



## Performance Improvement Revisited

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## Goals of this Lecture

- **Help you learn how to:**
  - Improve program performance by exploiting knowledge of underlying system
    - Compiler capabilities
    - Hardware architecture
    - Program execution
- **And thereby:**
  - Help you to write efficient programs
  - Review material from the second half of the course

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## Improving Program Performance

- **Most programs are already “fast enough”**
  - No need to optimize performance at all
  - Save your time, and keep the program simple/readable
- **Most parts of a program are already “fast enough”**
  - Usually only a small part makes the program run slowly
  - Optimize *only* this portion of the program, as needed
- **Steps to improve execution (time) efficiency**
  - Do timing studies (e.g., gprof)
  - Identify hot spots
  - **Optimize that part of the program**
  - Repeat as needed

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## Ways to Optimize Performance

- **Better data structures and algorithms**
  - Improves the “*asymptotic complexity*”
    - Better scaling of computation/storage as input grows
    - E.g., going from  $O(n^2)$  sorting algorithm to  $O(n \log n)$
  - Clearly important if large inputs are expected
  - Requires understanding data structures and algorithms
- **Better source code the compiler can optimize**
  - Improves the “*constant factors*”
    - Faster computation during each iteration of a loop
    - E.g., going from  $1000n$  to  $10n$  running time
  - Clearly important if a portion of code is running slowly
  - Requires understanding hardware, compiler, execution

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## Helping the Compiler Do Its Job

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## Limitations of Optimizing Compilers



- **Fundamental constraint**
  - Compiler must not change program behavior
  - Even under rare pathological inputs
- Behavior that may be obvious to the programmer can be obfuscated by languages and coding styles
  - Data ranges more limited than variable types suggest
  - Array elements remain unchanged by function calls
- **Most analysis is performed only within functions**
  - Whole-program analysis is too expensive in most cases
- **Most analysis is based only on static information**
  - Compiler has difficulty anticipating run-time inputs

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## Avoiding Repeated Computation



- A good compiler recognizes simple optimizations
  - Avoiding redundant computations in simple loops
  - Still, programmer may still want to make it explicit
- **Example**
  - Repetition of computation:  $n * i$

```
for (i = 0; i < n; i++)
  for (j = 0; j < n; j++)
    a[n*i + j] = b[j];
```



```
for (i = 0; i < n; i++) {
  int ni = n * i;
  for (j = 0; j < n; j++)
    a[ni + j] = b[j];
}
```

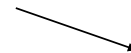
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## Worrying About Side Effects



- Is this transformation okay?

```
int func1(int x) {
  return f(x) + f(x) + f(x) + f(x);
}
```



```
int func1(int x) {
  return 4 * f(x);
}
```

- Not necessarily, if

```
int counter = 0;
int f(int x) {
  return counter++;
}
```

And this function may be defined in another file known only at link time

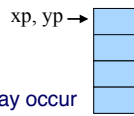
- **Compiler cannot always avoid repeated computation**
  - May not know if the code has a "side effect"
  - ... that makes the transformation change the code's behavior

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## Memory Aliasing



- **Memory aliasing**
  - Single data location accessed through multiple names
  - E.g., two pointers that point to the same memory location
- **Modifying the data using one name**
  - Implicitly modifies the values seen through other names
- **Blocks optimization by the compiler**
  - The compiler cannot tell when aliasing may occur
  - ... and so must forgo optimizing the code
- **Programmer often *does* know**
  - And *can* optimize the code accordingly



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## Aliasing Example



- Is this optimization okay?

```
int *x, *y;  
...  
*x = 5;  
*y = 10;  
printf("x=%d\n", *x);
```

printf("x=5\n");

- **Not necessarily**
  - If y and x point to the same location in memory...
  - ... the correct output is "x = 10\n"

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## Summary: Helping the Compiler



- **Compiler can perform many optimizations**
  - Register allocation
  - Code selection and ordering
  - Eliminating minor inefficiencies
- **But often the compiler needs your help**
  - Knowing if code is free of side effects
  - Knowing if memory aliasing will not happen
- **Modifying the code can lead to better performance**
  - Profile the code to identify the "hot spots"
  - Look at the assembly language the compiler produces
  - Rewrite the code to get the compiler to do the right thing

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## Exploiting the Hardware



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## Underlying Hardware



- Implements a collection of instructions
  - Instruction set varies from one architecture to another
  - Some instructions may be faster than others
- Registers and caches are faster than main memory
  - Number of registers and sizes of caches vary
  - Exploiting both spatial and temporal locality
- Exploits opportunities for parallelism
  - Pipelining: decoding one instruction while running another
    - Benefits from code that runs in a sequence
  - Superscalar: perform multiple operations per clock cycle
    - Benefits from operations that can run independently
  - Speculative execution: performing instructions before knowing they will be reached (e.g., without knowing outcome of a branch)

