

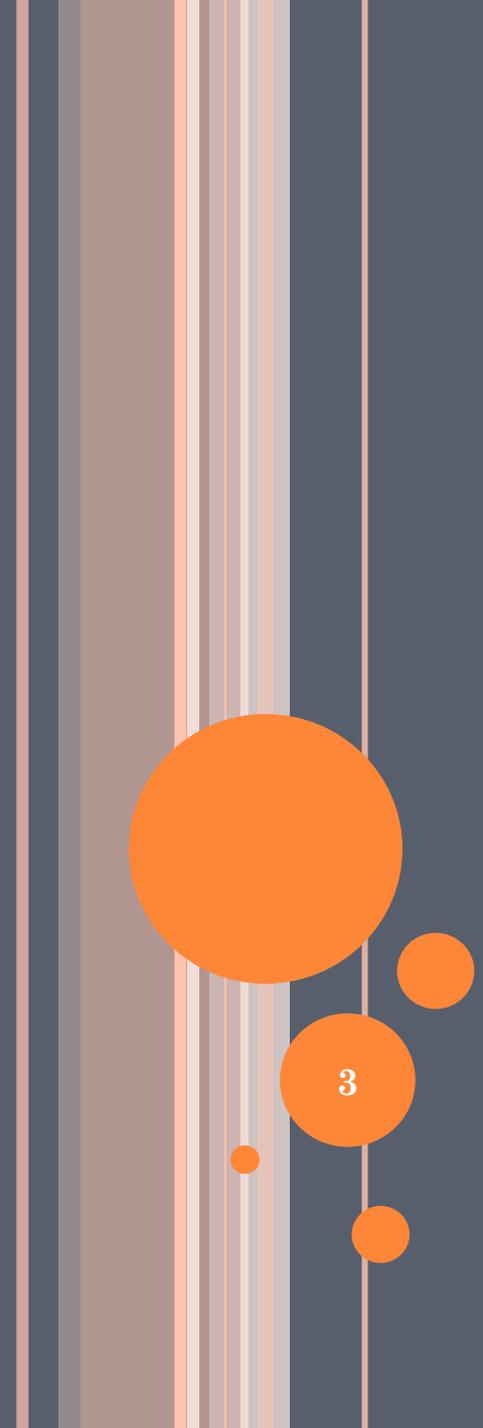
THREAD PARALLELISM

Stephen Beard

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LECTURE OUTLINE

- Introduction to Threads
- Correctness
- Performance



INTRODUCTION TO THREADS

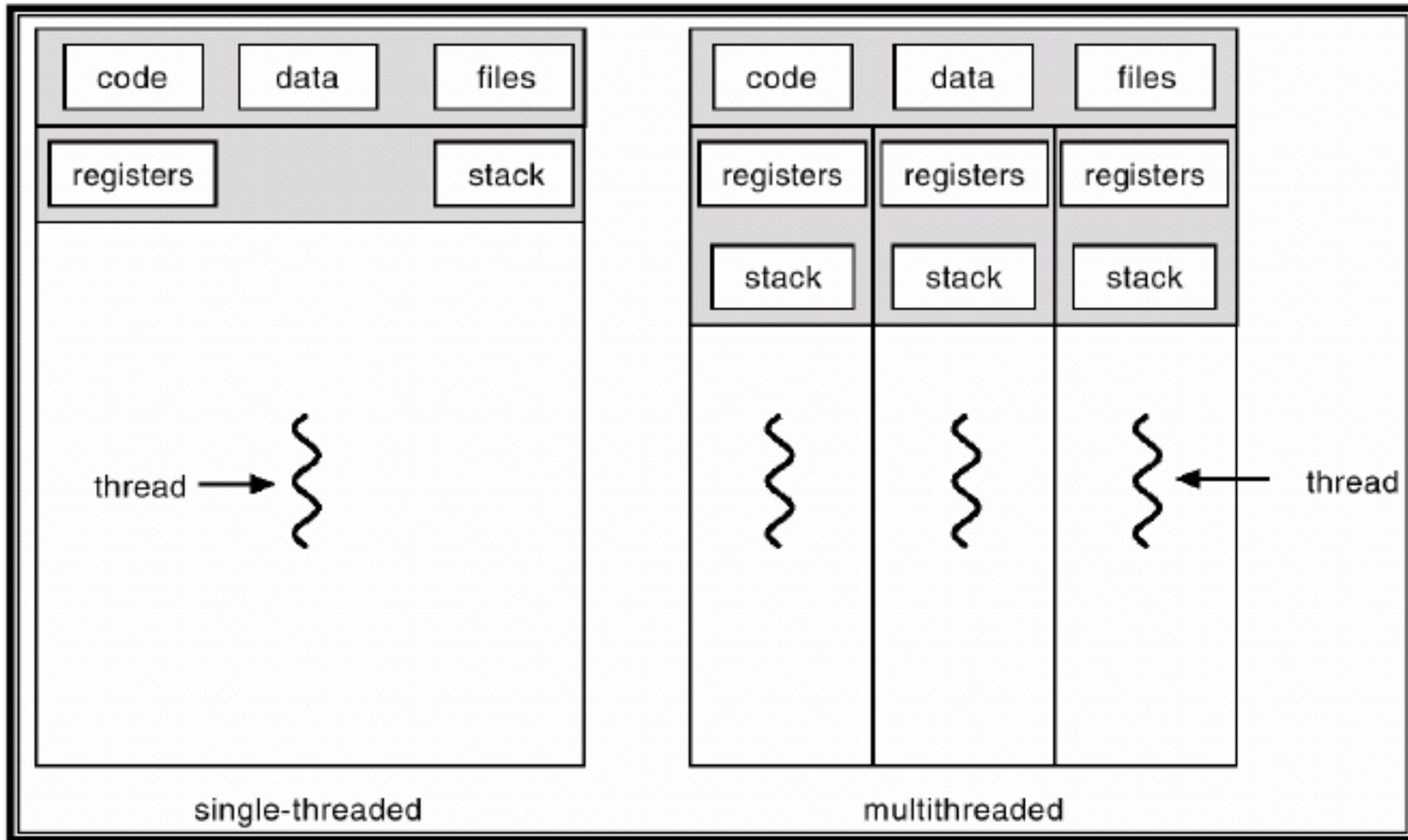
3



WHAT IS A THREAD?

4

WHAT IS A THREAD?



THREADS VS. PROCESSES

(Generalities)

Process

- “Heavyweight”
- Slower context switches
- Expensive IPC
- Independent

- Secure
 - Protected memory space

Thread

- “Lightweight”
- Faster context switches
- Direct communication
- Share state and resources

- Insecure
 - Shared memory space

USER THREADS AND KERNEL THREADS

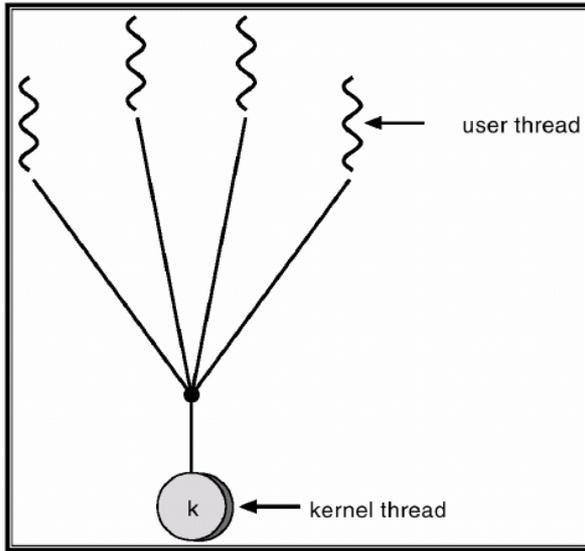
○ User Thread

- Implemented in software library
- Transparent to the OS
- Will block other threads
- Library typically uses non-blocking calls then manages threads
- Fast to create and manage
- Do not benefit from multithreading or multiprocessing

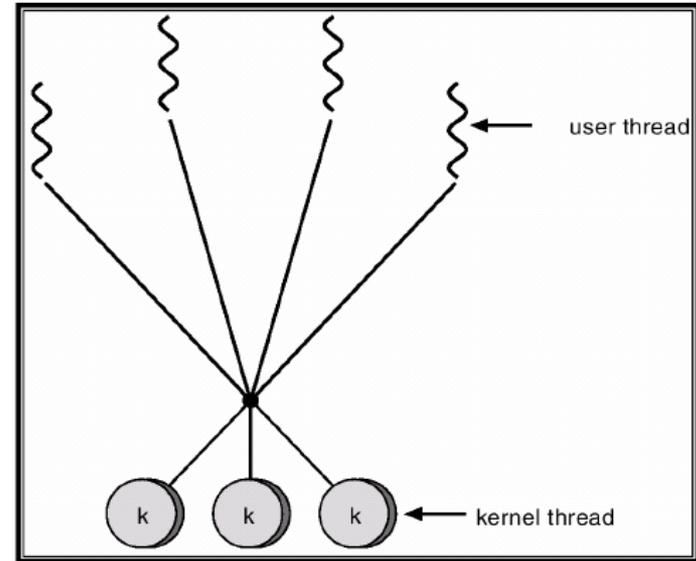
○ Kernel Thread

- Managed by OS
- Will not block other threads
- Slower to swap than user threads

