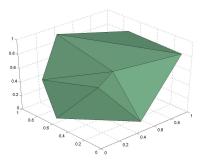
Introduction to LP and SDP Hierarchies



Madhur Tulsiani Princeton University

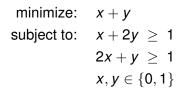
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Toy Problem

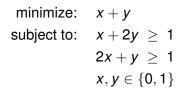
 $\begin{array}{lll} \mbox{minimize:} & x+y\\ \mbox{subject to:} & x+2y \ \geq \ 1\\ & 2x+y \ \geq \ 1\\ & x,y \in \{0,1\} \end{array}$

Toy Problem



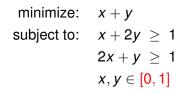


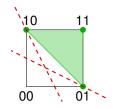
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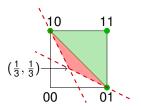
Toy Problem





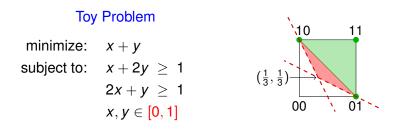
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minimize: x + ysubject to: $x + 2y \ge 1$ $2x + y \ge 1$ $x, y \in [0, 1]$

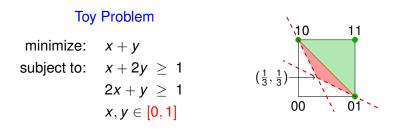


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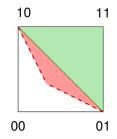


- Large number of approximation algorithms derived precisely as above.
- Analysis consists of understanding extra solutions introduced by the relaxation.



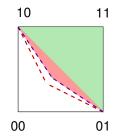
- Large number of approximation algorithms derived precisely as above.
- Analysis consists of understanding extra solutions introduced by the relaxation.
- Integrality Gap = $\frac{\text{Combinatorial Optimum}}{\text{Optimum of Relaxation}} = \frac{1}{2/3} = \frac{3}{2}$

- Would like to make our relaxations less relaxed.
- Various hierarchies give increasingly powerful programs at different levels (rounds), starting from a basic relaxation.

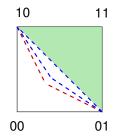


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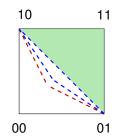
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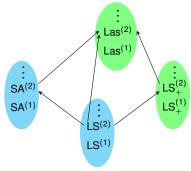
- Would like to make our relaxations less relaxed.
- Various hierarchies give increasingly powerful programs at different levels (rounds), starting from a basic relaxation.
- Powerful computational model capturing most known LP/SDP algorithms within constant number of levels.
- Does approximation get better a higher levels?



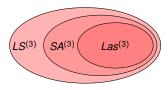
• Various hierarchies studied in the Operations Research literature:

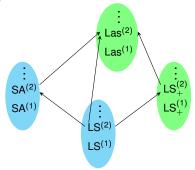
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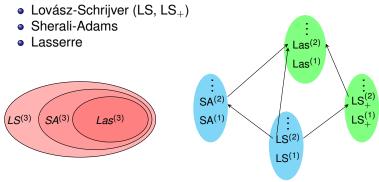


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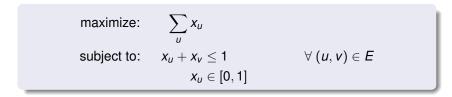
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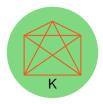


• Can optimize over r^{th} level in time $n^{O(r)}$. n^{th} level is tight.

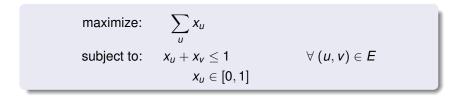
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Example: Souping up the Independent Set relaxation





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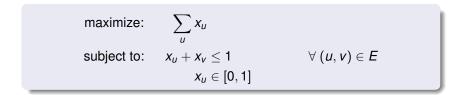


 $\sum_{u\in K} x_u \leq 1$



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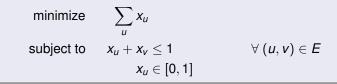






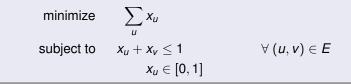
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- Implied by one level of LS₊ hierarchy.
- Polytime algorithm for Independent Set on perfect graphs [GLS 81].

