



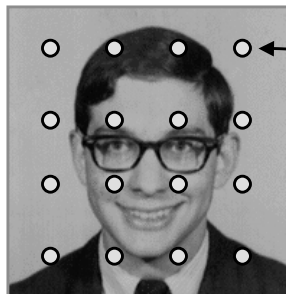
Image Sampling and Reconstruction

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Princeton University
COS 426, Fall 2000



Image Sampling

- An image is a 2D rectilinear array of samples
 - Quantization due to limited intensity resolution
 - Sampling due to limited spatial and temporal resolution



→ Pixels are
infinitely small
point samples

Image Reconstruction



- Re-create continuous image from samples
 - Example: cathode ray tube

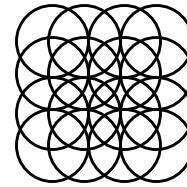
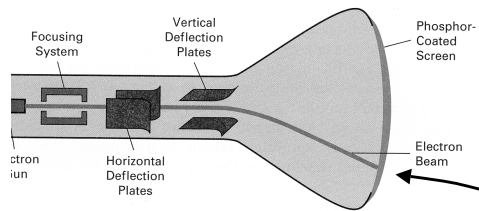


Image is reconstructed
by displaying pixels
with finite area
(Gaussian)

Sampling and Reconstruction

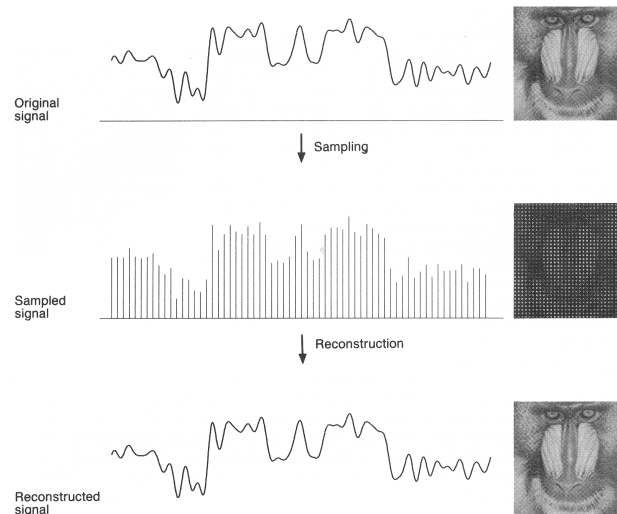
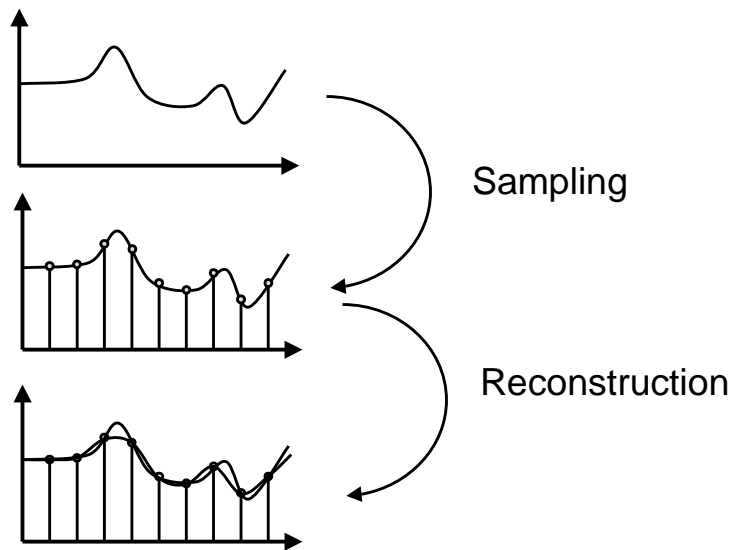


Figure 19.9 FvDFH

Sampling and Reconstruction



Sources of Error



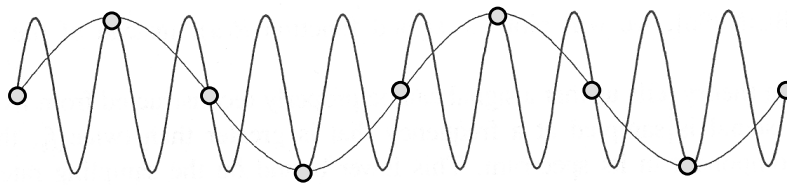
- Intensity quantization
 - Not enough intensity resolution
- Spatial aliasing
 - Not enough spatial resolution
- Temporal aliasing
 - Not enough temporal resolution

$$E^2 = \sum_{(x,y)} (I(x,y) - P(x,y))^2$$

Aliasing (in general)



