Interactive Visualization of Complex Scenes

> COS 426 Spring 2015 Princeton University

Interactive Visualization

Render images with interactive control of viewpoint



Mechanical CAD



Medicine



Driving Simulation



Entertainment



Architectural CAD



Education

Interactive Visualization Goals

Realism

Realistic enough to convey information

Frame rate:

>10-60 frames per second

Latency

<10-500 milliseconds response delay</p>

Computation

- Fast preprocessing
- Fast startup
- Low storage
- etc.

Scene Complexity

Examples:

- Automobile: ~20,000 parts
- Boeing Airplane: ~2,000,000 parts
- Aircraft Carrier: ~20,000,000 parts
- Sculptures: ~200,000,000,000 samples
- Outdoor Environments

Architectural Models





Soda Hall Model (7.6M polygons)

Structural Engineering Models



Coal-Fired Powerplant: 15 million triangles

Mechanical CAD Models



Submarine Torpedo Room (850K polygons)

Mechanical CAD Models

82 million triangles; 126,000 objects Newport News Shipbuilding







Rendering Acceleration Techniques

Visibility Culling

• Backface culling, view-frustum culling, occlusion culling, ...

Detail Elision

• Levels of detail, multiresolution, ...

Images

• Textures, billboards, imposters, ...

Visibility Culling



Quickly eliminate large portions of the scene that will not be visible in the final image

- Not the exact visibility solution, but a quick and conservative test to reject primitives that are not visible
 - Trivially reject stuff that is obviously not seen
 - Use Z-buffer and clipping for the exact solution



Visibility Culling

Basic idea: don't render what can't be seen

- Facing away from camera: backface culling
- Off-screen: view-frustum culling
- Occluded by other objects: occlusion culling



Back-Face Culling

Do not draw polygons facing backwards with respect to camera



A polygon is backfacing if $V \bullet N > 0$

Back-Face Culling

Avoid testing every face separately

- Cluster faces
- Precompute range of normals for each cluster
- Check cluster before testing every face





Hierarchical Back-Face Culling

Avoid testing every face separately

- Cluster faces hierarchically
- Precompute range of normals for each cluster
- Check cluster before testing every face ... hierarchically



View-Frustum Culling

Don't draw primitives outside the view frustum

- Organize primitives into clumps
- Before rendering the primitives in a clump, test their bounding volume against the view frustum



View-Frustum Culling

Hierarchical bounding volumes

• If a clump is entirely outside or entirely inside view frustum, no need to test its children



Hierarchical View-Frustum Culling

Hierarchical bounding volumes

• If a clump is entirely outside or entirely inside view frustum, no need to test its children





Hierarchical View Frustum Culling

Hierarchical bounding volumes

 If a clump is entirely outside or entirely inside view frustum, no need to test its children



Hierarchical View Frustum Culling

What shape should the bounding volumes be?

- Spheres and axis-aligned bounding boxes:
 - Simple to calculate/test
 - May be poor approximation
- Convex hulls:
 - More complex to calculate/test
 - Tighter approximation



Bounding Box (Axis-Aligned)



Bounding Sphere



Convex Hull

Uniform Grid Subdivision View Frustum

Octree Subdivision



BSP Subdivision



Occlusion Culling



Blue parts: occluders Red parts: occludees

Occlusion Culling

Object-precision

- Cells and portals
- Shadow volumes

Image-precision

- OpenGL occlusion test
- Hierarchical Z-buffer
- Hierarchical occlusion maps









Occlusion Culling

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Hierarchical Z-Buffer

Store z-buffer as pyramid and test depth hierarchically



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Pre-process

- Generate discrete set of independent levels of detail
 Run-time
 - Select level of detail according to viewpoint

Advantages

- Fairly efficient storage (2x original)
- No significant run-time overhead

Disadvantages

- Requires per-object simplification
- Not good for spatially large objects





Selecting Levels of Detail

Two possibilities:

- Guarantee quality, maximize frame rate
- Guarantee frame rate, maximize quality



Selecting Levels of Detail LOD W 3 d viewing plane r θ \mathcal{E} r Er p $w = 2d \tan(\frac{\theta}{2})$ eye



Guaranteeing Frame Rate





No Detail Elision 0.22 Seconds (19,881 Polygons) Optimization Detail Elision 0.05 Seconds (3,568 Polygons)

Guaranteeing Frame Rate





Objects Shaded by LOD (Higher LODs appear darker) **Pixel-by-Pixel Differences** (Larger differences appear brighter)

Multiresolution Meshes

Pre-process

• Generate tree of simplification operations

Run-time

Refine/coarsen current model according to viewpoint

Advantages

Allows finer control of tessellation

Disadvantages

- More run-time computation and complexity
- Difficult for retained-mode graphics

Multiresolution Meshes



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Imposters

Algorithm

- Select subset of model
- Create image of the subset
- Cull subset and replace with image

Why?

• Image displayed in (approx.) constant time

Aliaga

• Image reused for several frames

Simple Example





Simple Example





Simple Example



Aliaga

ssues



- What geometry should be replaced by images
- How should images be integrated into scene

Imposter representation

- What viewpoint(s) should be captured in image?
- How render from arbitrary viewpoints?



Imposter Placement







Portal Images





Ideal portal image would be one sampled from the current eye position



Creating Portal Images



Creating Portal Images





Summary

Visibility Culling

 Backface culling, view-frustum culling, occlusion culling, ...

Detail Elision

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Recurring Themes: Trivial reject checks Hierarchical processing