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## Addition Faster Than Multiplication



- Adding instead of multiplying
  - Addition is faster than multiplication
- Recognize sequences in products
  - Replace multiplication with repeated addition

```
for (i = 0; i < n; i++) {  
    int ni = n * i;  
    for (j = 0; j < n; j++)  
        a[ni + j] = b[j];  
}
```

```
int ni = 0;  
for (i = 0; i < n; i++) {  
    for (j = 0; j < n; j++)  
        a[ni + j] = b[j];  
    ni += n;  
}
```

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## Bit Operations Faster Than Arithmetic



- Use shifts to multiply/divide by powers of 2
    - “x >> 3” is faster than “x/8”
    - “x << 3” is faster than “x \* 8”
- 53    0 0 1 1 0 1 0 1
- 53 << 2    1 1 0 1 0 0 0 0
- Bit masking is faster than mod operation
    - “x & 15” is faster than “x % 16”
- 53    0 0 1 1 0 1 0 1
- & 15    0 0 0 0 1 1 1 1
- 5    0 0 0 0 0 1 0 1

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## Caching: Matrix Multiplication



- Caches
  - Slower than registers, but faster than main memory
  - Both instruction caches and data caches
- Locality
  - Temporal locality: recently-referenced items are likely to be referenced in near future
  - Spatial locality: Items with nearby addresses tend to be referenced close together in time
- Matrix multiplication
  - Multiply n-by-n matrices A and B, and store in matrix C
  - Performance heavily depends on effective use of caches

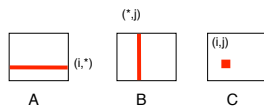
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## Matrix Multiply: Cache Effects



```
for (i=0; i<n; i++) {
  for (j=0; j<n; j++) {
    for (k=0; k<n; k++)
      c[i][j] += a[i][k] * b[k][j];
  }
}
```

- Reasonable cache effects
  - Good spatial locality for A
  - Poor spatial locality for B
  - Good temporal locality for C



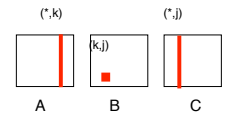
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## Matrix Multiply: Cache Effects



```
for (j=0; j<n; j++) {
  for (k=0; k<n; k++) {
    for (i=0; i<n; i++)
      c[i][j] += a[i][k] * b[k][j];
  }
}
```

- Rather poor cache effects
  - Bad spatial locality for A
  - Good temporal locality for B
  - Bad spatial locality for C



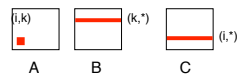
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## Matrix Multiply: Cache Effects



```
for (k=0; k<n; k++) {
  for (i=0; i<n; i++) {
    for (j=0; j<n; j++)
      c[i][j] += a[i][k] * b[k][j];
  }
}
```

- Good cache effects
  - Good temporal locality for A
  - Good spatial locality for B
  - Good spatial locality for C



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## Parallelism: Loop Unrolling



- What limits the performance?

```
for (i = 0; i < length; i++)
  sum += data[i];
```

- Limited apparent parallelism
  - One main operation per iteration (plus book-keeping)
  - Not enough work to keep multiple functional units busy
  - Disruption of instruction pipeline from frequent branches
- Solution: unroll the loop
  - Perform multiple operations on each iteration

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## Understanding Program Execution

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## Avoiding Function Calls

- **Function calls are expensive**
  - Caller saves registers and pushes arguments on stack
  - Callee saves registers and pushes local variables on stack
  - Call and return disrupt the sequence flow of the code
- **Function inlining:**

```
void g(void) {
    /* Some code */
}

void f(void) {
    ...
    g();
    ...
}
```

Some compilers support  
“inline” keyword directive.

```
void f(void) {
    ...
    /* Some code */
    ...
}
```

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## Writing Your Own Malloc and Free

- **Dynamic memory management**
  - `malloc()` to allocate blocks of memory
  - `free()` to free blocks of memory
- **Existing `malloc()` and `free()` implementations**
  - Designed to handle a wide range of request sizes
  - Good most of the time, but rarely the best for all workloads
- **Designing your own dynamic memory management**
  - Forego using traditional `malloc()` and `free()`, and write your own
  - E.g., if you know all blocks will be the same size
  - E.g., if you know blocks will usually be freed in the order allocated
  - E.g., <insert your known special property here>

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## Conclusion

- **Work smarter, not harder**
  - No need to optimize a program that is “fast enough”
  - Optimize only when, and where, necessary
- **Speeding up a program**
  - Better data structures and algorithms: better asymptotic behavior
  - Optimized code: smaller constants
- **Techniques for speeding up a program**
  - Coax the compiler
  - Exploit capabilities of the hardware
  - Capitalize on knowledge of program execution

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