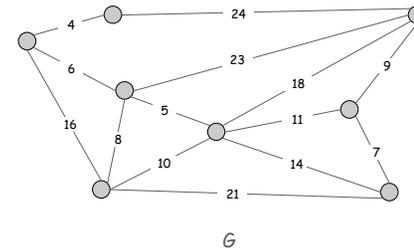


Minimum Spanning Tree

Minimum Spanning Tree

MST. Given connected graph G with positive edge weights, find a min weight set of edges that connects all of the vertices.



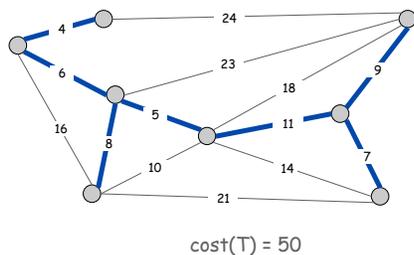
Reference: Chapter 20, Algorithms in Java, 3rd Edition, Robert Sedgewick.

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2

Minimum Spanning Tree

MST. Given connected graph G with positive edge weights, find a min weight set of edges that connects all of the vertices.



Theorem. [Cayley 1889] There are V^{V-2} spanning trees on the complete graph on V vertices.

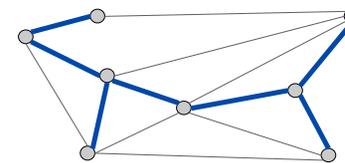
↑
can't solve by brute force

3

MST Origin

Otakar Boruvka (1926).

- Electrical Power Company of Western Moravia in Brno.
- Most economical construction of electrical power network.
- Concrete engineering problem is now a cornerstone problem in combinatorial optimization.



Otakar Boruvka

4

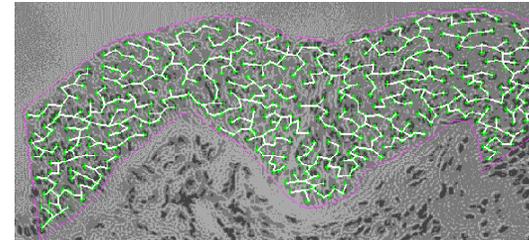
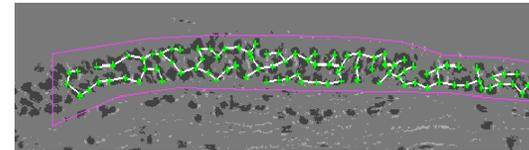
Applications

MST is fundamental problem with diverse applications.

- Network design.
 - telephone, electrical, hydraulic, TV cable, computer, road
- Approximation algorithms for NP-hard problems.
 - traveling salesperson problem, Steiner tree
- Indirect applications.
 - max bottleneck paths
 - LDPC codes for error correction
 - image registration with Renyi entropy
 - learning salient features for real-time face verification
 - reducing data storage in sequencing amino acids in a protein
 - model locality of particle interactions in turbulent fluid flows
 - autoconfig protocol for Ethernet bridging to avoid cycles in a network
- Cluster analysis.

Medical Image Processing

MST describes arrangement of nuclei in the epithelium for cancer research



http://www.bccrc.ca/ci/ta01_archlevel.html

5

6

Two Greedy Algorithms

Kruskal's algorithm. Consider edges in ascending order of cost. Add the next edge to T unless doing so would create a cycle.

Prim's algorithm. Start with any vertex s and greedily grow a tree T from s . At each step, add the cheapest edge to T that has exactly one endpoint in T .

Theorem. Both greedy algorithms compute an MST.

Greed is good. Greed is right. Greed works. Greed clarifies, cuts through, and captures the essence of the evolutionary spirit." - Gordon Gecko



Weighted Graphs

8

Weighted Graph Interface

Return Type	Method	Action
	WeightedGraph(int V)	create empty graph
void	insert(Edge e)	add edge e
Iterable<Edge>	adj(int v)	return iterator over edges incident to v
int	V()	return number of vertices
String	toString()	return string representation

```

for (int v = 0; v < G.V(); v++) {
    for (Edge e : G.adj(v)) {
        int w = e.other(v);
        // edge v-w
    }
}

```

iterate through all edges (once in each direction)

