Project 1: Bootloader
COS 318
Fall 2014
Project 1 Schedule

- Design Review
  - Tuesday, Sep 23
  - 10-min time slots from 9:30am-2:20pm
- Due date: Sunday, 9/28, 11:59pm
General Suggestions

- Read `assembly_example.s` in start code pkg
- Get `bootblock.s` working before starting on `createimage.c`
- Read documentation on AT&T syntax x86 Assembly language
- Read provided documentation on ELF format
- Start as early as you can, and get as much done as possible by the design review
Project 1 Overview

- Write a bootloader: **bootblock.s**
  - How to set up and start running the OS
  - Written in x86 Assembly language (AT&T syntax)

- Implement a tool to create a bootable OS image: **createimage.c**
  - Bootable image contains bootloader and kernel
  - How are executable files structured?
  - Become familiar with ELF format
Boot Process

- When powered up, nothing in RAM, so how do we get started?
  - Resort to hardware
  - Load BIOS from ROM
- BIOS:
  - Minimal functionality
  - Initialization of I/O devices
  - Search for bootable devices
Loading the Bootloader

• Found bootable storage volume:
  – HDD, USB, Floppy
  – Load bootloader

• How is this done?
  – Load first sector (512 bytes)
  – Memory location: 0x7c00
  – Switch control to this location to launch the bootloader
The Bootloader

- Load the kernel into memory
- Setup the kernel stack
- Switch control to the kernel
Let's Review Assembly

- About numbers, need good bookkeeping
- Move data, perform simple arithmetic
- Need a lot of steps to do useful things

**KEY:**
- Understand memory addresses
- Know where things are in memory
Memory Addressing

- 1MB of memory
  - Valid address range: 0x00000 - 0xFFFFF

- Real mode segmented model:
  - See full 1MB with 20-bit addresses
  - 16-bit segments and 16-bit offsets

- Addressing format: segment:offset
  - Actual address = 16*segment + offset
  - How would you write the address for the bootloader?
Registers

- 5 types of CPU registers:
  - General purpose: ax, bx, cx, dx (can address high or low-order byte via ah/al etc.)
  - Segment: cs, ds, es, ss
  - Pointer: ip, bp, sp
  - Index: di, si
  - Flags: df, zf (only 9 bits used)

- 32-bit registers have e prefix: e.g. eax
AT&T Syntax

- Prefix register names with % (e.g. %ax)
- Instruction format: instr src, dest
  - e.g. movw %ax, %bx
- Prefix constants, immediate values with $
  - e.g. movw $0x01, %ax
- Suffix instructions with size of data
  - b for byte, w for word (16 bits), l for long (32 bits)
  - Keep the size of your registers in mind!
Important Instructions

- **mov x, y**: moves data into a register
  - e.g. movw %ax, %ds

- **Jumps:**
  - **jmp imm**: %ip ← imm
    - e.g. jmp $print_char
  - **ljmp imm1, imm2**: %cs ← imm1, %ip ← imm2
    - e.g. ljmp $0x7c0:0x00, $0x00
Important Instructions

• Stack ops:
  - **push x**: %sp--, Mem[%ss:%sp] ← x
  - **pop x**: x ← Mem[%ss:%sp], %sp++

• Function calls:
  - **call <label>**: push %ip, jmp <label>
  - **ret**: pop %ip
  - Be careful not to override register values!
Important Instructions

- **Interrupts:**
  - `int imm`: invoke a software interrupt
    - `int 0x10` (console output)
    - `int 0x13` (disk I/O)
    - `int 0x16` (keyboard input)
  - Each interrupt offers several functions and parameters
    - Function indicated in `%ah`
    - Params in other regs
Read from Disk to Memory

• BIOS int 0x13, function 2:
  - Read disk sectors into memory
  - Parameters:
    • %ah = $0x02 (disk read function)
    • %al = # of sectors to read
    • %ch = cylinder number
    • %cl = sector number
    • %dh = head number
    • %dl = drive number (already set)
    • %es:%bx address into which we want to read the data
  - Finally call the interrupt: int $0x13
  - Refer to http://en.wikipedia.org/wiki/Cylinder-head-sector for more info
Assembly Program Structure

- Assembler directives:
  - Not instructions
  - Segment the program
- .text begins code segment
- .globl defines a list of symbols as global
- .data begins data segment
- .equ defines a constant (like #define)
  - e.g. .equ ZERO, $0x00
- .byte, .word, .asciz reserve space in memory
ELF Format

- Executable and linking format
- Created by assembler and link editor
- Object file: binary representation of programs intended to execute directly on a processor
- Support various processors/architectures:
  - Represent some control data in a machine-independent format
ELF Object File format

• Header (p. 9/10):
  - Beginning of file
  - Roadmap, file organization

• Program header table (p.33):
  - Array, each element describes a segment
  - Tells system how to create the process image
  - Files used to create an executable program must have a Phdr

Execution View

<table>
<thead>
<tr>
<th>ELF header</th>
</tr>
</thead>
<tbody>
<tr>
<td>Program header table</td>
</tr>
<tr>
<td>Segment 1</td>
</tr>
<tr>
<td>Segment 2</td>
</tr>
<tr>
<td>...</td>
</tr>
<tr>
<td>Section header table</td>
</tr>
<tr>
<td>optional</td>
</tr>
</tbody>
</table>

p. 7 in ELF manual
Warm-up Exercise

- Executable and linking format
- Created by assembler and link editor
- Object file: binary representation of programs intended to execute directly on a processor
- Support various processors/architectures:
  - Represent some control data in a machine-independent format