



Memory Allocation

CS 217



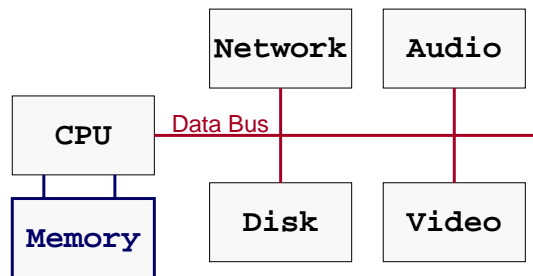
Memory Allocation

- Good programmers make efficient use of memory
- Understanding memory allocation is important
 - Create data structures of arbitrary size
 - Avoid “memory leaks”
 - Run-time performance



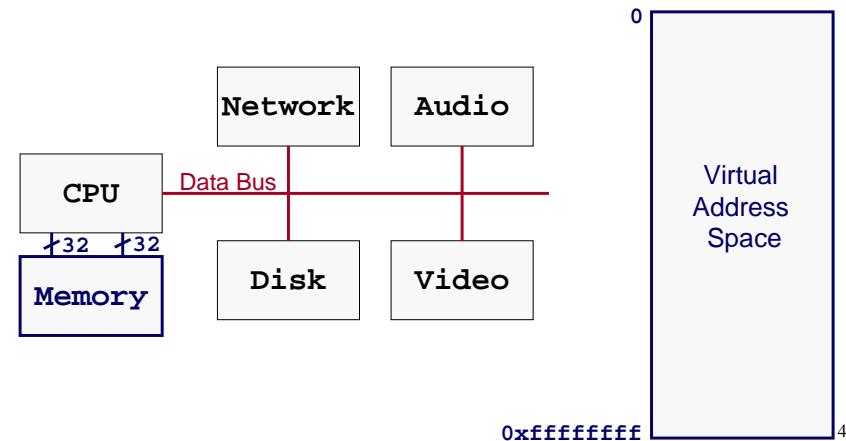
Memory

- What is memory?
 - Storage for variables, data, code, etc.



Memory

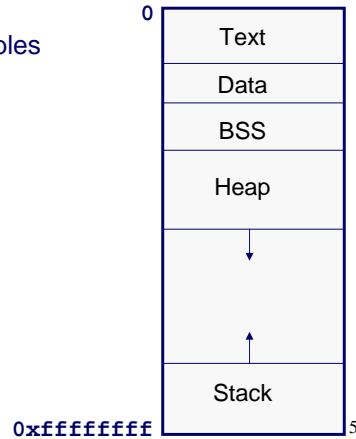
- What is memory?
 - Storage for variables, data, code, etc.
 - Unix provides virtual memory



Memory Layout



- How is memory organized?
 - Text = code, constant data
 - Data = initialized global and static variables
 - BSS = (Block Started by Symbol) uninitialized (zero) global & static variables
 - Stack = local variables
 - Heap = dynamic memory

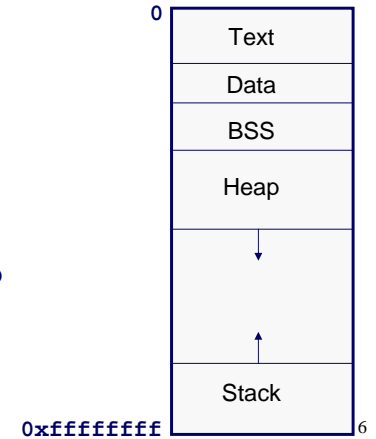


Memory Layout



```
char string = "hello" ← data
int iSize; ← bss

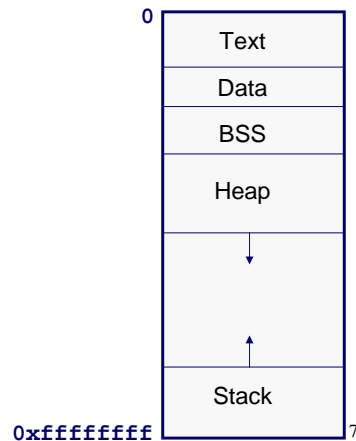
char *f(void)
{
    char *p; ← stack
    iSize = 8;
    p = malloc(iSize); ← heap
    return p;
} ← text
```



Memory Allocation



- How is memory allocated?
 - Global and static variables = program startup
 - Local variables = function call
 - Dynamic memory = malloc()



