

COS 226	Algorithms and Data Structures	Fall 2015
Final Exam		

You have 180 minutes for this exam. The exam is closed book, except that you are allowed to use one page of notes (8.5-by-11, one side, in your own handwriting). No calculators or other electronic devices are permitted. Give your answers and show your work in the space provided. You may use the back of each page for scratch space, or to continue long answers.

Name:	
NetID:	
Precept:	

- | | | |
|------|-------|----------------|
| P01 | 9:00 | Andy Guna |
| P02 | 10:00 | Andy Guna |
| P02A | 10:00 | Elena Sizikova |
| P03 | 11:00 | Maia Ginsburg |
| P03A | 11:00 | Nora Coler |
| P04 | 12:30 | Maia Ginsburg |
| P04A | 12:30 | Miles Carlsten |
| P05 | 1:30 | Tom Wu |

Write and sign: *“I pledge my honor that I have not violated the Honor Code during this examination.”*

Grading note: To ensure that guessing on true/false and multiple-choice questions does not affect your expected score, grading on these questions will be as follows:

- True / False: +1 point if correct, -1 point if incorrect, 0 points if left unanswered.
Multiple choice: +2 points if correct, -0.4 points if incorrect, 0 points if left unanswered.

Problem	Score
0	
1	
2	
3	
4	
5	
6	
Sub 1	

Problem	Score
7	
8	
9	
10	
11	
12	
13	
Sub 2	

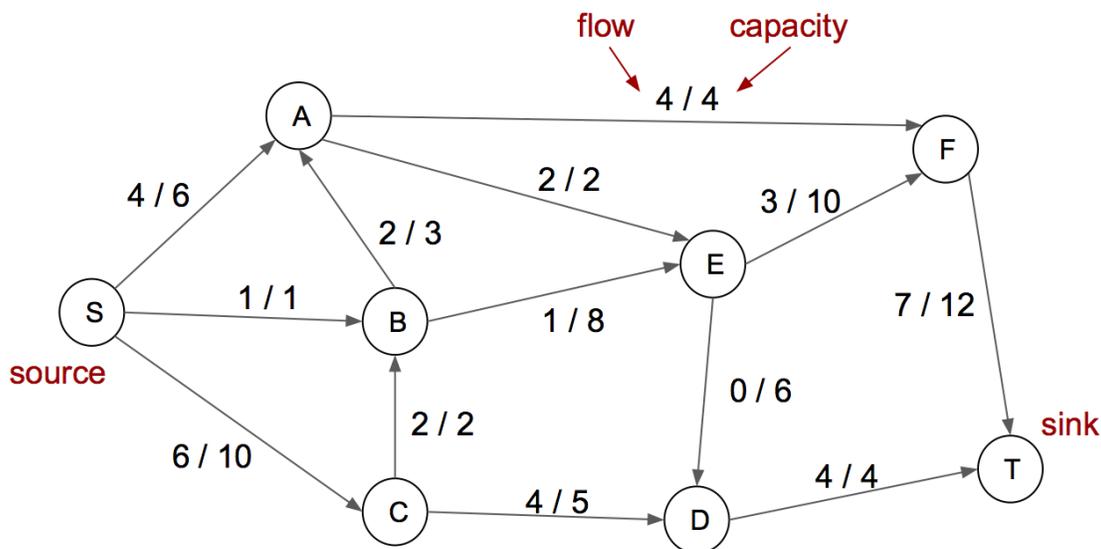
Total:

0. Init. (1 point)

In the space provided on the front of the exam, **write** your name, Princeton netID, and precept number, and **write and sign** the honor code.

1. Flow. (10 points)

Consider the following flow network and feasible flow f from the source vertex S to the sink vertex T.



(a) What is the value of the flow f ? **Circle** the correct answer.

- 3 5 7 11 13 17

(b) Starting from the flow given above, perform one iteration of the Ford-Fulkerson algorithm. **List** the sequence of vertices on the augmenting path, in order from S to T.

(c) What is the value of the maximum flow? **Circle** the correct answer.

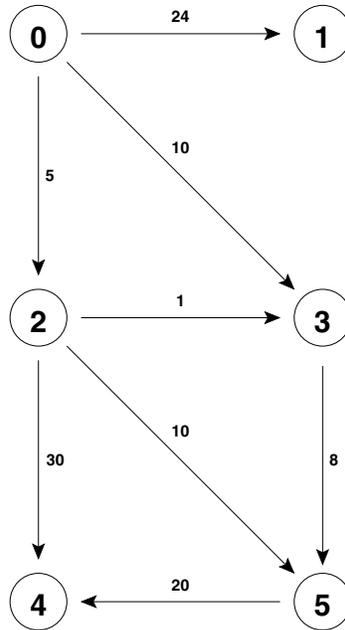
- 3 5 7 11 13 17

(d) **Circle** all vertices on the sink (T) side of the minimum cut.