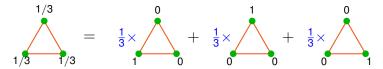


• Hope: x_1, \ldots, x_n is convex combination of 0/1 solutions.

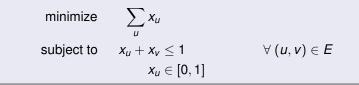
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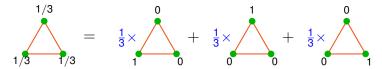
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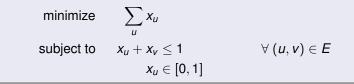


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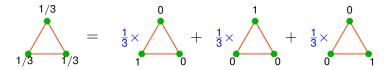


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Hierarchies add variables for conditional/joint probabilities.

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- Start with a 0/1 integer linear program.
- Hope: Fractional $(x_1, \ldots, x_n) = \mathbb{E}[(z_1, \ldots, z_n)]$ for integral (z_1, \ldots, z_n)

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- Constraints:

$$\sum_{i} a_{i} z_{i} \leq b$$

$$\mathbb{E}\left[\left(\sum_{i} a_{i} z_{i}\right) \cdot z_{5} z_{7}(1-z_{9})\right] \leq \mathbb{E}\left[b \cdot z_{5} z_{7}(1-z_{9})\right]$$

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$$\sum_{i} a_{i} \cdot (X_{\{i,5,7\}} - X_{\{i,5,7,9\}}) \leq b \cdot (X_{\{5,7\}} - X_{\{5,7,9\}})$$

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LP on n^r variables.

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• Using $0 \le z_1 \le 1, 0 \le z_2 \le 1$

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- $D(\{1,2,3\})$ and $D(\{1,2,4\})$ must agree with $D(\{1,2\})$.
- $SA^{(r)} \implies LCD^{(r)}$. If each constraint has at most k vars, $LCD^{(r+k)} \implies SA^{(r)}$

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The Lasserre Hierarchy

• Start with a 0/1 integer quadratic program.

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- Associated psd matrix Y (moment matrix)

$$Y_{S_1,S_2} = \mathbb{E}\left[Z_{S_1} \cdot Z_{S_2}\right] = \mathbb{E}\left[\prod_{i \in S_1 \cup S_2} Z_i\right]$$

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• $(Y \succeq 0)$ + original constraints + consistency constraints.

The Lasserre hierarchy (constraints)

• Y is psd. (i.e. find vectors \mathbf{U}_S satisfying $Y_{S_1,S_2} = \langle \mathbf{U}_{S_1}, \mathbf{U}_{S_2} \rangle$)

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- Original quadratic constraints as inner products.

SDP for Independent Set		
maximize	$\sum_{i \in V} \left \mathbf{U}_{\{i\}} \right ^2$	
subject to		$orall (i,j) \in E$ $orall S_1 \cup S_2 = S_3 \cup S_4$
	$\langle \mathbf{U}_{\mathcal{S}_1}, \mathbf{U}_{\mathcal{S}_2} \rangle \in [0, 1]$	$\forall S_1, S_2$

The "Mixed" hierarchy

 Motivated by [Raghavendra 08]. Used by [CS 08] for Hypergraph Independent Set.

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Captures what we actually know how to use about Lasserre solutions.