10

Edge Data Type

```

public class Edge implements Comparable<Edge> {
    public final int v, w;
    public final double weight;

    public Edge(int v, int w, double weight) {
        this.v = v;
        this.w = w;
        this.weight = weight;
    }

    public int other(int vertex) {
        if (vertex == v) return w;
        else return v;
    }

    public int compareTo(Edge f) {
        Edge e = this;
        if (e.weight < f.weight) return -1;
        else if (e.weight > f.weight) return +1;
        else return 0;
    }
}

```

11

Weighted Graph: Java Implementation

Identical to Graph.java but use Edge adjacency lists instead of int.

```

public class WeightedGraph {
    private int V; // # vertices
    private Sequence<Edge>[] adj; // adjacency lists

    public Graph(int V) {
        this.V = V;
        adj = new Sequence<Edge>[V];
        for (int v = 0; v < V; v++)
            adj[v] = new Sequence<Edge>();
    }

    public void insert(Edge e) {
        int v = e.v, w = e.w;
        adj[v].add(e);
        adj[w].add(e);
    }

    public Iterable<Edge> adj(int v) { return adj[v]; }
}

```

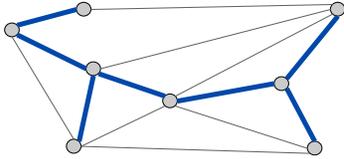
12

MST Structure

Spanning Tree

MST. Given connected graph G with positive edge weights, find a min weight set of edges that connects all of the vertices.

Def. A **spanning tree** of a graph G is a subgraph T that is connected and acyclic.



Property. MST of G is always a spanning tree.

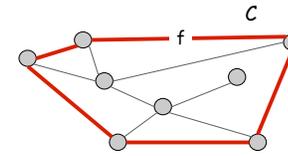
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Greedy Algorithms

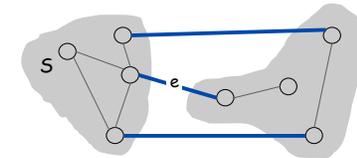
Simplifying assumption. All edge costs c_e are distinct.

Cycle property. Let C be any cycle, and let f be the max cost edge belonging to C . Then the MST does not contain f .

Cut property. Let S be any subset of vertices, and let e be the min cost edge with exactly one endpoint in S . Then the MST contains e .



f is not in the MST



e is in the MST

15

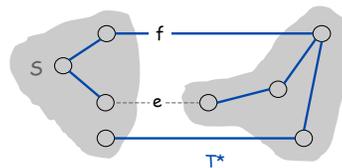
Cut Property

Simplifying assumption. All edge costs c_e are distinct.

Cut property. Let S be any subset of vertices, and let e be the min cost edge with exactly one endpoint in S . Then the MST T^* contains e .

Pf. [by contradiction]

- Suppose e does not belong to T^* . Let's see what happens.
- Adding e to T^* creates a (unique) cycle C in T^* .
- Some other edge in C , say f , has exactly one endpoint in S .
- $T = T^* \cup \{e\} - \{f\}$ is also a spanning tree.
- Since $c_e < c_f$, $\text{cost}(T) < \text{cost}(T^*)$.
- This is a contradiction. ■



16

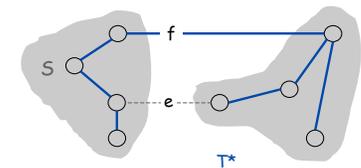
Cycle Property

Simplifying assumption. All edge costs c_e are distinct.

Cycle property. Let C be any cycle in G , and let f be the max cost edge belonging to C . Then the MST T^* does not contain f .

Pf. [by contradiction]

- Suppose f belongs to T^* . Let's see what happens.
- Deleting f from T^* disconnects T^* . Let S be one side of the cut.
- Some other edge in C , say e , has exactly one endpoint in S .
- $T = T^* \cup \{e\} - \{f\}$ is also a spanning tree.
- Since $c_e < c_f$, $\text{cost}(T) < \text{cost}(T^*)$.
- This is a contradiction. ■

