Vertex-Connectivity Survivable Network Design

Sanjeev Khanna University of Pennsylvania

Joint work with: Julia Chuzhoy (TTI)

Survivable Network Design (SNDP)

Input: A graph G(V,E) with costs on edges, and pairwise connectivity requirements r(u,v).
Goal: Minimum cost subset E' ⊆ E s.t. G(V,E') has r(u,v) disjoint paths for each pair u,v.

EC-SNDP: r(u,v) edge-disjoint paths. VC-SNDP: r(u,v) vertex-disjoint paths.

k = Max connectivity requirement for any pair.

SNDP Example



M >> 1

EC-SNDP Solution



*C*ost = 8

VC-SNDP Solution



Cost = 2M + 4 >> 8

Directed Graphs

[Dodis-K'99] If the underlying graph is directed, then even for k=1, SNDP is $2^{\log^{1} - \epsilon_{n}}$ -hard to approximate for any $\epsilon > 0$.

We focus on the undirected case from here on.

EC-SNDP Results

- 2-approximation for k = 1 via a primal-dual approach [Agrawal, Klein, Ravi '95].
- Extended to higher connectivity values. [Goemans, Mihail, Vazirani, Williamson '95], [Goemans, Goldberg, Plotkin, Shmoys, Williamson'94].
- 2-approximation by iterative LP-rounding. [Jain '98].

VC-SNDP Results

- $2^{\log^{1-\epsilon} n}$ hardness for any $\epsilon > 0$, for k=poly(n) [Kortsarz, Krauthgamer, Lee '03].
- $k^{\Omega(1)}$ -hardness [Chakraborty, Chuzhoy, K '08].
- 2-approximation if k = 2
 [Fleischer, Jain, Williamson '06].
- O((log k).log (n/n-k))-approx. if r(u,v) =k ∀ u,v.
 [Cheriyan, Vempala, Vetta '03], [Kortsarz, Nutov '04],
 [Fakcharoenphol, Laekhanukit '08], [Nutov '08].

Single-Source Vertex Connectivity

All vertex connectivity requirements are between a source s and a set T of terminals.

- O(k² log n)-approximation [Chuzhoy,K '08]; [Nutov' 08].
- O(k log n)-approximation if r(s,t) = k ∀ t ∈ T [Chuzhoy,K'08]; (an elegant simpler proof [Chekuri, Korula '08].)

Our Results

Nothing better than $O(n \log n)$ approximation for VC-SNDP even for k=3.

Theorem 1: VC-SNDP has a randomized $O(k^3 \log n)$ approximation algorithm for any k.

Theorem 2: Single-source VC-SNDP has a randomized $O(k^2 \log n)$ -approximation algorithm.

Rest of This Talk ...

- Element connectivity problem.
- Resilient set systems.
- Algorithm for general VC-SNDP.
- Improved algorithm for single-source VC-SNDP.
- Further developments.

Element Connectivity SNDP

Terminal: A vertex u s.t. r(u,v) > 0 for some v. Element: An edge or a non-terminal vertex.

Goal: A minimum cost subset $E' \subseteq E$ s.t. G(V,E') has r(u,v) element-disjoint paths for each u, v.

If u and v are k-element connected then they are k-edge connected as well, but may not be k-vertex connected.

Element Connectivity SNDP

 $r(t_1,t_2) = r(t_2,t_3) = r(t_1,t_3) = 2$



Cost = 8

Element Connectivity is Transitive

 t_1 and t_2 are k-element connected, and t_2 and t_3 are k-element connected, then so are t_1 and t_3 .



Only true for terminals.

Edge-connectivity is also transitive but not vertex-connectivity.

Element Connectivity is not Monotone

 $r(t_1, t_3) = 2$



Cost = 2M + 4 >> 8

Element Connectivity SNDP

- [Jain, Mandoiu, Vazirani, Williamson '99]
 - Introduced element connectivity SNDP.
 - A primal-dual O(log k)-approximation.
- 2-approximation via iterative LP-rounding [Fleischer, Jain, Williamson '01]
 [Cheriyan, Vempala, Vetta '03]
- Matches approximation ratio for EC-SNDP.

k-Resilient Family of Sets

A family {T₁, T₂, ..., T_p} of vertex subsets is k-resilient if for every pair (s,t) of vertices and every subset $X \subseteq V \setminus \{s,t\}$ of size (k-1), there is a T_i such that $s,t \in T_i$ and $X \cap T_i = \emptyset$.

If s and t are k-element connected w.r.t. terminal set T_i , then X can not disconnect s from t.

Algorithm for General VC-SNDP

Input: A graph G and a set P of pairs of vertices with connectivity requirements between 1 from k.