- In general:
 - Artifacts due to under-sampling or poor reconstruction
- Specifically, in graphics:
 - Spatial aliasing
 - Temporal aliasing



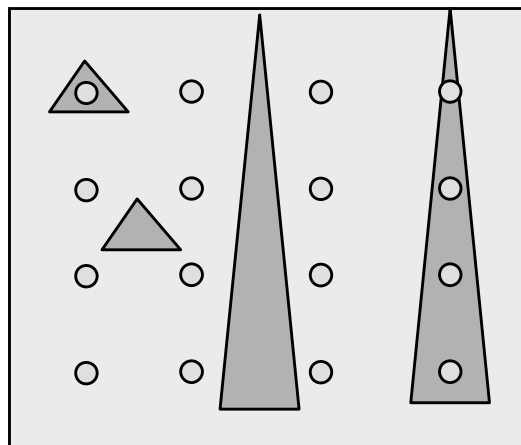
Under-sampling

Figure 14.17 FvDFH

Spatial Aliasing



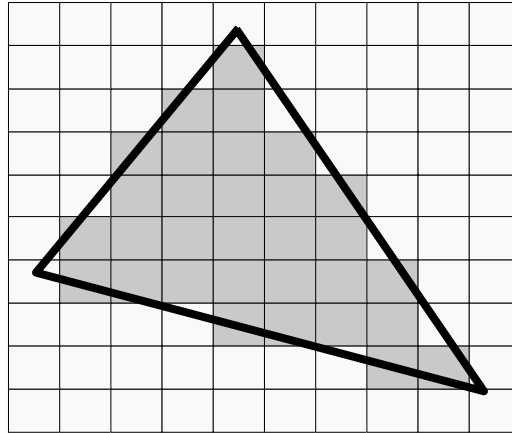
- Artifacts due to limited spatial resolution



Spatial Aliasing



- Artifacts due to limited spatial resolution

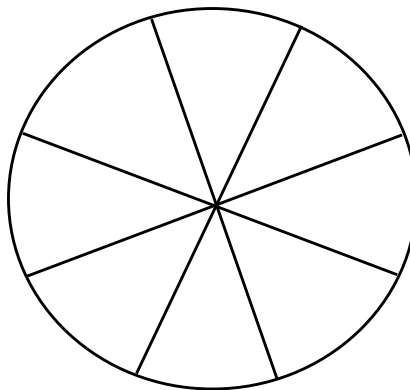


“Jaggies”

Temporal Aliasing



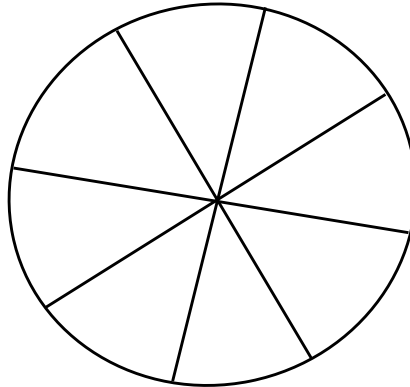
- Artifacts due to limited temporal resolution
 - Strobbing
 - Flickering



Temporal Aliasing



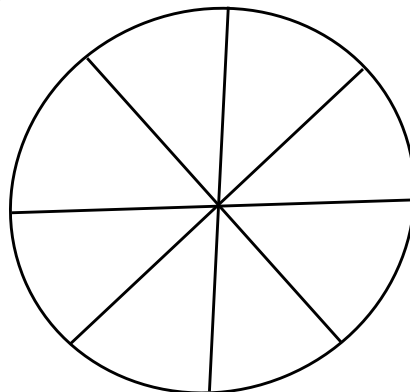
- Artifacts due to limited temporal resolution
 - Strobbing
 - Flickering



Temporal Aliasing



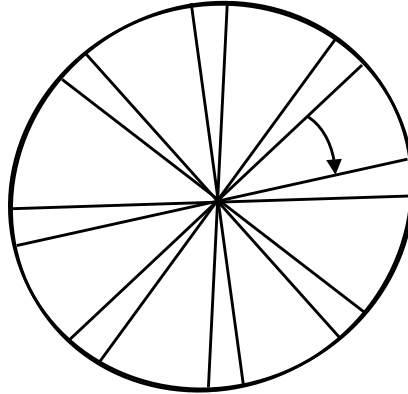
- Artifacts due to limited temporal resolution
 - Strobbing
 - Flickering