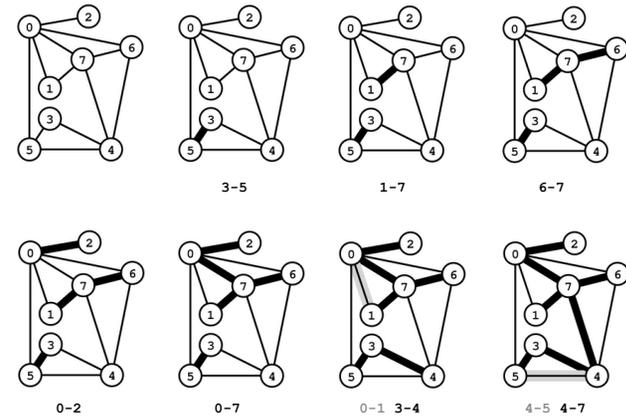


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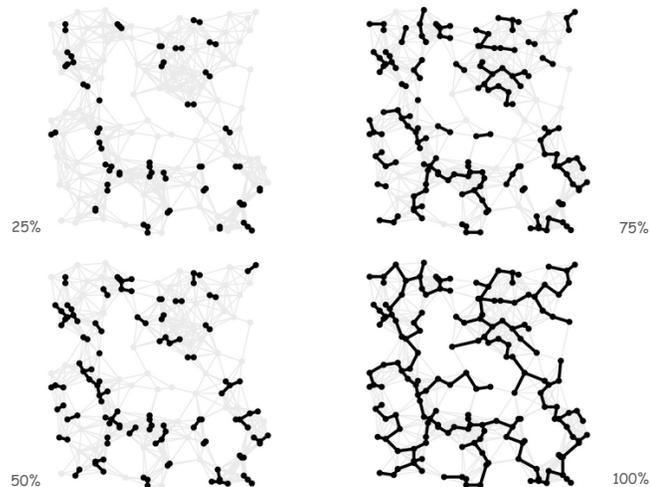
Kruskal's Algorithm

Kruskal's Algorithm: Example

Kruskal's algorithm. [Kruskal 1956] Consider edges in ascending order of cost. Add the next edge to T unless doing so would create a cycle.



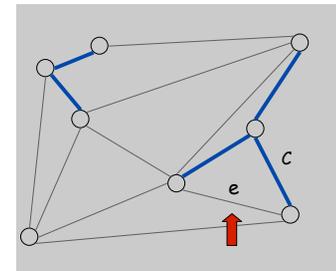
Kruskal's Algorithm: Example



Kruskal's Algorithm: Proof of Correctness

Theorem. Kruskal's algorithm computes the MST.

Pf (case 1). If adding e to T creates a cycle C , then e is the max weight edge in C , so the cycle property asserts that e is not in the MST.

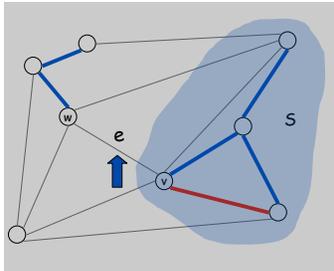


Kruskal's Algorithm: Proof of Correctness

Theorem. Kruskal's algorithm computes the MST.

Pf (case 2). If adding $e = (v, w)$ to T does not create a cycle, then e is the min weight edge with exactly one endpoint in S , so the cut property asserts that e is in the MST. ■

set of vertices in v 's connected component



22

Kruskal's Algorithm: Implementation

Q. How to check if adding an edge to T would create a cycle?

- A1.** Naïve solution: use DFS.
- $O(V)$ time per cycle check.
 - $O(EV)$ time overall.

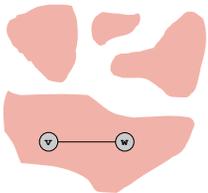
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Kruskal's Algorithm: Implementation

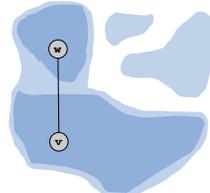
Q. How to check if adding an edge to T would create a cycle?

A2. Use the **union-find** data structure.

- Maintain a set for each connected component.
- If v and w are in same component, then adding $v-w$ creates a cycle.
- To add $v-w$ to T , merge sets containing v and w .



Case 1: adding $v-w$ creates a cycle



Case 2: add $v-w$ to T and merge sets

24

Kruskal's Algorithm: Java Implementation

```
public class Kruskal {
    private Sequence<Edge> mst = new Sequence<Edge>();

    public Kruskal(WeightedGraph G) {
        // sort edges in ascending order
        Edge[] edges = G.edges();
        Arrays.sort(edges);

        // greedily add edges to MST
        UnionFind uf = new UnionFind(G.V());
        for (int i = 0; (i < E) && (mst.size() < G.V()-1); i++) {
            int v = edges[i].v;
            int w = edges[i].w;
            if (!uf.find(v, w)) {
                uf.unite(v, w);
                mst.add(edges[i]);
            }
        }

        public Iterable<Edge> mst() { return mst; }
    }
}
```

safe to stop early if tree already has $V-1$ edges

25

Kruskal's Algorithm: Running Time

Kruskal running time. $O(E \log V)$.