- S A B C D E F T

2. SPT. (12 points)

Simulate Dijkstra's algorithm on the edge-weighted digraph below, starting from vertex 0.



(a) **Fill in** the following table:

	distTo []	edgeTo []
0		
1		
2		
3		
4		
5		

(b) What is the maximum number of items in the priority queue? **Circle** the correct answer.

- 1 2 3 4 5 6

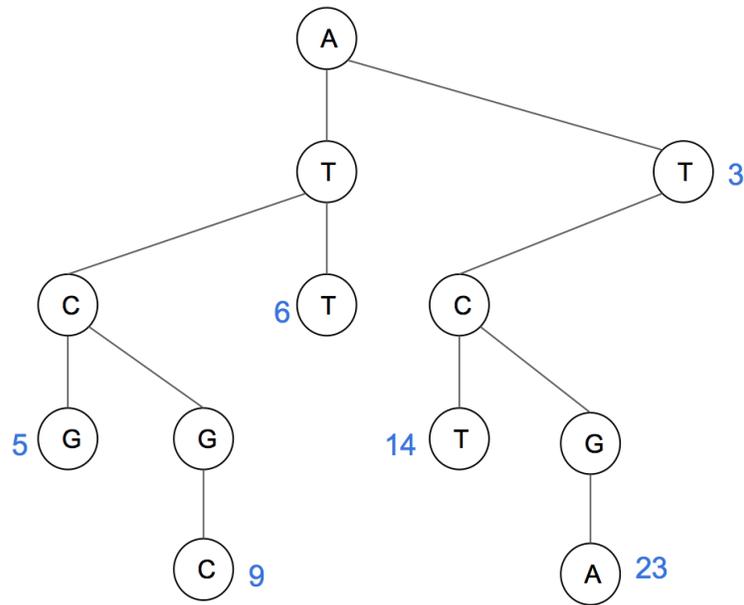
(c) What is the last vertex popped from the priority queue? **Circle** the correct answer.

- 0 1 2 3 4 5

(d) What letter is spelled out by the edges of the shortest-paths tree (SPT) computed by Dijkstra's algorithm?

3. TST. (13 points)

Consider the following Ternary Search Trie (TST), where the values are shown next to the nodes of the corresponding string keys.



(a) We would like to construct the above TST by inserting six strings into an empty TST. **Circle** the sequences below that **can** produce the above TST. There may be multiple correct answers.

Sequence 1: ATT ACG T CT AGC GA

Sequence 2: ATT T CT ACG GA AGC

Sequence 3: ATT T GA ACG CT AGC

Sequence 4: ATT T AGC ACG CT GA

Sequence 5: ATT ACG AGC T CT GA

Sequence 6: ATT T AGC GA ACG CT

Sequence 7: ATT ACG T CT GA AGC

(b) Insert the three strings CA, AGA, and GAC into the TST with the associated values 0, 18, and 29, respectively. **Update the figure above** to reflect the changes.

4. KMP DFA. (13 points)

(a) Below is a partially-completed Knuth-Morris-Pratt DFA for a string s of length 6 over the alphabet $\{A, B\}$. State 6 is the accept state. **Fill in** all the missing spots in the table.

	j	0	1	2	3	4	5
pat.charAt(j)	A	1	1				
B				3			3

(b) Given the following KMP DFA:

j	0	1	2	3	4	5	6
A	1	1	3	1	5	1	5
B	0	2	0	4	0	6	7

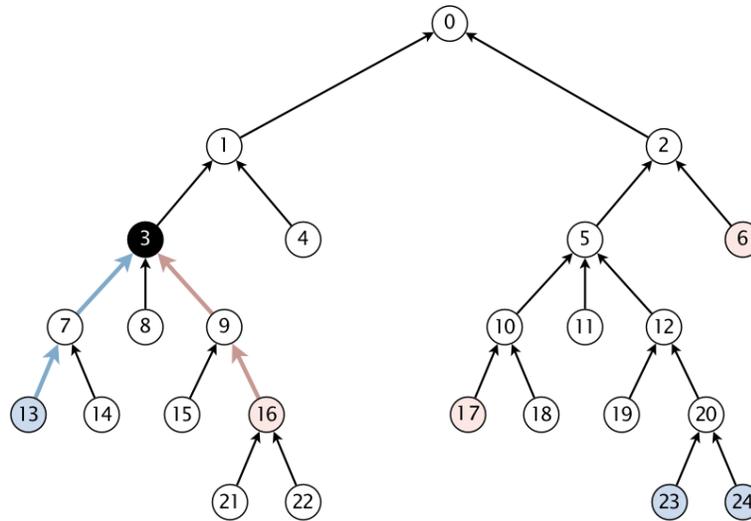
List the string that this DFA searches for.