Temporal Aliasing



- Artifacts due to limited temporal resolution
 - Strobing
 - Flickering



Antialiasing



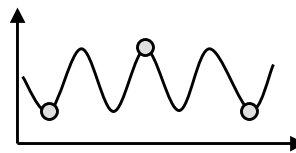
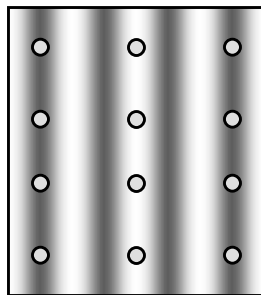
- Sample at higher rate
 - Not always possible
 - Doesn't always solve problem
- Pre-filter to form bandlimited signal
 - Form bandlimited function (low-pass filter)
 - Trades aliasing for blurring

Must consider
sampling theory!

Sampling Theory



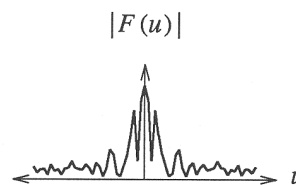
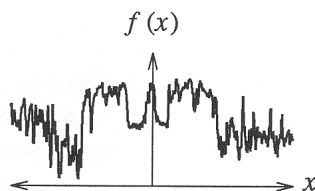
- How many samples are required to represent a given signal without loss of information?
- What signals can be reconstructed without loss for a given sampling rate?



Spectral Analysis



- Spatial domain:
 - Function: $f(x)$
 - Filtering: convolution
- Frequency domain:
 - Function: $F(u)$
 - Filtering: multiplication



Any signal can be written as a sum of periodic functions.

Fourier Transform

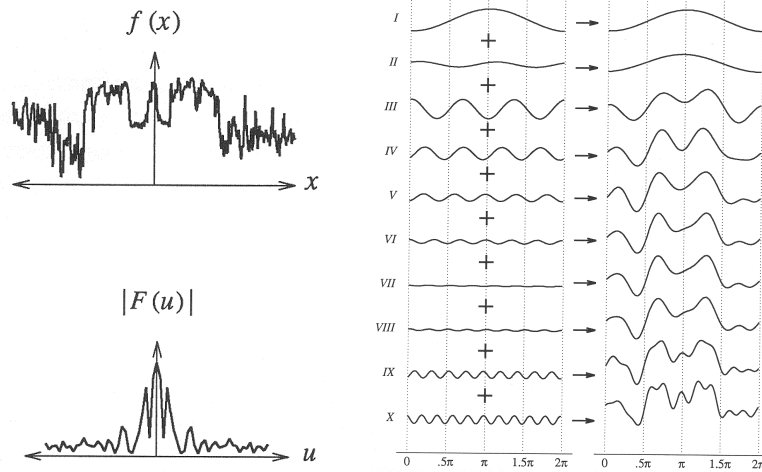


Figure 2.6 Wolberg

Fourier Transform

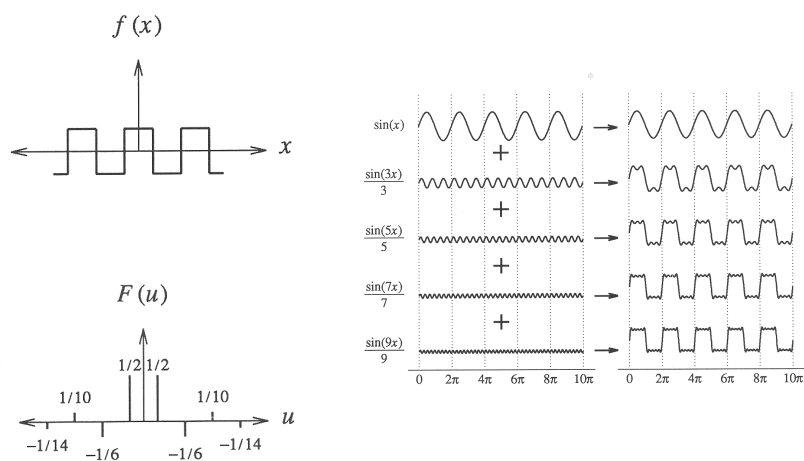


Figure 2.5 Wolberg

Fourier Transform



- Fourier transform:

$$F(u) = \int_{-\infty}^{\infty} f(x) e^{-i2\pi x} dx$$

- Inverse Fourier transform:

$$f(x) = \int_{-\infty}^{\infty} F(u) e^{+i2\pi u} du$$

Sampling Theorem



- A signal can be reconstructed from its samples, if the original signal has no frequencies above 1/2 the sampling frequency - Shannon
- The minimum sampling rate for bandlimited function is called "Nyquist rate"

