



## Assembly Language: IA-32 Instructions

1



## Goals of this Lecture

- **Help you learn how to:**
  - Manipulate data of various sizes
  - Leverage more sophisticated addressing modes
  - Use condition codes and jumps to change control flow
  - ... and thereby ...
  - Write more efficient assembly-language programs
  - Understand the relationship to data types and common programming constructs in high-level languages
- **Focus is on the assembly-language code**
  - Rather than the layout of memory for storing data (see precept)

2



## Handling Different Data Sizes

3



## Variable Sizes in High-Level Language

- **C data types vary in size**
  - Character: 1 byte
  - Short, int, and long: varies, depending on the computer
  - Float and double: varies, depending on the computer
  - Pointers: typically 4 bytes
- **Programmer-created types**
  - Struct: arbitrary size, depending on the fields
- **Arrays**
  - Multiple consecutive elements of some fixed size
  - Where each element could be a struct

4

## Supporting Different Sizes in IA-32

- Three main data sizes
  - Byte (b): 1 byte
  - Word (w): 2 bytes
  - Long (l): 4 bytes
- Separate assembly-language instructions
  - E.g., addb, addw, and addl
- Separate ways to access (parts of) a register
  - E.g., for EAX register: %ah or %al, %eax, and %eax
- Larger sizes (e.g., struct)
  - Manipulated in smaller byte, word, or long units

5

## Byte Order in Multi-Byte Entities

- IA-32 is a **little endian** architecture
  - Least significant byte of multi-byte entity is stored at lowest memory address
  - “Little end goes first”

The 4-byte int 5 (hex 00 00 00 05) at address 1000:

1000	00000101
1001	00000000
1002	00000000
1003	00000000

- Some other systems use **big endian**
  - Most significant byte of multi-byte entity is stored at lowest memory address
  - “Big end goes first”

The 4-byte int 5 (hex 00 00 00 05) at address 1000:

1000	00000000
1001	00000000
1002	00000000
1003	00000101

6

## Little Endian Example

```
int main(void) {
    int i=0x003377ff, j;
    unsigned char *p = (unsigned char *) &i;
    for (j=0; j<4; j++)
        printf("Byte %d: %x\n", j, p[j]);
}
```

Output on a  
little-endian  
machine

Byte 0: ff  
Byte 1: 77  
Byte 2: 33  
Byte 3: 0

7

## IA-32 General Purpose Registers

31	15	8	7	0	16-bit	32-bit	Common Use
	AH	AL			AX	EAX	Accumulator
	BH	BL			BX	EBX	Pointer to data
	CH	CL			CX	ECX	Counter for loops
	DH	DL			DX	EDX	I/O pointer
	SI					ESI	Pointers (string source and dest)
	DI					EDI	

General-purpose registers

- EBP: pointer to data on stack
- ESP: stack pointer

8

## C Example: One-Byte Data



Global *char* variable *i* is in *%al*,  
the *lower byte* of the “A” register.

```
char i;
...
if (i > 5) {
    i++;
}
else
    i--;
}

    cmpb $5, %al
    jle else
    incb %al
    jmp endif
else:
    decb %al
endif:
```

9

## C Example: Four-Byte Data



Global *int* variable *i* is in *%eax*,  
the *full 32 bits* of the “A” register.

```
int i;
...
if (i > 5) {
    i++;
}
else
    i--;
}

    cmpl $5, %eax
    jle else
    incl %eax
    jmp endif
else:
    decl %eax
endif:
```

10

## Memory Addressing Modes



11

## Loading and Storing Data



- Processors have many ways to access data
  - Known as “addressing modes”
  - Two simple ways seen in previous examples ...
- Immediate addressing
  - Example: `movl $0, %ecx`
  - Initialize register ECX with zero
  - Data (e.g., number “0”) embedded in the instruction
- Register addressing
  - Example: `movl %edx, %ecx`
  - Copy value in register EDX into register ECX
  - Choice of register(s) embedded in the instruction

