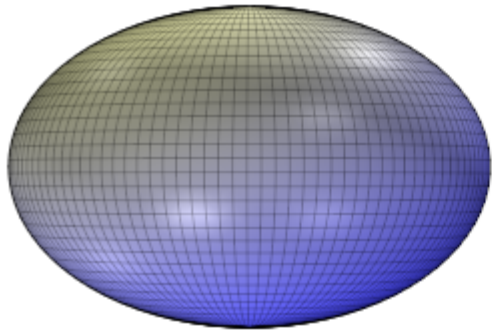


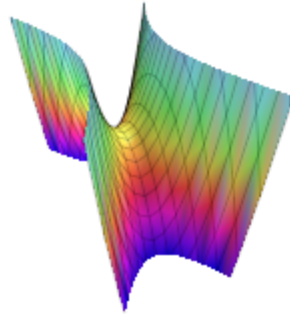
COS 426  
Computer Graphics  
Princeton University

# Ray Tracing

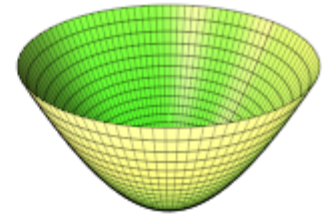
- **Ray/primitive intersection**
- Acceleration



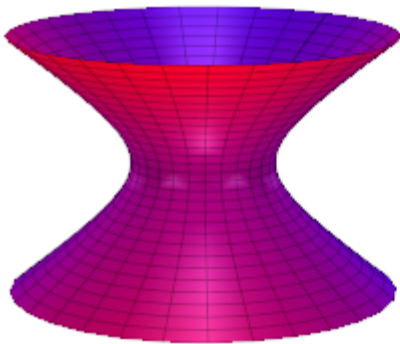
Ellipsoid



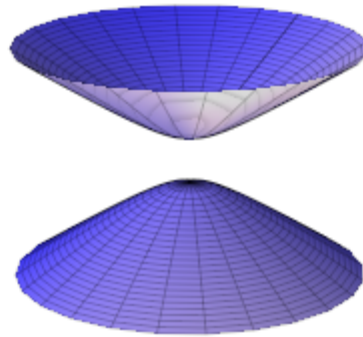
Hyperbolic paraboloid



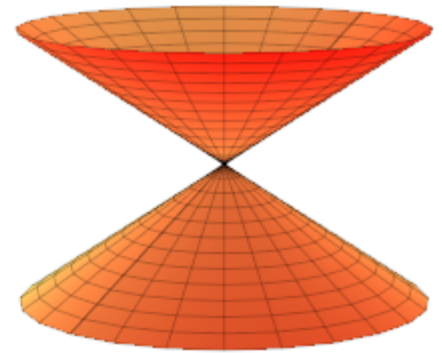
Elliptic paraboloid



Hyperboloid of one sheet

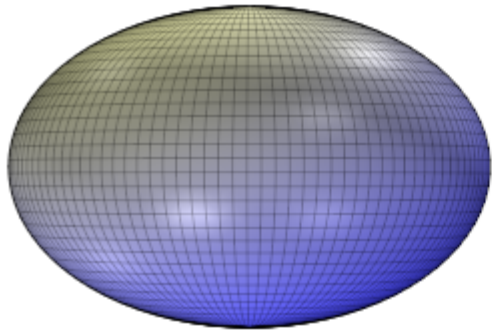


Hyperboloid of two sheets

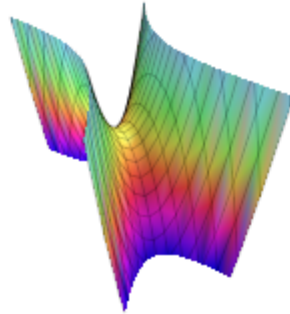


Cone

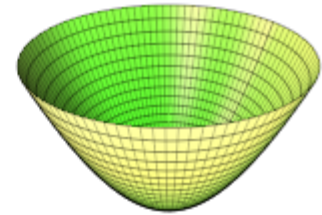
# Quadrics



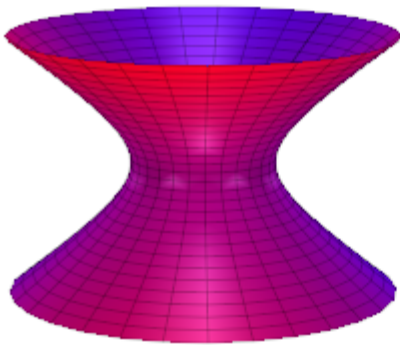
Ellipsoid



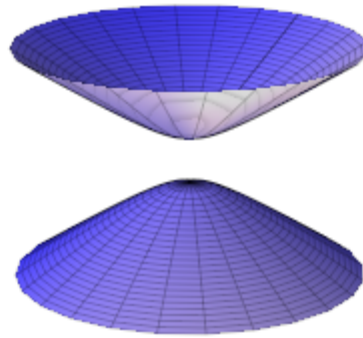
Hyperbolic paraboloid



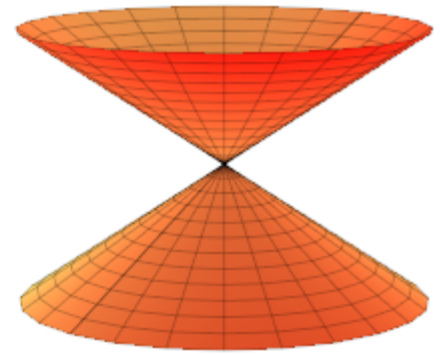
Elliptic paraboloid



Hyperboloid of one sheet

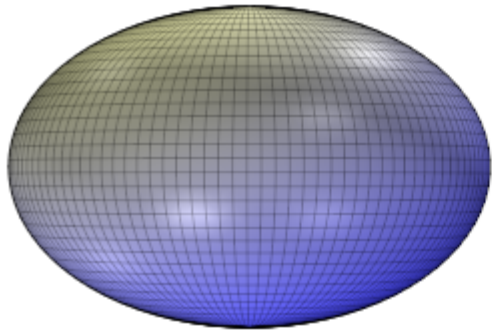


Hyperboloid of two sheets

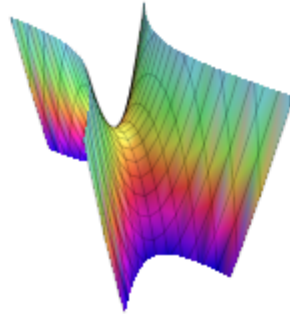


Cone

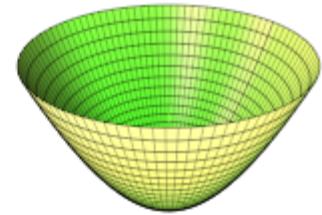
# Quadrics



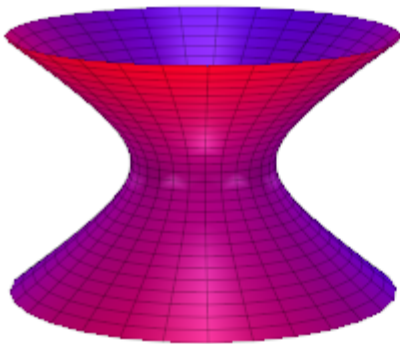
Ellipsoid



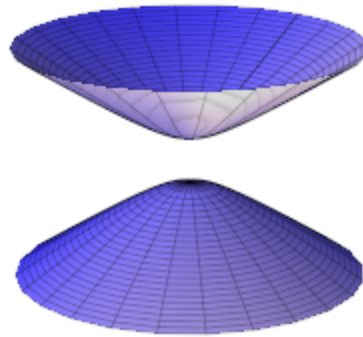
Hyperbolic paraboloid



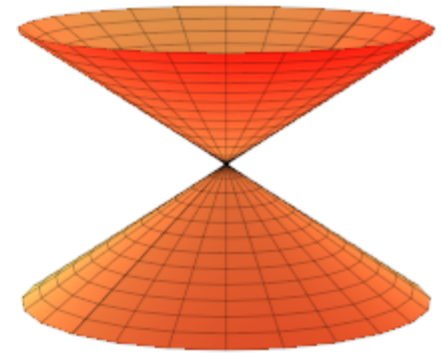
Elliptic paraboloid



Hyperboloid of one sheet



Hyperboloid of two sheets



Cone

