

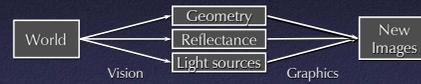
# Image-Based Rendering

COS 526, Fall 2006

Acknowledgment: Tom Funkhouser

## Image-Based Modeling and Rendering

- For many applications, re-rendering is goal
- Traditional vision / graphics pipelines:



- Image-based pipeline:

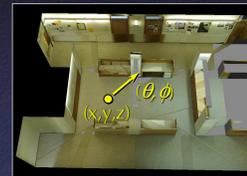


## Image-Based Modeling and Rendering

- Generate new views of a scene directly from existing views
- “Pure” IBR (such as lightfields): no geometric model of scene
- Other IBR techniques try to obtain higher quality with less storage by building a model

## Plenoptic Function

- $L(x, y, z, \theta, \phi, t, \lambda)$
- Captures all light flow in a scene
  - to/from any point  $(x, y, z)$ ,
  - in any direction  $(\theta, \phi)$ ,
  - at any time  $(t)$ ,
  - at any frequency  $(\lambda)$
- Enough information to construct any image of the scene at any time



[Funkhouser]

## Plenoptic Function Simplifications

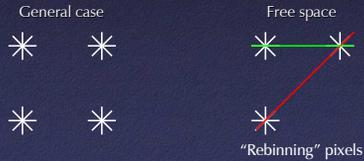
- Represent color as RGB: eliminate  $\lambda$
- Static scenes: ignore dependence on  $t$
- 7D  $\rightarrow 3 \times 5$ D

## Plenoptic Function – Special Cases

- Sample at one  $(x, y, z)$ :
  - $L(\theta, \phi)$  is just an (omnidirectional) image
- Full 5D  $L(x, y, z, \theta, \phi)$ :
  - Omnidirectional image at each point in space
  - Enough information to reconstruct any view

## Free Space

- Consider a region of space without occlusion
- Light travels in straight lines → some pixels in different images are the same ray of light

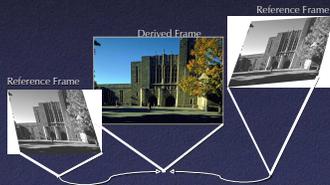


## Image-Based Representations

- 7D ↑ Ideal
- 6D Consider only 3 frequencies (RGB)
- 
- 5D Consider only one time instant (static scene)
- 4D Consider only viewpoints inside/outside scene
- 3D Consider one dimension fewer directions/positions
- 2D Consider viewpoints at finite set points or angles

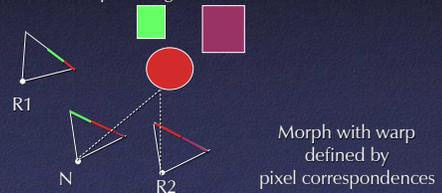
## View Interpolation

- Create novel images by resampling photographs
  - Reference images sample 5D plenoptic function



## View Interpolation

- Method:
  - Warp nearby reference images to novel viewpoint
  - Blend warped images



## Pixel Correspondences

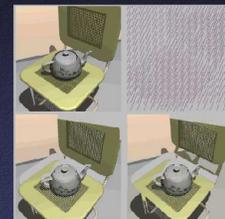
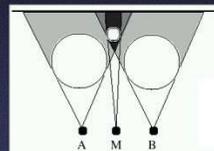
- Vision (e.g. stereo): disparity
- Feature matching: sparse
- 3D model: possibly coarse



[Szeliski]

## View Interpolation

- Problem: changes in visibility
  - Disocclusions



[McMillan]

## Disocclusions

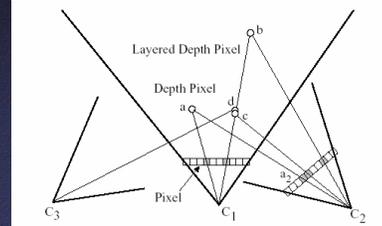
- Partial solutions:
  - Use more photographs
  - Fill holes by interpolating nearby pixels



[McMillan]

## Disocclusions

- Better solutions (when possible):
  - Multiple samples per pixel at different depths



## Disocclusions

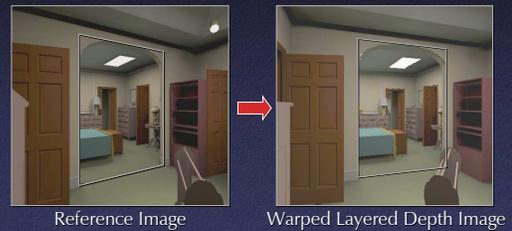
- Better solutions (when possible):
  - Multiple samples per pixel at different depths



[Popescu]

## Disocclusions

- Better solutions (when possible):
  - Multiple samples per pixel at different depths



## Light Field

- In unoccluded space, can reduce plenoptic function to 4D
- 2D array of 2D images
- Still contains enough information to reconstruct new views

## Lightfields

- Advantages:
  - Simpler computation vs. traditional CG
  - Cost independent of scene complexity
  - Cost independent of material properties and other optical effects
  - Avoid hard vision problems
- Disadvantages:
  - Static geometry
  - Fixed lighting
  - High storage cost

## Using Lightfields

- Obtain 2D slices of 4D data set
- Arbitrary views: take other 2D slices
- Challenges:
  - Capture
  - Parameterization
  - Compression
  - Rendering