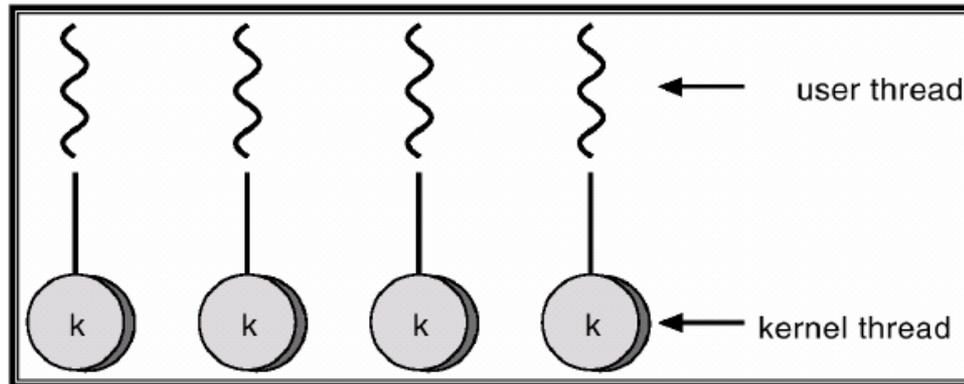
THREAD IMPLEMENTATIONS



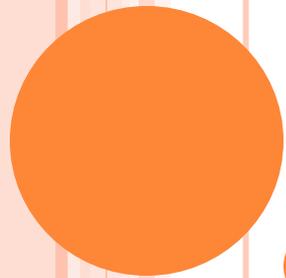
Many to One



Many to Many



One to One



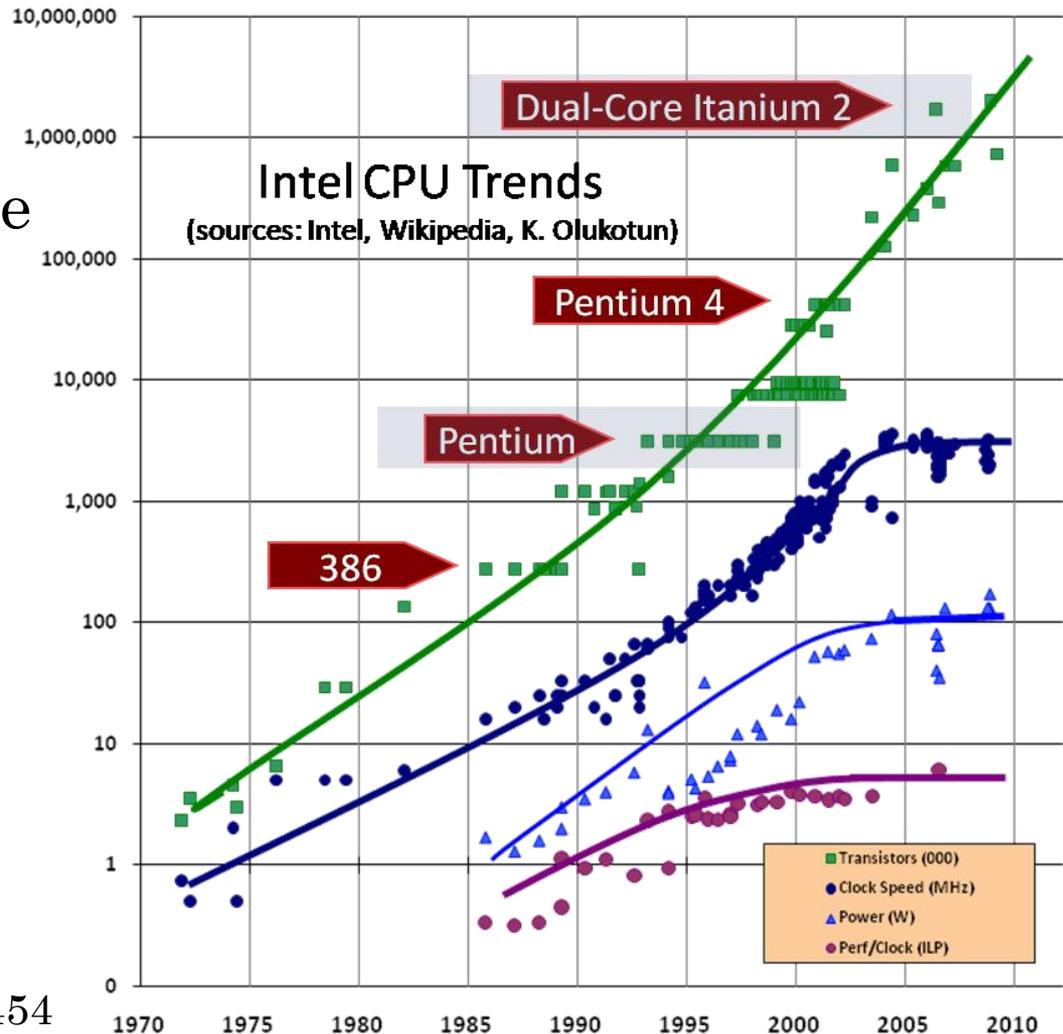
WHY USE THREADS?



WHY USE THREADS?

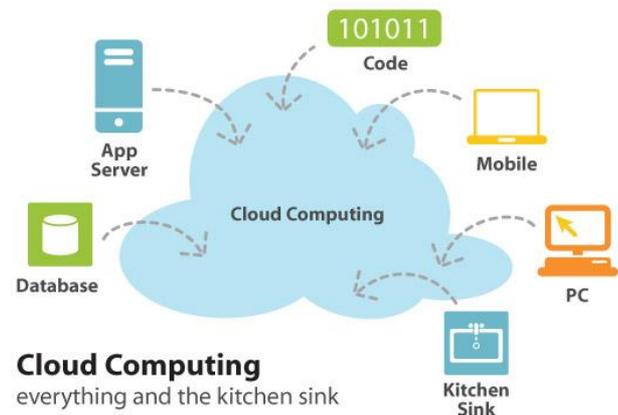
- Interactive Programs – Avoid blocking!

- Modern Hardware is designed for thread level parallelism (TLP)



HARDWARE FOR TLP

- Chip Multi-Processors
- GPUs
- Clusters
- Cloud Computing
- Multithreading

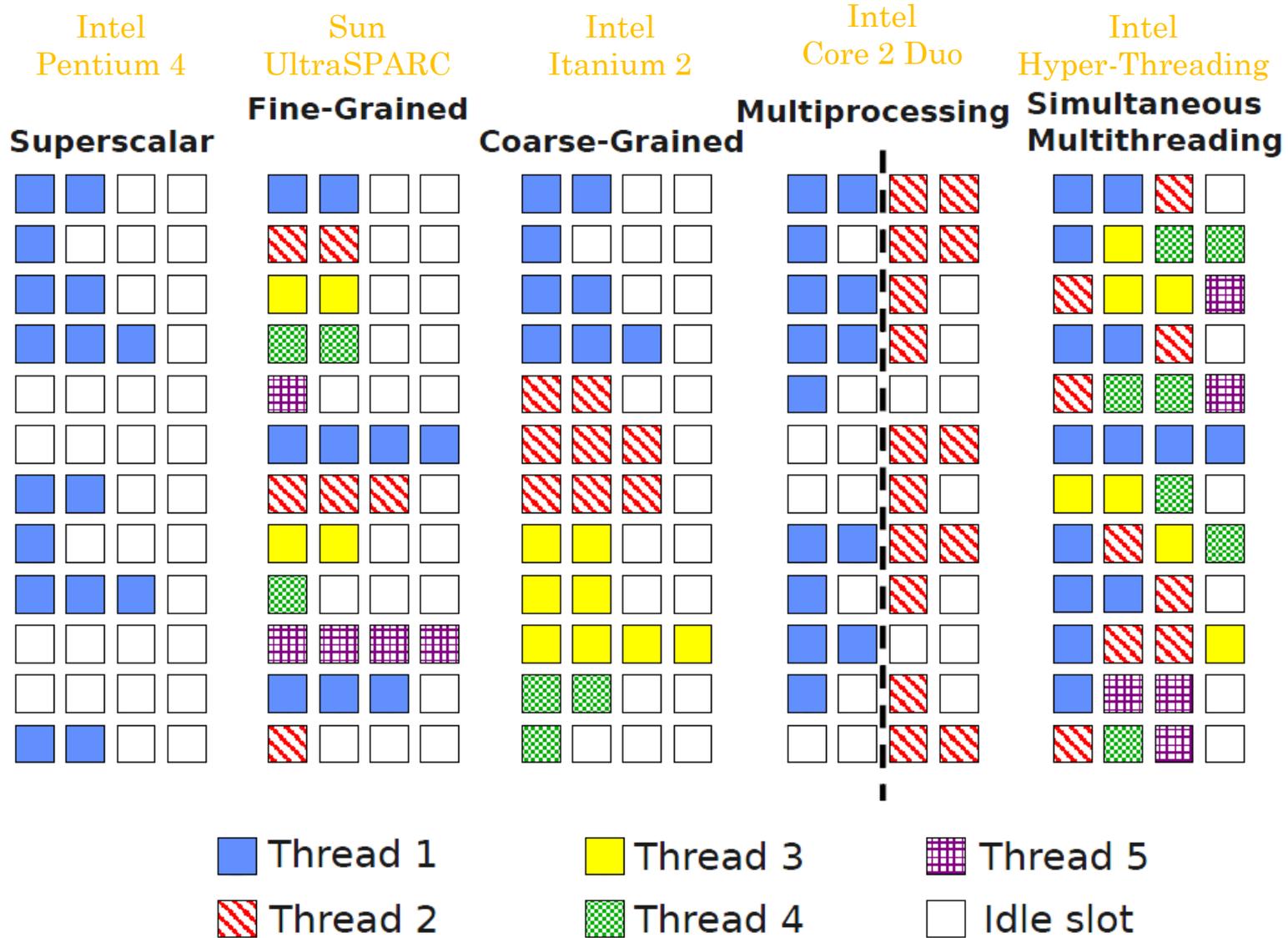


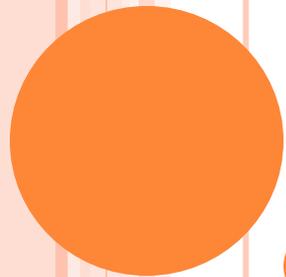
MULTI-THREADING TERMS

- Superscalar – ILP mechanism for performing multiple instructions concurrently (One CPU with multiple functional units)
- Fine-Grained – Switch between threads on each cycle
- Coarse-Grained – Switch between threads on ‘costly’ stalls (such as L2 cache miss)
- Multiprocessing – Multi-core
- Simultaneous – Multiple threads running concurrently on single processor

