

Clustering

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Informal goal

- Given set of objects and measure of similarity between them, group similar objects together
- What mean by “similar”?
- What is good grouping?
- Computation time / quality tradeoff

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General types of clustering

- “Soft” versus “hard” clustering
 - **Hard**: partition the objects
 - each object in exactly one partition
 - **Soft**: assign degree to which object in cluster
 - view as probability or score
- **flat** versus **hierarchical** clustering
 - hierarchical = clusters within clusters

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Applications:

Many

- biology
- astronomy
- computer aided design of circuits
- information organization
- marketing
- ...

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Clustering in information search and analysis

- Group information objects
 - ⇒ discover topics
 - ? other groupings desirable
- Clustering versus classifying
 - classifying: have pre-determined classes with example members
 - clustering:
 - get groups of similar objects
 - added problem of labeling clusters by topic
 - e.g. common terms within cluster of docs.

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Example applications in search

- Query evaluation: cluster pruning (§7.1.6)
 - cluster all documents
 - choose representative for each cluster
 - evaluate query w.r.t. cluster reps.
 - evaluate query for docs in cluster(s) having most similar cluster rep.(s)
- Results presentation: labeled clusters
 - cluster only query results
 - e.g. Yippy.com (metasearch)

hard / soft? flat / hier?

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Issues

- What, if any, attributes represent items for clustering purposes?
- What is measure of similarity between items?
 - General objects and matrix of pairwise similarities
 - Objects with specific properties that allow other specifications of measure
 - Most common:
 - Objects are d-dimensional vectors
 - » Euclidean distance
 - » cosine similarity
- What is measure of similarity between clusters?

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Issues continued

- Cluster goals?
 - Number of clusters?
 - flat or hierarchical clustering?
 - cohesiveness of clusters?
- How evaluate cluster results?
 - relates to measure of closeness between clusters
- Efficiency of clustering algorithms
 - large data sets => external storage
- Maintain clusters in dynamic setting?
- Clustering methods? - MANY!

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Quality of clustering

- In applications, quality of clustering depends on how **well solves problem at hand**
- Algorithm uses **measure of quality** that can be **optimized**, but that may or may not do a good job of capturing application needs.
- Underlying **graph-theoretic problems** usually **NP-complete**
 - e.g. graph partitioning
- Usually algorithm **not finding optimal clustering**

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General types of clustering methods

- **constructive**: decide in what cluster each object belongs and don't change
 - often faster
- **iterative improvement**: start with a clustering and move objects around to see if can improve clustering
 - often slower but better

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Vector model: K- means algorithm

