## Some Mesh Surface Properties

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## Curvature

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Curvature  $\kappa$  of a curve is reciprocal of radius of circle that best approximates it

Defined at a point  ${\bf p}$  in a direction  ${\bf w}$ 

Line has  $\kappa = 0$ 





The curvature at a point varies between some minimum and maximum – these are the principal curvatures  $\kappa_1$  and  $\kappa_2$ 

They occur in the *principal directions*  $d_1$  and  $d_2$  which are perpendicular to each other



## **Principal Curvatures**







# $\underbrace{\text{Minimum Curvature}}_{\kappa_1}$

Maximum Curvature  $\kappa_2$ 

## **Gaussian and Mean Curvature**







#### Planar points:

- Zero Gaussian curvature and zero mean curvature
- Tangent plane intersects surface at infinity points



#### Parabolic points:

- Zero Gaussian curvature, non-zero mean curvature
- Tangent plane intersects surface along 1 curves









## What Does Curvature Tell Us?

#### Elliptical points:

- Positive Gaussian curvature
- Convex/concave depending on sign of mean curvature
- Tangent plane intersects surface at 1 point







#### Hyperbolic points:

- Negative Gaussian curvature
- Tangent plane intersects surface along 2 curves







#### Mesh Saliency:

- Motivated by models of perceptual salience
- Difference between mean curvature blurred with  $\sigma$  and blurred with  $2\sigma$







#### Tensor voting

- Extract points {q<sub>i</sub>} in neighborhood
- Compute covariance matrix M
- Analyze eigenvalues and eigenvectors of M (via SVD)
- Eigenvectors are Principal Axes

$$\mathbf{M} = \frac{1}{n} \sum_{i=1}^{n} \begin{bmatrix} q_i^{x} q_i^{x} & q_i^{x} q_i^{y} & q_i^{x} q_i^{z} \\ q_i^{y} q_i^{x} & q_i^{y} q_i^{y} & q_i^{y} q_i^{z} \\ q_i^{z} q_i^{x} & q_i^{z} q_i^{y} & q_i^{z} q_i^{z} \end{bmatrix}$$

#### Covariance Matrix

$$\mathbf{M} = \mathbf{U}\mathbf{S}\mathbf{U}^{t}$$
$$\mathbf{S} = \begin{bmatrix} \lambda_{a} & 0 & 0 \\ 0 & \lambda_{b} & 0 \\ 0 & 0 & \lambda_{c} \end{bmatrix} \quad \mathbf{U} = \begin{bmatrix} A_{x} & A_{y} & A_{z} \\ B_{x} & B_{y} & B_{z} \\ C_{x} & C_{y} & C_{z} \end{bmatrix}$$

Eigenvalues & Eigenvectors

#### Tensor voting

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#### **Covariance Matrix**

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Eigenvalues & Eigenvectors

Eigenvectors are "Principal Axes of Inertia"

Eigenvalues are variances of the point distribution in those directions







Provides estimate of normal direction

• Eigenvector (principal axis) associated with smallest eigenvalue



## What Does PCA Tell Us?



Helps us construct a local coordinate frame for every point

- Map  $\hat{e}_1$  to X axis
- Map  $\hat{e}_2$  to Y axis
- Map  $\hat{e}_3$  to Z axis





## What Does PCA Tell Us?



Helps differentiate nearly plane-like, from stick-like, from sphere-like, etc.



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 $\lambda_2 / (\lambda_1 + \lambda_2 + \lambda_3)$ 

## **Statistics of Distances**

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#### Distances can be along surface (geodesic) or as a crow flies (Euclidean)



Geodesic distance to point



Geodesic vs. Euclidean distance



### **Statistics of Distances**



#### Average geodesic distance to other points on surface



## What Do Statistics of Distance Tell Us?



#### Histograms of geodesic distances

- Small distances relate to curvature
- Long distances relate to centeredness



## **Shape Diameter Function**

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#### Median distance along sampling of rays through interior





## **Shape Diameter Function**



Distinguish between thin and thick parts in a model Sharp changes often correlate with part boundaries





## Mesh Surface Properties in Assignment 2