Memory Allocation



```
int iSize; ← allocated in BSS, set to zero at startup

char *f(void)
{
    char *p; ← allocated on stack at start of function f
    iSize = 8;
    p = malloc(iSize); ← 8 bytes allocated in heap by malloc
    return p;
}
```

Memory Deallocation



- How is memory deallocated?
 - Global and static variables = program finish
 - Local variables = function return
 - Dynamic memory = free()
- All memory is deallocated at program termination
 - It is good style to free allocated memory anyway

Memory Deallocation



```

int iSize;                                     ← available until program termination

char *f(void)
{
    char *p;                                   ← deallocated by return from function f
    iSize = 8;
    p = malloc(iSize);                         ← deallocate by calling free(p)
    return p;
}
    
```

Dynamic Memory



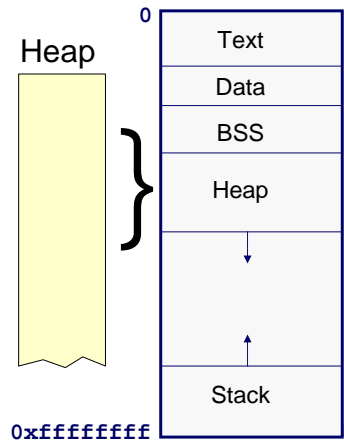
```

#include <stdlib.h>
void *malloc(size_t size);
void free(void *ptr);
    
```

size_t is a typedef for an appropriate-sized unsigned int, e.g.,
 typedef unsigned size_t

```

char *p1 = malloc(3);
char *p2 = malloc(1);
char *p3 = malloc(4);
free(p2);
char *p4 = malloc(6);
free(p3);
char *p5 = malloc(2);
free(p1);
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free(p5);
    
```



Dynamic Memory

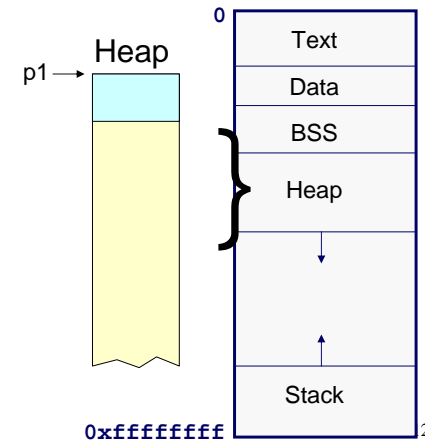


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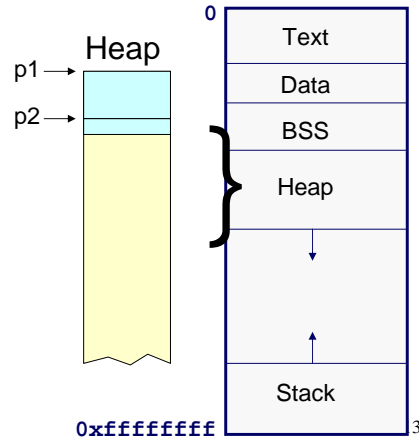


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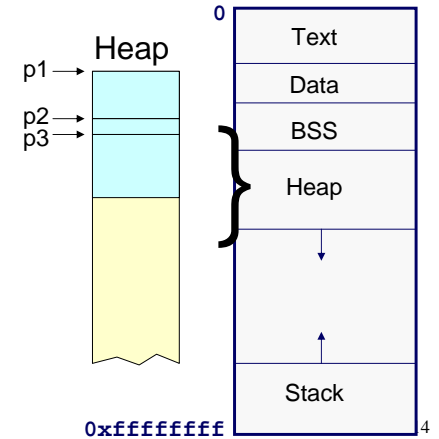


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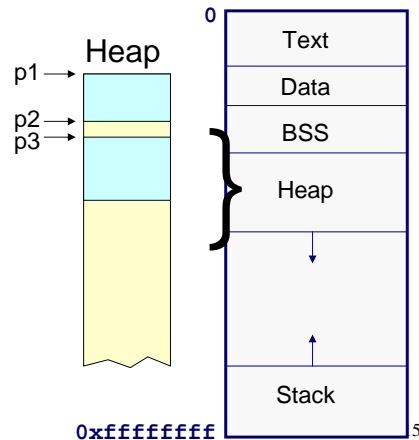


