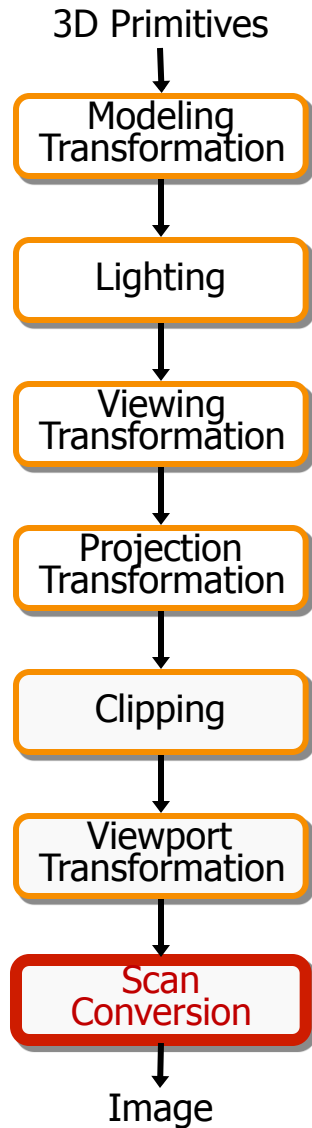




# 3D Rasterization II

COS 426

# 3D Rendering Pipeline (for direct illumination)





# Rasterization

- Scan conversion
  - Determine which pixels to fill
- Shading
  - Determine a color for each filled pixel
- Texture mapping
  - Describe shading variation within polygon interiors
- Visible surface determination
  - Figure out which surface is front-most at every pixel

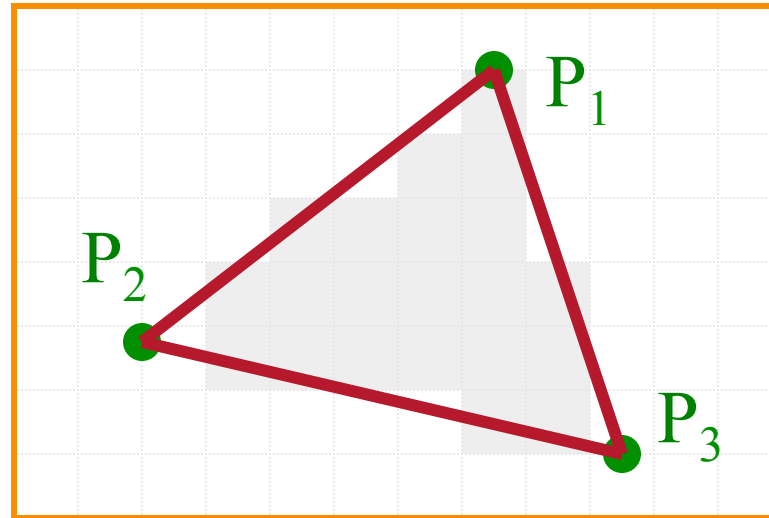


# Rasterization

- Scan conversion (last time)
  - Determine which pixels to fill
- **Shading**
  - Determine a color for each filled pixel
- Texture mapping
  - Describe shading variation within polygon interiors
- Visible surface determination
  - Figure out which surface is front-most at every pixel

# Shading

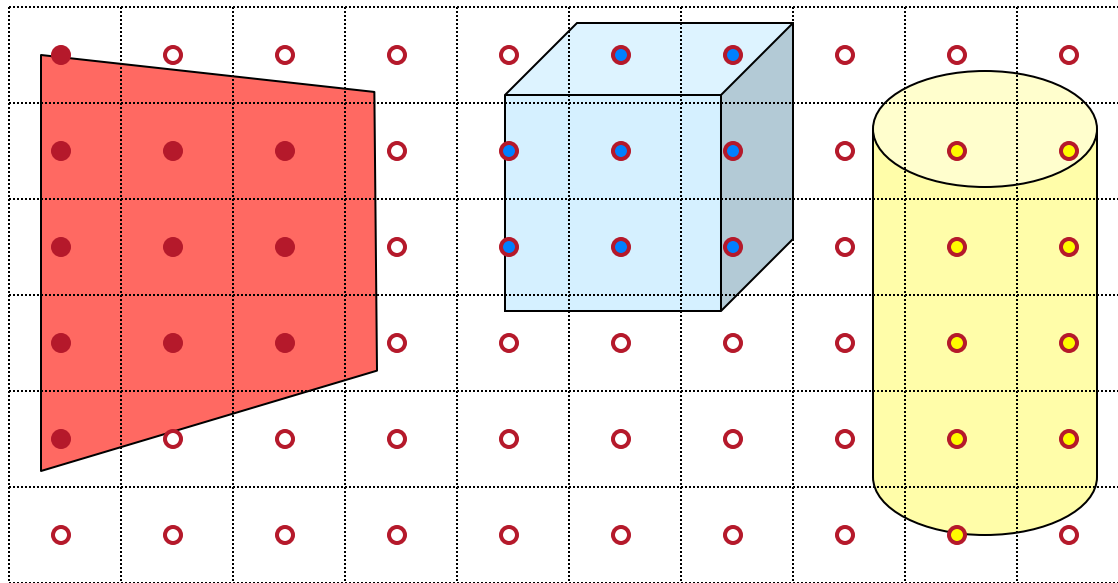
- How do we choose a color for each filled pixel?



Emphasis on methods that can be implemented in hardware

# Ray Casting

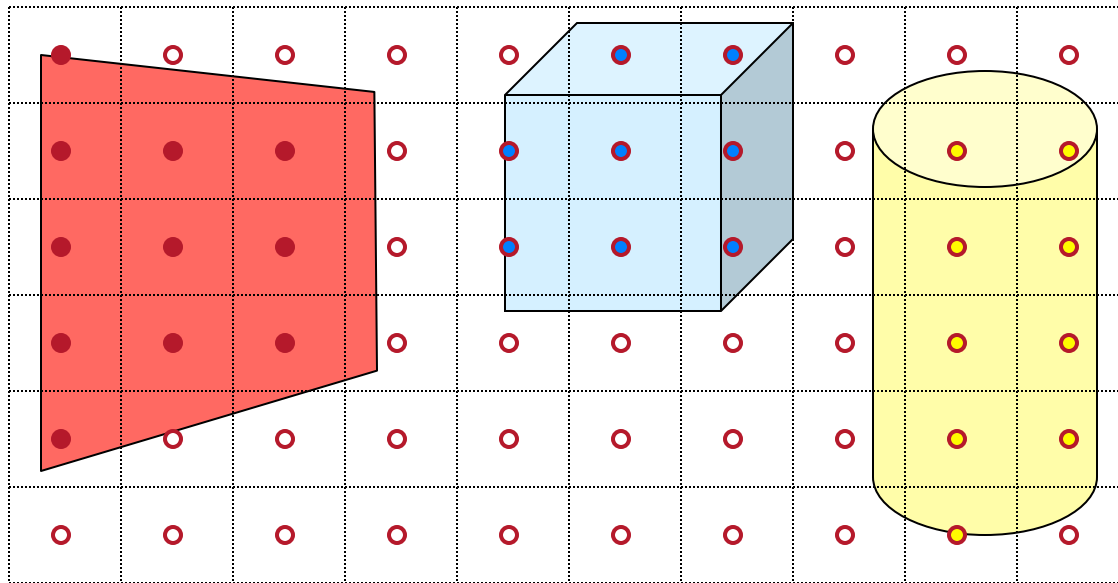
- Simplest shading approach is to perform independent lighting calculation for every pixel



$$I = I_E + K_A I_{AL} + \sum_i \left( K_D (N \cdot L_i) I_i + K_S (V \cdot R_i)^n I_i \right)$$

# Polygon Shading

- Can take advantage of spatial coherence
  - Illumination calculations for pixels covered by same primitive are related to each other



$$I = I_E + K_A I_{AL} + \sum_i \left( K_D (N \cdot L_i) I_i + K_S (V \cdot R_i)^n I_i \right)$$

# Polygon Shading Algorithms

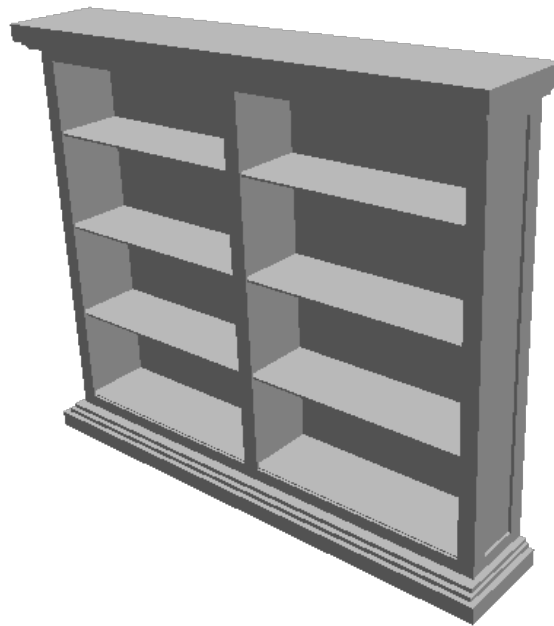


- **Flat Shading**
- Gouraud Shading
- Phong Shading



# Flat Shading

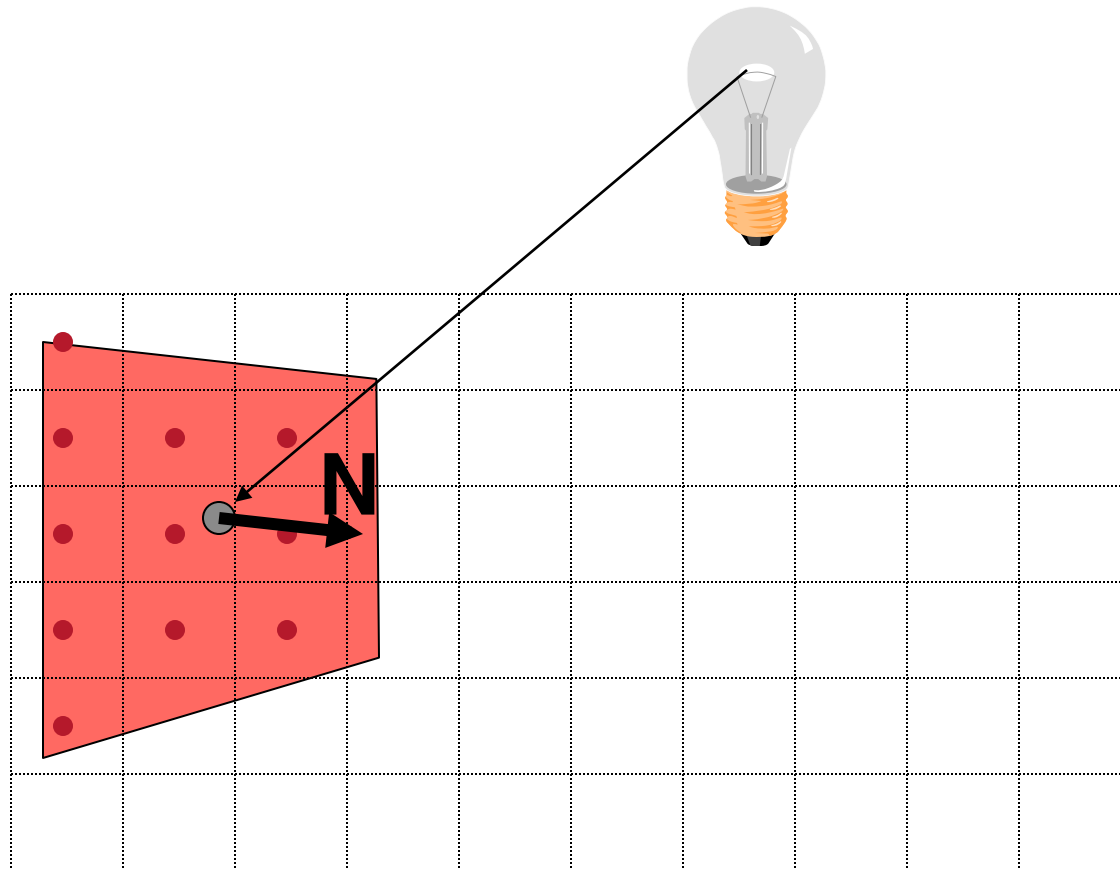
- What if a faceted object is illuminated only by directional light sources and is either diffuse or viewed from infinitely far away



$$I = I_E + K_A I_{AL} + \sum_i \left( K_D (N \cdot L_i) I_i + K_S (V \cdot R_i)^n I_i \right)$$

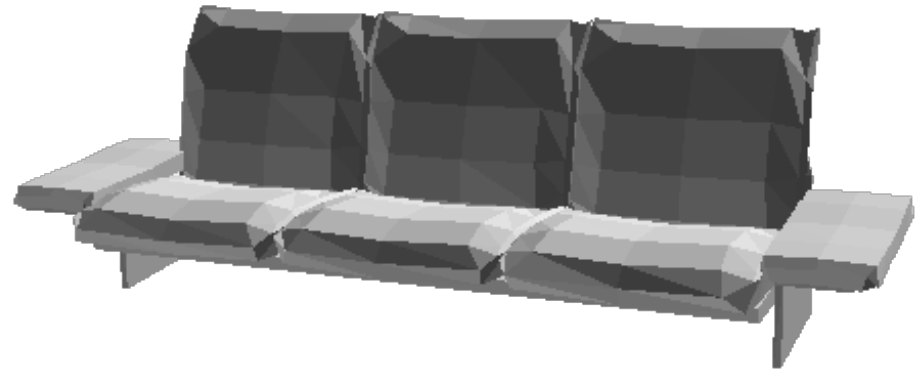
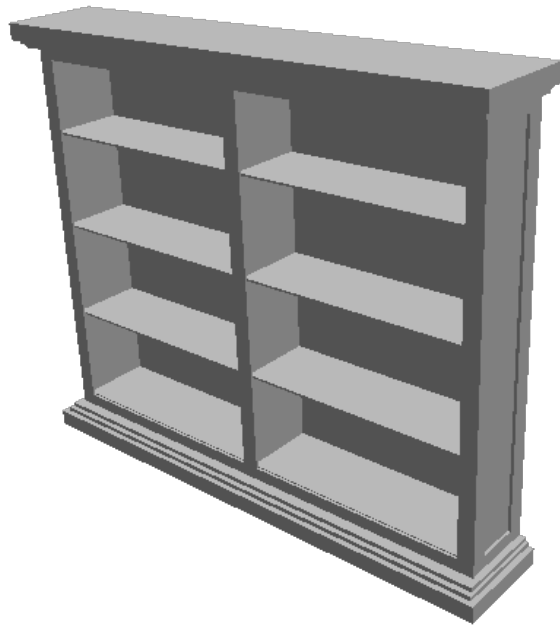
# Flat Shading

- One illumination calculation per polygon
  - Assign all pixels inside each polygon the same color



# Flat Shading

- Objects look like they are composed of polygons
  - OK for polyhedral objects
  - Not so good for smooth surfaces



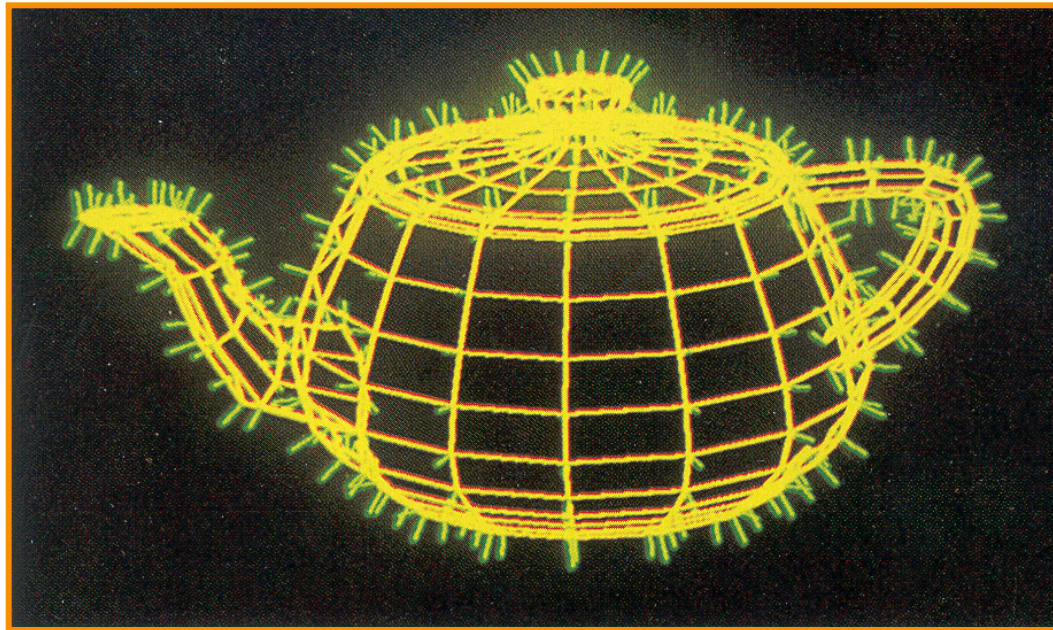
# Polygon Shading Algorithms



- Flat Shading
- **Gouraud Shading**
- Phong Shading

# Gouraud Shading

- What if smooth surface is represented by polygonal mesh with a normal at each vertex?