A signal is bandlimited if its highest frequency is bounded. The frequency is called the bandwidth.

Convolution



- Convolution of two functions (= filtering):

$$g(x) = f(x) \otimes h(x) = \int_{-\infty}^{\infty} f(\lambda)h(x - \lambda)d\lambda$$

- Convolution theorem
 - Convolution in frequency domain is same as multiplication in spatial domain, and vice-versa

Image Processing



- | | |
|---|--|
| <ul style="list-style-type: none">• Quantization<ul style="list-style-type: none">◦ Uniform Quantization◦ Random dither◦ Ordered dither◦ Floyd-Steinberg dither• Pixel operations<ul style="list-style-type: none">◦ Add random noise◦ Add luminance◦ Add contrast◦ Add saturation | <ul style="list-style-type: none">• Filtering<ul style="list-style-type: none">◦ Blur◦ Detect edges• Warping<ul style="list-style-type: none">◦ Scale◦ Rotate◦ Warps• Combining<ul style="list-style-type: none">◦ Morphs◦ Composite |
|---|--|

Image Processing



- Consider reducing the image resolution



Original image

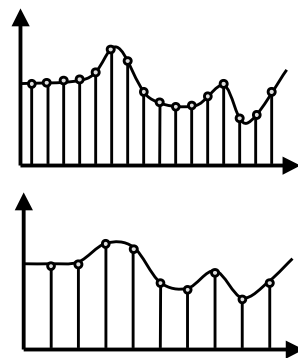


1/4 resolution

Image Processing



- Image processing is a resampling problem



Resampling

Thou shalt avoid aliasing!

Antialiasing in Image Processing



- General Strategy
 - Pre-filter transformed image via convolution with low-pass filter to form bandlimited signal
- Rationale
 - Prefer blurring over aliasing

Image Processing

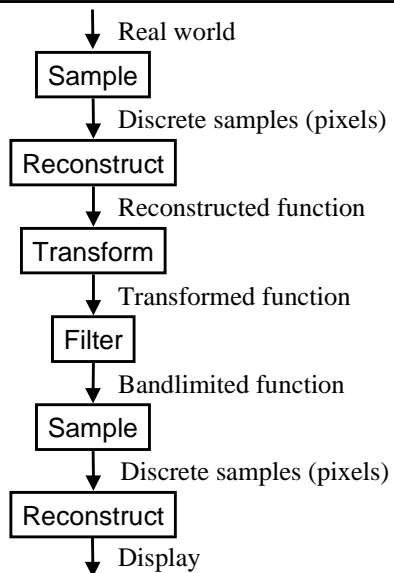


Image Processing

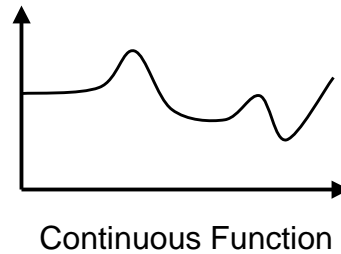
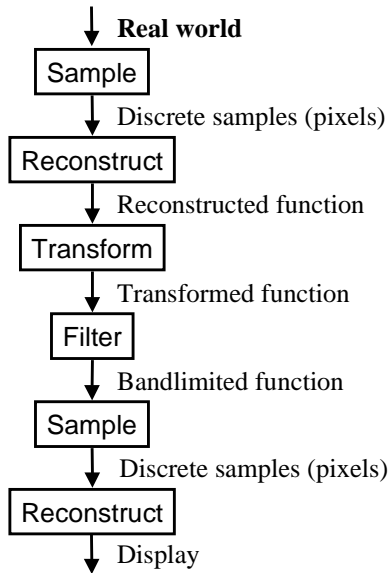


