The 3D Rasterization Pipeline

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Princeton University
3D Rendering Scenarios

• Offline
  ◦ One image generated with as much quality as possible for a particular set of rendering parameters
    ▪ Take as much time as is needed (minutes)
    ▪ Useful for photorealism, movies, etc.

  ➢ Interactive
    ◦ Images generated in fraction of a second (e.g., 1/30) as user controls rendering parameters (e.g., camera)
      ▪ Achieve highest quality possible in given time
      ▪ Visualization, games, etc.
3D Polygon Rendering

• Many applications use rendering of 3D polygons with direct illumination
3D Polygon Rendering

- Many applications use rendering of 3D polygons with direct illumination
Ray Casting Revisited

- For each sample ...
  - Construct ray from eye position through view plane
  - Find first surface intersected by ray through pixel
  - Compute color of sample based on illumination
3D Polygon Rasterization

- We can render polygons faster if we take advantage of **spatial coherence**
3D Polygon Rasterization

• How?
3D Polygon Rasterization

• How?
This is a pipelined sequence of operations to draw 3D primitives into a 2D image.
Rasterization Pipeline (for direct illumination)

OpenGL executes steps of 3D rendering pipeline for each polygon

```c
glBegin(GL_POLYGON);
glVertex3f(0.0, 0.0, 0.0);
glVertex3f(1.0, 0.0, 0.0);
glVertex3f(0.0, 1.0, 0.0);
glEnd();
```
Rasterization Pipeline (for direct illumination)

3D Primitives

Modeling Transformation

Transform into 3D world coordinate system

Lighting

Viewing Transformation

Projection Transformation

Clipping

Viewport Transformation

Scan Conversion

Image
Rasterization Pipeline  (for direct illumination)

3D Primitives

Modeling Transformation

Lighting

Viewing Transformation

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Clipping

Viewport Transformation

Scan Conversion

Image

Transform into 3D world coordinate system

Illuminate according to lighting and reflectance
Rasterization Pipeline (for direct illumination)

3D Primitives

- Modeling Transformation
  - Transform into 3D world coordinate system
- Lighting
  - Illuminate according to lighting and reflectance
- Viewing Transformation
  - Transform into 3D camera coordinate system
- Projection Transformation
- Clipping
- Viewport Transformation
- Scan Conversion
- Image
Rasterization Pipeline (for direct illumination)

- 3D Primitives
  - Modeling Transformation
  - Lighting
  - Viewing Transformation
  - Projection Transformation
  - Clipping
  - Viewport Transformation
  - Scan Conversion

- Transform into 3D world coordinate system
- Illuminate according to lighting and reflectance
- Transform into 3D camera coordinate system
- Transform into 2D camera coordinate system

Image
Rasterization Pipeline (for direct illumination)

3D Primitives

- **Modeling Transformation**
  - Transform into 3D world coordinate system

- **Lighting**
  - Illuminate according to lighting and reflectance

- **Viewing Transformation**
  - Transform into 3D camera coordinate system

- **Projection Transformation**
  - Transform into 2D camera coordinate system

- **Clipping**
  - Clip primitives outside camera’s view

- **Viewport Transformation**

- **Scan Conversion**

- **Image**
Rasterization Pipeline  (for direct illumination)

3D Primitives

Modeling Transformation

Transform into 3D world coordinate system

Lighting

Illuminate according to lighting and reflectance

Viewing Transformation

Transform into 3D camera coordinate system

Projection Transformation

Transform into 2D camera coordinate system

Clipping

Clip primitives outside camera’s view

Viewport Transformation

Transform into image coordinate system

Scan Conversion

Image
Rasterization Pipeline (for direct illumination)

3D Primitives

Modeling Transformation
Transform into 3D world coordinate system

Lighting
Illuminate according to lighting and reflectance

Viewing Transformation
Transform into 3D camera coordinate system

Projection Transformation
Transform into 2D camera coordinate system

Clipping
Clip primitives outside camera’s view

Viewport Transformation
Transform into image coordinate system

Scan Conversion
Draw pixels (includes texturing, hidden surface, ...)