$$Ax^2 + By^2 + Cz^2 + Dxy + Exz + Fyz + Gx + Hy + Iz + J = 0$$

# Quadratics

- Ray/primitive intersection:
  - Write down all equations
  - Solve for intersection

# Quadrics

- Ray/primitive intersection:
  - Write down all equations
  - Solve for intersection
- Quadric:

$$Ax^2 + By^2 + Cz^2 + Dxy + Exz + Fyz + Gx + Hy + Iz + J = 0$$

- Ray:
  - ???

# Quadrics

- Ray/primitive intersection:
  - Write down all equations
  - Solve for intersection
- Quadric:

$$Ax^2 + By^2 + Cz^2 + Dxy + Exz + Fyz + Gx + Hy + Iz + J = 0$$

- Ray:

$$p = p_0 + t \cdot v$$



# Quadrics

$$Ax^2 + By^2 + Cz^2 + Dxy + Exz + Fyz + Gx + Hy + Iz + J = 0$$

$$p = p_0 + t \cdot v \quad \left\{ \begin{array}{l} x = x_0 + t \cdot v_x \\ y = y_0 + t \cdot v_y \\ z = z_0 + t \cdot v_z \end{array} \right.$$

# Quadrics

$$Ax^2 + By^2 + Cz^2 + Dxy + Exz + Fyz + Gx + Hy + Iz + J = 0$$

$$p = p_0 + t \cdot v \quad \left\{ \begin{array}{l} x = x_0 + t \cdot v_x \\ y = y_0 + t \cdot v_y \\ z = z_0 + t \cdot v_z \end{array} \right.$$



$$K \cdot t^2 + L \cdot t + M = 0$$

# Quadrics

$$Ax^2 + By^2 + Cz^2 + Dxy + Exz + Fyz + Gx + Hy + Iz + J = 0$$

$$p = p_0 + t \cdot v \quad \left\{ \begin{array}{l} x = x_0 + t \cdot v_x \\ y = y_0 + t \cdot v_y \\ z = z_0 + t \cdot v_z \end{array} \right.$$