$E \leq V^2$ so $O(\log E)$ is $O(\log V)$

Operation	Frequency	Cost
sort	1	$E \log V$
union	$V - 1$	$\log^* V \dagger$
find	E	$\log^* V \dagger$

\dagger amortized bound using weighted quick union with path compression

Remark. If edges already sorted: $O(E \log^* V)$ time.

recall: $\log^* V \leq 5$ in this universe

Prim's Algorithm

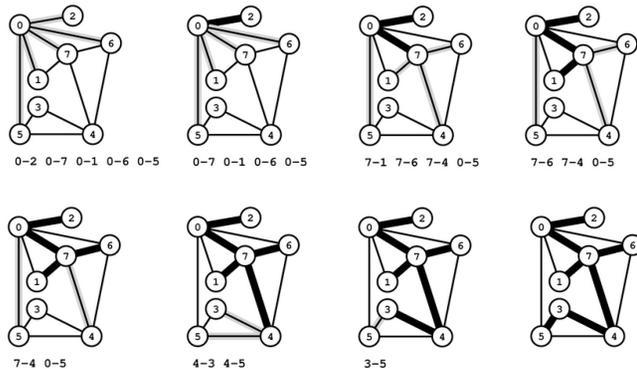
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Prim's Algorithm: Example

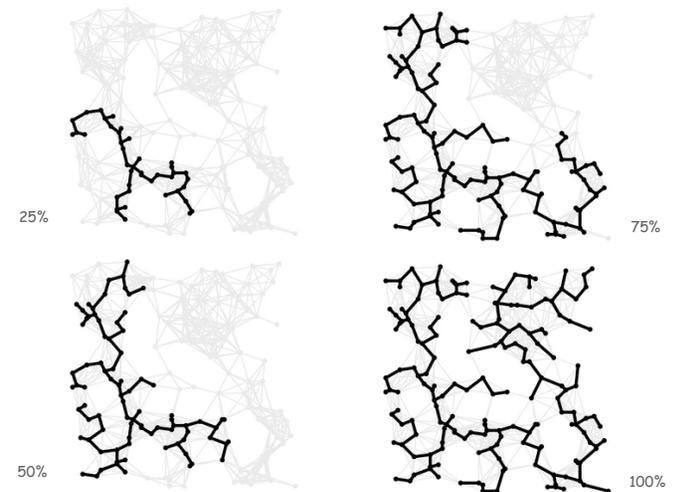
Prim's algorithm. [Jarník 1930, Dijkstra 1957, Prim 1959]

Start with vertex 0 and greedily grow tree T . At each step, add cheapest edge that has exactly one endpoint in T .



28

Prim's Algorithm: Example



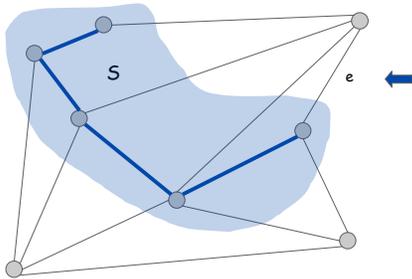
29

Prim's Algorithm: Proof of Correctness

Theorem. Prim's algorithm computes the MST.

Pf.

- Let S be the subset of vertices in current tree T .
- Prim adds the cheapest edge e with exactly one endpoint in S .
- Cut property asserts that e is in the MST. ■



30

Prim's Algorithm: Implementation

Q. How to find cheapest edge with exactly one endpoint in S ?

A1. Brute force: try all edges.

- $O(E)$ time per spanning tree edge.
- $O(EV)$ time overall.

31

Prim's Algorithm: Implementation

Q. How to find cheapest edge with exactly one endpoint in S ?

A2. Maintain edges with (at least) one endpoint in S in a priority queue.

- Delete min to determine next edge e to add to T .
- Disregard e if both endpoints are in S .
- Upon adding e to T , add edges incident to one endpoint to PQ .