Image
Rasterization Pipeline (for direct illumination)

3D Primitives

Modeling Transformation

Transform into 3D world coordinate system

Lighting

Illuminate according to lighting and reflectance

Viewing Transformation

Transform into 3D camera coordinate system

Projection Transformation

Transform into 2D camera coordinate system

Clipping

Clip primitives outside camera’s view

Viewport Transformation

Transform into image coordinate system

Scan Conversion

Draw pixels (includes texturing, hidden surface, ...)

Image
Transformations map points from one coordinate system to another.
Viewing Transformations

\[ p(x,y,z) \]

3D Object Coordinates

Modeling Transformation

3D World Coordinates

Viewing Transformation

3D Camera Coordinates

Projection Transformation

2D Screen Coordinates

Viewport Transformation

2D Image Coordinates

\[ p'(x',y') \]

Viewing Transformations
Review: Viewing Transformation

- Mapping from world to camera coordinates
  - Eye position maps to origin
  - Right vector maps to X axis
  - Up vector maps to Y axis
  - Back vector maps to Z axis
Review: Camera Coordinates

- Canonical coordinate system
  - Convention is right-handed (looking down -z axis)
  - Convenient for projection, clipping, etc.

[Diagram showing camera coordinates with axes labeled]

- Camera right vector maps to X axis
- Camera up vector maps to Y axis
- Camera back vector maps to Z axis (pointing out of page)
Finding the viewing transformation

• We have the camera (in world coordinates)

• We want $T$ taking objects from world to camera

\[ p^c = T \ p^w \]

• Trick: find $T^{-1}$ taking objects in camera to world

\[ p^w = T^{-1} p^c \]

\[
\begin{bmatrix}
    x' \\
    y' \\
    z' \\
    w'
\end{bmatrix}
= \begin{bmatrix}
    a & b & c & d \\
    e & f & g & h \\
    i & j & k & l \\
    m & n & o & p
\end{bmatrix}
\begin{bmatrix}
    x \\
    y \\
    z \\
    w
\end{bmatrix}
\]
Finding the Viewing Transformation

- Trick: map from camera coordinates to world
  - Origin maps to eye position
  - Z axis maps to Back vector
  - Y axis maps to Up vector
  - X axis maps to Right vector

\[
\begin{bmatrix}
x' \\
y' \\
z' \\
w'
\end{bmatrix} = \begin{bmatrix}
R_x & U_x & B_x & E_x \\
R_y & U_y & B_y & E_y \\
R_z & U_z & B_z & E_z \\
R_w & U_w & B_w & E_w
\end{bmatrix}\begin{bmatrix}
x \\
y \\
z \\
w
\end{bmatrix}
\]

- This matrix is $T^{-1}$ so we invert it to get $T$ … easy!
Viewing Transformations

\[ p(x,y,z) \]

- 3D Object Coordinates
- Modeling Transformation
  - 3D World Coordinates
  - Viewing Transformation
    - 3D Camera Coordinates
    - Projection Transformation
      - 2D Screen Coordinates
      - Viewport Transformation
        - 2D Image Coordinates
        - \( p'(x',y') \)

Viewing Transformations
Projection

• General definition:
  ◦ Transform points in $n$-space to $m$-space ($m<n$)

• In computer graphics:
  ◦ Map 3D camera coordinates to 2D screen coordinates
Taxonomy of Projections

Planar geometric projections
  Parallel
    Orthographic
      Top (plan)
      Front elevation
    Axonometric
      Side elevation
    Isometric
      Other
  Oblique
    Cabinet
      Cavalier
    Other
  Perspective
    One-point
    Two-point
    Three-point

FVFHP Figure 6.10
Taxonomy of Projections

Planar geometric projections

Parallel

Orthographic

Top (plan)

Front elevation

Axonometric

Side elevation

Isometric

Oblique

Cabinet

Cavalier

One-point

Perspective

Two-point

Three-point

Other

Other

FVFHP Figure 6.10
Parallel Projection

- Center of projection is at infinity
  - Direction of projection (DOP) same for all points
Orthographic Projections