$$K \cdot t^2 + L \cdot t + M = 0$$

↙ A positive real solution exists

↓ Two complex solutions

↘ Two real negative solutions

# Quadrics

$$Ax^2 + By^2 + Cz^2 + Dxy + Exz + Fyz + Gx + Hy + Iz + J = 0$$

$$p = p_0 + t \cdot v \quad \left\{ \begin{array}{l} x = x_0 + t \cdot v_x \\ y = y_0 + t \cdot v_y \\ z = z_0 + t \cdot v_z \end{array} \right.$$



$$K \cdot t^2 + L \cdot t + M = 0$$

A positive real solution exists

Two complex solutions

Two real negative solutions

Pick smallest positive value to find intersection

Does not intersect

Does not intersect

# Quadratics

## Simpler Derivation

$$Ax^2 + By^2 + Cz^2 + Dxy + Exz + Fyz + Gx + Hy + Iz + J = 0$$

$$p = p_0 + t \cdot v$$

# Quadratics

## Simpler Derivation

$$\underline{Ax^2 + By^2 + Cz^2 + Dxy + Exz + Fyz + Gx + Hy + Iz + J = 0}$$

$$p = p_0 + t \cdot v$$

$$pQp^T + Pp^T + R = 0$$

# Quadratics

## Simpler Derivation

$$\underline{Ax^2 + By^2 + Cz^2 + Dxy + Exz + Fyz + Gx + Hy + Iz + J = 0}$$

$$p = p_0 + t \cdot v$$

$$\underbrace{pQp^T}_{3 \times 3} + \underbrace{Pp^T}_{1 \times 3} + \underbrace{R}_{1 \times 1} = 0$$

# Quadrics

## Simpler Derivation

$$\underline{Ax^2 + By^2 + Cz^2 + Dxy + Exz + Fyz + Gx + Hy + Iz + J = 0}$$

$$p = p_0 + t \cdot v$$

$$\underset{3 \times 3}{p} \underset{3 \times 3}{Q} \underset{3 \times 1}{p}^T + \underset{1 \times 3}{P} \underset{3 \times 1}{p}^T + \underset{1 \times 1}{R} = 0$$

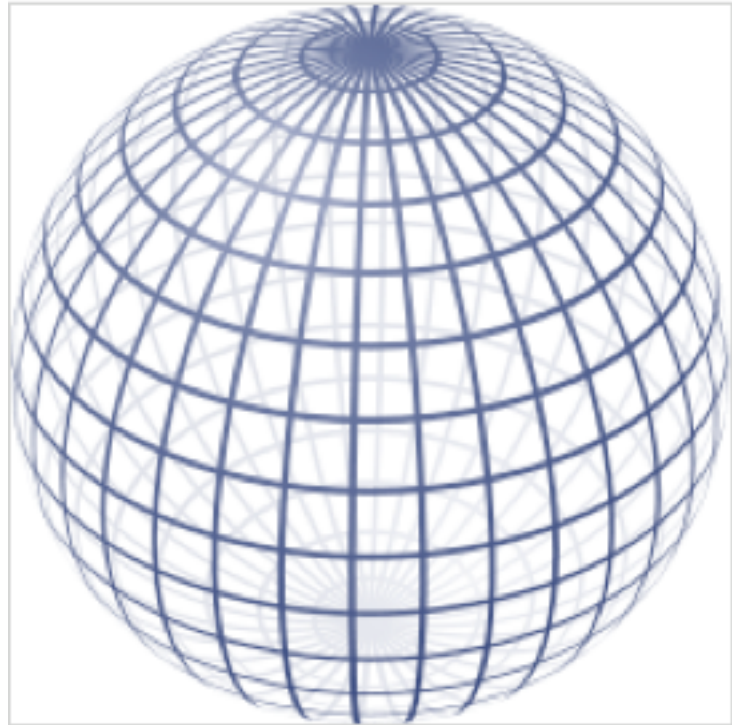
$$(p_0 + tv)Q(p_0 + tv)^T + P(p_0 + tv)^T + R = 0$$



# Quadratics

- If you use general quadric for sphere

$$pQp^T + Pp^T + R = 0$$



# Quadratics

- If you use general quadric for sphere

$$pQp^T + Pp^T + R = 0$$

- What do you need to define?

# Quadratics

- If you use general quadric for sphere

$$pQp^T + Pp^T + R = 0$$

- What do you need to define?
- Q, P, R

# Quadratics

- If you use general quadric for sphere

$$pQp^T + Pp^T + R = 0$$

– What do you need to define?

– Q, P, R

$$Q = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

# Quadratics

- If you use general quadric for sphere

$$pQp^T + Pp^T + R = 0$$

– What do you need to define?

– Q, P, R

$$Q = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$P = \begin{bmatrix} 0 & 0 & 0 \end{bmatrix}$$

# Quadratics

- If you use general quadric for sphere

$$pQp^T + Pp^T + R = 0$$

– What do you need to define?