The "Mixed" hierarchy

- Motivated by [Raghavendra 08]. Used by [CS 08] for Hypergraph Independent Set.
- Captures what we actually know how to use about Lasserre solutions.
- Level r has
 - Variables X_S for $|S| \le r$ and all Sherali-Adams constraints.
 - Vectors **U**₀, **U**₁, ..., **U**_n satisfying

 $\langle \mathbf{U}_i, \mathbf{U}_j \rangle = X_{\{i,j\}}, \langle \mathbf{U}_0, \mathbf{U}_i \rangle = X_{\{i\}} \text{ and } |\mathbf{U}_0| = 1.$

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Hands-on: Deriving some constraints

•
$$|\mathbf{U}_i - \mathbf{U}_j|^2 + |\mathbf{U}_j - \mathbf{U}_k|^2 \ge |\mathbf{U}_i - \mathbf{U}_k|^2$$
 is equivalent to
 $\langle \mathbf{U}_i - \mathbf{U}_j, \mathbf{U}_k - \mathbf{U}_j \rangle \ge 0$

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• $Mix^{(3)} \implies \exists$ distribution on z_i, z_j, z_k such that $\mathbb{E}[z_i \cdot z_j] = \langle \mathbf{U}_i, \mathbf{U}_j \rangle$ (and so on).

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- For all integer solutions $(z_i z_j) \cdot (z_k z_j) \ge 0$.

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- For all integer solutions $(z_i z_j) \cdot (z_k z_j) \ge 0$.

$$\therefore \langle \mathbf{U}_i - \mathbf{U}_j, \mathbf{U}_k - \mathbf{U}_j \rangle = \mathbb{E} \left[(z_i - z_j) \cdot (z_k - z_j) \right] \geq 0$$

"Clique constraints" for Independent Set

• For every clique K in a graph, adding the constraint

$$\sum_{i\in K} x_i \leq 1$$

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makes the independent set LP tight for perfect graphs.

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"Clique constraints" for Independent Set

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makes the independent set LP tight for perfect graphs.

- Too many constraints, but all implied by one level of the mixed hierarchy.
- For $i, j \in K$, $\langle \mathbf{U}_i, \mathbf{U}_j \rangle = 0$. Also, $\forall i \langle \mathbf{U}_0, \mathbf{U}_i \rangle = |\mathbf{U}_i|^2 = x_i$. By Pythagoras, $\sum_{i \in K} \left\langle \mathbf{U}_0, \frac{\mathbf{U}_i}{|\mathbf{U}_i|} \right\rangle^2 \le |\mathbf{U}_0|^2 = 1 \implies \sum_{i \in B} \frac{x_i^2}{x_i} \le 1.$

Derived by Lovász using the θ-function.

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• Restriction: $\mathbf{x} = (x_1, \dots, x_n) \in LS(P)$ if $\exists Y$ satisfying (think $Y_{ij} = \mathbb{E}[z_i z_j] = \mathbb{P}[z_i \land z_j]$)

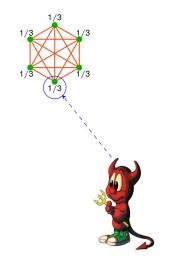
•
$$Y = Y^T$$

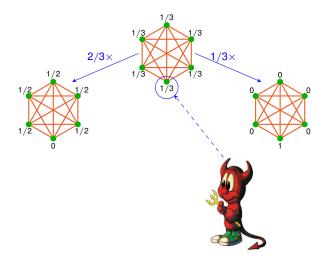
• $Y_{ii} = x_i$ $\forall i$
• $\frac{Y_i}{x_i} \in P, \ \frac{\mathbf{x} - Y_i}{1 - x_i} \in P$ $\forall i$
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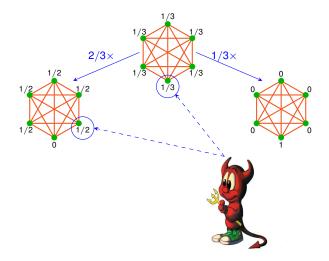
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- Above is an LP (SDP) in $n^2 + n$ variables.