- DOP perpendicular to view plane
Parallel Projection Matrix

- General parallel projection transformation:

\[
\begin{bmatrix}
    x_s \\
    y_s \\
    z_s \\
    w_s
\end{bmatrix} =
\begin{bmatrix}
    1 & 0 & L \cos \phi & 0 \\
    0 & 1 & L \sin \phi & 0 \\
    0 & 0 & 0 & 0 \\
    0 & 0 & 0 & 1
\end{bmatrix}
\begin{bmatrix}
    x_c \\
    y_c \\
    z_c \\
    1
\end{bmatrix}
\]
Parallel Projection View Volume

Parallelepiped View Volume

Back Plane

Front Plane

window

$Z_V$
Taxonomy of Projections

Planar geometric projections

Parallel

Orthographic
- Top (plan)
- Front elevation
- Side elevation

Axonometric
- Isometric

Oblique
- Cabinet
- Cavalier

One-point

Two-point

Three-point

Perspective

Other
Return to Perspective Projection

- Map points onto “view plane” along “projectors” emanating from “center of projection” (COP)
Perspective Projection

- Compute 2D coordinates from 3D coordinates with similar triangles

What are the coordinates of the point resulting from projection of \((x,y,z)\) onto the view plane?
Perspective Projection

- Compute 2D coordinates from 3D coordinates with similar triangles

\[(x, y, z) \rightarrow (-z, xD/z, yD/z)\]
Perspective Projection Matrix

- 4x4 matrix representation?

\[
x_s = x_c \frac{D}{z_c}
\]
\[
y_s = y_c \frac{D}{z_c}
\]
\[
z_s = D
\]
\[
w_s = 1
\]

\[
\begin{bmatrix}
x_s \\
y_s \\
z_s \\
w_s
\end{bmatrix}
= \begin{bmatrix}
\end{bmatrix}
\begin{bmatrix}
x_c \\
y_c \\
z_c
\end{bmatrix}
\]
Perspective Projection Matrix

- 4x4 matrix representation?

\[
\begin{align*}
    x_s &= x_c \frac{D}{z_c} & x_s &= x'/w' & x' &= x_c \\
    y_s &= y_c \frac{D}{z_c} & y_s &= y'/w' & y' &= y_c \\
    z_s &= D & z_s &= z'/w' & z' &= z_c \\
    w_s &= 1 & w' &= z_c / D
\end{align*}
\]

\[
\begin{bmatrix}
x_s \\
y_s \\
z_s \\
w_s
\end{bmatrix}
= \begin{bmatrix}
? & ? & ? & ?
\end{bmatrix}
\begin{bmatrix}
x_c \\
y_c \\
z_c \\
1
\end{bmatrix}
\]
Perspective Projection Matrix

• 4x4 matrix representation?

\[
\begin{align*}
x_s &= x_c \frac{D}{z_c} & x_s &= x'/w' & x' &= x_c \\
y_s &= y_c \frac{D}{z_c} & y_s &= y'/w' & y' &= y_c \\
z_s &= D & z_s &= z'/w' & z' &= z_c \\
w_s &= 1 & \quad & w' &= z_c / D
\end{align*}
\]

\[
\begin{bmatrix}
x_s \\ y_s \\ z_s \\ w_s
\end{bmatrix} =
\begin{bmatrix}
1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1/D & 0 & 0
\end{bmatrix}
\begin{bmatrix}
x_c \\ y_c \\ z_c \\ 1
\end{bmatrix}
\]
Perspective Projection Matrix

- In practice, want to compute a value related to depth to include in z-buffer

\[
\begin{align*}
x_s &= x_c \frac{D}{z_c} & x_s &= x'/ w' & x' &= x_c \\
y_s &= y_c \frac{D}{z_c} & y_s &= y'/ w' & y' &= y_c \\
z_s &= -D / z_c & z_s &= z'/ w' & z' &= -1 \\
w_s &= 1 & w' &= z_c / D
\end{align*}
\]

\[
\begin{bmatrix}
x_s \\
y_s \\
z_s \\
w_s
\end{bmatrix} = \begin{bmatrix}
1 & 0 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & -1 \\
0 & 0 & 1/D & 0 & 0
\end{bmatrix} \begin{bmatrix}
x_c \\
y_c \\
z_c \\
1
\end{bmatrix}
\]
Perspective vs. Parallel