- Let $\{T_1, T_2, ..., T_p\}$ be a k-resilient family.
- Let $P_i = \{ (s,t) \in P \mid s, t \in T_i \}$ for $1 \le i \le p$.
- Solve the element-connectivity instance defined by P_i on the input graph G.
- Let G_i be the 2-approximate solution obtained for P_i .
- Output $G_1 \cup G_2 \dots \cup G_p$.

Feasibility of the Solution

Fix any pair (s,t) with vertex-connectivity requirement $r(s,t) \in [1..k]$.

- Consider any $X \subseteq V \setminus \{s,t\} s.t. |X| \le r(s,t)-1 \le (k-1)$.
- Since $\{T_1, T_2, ..., T_p\}$ is a k-resilient family, there exists T_i s.t. s,t $\in T_i$ and $X \cap T_i = \emptyset$.
- So X is a set of non-terminals in the instance for T_i .

The pair (s,t) is r(s,t)-element connected in G_i , so X can not disconnect s from t.

Cost Analysis of the Solution

- Let OPT denote the cost of an optimal solution for the given VC-SNDP instance.
- Then cost of each element connectivity instance P_i is at most OPT.
- Cost of each solution G_i is at most 2.0PT.

Thus we get an O(p)-approximation.

Constructing a k-Resilient Family

- Set $p \approx 2k^3 \log n$.
- Each terminal $t \in T$ selects uniformly at random $q \approx p/2k \approx k^2 \log n$ indices from $\{1, 2, ..., p\}$.
- Let \u00f6(t) be the set of indices chosen by t.
- Define $T_i = \{t \mid i \in \phi(t)\}$.

Lemma: With high probability, $\{T_1, T_2, ..., T_p\}$ is a k-resilient family.

Proof of k-Resiliency

- Fix a pair (s,t).
- Let X be any set of \leq (k-1) vertices in V\{s,t}.
- Bad event E(s,t,X): $\phi(s) \cap \phi(t) \subseteq \bigcup_{t' \in X \cap T} \phi(t')$.
- Probability of $E(s,t,X) \leq n^{-4k}$.
 - Key observation: $|\bigcup_{t' \in X \cap T} \phi(t')| \le p/2$.
 - So w.h.p. φ(s) ∩ φ(t) contains an index outside the union U_{t' ∈ X ∩ T} φ(t').
- By union bounds, w.h.p. bad event E(s,t,X) does not occur for any s,t, X.

(w,r)-Cover-Free Families

A family F of sets is (w,r)-cover-free if for any distinct A₁, ..., A_w ∈ F, and any other B₁, ..., B_r ∈ F if we have

 $\mathbf{A}_1 \cap \mathbf{A}_2 \cap ... \cap \mathbf{A}_w \not\subseteq \mathbf{B}_1 \cup \mathbf{B}_2 \cup ... \cup \mathbf{B}_r.$

Then { T₁, T₂, ..., T_p } is k-resilient ⇔
 F = { φ(t) | t ∈ T } is a (2,k-1)-cover-free family on elements {1, 2, ..., p}.

Implication for k-Resilient Family

Need a (2,k-1)-cover-free family with n sets. How small can we make the universe size p?

Theorem [Stinson, Wei, and Zhu '00] A (2,k-1)-cover-free family with n sets exists on a universe of p elements only if $p = \Omega((k^3 \log n) / \log k)$.

The simple randomized construction is tight to within an O(log k) factor.

Single-Source VC-SNDP

Same algorithm but more efficient k-resilient family.

- Set p= 4(k² log n), each terminal t ∈ T selects uniformly at random q= p/(2k) indices from {1, 2,..., p}.
- Let $\phi(t)$ be the set of indices chosen by t.
- Define $T_i = \{ t \mid i \in \phi(t) \}$.

Lemma: W.h.p. $\{T_1, T_2, ..., T_p\}$ is a k-resilient family.

We get an $O(k^2 \log n)$ -approximation algorithm.

When Costs are on Vertices ...

- Provably harder: even for k = 1, Ω(log n)-hard while a 2-approximation exists for edge costs.
- Our approach is oblivious to edge costs vs. vertex costs issue: α-approximation for element connectivity SNDP in vertex cost model gives an O(αk³log n)-approximation for VC-SNDP with vertex costs.

Further Developments ...

[Nutov '09]

- For edge costs:
 - O(k log k)-approximation for single-source VC-SNDP.
- For vertex costs:
 - O(k log n)-approx. for element connectivity SNDP.
 - O(k⁴ log² n)-approximation for general SNDP.

Can be used with our approach to get same bound for vertex costs.

Concluding Remarks

- Simple reduction from vertex-connectivity to element-connectivity problem.
- Highlights an interesting connection between distinct notions of connectivity.
- Single-source case:
 - Ω(log^{2-ε} n)-hardness[Kortsarz,Krauthgamer,Lee'03]
 [Lando,Nutov '08].
 - O(k log k)-approximation.
 - Poly-logarithmic approximation when k is large?