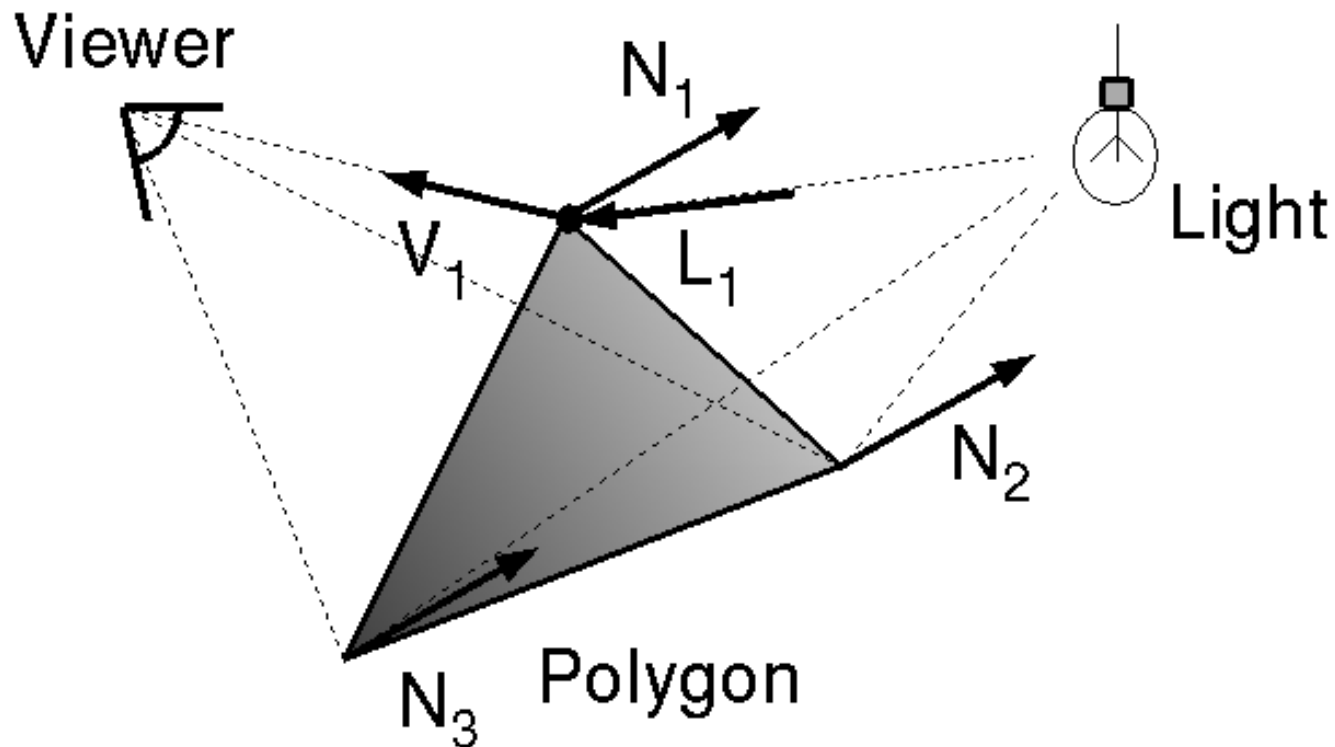


Watt Plate 7

$$I = I_E + K_A I_{AL} + \sum_i \left( K_D (N \cdot L_i) I_i + K_S (V \cdot R_i)^n I_i \right)$$

# Gouraud Shading

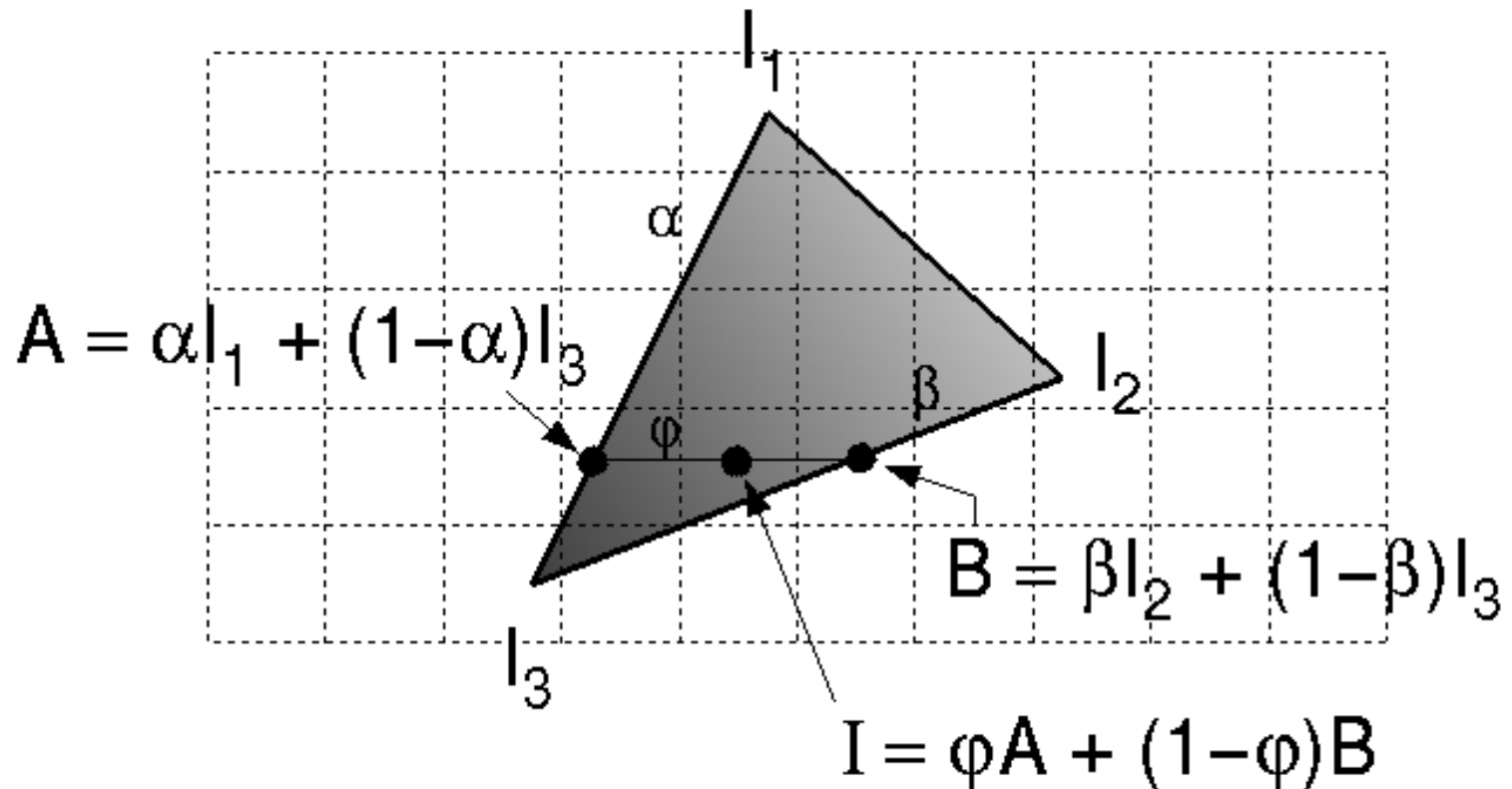
- Method 1: One lighting calculation per vertex
  - Assign pixels inside polygon by interpolating colors computed at vertices





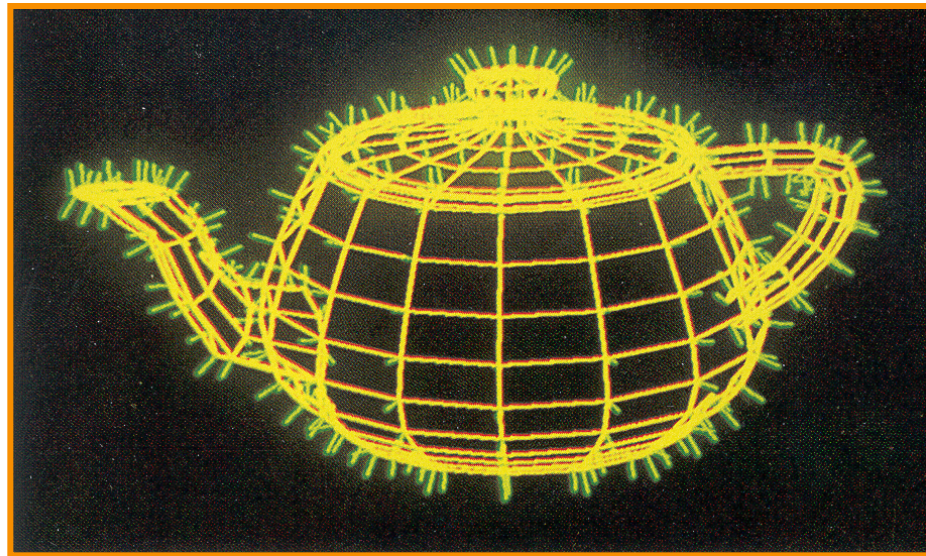
# Gouraud Shading

- Bilinearly interpolate colors at vertices down and across scan lines



# Gouraud Shading

- Smooth shading over adjacent polygons
  - Curved surfaces
  - Illumination highlights
  - Soft shadows



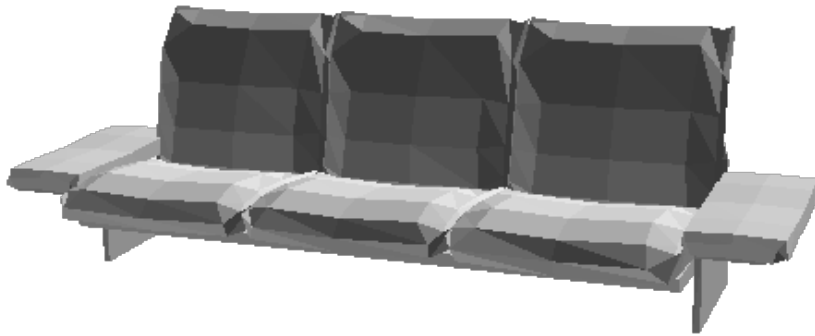
Mesh with shared normals at vertices



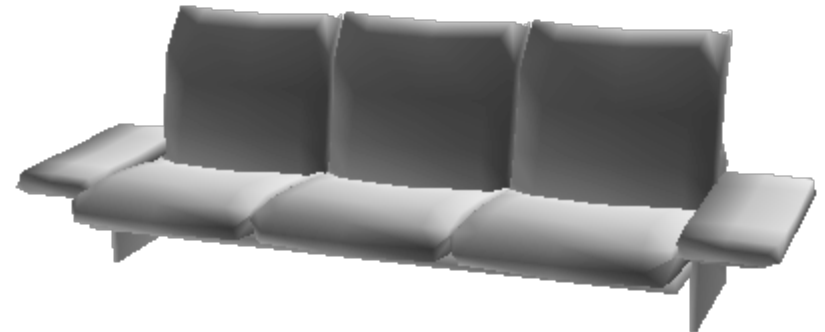
# Gouraud Shading



- Produces smoothly shaded polygonal mesh
  - Piecewise linear approximation
  - Need fine mesh to capture subtle lighting effects



Flat Shading



Gouraud Shading

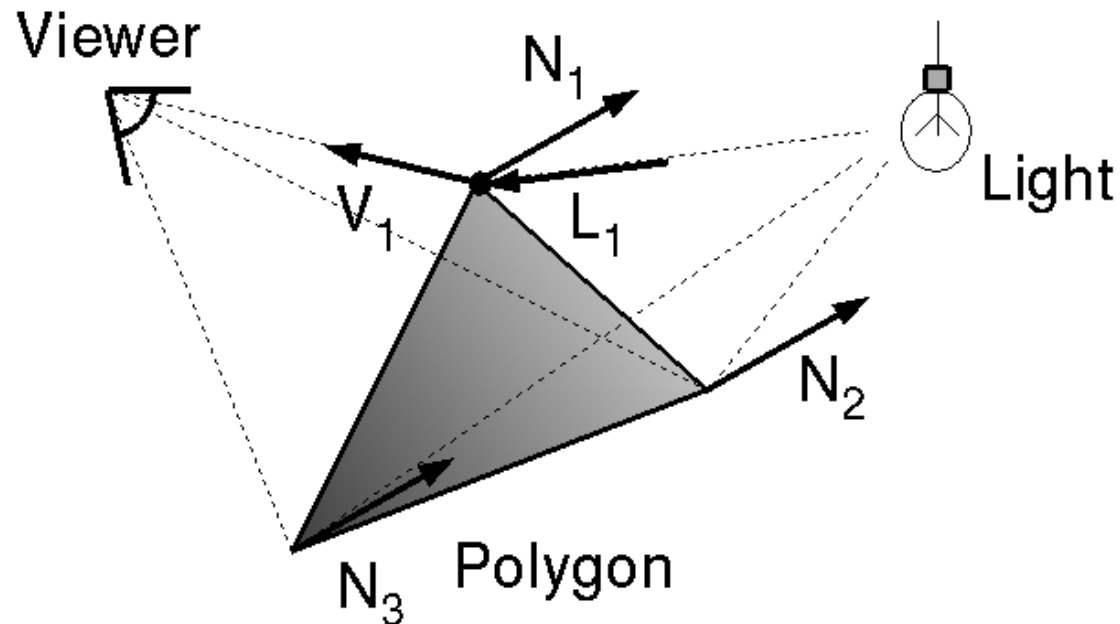
# Polygon Shading Algorithms



- Flat Shading
- Gouraud Shading
- **Phong Shading** ( $\neq$  Phong reflectance model)