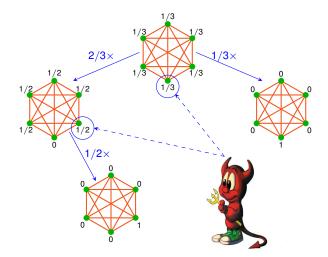


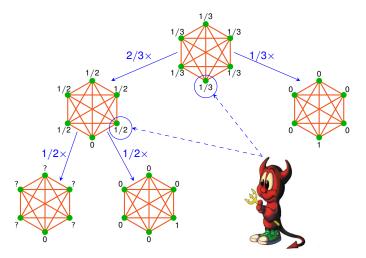
• *r*th level optimizes over distributions conditioned on *r* variables.



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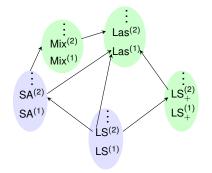
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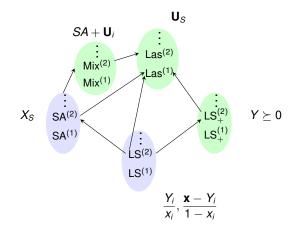
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Algorithmic Applications

- Many known LP/SDP relaxations captured by 2-3 levels.
- [Chlamtac 07]: Explicitly used level-3 Lasserre SDP for graph coloring.
- [CS 08]: Algorithms using Mixed and Lasserre hierarchies for hypergraph independent set (guarantee improves with more levels).
- [KKMN 10]: Hierarchies yield a PTAS for Knapsack.
- [BRS 11, GS 11]: Algorithms for Unique Games using n^ε levels of Lassere.

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Lower bound techniques

• Expansion in CSP instances (Proof Complexity)

Lower bound techniques

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Reductions

Lower bound techniques

- Expansion in CSP instances (Proof Complexity)
- Reductions
- [ABLT 06, STT 07, dIVKM 07, CMM 09]: Distributions from local probabilistic processes.
- [Charikar 02, GMPT 07, BCGM 10]: Polynomial tensoring.

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[RS 09, KS 09]: Higher level distributions from level-1 vectors.

Integrality Gaps for Expanding CSPs

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 MAX k-CSP: *m* constraints on *k*-tuples of (*n*) boolean variables. Satisfy maximum. e.g. MAX 3-XOR (linear equations mod 2)

$$z_1 + z_2 + z_3 = 0$$
 $z_3 + z_4 + z_5 = 1$...

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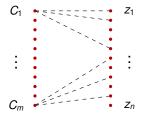
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Expansion: Every set S of constraints involves at least β|S| variables (for |S| < αm).

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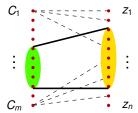


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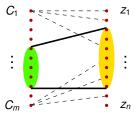


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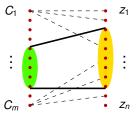
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• Used extensively in proof complexity e.g. [BW01], [BGHMP03]. For LS $_+$ by [AAT04].

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Variables: $X_{(S,\alpha)}$ for $|S| \le t$, partial assignments $\alpha \in \{0,1\}^S$

$$\begin{array}{lll} \text{maximize} & \sum_{i=1}^{m} \sum_{\alpha \in \{0,1\}^{T_i}} C_i(\alpha) \cdot X_{(T_i,\alpha)} \\ \text{subject to} & X_{(S \cup \{i\}, \alpha \circ 0)} + X_{(S \cup \{i\}, \alpha \circ 1)} = X_{(S,\alpha)} & \forall i \notin S \\ & X_{(S,\alpha)} \geq 0 \\ & X_{(\emptyset,\emptyset)} = 1 \end{array}$$

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• $X_{(S,\alpha)} \sim \mathbb{P}[\text{Vars in } S \text{ assigned according to } \alpha]$

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- Need distributions D(S) such that $D(S_1)$, $D(S_2)$ agree on $S_1 \cap S_2$.

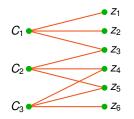
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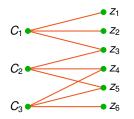
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- Distributions should "locally look like" supported on satisfying assignments.

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- \bullet Take $\gamma=0.9$
- Can show any three 3-XOR constraints are simultaneously satisfiable.

