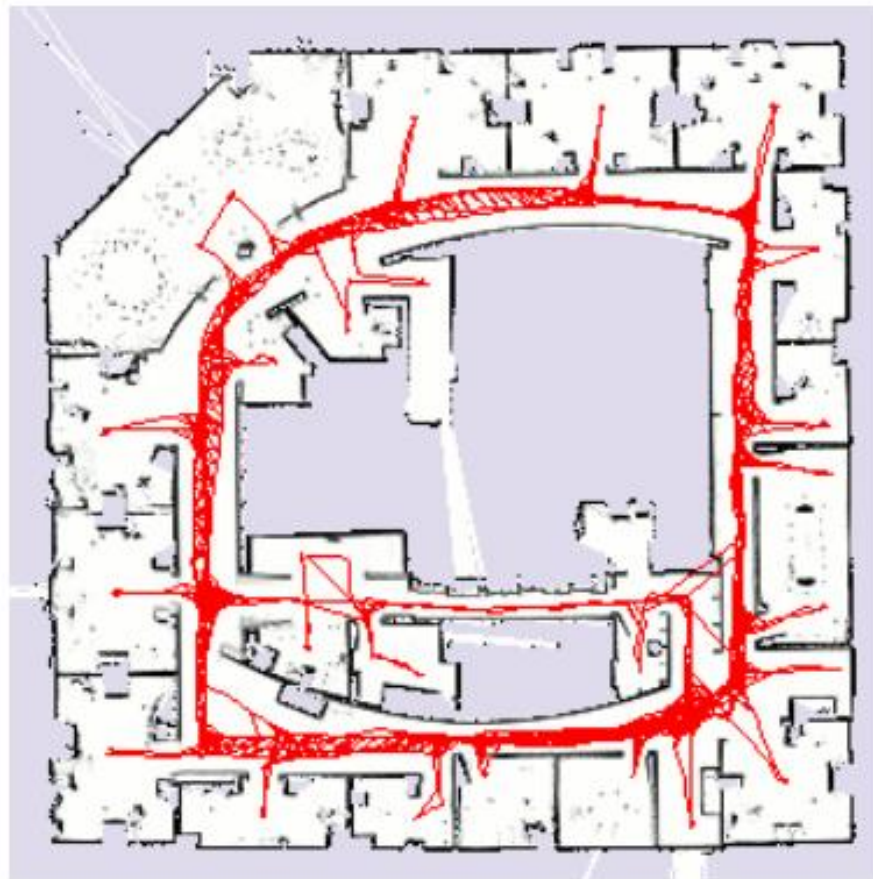


Intel Research Lab in Seattle

# Constraint-Aware Correspondences

Observation 2: almost all indoor environments follow the Manhattan World assumption

- Orthogonal corners
- Parallel surfaces



Intel Research Lab in Seattle

# Constraint-Aware Correspondences

Approach: detect and enforce Manhattan World constraints and use them to find correspondences