– Q, P, R

$$Q = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R = -r^2$$

$$P = \begin{bmatrix} 0 & 0 & 0 \end{bmatrix}$$

# Ray Tracing

- Ray/primitive intersection
- **Acceleration**

# Acceleration

- **Bounding Volume**
- Generate Structure (e.g. octree)
- Traverse Structure



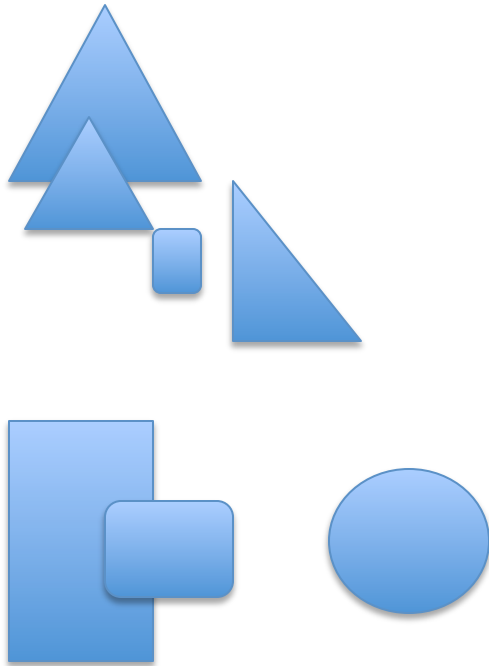
# Bounding Volume

- Bounding sphere
- Axis-aligned bounding box (AABB)
- Oriented bounding box (OBB)
- Bounding volume hierarchy

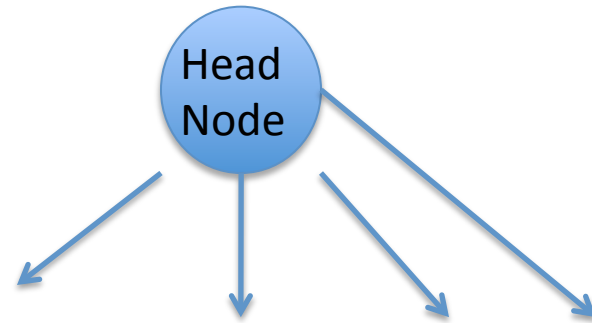
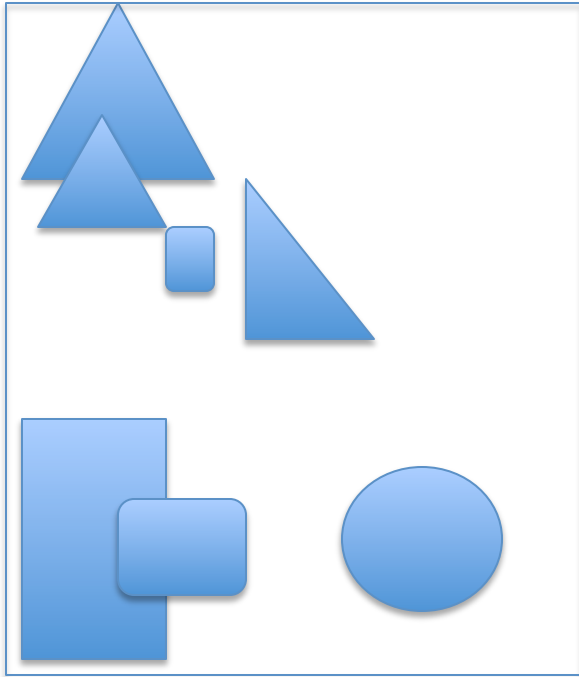
# Acceleration

- **Generate Structure (e.g. octree)**
- Traverse Structure

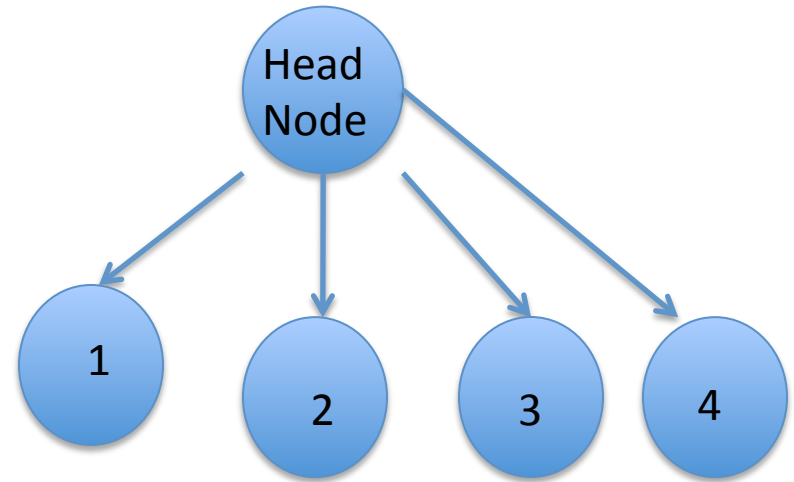
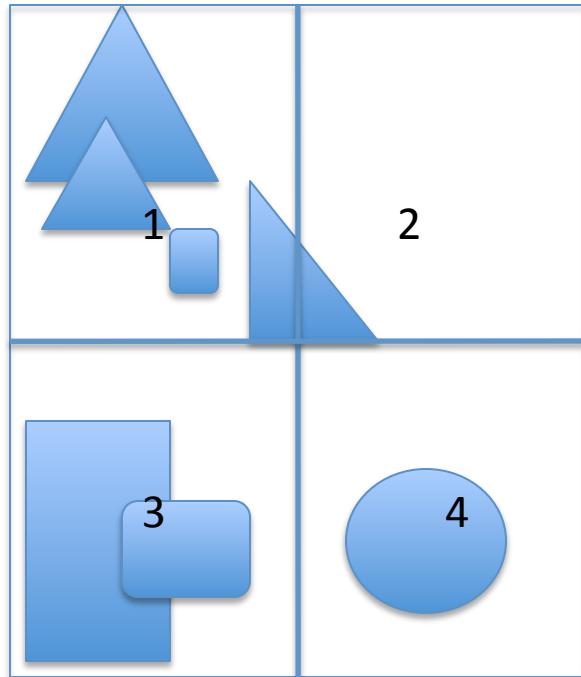
# Acceleration