Running time.

- $O(\log V)$ time per edge (using a binary heap).
- $O(E \log V)$ time overall.

the one not already in S

Prim's Algorithm: Java Implementation

```

public class LazyPrim {
    private Sequence<Edge> mst = new Sequence<Edge>();

    public LazyPrim(WeightedGraph G) {
        boolean[] marked = new boolean[G.V()];
        MinPQ<Edge> pq = new MinPQ<Edge>();

        marked[0] = true;
        for (Edge e : G.adj(0)) pq.insert(e);

        while (!pq.isEmpty()) {
            Edge e = pq.delMin();
            int v = e.v, w = e.w;
            if (!marked[v] || !marked[w]) mst.add(e);
            if (!marked[v])
                for (Edge f : G.adj(v)) pq.insert(f);
            if (!marked[w])
                for (Edge f : G.adj(w)) pq.insert(f);
            marked[v] = marked[w] = true;
        }
    }
}
    
```

32

33

Removing the Distinct Edge Costs Assumption

Simplifying assumption. All edge costs c_e are distinct.

One way to remove assumption. Kruskal and Prim only access edge weights through `compareTo`; suffices to introduce tie-breaking rule.

```
public int compareTo(Edge f) {
    Edge e = this;
    if (e.weight < f.weight) return -1;
    if (e.weight > f.weight) return +1;
    if (e.v < f.v) return -1;
    if (e.v > f.v) return +1;
    if (e.w < f.w) return -1;
    if (e.w > f.w) return +1;
    return 0;
}
```

34

Advanced MST Algorithms

Removing the Distinct Edge Costs Assumption

Simplifying assumption. All edge costs c_e are distinct.

Fact. Prim and Kruskal don't actually rely on the assumption.

only our proof of correctness does!

35

Advanced MST Algorithms

Year	Worst Case	Discovered By
1975	$E \log \log V$	Yao
1976	$E \log \log V$	Cheriton-Tarjan
1984	$E \log^* V, E + V \log V$	Fredman-Tarjan
1986	$E \log(\log^* V)$	Gabow-Galil-Spencer-Tarjan
1997	$E \alpha(V) \log \alpha(V)$	Chazelle
2000	$E \alpha(V)$	Chazelle
2002	optimal	Pettie-Ramachandran
20??	E	???

deterministic comparison based MST algorithms



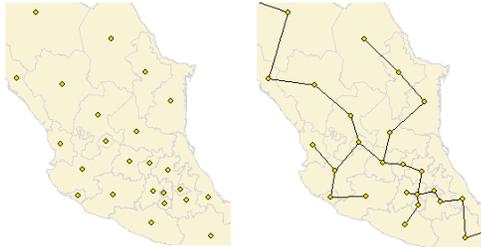
Year	Problem	Time	Discovered By
1976	Planar MST	E	Cheriton-Tarjan
1992	MST Verification	E	Dixon-Rauch-Tarjan
1995	Randomized MST	E	Karger-Klein-Tarjan

related problems

Euclidean MST

Euclidean MST. Given N points in the plane, find MST connecting them.

- Distances between point pairs are **Euclidean** distances.



Brute force. Compute $\Theta(N^2)$ distances and run Prim's algorithm.

Ingenuity. Exploit geometry and do it in $O(N \log N)$.

38

Euclidean MST

Key geometric fact. Edges of the Euclidean MST are edges of the Delaunay triangulation.

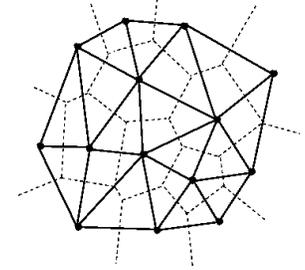
Euclidean MST algorithm.

- Compute Voronoi diagram to get Delaunay triangulation.
- Run Kruskal's MST algorithm on Delaunay edges.

Running time. $O(N \log N)$.

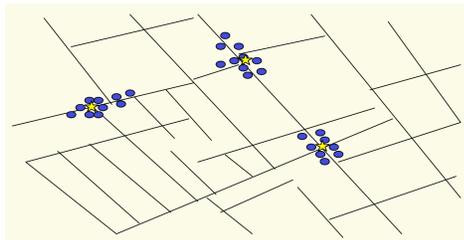
- Fact: $\leq 3N$ Delaunay edges since it's planar.
- $O(N \log N)$ for Voronoi.
- $O(N \log N)$ for Kruskal.