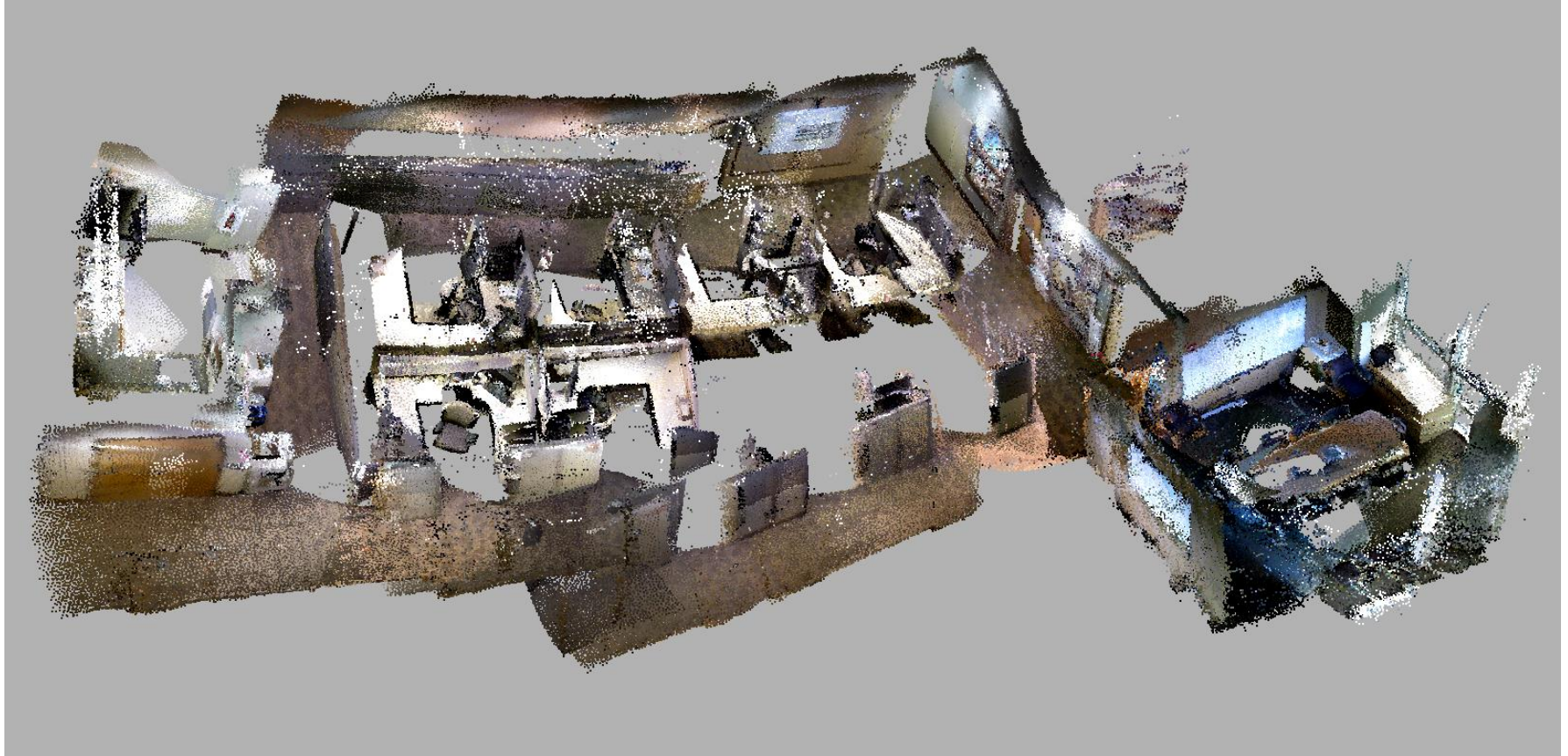
Camera Tracking  
without Constraints

Global Registration  
with Constraints



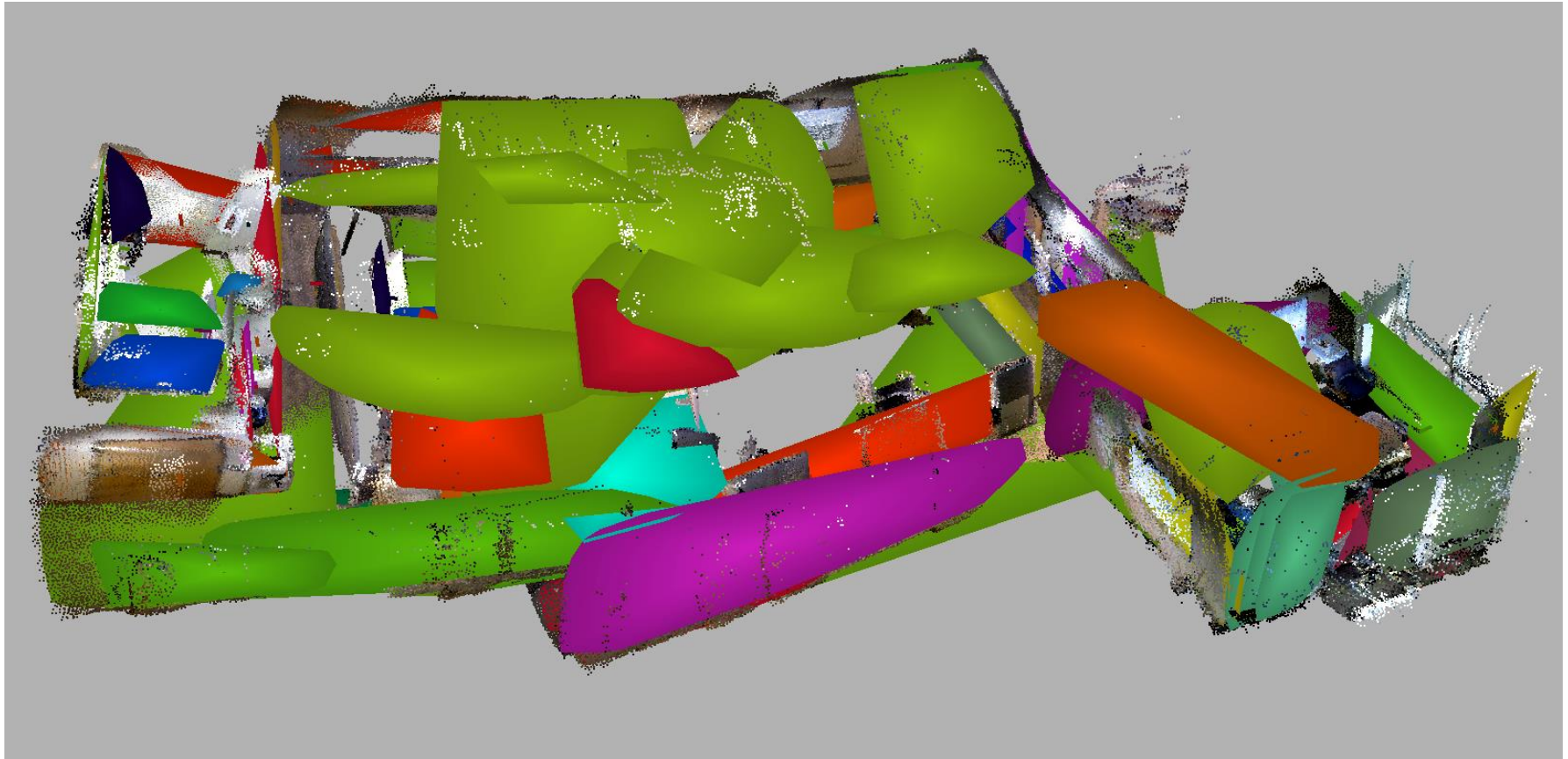
# Constraint-Aware ICP Algorithm

Like a global ICP algorithm ...



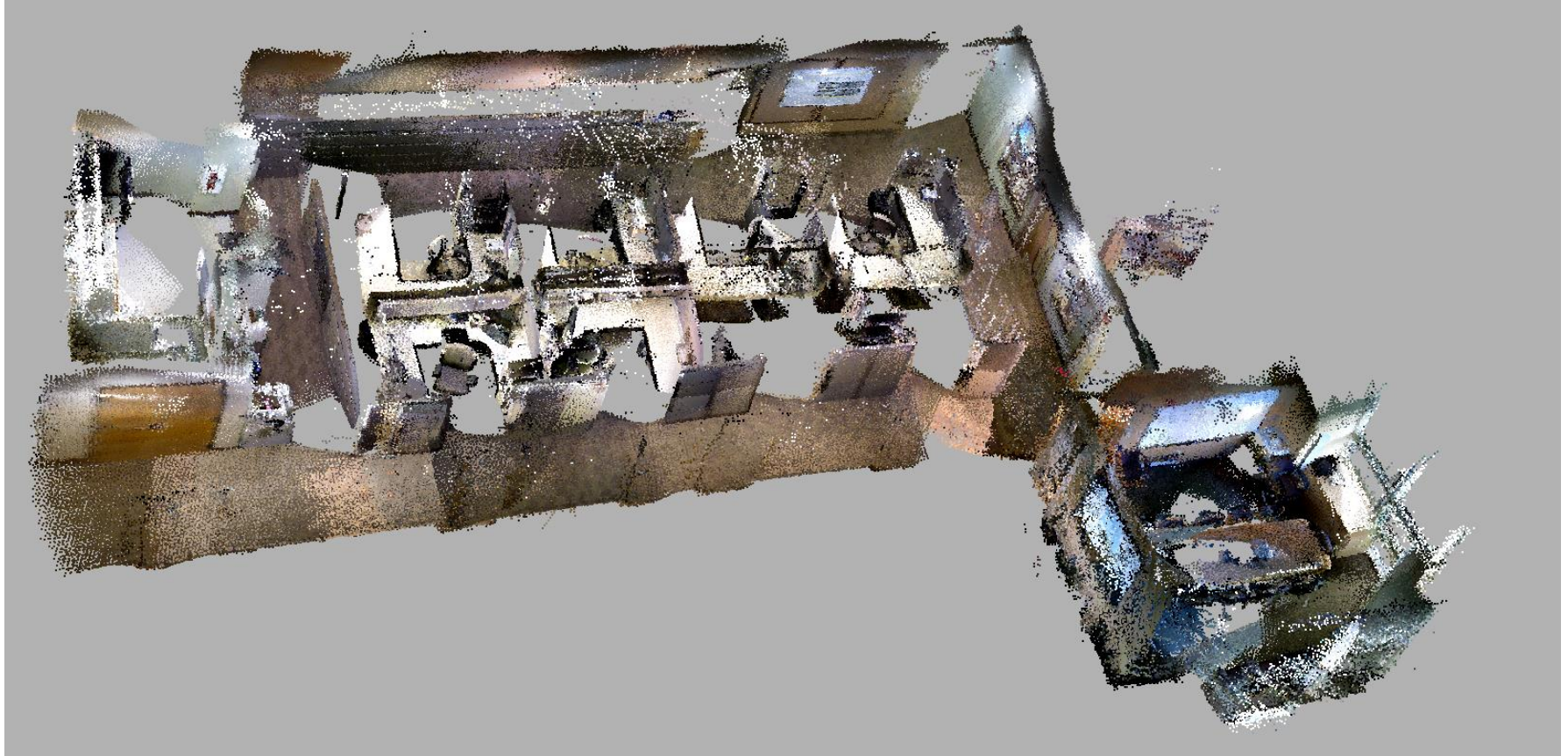
# Constraint-Aware ICP Algorithm

... but detect constraint model in inner loop, and ...



# Constraint-Aware ICP Algorithm

... optimize correspondences and constraints jointly



# Constraint-Aware ICP Issue

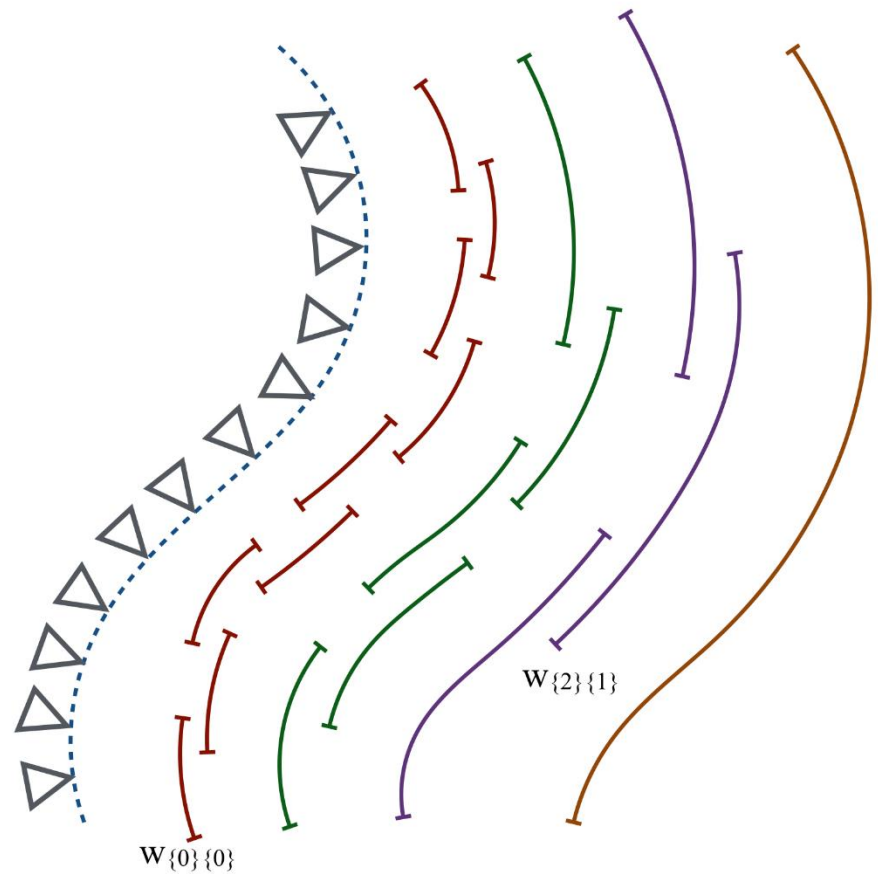
How detect constraints in warped point clouds?