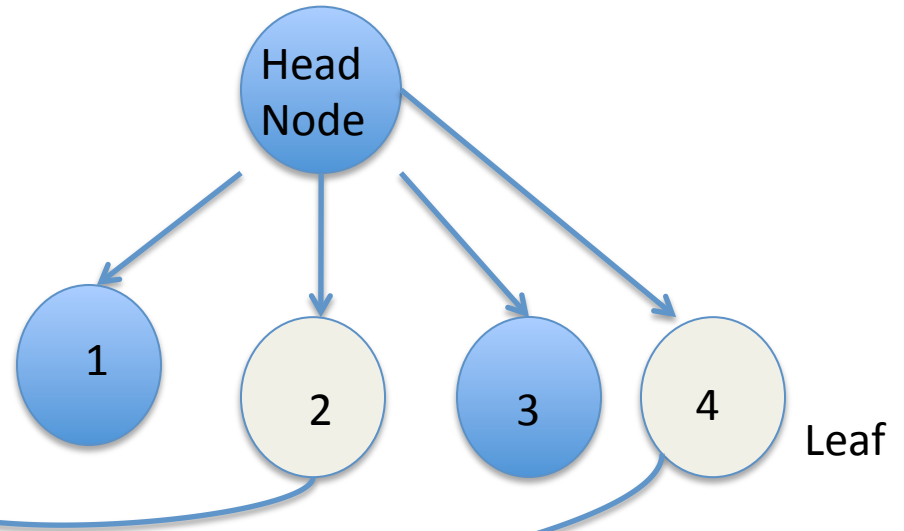
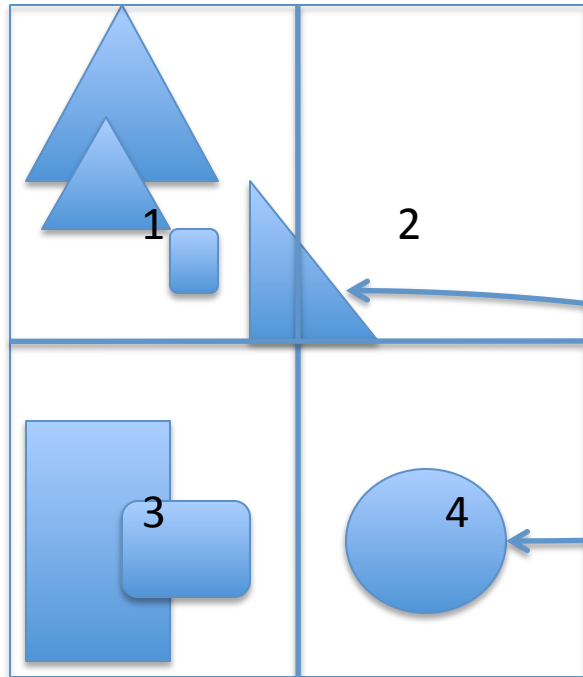
# Acceleration