# Phong Shading

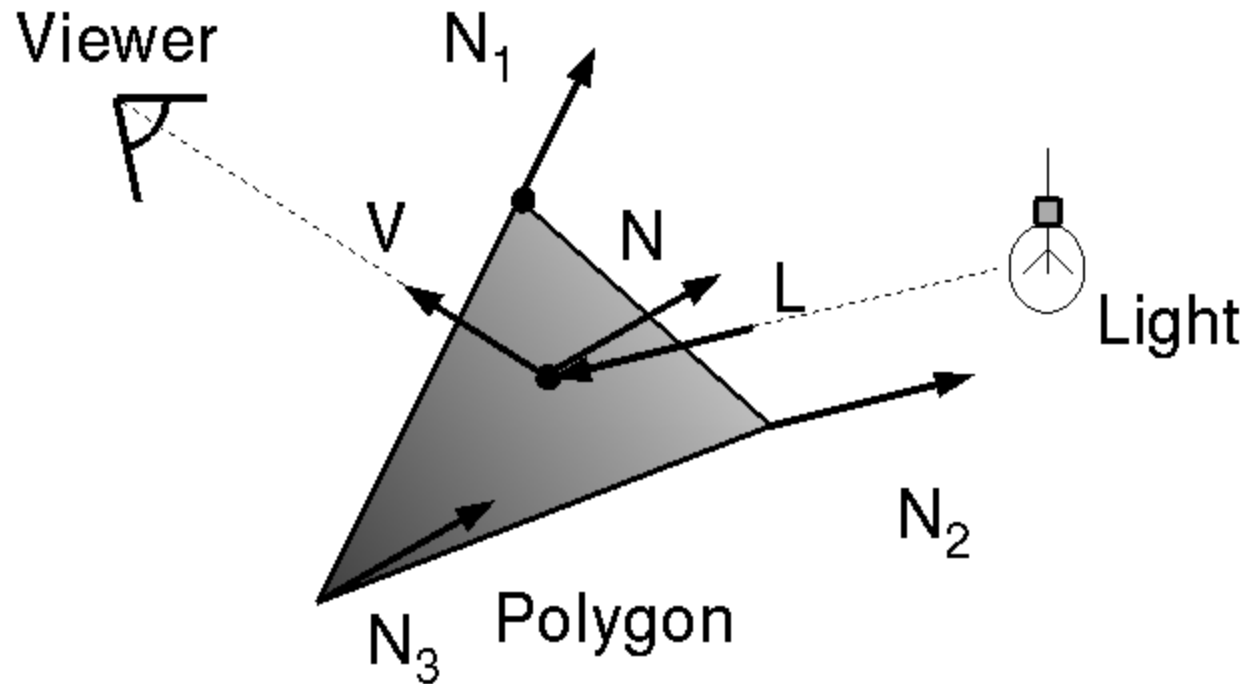
- What if polygonal mesh is too coarse to capture illumination effects in polygon interiors?



$$I = I_E + K_A I_{AL} + \sum_i \left( K_D (N \cdot L_i) I_i + K_S (V \cdot R_i)^n I_i \right)$$

# Phong Shading

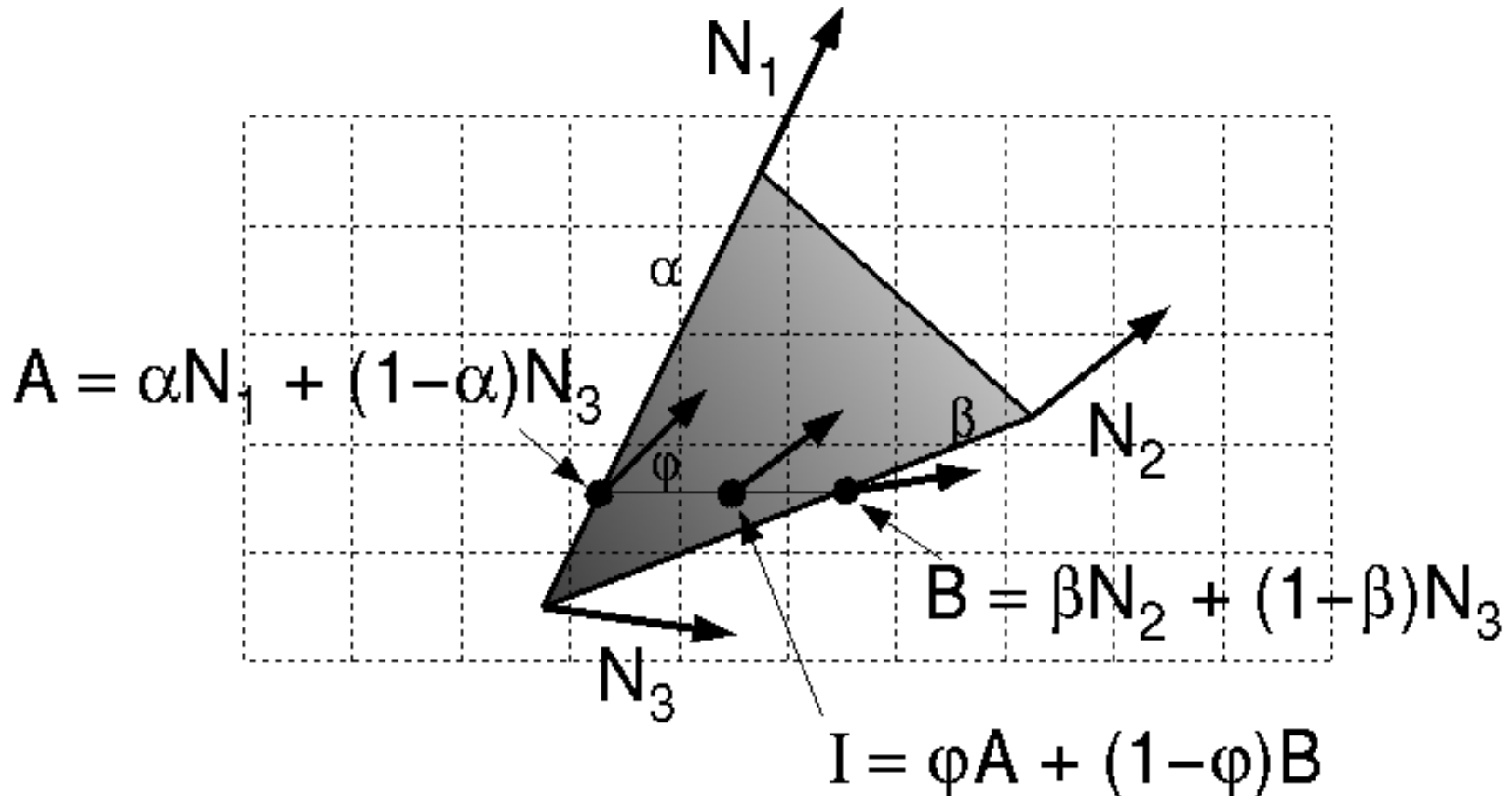
- One lighting calculation per pixel
  - Approximate surface normals for points inside polygons by bilinear interpolation of normals from vertices





# Phong Shading

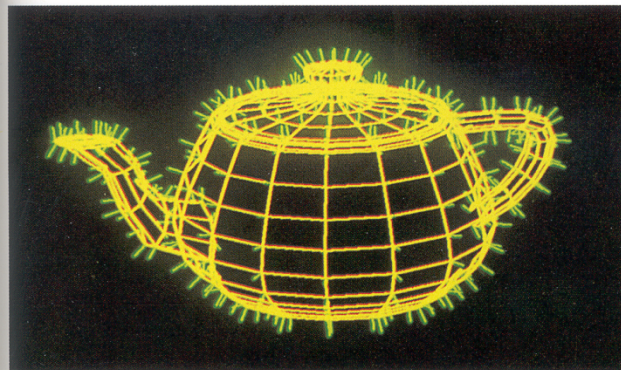
- Bilinearly interpolate surface normals at vertices down and across scan lines



# Polygon Shading Algorithms



Wireframe



Flat



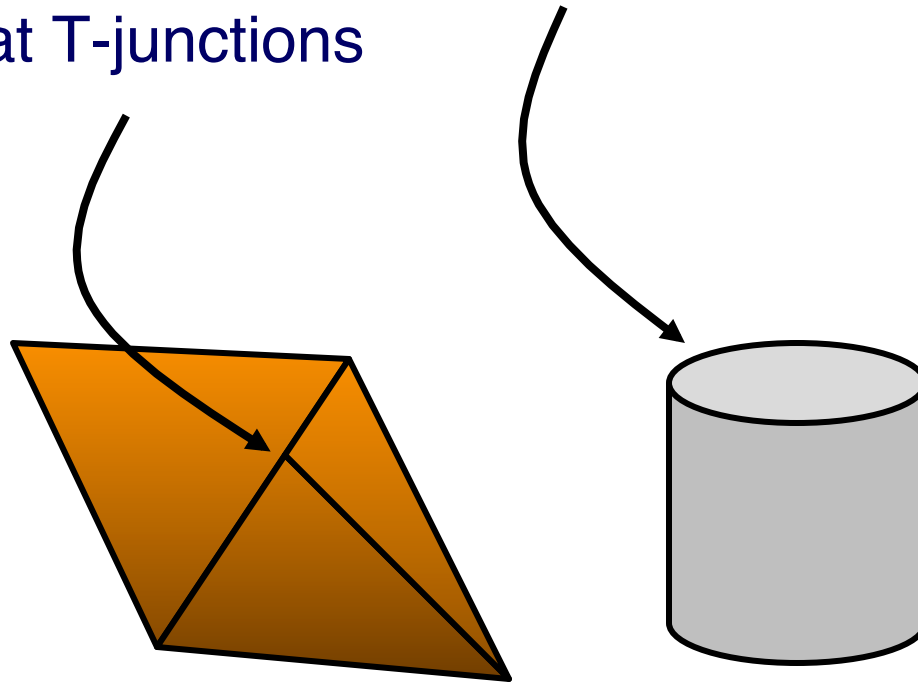
Gouraud



Phong

# Shading Issues

- Problems with interpolated shading:
  - Polygonal silhouettes
  - Perspective distortion (due to screen-space interpolation)
  - Problems computing shared vertex normals
  - Problems at T-junctions





# Rasterization

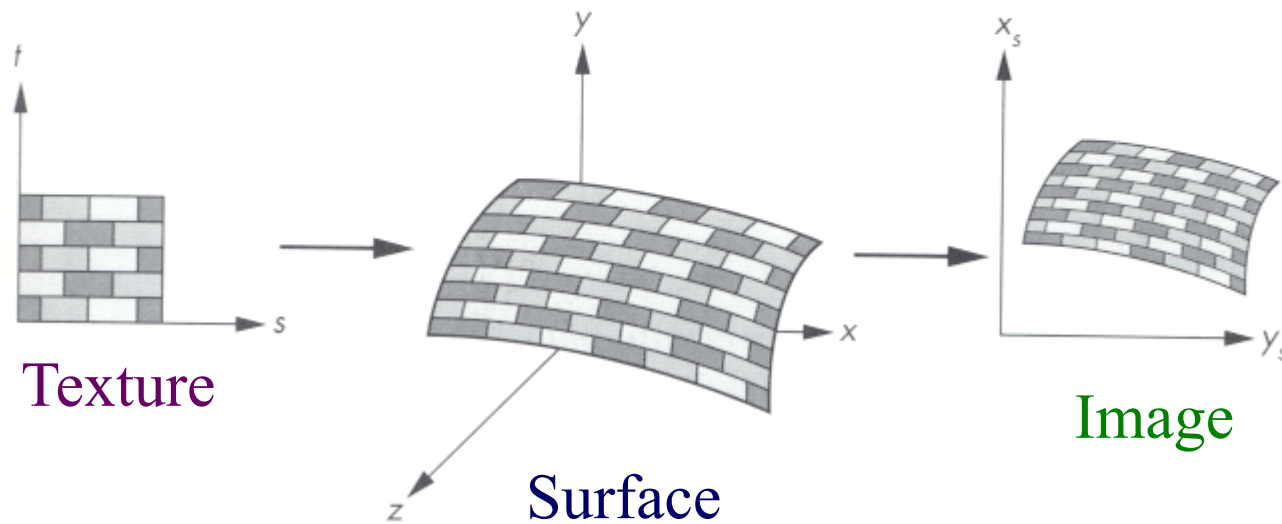
- Scan conversion
  - Determine which pixels to fill
- Shading
  - Determine a color for each filled pixel
- **Texture mapping**
  - Describe shading variation within polygon interiors
- Visible surface determination
  - Figure out which surface is front-most at every pixel



# Textures



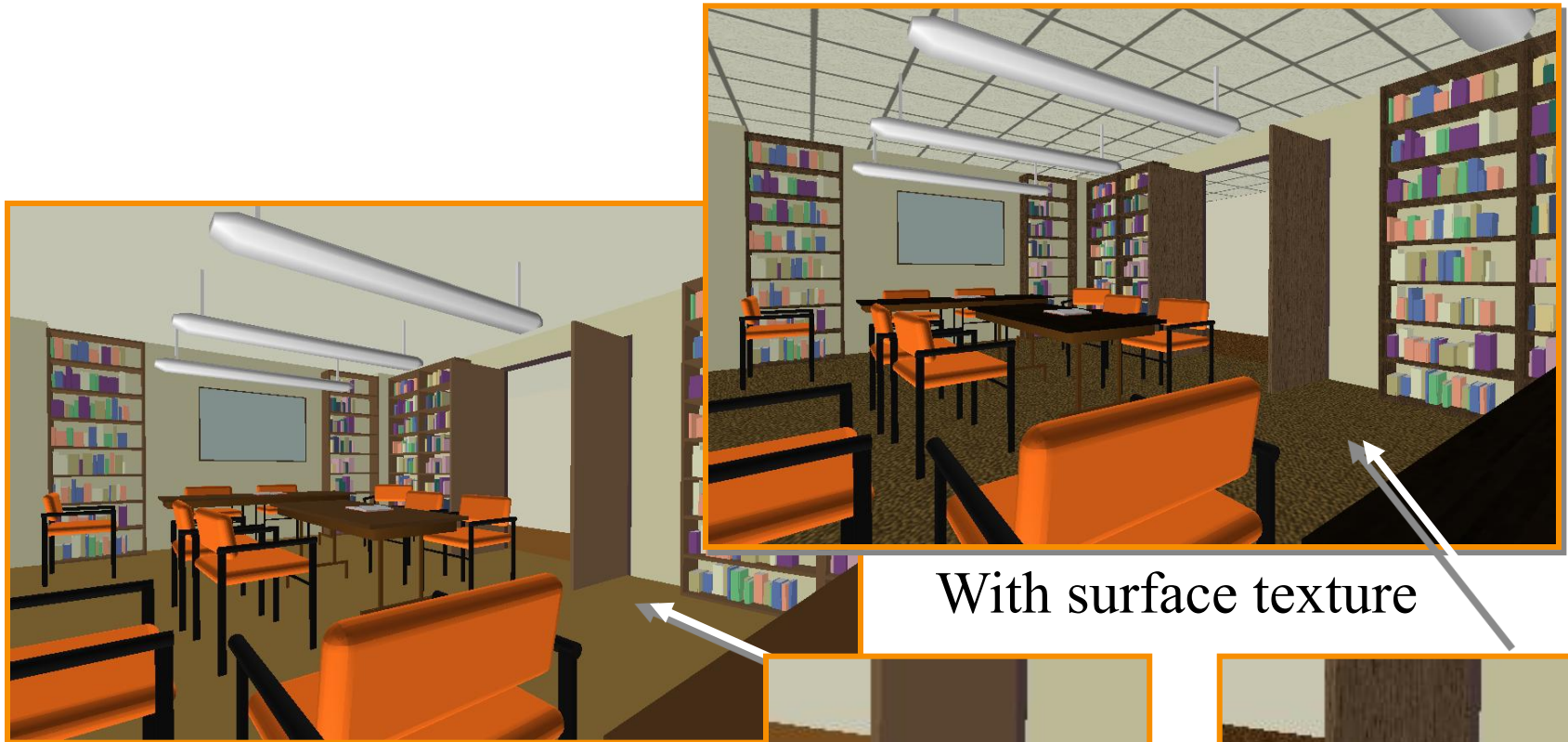
- Describe color variation in interior of 3D polygon
  - When scan converting a polygon, vary pixel colors according to values fetched from a texture image