# Fine-to-Coarse Registration

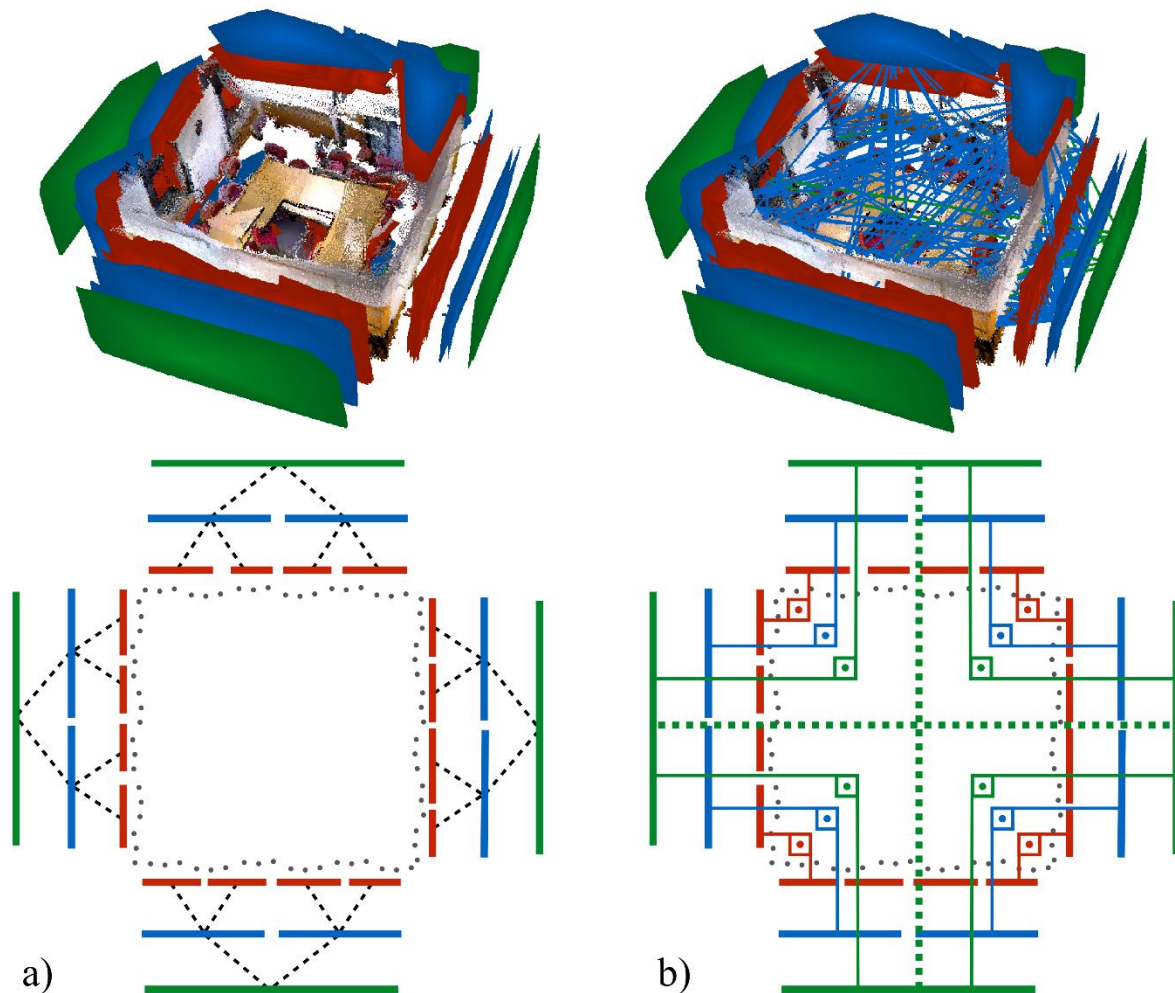
Iteratively:

1. Detect constraints within windows of size  $w$
2. Optimize
3. Increase  $w$



# Fine-to-Coarse Registration

Creates hierarchy of structure and constraints



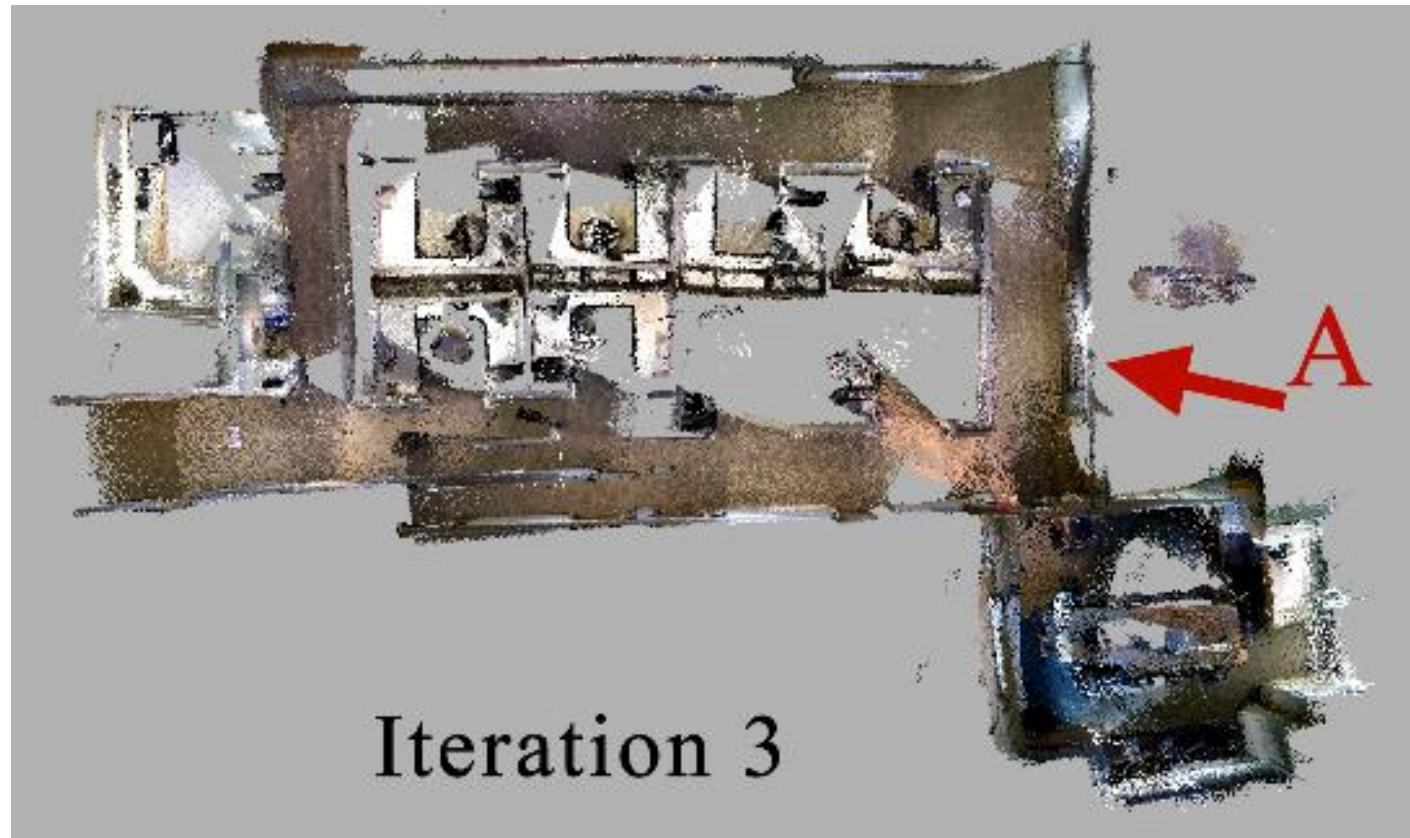
# Fine-to-Coarse Registration

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# Fine-to-Coarse Registration

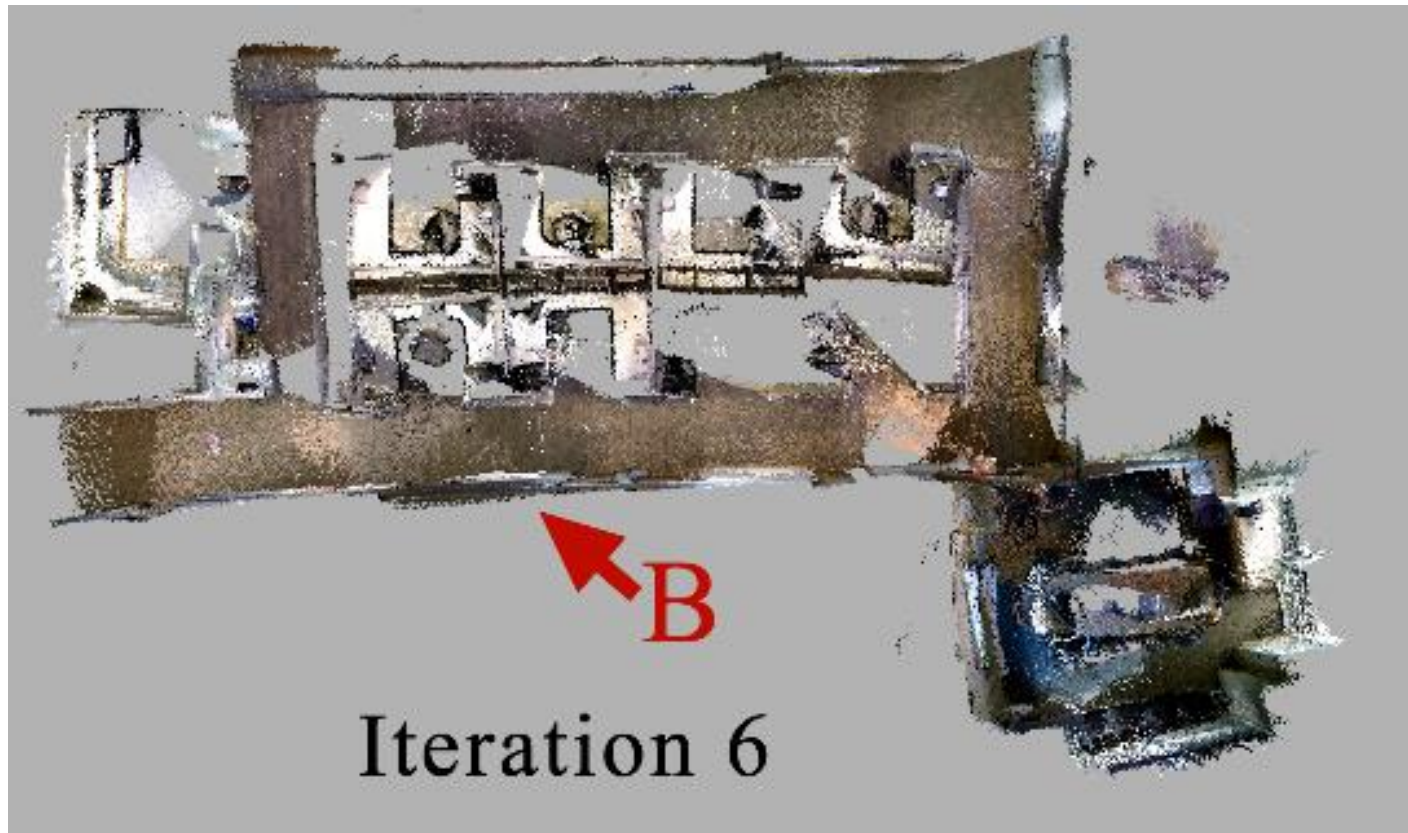
Fixes corners, straighten walls, ...