- Perspective projection
  + Size varies inversely with distance - looks realistic
    - Distance and angles are not (in general) preserved
    - Parallel lines do not (in general) remain parallel

- Parallel projection
  + Good for exact measurements
  + Parallel lines remain parallel
    - Angles are not (in general) preserved
    - Less realistic looking
Transformations

\[ p(x,y,z) \]

Transformations map points from one coordinate system to another

\[ p'(x',y') \]

1. **Modeling Transformation**
   - 3D Object Coordinates

2. **Viewing Transformation**
   - 3D World Coordinates
   - 3D Camera Coordinates

3. **Projection Transformation**
   - 3D Camera Coordinates
   - 2D Screen Coordinates

4. **Viewport Transformation**
   - 2D Screen Coordinates
   - 2D Image Coordinates

- 3D Object Coordinates
- 3D World Coordinates
- 3D Camera Coordinates
- 2D Screen Coordinates
- 2D Image Coordinates

Transformations map points from one coordinate system to another.
Viewport Transformation

- Transform 2D geometric primitives from screen coordinate system (normalized device coordinates) to image coordinate system (pixels)
Viewport Transformation

- Window-to-viewport mapping

\[ vx = vx_1 + (wx - wx_1) \times \frac{(vx_2 - vx_1)}{(wx_2 - wx_1)}; \]
\[ vy = vy_1 + (wy - wy_1) \times \frac{(vy_2 - vy_1)}{(wy_2 - wy_1)}; \]
Summary of Transformations

\[ p(x,y,z) \]

- **Modeling Transformation**
  - 3D Object Coordinates
  - 3D World Coordinates
- **Viewing Transformation**
  - 3D Camera Coordinates
  - 2D Screen Coordinates
- **Projection Transformation**
  - 2D Image Coordinates

\[ p'(x',y') \]

- **Modeling transformation**
- **Viewing transformations**
- **Viewport transformation**
3D Rendering Pipeline (for direct illumination)

3D Primitives

Modeling Transformation

Lighting

Viewing Transformation

Projection Transformation

Clipping

Viewport Transformation

Scan Conversion

Image

3D Modeling Coordinates

3D World Coordinates

3D World Coordinates

3D Camera Coordinates

2D Screen Coordinates

2D Screen Coordinates

2D Image Coordinates

2D Image Coordinates
Clipping

- Avoid drawing parts of primitives outside window
  - Window defines part of scene being viewed
  - Must draw geometric primitives only inside window
Polygon Clipping

• Find the part of a polygon inside the clip window?
Polygon Clipping

- Find the part of a polygon inside the clip window?
Sutherland Hodgeman Clipping

- Clip to each window boundary one at a time (for convex polygons)
Sutherland Hodgeman Clipping

- Clip to each window boundary one at a time
Sutherland Hodgeman Clipping

- Clip to each window boundary one at a time
Sutherland Hodgeman Clipping

- Clip to each window boundary one at a time
Sutherland Hodgeman Clipping

- Clip to each window boundary one at a time
Clipping to a Boundary

- Do **inside** test for each point in sequence,
  Insert new points when cross window boundary,
  Remove points outside window boundary

![Diagram showing clipping to a boundary with points P1, P2, P3, P4, and P5. The Window Boundary separates Inside and Outside regions.](image-url)
Clipping to a Boundary

- Do **inside** test for each point in sequence,
- Insert new points when cross window boundary,
- Remove points outside window boundary

![Diagram showing point P1 inside the window boundary, and points P2, P3, P4, P5 outside the boundary.](image)
Clipping to a Boundary

- Do **inside** test for each point in sequence,
  Insert new points when cross window boundary,
  Remove points outside window boundary
Clipping to a Boundary

- Do **inside** test for each point in sequence,
  Insert new points when cross window boundary,
  Remove points outside window boundary
Clipping to a Boundary

- Do *inside* test for each point in sequence,
  *Insert new points* when cross window boundary,
  *Remove points* outside window boundary

![Diagram showing clipping to a boundary](image)
Clipping to a Boundary

- Do **inside** test for each point in sequence,
- **Insert new points** when cross window boundary,
- **Remove points** outside window boundary
Clipping to a Boundary