# Surface Textures



- Add visual detail to surfaces of 3D objects



With surface texture

Polygonal model



# Surface Textures



- Add visual detail to surfaces of 3D objects



[Daren Horley]

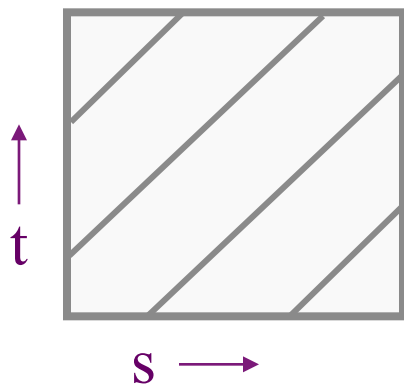


# Texture Mapping Overview

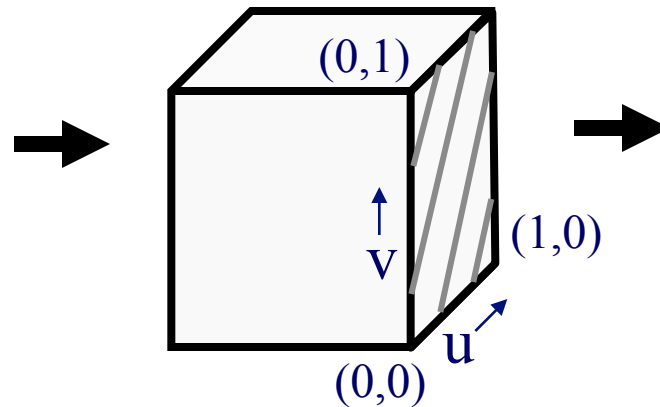
- Texture mapping stages
  - Parameterization
  - Mapping
  - Filtering
- Texture mapping applications
  - Modulation textures
  - Illumination mapping
  - Bump mapping
  - Environment mapping
  - Image-based rendering
  - Non-photorealistic rendering

# Texture Mapping

- Steps:
  - Define texture
  - Specify mapping from texture to surface
  - Look up texture values during scan conversion



Texture  
Coordinate  
System



Modeling  
Coordinate  
System

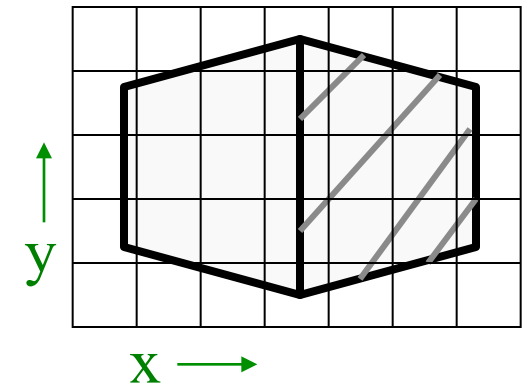
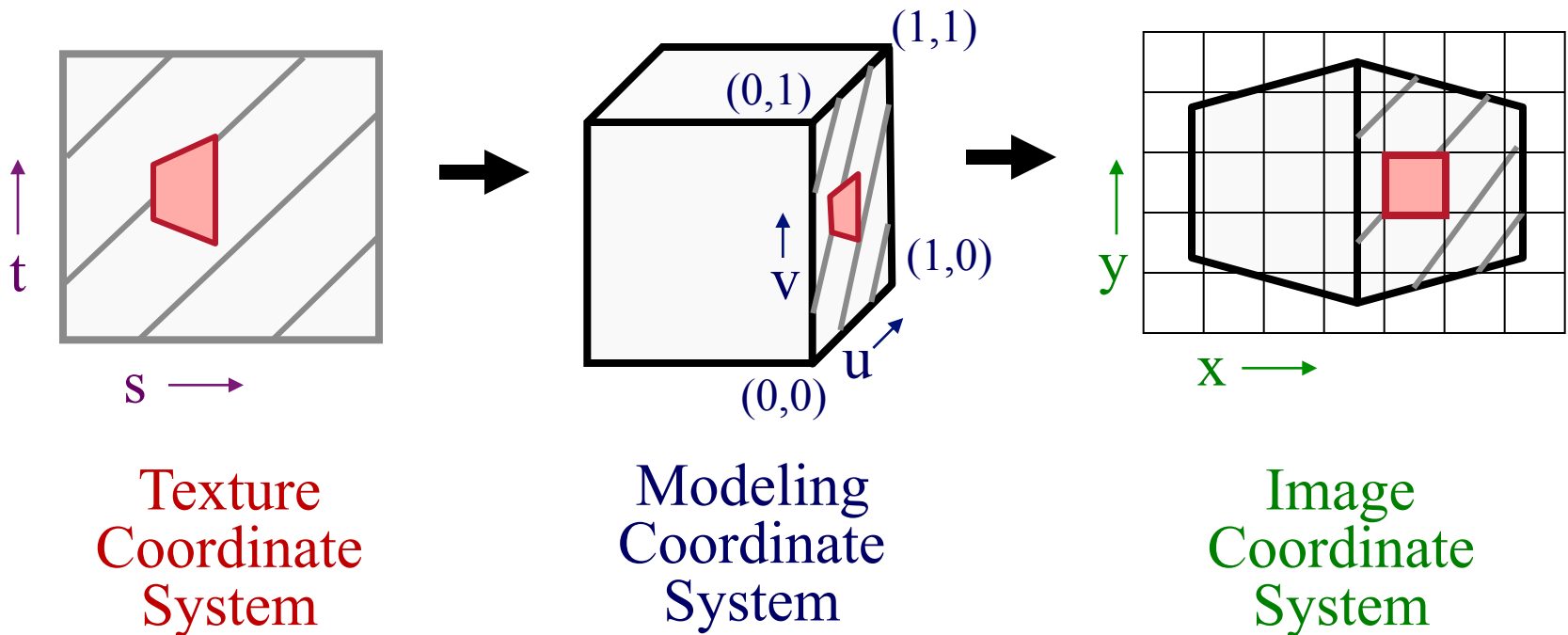


Image  
Coordinate  
System

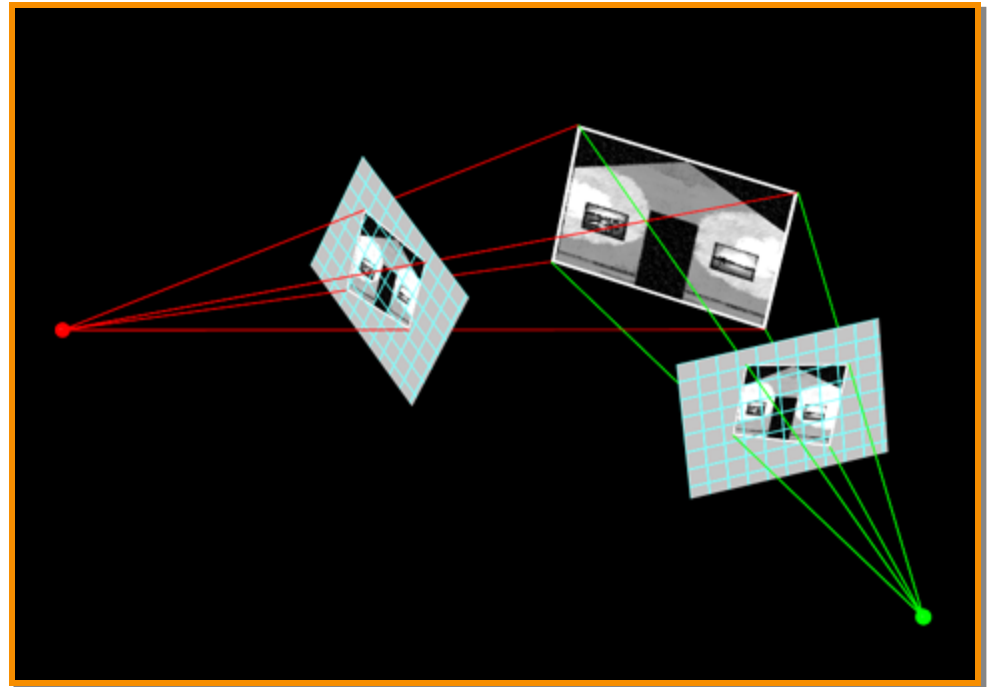
# Texture Mapping

- When scan converting, map from ...
  - image coordinate system  $(x,y)$  to
  - modeling coordinate system  $(u,v)$  to
  - texture image  $(s,t)$



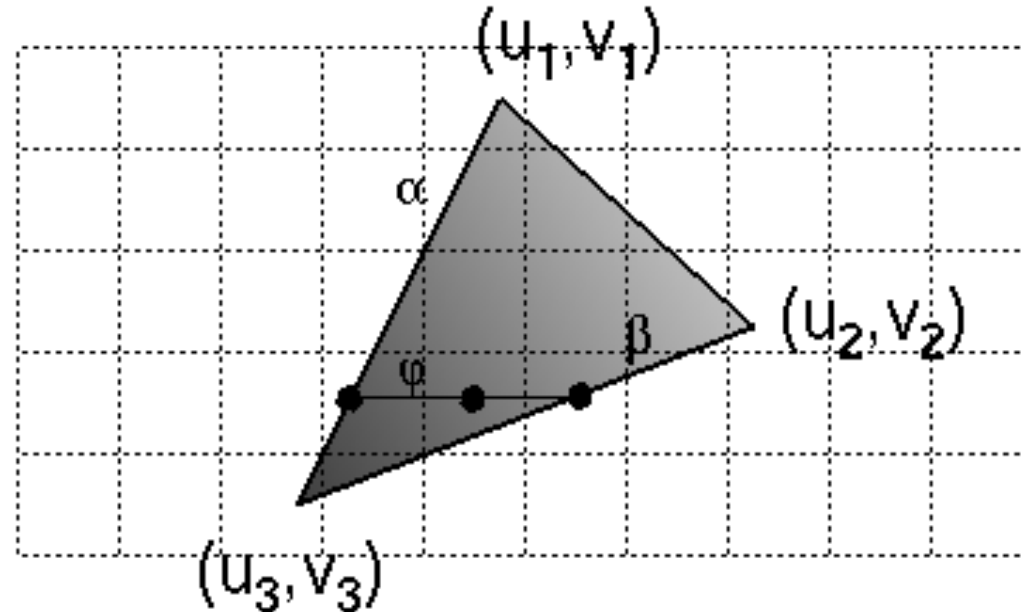
# Texture Mapping

- Texture mapping is a 2D projective transformation
  - texture coordinate system:  $(s,t)$  to
  - image coordinate system  $(x,y)$



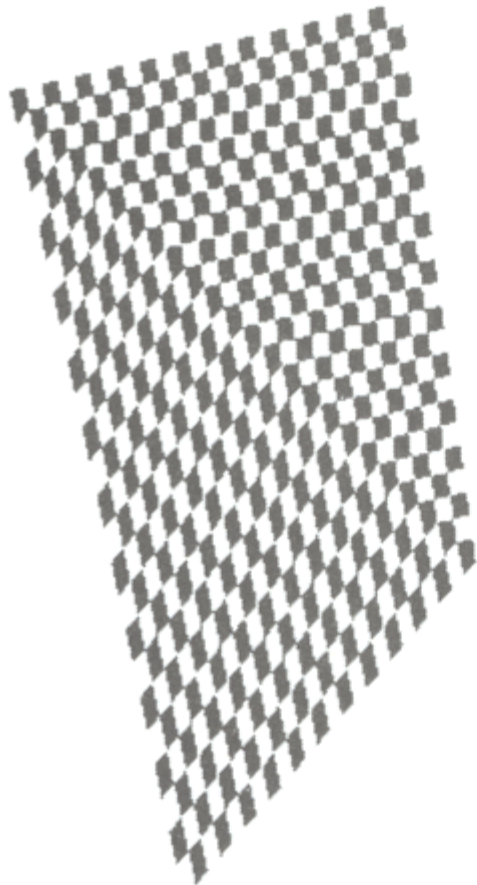
# Texture Mapping

- Scan conversion
  - Interpolate texture coordinates down/across scan lines
  - Distortion due to bilinear interpolation approximation
    - » Cut polygons into smaller ones, or
    - » Perspective divide at each pixel

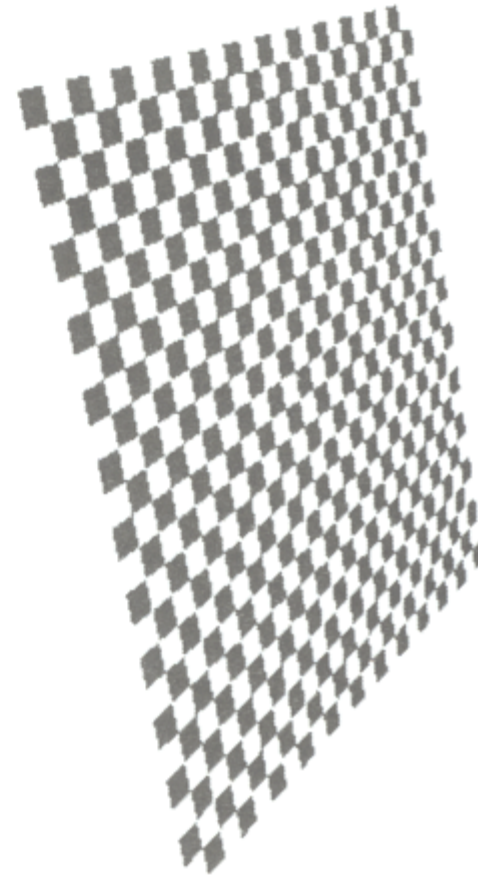




# Texture Mapping



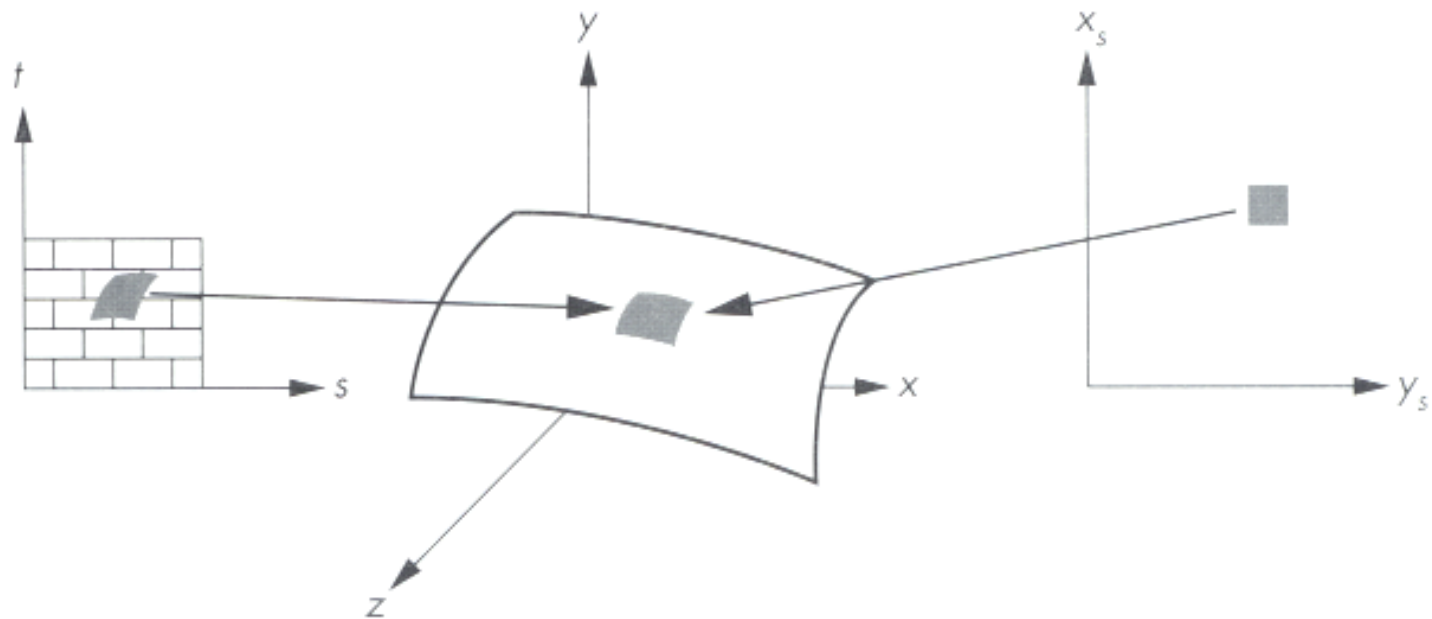
Linear interpolation  
of texture coordinates