12

## Accessing Memory



- Variables are stored in memory
  - Global and static local variables in Data or BSS section
  - Dynamically allocated variables in the heap
  - Function parameters and local variables on the stack
- Need to be able to load from and store to memory
  - To copy the data between main memory and registers
  - Or manipulate the data directly in memory
- IA-32 has many different addressing modes
  - Corresponding to common programming constructs
  - E.g., accessing a global variable, dereferencing a pointer, accessing a field in a struct, or indexing an array

13

## Direct Addressing



- Useful when the address is known in advance
  - Global variables in the Data or BSS sections
- Load or store from a particular memory location
  - Memory address is embedded in the instruction
  - Instruction reads from or writes to that address
- IA-32 example: `movl 2000, %ecx`
  - Four-byte variable located at address 2000
  - Read four bytes starting at address 2000
  - Load the value into the ECX register
- Can use a label for (human) readability
  - E.g., “i” to allow “`movl i, %eax`”

14

## Indirect Addressing



- Useful when address is not known in advance
  - Dereference a pointer, for dynamically allocated data
- Load or store from a previously-computed address
  - Register with the address is embedded in the instruction
  - Instruction reads from or writes to that address
- IA-32 example: `movl (%eax), %ecx`
  - EAX register stores a 32-bit address (e.g., 2000)
  - Read long-word variable stored at that address
  - Load the value into the ECX register
  - The “(%eax)” essentially dereferences the pointer stored in register %eax

15

## Base Pointer Addressing



- Useful when accessing part of a larger variable
  - Specific field within a “struct”
  - E.g., if “age” starts at the 8<sup>th</sup> byte of “student” record
- Load or store with an offset from a base address
  - `movl offset(r1), r2`
  - Register r1 stores the base address
  - Fixed offset also embedded in the instruction
  - Instruction computes the address and does access
- IA-32 example: `movl 8(%eax), %ecx`
  - EAX register stores a 32-bit base address (e.g., 2000)
  - Offset of 8 is added to compute address (e.g., 2008)
  - Load the value into the ECX register

16

## Indexed Addressing



- Load/store with offset made of register, multiplier
  - Fixed base address embedded in the instruction
  - Offset = register \* constant multiplier
- Useful to iterate through an array (e.g., a[i])
  - Base is the start of the array (i.e., "a")
  - Register is the index (i.e., "i")
  - Multiplier is the size of the element (e.g., 4 for "int")
- IA-32 example: `movl 2000(,%eax,4), %ecx`
  - Index register EAX (say, with value of 10)
  - Multiplied by a multiplier of 1, 2, 4, or 8 (here, 4)
  - Added to a fixed base of 2000 (to get 2040)

17

## Indexed Addressing Example



```
int a[20]; ← global variable
int i, sum=0;
for (i=0; i<20; i++)
    sum += a[i];
```

EAX: temporary  
EBX: sum  
ECX: i

```
movl $0, %ecx
movl $0, %ebx
sumloop:
movl a(,%ecx,4), %eax
addl %eax, %ebx
incl %ecx
cmpl $19, %ecx
jle sumloop
```

## Effective Address: More Generally



$$\text{Offset} = \begin{pmatrix} \text{eax} \\ \text{ebx} \\ \text{ecx} \\ \text{edx} \\ \text{esp} \\ \text{ebp} \\ \text{esi} \\ \text{edi} \end{pmatrix} + \begin{pmatrix} \text{eax} \\ \text{ebx} \\ \text{ecx} \\ \text{edx} \\ \text{esp} \\ \text{ebp} \\ \text{esi} \\ \text{edi} \end{pmatrix} * \begin{pmatrix} 1 \\ 2 \\ 4 \\ 8 \end{pmatrix} + \begin{pmatrix} \text{None} \\ 8\text{-bit} \\ 16\text{-bit} \\ 32\text{-bit} \end{pmatrix}$$