Image Processing

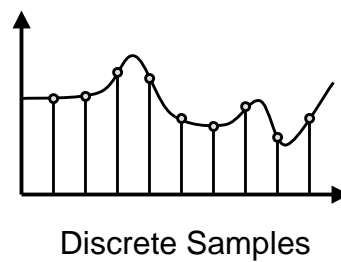
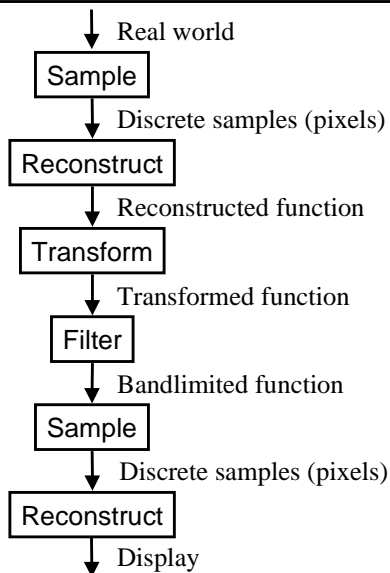


Image Processing

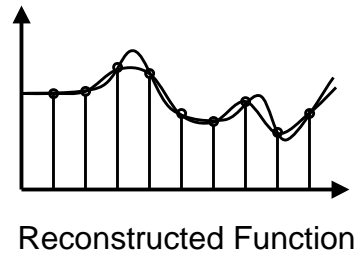
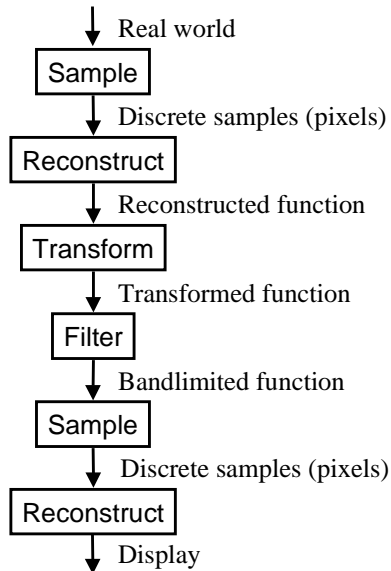


Image Processing

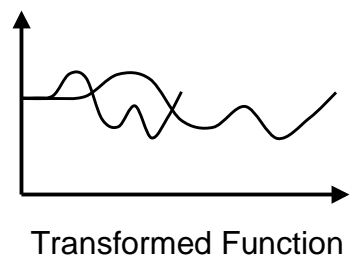
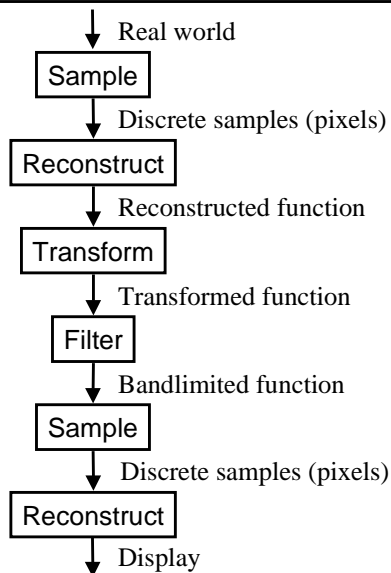