Correct interpolation  
with perspective divide

# Texture Filtering

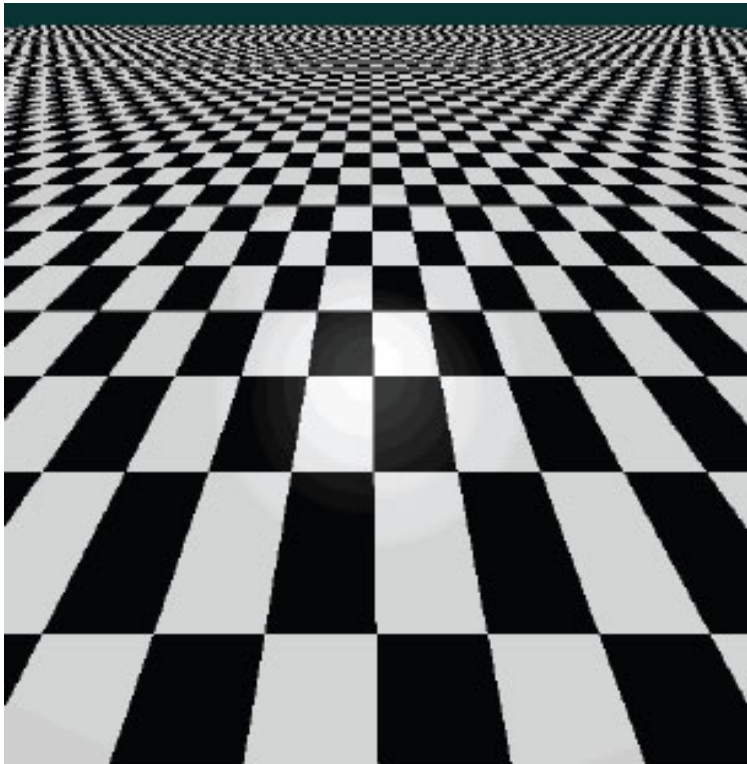
- Must **sample** texture to determine color at each pixel in image



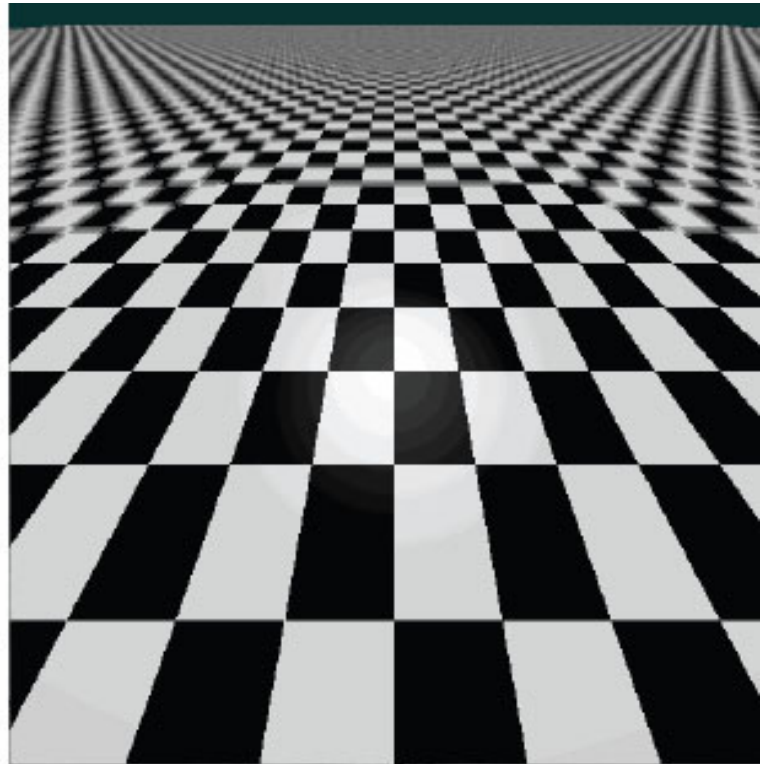
# Texture Filtering



- Aliasing is a problem



Point sampling

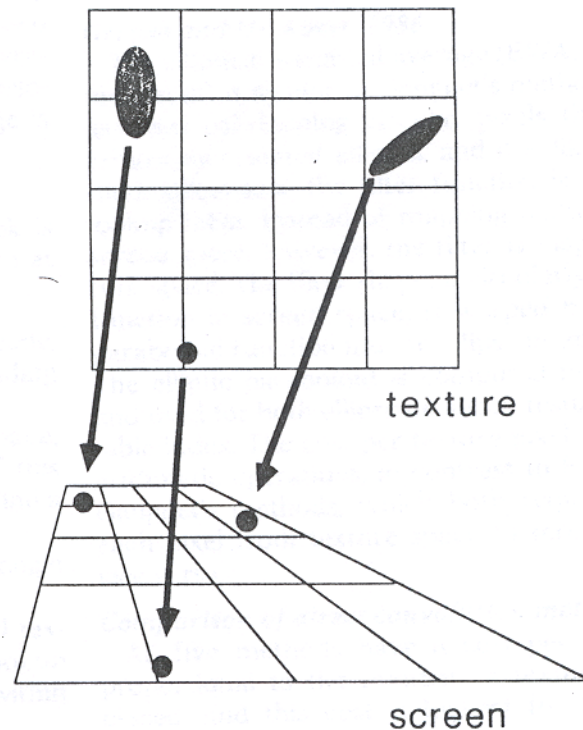


Area filtering

# Texture Filtering



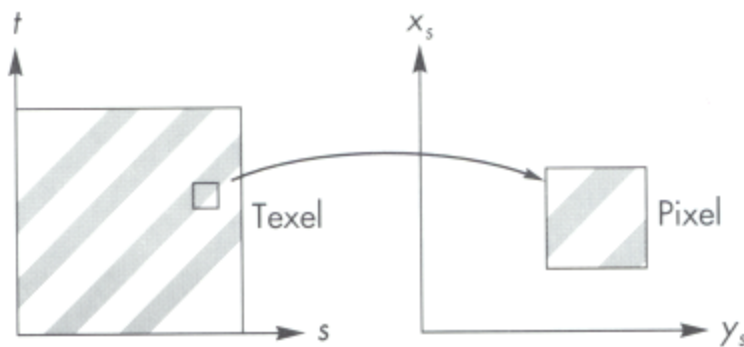
- Ideally, use elliptically shaped convolution filters



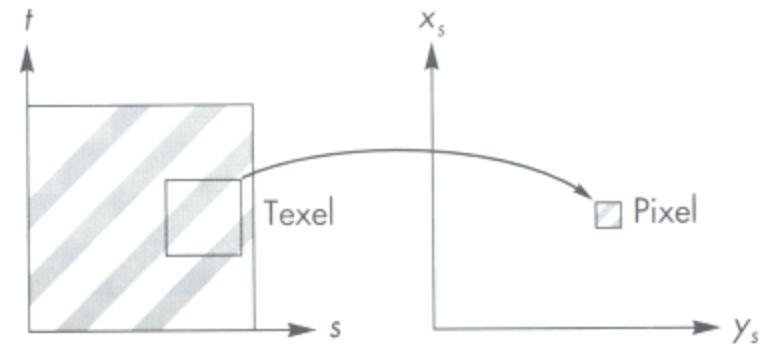
In practice, use rectangles or squares

# Texture Filtering

- Size of filter depends on projective warp
  - Compute prefiltered images to avoid run-time cost
    - » Mipmaps
    - » Summed area tables



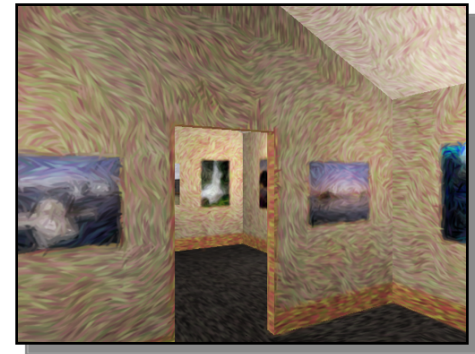
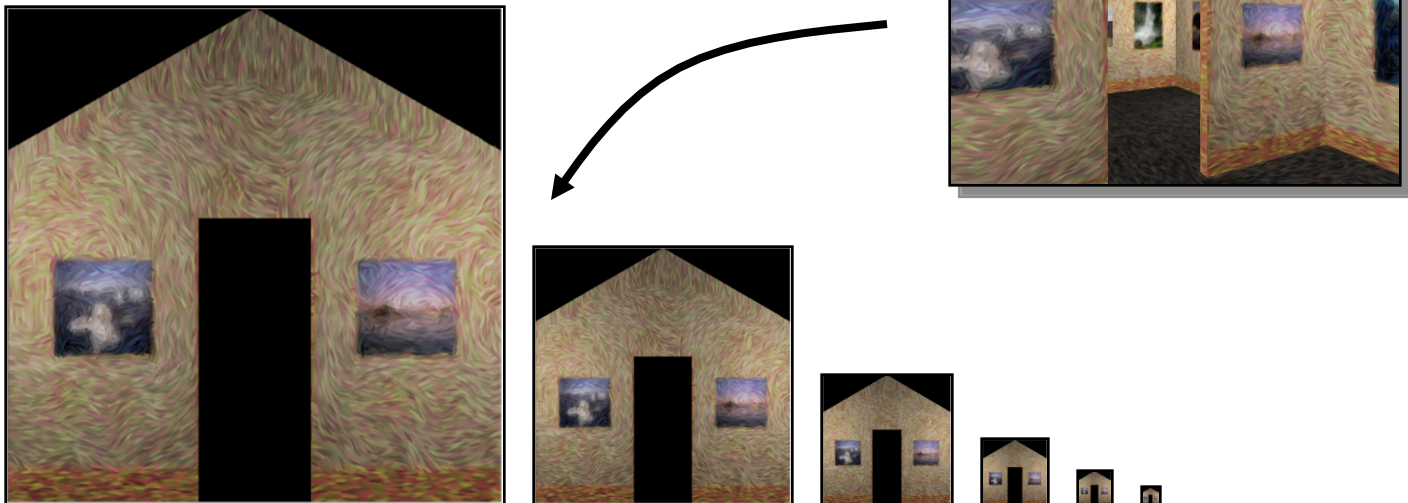
Magnification



Minification

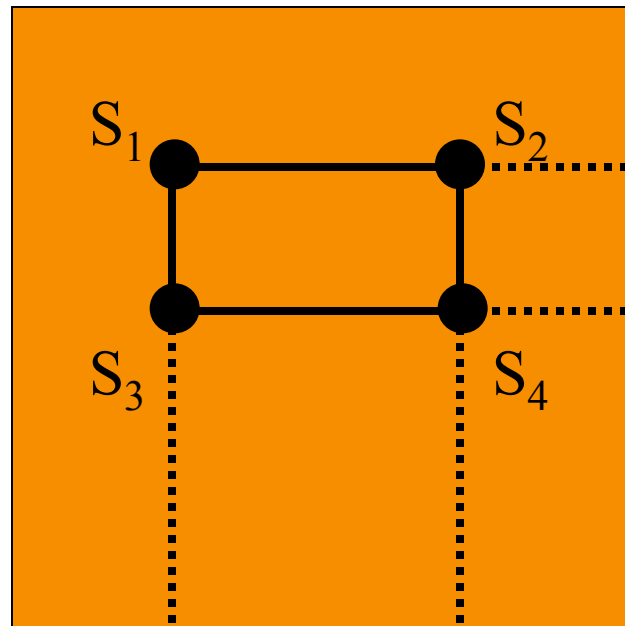
# Mipmaps

- Keep textures prefiltered at multiple resolutions
  - Usually powers of 2
  - For each pixel, linearly interpolate between two closest levels (i.e., **trilinear** filtering)
  - Fast, easy for hardware



# Summed-area tables

- At each texel keep sum of all values down & right
  - To compute sum of all values within a rectangle, simply combine four entries:  $S_1 - S_2 - S_3 + S_4$
  - Better ability to capture oblique projections, but still not perfect



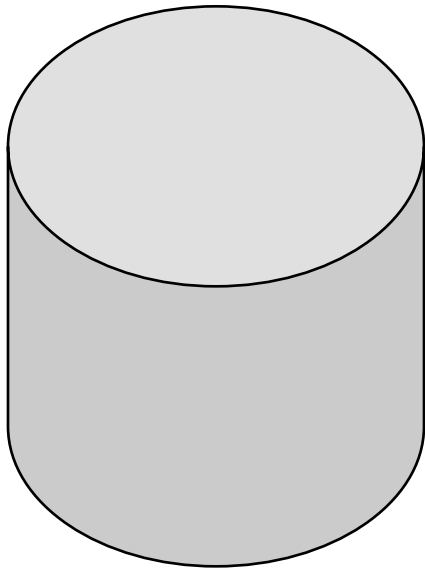


# Texture Mapping Overview

- Texture mapping stages
  - Parameterization
  - Mapping
  - Filtering
- Texture mapping applications
  - Modulation textures
  - Illumination mapping
  - Bump mapping
  - Environment mapping
  - Image-based rendering
  - Non-photorealistic rendering