Base                  Index                  scale                  displacement

- Displacement `movl foo, %ebx`
- Base `movl (%eax), %ebx`
- Base + displacement `movl foo(%eax), %ebx`  
`movl 1(%eax), %ebx`
- (Index \* scale) + displacement `movl (%edx,%eax,4), %ebx`
- Base + (index \* scale) + displacement `movl foo(%edx,%eax,4), %ebx`

19

## Data Access Methods: Summary



- Immediate addressing: data stored in the instruction itself
  - `movl $10, %ecx`
- Register addressing: data stored in a register
  - `movl %eax, %ecx`
- Direct addressing: address stored in instruction
  - `movl foo, %ecx`
- Indirect addressing: address stored in a register
  - `movl (%eax), %ecx`
- Base pointer addressing: indirect plus offset
  - `movl 4(%eax), %ecx`
- Indexed addressing: instruction contains base address, and specifies an index register and a multiplier (1, 2, 4, or 8)
  - `movl 2000(,%eax,1), %ecx`
  - Can also have an additional displacement register

20



## Condition Codes and Control Flow

21

## Control Flow



- **Common case**
  - Execute code sequentially
  - One instruction after another
- **Sometimes need to change control flow**
  - If-then-else
  - Loops
  - Switch
- **Two key ingredients**
  - Testing a condition
  - Selecting what to run next based on result

```

cmpl $5, %eax
jle else
incl %eax
jmp endif
else:
decl %eax
endif:

```



## Condition Codes

- **1-bit registers set by arithmetic & logic instructions**
  - ZF: Zero Flag
  - SF: Sign Flag
  - CF: Carry Flag
  - OF: Overflow Flag
- **Example: "addl Src, Dest" ("t = a + b")**
  - ZF: set if t == 0
  - SF: set if t < 0
  - CF: set if carry out from most significant bit (unsigned)
    - *Unsigned* overflow
  - OF: set if two's complement overflow
    - (a>0 && b>0 && t<0)
    - || (a<0 && b<0 && t>=0)

23



## Condition Codes (continued)

- **Example: "cmpl Src2,Src1" (compare b,a)**
  - Like computing a-b without setting destination
  - ZF: set if a == b
  - SF: set if (a-b) < 0
  - CF: set if carry out from most significant bit (unsigned)
  - OF: set if two's complement overflow
    - (a>0 && b<0 && (a-b)<0) || (a<0 && b>0 && (a-b)>0)
- **Flags are *not* set by lea, inc, or dec instructions**
  - Hint: this is useful for the extra-credit part of the assembly-language programming assignment

24

## Example Five-Bit Comparisons



- Comparison: `cmp $6, $12`

01100	→	01100
- 00110		+11010
??		00110

  - Not zero: ZF=0 (diff is not 00000)
  - Positive: SF=0 (first bit is 0)
  - No carry: CF=0 (unsigned diff is correct)
  - No overflow: OF=0 (signed diff is correct)
- Comparison: `cmp $12, $6`

00110	→	00110
- 01100		+10100
??		11010

  - Not zero: ZF=0 (diff is not 00000)
  - Negative: SF=1 (first bit is 1)
  - Carry: CF=1 (unsigned diff is wrong)
  - No overflow: OF=0 (signed diff is correct)
- Comparison: `cmp $-6, $-12`

10100	→	10100
- 11010		+00110
??		11010

  - Not zero: ZF=0 (diff is not 00000)
  - Negative: SF=1 (first bit is 1)
  - Carry: CF=1 (unsigned diff of 20 and 28 is wrong)
  - No overflow: OF=0 (signed diff is correct)

25

## Jumps after Comparison (cmpl)



- Equality
  - Equal: `je` (ZF is set)
  - Not equal: `jne` (~ZF)
- Below/above (e.g., unsigned arithmetic)
  - Below: `jb` (CF is set)
  - Above or equal: `jae` (~CF)
  - Below or equal: `jbe` (CF | ZF)
  - Above: `ja` ~(CF | ZF)
- Less/greater (e.g., signed arithmetic)
  - Less: `jl` (SF ^ OF)
  - Greater or equal: `jge` ~(SF ^ OF)
  - Less or equal: `jle` ((SF ^ OF) | ZF)
  - Greater: `jg` !((SF ^ OF) | ZF)