Lower bound. Any comparison-based Euclidean MST algorithm requires $\Omega(N \log N)$ comparisons.



39

Clustering



Outbreak of cholera deaths in London in 1850s.
Reference: Nina Mishra, HP Labs

Clustering

Clustering. Given a set of objects classify into coherent groups.

photos, documents, micro-organisms

Distance function. Numeric value specifying "closeness" of two objects.

number of corresponding pixels whose intensities differ by some threshold

Fundamental problem. Divide into clusters so that points in different clusters are far apart.

- Routing in mobile ad hoc networks.
- Identify patterns in gene expression.
- Document categorization for web search.
- Similarity searching in medical image databases
- Skycat: cluster 10^9 sky objects into stars, quasars, galaxies.

Clustering of Maximum Spacing

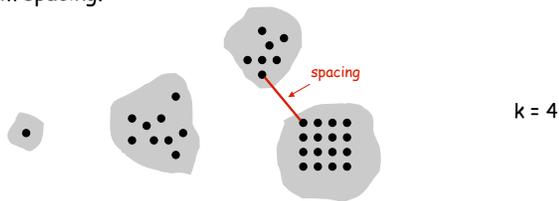
k-clustering. Divide objects into k non-empty groups.

Distance function. Assume it satisfies several natural properties.

- $c(v, w) = 0$ iff $v = w$ (identity of indiscernibles)
- $c(v, w) \geq 0$ (nonnegativity)
- $c(v, w) = c(w, v)$ (symmetry)

Spacing. Min distance between any pair of points in different clusters.

Clustering of maximum spacing. Given an integer k , find a k -clustering of maximum spacing.



42

Single-Link Clustering Algorithm

Single-link k-clustering algorithm.

- Form V clusters of one object each.
- Find the closest pair of objects such that each object is in a different cluster, and add an edge between them.
- Repeat until there are exactly k clusters.

Observation. This procedure is precisely Kruskal's algorithm (except we stop when there are k connected components).

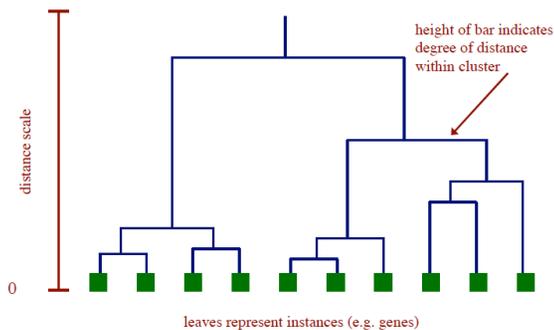
Property. Algorithm finds a k -clustering of maximum spacing.

43

Dendrogram

Dendrogram. Scientific visualization of hypothetical sequence of evolutionary events.

- Leaves = genes.
- Internal nodes = hypothetical ancestors.

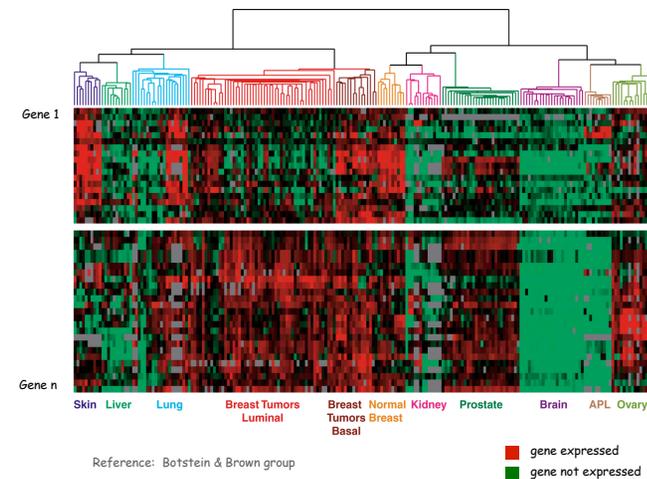


Reference: <http://www.biostat.wisc.edu/bmi576/fall-2003/lecture13.pdf>

44

Dendrogram of Cancers in Human

Tumors in similar tissues cluster together.



Reference: Botstein & Brown group

45