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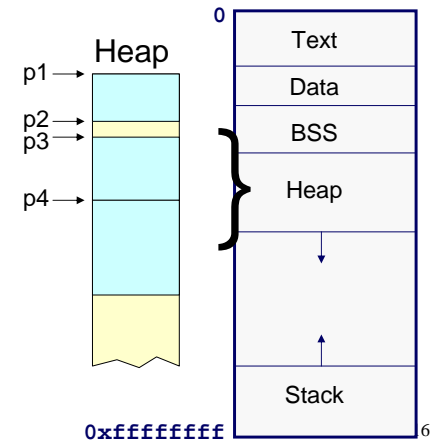


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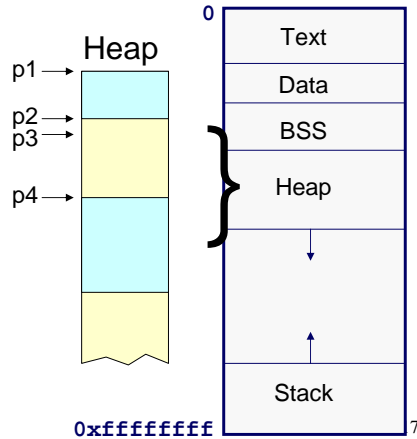


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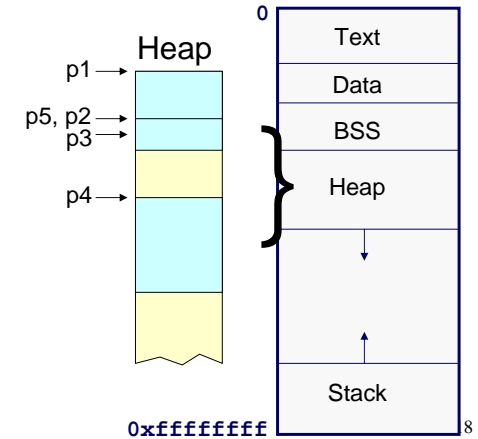


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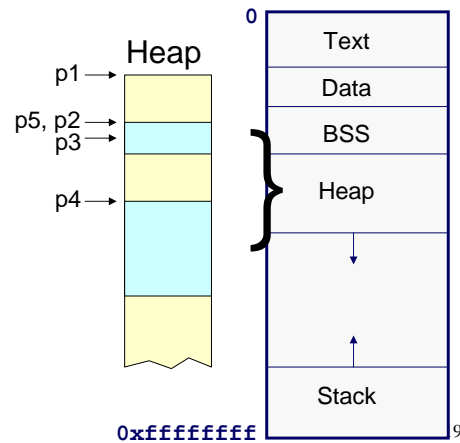


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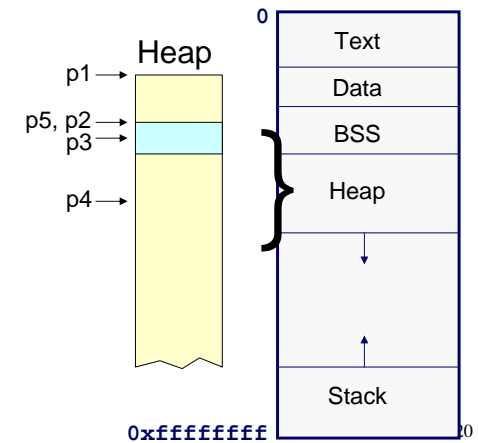


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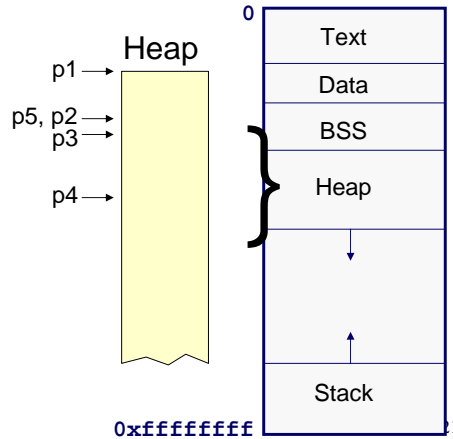


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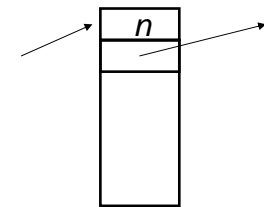
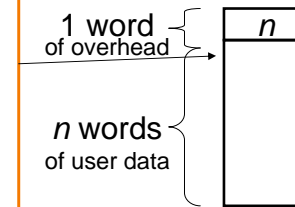
Memory allocator ADT