Image Processing

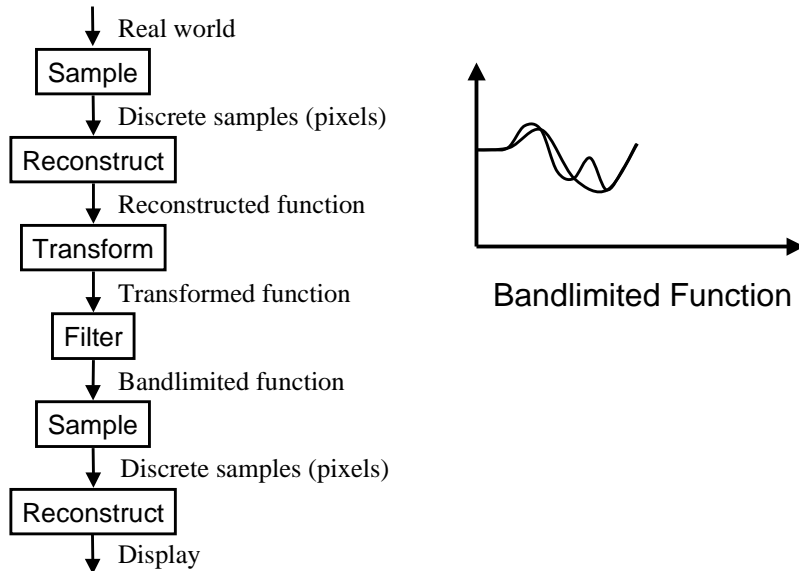


Image Processing

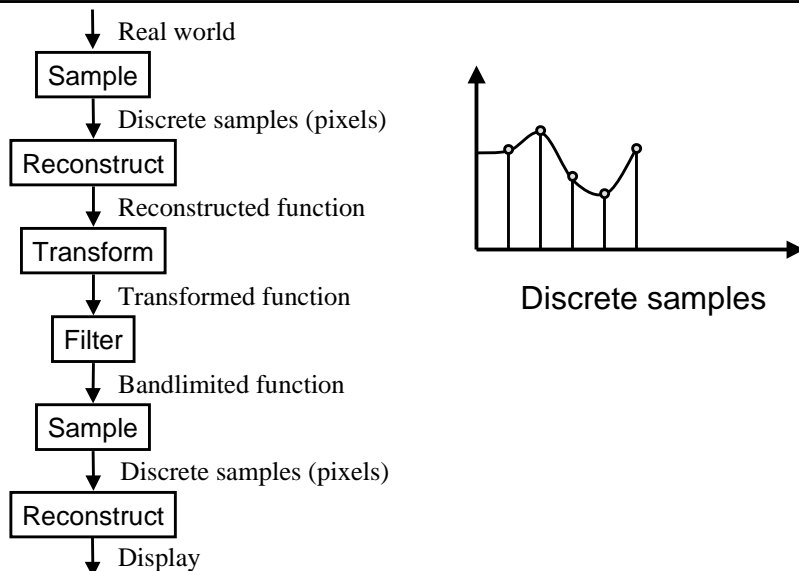
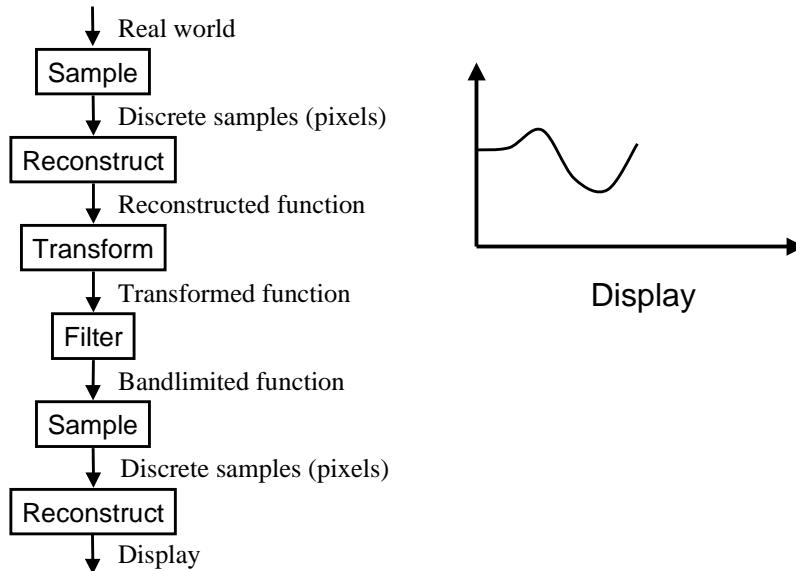


