Reasoning About Imperative Programs

COS 441 Slides 10

Agenda

- The last few weeks
 - reasoning about functional programming
 - It's very simple and very uniform: substitution of equal expressions for equal expressions
 - It works for any kind of data structure: Integers, lists, strings, trees; arbitrary user-defined data types; even actions that describe I/O effects
- The next few lectures
 - reasoning about imperative programs
 - It's fundamentally more complicated
 - In a very practical sense, this means it is fundamentally more difficult to write correct imperative programs
 - In addition to having to worry about *what* is true, you have to worry about *when* it is true

THE PROBLEM

A Simple Haskell Program

some Haskell definitions:

y = x

```
pair x y = (x,y)
sum (x1, y1) (x2, y2) = (x1+y1, x2+y2)
x = pair 2 3
```

A Simple Haskell Program

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x = pair 2 3
y = x
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what is sum x y equal to?

A Simple Haskell Program

some Haskell definitions:

```
pair x y = (x,y)
  sum (x1, y1) (x2, y2) = (x1+y1, x2+y2)
  x = pair 2 3
  \mathbf{y} = \mathbf{x}
what is sum x y equal to?
    sum x y
  = sum x x
  = sum (pair 2 3) (pair 2 3)
  = (2+2, 3+3)
                                                       you should be able to
  = (4, 6)
                                                       verify this in your sleep
```

the Java definitions:

```
class Pair {
 int x, y;
 Pair (int a1, int a2) {
    x = a1;
    y = a2;
 }
 static void sum (Pair p1, Pair p2) {
   p2.x = p1.x + p2.x;
   p2.y = p1.y + p2.y;
}
```

Pair p1 = new Pair (2, 3);

Pair p2 = p1;

the Java definitions:

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    int x, y;
    Pair (int a1, int a2) {
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static void sum (Pair p1, Pair p2) {
    p2.x = p1.x + p2.x;
    p2.y = p1.y + p2.y;
    }
}
```

a big departure from the Haskell program; we are imperatively updating the contents of the pair data structure with the sum!

```
Pair p1 = new Pair (2, 3);
```

Pair p2 = p1;

(an aside: notice how much more verbose Java is than Haskell!)

the Java definitions:

class Pair { int x, y;

```
Pair (int a1, int a2) {
    x = a1;
    y = a2;
}
```

```
static void sum (Pair p1, Pair p2) {
    p2.x = p1.x + p2.x;
    p2.y = p1.y + p2.y;
  }
}
```

Pair p1 = new Pair (2, 3);

Pair p2 = p1;

consider the statement:

sum(p1, p2); Pair p3 = p2;

what is p3 equal to?

Is p3.x == p1.x + p2.x ?
Is p3.y == p1.y + p2.y ?

the Java definitions:

class Pair { int x, y;

```
Pair (int a1, int a2) {
    x = a1;
    y = a2;
}
```

```
static void sum (Pair p1, Pair p2) {
    p2.x = p1.x + p2.x;
    p2.y = p1.y + p2.y;
  }
}
```

Pair p1 = new Pair (2, 3);

Pair p2 = p1;

consider the statement:

sum(p1, p2); Pair p3 = p2;

what is p3 equal to? Is p3.x == p1.x + p2.x ? Is p3.y == p1.y + p2.y ?

p2.x actually takes on *different values at different times* during the computation

Reasoning by simple equality, ignoring state changes completely breaks down

consider these statements:



what is p2 equal to?

consider these statements:



what is p2 equal to? Who knows!?!?

```
Example:

Pair p1 = new Pair(2, 3);

Pair p2 = p1

p1.x = 17;

p1.y = 23;
```

// p2 != (2,3)

consider these statements:



what is p2 equal to? Isn't it equal to p1 at least?

consider these statements:



what is p2 equal to? Isn't it equal to p1 at least?

```
Nope. Example:

Pair p1 = new Pair (2, 3);

Pair p2 = p1

p1 = new Pair (7,13)
```

// p1 != p2

Dramatic Differences

Haskell

- Variables are constant
- Data structures are immutable
- Properties of data are stable
- Local reasoning is easy
 - if p1 = (2,3) now, no intermittent
 code "..." changes that fact
- Code is more modular
- Order of definitions is irrelevant (provided names don't clash)
- Except when there are explicit dependencies, program parts can be run in parallel

Java

- Variables are updated
- Data structures are mutable
- Properties of data are unstable
- Local reasoning is hard
 - if p1 = (2,3) now, who knows
 what it will be after some
 intermittent code "..."
- Code is less modular
- Order of statements is crucial
- Program parts generally cannot be run in parallel

FLOYD-HOARE LOGIC: AN OVERVIEW

Hoare Logic: An Overview

Hoare Logic: An Overview



$$z = x + y;$$

 We can't count on stable properties of data, so what we will do instead is analyze the state of the computation in between every statement:

> { x > 0 & y > 0 } z = x + y;

x = x - 1;

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> { x > 0 & y > 0 } z = x + y; { z = x + y & x > 0 & y > 0 } x = x - 1;

 We can't count on stable properties of data, so what we will do instead is analyze the state of the computation in between every statement:

> { x > 0 & y > 0 } z = x + y;{ z = x + y & x > 0 & y > 0 } x = x - 1;{ z = x + 1 + y & x >= 0 & y > 0 }