MULTITHREADING

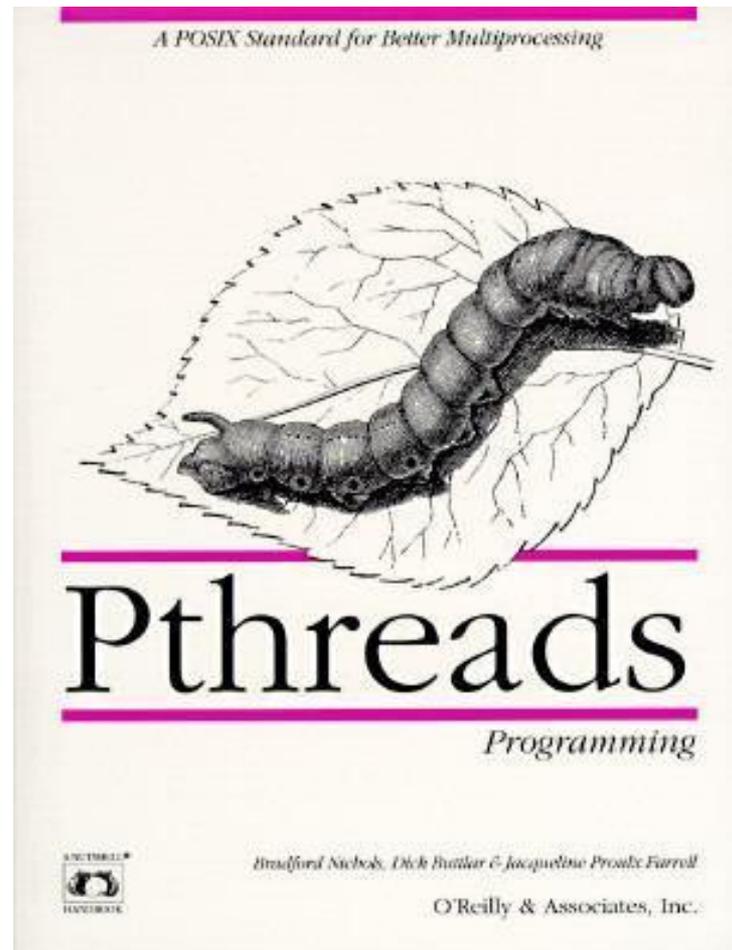
Ex:





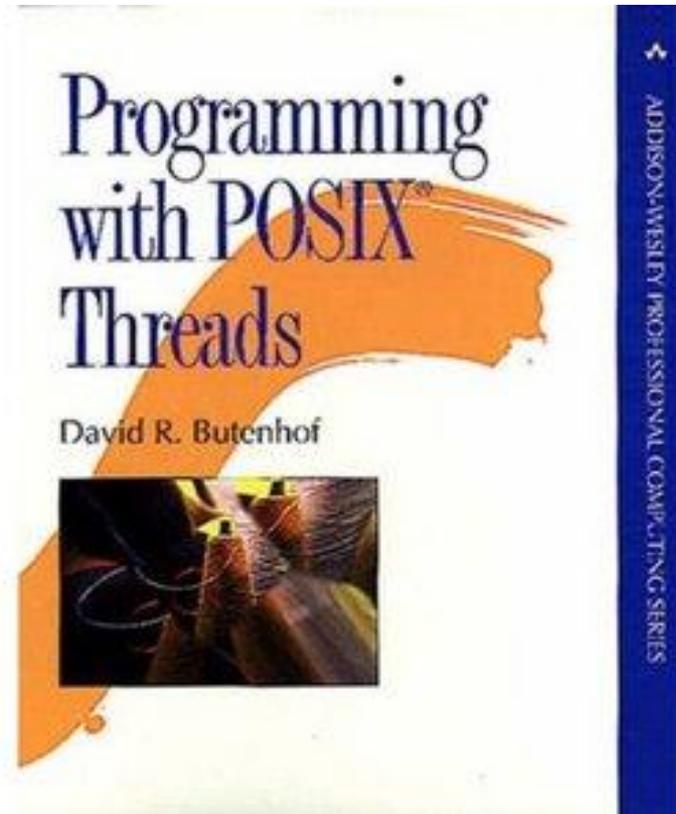
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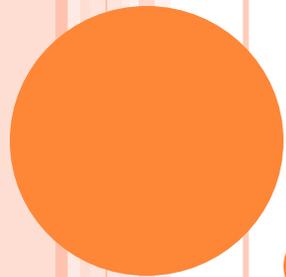
PTHREADS



PTHREADS (POSIX THREADS)

- C library that provides
 - Thread management
 - Shared Memory
 - Locks
- In Linux
 - One to One
 - Created using 'clone'





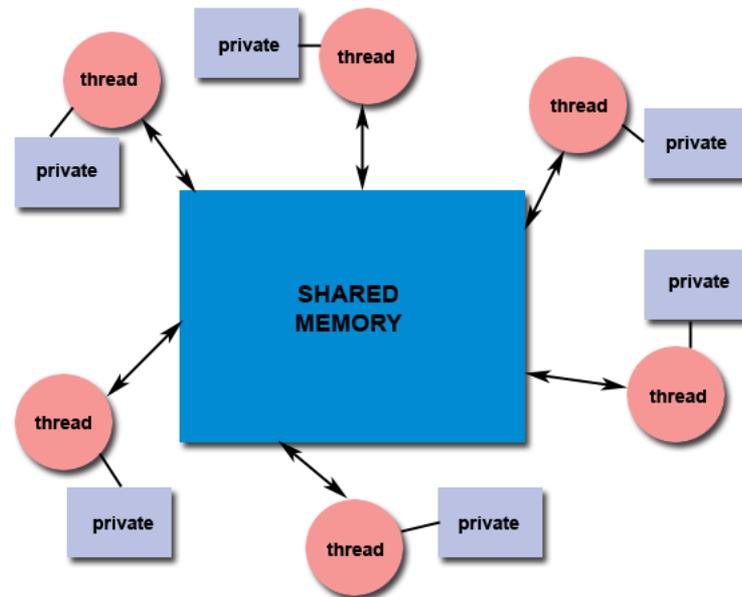
SIMPLE PTHREAD EXAMPLE

METHODS OF THREAD COMMUNICATION

Shared Memory -Memory that may be simultaneously accessed by multiple threads

```
int gInt;  
spawn t1, t2;
```

```
t1:      t2:  
...  
gInt = 5 ...  
...     int lInt = gInt  
        print lInt -> 5  
...     ...
```



METHODS OF THREAD COMMUNICATION

Message Passing - Threads pass messages for data transfer and synchronization

t1:

send 5

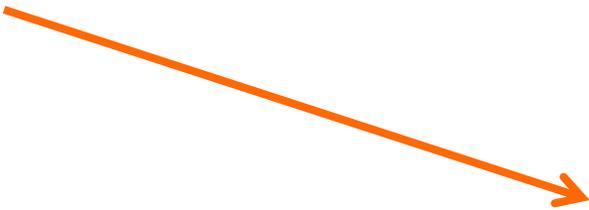
t2:

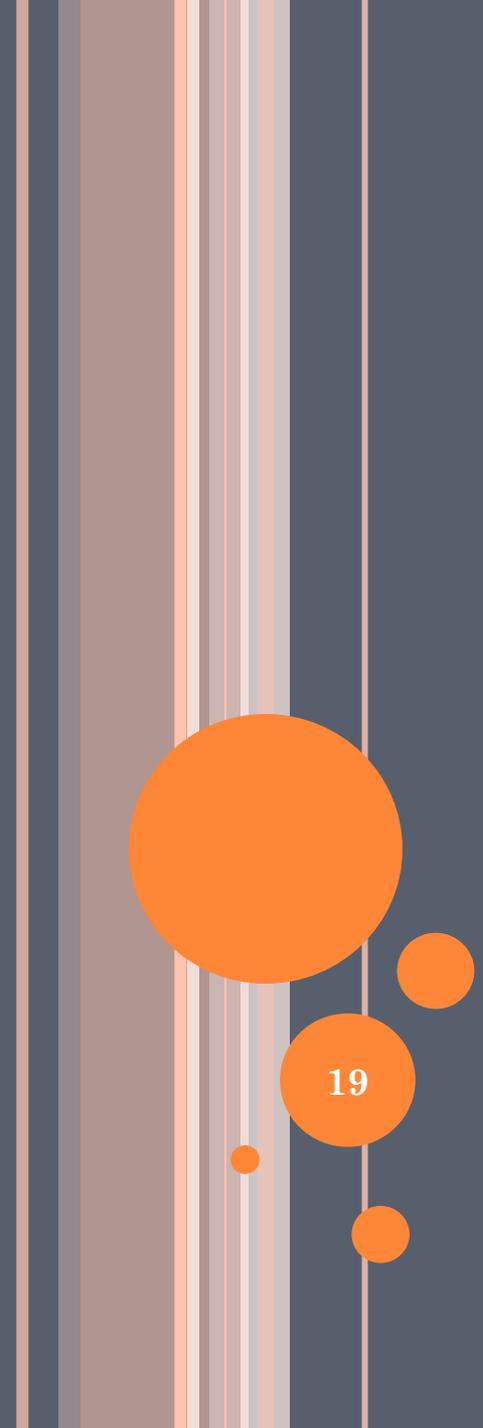
...