- Malloc & free are the operations of an ADT
 - How do they work inside?
- First answer: it's an ADT, you're not supposed to ask!
- Second answer:

```
malloc(s)
n = ⌈s / sizeof(int)⌉
```

```
free(p)
put p into linked list of free objects
```



Dangling pointers



- Dangling pointers point to data that's not there anymore
- Avoid dangling pointers!
- Example:

Example Code I

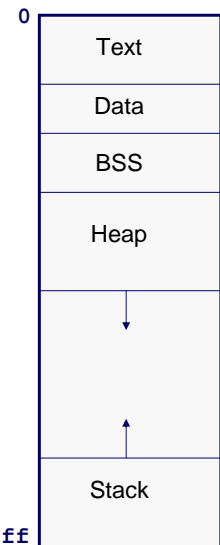


```
...
void ReadStrings(Array_T strings, FILE *fp)
{
    char buffer[MAX_STRING_LENGTH];
    while (fgets(buffer, MAX_STRING_LENGTH, fp)) {
        Array_insert(strings, buffer);
    }
}
...
int main()
{
    Array_T strings = Array_new();

    ReadStrings(strings, stdin);
    SortStrings(strings, strcmp);
    WriteStrings(strings, stdout);

    Array_free(strings);

    return 0;
}
```



Example Code I



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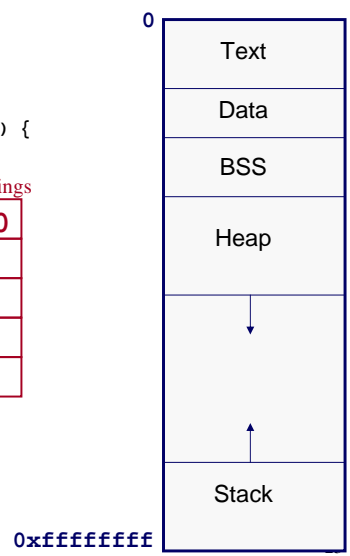
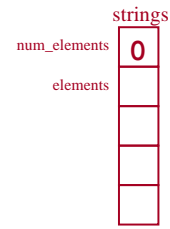
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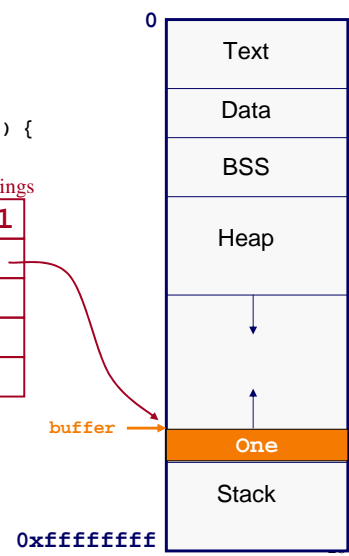
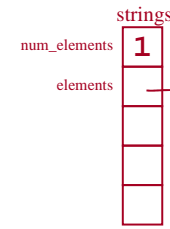
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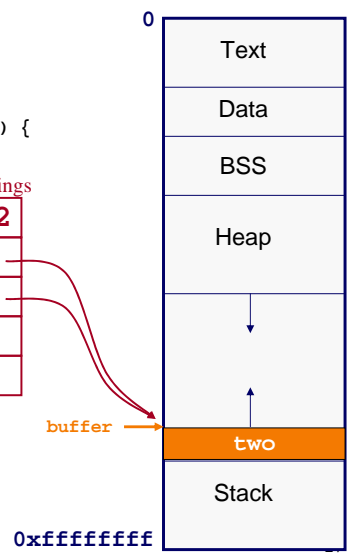
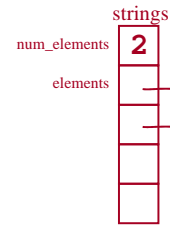
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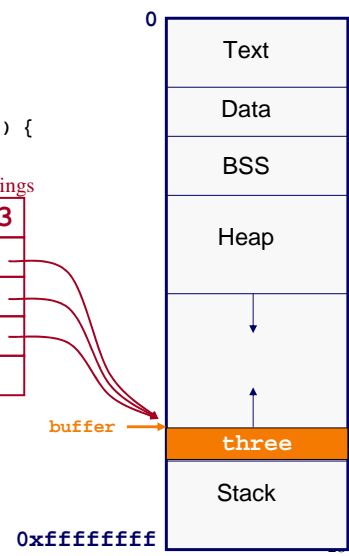
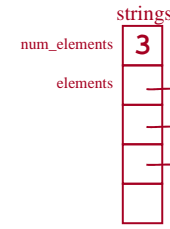
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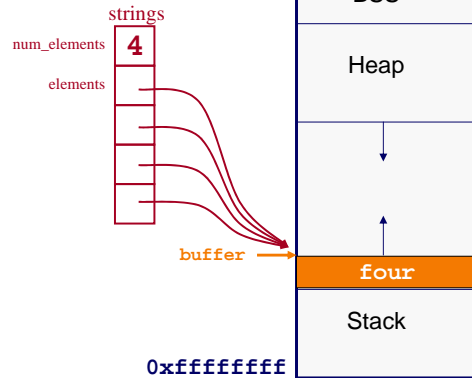
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Example Code I



```

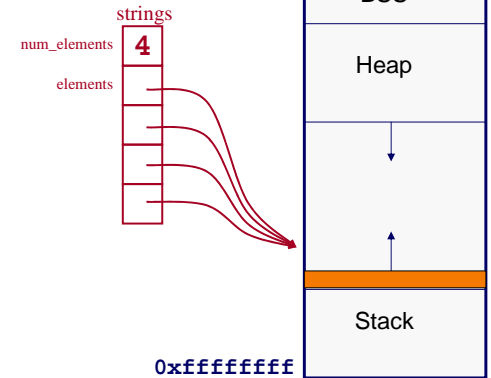
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Example Code II