26

## Branch Instructions



- Conditional jump
  - `{l,g,e,ne,...} target` if (condition) {eip = target}

Comparison	Signed	Unsigned	
=	e	e	"equal"
≠	ne	ne	"not equal"
>	g	a	"greater,above"
≥	ge	ae	"...-or-equal"
<	l	b	"less,below"
≤	le	be	"...-or-equal"
overflow/carry	o	c	
no ovl/carry	no	nc	
- Unconditional jump
  - `jmp target`
  - `jmp *register`

27

## Jumping



- Simple model of a "goto" statement
  - Go to a particular place in the code
  - Based on whether a condition is true or false
  - Can represent if-the-else, switch, loops, etc.
- Pseudocode example: If-Then-Else

```
if (Test) {
    then-body;
} else {
    else-body;
```



```
if (!Test) jump to Else;
then-body;
jump to Done;
Else:
    else-body;
Done;
```

28

## Jumping (continued)



- Pseudocode example: Do-While loop

```
do {  
  Body;  
} while (Test);
```

→

```
loop:  
  Body;  
  if (Test) then jump to loop;
```

- Pseudocode example: While loop

```
while (Test)  
  Body;
```

→

```
jump to middle;  
loop:  
  Body;  
middle:  
  if (Test) then jump to loop;
```

29

## Jumping (continued)



- Pseudocode example: For loop

```
for (Init; Test; Update)  
  Body
```

↘

```
Init;  
if (!Test) jump to done;  
loop:  
  Body;  
  Update;  
  if (Test) jump to loop;  
done:
```

30

## Example Instruction Types



31

## Arithmetic Instructions



- Simple instructions
  - add{b,w,l} source, dest      dest = source + dest
  - sub{b,w,l} source, dest      dest = dest - source
  - inc{b,w,l} dest              dest = dest + 1
  - dec{b,w,l} dest              dest = dest - 1
  - neg{b,w,l} dest              dest = ~dest + 1
  - cmp{b,w,l} source1, source2      source2 - source1
- Multiply
  - mul (unsigned) or imul (signed)
- Divide
  - div (unsigned) or idiv (signed)
- Many more in Intel manual (volume 2)
  - adc, sbb, decimal arithmetic instructions

32



## Bitwise Logic Instructions



### • Simple instructions

<code>and{b,w,l} source, dest</code>	<code>dest = source &amp; dest</code>
<code>or{b,w,l} source, dest</code>	<code>dest = source   dest</code>
<code>xor{b,w,l} source, dest</code>	<code>dest = source ^ dest</code>
<code>not{b,w,l} dest</code>	<code>dest = ~dest</code>
<code>sal{b,w,l} source, dest (arithmetic)</code>	<code>dest = dest &lt;&lt; source</code>
<code>sar{b,w,l} source, dest (arithmetic)</code>	<code>dest = dest &gt;&gt; source</code>

### • Many more in Intel Manual (volume 2)

- Logic shift
- Rotation shift
- Bit scan
- Bit test
- Byte set on conditions

33

## Data Transfer Instructions

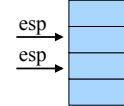


### • `mov{b,w,l} source, dest`

- General move instruction

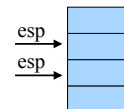
### • `push{w,l} source`

```
pushl %ebx # equivalent instructions
                subl $4, %esp
                movl %ebx, (%esp)
```



### • `pop{w,l} dest`

```
popl %ebx # equivalent instructions
                movl (%esp), %ebx
                addl $4, %esp
```



### • Many more in Intel manual (volume 2)

- Type conversion, conditional move, exchange, compare and exchange, I/O port, string move, etc.

34

## Conclusions



### • Accessing data

- Byte, word, and long-word data types
- Wide variety of addressing modes

### • Control flow

- Common C control-flow constructs
- Condition codes and jump instructions

### • Manipulating data

- Arithmetic and logic operations

### • Next time

- Calling functions, using the stack

35