...

recv lInt

Print lInt -> 5



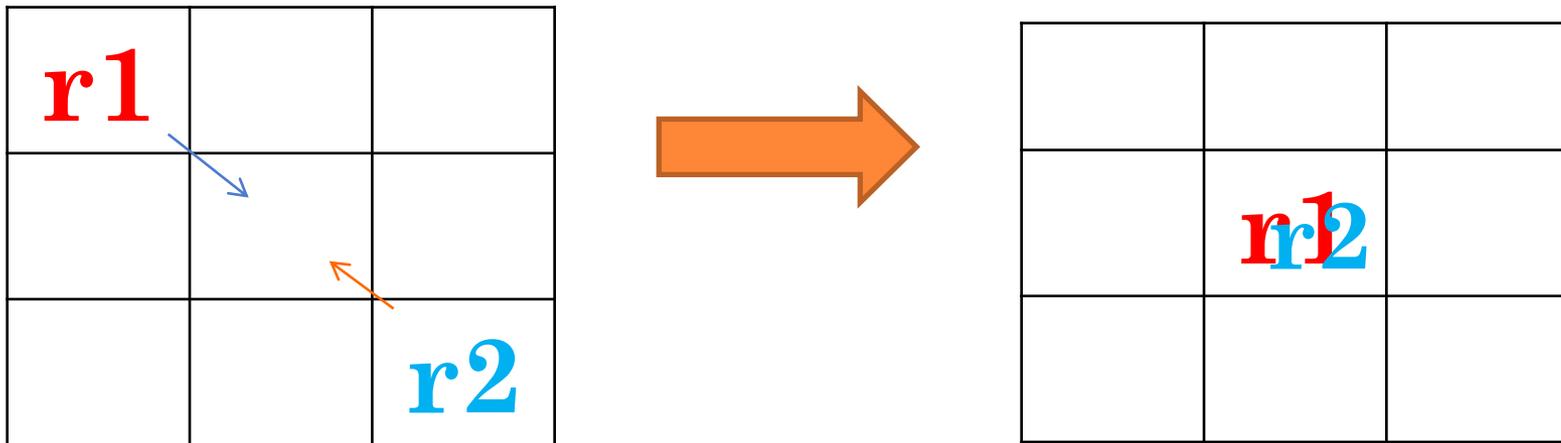


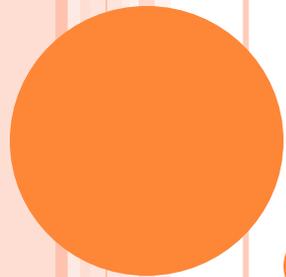
THREAD CORRECTNESS

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RACE CONDITIONS

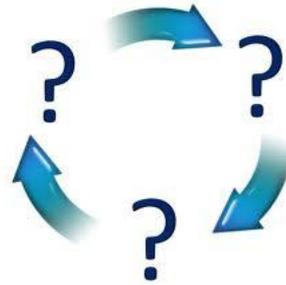
- Unsynchronized access to shared state from multiple threads whose outcome depends upon the order of access
- `r1.check`, `r2.check`, `r1.move`, `r2.move`, **CRASH**





RACE CONDITION PROGRAM

SYNCHRONIZATION



- Want to be able to control access to shared memory
- Several methods exist:
 - Mutex
 - Semaphore
 - Monitors
 - Barriers

NAIVELY FIXING OUR ROBOTS

Robot 1

```
lock()
r1.check()
unlock()
...
...
lock()
r1.move()
unlock()
```

Robot 2

```
lock()
...
...
r2.check()
unlock()
lock()
...
...
r2.move()
unlock()
```

CRASH

ATOMICITY

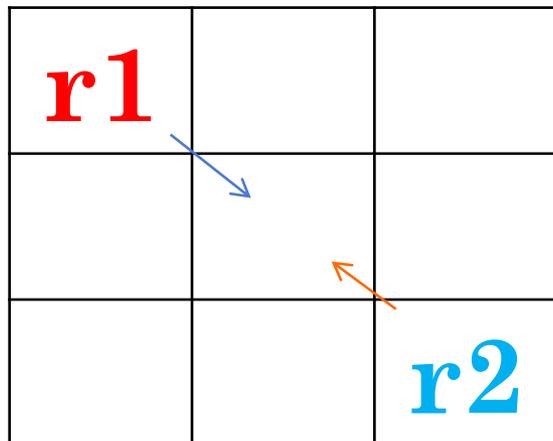
- A statement sequence S is atomic if S 's effects appear to other threads as if S executed without interruption



FIXING OUR ROBOTS

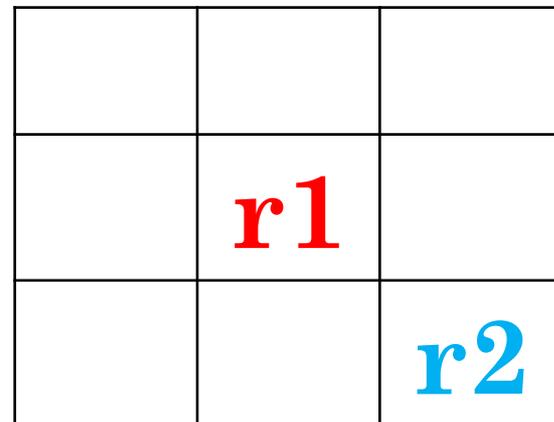
Robot 1

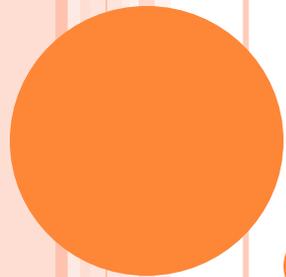
```
lock()  
r1.check()  
r1.move()  
unlock()
```



Robot 2

```
lock()  
...  
...  
...  
r2.check()  
unlock()
```





MUTEX EXAMPLE

MUTEX IMPLEMENTATION - HARDWARE

- Using XCHG on x86 to implement a mutex
 - XCHG exchanges two operands. If a memory operand is involved, BUS LOCK is asserted for the duration of the exchange.

```
LOCK:          ; mutex pointer is in EBX; clobbers EAX
  XOR EAX, EAX  ; Set EAX to 0
  XCHG EAX, [EBX]
  AND EAX, EAX  ; Test for 1
  JZ LOCK      ; if we got a zero, spin-wait
  RET
```

```
UNLOCK:       ; mutex pointer is in EBX
  MOV [EBX], 1
  RET
```

MUTEX IMPLEMENTATION - SOFTWARE

○ Peterson's Algorithm

- Works for two processes, but can generalize
- Does not work with out-of-order execution

```
flag[0] = 0;
flag[1] = 0;
```

```
P0: flag[0] = 1;
    turn = 1;
    while (flag[1] == 1 && turn == 1)
    {
        // busy wait
    }
    // critical section
    ...
    // end of critical section
    flag[0] = 0;
```

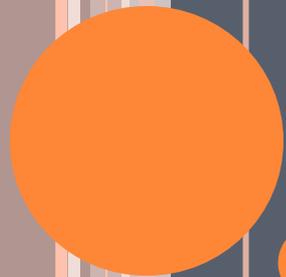
```
P1: flag[1] = 1;
    turn = 0;
    while (flag[0] == 1 && turn == 0)
    {
        // busy wait
    }
    // critical section
    ...
    // end of critical section
    flag[1] = 0;
```

MUTEX IMPLEMENTATION

- Exact locking mechanism is hardware dependent
- If a thread fails to acquire lock
 - Waits for lock
 - Spin vs Yield
- How to handle multiple threads waiting on single lock
 - Queue
 - Scheduler
- Reentrant Locks
 - Allowed to acquire same lock multiple times
 - Must be released same number of times

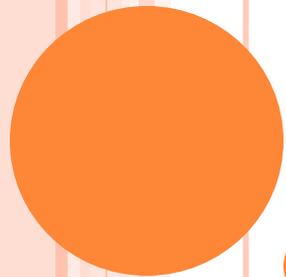
OTHER ISSUES WITH LOCKS

- Dead-lock – Circular waiting on locks
- Live-lock – Locks state changing with no progress
- Lock contention – Many threads require access to single lock
- Lock overhead – Locking mechanisms are slow
- Priority Inversion – Low priority thread holds lock, prevents progress of high priority
- Convoying – Lock contention with slowest threads acquiring the lock first