```
\{x > 0 \& y > 0\}
z = x + y;
\{z = x + y \& x > 0 \& y > 0\}
x = x - 1;
\{z = x + 1 + y \& x >= 0 \& y > 0\}
\{z > x + y \& x >= 0 \& y > 0\}
```

 We can't count on stable properties of data, so what we will do instead is analyze the state of the computation in between every statement:



 $\{z > x + y \& x \ge 0 \& y \ge 0\}$

Hoare Triples

- A (partial) Hoare triple has the form { P } C { Q } where
 - P is a precondition that describes allowed initial states
 - C is a (possibly compound C-like or Java-like) statement
 - Q is a postcondition that describes allowed final states
- A (partial) Hoare triple is valid if whenever we start in a state that satisfies the pre-condition P and execution of C terminates, we wind up in a state that satisfies Q
- A fully annotated program {P1} C1 {P2} C2 ... CK {PK+1} serves as a proof of validity for the triple {P1} C1 C2 ... CK {PK+1} provided each individual components {Pi} Ci {Pi+1} obeys the Rules of Hoare Logic

Partial vs. Total Hoare Triples

- Partial Hoare Triples are valid even when a program does not terminate
- Total Hoare Triples are valid if the partial triple is valid and the program does terminate
- Partial triples are good for establishing safety properties
 - ie: certain "bad things" never happen
 - eg: an array is never indexed out of bounds
 - eg: a null pointer is never dereferenced
- Total triples are good for establishing liveness properties:
 - ie: eventually "something good" happens
 - eg: the program terminates and produces an answer
- Total triples are even more of a pain in the neck than partial ones so we are going to ignore them; fewer people use them

DESCRIBING PROGRAM STATES

- What is a program state?
 - It is a finite partial map from program variables to integer values

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- Example:
$$[x = 2, y = 17, z = 3]$$

- What is a program state?
 - It is a finite partial map from program variables to integer values

a finite number of elements in the domain of the map partial: not all variablesare necessarily present(typically there are infinitelymany possible variables)

- Example: [x = 2, y = 17, z = 3]
- Finite partial maps E typically support several operations:
 - lookup: E(x)
 - update: E[x = N]
 - domain: dom(E)

a new map in which x is mapped to N but is otherwise the same as E

ie: function

the set of variables in the domain of E

Program States in Haskell

module State where

type Var = String type State = [(Var, Int)]

```
look :: State -> Var -> Maybe Int
look [] v = Nothing
look ((v',i):xs) v =
  if v == v'
  then Just i
  else look xs v
up :: State -> Var -> Int -> State
up [] v i = [(v,i)]
up ((v',i')) v i =
```

up ((v',i'):xs) v i = if v == v' then (v,i):xs

else (v',i'):up xs v i

finite maps as lists; we could implement them as search trees for greater efficiency

dom :: State -> [Var] dom = map (\(v,i) -> v)

Describing Program States

- We are going to use logic to describe program states
- For example, this formula:

(x = 3 & y = 0) || (x = 2 & y = 1)

• Describes this state:

[x = 3, y = 0]

• And all of these:

. . .

the formula does not necessarily have to constrain all the variables

Formulae

Math

R

```
integer variables
x := x1 | x2 | x3 | ... | y | z | ...
integer expressions
e ::= N | x | e + e | e * e
predicates
p ::= e = e | e < e
formulae
f ::= true
    false
     р
    | f & f
    | f || f
    |~f
```

I will also use P, Q, F for formulae

Formulae

Math

integer variables x := x1 | x2 | x3 | ... | y | z | ...

integer expressions e ::= N | x | e + e | e * e

predicates

p ::= e = e | e < e

formulae f ::= true

> | false | p | f & f | f || f | ~f

Haskell

type Var = String

data Exp = Const Int | Var Var | Add Exp Exp | Mult Exp Exp

data Pred = Eq Exp Exp | Less Exp Exp

data Form = Tru | Fal | Pred Pred | And Form Form | Or Form Form | Not Form

Math vs. Haskell

- Denotational semantics: Math notation or Haskell notation?
- Haskell semantic definitions are clearer
- Haskell gives us an implementation that will evaluate formulae
- Math is more concise, especially in examples:

- Add (Add (Const 3) (Const 4)) (Const 5) vs (3 + 4) + 5

- If I were writing an academic research paper, I'd do it in math
- For teaching, I'll give semantics first in Haskell but then show you how to redefine them using the standard mathematical notation

SEMANTICS OF FORMULAE: PRESENTATION I: HASKELL

Denotational Semantics

- Recall: A denotational semantics gives a meaning to newly defined syntactic objects by translating these objects in to a better understood language or mathematical object
- Denotational semantics of expressions:
 - esem :: State -> Exp -> Maybe Int
 - esem s e == Just n ===> "expression e in state s has value n"
 - esem s e == Nothing ===> "expression e is not defined in state s"

Semantics of Expressions in Haskell