```

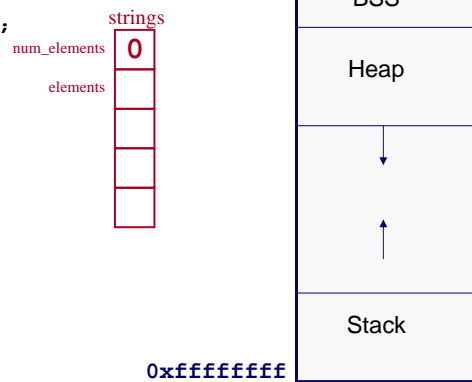
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void ReadStrings(Array_T strings, FILE *fp)
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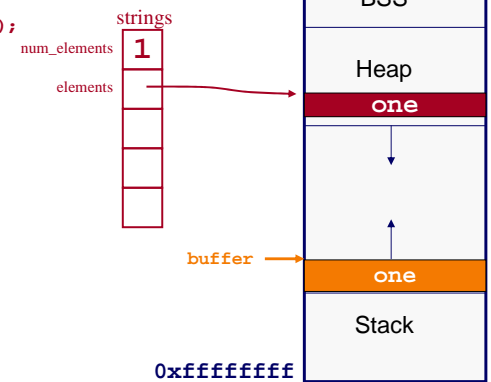
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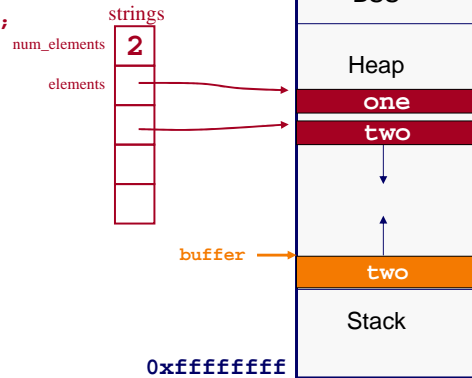
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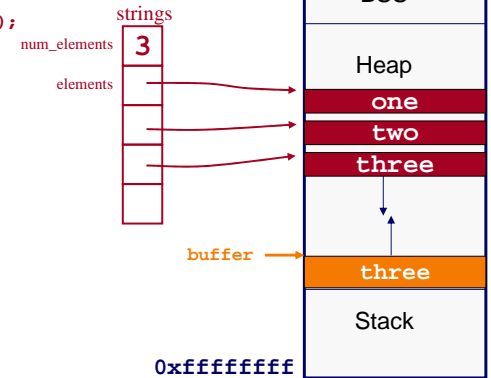
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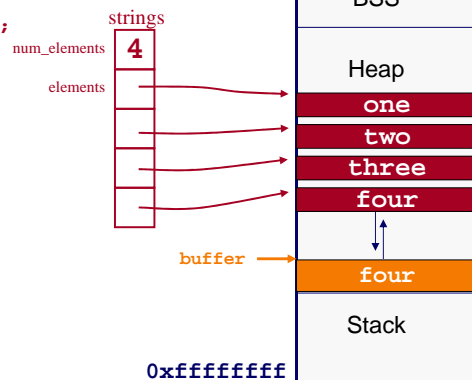
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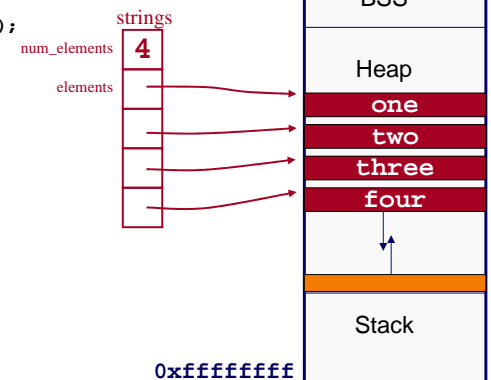
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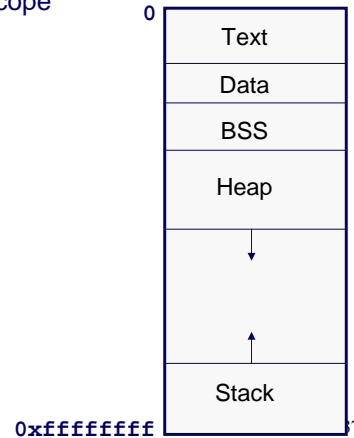
Static Local Variables