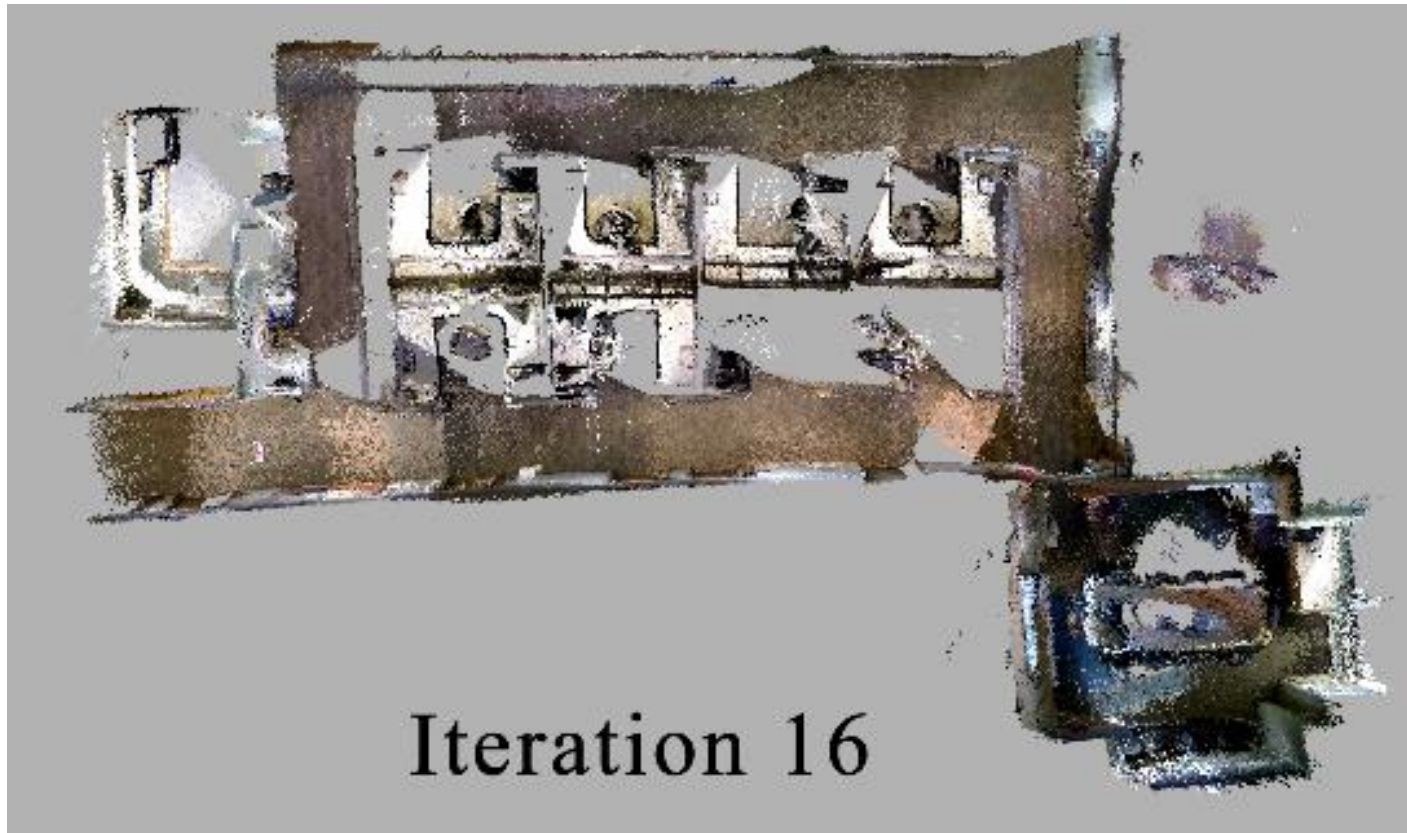
# Fine-to-Coarse Registration

Fixes corners, straighten walls, closes loops, ...



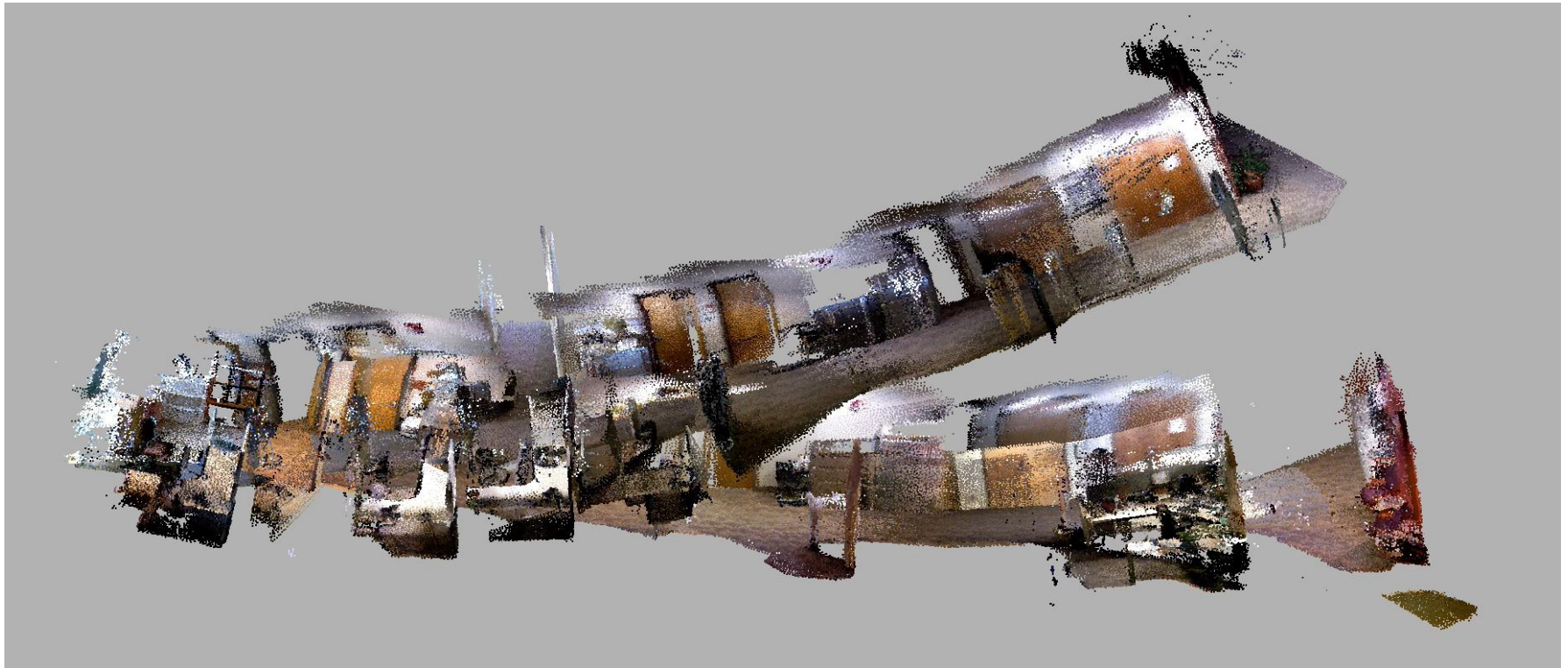
# Fine-to-Coarse Registration

Fixes corners, straighten walls, closes loops, snaps



# Fine-to-Coarse Registration Example

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# Constraint-Aware ICP Results

Comparison to previous methods:

SUN3D

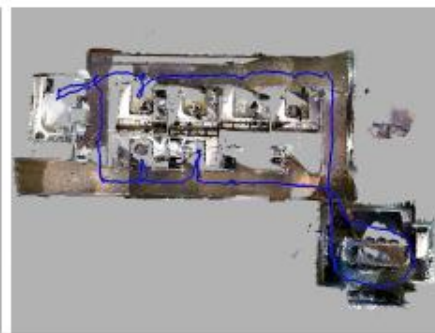
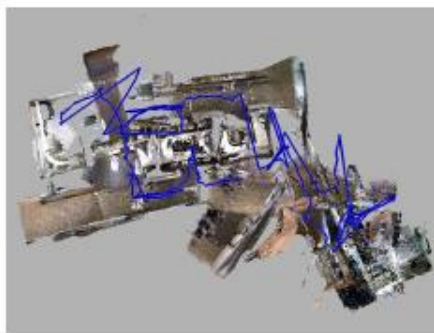
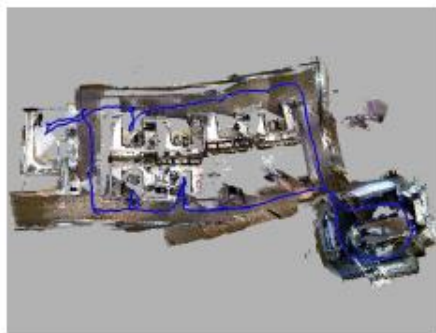
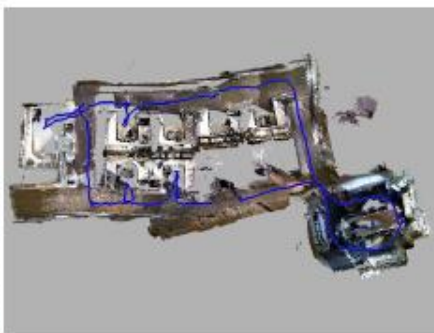
$T_0$

Xiao et al.

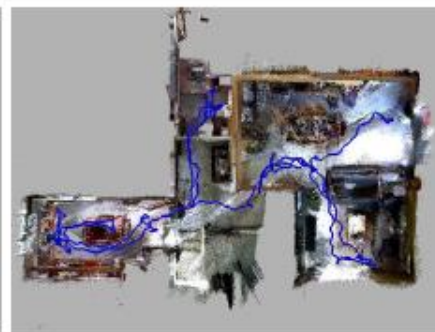
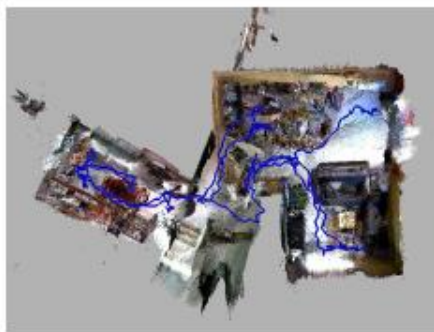
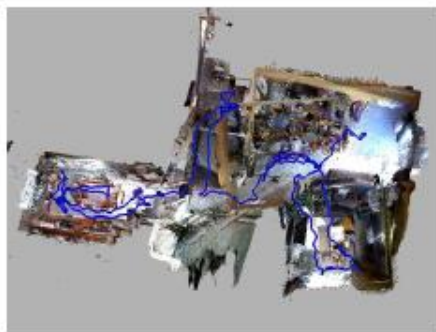
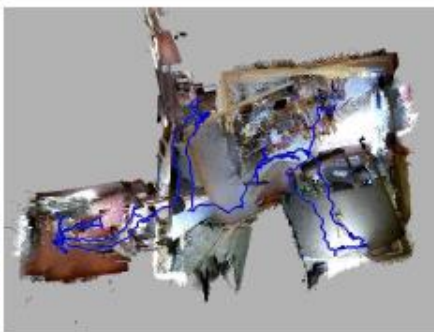
Choi et al.

Ours

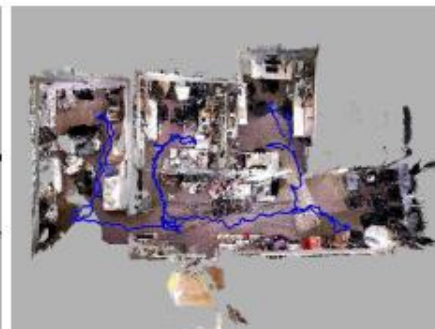
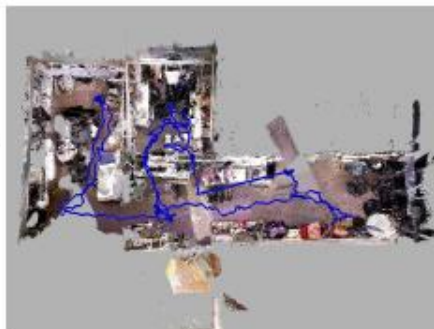
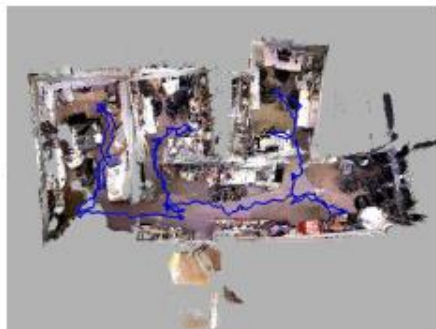
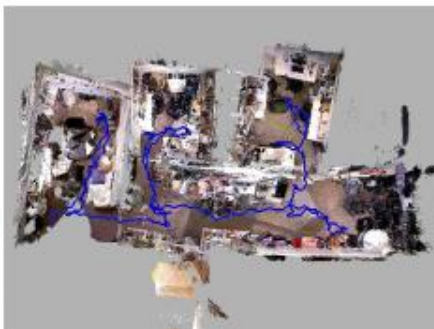
brown\_bm\_1



home\_at\_scan1



ted\_lab\_2



# Constraint-Aware ICP Results



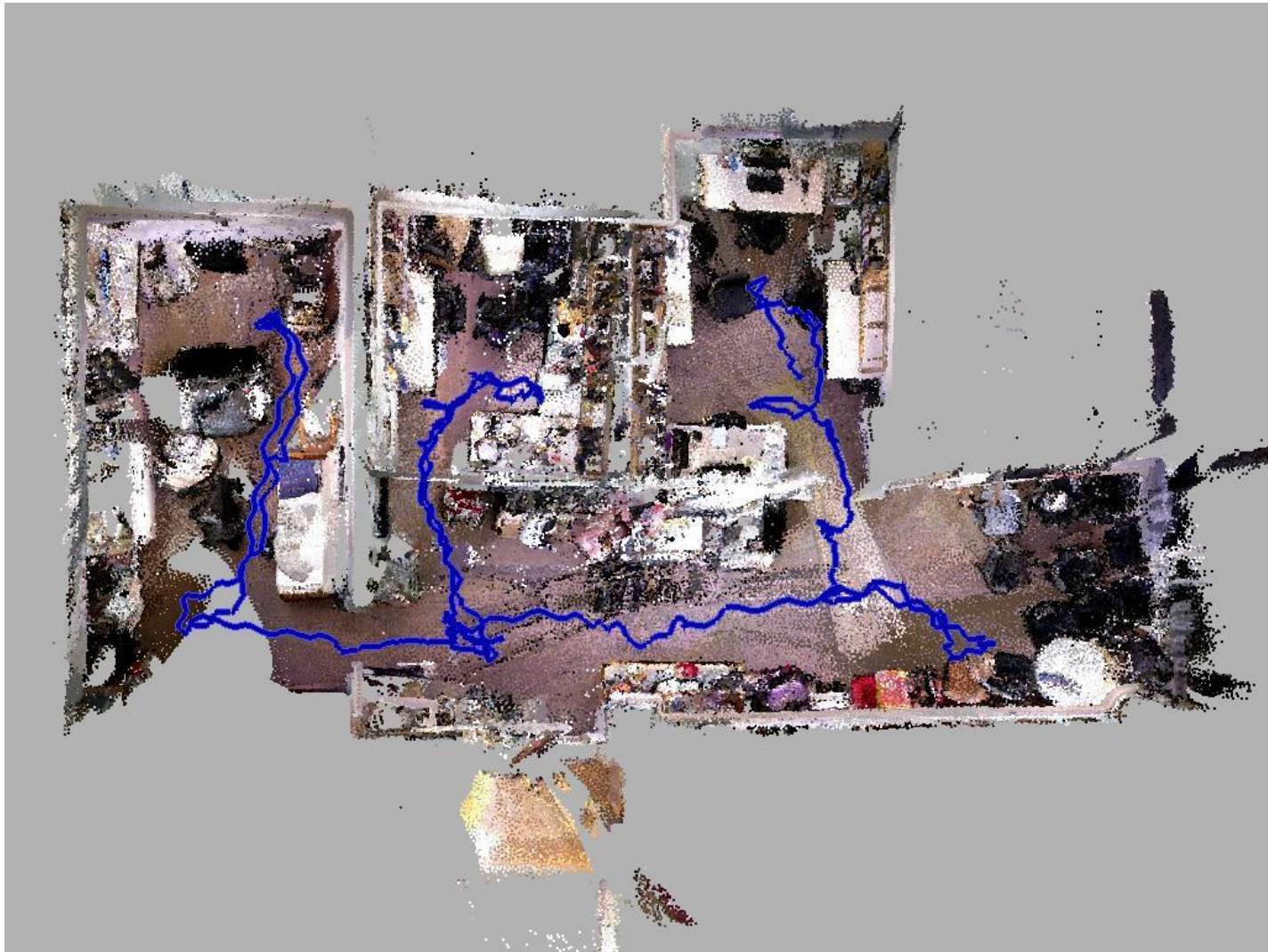
[Xiao et al., 2013]