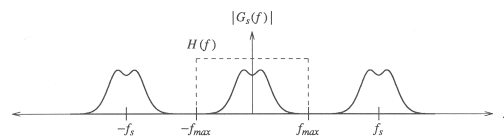
Image Processing



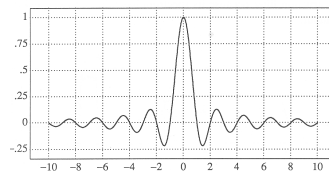
Ideal Low-Pass Filter



- Frequency domain



- Spatial domain



$$\text{Sinc}(x) = \frac{\sin \pi x}{\pi x}$$

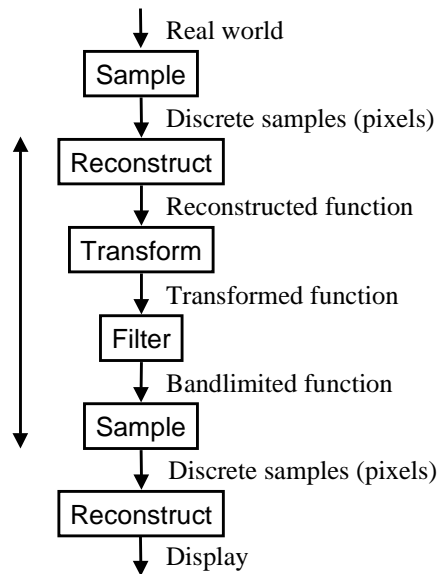
Figure 4.5 Wolberg

Practical Image Processing



- Finite low-pass filters

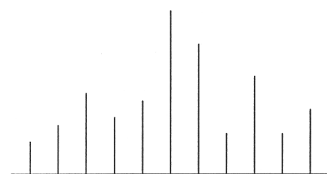
- Point sampling (bad)
- Triangle filter
- Gaussian filter



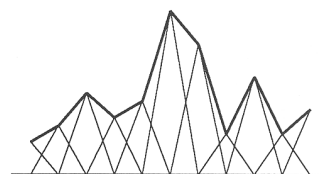
Triangle Filter



- Convolution with triangle filter



Input



Output

Figure 2.4 Wolberg

Gaussian Filter



- Convolution with Gaussian filter

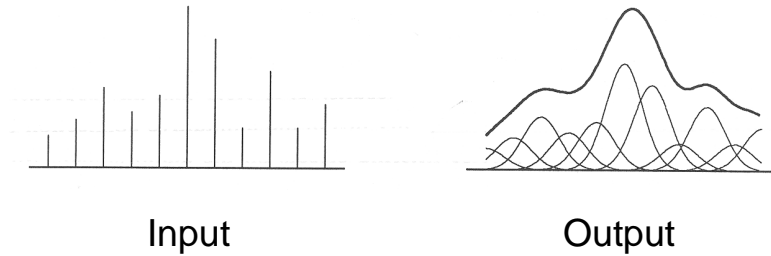


Figure 2.4 Wolberg

Image Processing



- Quantization
 - Uniform Quantization
 - Random dither
 - Ordered dither
 - Floyd-Steinberg dither
- Pixel operations
 - Add random noise
 - Add luminance
 - Add contrast
 - Add saturation
- Filtering
 - Blur
 - Detect edges
- Warping
 - Scale
 - Rotate
 - Warps
- Combining
 - Morphs
 - Composite

Image Processing



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 - Composite

Adjusting Brightness



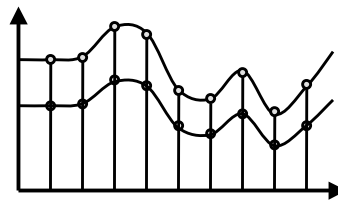
- Simply scale pixel components
 - Must clamp to range (e.g., 0 to 255)



Original



Brighter



Adjusting Contrast



- Compute mean luminance \bar{L} for all pixels
 - luminance = $0.30*r + 0.59*g + 0.11*b$
- Scale deviation from \bar{L} for each pixel component
 - Must clamp to range (e.g., 0 to 255)



Original



More Contrast

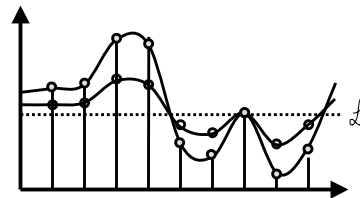


Image Processing



- Quantization
 - Uniform Quantization
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Adjust Blurriness



- Convolve with a filter whose entries sum to one
 - Each pixel becomes a weighted average of its neighbors



Original



Blur

$$\text{Filter} = \begin{bmatrix} 1/16 & 2/16 & 1/16 \\ 2/16 & 4/16 & 2/16 \\ 1/16 & 2/16 & 1/16 \end{bmatrix}$$

Edge Detection



- Convolve with a filter that finds differences between neighbor pixels



Original



Detect edges

$$\text{Filter} = \begin{bmatrix} -1 & -1 & -1 \\ -1 & +8 & -1 \\ -1 & -1 & -1 \end{bmatrix}$$

Image Processing



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Scaling



- Resample with triangle or Gaussian filter

More on this next lecture!



Original



1/4X
resolution



4X
resolution

Summary



- Image processing is a resampling problem
 - Avoid aliasing
 - Use filtering