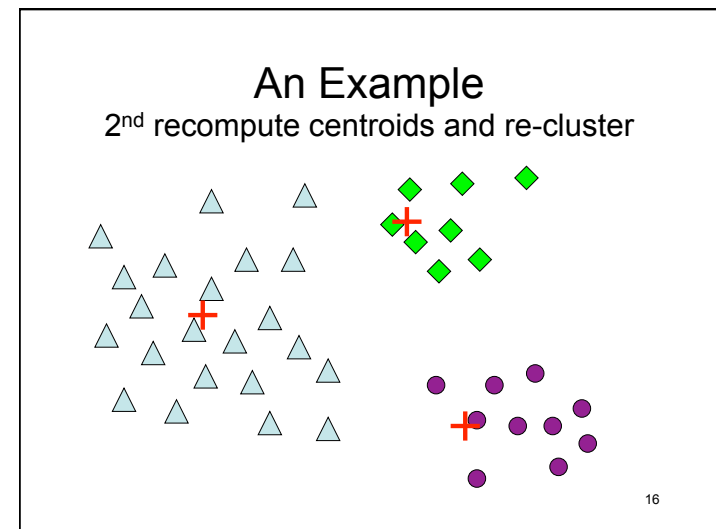
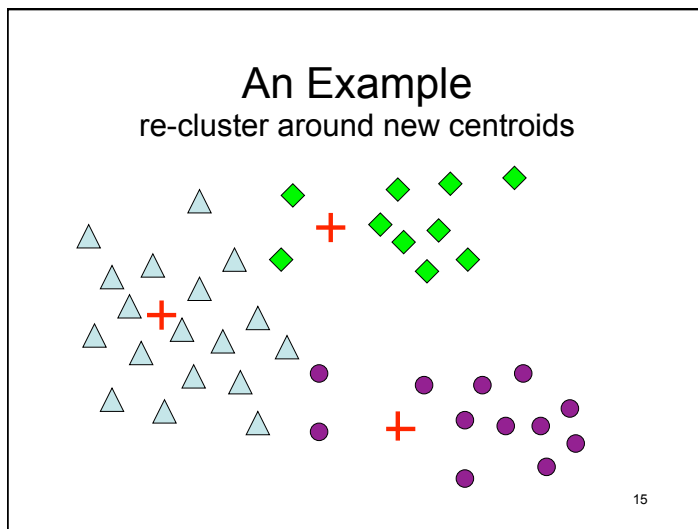
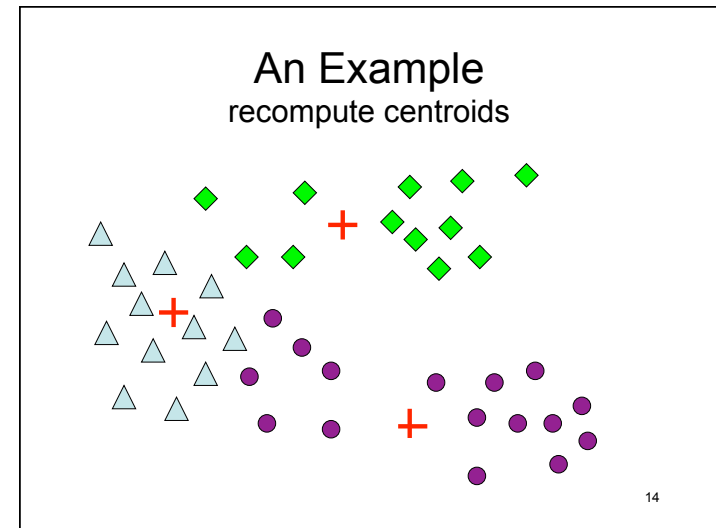
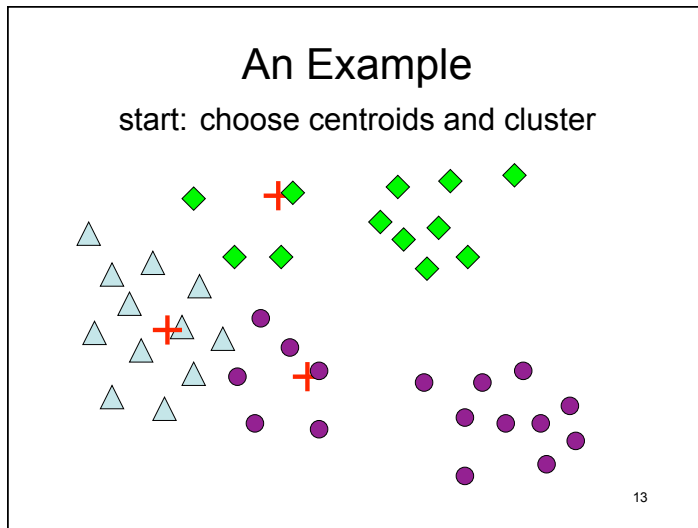
- Well known, well used
- Flat clustering
- Number of clusters picked ahead of time
- Iterative improvement
- Uses notion of **centroid**
- Typically uses Euclidean distance

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K-means overview

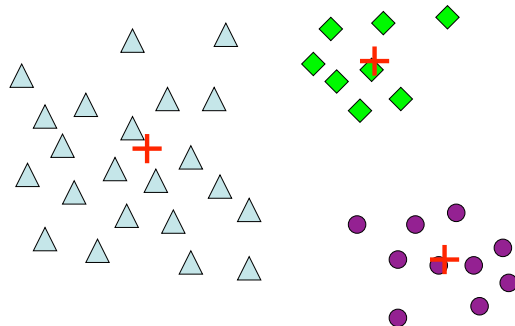
- **Choose k** points among set to be clustered
 - Call them k **centroids**
 - not required to be in set to be clustered
- For **each point** not selected, assign it **to its closest centroid**
 - Assignments give initial clustering
- Until “happy” do:
 - **Recompute centroids** of clusters:
centroid of set of vectors $\{v_i \mid 1 \leq i \leq n\} = 1/n * \sum_{i=1}^n v_i$
 - New centroids may not be points of original set
 - **Reassign all points** to closest centroid
 - Updates clusters