PERFORMANCE

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THREAD GRANULARITY

THREAD GRANULARITY

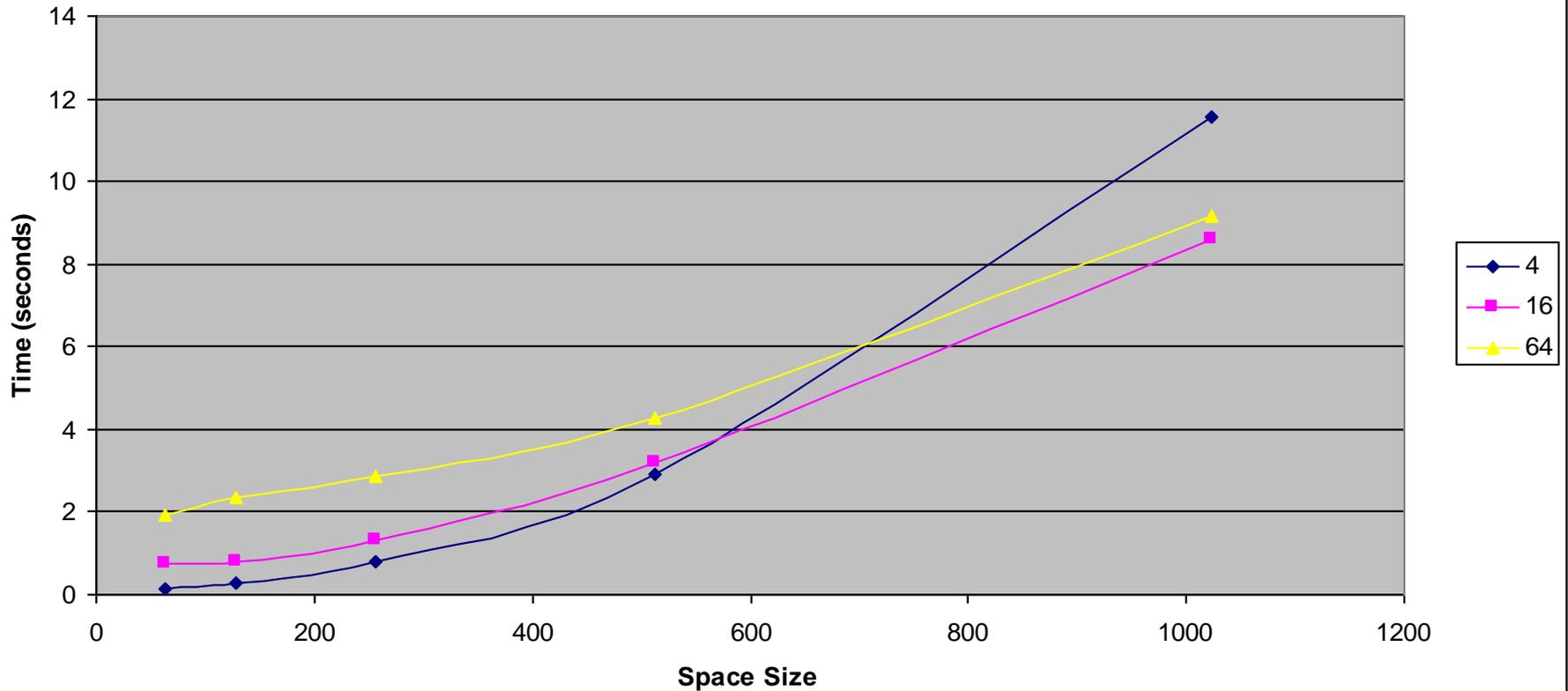
- Better to have lots of threads doing a little work or a few threads doing lots of work?
 - Depends on:
 - How much communication overhead will result?
 - Implementation of threads
 - Hardware

JACOBI ITERATIONS

- For a matrix, on each iteration element's new value = average of neighbors old values
- How many threads?

JACOBI IN C USING MPI

Row for 800 iterations

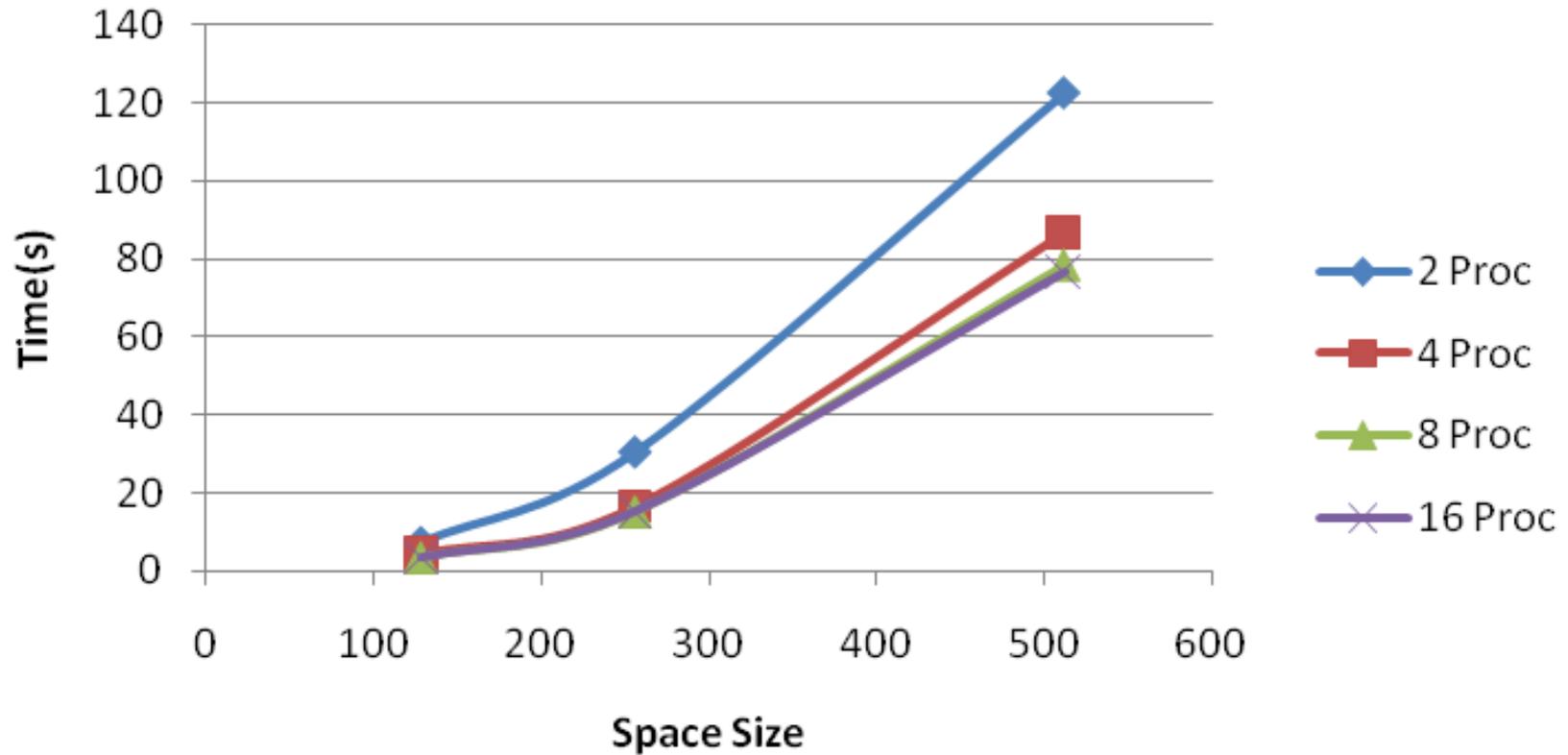


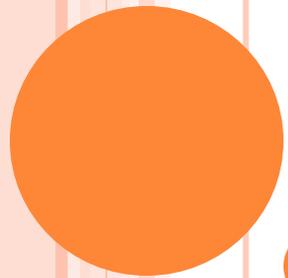
Erlang

MPI

JACOBI IN ERLANG

400 Iterations

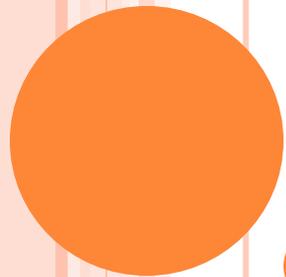




LOCKING GRANULARITY

LOCKING GRANULARITY

- Better to lock the entire structure, or parts?
 - Lock entire list when performing an operation
 - Only alter one lock per access to list
 - One thread in list blocks all others from accessing list
 - Lock each element of the list, hand-over-hand
 - Threads can work on different parts of the list concurrently
 - Lock per element, or group of elements
 - Threads in front of list prevent access to rest of list



LOCK FREE DATA STRUCTURES



LOCK-FREE ALGORITHMS

- Can be more efficient and scalable than locking
- Not the same as wait-free
 - Lock-free guarantees system progress
 - Wait-free guarantees thread progress
 - Operation must have bound on number of steps till completion
 - Very rare as their performance is generally low
- Good for many reads, few writes
 - Most attempt operation then retry if changed occurred during operation

COMPARE-AND-SWAP CMPXCHG ON X86

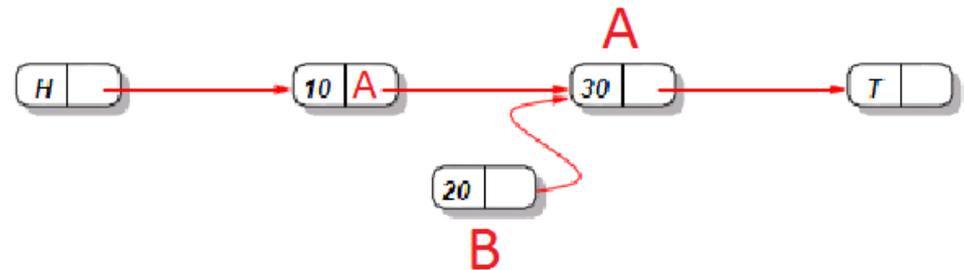
- Atomically compares contents of memory location to a given value, if they match it updates value

```
int compare_and_swap ( int* register, int oldval, int newval)
{
    int old_reg_val = *register;
    if (old_reg_val == oldval)
        *register = newval;
    return old_reg_val;
}
```