- **static** keyword in declaration of local variable means:
 - Available (if within scope) throughout entire program execution
 - Variable is allocated from Data or BSS, not stack
 - Acts like global variable with limited scope

```
int iSize;

char *f(void)
{
    static int first = 1;
    if (first) {
        iSize = GetSize();
        first = 0;
    }
    ...
}
```



Memory Initialization



- Local variables have undefined values
 - `int count;`
- Memory allocated by malloc has undefined values
 - `char *p = malloc(8);`
- If you need a variable to start with a particular value, use an explicit initializer
 - `int count = 0;`
 - `p[0] = '\0';`
- Global and static variables are initialized to 0 by default

```
static int count = 0;
is the same as
static int count;
```

It is bad style to depend on this

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Summary



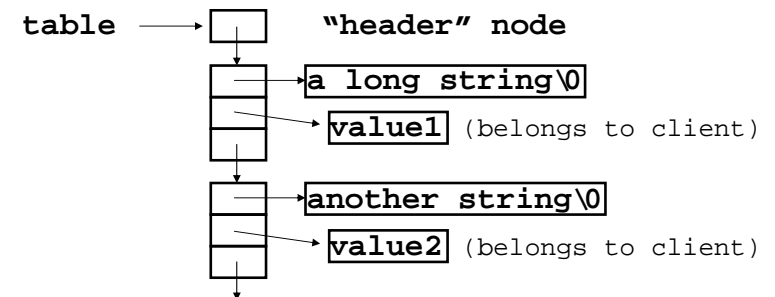
- Three types of memory
 - Global and static variables = BSS
 - Local variables = stack
 - Dynamic memory = heap
- Three types of allocation/deallocation strategies
 - Global and static variables (BSS) = program startup/termination
 - Local variables (stack) = function entry/return
 - Dynamic memory (heap) = malloc()/free()
- Take the time to understand the differences!

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ADT Implementation



- Recall the simple implementation of the symtable ADT:

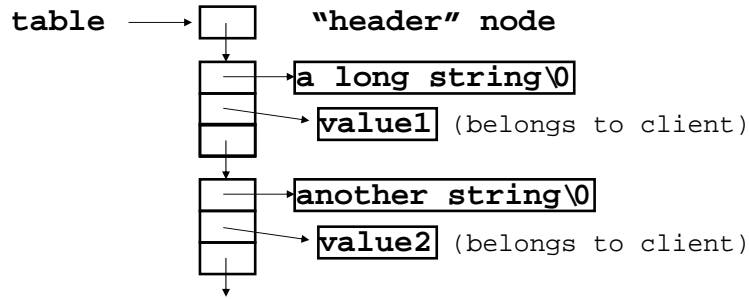
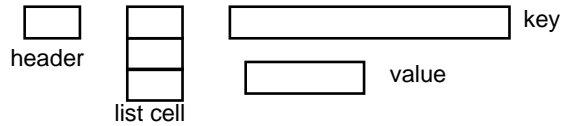


