

# Lecture 3: Model checking

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Model Checking Problem: given a Kripke structure  $K$  and an LTL formula  $\varphi$ , do we have  $K \models \varphi$ ?

Model Checking, as an algorithmic discipline: exhaustively explore all possible behaviours of the system, searching for a violation. Many tools for doing this efficiently (SPIN, nuSMV).

## 1 Automata over infinite words

Fix a set of propositions  $P$ .

- For any Kripke structure  $K$ , define  $\mathcal{L}(K) = \{L(\pi) : \pi \in \text{Path}(K)\}$
- For any LTL formula  $\varphi$ , define  $\mathcal{L}(\varphi) \triangleq \{\pi \in (2^P)^\omega : \pi \models \varphi\}$  to be the set of paths that satisfy  $\varphi$ .

Idea:  $K \models \varphi$  exactly when  $\mathcal{L}(K) \subseteq \mathcal{L}(\varphi)$ .

If  $K$  is finite, then the model checking problem is decidable by reduction to inclusion testing for Büchi automata: there is a Büchi automaton that recognizes both  $\mathcal{L}(K)$  and  $\mathcal{L}(\varphi)$ , and inclusion checking is decidable.

**Definition 1.1** (Büchi automaton). *A (non-deterministic) Büchi automaton  $A = \langle Q, \Sigma, \Delta, I, F \rangle$  where*

- $Q$  is a finite set of states
- $\Sigma$  is a finite alphabet
- $\Delta \subseteq Q \times \Sigma \times Q$  is a transition relation

- $I \subseteq Q$  is a set of initial states
- $F \subseteq Q$  is a set of final states

A word  $w = w_0w_1w_2\dots \in \Sigma^\omega$  is accepted by a Büchi automaton  $A = \langle Q, \Sigma, \Delta, I, F \rangle$  if there exists an *accepting run*  $q_0q_1q_2\dots$  consisting of an infinite sequence of states such that:

- $q_0 \in Q$  is initial
- for each  $i$ ,  $\langle q_i, w_i, q_{i+1} \rangle \in \Delta$
- The set  $\{i : q_i \in F\}$  is infinite

**Proposition 1.2.** *Let  $K$  be a Kripke structure. There is a Büchi automaton  $A(K)$  such that  $\mathcal{L}(A(K)) = \mathcal{L}(K)$ .*

*Proof.* Let  $K = \langle K_S, K_I, K_R, K_L \rangle$  be a Kripke structure over a set of propositions  $P$  (for simplicity, suppose  $K_R$  is total). Define  $A(K) = \{A_K, A_\Sigma, A_\Delta, A_I, A_F\}$  where

- $A_Q = K_S$
- $A_\Sigma = 2^P$
- $A_\Delta = \{\langle s, K_L(s), t \rangle : s K_R t\}$
- $A_I = K_I$
- $A_F = K_S$

□

**Proposition 1.3.** *For any Büchi automata  $A$  and  $B$ , there is an automaton that recognizes  $\mathcal{L}(A) \cap \mathcal{L}(B)$ .*

*Proof.* Construct as follows:

- $Q = A_Q \times B_Q \times \{A, B\}$
- $\Sigma = A_\Sigma$
- The transition relation  $\Delta$  is defined to be the set of all  $\langle (a, b, c), \sigma, (a', b', c) \rangle$  such that:

- $\langle a, \sigma, a' \rangle \in \Delta_A,$
- $\langle b, \sigma, b' \rangle \in \Delta_B,$
- $c = A, a \in A_F$  implies  $c' = B$
- $c = B, b \in B_F$  implies  $c' = A$
- $c = A \wedge a \notin A_F$  or  $c = B \wedge b \notin B_F$  implies  $c' = c.$
- $A_I = \{(a, b, A) : a \in A_I, b \in B_I\}$
- $A_F = \{(a, b, B) : b \in F\}$

□

**Proposition 1.4.** *For any Büchi automaton  $A$ , there is an automaton that recognizes  $\overline{\mathcal{L}A}$*

- However, this is complicated and can be avoided: rather than checking  $\mathcal{L}(A(K)) \cap \overline{\mathcal{L}(A(\varphi))} = \emptyset$ , we check  $\mathcal{L}(A(K)) \cap \mathcal{L}(A(\neg\varphi)) = \emptyset$ .