- Hardware support handles this operation atomically
- Integral in lock free structures

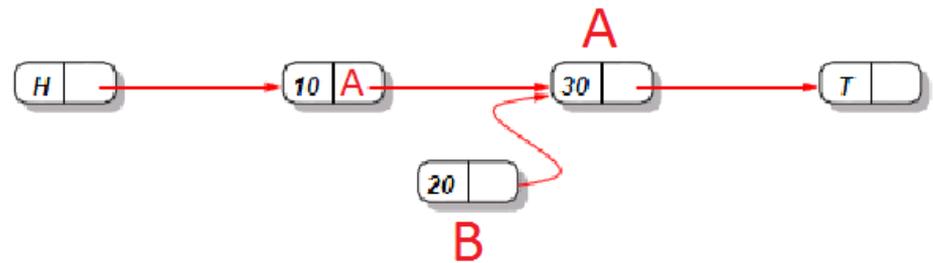
LOCK-FREE LINKED LIST – INSERTION

- Create new node
- do
 - Find insertion location, note left and right nodes

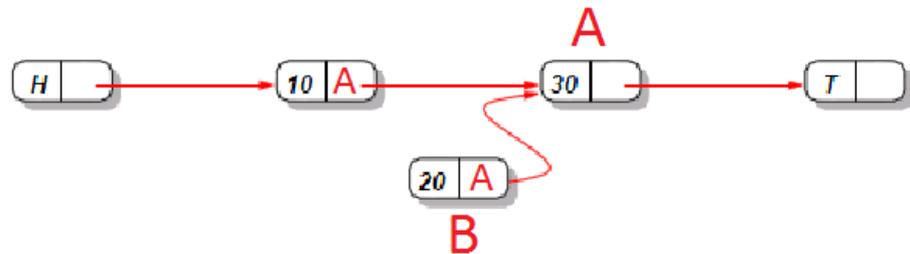


LOCK-FREE LINKED LIST – INSERTION

- Create new node
- do
 - Find insertion location, note left and right nodes

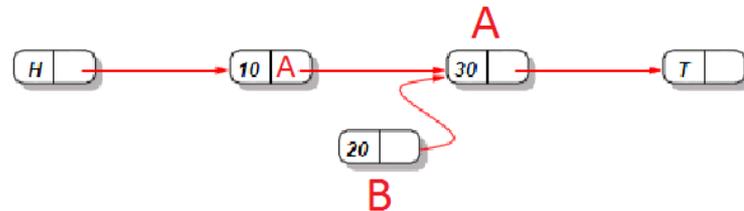


- Set new.next = right

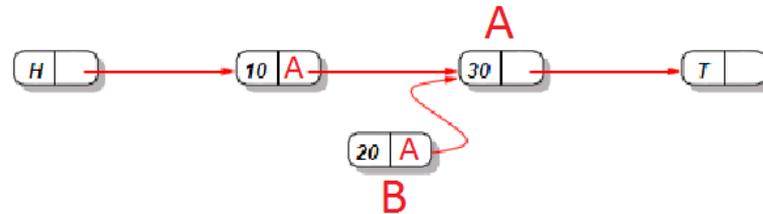


LOCK-FREE LINKED LIST – INSERTION

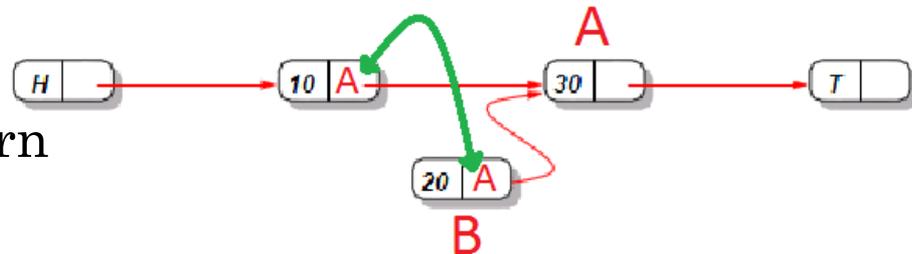
- Create new node
- do
 - Find insertion location, note left and right nodes



- Set new.next = right

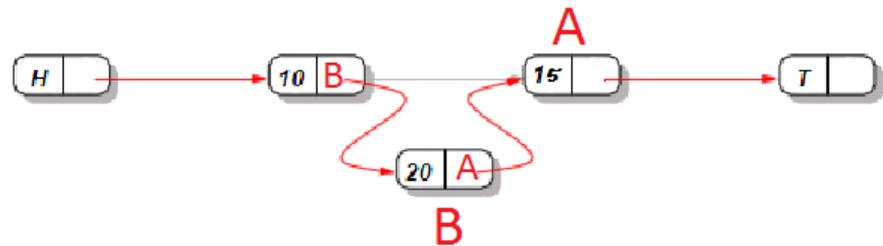


- If(CAS &left.next, right, new) then return



LOCK-FREE LINKED LIST – INSERTION

- Create new node
- do
 - Find insertion location, note left and right nodes
 - Set new.next = right
 - If(CAS &left.next, right, new) then return
- while(true)

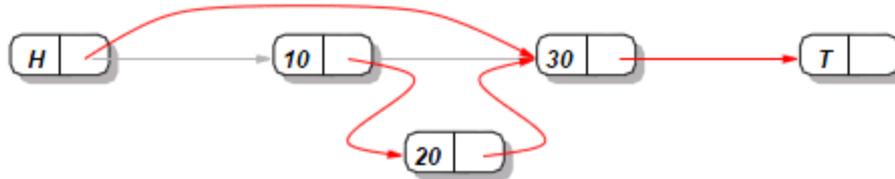


LOCK-FREE LINKED LIST

- Delete creates problems
 - Naive Delete



- Fails for concurrent insert



LOCK-FREE LINKED LIST

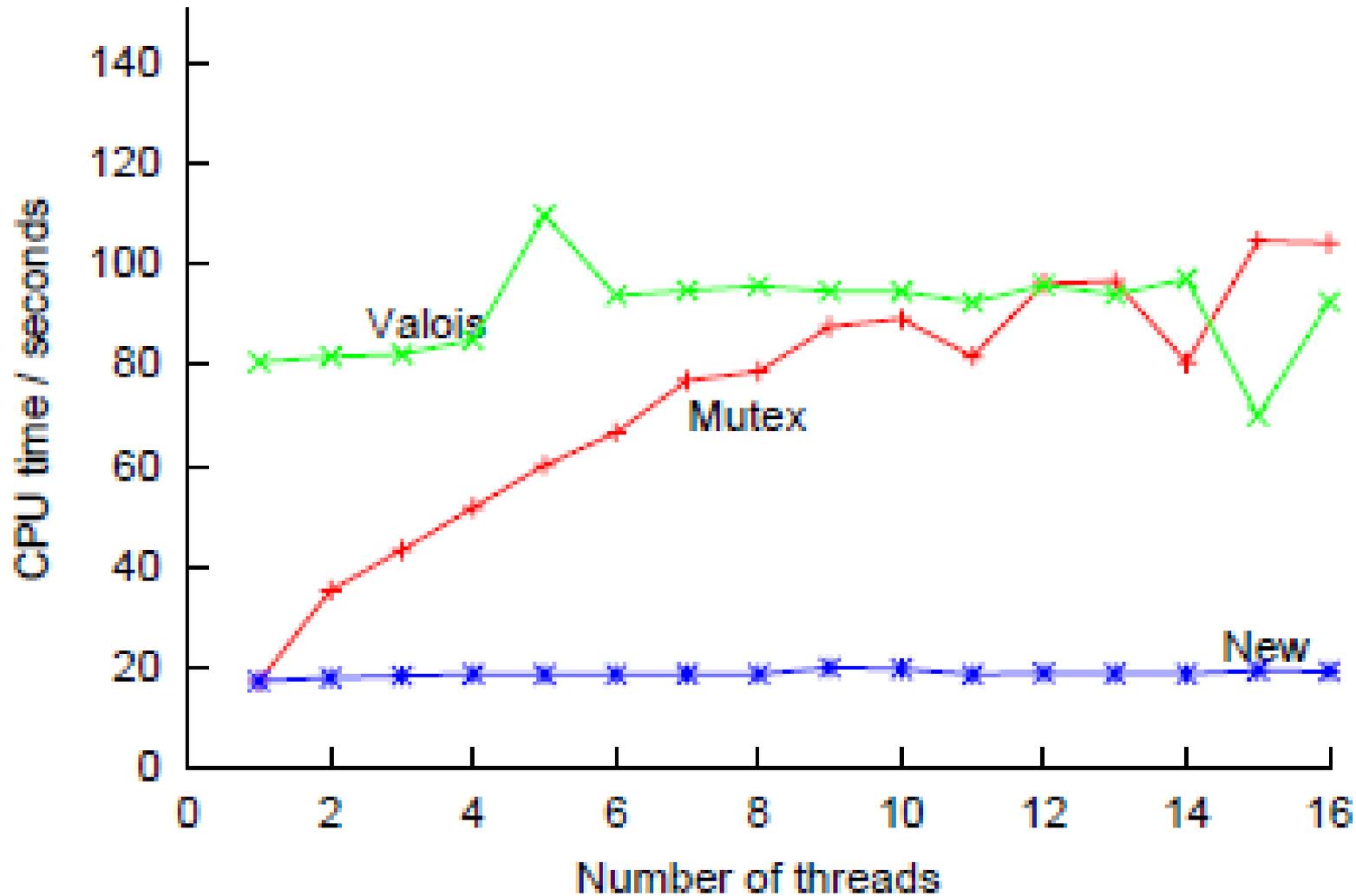
- Correct delete requires two compares
 - First mark deleted node as ‘logically deleted’