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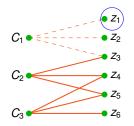


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 $\mathbb{E}_{z_1...z_6}\left[C_1(z_1, z_2, z_3) \cdot C_2(z_3, z_4, z_5) \cdot C_3(z_4, z_5, z_6)\right]$

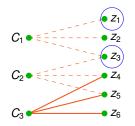


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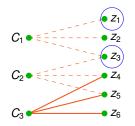
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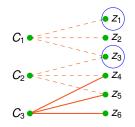
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$$= 1/8$$



• Take $\gamma=$ 0.9

- Can show any three 3-XOR constraints are simultaneously satisfiable.
- Can take $\gamma \approx (k 2)$ and any αn constraints.
- Just require $\mathbb{E}[C(z_1, \ldots, z_k)]$ over any k 2 vars to be constant.

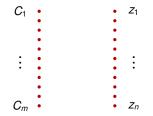
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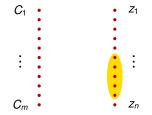
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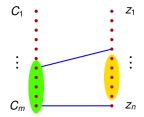
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• Want to define distribution D(S) for set S of variables.



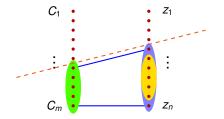
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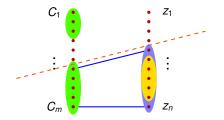
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- Find set of constraints C such that G C S remains expanding.
 D(S) = uniform over assignments satisfying C

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- Want to define distribution D(S) for set S of variables.
- Find set of constraints C such that G C S remains expanding.
 D(S) = uniform over assignments satisfying C
- Remaining constraints "independent" of this assignment.
- Gives optimal integrality gaps for $\Omega(n)$ levels in the mixed hierarchy.

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Vectors for Linear CSPs

• Start with a $\{-1, 1\}$ quadratic integer program. $(z_1, \ldots, z_n) \rightarrow ((-1)^{z_1}, \ldots, (-1)^{z_n})$

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Consider the psd matrix Y

$$\tilde{Y}_{S_1,S_2} = \mathbb{E}\left[\tilde{Z}_{S_1}\cdot \tilde{Z}_{S_2}\right] = \mathbb{E}\left[\prod_{i\in S_1\Delta S_2} (-1)^{z_i}\right]$$

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SDP for MAX 3-XOR

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SDP for MAX 3-XOR

$$\begin{array}{ll} \text{maximize} & \sum_{C_i \equiv (z_{i_1} + z_{i_2} + z_{i_3} = b_i)} \frac{1 + (-1)^{b_i} \left\langle \mathbf{W}_{\{i_1, i_2, i_3\}}, \mathbf{W}_{\emptyset} \right\rangle}{2} \\ \text{subject to} & \left\langle \mathbf{W}_{S_1}, \mathbf{W}_{S_2} \right\rangle = \left\langle \mathbf{W}_{S_3}, \mathbf{W}_{S_4} \right\rangle & \forall S_1 \Delta S_2 = S_3 \Delta S_4 \\ & |\mathbf{W}_S| = 1 & \forall S, \ |S| \leq r \\ \end{array}$$

 [Schoenebeck'08]: If width 2r resolution does not derive contradiction, then SDP value =1 after r levels of Lasserre.

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SDP for MAX 3-XOR

- [Schoenebeck'08]: If width 2r resolution does not derive contradiction, then SDP value =1 after r levels of Lasserre.
- Expansion guarantees there are no width 2*r* contradictions.

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• Used by [FO 06], [STT 07] for LS₊ hierarchy.

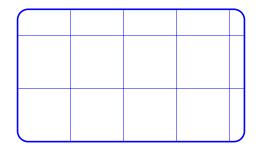
•
$$z_1 + z_2 + z_3 = 1 \mod 2 \implies (-1)^{z_1 + z_2} = -(-1)^{z_3}$$

 $\implies \mathbf{W}_{\{1,2\}} = -\mathbf{W}_{\{3\}}$

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Equations of width 2*r* divide |S| ≤ *r* into equivalence classes. Choose orthogonal e_C for each class C.