## 2 LTL tableaux

Automata are *local* in the sense that they make decisions based on the next letter of the sequence. Let's localize LTL semantics so that satisfaction  $\pi \models \varphi$  is expressed only in terms of  $\pi$ ,  $\pi_0$ , and  $\pi[1\dots]$ . Most are already local:

$$\begin{aligned} \pi \models p &\iff \pi_0 \models p \\ \pi \models \varphi \vee \psi &\iff \pi \models \varphi \vee \pi \models \psi \\ \pi \models \neg\varphi &\iff \pi \not\models \varphi \\ \pi \models \mathbf{X}\varphi &\iff \pi[1\dots] \models \varphi \end{aligned}$$

The one that is not is  $\varphi \mathbf{U} \psi$ . However, we can take

$$\pi \models \varphi \mathbf{U} \psi \iff \pi \models \psi \text{ or } \pi \models (\varphi \wedge (\varphi \mathbf{U} \psi))$$

Thus, the evaluation of an LTL formula can be expressed in terms of its

sub-formulas:

$$\begin{aligned}
sub(p) &= \{p\} \\
sub(\varphi_1 \vee \varphi_2) &= \{\varphi_1 \vee \varphi_2\} \cup sub(\varphi_1) \cup sub(\varphi_2) \\
sub(\neg\varphi) &= \{\neg\varphi\} \cup sub(\varphi) \\
sub(\mathbf{X}\varphi) &= \{\mathbf{X}\varphi\} \cup sub(\varphi) \\
sub(\varphi \mathbf{U} \psi) &= \{\varphi \mathbf{U} \psi, \mathbf{X}(\varphi \mathbf{U} \psi)\} \cup sub(\varphi) \cup sub(\psi)
\end{aligned}$$

Note:  $|sub(\varphi)| \leq 2|\varphi|$ .

**Definition 2.1.** A set  $\Phi \subseteq sub(\varphi)$  is consistent if:

- for all  $\varphi_1 \vee \varphi_2 \in sub(\varphi)$ ,  $\varphi_1 \vee \varphi_2 \in \Phi \iff \varphi_1 \in sub(\varphi)$  or  $\varphi_2 \in \Phi$
- for all  $\neg\psi \in sub(\varphi)$ ,  $\neg\psi \in \Phi \iff \psi \notin \Phi$
- for all  $\psi_1 \mathbf{U} \psi_2 \in sub(\varphi)$ ,  $\psi_1 \mathbf{U} \psi_2 \in \Phi \iff \psi_2 \in \Phi$  or both  $\psi_1 \in \Phi$  and  $\mathbf{X}(\psi_1 \mathbf{U} \psi_2) \in \Phi$ .

**Definition 2.2** (Generalized Büchi automaton). A Generalized Büchi automaton (GBA) is a Büchi automaton equipped with a set  $\mathcal{F}$  of sets of final states. A word is accepted by a GBA if there is an accepting run such that each  $F \in \mathcal{F}$  is visited infinitely often.

**Proposition 2.3.** For any generalized Büchi automaton  $A$ , there is a Büchi automaton that accepts the same language.