(c) Given each of the following strings as input, what state would the DFA in (b) end in? **Circle** the correct answer for each string.

- BABBAA: 0 1 2 3 4 5 6 accept
- ABABABA: 0 1 2 3 4 5 6 accept
- BABABABA: 0 1 2 3 4 5 6 accept
- BBAABBABAB: 0 1 2 3 4 5 6 accept

5. DAG. (10 points)

Consider the following directed graph.



A = { 13, 23, 24 }, B = { 6, 16, 17 }

shortest ancestral path: 13-7-3-9-16

(a) You wish to find the shortest common ancestor (SCA) of the two given sets, using BFS. **List the first six** vertices added to the queue by running `BreadthFirstDirectedPaths.java` on an iterator with the sources from set A = {13,23,24}?

(b) **How many** vertices in all will `BreadthFirstDirectedPaths.java` visit when passed an iterator with the sources from set B = {6,16,17}?

(c) Using BFS to find the SCA can take running time proportional to $V + E$. Suppose you wished to use DFS instead. What would be the order-of-growth running time? **Circle** the correct answer.

constant
 $V + E$
 $E \log V$
 $V \log E$
 $(V + E)^2$
exponential

(d) True or false: any pair of vertices in a **rooted** directed acyclic graph (DAG) has at least one shortest common ancestor.

True False

(e) True or false: any pair of vertices in **any** DAG for which a topological sort exists has at least one shortest common ancestor.

True False

6. Regex. (11 points)

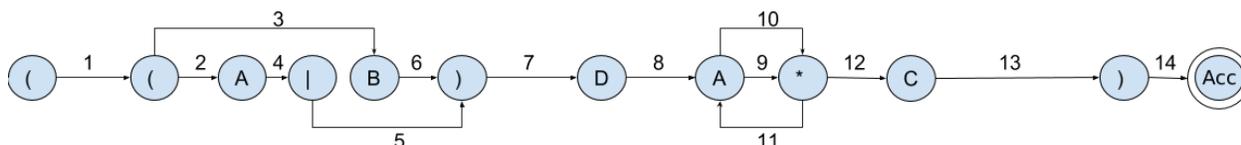
(a) Consider the regular expression

$$((A|B)DA^*C)$$

Circle all words matched by this regular expression.

ABDAC ADAAC ABDACA BDC BDAC AACA

(b) The following NFA matches the regular expression in (a):



Which of the labeled edges correspond to ϵ transitions (as opposed to *match* transitions)? **Circle the numbers** of only the ϵ transitions:

1 2 3 4 5 6 7 8 9 10 11 12 13 14

(c) Which of the following (if any) are true reasons why we usually prefer NFAs for matching a regular expression (RE), as opposed to DFAs? **Circle** the correct answer in each case.

The size of the NFA is linear in the size of the RE, while the size of the DFA might be as bad as quadratic.

True False

The size of the NFA is linear in the size of the RE, while the size of the DFA might be as bad as exponential.

True False

The running time to simulate the NFA is linear in the size of the RE, while the running time for the DFA might be as bad as quadratic.

True False

The running time to simulate the NFA is linear in the size of the RE, while the running time for the DFA might be as bad as exponential.

True False

The NFA only has two kinds of transitions (match and ϵ), while the DFA requires determining the correct transition for each possible input character.

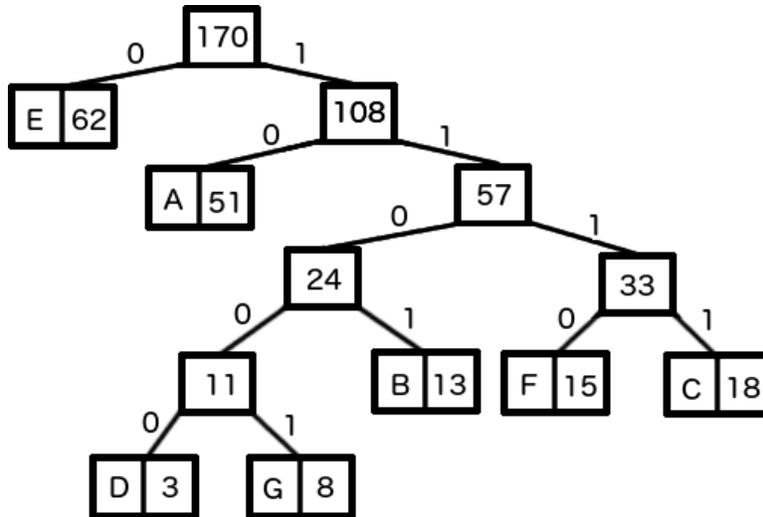
True False

The DFA might require backing up in the input stream, while the NFA does not.