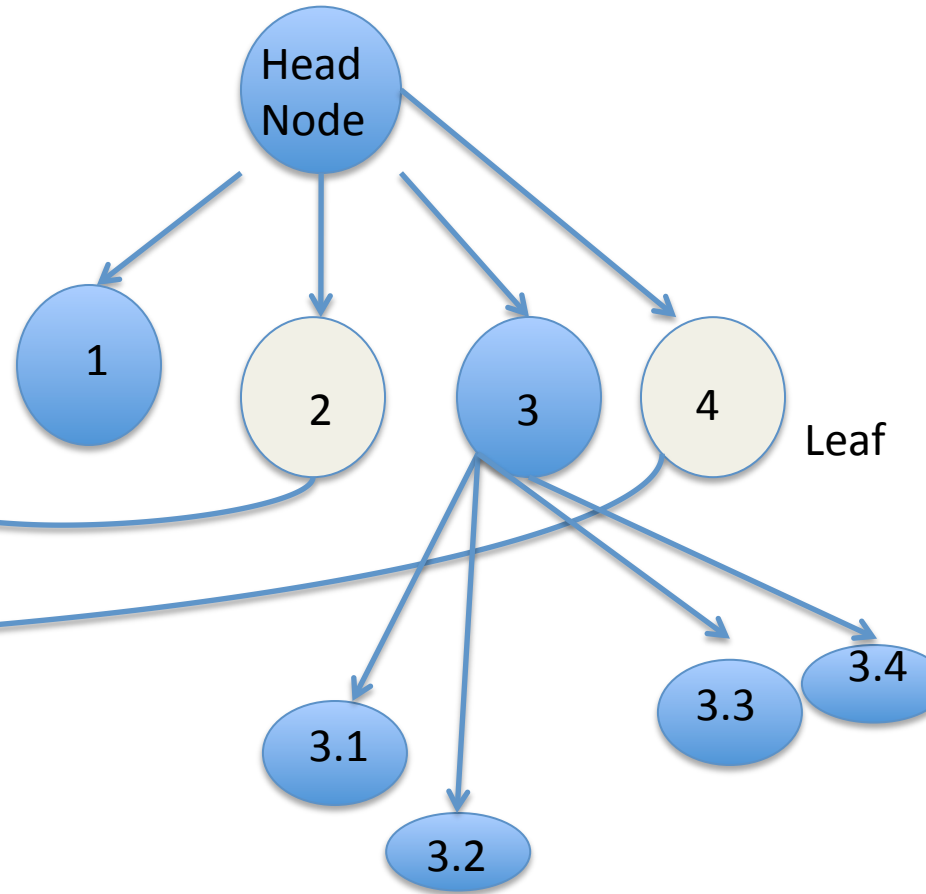
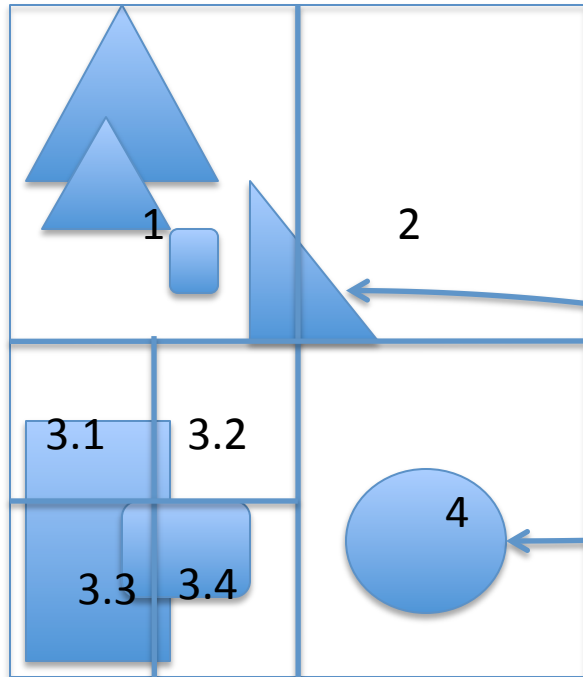
# Acceleration