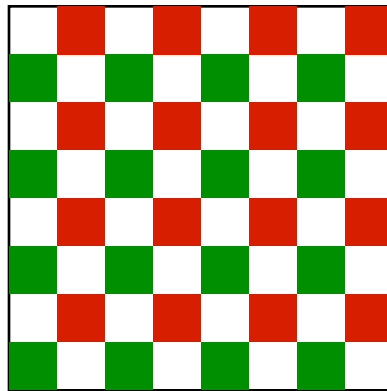


# Parameterization



geometry

+



image

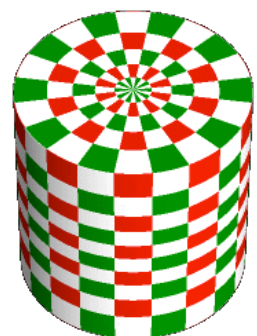
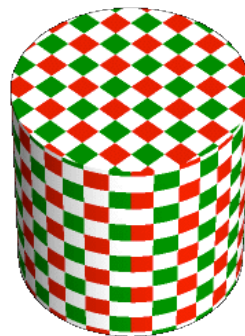
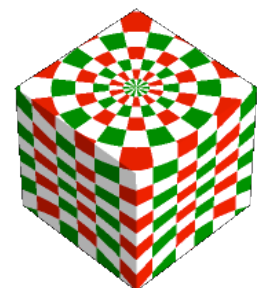
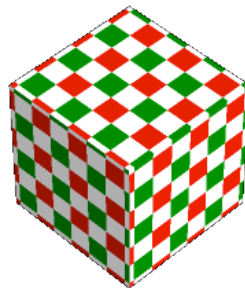
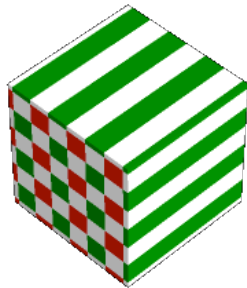
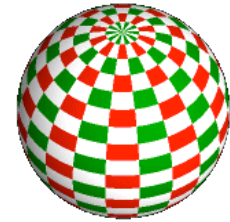
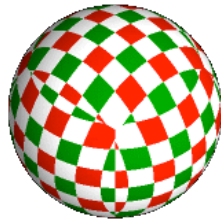
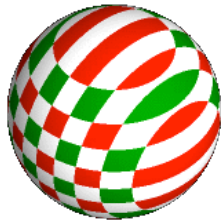
=



texture map

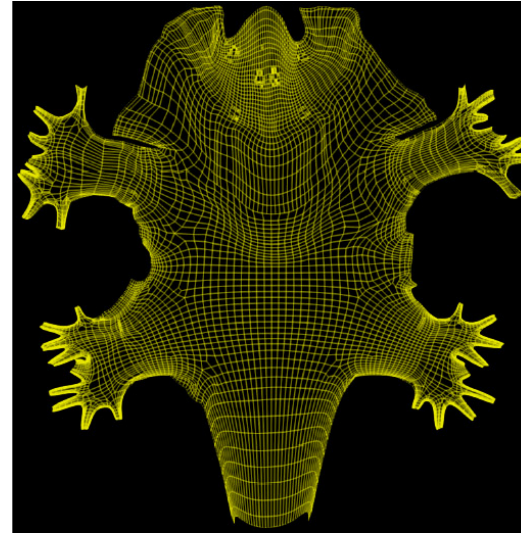
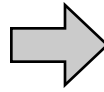
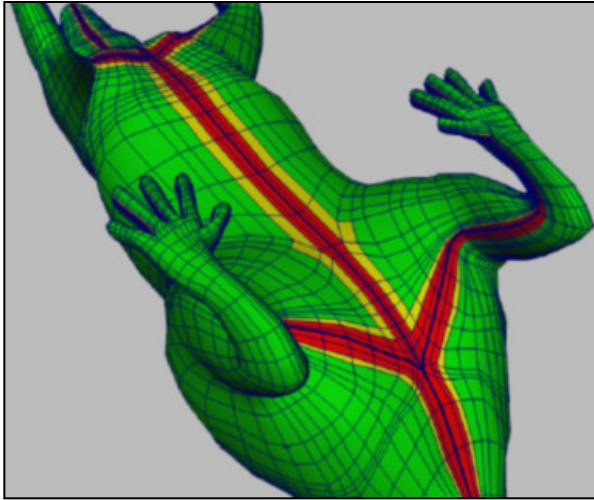
- Q: How do we decide *where* on the geometry each color from the image should go?

# Option: function gives projection

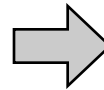
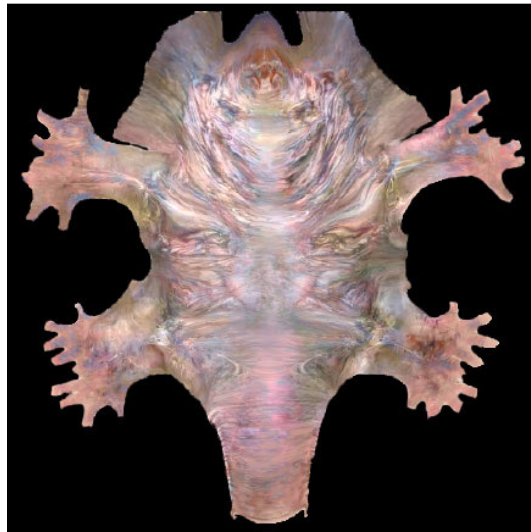


[Paul Bourke]

# Option: unfold the surface



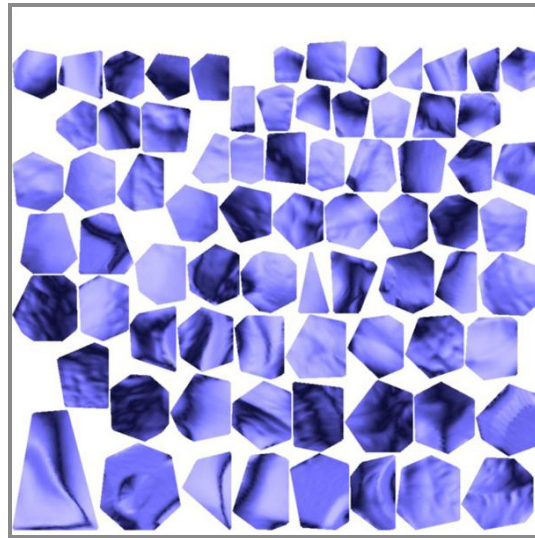
[Piponi2000]



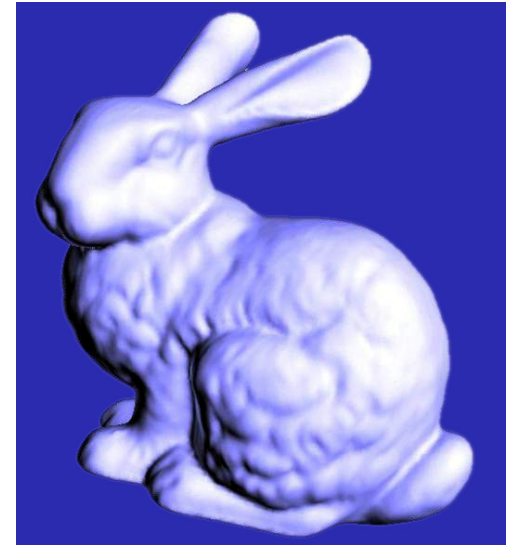
# Option: make an atlas



charts



atlas



surface

[Sander2001]

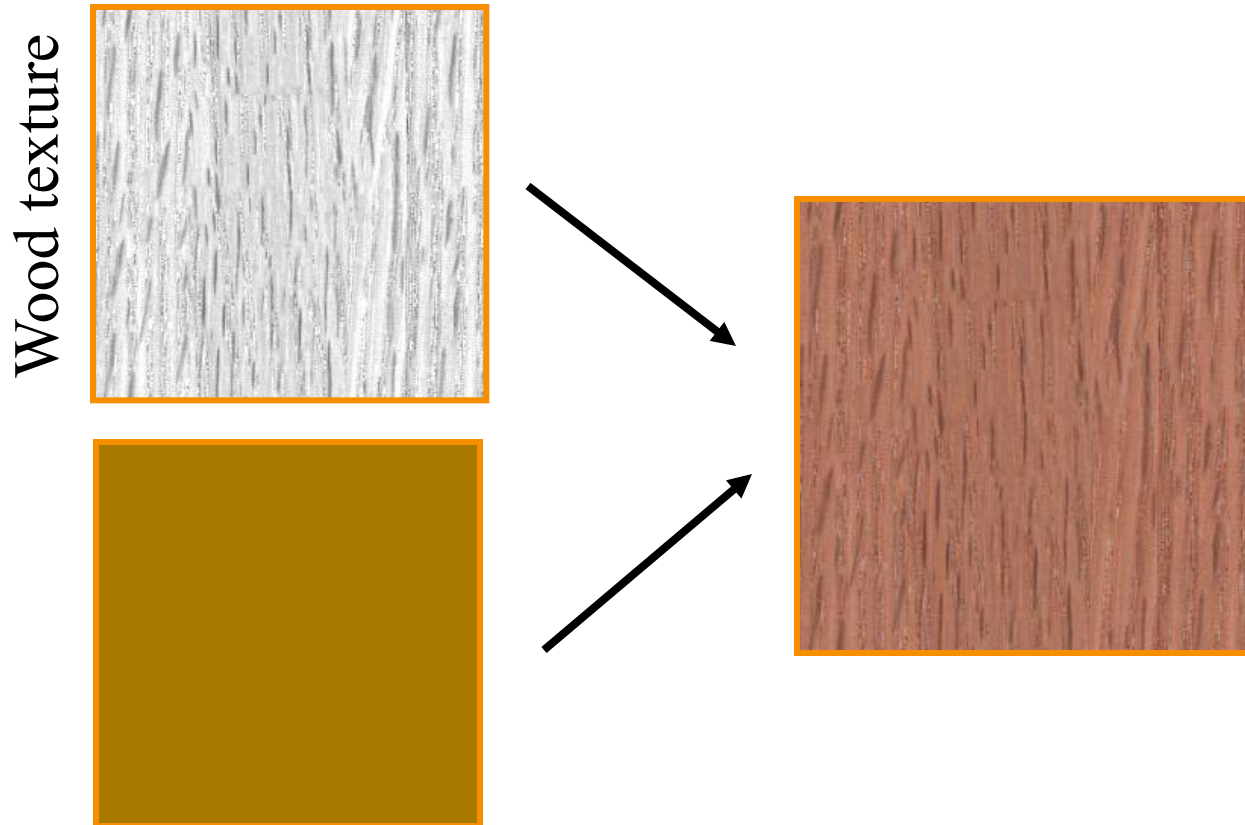


# Texture Mapping Overview

- Texture mapping stages
  - Parameterization
  - Mapping
  - Filtering
- Texture mapping applications
  - Modulation textures
  - Illumination mapping
  - Bump mapping
  - Environment mapping
  - Image-based rendering

# Modulation textures

Texture values scale result of lighting calculation



$$I = T(s, t) \left( I_E + K_A I_A + \sum_L \left( K_D (N \cdot L) + K_S (V \cdot R)^n \right) S_L I_L + K_T I_T + K_S I_S \right)$$

# Illumination Mapping

Map texture values to surface material parameter

- $K_A$
- $K_D$
- $K_S$
- $K_T$
- $n$

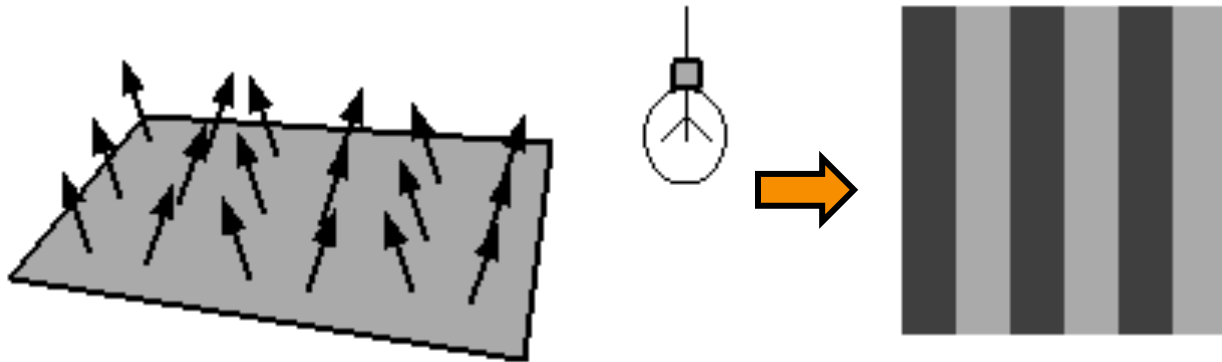


Texture  
value

$$I = I_E + K_A I_A + \sum_L \left( K_D(s, t)(N \cdot L) + K_S(V \cdot R)^n \right) S_L I_L + K_T I_T + K_S I_S$$

