

Midterm Solutions

1. Analysis of algorithms.

- (a) $\frac{3}{800,000,000}N^3$
 (b) N^3

2. Data structure and algorithm properties.

- (a) *E* Min height of a binary heap with N keys. A. ~ 1
E Max height of a binary heap with N keys. B. $\sim \frac{1}{2} \lg N$
C Min height of a 2-3 tree with N keys. C. $\sim \log_3 N$
E Max height of a 2-3 tree with N keys. D. $\sim \ln N$
E Min height of left-leaning red-black BST with N keys. E. $\sim \lg N$
F Max height of left-leaning red-black BST with N keys. F. $\sim 2 \lg N$
A Min height of a weighted quick union tree with N items. G. $\sim 2 \ln N$
E Max height of a weighted quick union tree with N items. H. $\sim N$

- (b) insertion sort and top-down mergesort are parsimonious

Selection sort counterexample: C B A. The keys B and C get compared twice, once in first iteration and once in second iteration.

Heapsort counterexample: C B A. The keys A and B get compared twice, once in the heap construction phase (when sinking C) and once in the sortdown phase (when sinking A after C and A are exchanged).

3. Data structures.

- (a)
 - Best case: $\sim 2N$
When the array is full.
 - Worst case: $\sim 8N$
When the array is one-quarter full.

<i>operation</i>	<i>description</i>	<i>time</i>
charAt(int i)	<i>return the ith character in sequence</i>	1
deleteCharAt(int i)	<i>delete the ith character in the sequence</i>	N
append(char c)	<i>append c to the end of the sequence</i>	1
set(int i, char c)	<i>replace the ith character with c</i>	1

4. **8 sorting and shuffling algorithms.**

7 9 3 5 4 2 6 8

5. **Red-black BSTs.**

(a) U V W X

(b) P S Y

	E	N	G
(c) rotateLeft()	1	1	1
rotateRight()	0	0	3
flipColors()	1	0	3

6. **Hashing.**

(a)	0	1	2	3	4	5	6
	G	D	B	F	E	A	C

(b) I. Possible.

Consider the order F D B G E C A.

II. Impossible.

No key is in the correct position.

III. Impossible.

We can assume B and G were inserted first since they are in correct position. But then third key inserted is guaranteed to be in correct position.

7. **Comparing two arrays of points.**

(a) • Sort $a[]$ using heapsort (using the point's natural order).

- For each point $b[j]$, use binary search to search for it in the sorted array $a[]$, incrementing a counter if found.

(b) $N \log M$.

The running time is $M \log M$ for the sort and $N \log M$ for the N binary searches. Since $N \geq M$, the latter term is the bottleneck.

(c) 1.

Both heapsort and binary search use at most a constant amount of extra space.

8. Randomized priority queue.

- `sample()`: Pick a random array index r (between 1 and N) and return the key $a[r]$.
- `delRandom()`:
 - *Select*: pick a random array index r (between 1 and N) and save away the key $a[r]$, to be returned.
 - *Delete*: exchange $a[r]$ and $a[N]$ and decrement N .
 - *Restore heap order invariants*: call `sink(r)` and `swim(r)` to fix up any heap order violation at r . Note that $a[N]$ in the original heap need not be the largest key, so the call to `swim(r)` is necessary.

```
public Key sample() {
    int r = 1 + StdRandom.uniform(N); // between 1 and N
    return a[r];
}

public Key delRandom() {
    int r = 1 + StdRandom.uniform(N); // between 1 and N
    Key key = a[r]; // save away
    exch(r, N--); // to make deleting easy
    sink(r); // if a[N] was too big
    swim(r); // if a[N] was too small
    a[N+1] = null; // avoid loitering
    return key;
}
```