*Proof.* The construction is similar to the one for intersection. Let  $A = \langle A_Q, A_\Sigma, A_\Delta, A_I, A_{\mathcal{F}} \rangle$  be a GBA. Write  $A_{\mathcal{F}}$  as  $A_{\mathcal{F}} = \{F_0, \dots, F_n\}$

- $Q = A_Q \times \{0, \dots, n\}$
- $\Sigma = A_\Sigma$
- $\Delta = \{ \langle (a, i), \sigma, (a', i') \rangle : \langle a, \sigma, a' \rangle \in \Delta_A, i' = i + 1_{a \in F_i} \pmod{n+1} \}$   
where  $1_{a \in F_i} = \begin{cases} 1 & \text{if } a \in F_i \\ 0 & \text{otherwise} \end{cases}$
- $A_I = \{(a, 0) : a \in A_I\}$
- $A_{\mathcal{F}} = \{(a, n) : a \in F_n\}$

□

**Definition 2.4** (LTL tableau). *Let  $\varphi$  be an LTL formula. Its tableau is a generalized Büchi automaton  $A(\varphi) = \langle Q, \Sigma, \Delta, I, \mathcal{F} \rangle$  where*

- $Q = \{\Phi \in 2^{\text{sub}(\varphi)} : \Phi \text{ is consistent}\}$
- $\Sigma = 2^P$
- $\Delta = \{\langle \Phi, \sigma, \Psi \rangle : \forall \mathbf{X}\varphi \in \text{sub}(\varphi), \mathbf{X}\varphi \in \Phi \iff \varphi \in \Psi, \sigma = P \cap \Phi\}$
- $I = \{\Phi \in Q : \varphi \in I\}$
- For each  $\varphi \mathbf{U} \psi \in \text{sub}(\varphi)$ , define  $F_{\varphi \mathbf{U} \psi} \triangleq \{\Phi \in Q : \varphi \mathbf{U} \psi \notin \Phi \vee \psi \in \Phi\}$ . Define  $\mathcal{F} = \{F_{\varphi \mathbf{U} \psi} : \varphi \mathbf{U} \psi \in \text{sub}(\varphi)\}$ .

**Theorem 2.5.**  $\mathcal{L}(\varphi) = \mathcal{L}(A(\varphi))$ .

*Proof.* For any path  $\pi$ , define  $\text{sat}_\varphi(\pi) \triangleq \{\psi \in \text{sub}(\varphi) : \pi \models \psi\}$ . Clearly,  $\text{sat}_\varphi(\pi)$  is consistent for any  $\pi$ .

“ $\mathcal{L}(\varphi) \subseteq \mathcal{L}(A(\varphi))$ ”. Prove that for any  $\pi \in \mathcal{L}(\varphi)$  we have  $\pi \in \mathcal{L}(A(\varphi))$ . We want to show that

$$\text{sat}_\varphi(\pi) \text{sat}_\varphi(\pi[1\dots]) \text{sat}_\varphi(\pi[2\dots])$$

is an accepting run. To show that this is a run of  $A(\varphi)$ , we must show that for any  $\pi$ ,  $\langle \text{sat}_\varphi(\pi), \pi_0, \text{sat}_\varphi(\pi[1\dots]) \rangle \in \Delta$ . This follows directly from the definitions. To show that this is an *accepting* run, we must show that it meets each  $F_{\psi_1 \mathbf{U} \psi_2}$  infinitely often. It must be the case that either

- $\psi_1 \mathbf{U} \psi_2$  is satisfied infinitely often, and so  $\psi_2$  must also be satisfied infinitely often (and so  $\text{sat}_\varphi(\pi[i\dots])$  contains  $\psi_2$  infinitely often), or
- $\psi_1 \mathbf{U} \psi_2$  is not satisfied infinitely often (and so  $\text{sat}_\varphi(\pi[i\dots])$  doesn't contain  $\psi_1 \mathbf{U} \psi_2$  infinitely often).

“ $\mathcal{L}(A(\varphi)) \subseteq \mathcal{L}(\varphi)$ ” We prove that for all  $\psi \in \text{sub}(\varphi)$ , for all consistent  $\Phi$  and all  $\pi \in \mathcal{L}(\Phi)$ ,  $\psi \in \Phi \iff \pi \models \psi$ . Since the accepting states of  $A(\varphi)$  all contain  $\varphi$  this implies that  $\mathcal{L}(A(\varphi)) \subseteq \mathcal{L}(\varphi)$ . We prove the result by induction on  $\psi$ . Let  $\Phi$  be a consistent set and let  $\pi \in \mathcal{L}(\Phi)$ .