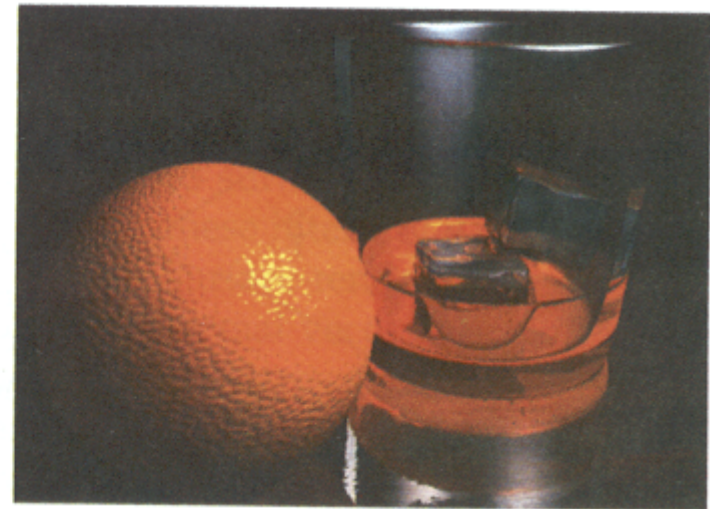
# Bump Mapping

Texture values perturb surface normals



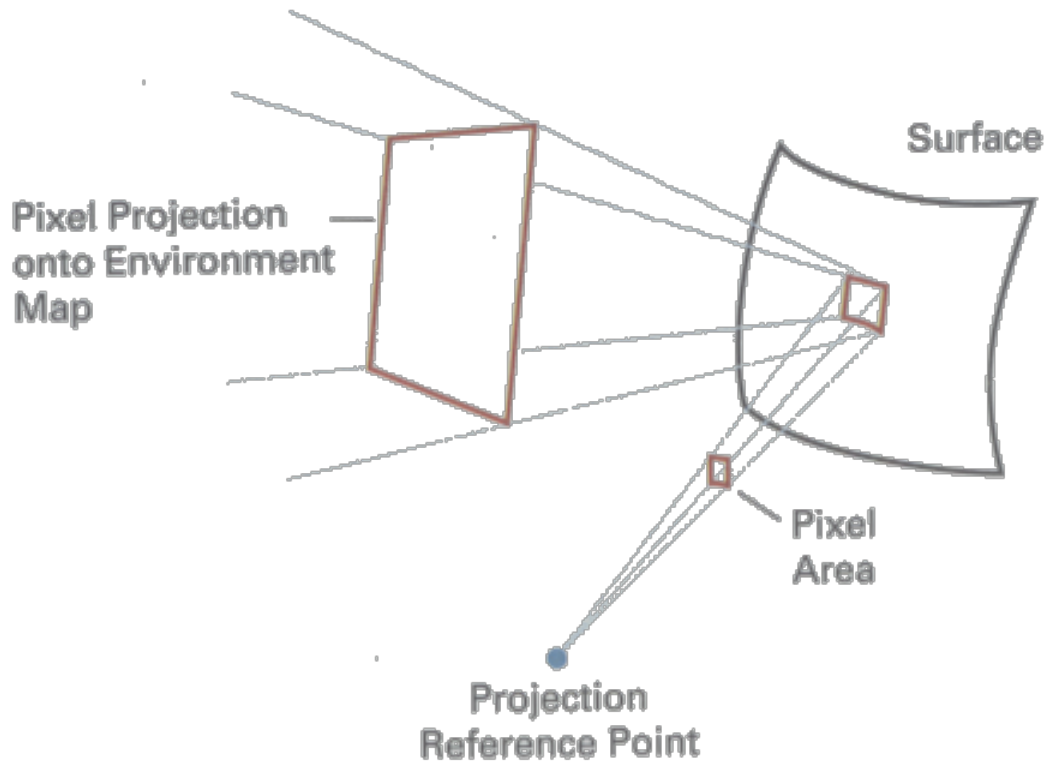


# Bump Mapping



# Environment Mapping

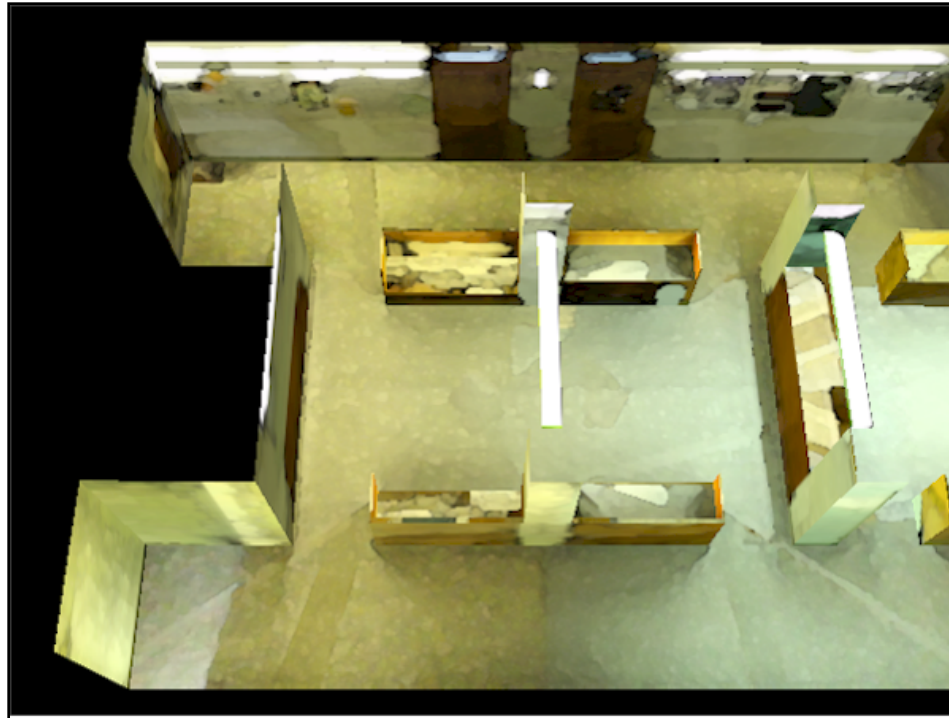
Texture values are reflected off surface patch



# Image-Based Rendering



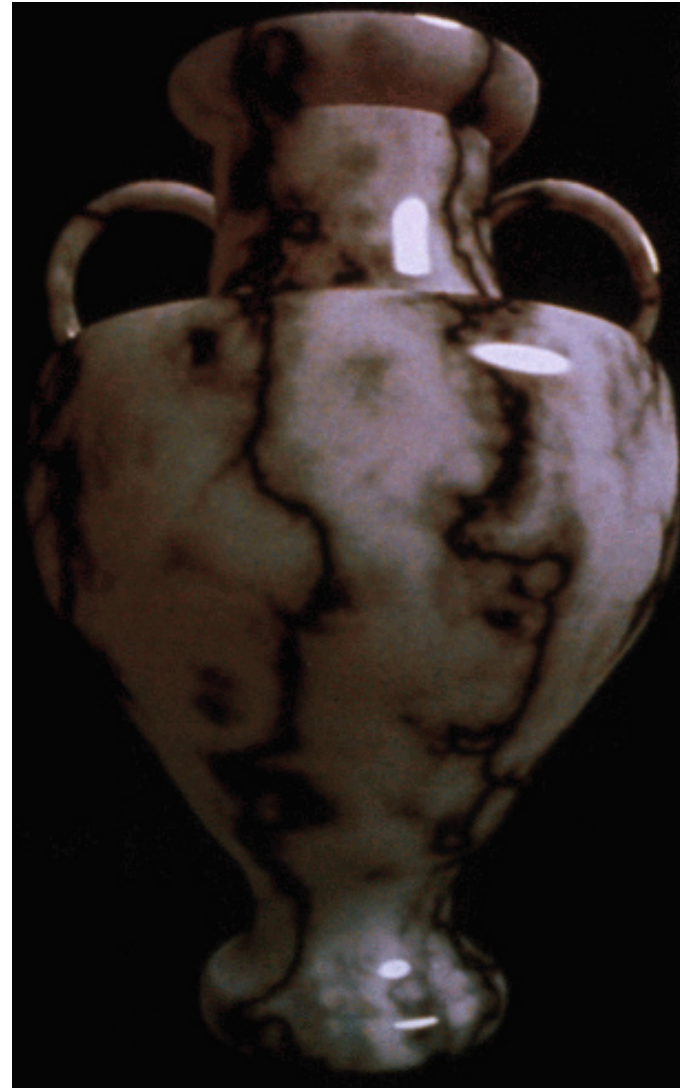
Map photographic textures to provide details for coarsely detailed polygonal model



# Solid textures

Texture values indexed  
by 3D location  $(x,y,z)$

- Expensive storage, or
- Compute on the fly,  
e.g. Perlin noise →





# Texture Mapping Summary

- Texture mapping stages
  - Parameterization
  - Mapping
  - Filtering
- Texture mapping applications
  - Modulation textures
  - Illumination mapping
  - Bump mapping
  - Environment mapping
  - Image-based rendering
  - Volume textures



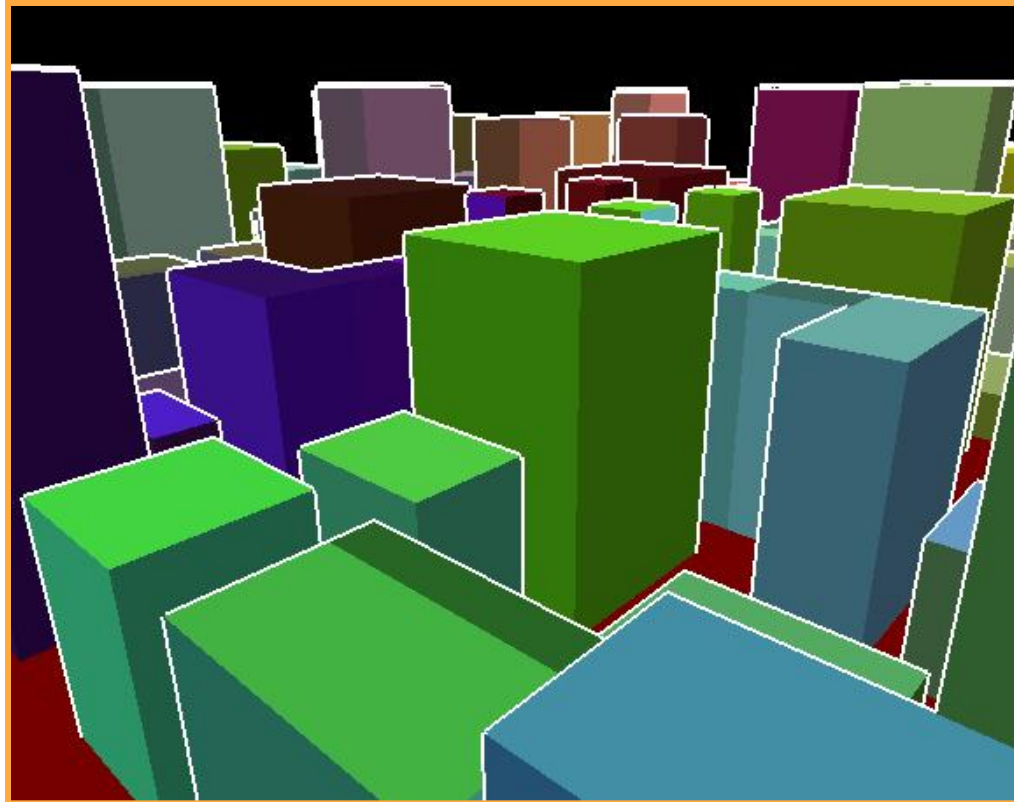
# Rasterization

- Scan conversion
  - Determine which pixels to fill
- Shading
  - Determine a color for each filled pixel
- Texture mapping
  - Describe shading variation within polygon interiors
- **Visible surface determination**
  - Figure out which surface is front-most at every pixel



# Visible Surface Determination

Make sure only front-most surface contributes to color at every pixel

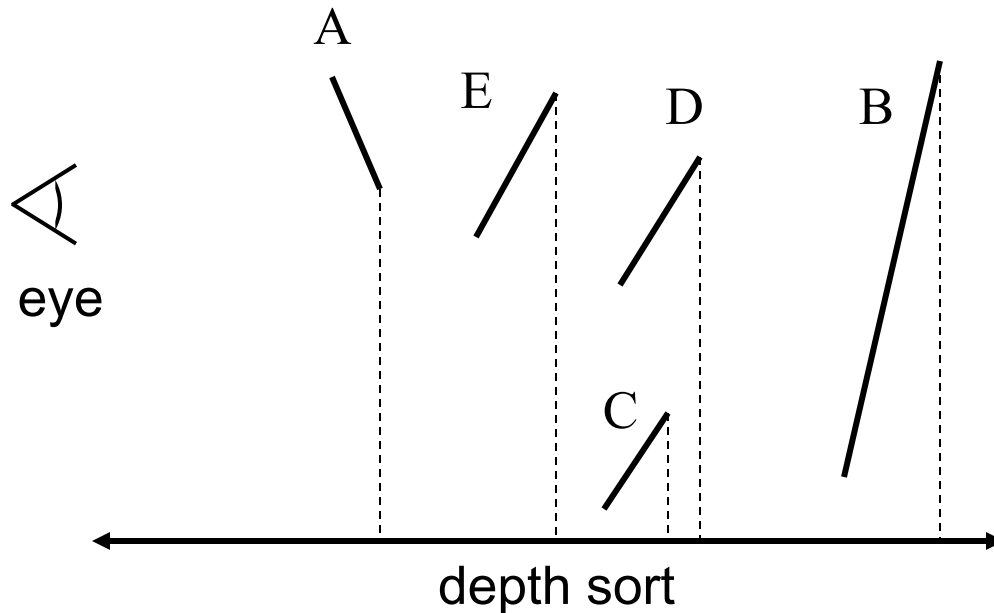


# Depth sort



## “Painter’s algorithm”

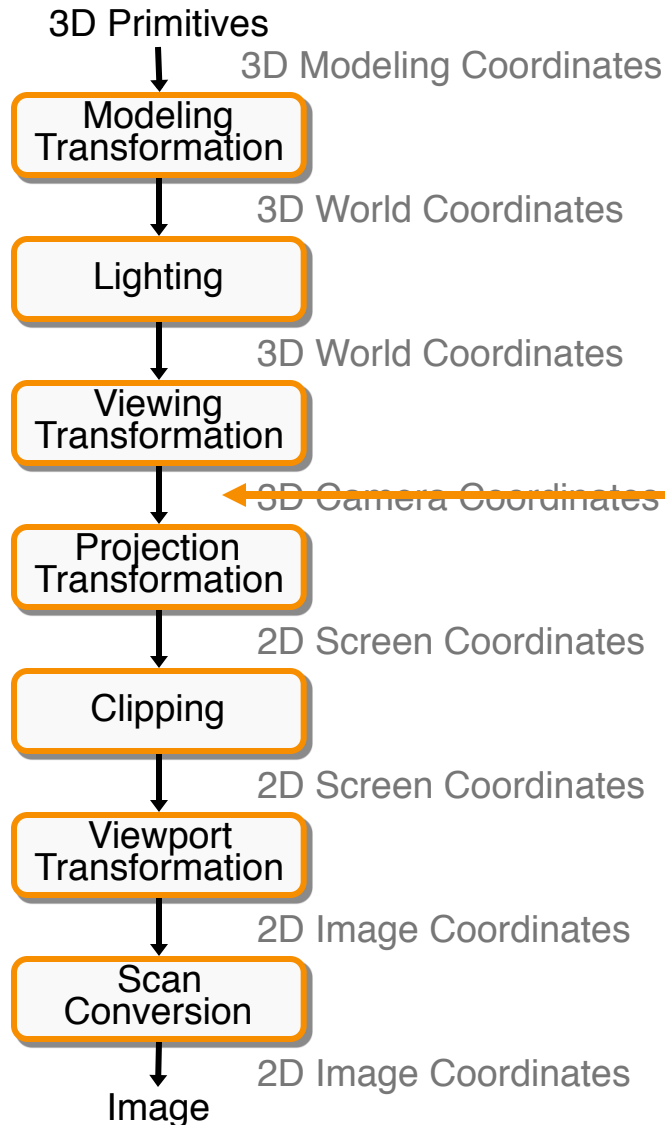
- Sort surfaces in order of decreasing maximum depth
- Scan convert surfaces in **back-to-front** order, **overwriting** pixels







# 3D Rendering Pipeline



Depth sort

## Depth sort comments

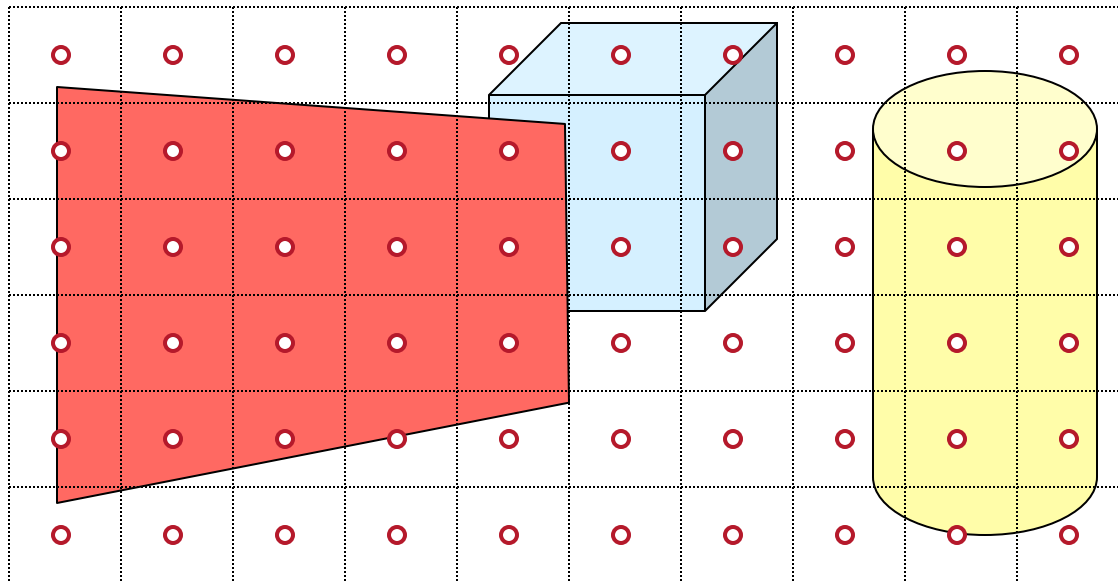
- $O(n \log n)$
- Better with frame coherence?
- Implemented in software
- Render every polygon
- Often use BSP-tree or static list ordering