- Do **inside** test for each point in sequence, **Insert new points** when cross window boundary, **Remove points** outside window boundary
Clipping to a Boundary

- Do **inside** test for each point in sequence, **Insert new points** when cross window boundary, **Remove points** outside window boundary
Clipping to a Boundary

- Do **inside** test for each point in sequence,
  - **Insert new points** when cross window boundary,
  - **Remove points** outside window boundary
3D Rendering Pipeline (for direct illumination)

- 3D Primitives
  - Modeling Transformation
    - 3D Modeling Coordinates
  - Lighting
    - 3D World Coordinates
  - Viewing Transformation
    - 3D World Coordinates
  - Projection Transformation
    - 3D Camera Coordinates
  - Clipping
    - 2D Screen Coordinates
  - Viewport Transformation
    - 2D Screen Coordinates
  - Scan Conversion
    - 2D Image Coordinates
  - Image
    - 2D Image Coordinates

Viewing Window
3D Rendering Pipeline (for direct illumination)

- 3D Primitives
- Modeling Transformation
- Lighting
- Viewing Transformation
- Projection Transformation
- Clipping
- Viewport Transformation
- Scan Conversion

3D Primitives

Modeling Transformation

Lighting

Viewing Transformation

Projection Transformation

Clipping

Viewport Transformation

Scan Conversion

Image

3D Modeling Coordinates

3D World Coordinates

3D World Coordinates

3D Camera Coordinates

2D Screen Coordinates

2D Screen Coordinates

2D Image Coordinates

2D Image Coordinates

Standard (aliased) Scan Conversion
3D Primitives

Modeling Transformation

Lighting

Viewing Transformation

Projection Transformation

Clipping

Viewport Transformation

Scan Conversion

Image

3D Primitives

3D Modeling Coordinates

Modeling Transformation

3D World Coordinates

Lighting

3D World Coordinates

Viewing Transformation

3D Camera Coordinates

Projection Transformation

2D Screen Coordinates

Clipping

2D Screen Coordinates

Viewport Transformation

2D Image Coordinates

Scan Conversion

2D Image Coordinates

Antialiased Scan Conversion

3D Rendering Pipeline (for direct illumination)
Scan Conversion

- Render an image of a geometric primitive by setting pixel colors

```c
void SetPixel(int x, int y, Color rgba)
```

- Example: Filling the inside of a triangle
Triangle Scan Conversion

- Properties of a good algorithm
  - Symmetric
  - Straight edges
  - No cracks between adjacent primitives
  - (Antialiased edges)
  - FAST!
Simple Algorithm

- Color all pixels inside triangle

```c
void ScanTriangle(Triangle T, Color rgba)
{
    for each pixel P in bbox(T)
    {
        if (Inside(T, P))
            SetPixel(P.x, P.y, rgba);
    }
}
```
Triangle Sweep-Line Algorithm

• Take advantage of spatial coherence
  ◦ Compute which pixels are inside using horizontal spans
  ◦ Process horizontal spans in scan-line order

• Take advantage of edge linearity
  ◦ Use edge slopes to update coordinates incrementally
void ScanTriangle(Triangle T, Color rgba) {
    for each edge pair { 
        initialize $x_L$, $x_R$;
        compute $dx_L/dy_L$ and $dx_R/dy_R$;
        for each scanline at $y$
            for (int $x = x_L$; $x <= x_R$; $x++$)
                SetPixel($x$, $y$, rgba);
        $x_L += dx_L/dy_L$;
        $x_R += dx_R/dy_R$;
    }
}
void ScanTriangle(Triangle T, Color rgba) {
    for each edge pair {
        initialize $x_L$, $x_R$;
        compute $dx_L/dy_L$ and $dx_R/dy_R$;
        for each scanline at $y$
            for (int $x = x_L$; $x <= x_R$; $x++$)
                SetPixel($x$, $y$, rgba);
        $x_L += dx_L/dy_L$;
        $x_R += dx_R/dy_R$;
    }
}

Minimize computation
in inner loops
GPU Architecture

GeForce 6 Series Architecture
GPU Architecture

GeForce 6 Series Architecture