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An Example

3rd (final) recompute and re-cluster



Illustrations thanks to 2006 student Martin Makowiecki

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Details for K-means

- Need definition of **centroid**
 $c_i = 1/|C_i| \sum_{x \in C_i} x$ for i^{th} cluster C_i containing objects x
 notion of **sum of objects** ?
- Need definition of **distance to** (similarity to) **centroid**
- Typically vector model with Euclidean distance
- minimizing sum of squared distances of each point to its centroid = **Residual Sum of Squares**

$$RSS = \sum_{i=1}^K \sum_{x \in C_i} dist(c_i, x)^2$$

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K-means performance

- Can prove RSS decreases with each iteration, so **converge**
- Can achieve **local optimum**
 - No change in centroids
- Running time depends on how demanding stopping criteria
- Works well in practice
 - speed
 - quality

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Time Complexity of K-means

- Let t_{dist} be the time to calculate the distance between two objects
- Each **iteration** time complexity:
 $O(K \cdot n \cdot t_{\text{dist}})$
 n = number of objects
- Bound number of **iterations** I giving
 $O(I \cdot K \cdot n \cdot t_{\text{dist}})$
- for **m-dimensional vectors**:
 $O(I \cdot K \cdot n \cdot m)$
 m large and **centroids not sparse**

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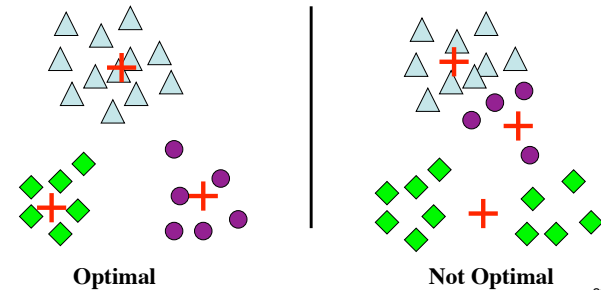
Space Complexity of K-means

- Store points and centroids
 - vector model: $O((n + K)m)$
- External algorithm versus internal?
 - store k centroids in memory
 - run through points each iteration

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Choosing Initial Centroids

- Bad initialization leads to poor results



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Choosing Initial Centroids

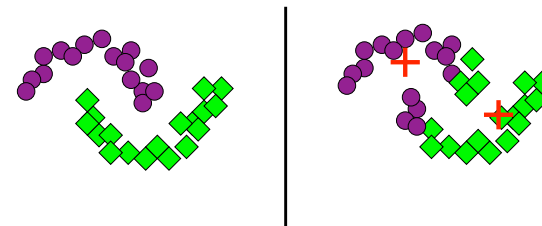
Many people spent much time examining
how to choose seeds

- Random
 - Fast and easy, but often poor results
- Run random multiple times, take best
 - Slower, and still no guarantee of results
- Pre-conditioning
 - remove outliers
- Choose seeds algorithmically
 - run hierarchical clustering on sample points and use resulting centroids
 - Works well on small samples and for few initial centroids

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K-means weakness

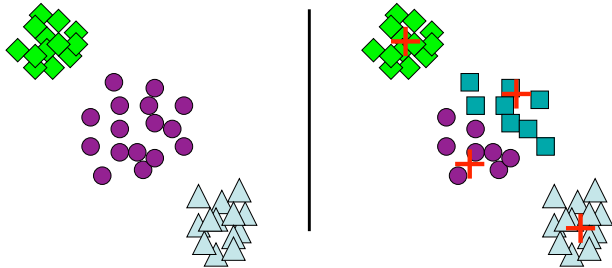
Non-globular clusters



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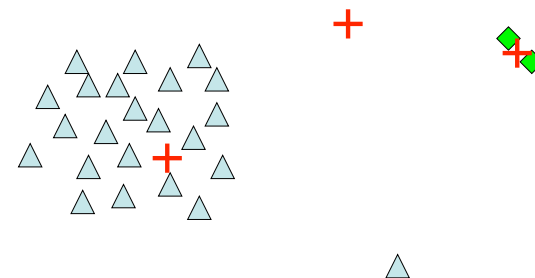
K-means weakness