True False

7. Huffman. (10 points)

Consider the following Huffman tree:



(a) Decode the following 24-bit bitstring: 111000110001100001011000

(b) What is the compression ratio (compressed size / uncompressed size) for the above bitstring? Assume that characters were represented by 8 bits before compression.

(c) What is the *best* compression ratio achievable on *any* string using this Huffman tree?

(d) Suppose you added another character, H, with a count of 1. After re-creating the new Huffman code, *circle all* the letters that acquire a *different* codeword.

A B C D E F G

(e) Using the Huffman code from (d), what is the *worst* compression ratio achievable on *any* string?

8. Graph T/F. (10 points)

(a) The adjacency matrix representation is usually preferred over adjacency lists, especially for storing sparse graphs compactly.

True False

(b) Given the data structures produced by depth-first search (DFS), one can check whether a given vertex is connected to the source in constant time.

True False

(c) Breadth-first search (BFS) will visit every vertex in a directed graph, in nondecreasing order from the source.

True False

(d) BFS and DFS are interchangeable and equally practical for all applications of graph search.

True False

(e) Kruskal's algorithm computes the minimum spanning tree (MST) in time proportional to $E \log E$ (in the worst case).

True False

(f) Given any directed graph, there is always a shortest-paths tree (SPT) containing every vertex reachable from a source vertex s .

True False

(g) Dijkstra's algorithm can find shortest paths in a directed graph with negative weights, but no negative cycles.

True False

(h) An st -cut in a graph is any partition of vertices into two disjoint sets, such that vertices s and t wind up in different sets.

True False

(i) A graph flow is a max flow if and only if there exists no cut with the same capacity as the flow's value.

True False

(j) The choice of which augmenting paths to consider first in the Ford-Fulkerson algorithm doesn't impact the number of paths that need to be considered.

True False

9. Sort. (14 points)

The column on the left is an array of strings to be sorted. The column on the right is in sorted order. The other columns are the contents of the array at some intermediate step during one of the algorithms below. **Write the number** of each algorithm under the corresponding column. You may use each number more than once.

mink	bear	bear	calf	crow	myna	crab	bear	bear
moth	calf	calf	lamb	lamb	crab	toad	crow	calf
crow	crow	crow	hare	deer	lamb	swan	calf	crab
myna	crab	crab	wasp	crab	toad	bear	crab	crow
swan	deer	hare	hawk	hare	mule	deer	deer	deer
wolf	hare	kiwi	ibex	bear	hare	ibex	hare	hare
mule	hawk	deer	bear	kiwi	sole	hoki	hawk	hawk
slug	hoki	hawk	deer	calf	wolf	mule	hoki	hoki
hare	ibex	ibex	mink	hawk	calf	sole	ibex	ibex
bear	kiwi	hoki	lion	ibex	slug	wolf	kiwi	kiwi
kiwi	lion	lion	kiwi	hoki	moth	calf	lion	lamb
calf	lynx	lynx	slug	lion	kiwi	lamb	lynx	lion
hawk	lamb	lamb	toad	lynx	hoki	myna	lamb	lynx
ibex	mink	mink	hoki	mink	mink	mink	mink	mink
oryx	moth	mule	sole	mule	hawk	lynx	moth	moth
lion	myna	myna	wolf	myna	swan	lion	myna	mule
sole	mule	moth	moth	moth	lion	crow	mule	myna
wasp	oryx	wasp	crab	wasp	wasp	hare	oryx	oryx
lynx	swan	sole	crow	sole	bear	wasp	swan	slug
hoki	slug	oryx	oryx	oryx	deer	moth	slug	sole
crab	sole	slug	mule	slug	crow	slug	sole	swan
deer	toad	wolf	swan	wolf	ibex	kiwi	toad	toad
lamb	wolf	toad	myna	toad	oryx	hawk	wolf	wasp
toad	wasp	swan	lynx	swan	lynx	oryx	wasp	wolf
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0								4

(0) Original input

(1) 3-way radix quicksort
(no shuffle)

(2) LSD radix sort

(3) MSD radix sort

(4) Sorted

10. G^2 . (10 points)

The *square* of a digraph G consisting of vertices V and edges E is a digraph G^2 such that:

- the vertices in G^2 are the same as the vertices in G , and
- two vertices in G^2 are connected by an edge (u, v) if and only if G contains edges (u, w) and (w, v) , for some vertex w .