# Z-Buffer

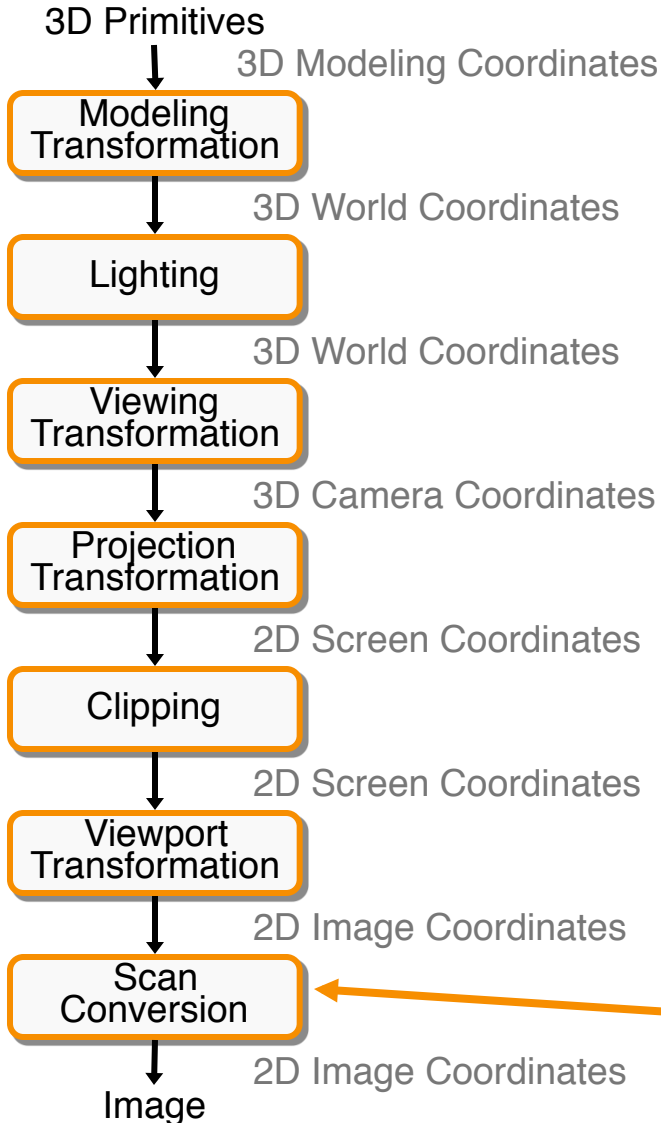


Maintain color & depth of closest object per pixel

- Framebuffer now RGBA<sub>z</sub> – initialize z to far plane
- Update only pixels with depth closer than in z-buffer
- Depths are interpolated from vertices, just like colors

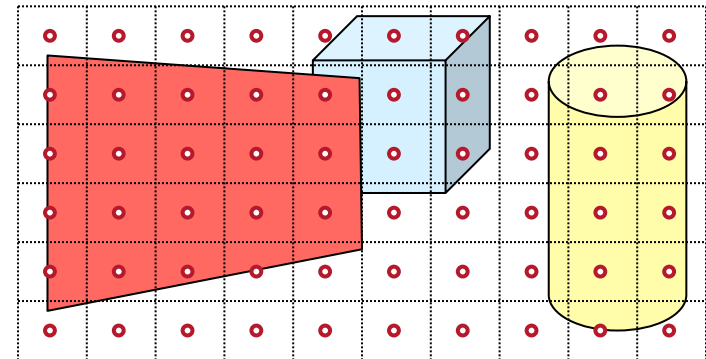


# Z-Buffer



## Z-buffer comments

- + Polygons rasterized in any order
- + Process one polygon at a time
- + Suitable for hardware pipeline
- Requires extra memory for z-buffer
- Subject to aliasing (A-buffer)
- o Commonly in hardware



Z-Buffer

# Hidden Surface Removal Algorithms

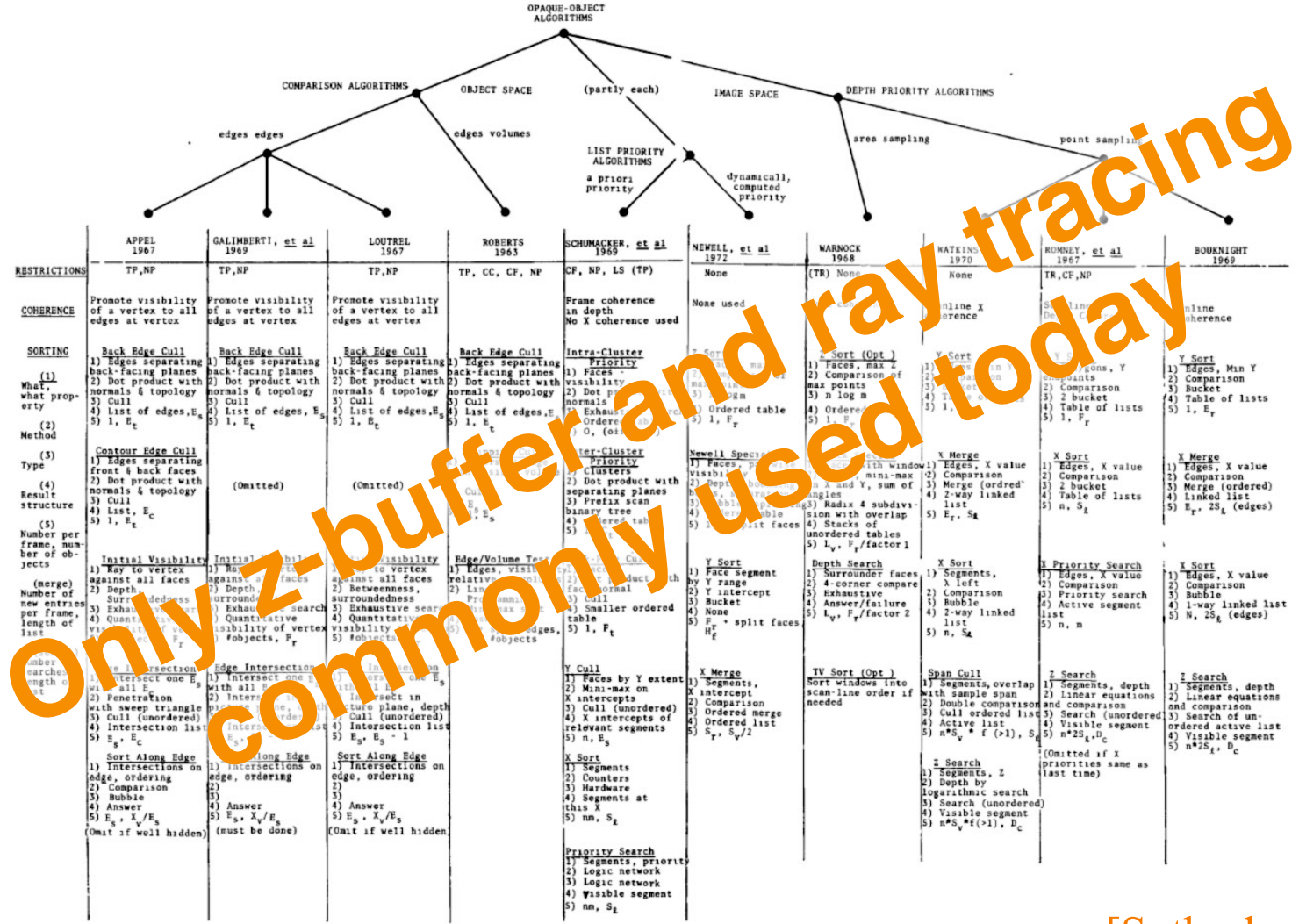


Figure 29. Characterization of ten opaque-object algorithms & Comparison of the algorithms.

[Sutherland '74]

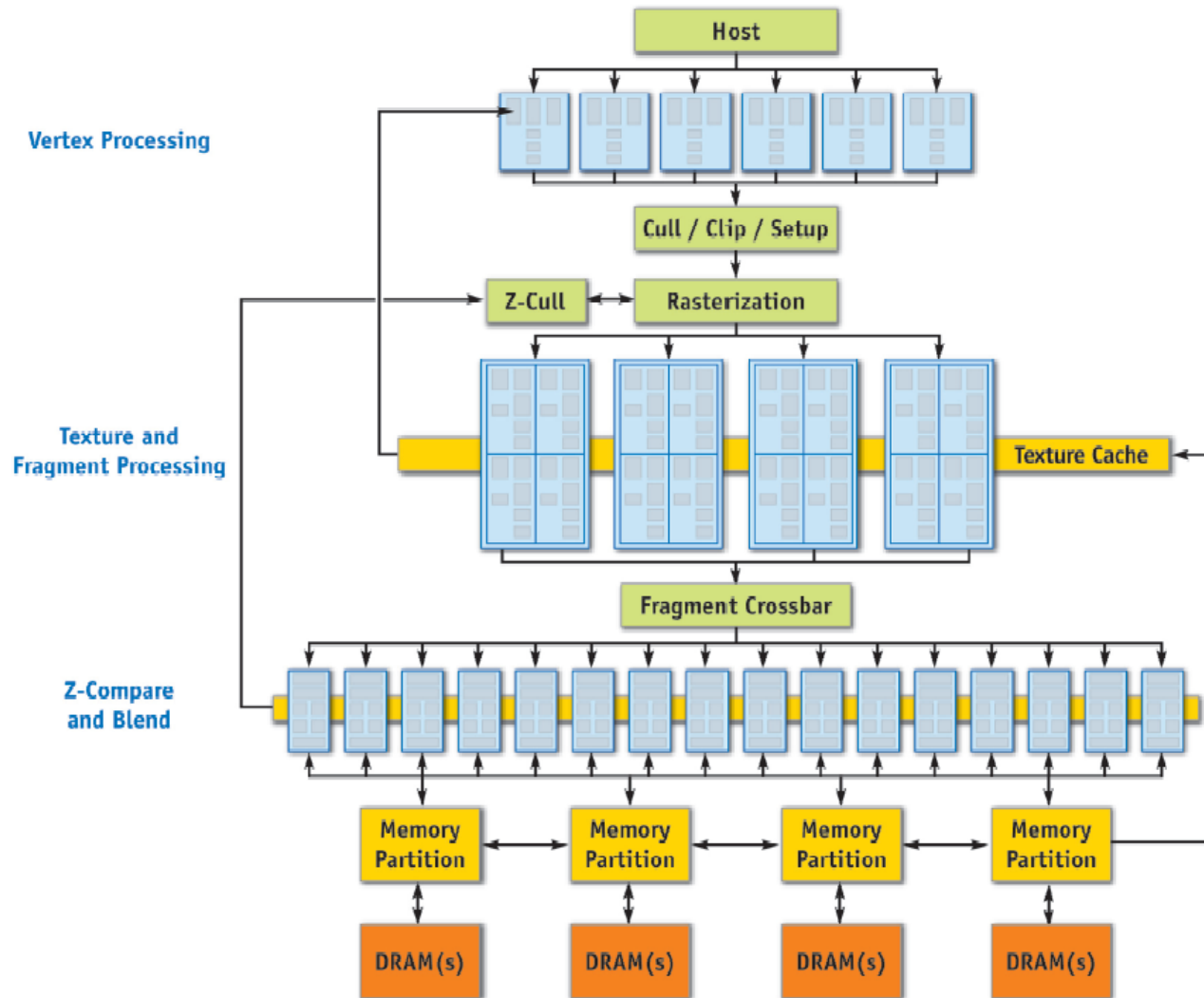


# Rasterization Summary

- Scan conversion
  - Sweep-line algorithm
- Shading algorithms
  - Flat, Gouraud
- Texture mapping
  - Mipmaps
- Visibility determination
  - Z-buffer

This is all in hardware

# GPU Architecture

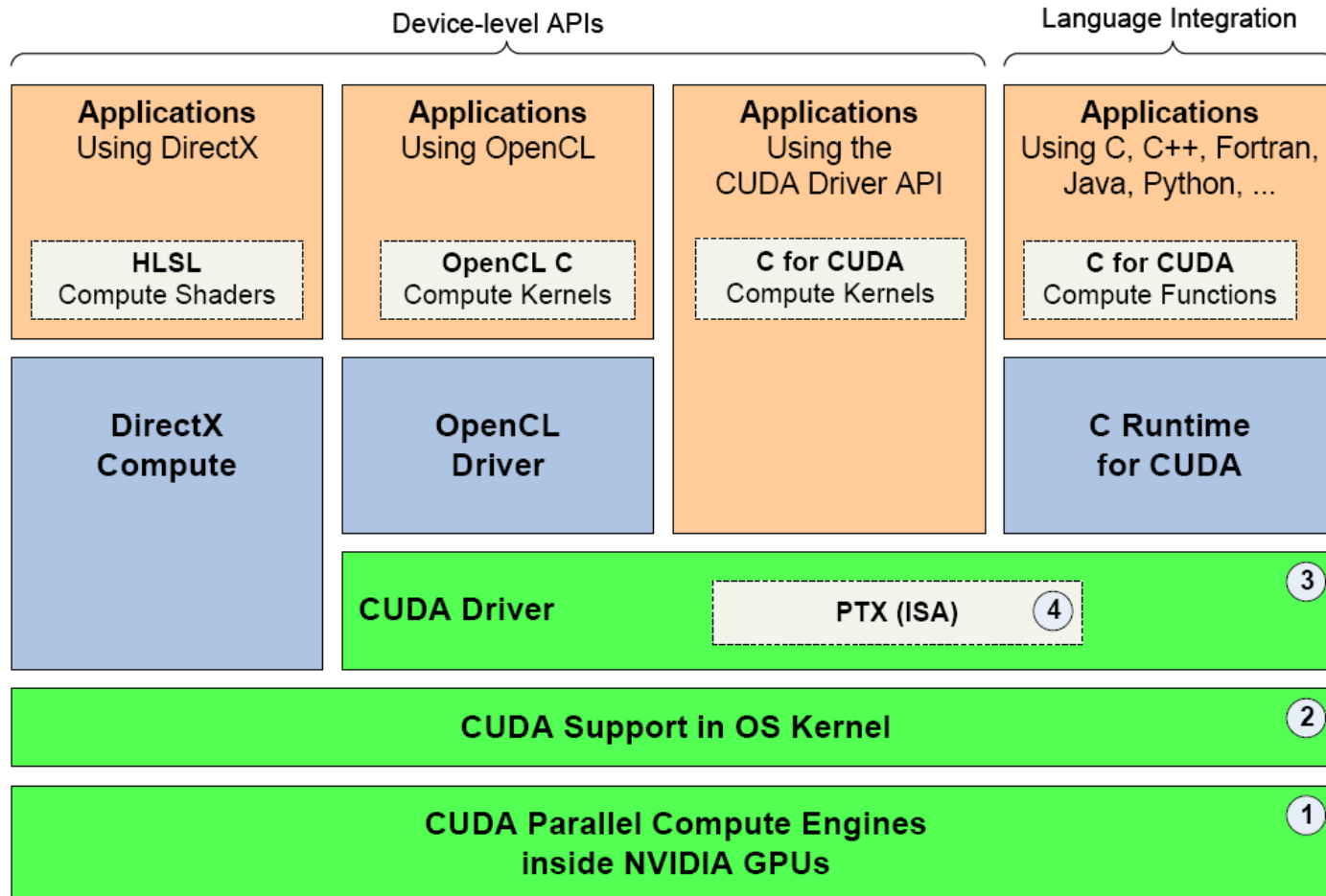


GeForce 6 Series Architecture

# Actually ...



- Graphics hardware is programmable



# Trend ...



- GPU is general-purpose parallel computer