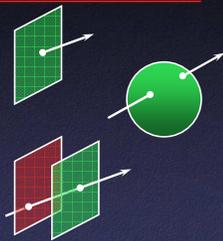


## Capturing Lightfields

- Need a 2D set of (2D) images
- Choices:
  - Camera motion: human vs. computer
  - Constraints on camera motion
  - Coverage and sampling uniformity
  - Aliasing

## Lightfield Parameterization

- Point / angle
- Two points on a sphere
- Points on two planes
- Original images and camera positions



## Compression

- Compress individual images (JPEG, etc.)
- Adapt video compression to 2D arrays
- Decomposition into basis functions
- Vector quantization

## Rendering

- How to select rays?
- Interpolation
- Taking advantage of hardware
  - Graphics hardware
  - Compression hardware

## Implementations

- Lightfields, Levoy and Hanrahan (SIGGRAPH 96)
- Lumigraphs, Gortler et al. (SIGGRAPH 96)
- Unstructured lumigraphs, Buehler et al. (SIGGRAPH 01)

## Light Field Rendering

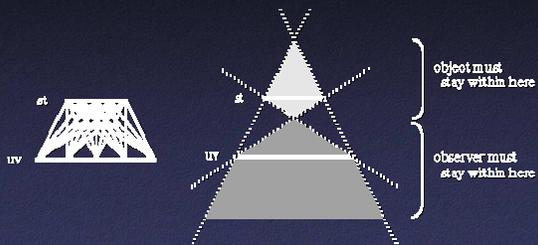
- Capture:
  - Computer-controlled camera rig
  - Move camera to grid of locations on a plane



## Light Field Two-Plane Parameterization

- Two planes, evenly sampled: “light slab”
- In general, planes in arbitrary orientations
- In practice, one plane = camera locations
  - Minimizes resampling

## Light Field Coverage



## Multi-Slab Light Fields



## Rendering

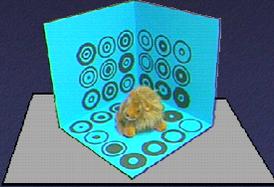
- For each desired ray:
  - Compute intersection with  $(u,v)$  and  $(s,t)$  planes
  - Take closest ray
- Variants: interpolation
  - Bilinear in  $(u,v)$  only
  - Bilinear in  $(s,t)$  only
  - Quadrilinear in  $(u,v,s,t)$

## Light Field Compression

- Based on vector quantization
- Preprocessing: build a representative codebook of 4D tiles
- Each tile in lightfield represented by index
- Example:  $2 \times 2 \times 2 \times 2$  tiles, 16 bit index = 24:1 compression

## The Lumigraph

- Capture: move camera by hand
- Camera intrinsics assumed calibrated
- Camera pose recovered from markers

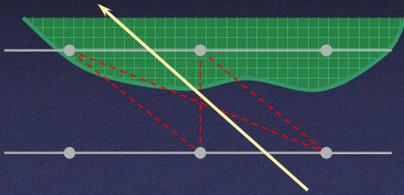


## Lumigraph Postprocessing

- Obtain rough geometric model
  - Chroma keying (blue screen) to extract silhouettes
  - Octree-based space carving
- Resample images to two-plane parameterization

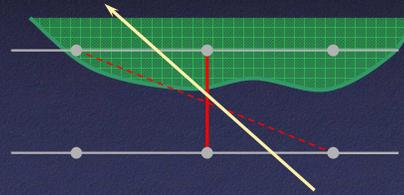
## Lumigraph Rendering

- Use rough depth information to improve rendering quality



## Lumigraph Rendering

- Use rough depth information to improve rendering quality



## Lumigraph Rendering



Without using geometry



Using approximate geometry

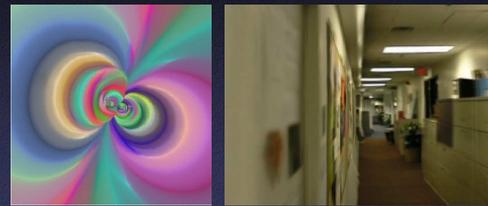
## Unstructured Lumigraph Rendering

- Further enhancement of lumigraphs: do not use two-plane parameterization
- Store original pictures: no resampling
- Hand-held camera, moved around an environment

## Unstructured Lumigraph Rendering

- To reconstruct views, assign penalty to each original ray
  - Distance to desired ray, using approximate geometry
  - Resolution
  - Feather near edges of image
- Construct “camera blending field”
- Render using texture mapping

## Unstructured Lumigraph Rendering



Blending field

Rendering

## Other Lightfield Acquisition Devices

- Spherical motion of camera around an object
- Samples space of directions uniformly
- Second arm to move light source – measure reflectance



4 degree-of-freedom gantry

## Other Lightfield Acquisition Devices

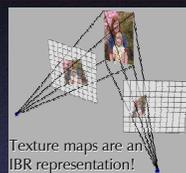
- Acquire an entire light field at once
- Video rates
- Integrated MPEG2 compression for each camera



(Bennett Wilburn, Michal Smulski, Mark Horowitz)

## Other IBR Representations

- Texture maps
- VDTMs
- Surface light fields
- Concentric mosaics
- Panorama
- Etc.



(McMillan)

## IBR Summary

- Advantages
  - Photorealistic - by definition
  - Do not have to create 3D detailed model
  - Do not have to do lighting simulation
  - Performance independent of scene
- Disadvantages
  - Static scenes only
  - Real-world scenes only
  - Difficult for scenes with specularities, etc.
  - Limited range of viewpoints
  - Limited resolution