# Constraint-Aware ICP Results



[Choi et al., 2015]

# Constraint-Aware ICP Results



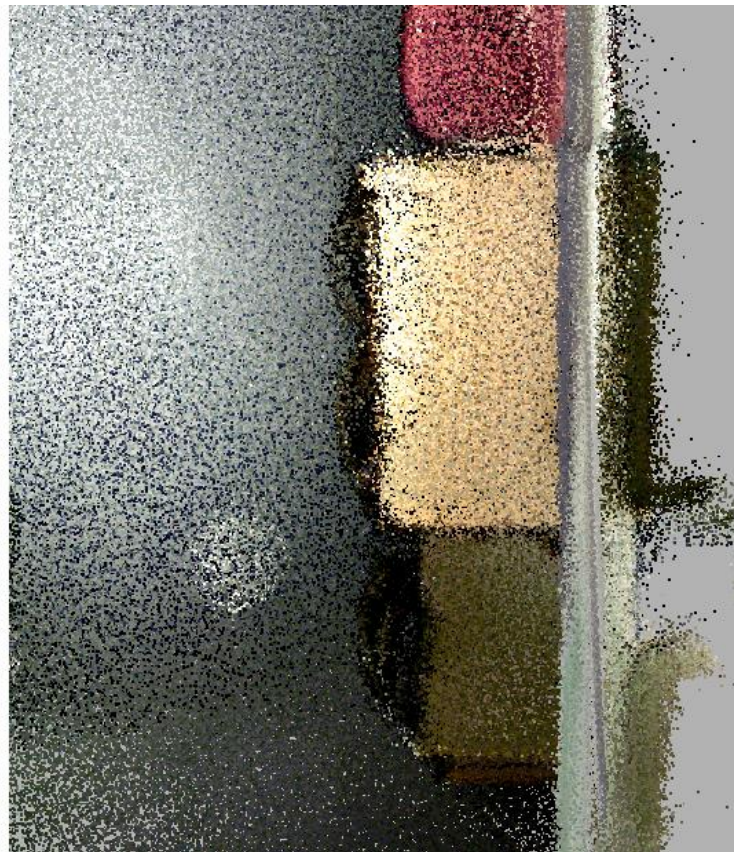
Ours

# Constraint-Aware ICP Results

Comparison to previous methods:



[Xiao et al., 2013]



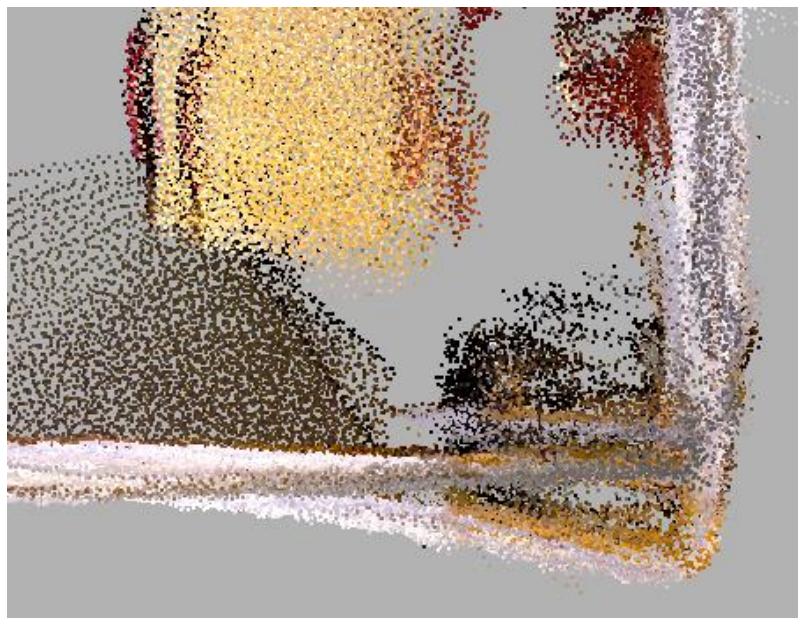
Ours



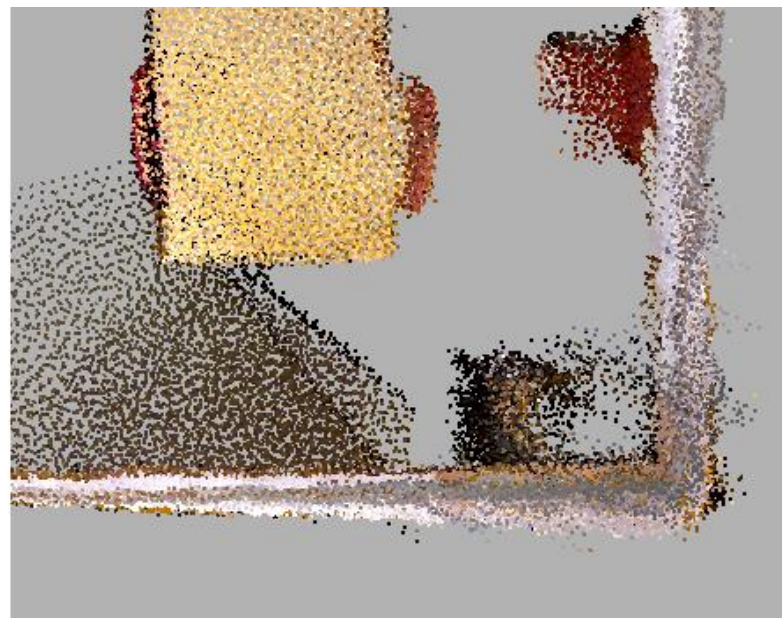
# Constraint-Aware ICP Results

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Comparison to previous methods:



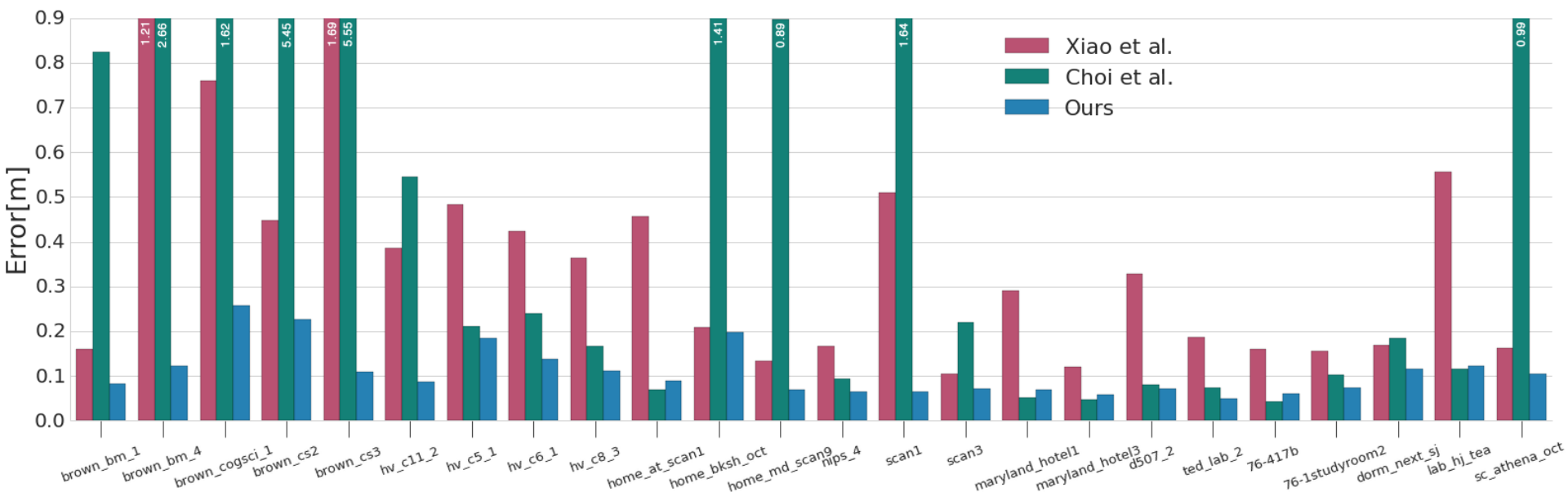
[Choi et al., 2015]



Ours

# Constraint-Aware ICP Results

Comparison to previous methods:



# Outline of Talk

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Introduction

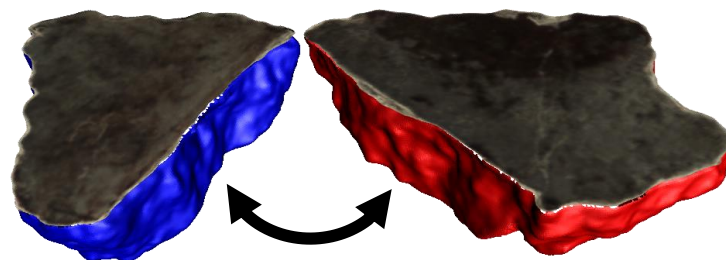
Latent structures

- Symmetries
- Parts
- Affordances
- Constraints
- **Assemblies**

Conclusion

# Assembly-Aware Correspondences

Observation 1: assembling fractured objects requires finding complementary surface correspondences



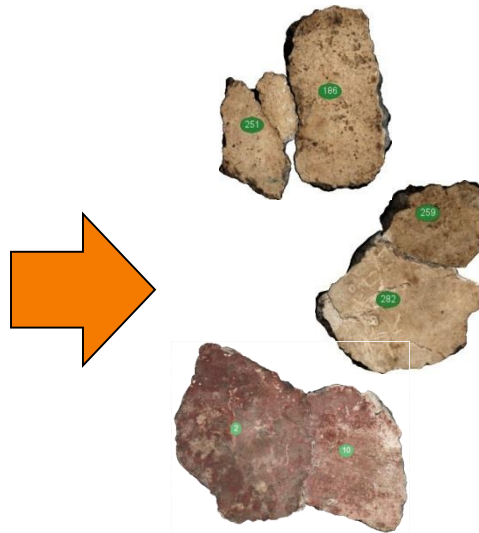
Fragments of fractured wall painting from Akrotiri [Doumas et al.]