Wrong number of clusters



K-means weakness

Outliers and empty clusters



Real cases tend to be harder

- Different attributes of the feature vector have vastly different sizes
 - size of star versus color
- Can weight different features
 - how weight greatly affects outcome
- Difficulties can be overcome

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Clustering Algorithms for general similarity measures

general similarity measure:
specified by object X object similarity matrix

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Types of general clustering methods

- **constructive** algorithms
- **agglomerative** versus **divisive** construction
 - **agglomerative** = bottom-up
 - build up clusters from single objects
 - **divisive** = top-down
 - break up cluster containing all objects into smaller clusters
 - both agglom' tive and divisive give **hierarchies**
 - hierarchy can be trivial:

1 (. .) . . .
 3 (((. . .) .) .) .

2 ((. . .) .) . .
 4 ((((. . .) .) .) .) .

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Similarity between clusters

Possible definitions:

- similarity between most similar pair of objects with one in each cluster
 - called **single link**
- similarity between least similar pair objects, one from each cluster
 - called **complete linkage**



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Similarity between clusters, cont.

Possible definitions:

- average of pairwise similarity between **all pairs** of objects, **one from each cluster**
 - “centroid” similarity
 - average of pairwise similarity between **all pairs** of distinct objects, **including w/in same cluster**
 - “group average” similarity
- Generally no representative point for a cluster;
 - compare K-means
 - If using Euclidean distance as metric
 - **centroid**
 - **bounding box**

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General **Agglomerative**

- Uses any computable cluster similarity measure $\text{sim}(C_i, C_j)$
- For n objects $v_1, \dots, v_n$, assign each to a singleton cluster $C_i = \{v_i\}$.
- repeat {
 - identify two most **similar clusters** C_j and C_k (could be ties – chose one pair)
 - delete C_j and C_k and add $(C_j \cup C_k)$ to the set of clusters
- } until only one cluster
- Dendrograms diagram the sequence of cluster merges.

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Agglomerative: remarks

- *Intro. to IR* discusses in great detail for cluster similarity:
 - single-link, complete-link, group average, centroid
- Uses priority queues to get time complexity $O((n^2 \log n) * (\text{time to compute cluster similarity}))$
 - one priority queue for each cluster: contains similarities to all other clusters plus bookkeeping info
 - time complexity more precisely:
 $O((n^2) * (\text{time to compute object-object similarity}) + (n^2 \log n) * (\text{time to compute } \text{sim}(\text{cluster}_z, \text{cluster}_j \cup \text{cluster}_k) \text{ if know } \text{sim}(\text{cluster}_z, \text{cluster}_j) \text{ and } \text{sim}(\text{cluster}_z, \text{cluster}_k)))$
- Problem with priority queue?

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Single pass agglomerative-like

Given arbitrary order of objects to cluster: $v_1, \dots, v_n$ and threshold τ

```

Put  $v_1$  in cluster  $C_1$  by itself
For  $i = 2$  to  $n$  {
  for all existing clusters  $C_j$ 
    calculate  $\text{sim}(v_i, C_j)$ ;
  record most similar cluster to  $v_i$  as  $C_{\max(i)}$ 
  if  $\text{sim}(v_i, C_{\max(i)}) > \tau$  add  $v_i$  to  $C_{\max(i)}$ 
  else create new cluster  $\{v_i\}$ 
}
```

ISSUES?

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Issues

- put v_i in cluster after seeing only $v_1, \dots, v_{i-1}$
- not hierarchical
- tends to produce large clusters
 - depends on τ
- depends on order of v_i

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Alternate perspective for single-link algorithm

- Build a **minimum spanning tree (MST)**
 - graph algorithm
 - edge weights are pair-wise similarities
 - since in terms of similarities, not distances, really want **maximum** spanning tree
- For some threshold τ , remove all edges of similarity $< \tau$
- Tree falls into pieces $\Rightarrow$ clusters
- Not hierarchical, but get hierarchy for sequence of τ

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