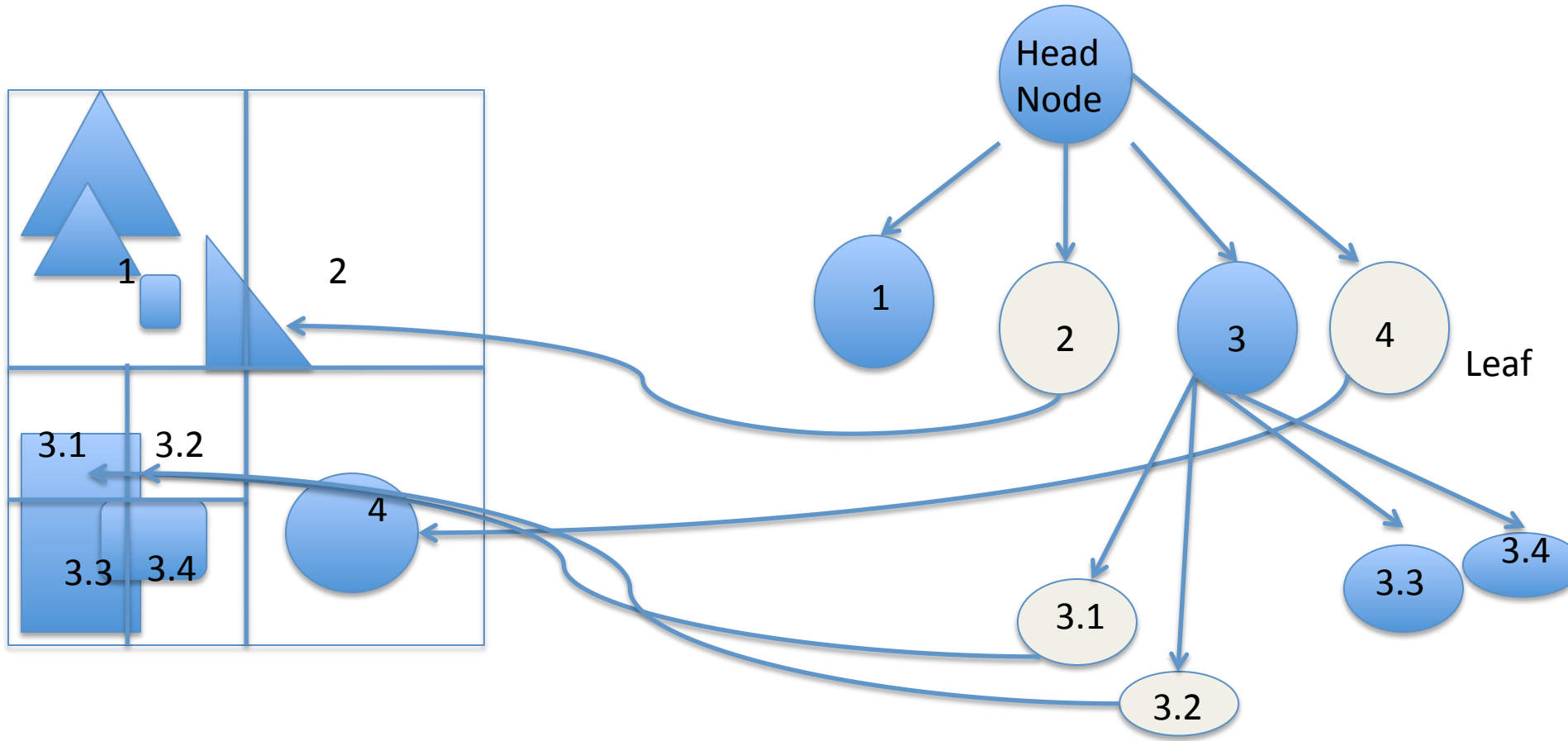
# Acceleration



# Acceleration

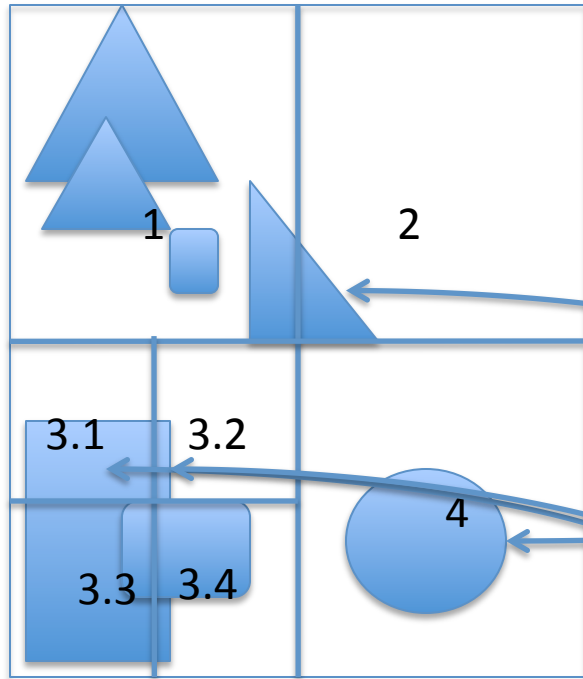


# Acceleration

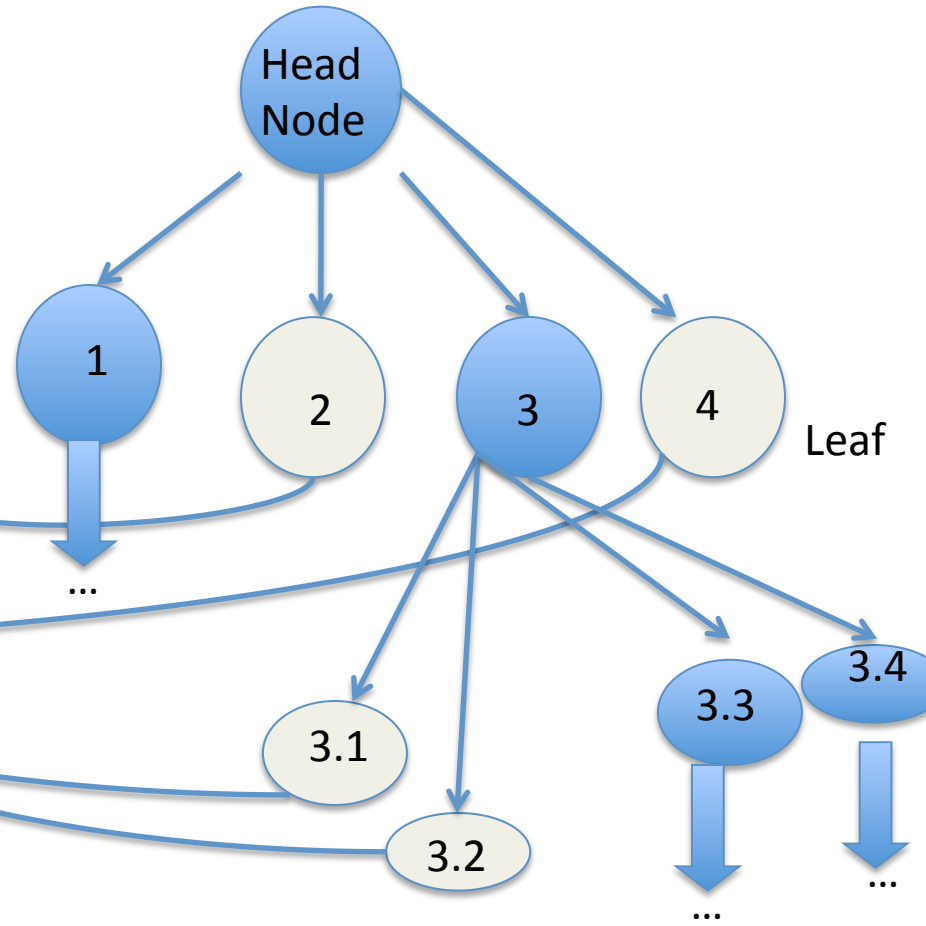




# Acceleration



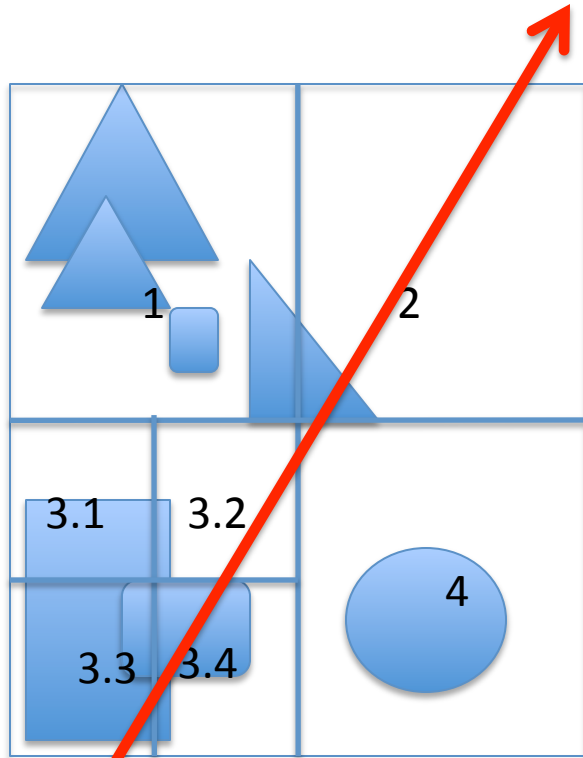
When do we stop?



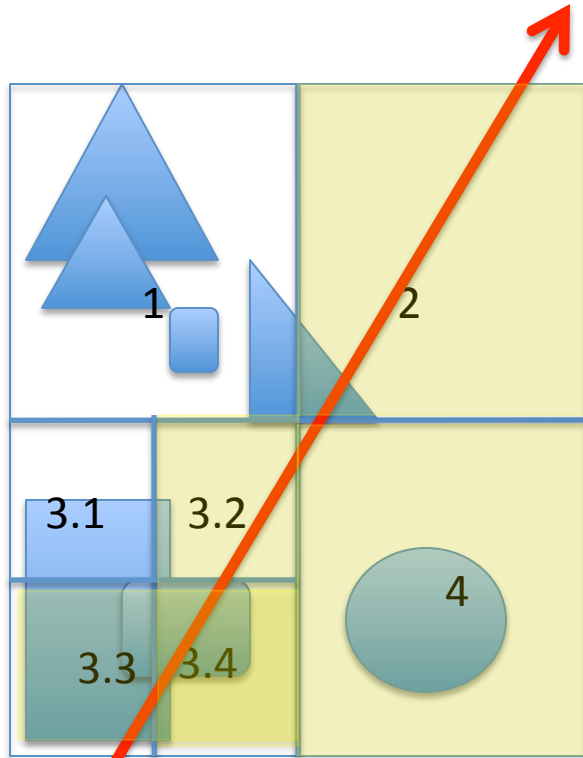
# Acceleration

- Generate Structure (e.g. octree)
- **Traverse Structure**

# Acceleration



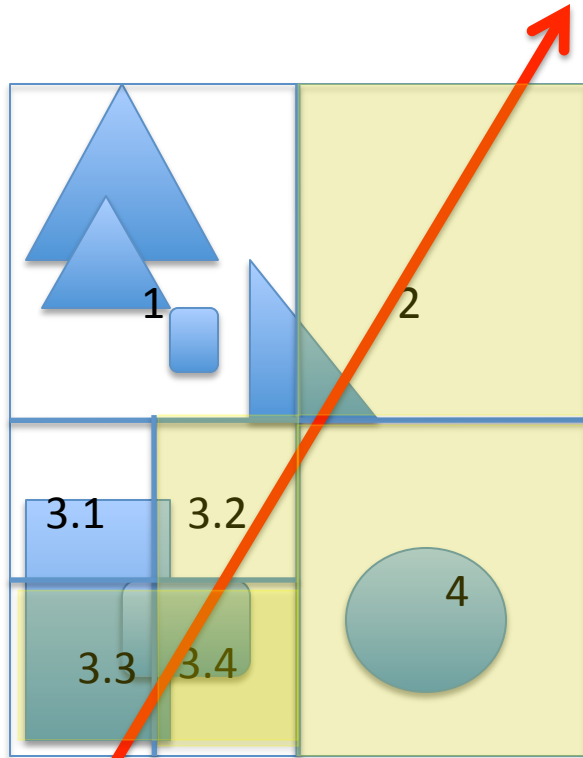
# Acceleration



ORDER: 3.3, 3.4, 3.2, 2

If a ray intersected something in 3.3,  
can it intersect something (with a smaller  $t$ )  
in a later node?

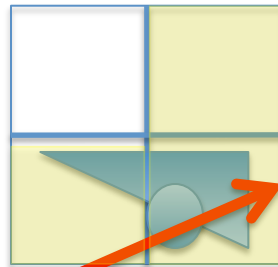
# Acceleration



ORDER: 3.3, 3.4, 3.2, 2

If a ray intersected something in 3.3,  
can it intersect something (with a smaller  $t$ )  
in a later node?

Think about objects on boundaries.



Example: should intersect the circle,  
but the triangle is visited first

The End

Questions?