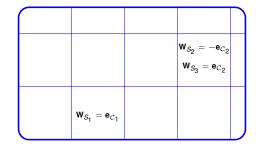


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- No contradictions ensure each $S \in C$ can be uniquely assigned $\pm \mathbf{e}_{C}$.

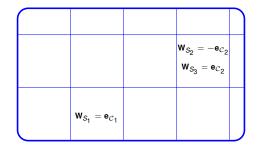


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- Equations of width 2*r* divide |S| ≤ *r* into equivalence classes. Choose orthogonal e_C for each class C.
- No contradictions ensure each $S \in C$ can be uniquely assigned $\pm \mathbf{e}_{C}$.
- Relies heavily on constraints being linear equations.



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Reductions

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 If problem A reduces to B, can we say Integrality Gap for A ⇒ Integrality Gap for B?

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- Reduction from integer program A to integer program B. Each variable z'_i of B is a boolean function of few (say 5) variables z_i, ..., z_i of A.

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- To show: If A has good vector solution, so does B.
- Question posed in [AAT 04]. First done by [KV 05] from Unique Games to Sparsest Cut.

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 FGLSS: Reduction from MAX k-CSP to Independent Set in graph G_φ.



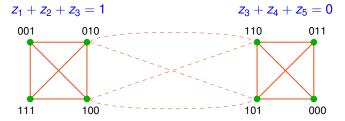
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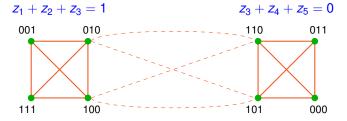
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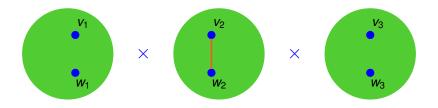
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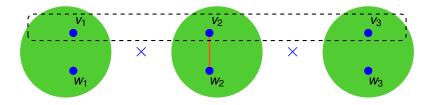
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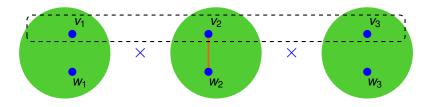
- Need vectors for subsets of vertices in the G_Φ.
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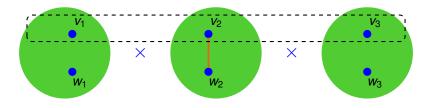


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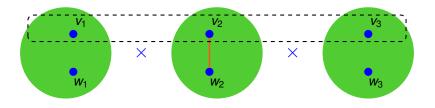
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$$\overline{U}_{\{(v_1, v_2, v_3)\}} = ?$$





• $\overline{\mathbf{U}}_{\{(\mathbf{v}_1,\mathbf{v}_2,\mathbf{v}_3)\}} = \mathbf{U}_{\{\mathbf{v}_1\}} \otimes \mathbf{U}_{\{\mathbf{v}_2\}} \otimes \mathbf{U}_{\{\mathbf{v}_3\}}$

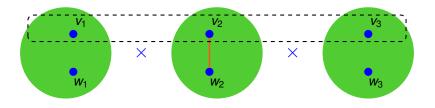




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• Similar transformation for sets (project to each copy of *G*).

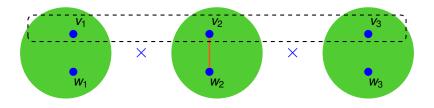
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• Together give a gap of $\frac{n}{2^{O(\sqrt{\log n \log \log n})}}$.

A few problems

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Problem 1: Lasserre Gaps

- Show an integrality gap of 2
 e for Vertex Cover, even for O(1) levels of the Lasserre hierarchy.
- Obtain integrality gaps Unique Games (and Small-Set Expansion)
 - Gaps for O((log log n)^{1/4}) levels of mixed hierarchy were obtained by [RS 09] and [KS 09].

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Extension to Lasserre?

- Technique seems specialized for linear equations.
- Breaks down even if there are few local contradictions (which doesn't rule out a gap).

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What extra constraints do vectors capture?

Thank You

Questions?