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Memory Management Issues



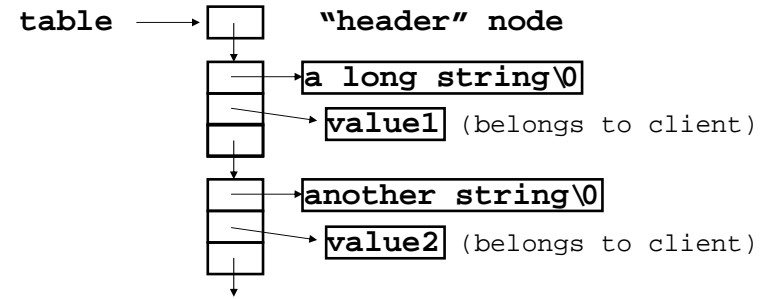
- Does ADT or client “own” the data?
 - Who mallocs/frees each kind of node?



Who Free What



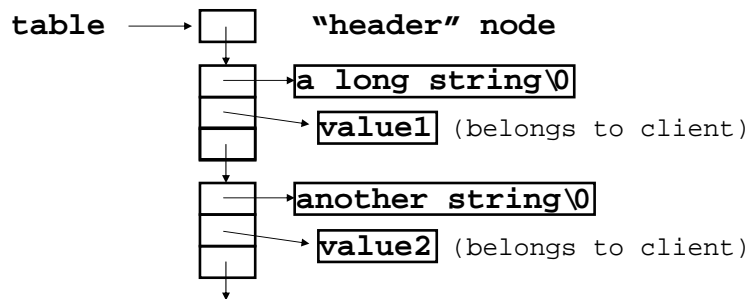
- Who frees the list header and the list cells?



Who Free What



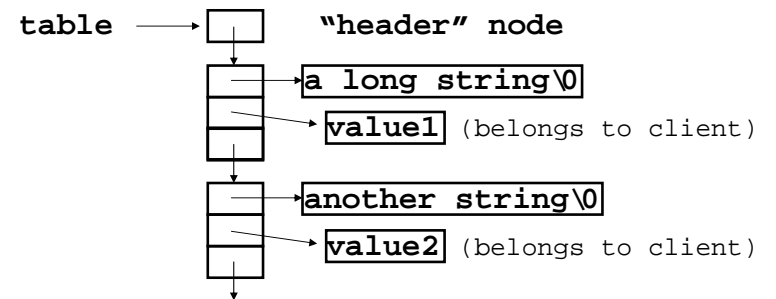
- What happens if,
`{SymTable_T table; . . . free(table);}`
then the list cells don't get freed!
- So, ADT must “own” headers and list cells



Who Free What, cont'd



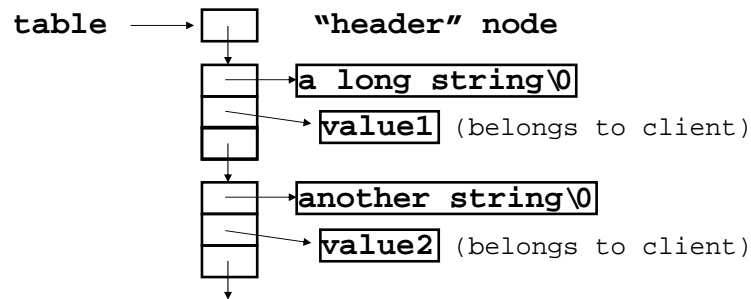
- Who frees the value pointers?



Who Free What, cont'd



- Who frees the value pointers?
- What's wrong with the ADT freeing the value pointers?

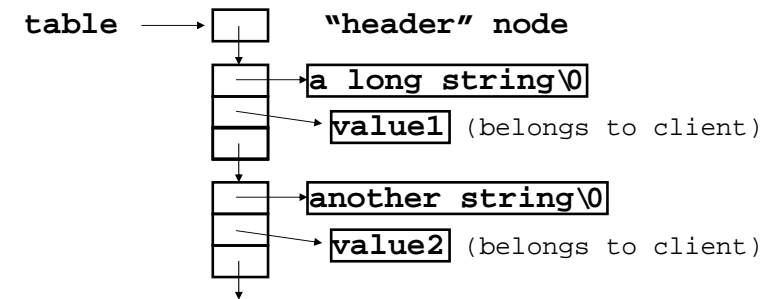


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Who Free What, cont'd



- ADT just sees `void *value;`
- Value pointer might be root of big data structure, all the pieces need to be freed.
- Thus, client must "own" the value nodes.