- Then ‘physically delete’ the node



PERFORMANCE OF LOCK-FREE LINKED LIST



1 million random insertion, deletions on keys 0 - 8191

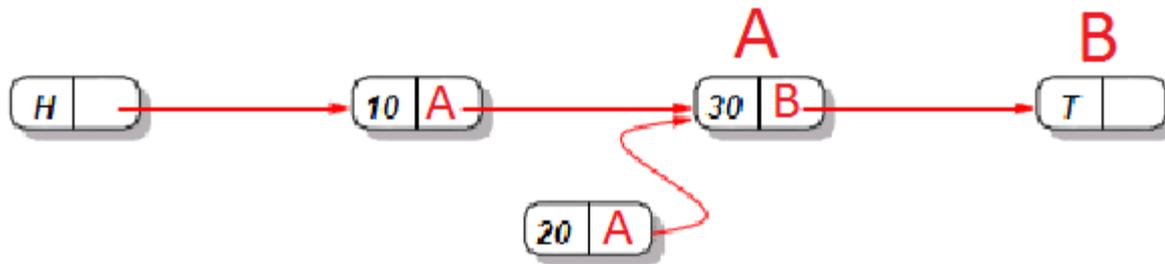
LOCK-FREE ABA PROBLEM – 1

Thread 1:

Insert 20 #interrupted

Thread 2:

...



ABA PROBLEM – 2

Thread 1:

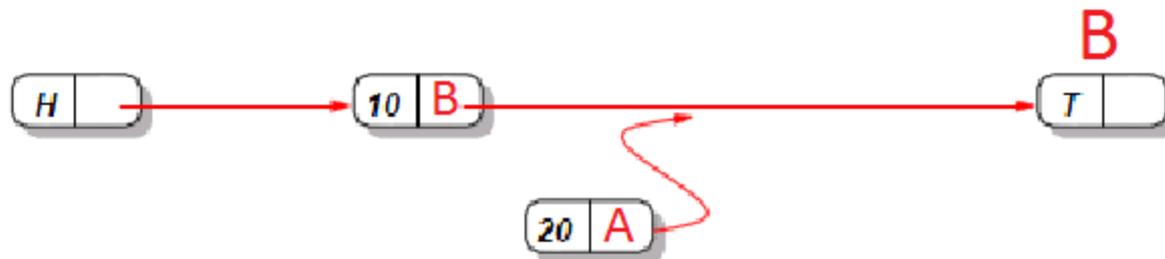
Insert 20 #partial completion

...

Thread 2:

...

delete 30 address A



ABA PROBLEM – 3

Thread 1:

Insert 20 #partial completion

...

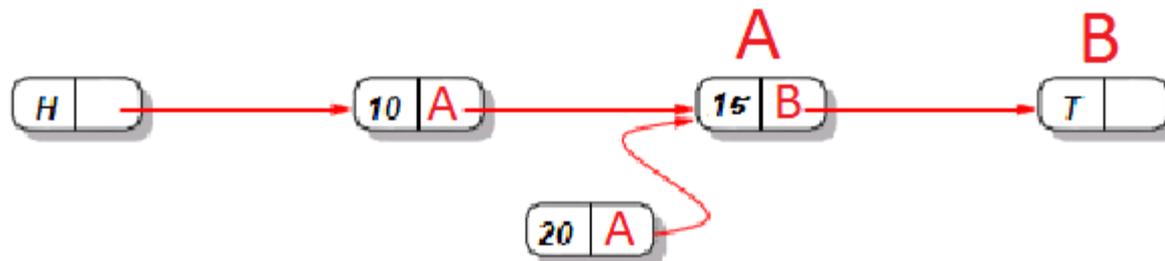
...

Thread 2:

...

delete 30 #address A

insert 15 #address A



ABA PROBLEM – 4

Thread 1:

Insert 20 #partial completion

...

...

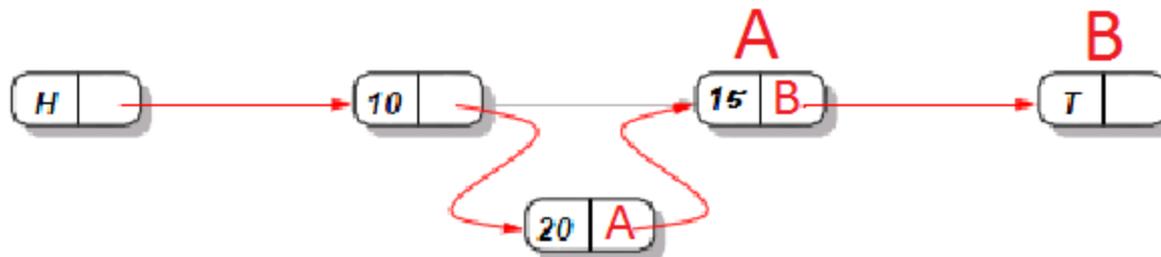
Insert 20 #finishes and
#improperly succeeds

Thread 2:

...