That is, vertices u and v are connected by an edge in G^2 whenever G contains a path with exactly *two* edges from u to v .

Describe an algorithm for computing the square of a digraph (represented using adjacency lists). For full credit, your solution should run in $O(VE)$ time. To simplify the problem, you need not remove duplicates from the adjacency lists in G^2 .

11. ST Analysis. (10 points)

You are deciding between symbol table implementations to store L -character strings, consisting of characters from the extended-ASCII ($R = 256$) character set. Analyze the **worst-case** order-of-growth running time required by the `get()` operation (with the key present in the symbol table—i.e., a search hit) for the following implementations, assuming that N strings are already in the symbol table. **Circle** the correct answer in each case.

(a) A Left-Leaning Red-Black BST of strings.

Worst-case number of **character comparisons**:

$$\lg N \quad \lg^2 N \quad L + \lg^2 N \quad L \lg N \quad (\lg N)(\log_R L) \quad NL$$

(b) An M -entry hash table with separate chaining. Assume the hash table has been resized such that the average chain length N/M is bounded: $2 \leq N/M \leq 8$. Do not include the time to compute the `hashCode`.

Worst-case number of **character comparisons**:

$$M + L \quad NL/M \quad ML/N \quad (N/M) \log_R L \quad (\log_R L) \left(1 + \frac{1}{1 - N/M} \right) \quad NL$$

(c) An M -entry hash table with linear probing. Assume the hash table has been resized such that the average occupancy N/M is bounded: $1/8 \leq N/M \leq 1/2$. Do not include the time to compute the `hashCode`.

Worst-case number of **character comparisons**:

$$M + L \quad NL/M \quad ML/N \quad (N/M) \log_R L \quad (\log_R L) \left(1 + \frac{1}{1 - N/M} \right) \quad NL$$

(d) An R -way trie.

Worst-case number of **array accesses**:

$$R \quad L \quad R + L \quad RL \quad \log_R N \quad L + \log_R N$$

(e) A ternary search trie (TST).

Worst-case number of **character comparisons**:

$$R \quad L \quad R + L \quad RL \quad \log_R N \quad L + \log_R N$$

12. Reduction. (10 points)

(a) The FIND-42ND problem is to find the 42nd smallest item in an (initially unsorted) array. You can implement this easily by sorting the array in $O(N \log N)$ time and returning the item in the 42nd position. Given this, which of the following (if any) must be true? **Circle** the correct answer in each case.

FIND-42ND reduces to sorting.

True False

Sorting reduces to FIND-42ND.

True False

$O(N \log N)$ is a lower bound on FIND-42ND.

True False

$O(N \log N)$ is an upper bound on FIND-42ND.

True False

FIND-42ND must be NP-complete.

True False

FIND-42ND cannot be NP-complete unless $P = NP$.

True False

(b) Of course, it is also easy to implement FIND-42ND in $O(N)$ time, using $O(42)$ additional space. Furthermore, it is possible to show that linear time is the lower bound on FIND-42ND, since all elements must be examined. Given this algorithm and the reduction in (a), which of the following (if any) must be true:

$O(N)$ is a lower bound on sorting.

True False

$O(N)$ is an upper bound on sorting.

True False

Sorting is strictly harder than FIND-42ND, so can never be accomplished in $O(N)$ time.

True False

New developments in sorting might result in an asymptotically faster algorithm for FIND-42ND.

True False

13. MST. (16 points)

You are given an edge-weighted undirected graph, using the adjacency list representation, together with the list of edges in its minimum spanning tree (MST). Describe an efficient algorithm for updating the MST, when each of the following operations is performed on the graph. Assume that common graph operations (e.g., DFS, BFS, finding a cycle, etc.) are available to you, and don't describe how to re-implement them.

- (a) Update the MST when the weight of an edge that *was not* part of the MST is *decreased*.
Give the order-of-growth running time of your algorithm as a function of V and/or E .

- (b) Update the MST when the weight of an edge that *was* part of the MST is *decreased*.
Give the order-of-growth running time of your algorithm as a function of V and/or E .

(c) Update the MST when the weight of an edge that *was not* part of the MST is *increased*.
Give the order-of-growth running time of your algorithm as a function of V and/or E .

(d) Update the MST when the weight of an edge that *was* part of the MST is *increased*.
Give the order-of-growth running time of your algorithm as a function of V and/or E .