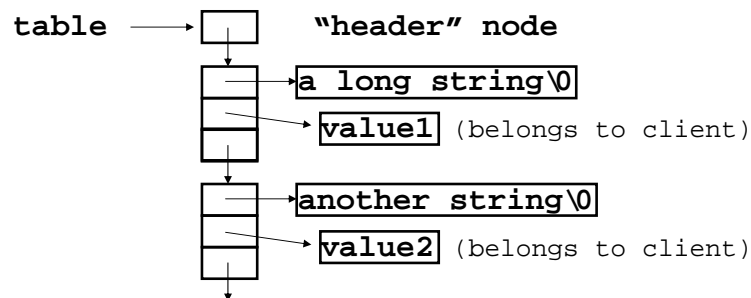


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Who Owns The Key?



- Who frees keys?

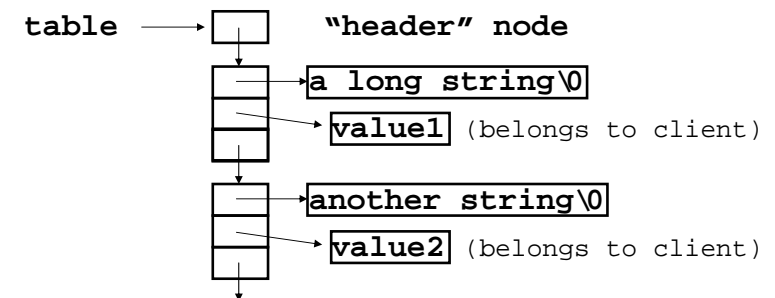


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Who Owns The Key?



- Both client and ADT "know" about `char *key;`
- Therefore, we are faced with a design choice
- Choice 1: client owns the key.
 - Consequence: must call `SymTable_put` only with a string that will last a long time. *(But our client didn't do that!)*



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Previous Example Overwrites “line”



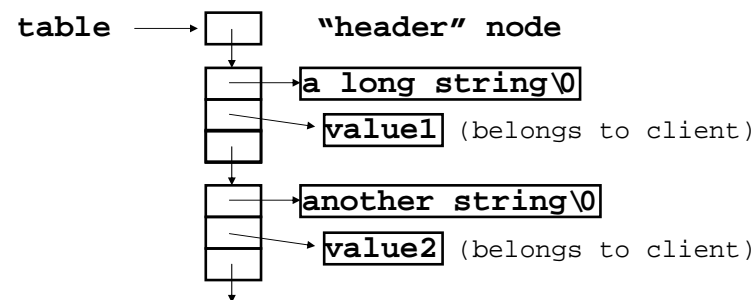
```
int main(int argc, char *argv[]) {
    char line[MAXLINE];
    SymTable_T table = SymTable_new();
    struct stats *v;
    while (fgets(line, MAXLINE, stdin)) {
        v = SymTable_get(table, line);
        if (!v) {
            v = makeStats(0);
            SymTable_put(table, line, v);
        }
    }
    SymTable_map(table, maybeprint, NULL);
    return EXIT_SUCCESS;
}
```

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Choice 2: ADT owns the key



- Consequence: `SymTable_put` must copy its key argument into a newly malloc'ed string object.



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Put Away Your Toys...



- When client is done with a symbol table, it should give the memory back.
- But client can't call `free` directly (as we already demonstrated)
- So there must be an interface function for client to say "I'm done with this"
- It should free the header, list cells, strings
`SymTable_free(SymTable_T table);`
- Should it free the values?
 - Can't do it by calling `free` directly (as we already demonstrated)
 - Another design choice!

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Options to Free Values



- Option 1: Client frees all the values before calling `SymTable_free(table)`
 - Can do this using `SymTable_map(table, free_it, NULL);`
 - Minor bother: temporarily leaves dangling pointers in the table
 - Minor bother: it's clumsy
- Option 2: `SymTable_free` calls client function

```
void SymTable_free(SymTable_T table,
    void (*f)(char *key, void *value, void *extra),
    void *extra);
```

/* Free entire table. During this process, if f is not NULL, apply f to each binding in table. It is a checked runtime error for table to be NULL. */
- We will choose Option 1.

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