delete 30 #address A

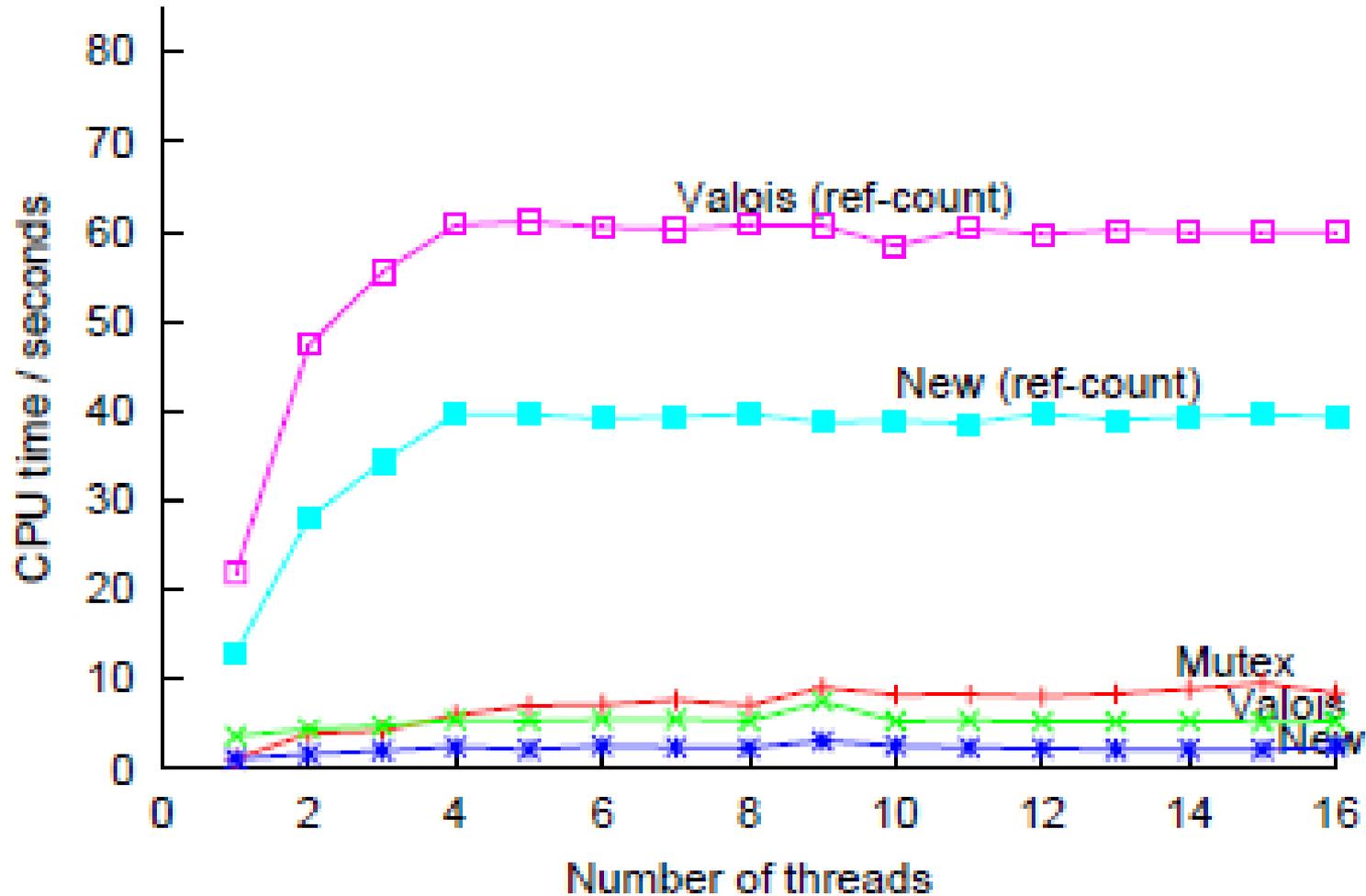
insert 15 #address A



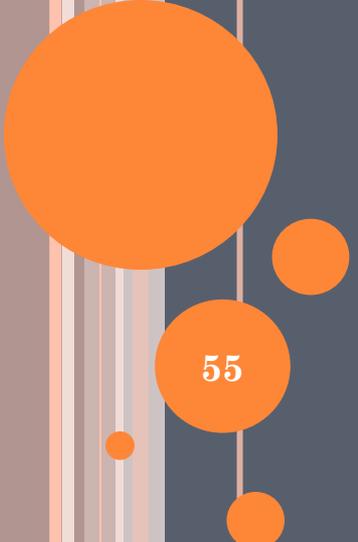
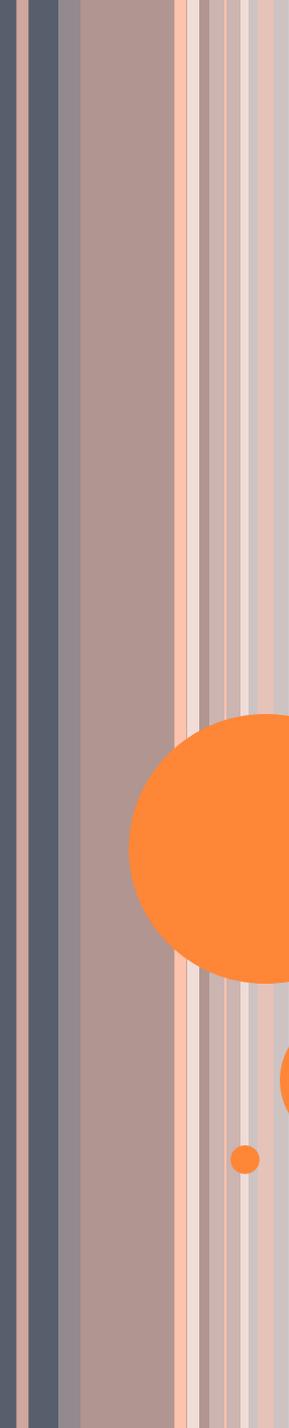
SOLUTIONS TO ABA

- Keep “tag” bits on each pointer – ABA’
 - Requires double-word CAS
- Use reference counts on cells (Valois)
 - Only reuse cell when reference count = 0
- Use ‘Load Linked’ and ‘Store Conditional’
 - LL returns value of memory location
 - SC stores only if no updates occurred since LL

PERFORMANCE NOT ALWAYS GREAT



1 million random insertion, deletions on keys 0 - 255

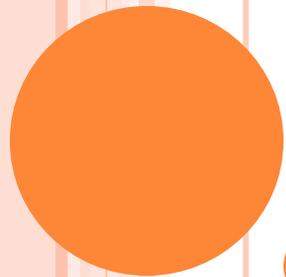


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NEXT TIME...

Multi-process synchronization problems

- Producer Consumer!
- Reader-Writer!
- DOALL!



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APPENDIX

More interesting topics

AVOIDING ERRORS WITH PTHREADS

- Create data structures that handle most of the synchronization for you
 - Code the locks once correctly, then don't worry about them anymore
- For example:
 - Create a synchronized list
 - Perform locks inside add/remove/search functions
 - Synchronization now transparent to rest of program

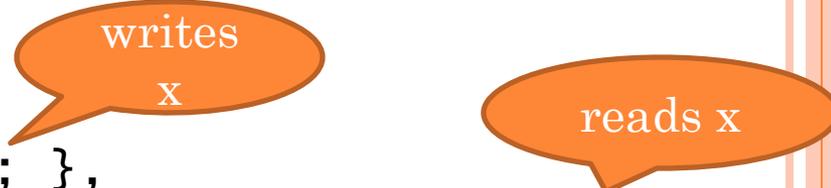
SMART PROGRAMMING WITH PTHREADS

- Locks serialize the program, want to use as little as possible
- Only place lock around critical area
 - Less time spent holding lock, less lock contention
- Locks have high overhead
 - Constant locking and unlocking can result in poor performance

WHAT IS A DATA RACE?

- Two **concurrent** accesses to a memory location at least one of which is a write.
- Example: Data race between a read and a write

```
int x = 1;
Parallel.Invoke(
    () => { x = 2; },
    () => { System.Console.WriteLine(x); }
);
```



- Outcome nondeterministic or worse
 - may print 1 or 2, or arbitrarily bad things on a relaxed memory model



DATA RACES AND HAPPENS-BEFORE

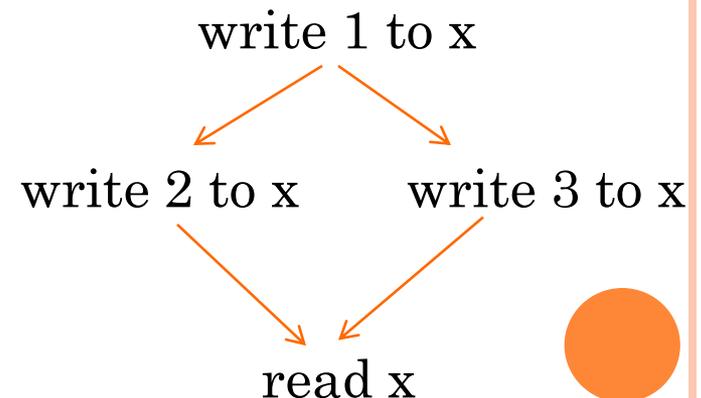
- Example of a data race with two writes:

```
int x = 1;
Parallel.Invoke( () => { x = 2; },
                () => { x = 3; } );
System.Console.WriteLine(x);
```

- We visualize the ordering of memory accesses with a happens-before graph:

There is no path between (write 2 to x) and (write 3 to x), thus they are concurrent, thus they create a data race

(note: the read is not in a data race)



QUIZ: WHERE ARE THE DATA RACES?

```
Parallel.For(1,2,  
i => {  
    x = a[i];  
});
```

```
Parallel.For(1,2,  
i => {  
    a[i] = x;  
});
```

```
Parallel.For(1,2,  
i => {  
    a[i] = a[i+1];  
});
```

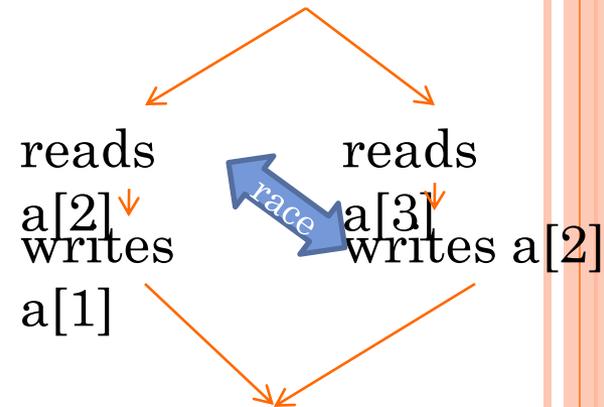
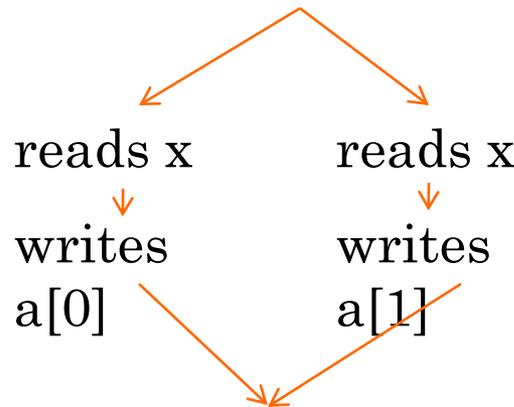
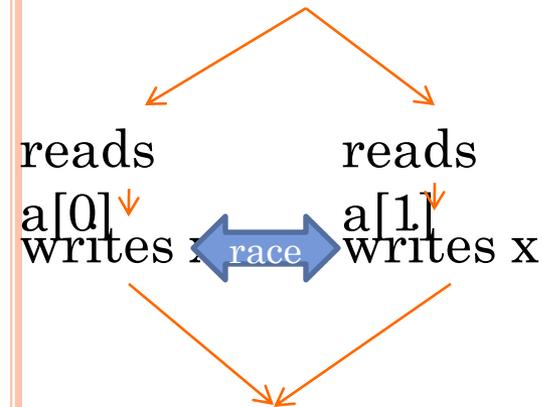


QUIZ: WHERE ARE THE DATA RACES?

```
Parallel.For(1, 2,  
i => {  
    x = a[i];  
});
```

```
Parallel.For(1, 2,  
i => {  
    a[i] = x;  
});
```

```
Parallel.For(1, 2,  
i => {  
    a[i] = a[i+1];  
});
```



Race between two writes.

No Race between two reads.

Race between a read and a write.

SPOTTING READS & WRITES

- Sometimes a single statement performs multiple memory accesses

When you execute

$x += y$

there are actually two reads and one write:

reads x
reads y
writes x

When you execute

$a[i] = x$

there are actually three reads and one write:

reads x
reads a
reads i
writes a[i]

DATA RACES CAN BE HARD TO SPOT.

```
Parallel.For(0, 10000,  
    i => {a[i] = new Foo();})
```

- Code looks fine... at first.



DATA RACES CAN BE HARD TO SPOT.

```
Parallel.For(0, 10000,  
    i => {a[i] = new Foo();})
```

- Problem: we have to follow calls... even if they look harmless at first (like a constructor).

```
class Foo {  
    private static int counter;  
    private int unique_id;  
    public Foo()  
    {  
        unique_id = counter++;  
    }  
}
```

**Data
Race
on
static
field !**