- Case  $p \in P$ :  $\pi \in \mathcal{L}(\Phi)$  implies that  $\pi_0 = P \cap \Phi$  (by def'n of  $\Delta$ ).  $\pi \models p \iff \pi_0 \models p \iff p \in \Phi$ .
- Case  $\psi_1 \vee \psi_2$ : By consistency,  $\psi_1 \vee \psi_2 \in \Phi \iff \psi_1 \in \Phi \vee \psi_2 \in \Phi$ . By the induction hypothesis,  $\psi_1 \in \Phi \iff \pi \models \psi_1$  and  $\psi_2 \in \Phi \iff \pi \models \psi_2$ , so  $\psi_1 \vee \psi_2 \in \Phi \iff \pi \models \psi_1 \vee \pi \models \psi_2 \iff \pi \models \psi_1 \vee \psi_2$ .

- Case  $\neg\psi$ : By consistency,  $\neg\psi \in \Phi \iff \psi \notin \varphi$ . By induction hypothesis,  $\psi \notin \Phi \iff \pi \not\models \varphi$ . So  $\neg\psi \in \Phi \iff \pi \notin \varphi \iff \pi \models \varphi$ .
- Case  $\mathbf{X}\psi$ : Since  $\pi \in \mathcal{L}(\Phi)$ , there is some  $\Phi'$  such that  $\pi[1\dots] \in \mathcal{L}(\Phi')$  and  $\langle \Phi, \pi_0, \Phi' \rangle \in \Delta$ . By def'n,  $\mathbf{X}\psi \in \Phi \iff \psi \in \Phi'$ . By the induction hypothesis,  $\pi[1\dots] \in \mathcal{L}(\Phi')$  entails that  $\varphi \in \Phi' \iff \pi[1\dots] \models \psi$ . So  $\mathbf{X}\psi \in \Phi \iff \pi \models \mathbf{X}\psi$ .
- Case  $\psi_1 \mathbf{U} \psi_2$ : Let  $\Phi_0\Phi_1\dots$  be an accepting run for  $\pi$ .
  - $\pi \models \psi_1 \mathbf{U} \psi_2$ : There exists some *least*  $i$  such that  $\pi[j\dots] \models \psi_2$  and  $\pi[i\dots] \models \psi_1$  for all  $j < i$ . By the induction hypothesis,  $\psi_2 \in \Phi_i$  and  $\psi_1 \in \Phi_j$  for all  $j < i$ . We may prove by induction that  $\psi_1 \mathbf{U} \psi_2 \in \Phi_j$  for all  $j \leq i$ , so  $\psi_1 \mathbf{U} \psi_2 \in \Phi$ .
  - $\pi \not\models \psi_1 \mathbf{U} \psi_2$ :
    - \* Case  $\pi[i\dots] \models \psi_1$  for all  $i$ , and  $\pi[i\dots] \not\models \psi_2$  for all  $i$ . By IH,  $\psi_1 \in \Phi_i$  for all  $i$  and  $\psi_2 \notin \Phi_i$  for all  $i$ . For a contradiction, suppose that  $\psi_1 \mathbf{U} \psi_2 \in \Phi$ . Prove by induction that  $\psi_1 \mathbf{U} \psi_2 \in \Phi_i$  for all  $i$ . This contradicts the fact that infinitely many  $\Phi_i$  must be in  $F_{\psi_1 \mathbf{U} \psi_2}$ .
    - \* Case there exists some *least*  $i$  such that  $\pi[i\dots] \not\models \psi_1$ ,  $\pi[i\dots] \not\models \psi_2$ , and  $\pi[j\dots] \models \psi_1$  for all  $j < i$ . By the induction hypothesis,  $\psi_1 \in \Phi_j$  for all  $j < i$ , and  $\psi_1, \psi_2 \notin \Phi_j$ . Prove by induction that for all  $j \leq i$ ,  $\psi_1 \mathbf{U} \psi_2 \notin \Phi_j$ .

□