```
esem :: State -> Exp -> Maybe Int
```

```
esem s (Const i) = Just i
```

```
esem s (Var v) = look s v
```

Semantics of Predicates

- Denotational Semantics of Predicates:
 - psem :: State -> Pred -> Maybe Bool
 - psem p e == Just True ===> "predicate p in state s is valid"
 - psem p e == Just False ===> "predicate p in state s is not valid"
 - psem p e == Nothing ====> "predicate p is not defined in state s"

Semantics of Predicates in Haskell

```
psem :: State -> Pred -> Maybe Bool
```

Semantics of Formulae

- Denotational semantics of formulae
 - fsem :: State -> Form -> Maybe Int
 - fsem f e == Just True ===> "formula f in state s is valid" ====> "formula f describes state s"
 - fsem f e == Just False ===> "formula f in state s is not valid"
 ===> "formula f does not describe state s"

– fsem f e == Nothing ===> "formula f is not defined in state s"

Semantics of Formulae in Haskell



What can we do with the semantics?

- We can determine which formulae are equivalent
 - Equivalent formulae describe the same set of states

- f1 == f2 iff for all s, fsem s f1 == fsem s f2

- Question: Could you define a type class instance that implemented this notion of equality?
- Exercises. Prove the following using the Haskell definitions:
 - Tru == Not Fal
 - Fal == Not Tru
 - Not (Not f) == f
 - And f1 f2 == And f2 f1
 - Or f1 f2 == Or f2 f1
 - Or (Or f1 f2) f3 == Or f1 (Or f2 f3)
 - Not (And f1 f2) == Or (Not f1) (Not f2)

What can we do with the semantics?

Lemma: Tru == Not Fal

Proof:

consider any s, we must prove: fsem s Tru = fsem s (Not Fal).

fsem s Tru

- == Just True (unfold fsem)
- == Just (not False) (fold not)
- == fsem s (Not Fal) (fold fsem s)

What can we do with the semantics?

- We can define the strength of a formula:
 - f1 is stronger than f2 if f1 describes a subset of the states described by f2. Alternatively, f2 is weaker than f1.
 - we write f1 => f2 iff

for all s, fsem s f1 == Just True implies fsem s f2 == Just True

- Exercises. Prove the following using the Haskell definitions:
 - Fal => Tru
 - And f1 f2 => f1 (for any f1, f2)

A bit of a glitch

- f1 => Or f1 f2 is not true in general. Why?
- Recall: To prove a conjecture isn't true in general, give a counter-example. Here's one:
 - Let f1 = Tru
 - Let $f^2 = Eq x x$

– Tru => Or Tru (Eq x x) iff

for all s, fsem s Tru => fsem s (Or Tru (Eq x x))

- consider s = []; in this case:
 - fsem s Tru = Just True
 - fsem s (Or Tru (Eq x x)) = Nothing

Resolving the glitch

- We assume there is some (finite) set of variables G that are allowed to appear in expressions, formulae and programs
 - An expression, formula, or program is well-formed if its variables are a subset of G
 - ie: the expression/formula/program only uses the allowed variables
 - A state s is well-formed if dom(s) is a superset or equal to G
 - ie: s defines all of the allowed variables
- New definitions. Consider any well-formed f1 and f2:
 - f1 == f2 iff for all well-formed s,

fsem s f1 == fsem s f2

- f1 => f2 iff for all well-formed s,

fsem s f1 == Just True implies fsem s f2 == Just True

- From now on we will only work with well-formed objects
 - ie: we won't mention it, but you can assume every state, formula, etc., from here on out in these slides is well-formed
- From now on, formulae are either valid or invalid
 - ie: fsem s f == Just True or fsem s f == Just False
 - fsem s f is never Nothing when s and f are well-formed
 - hence, we can start ignoring the "Just" in the result
 - I'll often simply say "fsem s f is true" or "f is true" (in some state)
 - In this setting f1 => f2 is the classical notion of logical implication you are used to

SUMMARY!

Summary

- Hoare Triples characterize program properties
- States map variables to values
- Formulae describe states:
 - semantics in Haskell: fsem :: State -> Form -> Maybe Bool
 - formulae and states we deal with are well-formed
 - well-formedness is a very simple syntactic analysis
 - P => Q means P is stronger than Q; P describes fewer states