# Assembly-Aware Correspondences

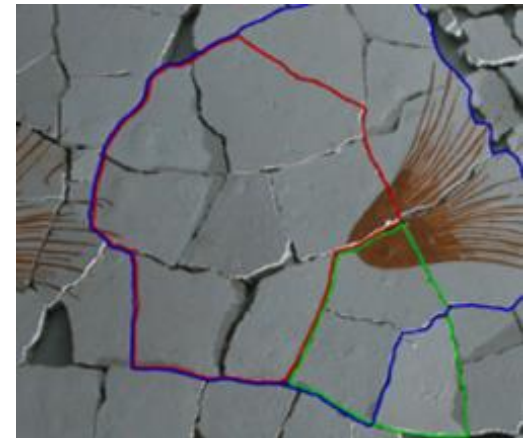
Observation: fracture correspondences are constrained by latent structure of global assembly



Scanned  
Fragments



Candidate  
Correspondences



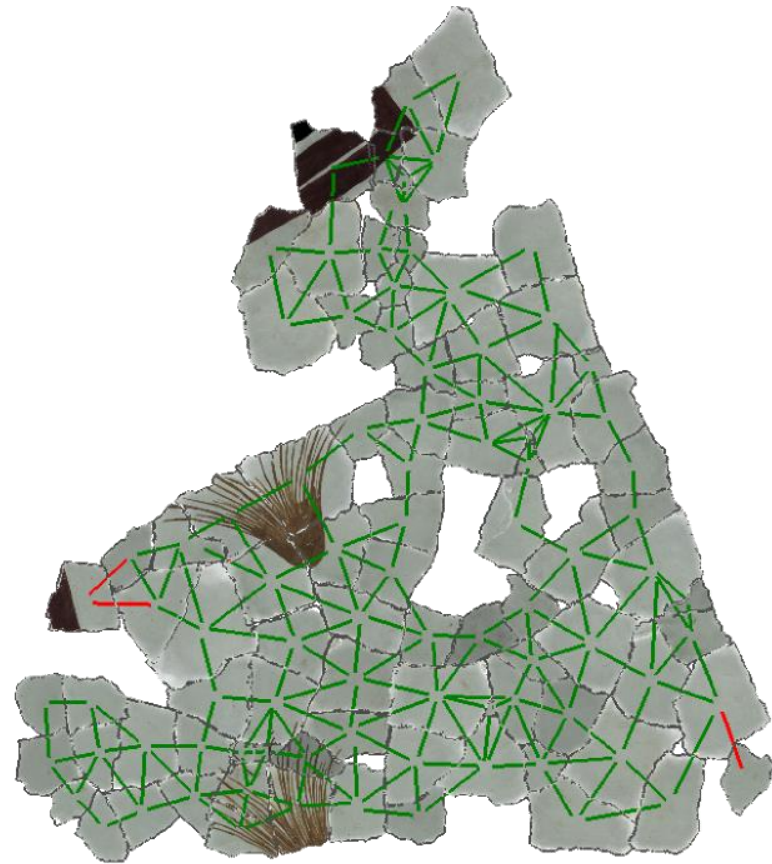
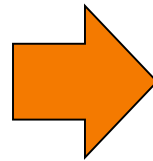
Assembly of  
Correspondences

# Assembly-Aware Correspondences

Approach: search for global assembly directly



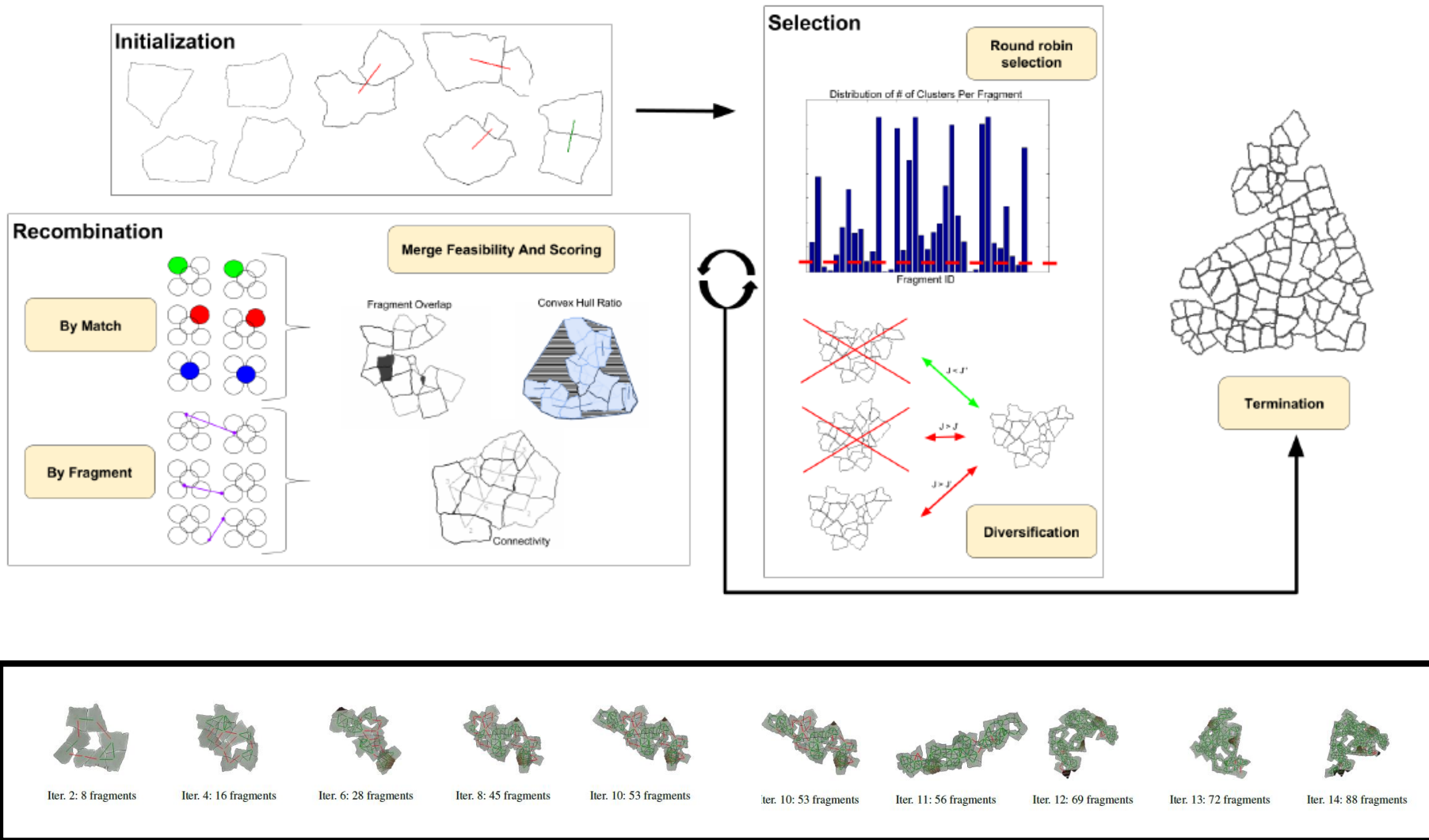
Scanned Fragments



Global Assembly

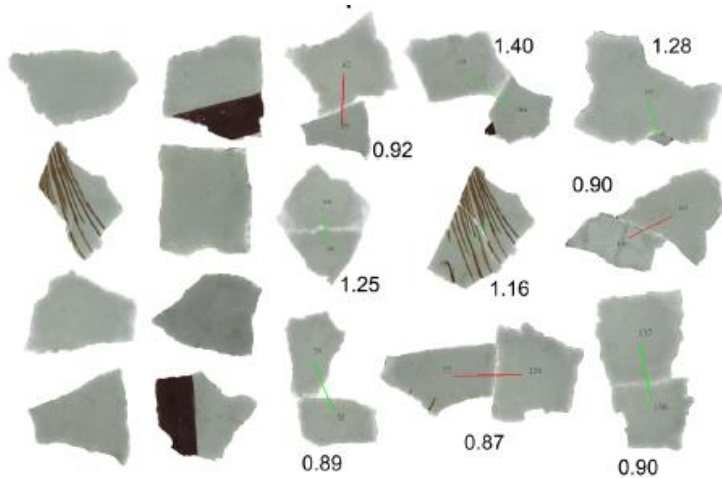
# Assembly Search Algorithm

Genetic algorithm:



# Assembly Search Result

Able to predict correspondences with higher precision and recall with our genetic algorithm



Pairwise Correspondences



Our Result



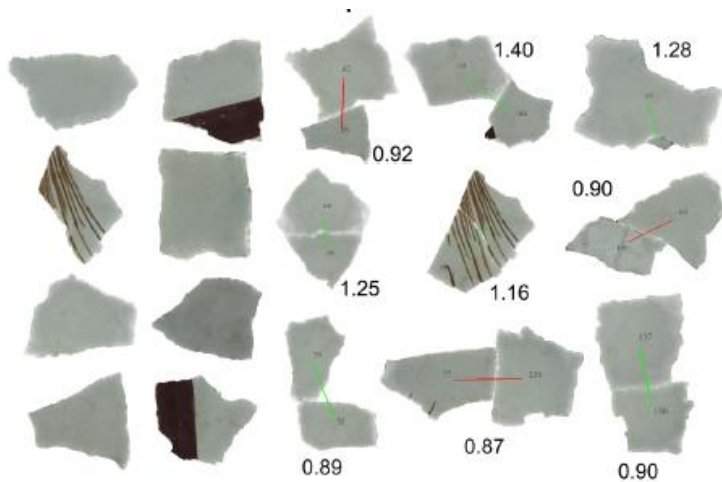
Ground Truth





# Assembly Search Result

Able to predict correspondences with higher precision and recall with our genetic algorithm



Pairwise Correspondences



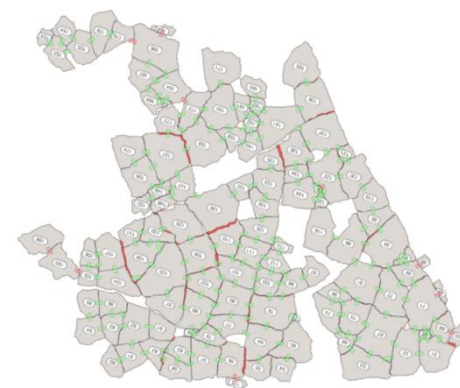
Our Result



Ground Truth



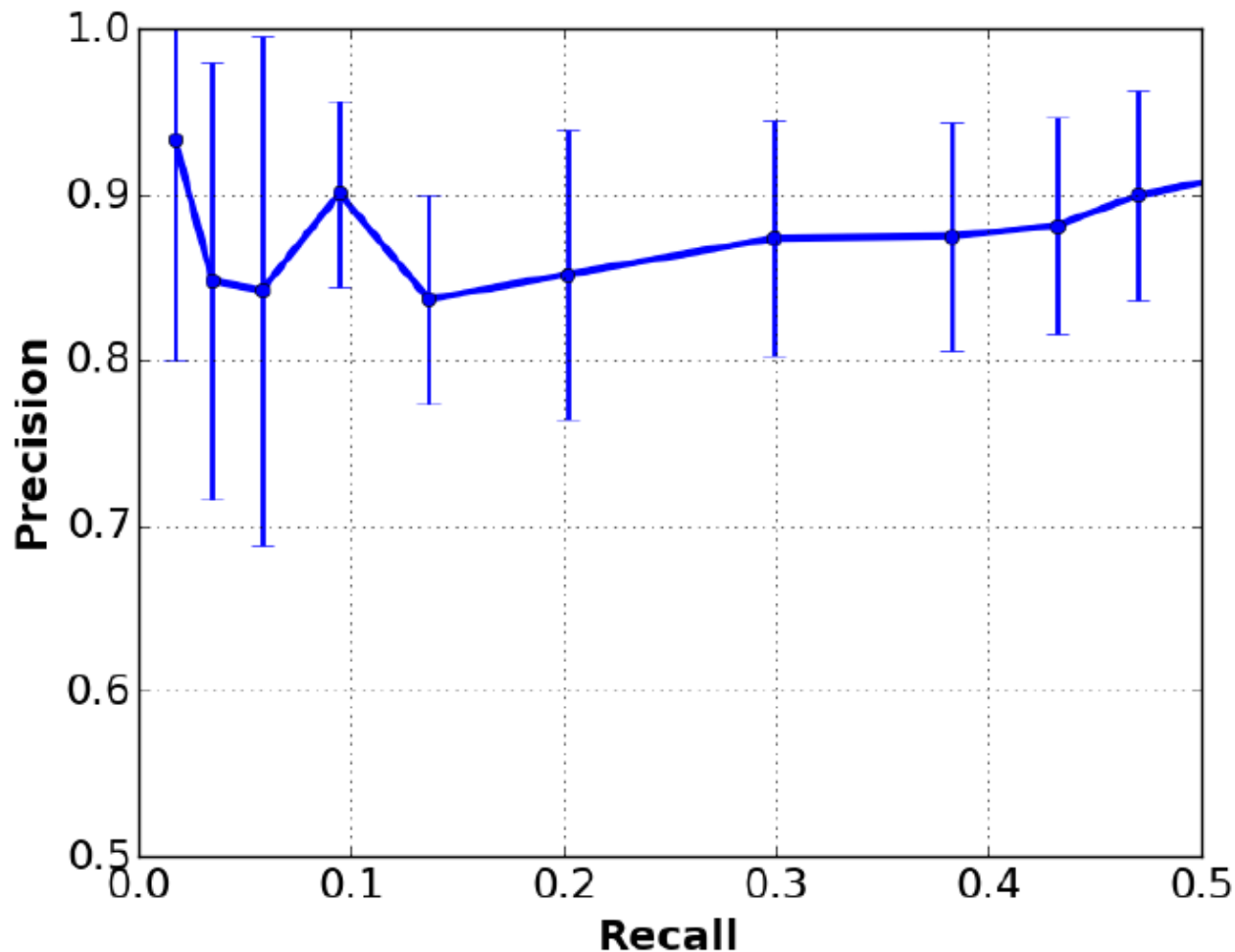
[Hierarchical Clustering]



[Casteneda et al., 2011]

# Assembly Search Result

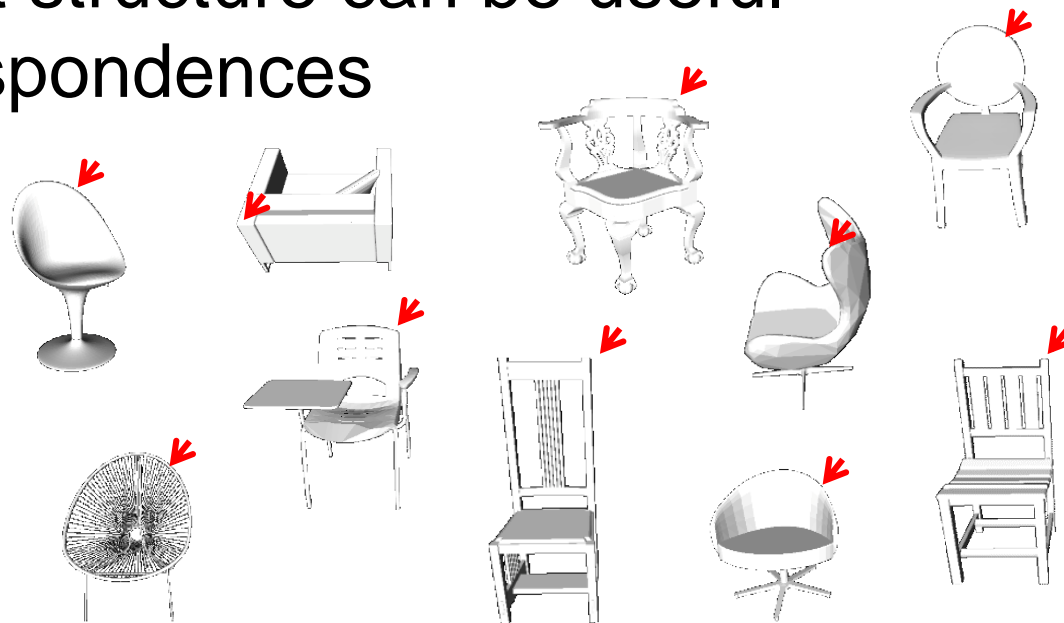
Precision of predicted correspondences gets better as recall increases during our genetic search



# Conclusion

Discovering latent structure can be useful for finding correspondences

- Symmetries
- Parts
- Affordances
- Constraints
- Assemblies



Future work on surface correspondence should focus more on structure and semantics

- Hierarchies, supports, contexts, shape priors, physical properties, manufacturing methods, etc.

# Acknowledgments

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## Collaborators:

- Sid Chaudhuri, Steve Diverdi, Leo Guibas, Maciej Halber, Vladimir Kim, Yaron Lipman, Tianqiang Liu, Wilmot Li, Niloy Mitra, Elena Sizikova

## Data sets:

- Bronstein et al. (TOSCA), Brown et al. (3D Warehouse), Giorgi et al. (SHREC Watertight), Anguelov et al. (SCAPE), Xiao et al. (SUN3D), Weyrich et al. (Fresco)

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- Intel, Adobe, Google, NSF

**Thank You!**